## STA 331 2.0 Stochastic Processes

#### 2. Markov Chains

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# n-step transition probabilities - $P_{ij}^n$

 $P_{ij}$  - One step transition probabilities

 $P_{ij}^n$  - n - step transition probabilities

Probability that a process in state i will be in state j after n additional transitions. That is,

$$P_{ij}^n = P(X_{n+k} = j | X_k = i), \ n \ge 0, \ i, j \ge 0.$$

# **Chapman-Kolmogrov Equations**

$$P_{ij}^{n+m} = \sum_{k=0}^{\infty} P_{ik}^n P_{kj}^m \text{ for all n, m} \geq 0, \text{ all i, j,}$$

where,  $P_{ik}^n P_{kj}^m$  represents the probability that starting in i the process will go to state j in n+m with an intermediate stop in state k after n steps.

In-class

This can be used to compute *n*-step transition probabilities

## In-class

### In-class

$$P_{ij}^{n+m} = \sum_{k=0}^{\infty} P_{ik}^n P_{kj}^m$$
 for all n, m  $\geq$  0, all i, j.

Proof:

### *n* - step transition matrix

The n-step transition matrix is

$$\mathbf{P}^{(n)} = \begin{bmatrix} P_{00}^{(n)} & P_{01}^{(n)} & P_{02}^{(n)} & \dots \\ P_{10}^{(n)} & P_{11}^{(n)} & P_{12}^{(n)} & \dots \\ & \ddots & \ddots & \dots \\ & \ddots & \ddots & \dots \end{bmatrix}$$

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## *n* - step transition matrix (cont.)

The Chapman-Kolmogrov equations imply

$$\mathbf{P}^{(n+m)}=P^{(n)}P^{(m)}.$$

In particular,

$$P^{(2)} = P^{(1)}P^{(1)} = PP = P^2.$$

By induction,

$$P^{(n)} = P^{(n-1+1)} = P^{n-1}P = P^n$$
.

### *n* - step transition matrix

### Proposition

$$P^{(n)} = P^n = P \times P \times P \times ... \times P, \ n \ge 1.$$

That is,  $P^{(n)}$  is equal to P multiplied by itself n times.

# Example 1

Let  $X_i = 0$  if it rains on day i; otherwise  $X_i = 1$ . Suppose  $P_{00} = 0.7$  and  $P_{10} = 0.4$ . Suppose it rains on Monday. Then, what is the probability that it rains on Friday.

## Example 1 - using R

```
p \leftarrow matrix(c(0.7, 0.4, 0.3, 0.6), nrow = 2); p
      [,1] [,2]
[1,] 0.7 0.3
[2,] 0.4 0.6
p%*%p%*%p%*%p
       [,1] [,2]
[1,] 0.5749 0.4251
[2,] 0.5668 0.4332
So that P_{00}^{(4)} = 0.5749
```

## Example 2

Recall the example from class in which the weather today depends on the weather for the previous two days.

						0.7	0	0.3	0	l
Sate	Yesterday	Today	Tomorrow	Probability		^ -	_	۰ -	_	l
0-RR	1	1	1	0.7	_	0.5	U	0.5	U	ı
1-SR	0	1	1	0.5	P=			_		ı
2-RS	1	0	1	0.4		0	0.4	0	0 0.6	ı
3-SS	0	0	1	0.2						П
						0	0.2	0	8.0	ı
					I			•	_	J

Now suppose that it was sunny both yesterday and the day before yesterday. What's the probability that it will rain tomorrow?

# Example 2 (cont.)

```
[,1] [,2] [,3] [,4]
[1,] 0.49 0.12 0.21 0.18
[2,] 0.35 0.20 0.15 0.30
[3,] 0.20 0.12 0.20 0.48
[4,] 0.10 0.16 0.10 0.64
```

### **Unconditional Probabilities**

Suppose we know the initial probabilities,

$$\alpha_i = P(X_0 = i), \quad \text{, } i = 0, 1, 2, \dots$$
 and  $\sum_i \alpha_i = 1.$ 

According to the Law of total probability

$$P(X_n = j) = \sum_{i=0}^{\infty} P(X_n = j \cap X_0 = i)$$

$$= \sum_{i=0}^{\infty} P(X_n = j | X_0 = i) P(X_0 = i)$$

$$= \sum_{i=0}^{\infty} P_{ij}^{(n)} \alpha_i$$

# Example 3 (based on Example 1)

Let  $X_i = 0$  if it rains on day i; otherwise  $X_i = 1$ . Suppose  $P_{00} = 0.7$  and  $P_{01} = 0.4$ . Suppose it rains on Monday. Suppose  $P(X_0 = 0) = 0.4$  and  $P(X_0 = 1) = 0.6$ . What is the probability that it will not rain on the 4th day after we start keeping records?

# Example 3 (cont.)

Let  $X_i=0$  if it rains on day i; otherwise  $X_i=1$ . Suppose  $P_{00}=0.7$  and  $P_{01}=0.4$ . Suppose it rains on Monday. Suppose  $P(X_0=0)=0.4$  and  $P(X_0=1)=0.6$ . What is the probability that it will not rain on the 4th day after we start keeping records?

```
p <- matrix(c(0.7, 0.4, 0.3, 0.6), nrow = 2)
p%*%p%*%p%*%p
```

# Example 4

Suppose that a taxi driver operates between Wijerama and Nugegoda. If the driver is in Wijerama the probability that he gets a trip to Nugegoda from one passenger or a group of travelling together is 0.2 and that for him to get a trip nearby Wijerama is 0.8. If the driver is in Nugegoda he has equal chance of getting a trip to Wijerama or nearby Nugegoda. The behaviour of the driver evolves over time in a probabilistic manner.

