

In this lab, your task is to build a character-level language model with LSTM layer.

```
1 from google.colab import drive
2 drive.mount('/content/drive')
   Mounted at /content/drive
1 cd "/content/drive/MyDrive/UCCD3074 Labs/UCCD3074 Lab10"
    /content/drive/MyDrive/UCCD3074 Labs/UCCD3074 Lab10
1 import os
2 import math
3 import torch
4 import torch.nn as nn
5 from torch.nn import functional as F
7 import time
1 torch.manual seed(1234)
2 device = 'cuda' if torch.cuda.is available() else "cpu"
1 if not os.path.exists('input.txt'):
      !wget 'https://raw.githubusercontent.com/karpathy/char-rnn/master/data/tinyshakespeare/input.txt'
```

Preprocessing

Read the dataset into the string raw_data.

```
1 with open('./input.txt', 'r', encoding='utf-8') as f:
2    raw_data = f.read()
```

Create the vocabulary

```
1 vocab = sorted(list(set(raw_data)))
2 vocab_size=len(vocab)
3 print('vocab_size:', vocab_size)
    vocab_size: 65

1 stoi = {ch:i for i, ch in enumerate(vocab)}
2 itos = {i:ch for i, ch in enumerate(vocab)}

1 encode_text = lambda s : [stoi[c] for c in s]  # encode: take a string, output a list of integers
2 decode_text = lambda l : ''.join([itos[i] for i in l])

1 data = torch.tensor(encode_text(raw_data), dtype=torch.long)
```

The function get_batch randomly sample a block of text as input x. The label y is the block of text shifted by 1 position of x.

```
1 def get_batch(batch_size, block_size):
2    ix = torch.randint(len(data) - block_size, (batch_size,))
3    x = torch.stack([data[i:i+block_size] for i in ix])
4    y = torch.stack([data[i+1:i+block_size+1] for i in ix])
5    x, y = x.to(device), y.to(device)
6    return x, y
```

Character-level language model with Transformer model

Now, let's build the character-level language model with LSTM. The network LMNet has the following layers:

Layer	Configuration	Shape
Input	-	(B, T)
Token Embedding	num_embedding = vocab_size, embedding_dim = d_model	(B, T, d_model)
Position Embedding	d_model = d_model	(B, T, d_model)
TransformerEncoder	d_model (default: 512), nhead (default = 6), dim_feedforward, batch_first (default: False)	(B, T, d_model)
fc	in_features = d_model, out_features = vocab_size	(B, T, vocab_size)

▼ Transformer in PyTorch

PyTorch offers the necessary transformer layers to built the transformer model, including:

- 1. <u>nn.Transformer</u> a tranformer model. The module is constructed from nn.TranformerEncoder and nn.TransformerDecoder below.
- 2. nn.TransformerEncoder a stack of N encoder layers
- 3. nn.TransformerDecoder a stack of N decoder layers
- 4. nn.TransformerEncoderLayer made up of multi-head (self) attention and feedforward network
- 5. nn.TransformerDecoderLayer made up of multi-head (self) attention, multi-head (encoder) attention and feedforward network

Transformer Language Model

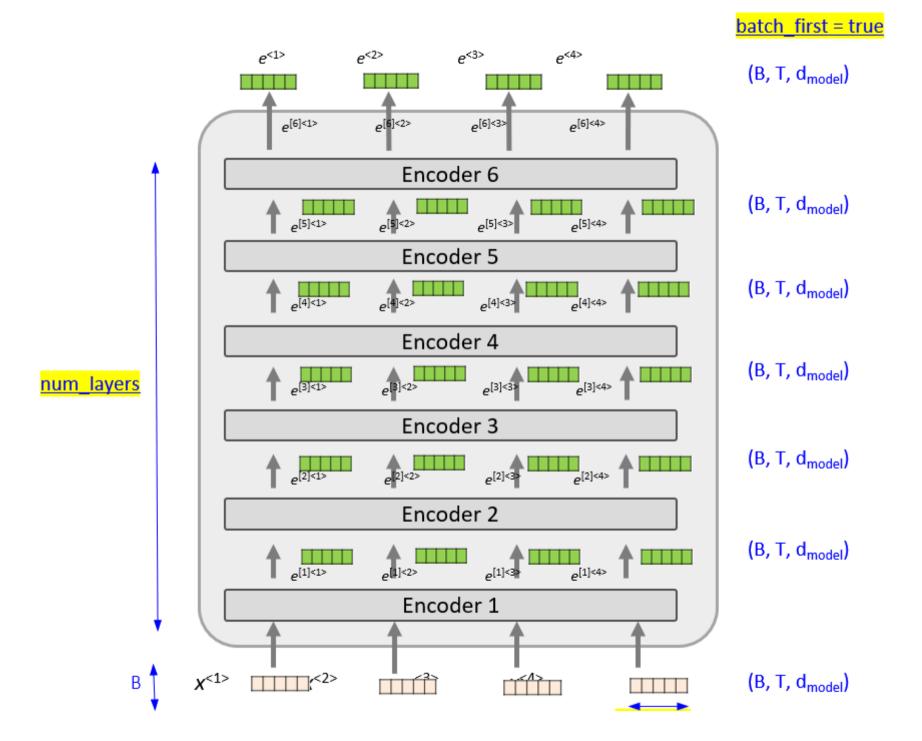
To implement a language model, we need only the encoder portion of Transformer. It can be constructed with nn.TransformerEncoder and nn.TransformerEncoderLayer. The following diagram show the network that we shall use to build the language model.

