Lab 6A: CNN Architectures and Transfer Learning (Guide)

The learning objectives for this lab exercise are as follows:

- 1. Customize the standard CNN Network to a targeted task
- 2. Perform different kinds of transfer learning:
 - A. Train from scratch
 - B. Finetune the whole model
 - C. Finetune the upper layers of the model
 - D. As a feature extractor

In practice, it is common to use a **standard CNN architectures** such that ResNet, MNASNet, ResNeXt, EfficientNet, etc. to build a model. The effectiveness of these network architectures has been well attested for a wide range of applications.

Rather than training from scratch, it is advisable to use **transfer learning** by training on top of a standard model that has been **pretrained** on the ImageNet dataset. Transfer learning reduces overfitting and improves the generalization performance of the trained model, especially when the training set for the targeted task is small. The torchvision.models package contains these different network models that have been pre-trained on ImageNet.

We perform transfer learning in two ways:

- 1. Finetuning the convnet. Instead of random initialization, initialize the network with the pretrained network.
- 2. Fixed feature extractor: Freeze the weights for all of the layers of the network except for the final fully connected (fc) layer. Replace the last fc layer so that the output size is the same as the number of classes for the new task. The new layer is initialized with random weights and only this layer is trained.

Mount google drive onto virtual machine

```
from google.colab import drive
    drive.mount('/content/gdrive')
```

Mounted at /content/gdrive

Change current directory to Lab 6

```
In []: cd "/content/gdrive/My Drive/UCCD3074_Labs/UCCD3074_Lab6"

/content/gdrive/My Drive/UCCD3074_Labs/UCCD3074_Lab6

Load required libraries

In [1]: import numpy as np import torchvision.models as models

import torch, torchvision import torch.nn as nn import torch.nn.functional as F import torch.optim as optim from torch.utils.data import DataLoader import torchvision.transforms as transforms

from cifar10 import CIFAR10
```

Helper Functions

Define the train function

```
In [2]: loss_iter = 1

def train(net, num_epochs, lr=0.1, momentum=0.9, verbose=True):
    history = []
    loss_iterations = int(np.ceil(len(trainloader)/loss_iter))

# transfer model to GPU
if torch.cuda.is_available():
    net = net.cuda()

# set the optimizer
optimizer = optim.SGD(net.parameters(), lr=lr, momentum=momentum)

# set to training mode
net.train()

# train the network
```

```
for e in range(num epochs):
    running loss = 0.0
    running_count = 0.0
    for i, (inputs, labels) in enumerate(trainloader):
        # Clear all the gradient to 0
        optimizer.zero_grad()
        # transfer data to GPU
        if torch.cuda.is available():
            inputs = inputs.cuda()
            labels = labels.cuda()
        # forward propagation to get h
        outs = net(inputs)
        # compute Loss
       loss = F.cross_entropy(outs, labels)
        # backpropagation to get dw
       loss.backward()
        # update w
        optimizer.step()
        # get the loss
        running_loss += loss.item()
        running count += 1
         # display the averaged loss value
       if i % loss_iterations == loss_iterations-1 or i == len(trainloader) - 1:
            train_loss = running_loss / running_count
            running_loss = 0.
            running count = 0.
            if verbose:
                print(f'[Epoch {e+1:2d}/{num epochs:d} Iter {i+1:5d}/{len(trainloader)}]: train loss = {train loss:.4f}')
            history.append(train_loss)
return history
```

```
In [3]: def evaluate(net):
            # set to evaluation mode
            net.eval()
            # running correct
            running corrects = 0
            for inputs, targets in testloader:
                # transfer to the GPU
                if torch.cuda.is available():
                    inputs = inputs.cuda()
                    targets = targets.cuda()
                # perform prediction (no need to compute gradient)
                with torch.no_grad():
                    outputs = net(inputs)
                    , predicted = torch.max(outputs, 1)
                    running corrects += (targets == predicted).double().sum()
            print('Accuracy = {:.2f}%'.format(100*running corrects/len(testloader.dataset)))
```

1. Load CIFAR10 dataset

Here, we use a sub-sample of CIFAR10 where we use a sub-sample of 1000 training and testing samples. The sample size is small and hence is expected to face overfitting issue. Using a pretrained model alleviates the problem.

