▼ Lab2A - Introduction to PyTorch

Tensor (torch.tensor) is the data structure used in PyTorch to build a deep learning system. Tensors are similar to NumPy's ndarrays, with the addition being that Tensors can also be used on a GPU to accelerate computing.

Objectives:

In this lab, you learn how to

- · Create tensors in PyTorch
- Perform mathematical operation on tensors
- Convert between PyTorch tensor and Numpy array
- Reshape a PyTorch tensor
- · Transfer tensor to and from GPU

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Reference:

• PyTorch Official Tutorial: What is PyTorch

1 import torch

▼ 1. Creating tensors

Create with some predefined value and the data type is torch.float32.

Create with some predefined value and the data type is torch.int64.

Construct a matrix filled with zeros and explicitly specify the data type as int32

Construct a matrix filled with ones and of dtype float64

Construct a tensor filled with random numbers from a uniform distribution on the interval [0, 1).

Construct a tensor filled with random numbers from a normal distribution with mean 0 and variance 1.

Construct a tensor filled with integers ranging from 0 to 9 with a shape of (5, 3). The 1st argument is the starting index (inclusive), the 2nd argument is the ending index (exclusive), and the third argument is a tuple specifying the targeted shape.

```
1 x = torch.randint(0, 10, (5, 3))
2 print(x)
```

▼ 2. Tensor Operations

Size of tensors

▼ Element-wise operations

In PyTorch, many operations, e.g., *, +, /, torch.exp, torch.log, etc., are basically element-wise operations of two arrays with the **same** shape. E.g., element-wise multiplication multiplies the items at the corresponding location.

Element-wise multiplication with the * operator

```
1 a = torch.randint(0, 10, (5,))
2 print('a:\n', a)
3
4 b = torch.randint(0, 10, (5,))
5 print('b:\n', b)
6
```

```
7 c = a * b
8 print('cb:\n', c)

a:
    tensor([9, 8, 0, 8, 2])
b:
    tensor([8, 9, 3, 5, 5])
cb:
    tensor([72, 72, 0, 40, 10])
```

Element-wise multiplication with torch.multiply function

```
1 a = torch.randint(0, 10, (5,))
2 print('a:\n', a)
3
4 b = torch.randint(0, 10, (5,))
5 print('b:\n', b)
6
7 c = torch.multiply(a, b)
8 print('c:\n', c)

a:
    tensor([4, 1, 9, 6, 8])
b:
    tensor([3, 0, 5, 8, 1])
c:
    tensor([12, 0, 45, 48, 8])
```

Element-wise multiplication with <tensor>.multiply method

```
1 a = torch.randint(0, 10, (5,))
2 print('a:', a)
3
4 b = torch.randint(0, 10, (5,))
5 print('b:', b)
6
7 c = a.multiply(b)
8 print('c:', c)
```

```
a: tensor([4, 2, 5, 3, 5])
b: tensor([2, 4, 1, 7, 9])
c: tensor([8, 8, 5, 21, 45])
```

Inplace element-wise multiplication with <tensor>.multiply_ method

```
1 a = torch.randint(0, 10, (5,))
2 print('a:', a)
3
4 b = torch.randint(0, 10, (5,))
5 print('b:', b)
6
7 b.multiply_(a)
8 print('\nInplace multiplication:')
9 print('a:', a)
10 print('b:', b)

a: tensor([8, 3, 9, 2, 0])
b: tensor([4, 0, 8, 6, 3])

Inplace multiplication:
a: tensor([8, 3, 9, 2, 0])
b: tensor([32, 0, 72, 12, 0])
```

▼ Broadcasting

Boadcasting allows element-wise operations on tensors that are not of the same size. Pytorch automatically broadcast the *smaller* tensor to the size of the *larger* tensor, if certain constraints are met.

