# Lab2A - Introduction to PyTorch

Tensor (torch.tensor) is the data structure used in PyTorch to build a deep learning system. Tensors are similar to NumPy's ndarrays, with the addition being that Tensors can also be used on a GPU to accelerate computing.

## Objectives:

In this lab, you learn how to

- Create tensors in PyTorch
- Perform mathematical operation on tensors
- Convert between PyTorch tensor and Numpy array
- Reshape a PyTorch tensor
- Transfer tensor to and from GPU

#### Table of Content:

- 1. Creating tensors
- 2. Tensor operations
- 3. Indexing
- 4. Reshaping tensors
- 5. CUDA Tensors
- 6. Exercise

#### Reference:

• PyTorch Official Tutorial: What is PyTorch

1 import torch

# ▼ 1. Creating tensors

Create with some predefined value. The following also shows another way to ensure that datatype (.dtype) is torch.float32.

Construct a matrix filled with zeros and of dtype int32

Construct a matrix filled with ones and of dtype float64

Construct a tensor filled with random numbers from a uniform distribution on the interval [0, 1).

Construct a tensor filled with random numbers from a normal distribution with mean 0 and variance 1.

Construct a tensor filled with integers ranging from 0 to 9 with a shape of (5, 3). The 1st argument is the starting index (inclusive), the 2nd argument is the ending index (exclusive), and the third argument is a tuple specifying the targeted shape.

# ▼ 2. Tensor Operations

Size of tensors

```
Shape of x: torch.Size([5, 3])
Shape of x: torch.Size([5, 3])
```

### ▼ Element-wise operations

In PyTorch, many operations, e.g., \*, +, /, torch.exp, torch.log, etc., are basically element-wise operations of two arrays with the **same** shape. E.g., element-wise multiplication multiplies the items at the corresponding location.

Element-wise multiplication with the \* operator

```
1 a = torch.randint(0, 10, (5,))
2 print('a:\n', a)
3
4 b = torch.randint(0, 10, (5,))
5 print('b:\n', b)
6
7 c = a * b
8 print('cb:\n', c)

a:
    tensor([6, 6, 1, 7, 1])
    b:
    tensor([4, 6, 0, 4, 9])
    cb:
    tensor([24, 36, 0, 28, 9])
```

Element-wise multiplication with torch.multiply function

```
1 a = torch.randint(0, 10, (5,))
2 print('a:\n', a)
3
4 b = torch.randint(0, 10, (5,))
5 print('b:\n', b)
6
7 c = torch.multiply(a, b)
8 print('c:\n', c)

a:
    tensor([2, 8, 3, 2, 8])
b:
    tensor([7, 5, 8, 8, 1])
```

```
c:
tensor([14, 40, 24, 16, 8])
```

Element-wise multiplication with <tensor>.multiply method

```
1 a = torch.randint(0, 10, (5,))
2 print('a:', a)
3
4 b = torch.randint(0, 10, (5,))
5 print('b:', b)
6
7 c = a.multiply(b)
8 print('c:', c)
    a: tensor([1, 7, 3, 0, 6])
    b: tensor([4, 5, 8, 9, 4])
    c: tensor([ 4, 35, 24, 0, 24])
```

Inplace element-wise multiplication with <tensor>.multiply method

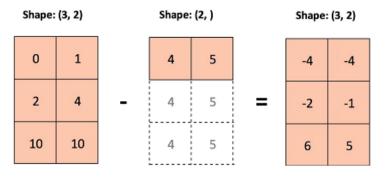
```
1 a = torch.randint(0, 10, (5,))
2 print('a:', a)
3
4 b = torch.randint(0, 10, (5,))
5 print('b:', b)
6
7 b.multiply_(a)
8 print('\nInplace multiplication:')
9 print('a:', a)
10 print('b:', b)

a: tensor([1, 7, 9, 3, 2])
b: tensor([0, 7, 7, 0, 3])

Inplace multiplication:
    a: tensor([1, 7, 9, 3, 2])
    b: tensor([0, 49, 63, 0, 6])
```

## ▼ Broadcasting

Boadcasting allows element-wise operations on tensors that are not of the same size. Pytorch automatically broadcast the *smaller* tensor to the size of the *larger* tensor, if certain constraints are met.



```
1 a = torch.randint(0, 10, (3, 2))
2 print('a:\n', a)
4 b = torch.randint(0, 10, (2,))
5 print('b:\n', b)
6
7 c = a - b
8 print('\na - b:\n', c)
    a:
    tensor([[3, 6],
            [1, 2],
            [2, 0]])
    b:
    tensor([7, 9])
    a - b:
    tensor([[-4, -3],
            [-6, -7],
            [-5, -9]])
1 a = torch.randint(0, 10, (3, 2))
2 print('a:\n', a)
4 b = torch.randint(0, 10, (3, 1))
5 print('b:\n', b)
6
7 c = a - b
8 print('\na - b:\n', c)
```

## ▼ Matrix operations

Matrix operations are different from element-wise operation where the former is based on the rules of linear algebra.