Files already downloaded and verified Files already downloaded and verified

2. The ResNet50 model

In this section, we shall build our network using a standard network architectures. We customize a pre-trained ResNet50 by replacing its classifier layer, i.e., the last fully connected layer with our own. The original ImageNet classifier is designed to classify 1000 output classes whereas our CIFAR10 classifier handles only 10 classes.

Using the pre-trained models

First, let's learn how to load and use a pre-trained model as it is. The following table lists the pretrained models for ResNet50 together their reported accurcies on ImageNet-1K with single crops.

weight	Acc@1	Acc@5	Params
ResNet50_Weights.IMAGENET1K_V1	76.13	92.862	25.6MB
ResNet50_Weights.IMAGENET1K_V2	80.858	95.434	25.6MB

where IMAGENET1K_V2 improves upon IMAGENET1K_V1 by using a new training recipe

To specify the pretrained model, you can use the predefined constant:

Inferencing with the pretrained model

Some pretrained model needs specific preprocessing steps (e.g., resize into a specific resolution / rescale the values, etc.). The preprocessing steps vary depending on how the model was trained. The necessary information for inference transforms are provided on the weight documentation. But to simplify inference, TorchVision also bundle a transform utility into ResNet.Weights.

```
weight = ResNet50 Weights.IMAGENET1K V2
 In [8]:
          preprocess = weight.transforms()
In [9]: from torchvision.io import read image
         img = read image('img1.jpg')
          print('Shape of x (before preprocessing)', img.shape)
          x = preprocess(img)
          print('Shape of x after preprocessing:', x.shape)
          x = x.unsqueeze(0)
          print('Shape of x after unsqueezing:', x.shape)
         Shape of x (before preprocessing) torch.Size([3, 162, 288])
         Shape of x after preprocessing: torch.Size([3, 224, 224])
         Shape of x after unsqueezing: torch.Size([1, 3, 224, 224])
         Perform inference with the pretrained model. The classes of the pretrained model can be found at weights.meta['categories'].
        net.eval()
In [10]:
          with torch.no grad():
             score = net(x)
             predicted = score.argmax(axis=1)[0]
          print('Predicted label =', weight.meta['categories'][predicted])
         Predicted label = tabby
```