Shape: (3, 2)		Shape: (2,)			Shape: (3, 2)		
0	1		4	5		-4	-4
2	4	-	4	5	=	-2	-1
10	10		4	5		6	5

```
1 a = torch.randint(0, 10, (3, 2))
2 print('a:\n', a)
3
4 b = torch.randint(0, 10, (2,))
5 print('b:\n', b)
7 c = a - b
8 print('\na - b:\n', c)
   a:
    tensor([[9, 9],
           [3, 9],
           [9, 2]])
   b:
    tensor([2, 1])
   a - b:
    tensor([[7, 8],
           [1, 8],
           [7, 1]])
1 a = torch.randint(0, 10, (3, 2))
2 print('a:\n', a)
3
4 b = torch.randint(0, 10, (3, 1))
5 print('b:\n', b)
7 c = a - b
8 print('\na - b:\n', c)
   a:
    tensor([[5, 0],
           [8, 1],
           [0, 6]])
   b:
    tensor([[4],
           [3],
           [4]])
   a - b:
    tensor([[ 1, -4],
```

```
[ 5, -2],
[-4, 2]])
```

▼ Matrix operations

Matrix operations are different from element-wise operation where the former is based on the rules of linear algebra.

To perform matrix operation, different from numpy, the dot command is used only to perform vector-vector multiplication (dot). Other specific commands are used for matrix-vector multiplication (mv) and matrix-matrix multiplication (mm). If you wish to perform matrix multiplication on matrices of different shape, you can use the command matmul or the @ operator.

dot

```
1 a = torch.randn(2,)
2 print('a\n', a)
3
4 b = torch.randn(2,)
5 print('b\n', b)
6
7 r = torch.dot(a, b)
8 print('r\n', r)

a
    tensor([-1.1423,  0.9024])
b
    tensor([-0.9470, -1.4128])
r
    tensor(-0.1932)
```

mν

```
1 mat = torch.randn(2, 4)
2 print('mat\n', mat)
4 vec = torch.randn(4)
5 print('vec\n', vec)
6
7 r = torch.mv(mat, vec)
8 print('r\n', r)
    mat
     tensor([[ 0.6821, 0.1801, -0.8310, -0.4715],
            [-1.5674, -0.5946, 0.6564, 2.5081]])
    vec
     tensor([-2.8798, 1.3170, -0.5992, 1.5482])
     tensor([-1.9591, 7.2202])
mm
1 mat1 = torch.randn(2, 3)
2 print('mat1\n', mat1)
4 \text{ mat2} = \text{torch.randn}(3, 4)
5 print('mat2\n', mat2)
7 r = torch.mm(mat1, mat2)
8 print('r\n', r)
    mat1
     tensor([[-0.0256, -0.4530, -1.2581],
            [-0.2969, -0.5649, 1.0206]])
    mat2
     tensor([[-0.3827, 1.5844, 0.5748, 1.4324],
            [-0.6114, -0.4763, 1.5103, 1.7844],
            [-0.0804, -0.1819, 0.9593, -0.7520]])
     tensor([[ 0.3880, 0.4041, -1.9059, 0.1011],
            [0.3770, -0.3870, -0.0448, -2.2008]])
```

```
1 r1 = torch.matmul(a, b)
2 print('r1\n', r1)
 3
4 r2 = torch.matmul(mat, vec)
5 print('r2\n', r2)
7 r3 = torch.matmul(mat1, mat2)
8 print('r3\n', r3)
    r1
     tensor(-0.1932)
    r2
     tensor([-1.9591, 7.2202])
    r3
     tensor([[ 0.3880, 0.4041, -1.9059, 0.1011],
            [ 0.3770, -0.3870, -0.0448, -2.2008]])
The @ operator
1 r1 = a @ b
2 print('r1\n', r1)
4 r2 = mat @ vec
5 print('r2\n', r2)
7 r3 = mat1 @ mat2
8 print('r3\n', r3)
    r1
     tensor(-0.1932)
    r2
     tensor([-1.9591, 7.2202])
    r3
     tensor([[ 0.3880, 0.4041, -1.9059, 0.1011],
            [ 0.3770, -0.3870, -0.0448, -2.2008]])
```