To perform matrix operation, different from numpy, the dot command is used only to perform vector-vector multiplication (dot). Other specific commands are used for matrix-vector multiplication (mv) and matrix-matrix multiplication (mm). If you wish to perform matrix multiplication on matrices of different shape, you can use the command matmul or the @ operator.

dot

```
1 a = torch.Tensor([4, 2])
2 b = torch.Tensor([3, 1])
3 r = torch.dot(a, b)
4
5 print(r)
    tensor(14.)

mv

1 mat = torch.randn(2, 4)
2 vec = torch.randn(4)
3 r = torch.mv(mat, vec)
4 print(r)
    tensor([0.4885, 2.9056])
```

```
mm
```

```
1 \text{ mat1} = \text{torch.randn}(2, 3)
2 \text{ mat2} = \text{torch.randn}(3, 4)
3 r = torch.mm(mat1, mat2)
 4
 5 print(r)
    tensor([[-0.4559, -2.4688, -1.7561, 2.0766],
             [-0.3222, -1.2150, -7.6438, 3.0513]])
matmul
1 r1 = torch.matmul(a, b)
2 r2 = torch.matmul(mat, vec)
3 r3 = torch.matmul(mat1, mat2)
 5 print(r1)
6 print(r2)
7 print(r3)
    tensor(14.)
    tensor([0.4885, 2.9056])
    tensor([[-0.4559, -2.4688, -1.7561, 2.0766],
             [-0.3222, -1.2150, -7.6438, 3.0513]])
The @ operator
1 r1 = a @ b
2 r2 = mat @ vec
3 r3 = mat1 @ mat2
 4
5 print(r1)
 6 print(r2)
7 print(r3)
    tensor(14.)
    tensor([0.4885, 2.9056])
    tensor([[-0.4559, -2.4688, -1.7561, 2.0766],
             [-0.3222, -1.2150, -7.6438, 3.0513]])
```

# ▼ 3. Indexing

You can use standard Numpy-like indexing with Torch

```
1 \times = \text{torch.randint}(0, 100, (5,10))
2 print(x)
    tensor([[27, 68, 98, 80, 91, 3, 35, 18, 34, 8],
            [21, 2, 32, 34, 78, 95, 51, 33, 72, 75],
            [46, 57, 26, 11, 47, 3, 81, 28, 92, 41],
            [53, 49, 64, 47, 69, 48, 74, 33, 57, 23],
            [81, 73, 14, 6, 57, 13, 8, 79, 59, 58]])
1 # accessing column 1
2 print(x[:,1])
    tensor([68, 2, 57, 49, 73])
1 # accessing columns 2 and 3
2 print(x[:, 2:4])
    tensor([[98, 80],
            [32, 34],
            [26, 11],
            [64, 47],
            [14, 6]])
1 # accessing row 1
2 print(x[1,:])
    tensor([21, 2, 32, 34, 78, 95, 51, 33, 72, 75])
1 # accessing rows 2 and 3
2 print(x[2:4,:])
    tensor([[46, 57, 26, 11, 47, 3, 81, 28, 92, 41],
            [53, 49, 64, 47, 69, 48, 74, 33, 57, 23]])
```

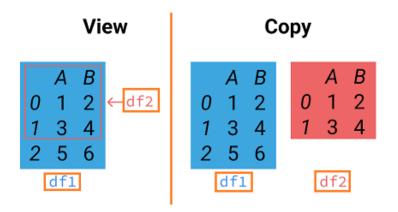
# ▼ 4. Reshaping Tensors

#### Tensor.reshape

Returns a tensor with the same data and number of elements as self but with the specified shape.

```
1 \times = \text{torch.randint}(0, 100, (2,4))
2 print('x:\n', x)
    х:
     tensor([[50, 46, 80, 73],
            [70, 12, 47, 47]])
1 # Reshape from (2, 4) to (8, 1)
2 y = x.reshape(8, -1)
3 print('y:\n', y)
    у:
     tensor([[50],
             [46],
             [80],
            [73],
             [70],
            [12],
             [47],
            [47]])
1 # Reshape from (2, 4) to (4, 2)
2z = x.reshape(4, 2)
3 print('z:\n', z)
    z:
     tensor([[50, 46],
            [80, 73],
            [70, 12],
            [47, 47]])
```

This method returns a **view** if shape is compatible with the current shape. Else, it may return a **copy**. This allows it to work with both <u>contiguous</u> and <u>non-contigous</u> data.



In the examples above, we create a view since the shapes of reshaped tensors y and z are compatible with the original tensor x. Note that after a change is performed on x, then the changes will occur to both y and z.