Customizing ResNet50

In the following, we shall replace the last layer with a new classifier layer. The pre-trained model is designed to classify ImageNet's 1000 image categories. In the following, we shall customize it to classify Cifar10's 10 classes. First, let's look at how ResNet50 is implemented in PyTorch.

```
In [11]: print(net)
```

```
ResNet(
  (conv1): Conv2d(3, 64, kernel size=(7, 7), stride=(2, 2), padding=(3, 3), bias=False)
  (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (relu): ReLU(inplace=True)
  (maxpool): MaxPool2d(kernel size=3, stride=2, padding=1, dilation=1, ceil mode=False)
  (layer1): Sequential(
    (0): Bottleneck(
      (conv1): Conv2d(64, 64, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
      (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
      (conv3): Conv2d(64, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
      (relu): ReLU(inplace=True)
      (downsample): Sequential(
        (0): Conv2d(64, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
        (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (1): Bottleneck(
      (conv1): Conv2d(256, 64, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
      (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
      (conv3): Conv2d(64, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
      (relu): ReLU(inplace=True)
    (2): Bottleneck(
      (conv1): Conv2d(256, 64, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
      (conv2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
      (conv3): Conv2d(64, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
      (relu): ReLU(inplace=True)
    )
 (layer2): Sequential(
    (0): Bottleneck(
      (conv1): Conv2d(256, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
      (conv2): Conv2d(128, 128, kernel_size=(3, 3), stride=(2, 2), padding=(1, 1), bias=False)
      (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
      (conv3): Conv2d(128, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
      (bn3): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
```

```
(relu): ReLU(inplace=True)
    (downsample): Sequential(
      (0): Conv2d(256, 512, kernel size=(1, 1), stride=(2, 2), bias=False)
      (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (1): Bottleneck(
    (conv1): Conv2d(512, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
    (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
    (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (conv3): Conv2d(128, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
    (bn3): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (relu): ReLU(inplace=True)
  (2): Bottleneck(
    (conv1): Conv2d(512, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
    (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
    (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (conv3): Conv2d(128, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
    (bn3): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (relu): ReLU(inplace=True)
  (3): Bottleneck(
    (conv1): Conv2d(512, 128, kernel size=(1, 1), stride=(1, 1), bias=False)
    (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
    (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (conv3): Conv2d(128, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
    (bn3): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (relu): ReLU(inplace=True)
(layer3): Sequential(
 (0): Bottleneck(
    (conv1): Conv2d(512, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
    (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), bias=False)
    (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (conv3): Conv2d(256, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
    (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (relu): ReLU(inplace=True)
    (downsample): Sequential(
      (0): Conv2d(512, 1024, kernel size=(1, 1), stride=(2, 2), bias=False)
      (1): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
```

```
(1): Bottleneck(
 (conv1): Conv2d(1024, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
  (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
  (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (conv3): Conv2d(256, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
 (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (relu): ReLU(inplace=True)
(2): Bottleneck(
  (conv1): Conv2d(1024, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
  (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
  (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (conv3): Conv2d(256, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
 (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
 (relu): ReLU(inplace=True)
(3): Bottleneck(
 (conv1): Conv2d(1024, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
 (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
  (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (conv3): Conv2d(256, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
  (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
 (relu): ReLU(inplace=True)
(4): Bottleneck(
  (conv1): Conv2d(1024, 256, kernel size=(1, 1), stride=(1, 1), bias=False)
  (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
  (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
 (conv3): Conv2d(256, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
  (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (relu): ReLU(inplace=True)
(5): Bottleneck(
  (conv1): Conv2d(1024, 256, kernel_size=(1, 1), stride=(1, 1), bias=False)
 (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (conv2): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
  (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (conv3): Conv2d(256, 1024, kernel size=(1, 1), stride=(1, 1), bias=False)
  (bn3): BatchNorm2d(1024, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (relu): ReLU(inplace=True)
```

```
(laver4): Sequential(
            (0): Bottleneck(
              (conv1): Conv2d(1024, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
              (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
              (conv2): Conv2d(512, 512, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), bias=False)
              (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
              (conv3): Conv2d(512, 2048, kernel size=(1, 1), stride=(1, 1), bias=False)
              (bn3): BatchNorm2d(2048, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
              (relu): ReLU(inplace=True)
              (downsample): Sequential(
                (0): Conv2d(1024, 2048, kernel size=(1, 1), stride=(2, 2), bias=False)
                (1): BatchNorm2d(2048, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
            (1): Bottleneck(
              (conv1): Conv2d(2048, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
              (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
              (conv2): Conv2d(512, 512, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
              (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
              (conv3): Conv2d(512, 2048, kernel size=(1, 1), stride=(1, 1), bias=False)
              (bn3): BatchNorm2d(2048, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
              (relu): ReLU(inplace=True)
            (2): Bottleneck(
              (conv1): Conv2d(2048, 512, kernel size=(1, 1), stride=(1, 1), bias=False)
              (bn1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
              (conv2): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
              (bn2): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
              (conv3): Conv2d(512, 2048, kernel size=(1, 1), stride=(1, 1), bias=False)
              (bn3): BatchNorm2d(2048, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
              (relu): ReLU(inplace=True)
          (avgpool): AdaptiveAvgPool2d(output size=(1, 1))
          (fc): Linear(in features=2048, out features=1000, bias=True)
        for name, _ in net.named_children():
In [ ]:
            print(name)
```

```
conv1
bn1
relu
maxpool
layer1
layer2
layer3
layer4
avgpool
fc
```