→ 3. Indexing

You can use standard Numpy-like indexing with Torch

```
1 \times = \text{torch.randint}(0, 100, (5,10))
2 print(x)
   tensor([[27, 68, 98, 80, 91, 3, 35, 18, 34, 8],
            [21, 2, 32, 34, 78, 95, 51, 33, 72, 75],
            [46, 57, 26, 11, 47, 3, 81, 28, 92, 41],
            [53, 49, 64, 47, 69, 48, 74, 33, 57, 23],
            [81, 73, 14, 6, 57, 13, 8, 79, 59, 58]])
1 # accessing column 1
2 print(x[:,1])
   tensor([68, 2, 57, 49, 73])
1 # accessing columns 2 and 3
2 print(x[:, 2:4])
   tensor([[98, 80],
            [32, 34],
            [26, 11],
            [64, 47],
            [14, 6]])
1 # accessing row 1
2 print(x[1,:])
   tensor([21, 2, 32, 34, 78, 95, 51, 33, 72, 75])
1 # accessing rows 2 and 3
2 print(x[2:4,:])
   tensor([[46, 57, 26, 11, 47, 3, 81, 28, 92, 41],
            [53, 49, 64, 47, 69, 48, 74, 33, 57, 23]])
```

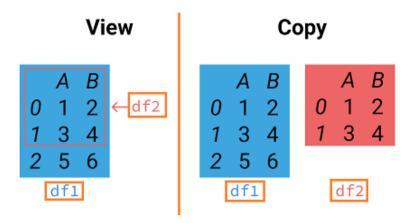
▼ 4. Reshaping Tensors

Tensor.reshape

Returns a tensor with the same data and number of elements as self but with the specified shape.

```
1 \times = \text{torch.randint}(0, 100, (2,4))
2 print('x:\n', x)
    x:
     tensor([[50, 46, 80, 73],
            [70, 12, 47, 47]])
1 # Reshape from (2, 4) to (8, 1)
2 y = x.reshape(8, -1)
3 print('y:\n', y)
   у:
     tensor([[50],
            [46],
            [80],
            [73],
            [70],
            [12],
            [47],
            [47]])
1 # Reshape from (2, 4) to (4, 2)
2z = x.reshape(4, 2)
3 print('z:\n', z)
     tensor([[50, 46],
            [80, 73],
            [70, 12],
            [47, 47]])
```

This method returns a **view** if shape is compatible with the current shape. Else, it may return a **copy**. This allows it to work with both <u>contiguous</u> and <u>non-contiguous</u> data.



In the examples above, we create a view since the shapes of reshaped tensors y and z are compatible with the original tensor x. Note that after a change is performed on x, then the changes will occur to both y and z.

The following code confirms that y and z are indeed views of x. Any changes to x will be observed in y and z as well.

```
1 \times [0,0] = -3
3 print('x:\n', x)
4 print('y:\n', y)
5 print('z:\n', z)
    х:
     tensor([[-3, 46, 80, 73],
            [70, 12, 47, 47]])
    у:
     tensor([[-3],
            [46],
            [80],
            [73],
            [70],
            [12],
            [47],
            [47]])
     tensor([[-3, 46],
            [80, 73],
            [70, 12],
            [47, 47]])
```

To check if two tensors have the same base content, use the command data_ptr()

```
1 y.data_ptr() == x.data_ptr()
True
```

Example of use of reshape that results in a copy

```
1 p = x.T.reshape(-1)
2
3 p.data_ptr() == x.data_ptr()
False
```

Tensor.view

Tensor.view always returns a view of the original tensor with the new shape, i.e., it will share the underlying data with the original tensor.