The following code confirms that y and z are indeed views of x. Any changes to x will be observed in y and z as well.

```
1 \times [0,0] = -3
3 print('x:\n', x)
4 print('y:\n', y)
5 print('z:\n', z)
    х:
     tensor([[-3, 46, 80, 73],
             [70, 12, 47, 47]])
    у:
     tensor([[-3],
             [46],
             [80],
             [73],
             [70],
             [12],
             [47],
             [47]])
    z:
     tensor([[-3, 46],
             [80, 73],
             [70, 12],
             [47, 47]])
```

To check if two tensors have the same base content, use the command data\_ptr()

```
1 y.data_ptr() == x.data_ptr()
True
```

Example of use of reshape that results in a copy

```
1 p = x.T.reshape(-1)
2
3 p.data_ptr() == x.data_ptr()
False
```

#### Tensor.view

Tensor.view always returns a **view** of the original tensor with the new shape, i.e., it will share the underlying data with the original tensor.

```
1 \times = \text{torch.randint}(0, 100, (2, 4))
2 print('x:\n', x)
     tensor([[37, 39, 67, 95],
            [46, 47, 98, 69]])
1 # Convert from (2, 4) to (8, 1)
2 y = x.view(8, -1)
3 print('y:\n', y)
    у:
     tensor([[37],
             [39],
            [67],
             [95],
             [46],
             [47],
             [98],
             [69]])
1 # Convert from (2, 4) to (4, 2)
2 z = x.view(4, 2)
```

Similar to the numpy's reshape function, pytorch's view returns a reference of the original matrix albeit in a different shape

## ▼ 5. CUDA Tensors

Creating tensor in the GPU

▼ Creating tensor in the cpu explicitly (default )

▼ Transfering tensor from cpu to gpu

Transfer using the .cuda() command.

```
3
    4 \times = x.cuda() # move to GPU
    5 print(x)
       tensor([[0.1697, 0.0962],
                [0.7331, 0.6139],
                [0.5735, 0.4806]])
       tensor([[0.1697, 0.0962],
                [0.7331, 0.6139],
                [0.5735, 0.4806]], device='cuda:0')
   Transfer using the .to() command
   1 x = torch.rand(3, 2) # create tensor in the CPU (default)
    2 print(x)
    3
    4 gpu = torch.device('cuda') # move to GPU
    5 x = x.to(gpu)
    6 print(x)
       tensor([[0.6615, 0.6024],
                [0.3098, 0.0767],
                [0.5146, 0.0107]])
       tensor([[0.6615, 0.6024],
                [0.3098, 0.0767],
                [0.5146, 0.0107]], device='cuda:0')
▼ Transfering tensor from gpu to cpu
  Transfer using the .cpu() command.
```

```
1 x = torch.rand(3, 2, device = 'cuda') # create tensor in gpu. The device argument also accepts a string besides a device object
2 print(x)
4 \times = x.cpu() # move to CPU
5 print(x)
    tensor([[0.8319, 0.3893],
            [0.3291, 0.6083],
            [0.1008, 0.6127]], device='cuda:0')
    tensor([[0.8319, 0.3893],
```

```
[0.3291, 0.6083], [0.1008, 0.6127]])
```

Transfer using the .to() command.

## ▼ Exercise

Question 1. The following code is used to preprocess a batch data for Logistic Regression.

1.1 Create a random tensor  $X_{ori}$  using the normal distribution of shape (4, 16, 16, 3). The tensor represent m=4 color image samples, each having a resolution of (16, 16) Expected ans: Shape of  $X_{ori}$ : torch.Size([4, 16, 16, 3])

```
1 ...
2 print('Shape of X_ori:', X_ori.shape)
```

Double-click (or enter) to edit

1.2 Reshape  $X_{ori}$  into a shape of (4, 16\*16\*3). Then transpose the result to get a tensor of shape (768, 4) where each column represents a sample. Save the result as X.

Expected ans:

```
Shape of X: torch.Size([768, 4])
1 ...
2 print('Shape of X:', X.shape)
```

1.3 Check if a GPU is available in the system. If yes, transfer the tensor x to the GPU. Then, verify if X has really been loaded into the GPU ( $X.is\_cuda$ ) and print out the device ID of the GPU ( $X.get\_device$ ()).

Expected ans:

```
X is loaded to GPU: 0

1 if ...gpu is available...
2    ... load x to gpu ...
3
4 if ...x is successfully loaded into GPU:
5    print('X is loaded to GPU:', ... get the GPU ID...)
6 else:
7    print('X is loaded to CPU')
```

#### Question 2.

2.1 Create the tensor A. Ensure that the datatype for A is float32:

2.2 Extract the 2nd row from A. (Expected ans: tensor([2., 4., 2., 2.]))

```
1 print(...)
2.3 Extract the 3rd column from A. (Expected ans: tensor([4., 2., 2.]))
1 print(...)
2.4 Write the code to extract the following sub-block (rows 1 to 2 and columns 1 to 2) from A.
tensor([[4., 2.],
        [1., 2.]])
1 print(...)
2.5 Compute the mean of all columns.
Expected ans:
 tensor([3.7500, 2.5000, 2.2500], dtype=torch.float64)
1 print(...)
2.6 Repeat question 2.5, but this time retain the original dimensions such that the output has a shape of (3,1)
Expected ans:
 tensor([[3.7500],
        [2.5000],
        [2.2500]], dtype=torch.float64)
1 print(...)
```

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