Here are some observations:

- conv1, bn1, relu and maxpool are the stem network
- There are 4 blocks in the network, namely layer1, layer2, layer3 and layer4.
- Each of the block contains two convolutional layers.
- The second last layer (avgpool) performs global average pooling to average out the spatial dimensions.
- The last layer (fc) is a linear layer that functions as a classifier. This is the layer that we want to replace to fit our model.

To customize the network, we need to replace the fc layer with our own classifier layer.

```
In [ ]: def build_network(weights=None):
    net = resnet50(weights=weights)
    in_c = net.fc.in_features
    net.fc = nn.Linear(in_c, 10)
    return net
```

Let's visualize what we have built. Note that the last layer of the network (fc) now has 10 instead of 1000 neurons.

```
In [ ]: print(build_network())
```

Model 1: Training from scratch

Let's build the network **without** loading the pretrained model. To do this, we set weights=None.

```
In [ ]: net1 = build_network(weights=None)
```

Train the model and save the training loss history into history1.

```
history1 = train(net1, num epochs=30, lr=0.01, momentum=0.8)
        [Epoch 1/30 Iter
                              32/32]: train loss = 4.4605
        [Epoch 2/30 Iter
                              32/32]: train loss = 2.8071
        [Epoch 3/30 Iter
                              32/321: train loss = 2.6078
        [Epoch 4/30 Iter
                              32/32]: train loss = 2.2501
        [Epoch 5/30 Iter
                              32/32]: train loss = 2.1665
        [Epoch 6/30 Iter
                              32/32]: train loss = 2.0636
        [Epoch 7/30 Iter
                              32/321: train loss = 2.0430
        [Epoch 8/30 Iter
                              32/32]: train loss = 1.9960
                             32/32]: train_loss = 1.9771
        [Epoch 9/30 Iter
        [Epoch 10/30 Iter
                              32/32]: train loss = 1.8862
                              32/32]: train loss = 1.9134
        [Epoch 11/30 Iter
        [Epoch 12/30 Iter
                              32/32]: train loss = 1.8538
        [Epoch 13/30 Iter
                             32/32]: train loss = 1.8350
        [Epoch 14/30 Iter
                              32/32]: train loss = 1.8004
        [Epoch 15/30 Iter
                              32/32]: train loss = 1.7669
        [Epoch 16/30 Iter
                              32/32]: train loss = 1.6987
        [Epoch 17/30 Iter
                              32/32]: train loss = 1.7374
        [Epoch 18/30 Iter
                              32/32]: train_loss = 1.6700
                              32/32]: train loss = 1.7457
        [Epoch 19/30 Iter
                              32/32]: train loss = 1.6286
        [Epoch 20/30 Iter
        [Epoch 21/30 Iter
                              32/32]: train loss = 1.6843
        [Epoch 22/30 Iter
                              32/32]: train loss = 1.5599
        [Epoch 23/30 Iter
                              32/32]: train loss = 1.5442
        [Epoch 24/30 Iter
                              32/32]: train loss = 1.5833
        [Epoch 25/30 Iter
                              32/32]: train loss = 1.5343
        [Epoch 26/30 Iter
                              32/32]: train loss = 1.5184
        [Epoch 27/30 Iter
                              32/32]: train loss = 1.5077
                             32/32]: train loss = 1.4209
        [Epoch 28/30 Iter
        [Epoch 29/30 Iter
                             32/32]: train_loss = 1.4528
        [Epoch 30/30 Iter
                             32/32]: train loss = 1.4286
        Evaluate the model
        evaluate(net1)
In [ ]:
        Accuracy = 40.50\%
```

Model 2: Finetuning the pretrained model

Typically, a standard network come with a pretrained model trained on ImageNet's large-scale dataset for the image classification task.