The network is implemented in two steps.

1. Create an encoder layer with nn.TransformerEncoderLayer.

- d_model (int) the number of expected features in the input (required).
- onhead (int) the number of heads in the multiheadattention models (required).
- dim_feedforward (int) the dimension of the feedforward network model (default=2048).
- batch_first (bool) If True, then the input and output tensors are provided as (batch, seq, feature). Default: False (seq, batch, feature).
- 2. Create the encoder block with nn. Transformer Encoder by stacking multiple encoder layers
 - encoder_layer an instance of the TransformerEncoderLayer() class (required).
 - num_layers the number of sub-encoder-layers in the encoder (required).

The following figure shows a Transformer's Encoder block. It consists of num_layers encoder layers. When batch_size = True, the input to the transformer model has a shape of (B, T, d_model) where B is the batch size, T is the sequence length and d_model is the feature dimension of each token. The transformer model can handle different batch sizes B and sequence length T during inference. However, the d_model is a hyperparameter and is fixed during inference.



d model

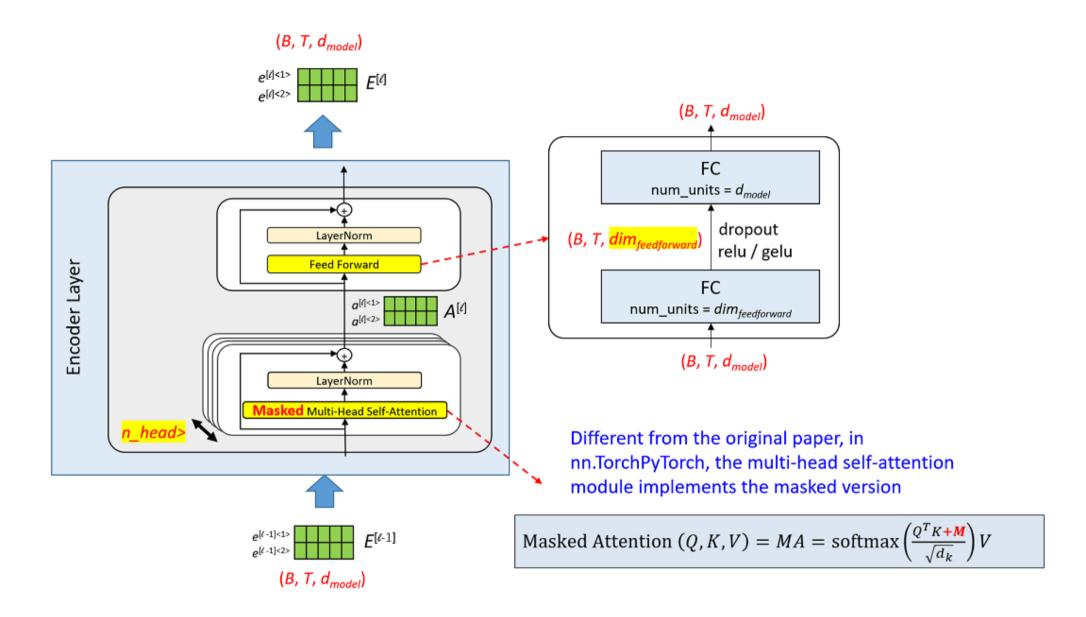
The following figure shows the block diagram for the encoder layer. Each layer contains a total of n_head heads. Each head consists of two modules:

1. Self-attention module

Different from the origin transformer, PyTorch implementation replaces the *multi-head self-attention* layer with the **masked** version as shown below. This allows it the encoder be used for generative language modeling.

2. Feed forward module

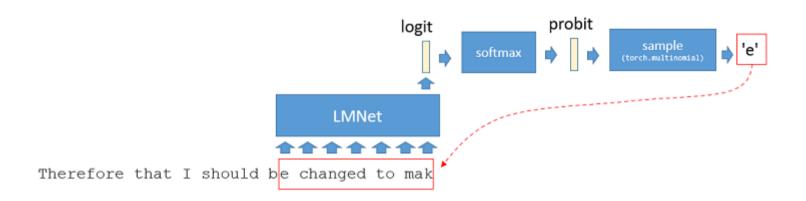
This modules consists of two linear layer. The output feature length of the 1st linear layer is set to <code>dim_feedforward</code> while the 2nd linear layer is set to <code>d_model</code>.