## 0 - Wijerama, 1 - Nugegoda

$$\mathbf{P} = \left[ \begin{array}{cc} 0.8 & 0.2 \\ 0.5 & 0.5 \end{array} \right]$$

# Example 4 (cont.)

i) If the driver is currently at Wijerama, what is the probability that he will be back at Wijerama after three trips?

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```
p <- matrix(c(0.8, 0.5, 0.2, 0.5), ncol=2)
p%*%p%*%p
```

```
[,1] [,2]
[1,] 0.722 0.278
[2,] 0.695 0.305
```

# Example 4 (cont.)

ii) If the driver is at Nugegoda, how many trips on the average will be in Nugegoda before he next goes to Wijerama?

# Example 4 (cont.): In-class

# Example 4 (cont.): In-class

Suppose  $P^{(0)} = (0.5, 0.5)$ , equal chance for driver be in either Wijerama or Nugegoda. What is probability he will be in Wijerama after the first trip.

In-class: Method 1

# Probability after n-th step

$$\mathbf{P}^{(n)} = \mathbf{P}^{(0)}\mathbf{P}^n$$

## In-class: Method 2

# **Types of States**

Definition: If  $P_{ij}^{(n)} > 0$  for some  $n \ge 0$ , state j is **accessible** from i.

Notation:  $i \rightarrow j$ .

*Definition*: If  $i \rightarrow j$  and  $j \rightarrow i$ , then i and j **communicate**.

Notation:  $i \leftrightarrow j$ .

### Theorem:

### Communication is an equivalence relation:

- (i)  $i \leftrightarrow i$  for all i (reflexive).
- (ii)  $i \leftrightarrow j$  implies  $j \leftrightarrow i$  (symmetric).
- (iii)  $i \leftrightarrow j$  and  $j \leftrightarrow k$  imply  $i \leftrightarrow k$  (transitive).

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### Note:

- Two states that communicate are said to be in the same class.
- The concept of communication divides the state space up into a number of separate classes.

In-class: demonstration

# Theorem (cont.)

**Definition**: An equivalence class consists of all states that communicate with each other.

Remark: Easy to see that two equivalence classes are disjoint.

Example: The following P has equivalence classes  $\{0,1\}$  and  $\{2,3\}$ 

$$\mathbf{P} = \begin{bmatrix} 0.5 & 0.5 & 0 & 0 \\ 0.5 & 0.5 & 0 & 0 \\ 0 & 0 & 0.75 & 0.25 \\ 0 & 0 & 0.25 & 0.75 \end{bmatrix}$$

# **Equivalence class (cont.)**

What about this?

$$\mathbf{P} = \begin{bmatrix} 0.5 & 0.5 & 0 & 0 \\ 0.5 & 0.3 & 0.2 & 0 \\ 0 & 0 & 0.75 & 0.25 \\ 0 & 0 & 0.25 & 0.75 \end{bmatrix}$$

### **Irreducible**

Definition: A MC is irreducible if there is only one equivalence class (i.e., if all states communicate with each other).

What about these?

$$\mathbf{P} = \begin{bmatrix} 0.5 & 0.5 & 0 & 0 \\ 0.5 & 0.5 & 0 & 0 \\ 0 & 0 & 0.75 & 0.25 \\ 0 & 0 & 0.25 & 0.75 \end{bmatrix} \qquad \mathbf{P} = \begin{bmatrix} 0.5 & 0.5 & 0 & 0 \\ 0.5 & 0.3 & 0.2 & 0 \\ 0 & 0 & 0.75 & 0.25 \\ 0 & 0 & 0.25 & 0.75 \end{bmatrix}$$

$$\mathbf{P} = \begin{bmatrix} 0.5 & 0.5 & 0 & 0 \\ 0.5 & 0.3 & 0.2 & 0 \\ 0 & 0 & 0.75 & 0.25 \\ 0 & 0 & 0.25 & 0.75 \end{bmatrix}$$

# Irreducible (cont.)

What about these?

$$\mathbf{P} = \left[ \begin{array}{cc} 0.5 & 0.5 \\ 0.25 & 0.75 \end{array} \right]$$

$$\mathbf{P} = \left[ \begin{array}{ccc} 0.25 & 0 & 0.75 \\ 1 & 0 & 0 \\ 0 & 0.5 & 0.5 \end{array} \right]$$

# Identify the equivalence classes

Consider a Markov chain with a state space  $S = \{0, 1, 2, 3, 4\}$  and having the following one-step transition probability matrix.

$$\mathbf{P} = \begin{bmatrix} 0.4 & 0.2 & 0 & 0.4 & 0 \\ 0.2 & 0.4 & 0.1 & 0.3 & 0 \\ 0.1 & 0.2 & 0.5 & 0.1 & 0.1 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

### Problems 1

Example 4.10

Example 4.11

Example 4.12

<sup>&</sup>lt;sup>1</sup>Introduction to Probability Models, Sheldon M. Ross

### Classification of States - next week

Reading Section 4.3: Classification of States<sup>2</sup>

 $<sup>^2\</sup>mbox{Introduction}$  to Probability Models, Sheldon M. Ross