- In the following, we shall load resnet50 with the pretrained model and use it to **initialize** the network. To do this, we set weights='IMAGENET1K V2'.
- The training will update the parameters **all layers** of the network.

For Windows system, the pretrained model will be saved to the following directory: C:\Users\<user name>\.cache\torch\checkpoints . A PyTorch model has an extension of .pt or .pth .

conv1.weight : True bn1.weight : True bn1.bias : True laver1.0.conv1.weight : True layer1.0.bn1.weight : True layer1.0.bn1.bias : True layer1.0.conv2.weight : True layer1.0.bn2.weight : True layer1.0.bn2.bias : True layer1.0.conv3.weight : True layer1.0.bn3.weight : True layer1.0.bn3.bias : True layer1.0.downsample.0.weight : True layer1.0.downsample.1.weight : True layer1.0.downsample.1.bias : True layer1.1.conv1.weight : True layer1.1.bn1.weight : True layer1.1.bn1.bias : True layer1.1.conv2.weight : True layer1.1.bn2.weight : True layer1.1.bn2.bias : True layer1.1.conv3.weight : True layer1.1.bn3.weight : True layer1.1.bn3.bias : True layer1.2.conv1.weight : True layer1.2.bn1.weight : True layer1.2.bn1.bias : True layer1.2.conv2.weight : True layer1.2.bn2.weight : True layer1.2.bn2.bias : True layer1.2.conv3.weight : True layer1.2.bn3.weight : True layer1.2.bn3.bias : True layer2.0.conv1.weight : True layer2.0.bn1.weight : True layer2.0.bn1.bias : True layer2.0.conv2.weight : True layer2.0.bn2.weight : True layer2.0.bn2.bias : True layer2.0.conv3.weight : True layer2.0.bn3.weight : True layer2.0.bn3.bias : True layer2.0.downsample.0.weight : True layer2.0.downsample.1.weight : True layer2.0.downsample.1.bias : True layer2.1.conv1.weight : True

layer2.1.bn1.weight : True laver2.1.bn1.bias : True laver2.1.conv2.weight : True layer2.1.bn2.weight : True layer2.1.bn2.bias : True layer2.1.conv3.weight : True layer2.1.bn3.weight : True layer2.1.bn3.bias : True layer2.2.conv1.weight : True layer2.2.bn1.weight : True layer2.2.bn1.bias : True layer2.2.conv2.weight : True layer2.2.bn2.weight : True layer2.2.bn2.bias : True layer2.2.conv3.weight : True layer2.2.bn3.weight : True layer2.2.bn3.bias : True layer2.3.conv1.weight : True layer2.3.bn1.weight : True layer2.3.bn1.bias : True layer2.3.conv2.weight : True layer2.3.bn2.weight : True layer2.3.bn2.bias : True layer2.3.conv3.weight : True layer2.3.bn3.weight : True layer2.3.bn3.bias : True layer3.0.conv1.weight : True layer3.0.bn1.weight : True layer3.0.bn1.bias : True layer3.0.conv2.weight : True layer3.0.bn2.weight : True layer3.0.bn2.bias : True layer3.0.conv3.weight : True layer3.0.bn3.weight : True layer3.0.bn3.bias : True layer3.0.downsample.0.weight : True layer3.0.downsample.1.weight : True layer3.0.downsample.1.bias : True layer3.1.conv1.weight : True layer3.1.bn1.weight : True layer3.1.bn1.bias : True layer3.1.conv2.weight : True layer3.1.bn2.weight : True layer3.1.bn2.bias : True layer3.1.conv3.weight : True layer3.1.bn3.weight : True