Similar to the numpy's reshape function, pytorch's view returns a reference of the original matrix albeit in a different shape

▼ 5. CUDA Tensors

Creating tensor in the GPU

▼ Creating tensor in the cpu explicitly (default)

▼ Transfering tensor from cpu to gpu

Transfer using the .cuda() command.

```
1 x = torch.rand(3, 2, device = "cpu") # create tensor in cpu. The device argument also accepts a string besides a device object
 2 print(x)
 4 \times = x.cuda() # move to GPU
 5 print(x)
    tensor([[0.1697, 0.0962],
             [0.7331, 0.6139],
             [0.5735, 0.4806]])
    tensor([[0.1697, 0.0962],
             [0.7331, 0.6139],
             [0.5735, 0.4806]], device='cuda:0')
Transfer using the .to() command
 1 x = torch.rand(3, 2) # create tensor in the CPU (default)
 2 print(x)
 4 gpu = torch.device('cuda') # move to GPU
 5 x = x.to(gpu)
 6 print(x)
    tensor([[0.6615, 0.6024],
             [0.3098, 0.0767],
             [0.5146, 0.0107]])
    tensor([[0.6615, 0.6024],
             [0.3098, 0.0767],
             [0.5146, 0.0107]], device='cuda:0')
```

▼ Transfering tensor from gpu to cpu

Transfer using the .cpu() command.

```
1 x = torch.rand(3, 2, device = 'cuda') # create tensor in gpu. The device argument also accepts a string besides a device object
 2 print(x)
 4 \times = x.cpu() # move to CPU
 5 print(x)
    tensor([[0.8319, 0.3893],
             [0.3291, 0.6083],
             [0.1008, 0.6127]], device='cuda:0')
    tensor([[0.8319, 0.3893],
             [0.3291, 0.6083],
             [0.1008, 0.6127]])
Transfer using the .to() command.
 1 x = torch.rand(3, 2, device = 'cuda') # create tensor in the GPU
 2 print(x)
 4 device = torch.device('cpu')
 5 x = x.to(device) # move to CPU
 6 print(x)
    tensor([[0.4656, 0.7950],
             [0.9062, 0.2038],
             [0.2981, 0.6544]], device='cuda:0')
    tensor([[0.4656, 0.7950],
             [0.9062, 0.2038],
             [0.2981, 0.6544]])
```

▼ Exercise

Question 1. The following code is used to preprocess a batch data for Logistic Regression.

1.1 Create a random tensor X_ori using the normal distribution of shape (4, 16, 16, 3). The tensor represent m=4 color image samples, each having a resolution of (16, 16). Expected ans: Shape of X_ori: torch.Size([4, 16, 16, 3])

```
2 print('Shape of X_ori:', X_ori.shape)
```

Double-click (or enter) to edit

1.2 Reshape X_{ori} into a shape of (4, 16*16*3). Then transpose the result to get a tensor of shape (768, 4) where each column represents a sample. Save the result as X.

Expected ans:

```
Shape of X: torch.Size([768, 4])
1 ...
2 print('Shape of X:', X.shape)
```

1.3 Check if a GPU is available in the system. If yes, transfer the tensor x to the GPU. Then, verify if X has really been loaded into the GPU ($x.is_cuda$) and print out the device ID of the GPU ($x.get_device$ ()).

Expected ans:

```
X is loaded to GPU: 0

1 if ...gpu is available...
2    ... load x to gpu ...
3
4 if ...x is successfully loaded into GPU:
5    print('X is loaded to GPU:', ... get the GPU ID...)
6 else:
7    print('X is loaded to CPU')
```

Question 2.

2.1 Create the tensor A. Ensure that the datatype for A is float32.

```
A = [[3, 2, 4, 6],
         [2, 4, 2, 2],
         [5, 1, 2, 1]]
1 ...
2 print(A)
2.2 Extract the 2nd row from A. (Expected ans: tensor([2., 4., 2., 2.])).
1 print(...)
2.3 Extract the 3rd column from A. (Expected ans: tensor([4., 2., 2.])).
1 print(...)
2.4 Write the code to extract the following sub-block (rows 1 to 2 and columns 1 to 2) from A.
tensor([[4., 2.],
        [1., 2.]])
1 print(...)
2.5 Compute the mean of the rows.
Expected ans:
tensor([3.7500, 2.5000, 2.2500], dtype=torch.float64)
1 print(...)
```

2.6 Repeat question 2.5, but this time retain the original dimensions such that the output has a shape of (3,1).

Expected ans:

--- END OF LAB02A ---