▼ Generating novel text

To generate novel text, we implement the method generate. Since the network is trained on a sequence of length $T = block_size$, when generating the text, we feed the most recent $block_size$ characters into the network to generate the next character. Here are the steps:

- 1. Crop the most recent block_size characters in the generated text
- 2. The cropped text is fed to the generative model to generate the next character. The network output the logit value.
- 3. Convert the logit of the network to probit value by performing softmax operation.
- 4. Sample a character from the probit by using torch.multinorm
- 5. Append the sampled character to the end of the generated text.
- 6. Repeat steps 1-5 for text_len times

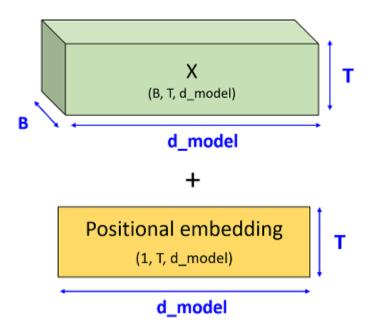


Positional Embedding

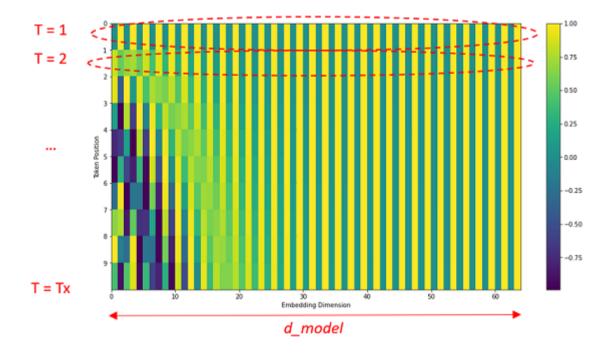
The following PositionalEncoding module injects some information about the relative or absolute position of the tokens in the sequence. The positional encodings have the same dimension as the embeddings so that the two can be summed. To do so, we can use sine and cosine functions of different frequencies to embed the distance.

$$PE_{(t,2i)} = \sin(t/10000^{2i/d_{model}}) \ PE_{(t,2i+1)} = \cos(t/10000^{2i/d_{model}})$$

where t is the (time) index of the token in the input sequence and i is the index of the embedding feature representing the token



The following diagram shows how the position embedding looks like for different time steps.



▼ Implement the Position Embedding

```
1 class PositionEmbedding(nn.Module):
 2
      def __init__(self, d_model: int, batch_first: bool = False, max_len: int = 5000, dropout: float = 0.
 3
           super().__init__()
 4
           self.dropout = nn.Dropout(p=dropout)
           self.batch_first = batch_first
 7
           # Shape of position: (max len, 1)
 8
           position = torch.arange(max_len).unsqueeze(1)
10
           # Shape of div_term: 1d tensor of shape (d_model/2, )
11
12
           div_term1 = torch.exp(torch.arange(0, d_model, 2) * (-math.log(10000.0) / d_model))
13
           div_term2 = div_term1[:-1] if d_model % 2 == 1 else div_term1
14
```

```
# snape o+ pe: (max_len, l, a_model)
15
16
          if self.batch first:
               pe = torch.zeros(1, max_len, d_model)
17
18
               pe[0, :, 0::2] = torch.sin(position * div_term1)
               pe[0, :, 1::2] = torch.cos(position * div term2)
19
               self.register buffer('pe', pe)
20
21
           else:
22
               pe = torch.zeros(max len, 1, d model)
               pe[:, 0, 0::2] = torch.sin(position * div term1)
23
               pe[:, 0, 1::2] = torch.cos(position * div term2)
24
               self.register buffer('pe', pe)
25
26
       def forward(self, x):
27
28
29
           Arguments:
30
              x: Tensor, shape ``[seq len, batch size, embedding dim]``
31
32
           # Shape of self.pe: (T, 1, embedding dim)
33
           # shape of x
                           : (T, B, embedding dim)
           if self.batch first:
34
              x = x + self.pe[:, :x.size(1), :]
35
36
           else:
37
              x = x + self.pe[:x.size(0)]
           return self.dropout(x)
38
```

Test the position embedding layer.