layer3.1.bn3.bias : True layer3.2.conv1.weight : True laver3.2.bn1.weight : True laver3.2.bn1.bias : True layer3.2.conv2.weight : True layer3.2.bn2.weight : True layer3.2.bn2.bias : True layer3.2.conv3.weight : True layer3.2.bn3.weight : True layer3.2.bn3.bias : True layer3.3.conv1.weight : True layer3.3.bn1.weight : True laver3.3.bn1.bias : True layer3.3.conv2.weight : True layer3.3.bn2.weight : True layer3.3.bn2.bias : True layer3.3.conv3.weight : True layer3.3.bn3.weight : True layer3.3.bn3.bias : True layer3.4.conv1.weight : True layer3.4.bn1.weight : True layer3.4.bn1.bias : True layer3.4.conv2.weight : True layer3.4.bn2.weight : True layer3.4.bn2.bias : True layer3.4.conv3.weight : True layer3.4.bn3.weight : True layer3.4.bn3.bias : True layer3.5.conv1.weight : True layer3.5.bn1.weight : True layer3.5.bn1.bias : True layer3.5.conv2.weight : True layer3.5.bn2.weight : True layer3.5.bn2.bias : True layer3.5.conv3.weight : True layer3.5.bn3.weight : True layer3.5.bn3.bias : True layer4.0.conv1.weight : True layer4.0.bn1.weight : True layer4.0.bn1.bias : True layer4.0.conv2.weight : True layer4.0.bn2.weight : True laver4.0.bn2.bias : True layer4.0.conv3.weight : True layer4.0.bn3.weight : True layer4.0.bn3.bias : True

```
layer4.0.downsample.0.weight : True
layer4.0.downsample.1.weight : True
layer4.0.downsample.1.bias : True
layer4.1.conv1.weight : True
layer4.1.bn1.weight : True
layer4.1.bn1.bias : True
layer4.1.conv2.weight : True
layer4.1.bn2.weight : True
layer4.1.bn2.bias : True
layer4.1.conv3.weight : True
layer4.1.bn3.weight : True
layer4.1.bn3.bias : True
layer4.2.conv1.weight : True
layer4.2.bn1.weight : True
layer4.2.bn1.bias : True
layer4.2.conv2.weight : True
layer4.2.bn2.weight : True
layer4.2.bn2.bias : True
layer4.2.conv3.weight : True
layer4.2.bn3.weight : True
layer4.2.bn3.bias : True
fc.weight : True
fc.bias : True
```

Train the model and save into history2.

```
In [ ]: history2 = train(net2, num_epochs=30, lr=0.01, momentum=0.8)
```

```
[Epoch 1/30 Iter
                     32/32]: train loss = 1.9645
[Epoch 2/30 Iter
                     32/32]: train loss = 1.0289
[Epoch 3/30 Iter
                     32/32]: train loss = 0.5807
[Epoch 4/30 Iter
                     32/32]: train loss = 0.3406
[Epoch 5/30 Iter
                     32/32]: train loss = 0.2320
[Epoch 6/30 Iter
                     32/32]: train loss = 0.1732
[Epoch 7/30 Iter
                     32/32]: train loss = 0.1001
[Epoch 8/30 Iter
                     32/32]: train loss = 0.0991
[Epoch 9/30 Iter
                     32/32]: train loss = 0.0664
[Epoch 10/30 Iter
                     32/32]: train loss = 0.0696
[Epoch 11/30 Iter
                     32/32]: train loss = 0.0682
[Epoch 12/30 Iter
                     32/32]: train loss = 0.0461
[Epoch 13/30 Iter
                     32/32]: train loss = 0.0342
[Epoch 14/30 Iter
                     32/32]: train loss = 0.0549
[Epoch 15/30 Iter
                     32/32]: train loss = 0.0681
[Epoch 16/30 Iter
                     32/32]: train loss = 0.0402
[Epoch 17/30 Iter
                     32/32]: train loss = 0.0547
[Epoch 18/30 Iter
                     32/32]: train loss = 0.0390
[Epoch 19/30 Iter
                     32/32]: train loss = 0.0977
                     32/32]: train loss = 0.0600
[Epoch 20/30 Iter
[Epoch 21/30 Iter
                     32/32]: train loss = 0.0325
[Epoch 22/30 Iter
                     32/32]: train loss = 0.0353
[Epoch 23/30 Iter
                     32/32]: train loss = 0.0356
[Epoch 24/30 Iter
                     32/32]: train loss = 0.0212
[Epoch 25/30 Iter
                     32/32]: train loss = 0.0112
[Epoch 26/30 Iter
                     32/32]: train loss = 0.0105
[Epoch 27/30 Iter
                     32/32]: train loss = 0.0176
[Epoch 28/30 Iter
                     32/32]: train loss = 0.0373
[Epoch 29/30 Iter
                     32/32]: train_loss = 0.0305
[Epoch 30/30 Iter
                     32/32]: train loss = 0.0128
Evaluate the network
evaluate(net2)
```