▼ Implement the Language Model

```
1 class LMNet(nn.Module):
      def init (self, vocab size, d model=512, nhead=8, dim feedforward=2048, num layers=6, batch first=True):
 2
          super(). init ()
 3
          # token embedding
 5
          self.token embedding = nn.Embedding(vocab size, d model)
 6
 7
          # positional embedding layer
          self.pos embedding = PositionEmbedding(d model, batch first)
 9
10
11
          # create the encoder block
                             = nn.TransformerEncoderLayer(d model, nhead, dim feedforward, batch first=batch first)
12
          encoder layer
          self.encoder net = nn.TransformerEncoder(encoder layer, num layers)
13
14
          # create the linear layer
15
                               = nn.Linear(d model, vocab size)
16
          self.fc
17
18
      def forward(self, x, mask=None):
                                                   # (B,T)
19
20
          # convert each token into its embedding vetor
          x = self.token embedding(x) # (B,T,d model)
21
22
          # add position embedding to x
23
24
          x = self.pos embedding(x)
                                        # (B,T,d model)
25
          # perform sequence model inference
26
27
          if mask is not None:
```

```
28
              x = self.encoder net(x, mask) # (B,T,d model)
29
          else:
30
              x = self.encoder_net(x)
31
32
          # generate logits
          x = self.fc(x)
                                        # (B,T,vocab size)
33
34
35
          return x
36
37
      def generate(self, text len, block size):
38
          text = torch.zeros((1,1), dtype=torch.long).to(device) # text token (B, T) where B is fixed to 1, T = 1 initially
39
40
          # repeat until the length of text = "text len"
41
          for in range(text len): # (B, T)
42
43
              # crop text to the last block-size tokens
44
              text cond = text[:, -block size:] # (B, T)
45
46
              # get the predictions
47
              seq len = text cond.shape[-1]
48
              mask = create mask(seq len)
49
              yhat = self(text cond, mask) # logits: (B, T, C)
50
51
52
              # focus oly on the last time step
53
              yhat = yhat[:, -1, :] # becomes (B, C)
54
              # apply soft max to get probabilities
55
              probs = F.softmax(yhat, dim=-1) # (B, C)
56
57
              # sample from distribution
58
              next token = torch.multinomial(probs, num samples=1) # (B, 1)
59
60
              # append sampled index to the running sequence
61
              text = torch.cat((text, next_token), dim=1) # (B, T+1)
62
63
              # print the sample
64
```

```
print(itos[next token.item()], end='')
65
               time.sleep(0.1)
66
67
Test the model without any masking
 1 d model=512
 2 nhead=8
 3 dim feedforward=2048
 4 num layers=6
 5 vocab size = len(vocab)
 6 batch first = True
 7 batch size=4
 8 block size=8
 1 model = LMNet(vocab_size, d_model, nhead, dim_feedforward, num_layers, batch_first).to(device)
 1 x, y = get_batch(batch_size, block_size)
 2 x, y = x.to(device), y.to(device)
 3
 4 \text{ yhat} = \text{model}(x)
 6 print('Shape of x: ', x.shape)
 7 print('Shape of yhat: ', yhat.shape)
     Shape of x:
                     torch.Size([4, 8])
     Shape of yhat: torch.Size([4, 8, 65])
Test the model with masking
 1 def create_mask(Tx):
       mask = torch.triu(torch.ones(Tx, Tx) * float('-inf'), diagonal=1).to(device)
       mask = mask.to(device)
```

```
4    return mask
5
6 mask = create_mask(block_size)
7 print('Shape of mask:', mask.shape)
        Shape of mask: torch.Size([8, 8])

1 yhat = model(x, mask)
2 print('Shape of yhat:', yhat.shape)
        Shape of yhat: torch.Size([4, 8, 65])
```

Train the model

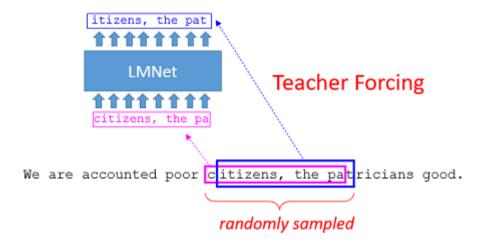
```
1 max_iters
                = 5000
 2 batch size
                = 128
 3 block size
                = 256
 4 1r
                = 5e-4
 5 max iters
                 = 8000
 6 show_interval = 200
 8 d model=256
 9 nhead=4
10 dim feedforward=512
11 num layers=6
12 vocab_size = len(vocab)
Create the model
 1 model = LMNet(vocab_size, d_model, nhead, dim_feedforward, num_layers).to(device)
```

Create the optimizer

```
1 optimizer = torch.optim.AdamW(model.parameters(), lr=lr)
```

Train the model

To train the model, we use **teacher forcing** where the predicted output is simply the 1-shifted sequence of the input sequence. We shall train the network with sentence sequence of length <code>block_size</code>. Since the network is trained on sequences of length <code>block_size</code>, during inference, the generative model should use input sequence of similar length to get good results.



During training, the network is based on the many-to-many architecture. However, during inference (Figure at generating novel text), the network is based on many-to-one architecture.