Model 3: As a fixed feature extractor

In []:

Accuracy = 85.10%

When the dataset is too small, fine-tuning the model may still incur overfitting. In this case, you may want to try to use the pretrained as a fixed feature extractor where we train only the classifier layer (i.e., **last layer**) that we have newly inserted into the network.

```
In [ ]: # Load the pretrained model
    net3 = build_network(weights='IMAGENET1K_V2')

We set requires_grad=False for all parameters except for the newly replaced layer fc , i.e., the last two parameters in resnet.parameters() .

In [ ]: parameters = list(net3.parameters())
    for param in parameters[:-2]:
        param.requires_grad = False

In [ ]: for name, param in net3.named_parameters():
        print(name, ':', param.requires_grad)
```

conv1.weight : False bn1.weight : False bn1.bias : False laver1.0.conv1.weight : False layer1.0.bn1.weight : False layer1.0.bn1.bias : False layer1.0.conv2.weight : False layer1.0.bn2.weight : False layer1.0.bn2.bias : False layer1.0.conv3.weight : False layer1.0.bn3.weight : False layer1.0.bn3.bias : False laver1.0.downsample.0.weight : False layer1.0.downsample.1.weight : False layer1.0.downsample.1.bias : False layer1.1.conv1.weight : False layer1.1.bn1.weight : False layer1.1.bn1.bias : False layer1.1.conv2.weight : False layer1.1.bn2.weight : False layer1.1.bn2.bias : False layer1.1.conv3.weight : False layer1.1.bn3.weight : False layer1.1.bn3.bias : False layer1.2.conv1.weight : False layer1.2.bn1.weight : False layer1.2.bn1.bias : False layer1.2.conv2.weight : False layer1.2.bn2.weight : False layer1.2.bn2.bias : False layer1.2.conv3.weight : False layer1.2.bn3.weight : False layer1.2.bn3.bias : False layer2.0.conv1.weight : False layer2.0.bn1.weight : False layer2.0.bn1.bias : False layer2.0.conv2.weight : False layer2.0.bn2.weight : False layer2.0.bn2.bias : False layer2.0.conv3.weight : False layer2.0.bn3.weight : False layer2.0.bn3.bias : False layer2.0.downsample.0.weight : False layer2.0.downsample.1.weight : False layer2.0.downsample.1.bias : False layer2.1.conv1.weight : False

layer2.1.bn1.weight : False laver2.1.bn1.bias : False laver2.1.conv2.weight : False laver2.1.bn2.weight : False layer2.1.bn2.bias : False layer2.1.conv3.weight : False layer2.1.bn3.weight : False layer2.1.bn3.bias : False layer2.2.conv1.weight : False layer2.2.bn1.weight : False layer2.2.bn1.bias : False layer2.2.conv2.weight : False layer2.2.bn2.weight : False layer2.2.bn2.bias : False layer2.2.conv3.weight : False layer2.2.bn3.weight : False layer2.2.bn3.bias : False layer2.3.conv1.weight : False layer2.3.bn1.weight : False layer2.3.bn1.bias : False layer2.3.conv2.weight : False layer2.3.bn2.weight : False layer2.3.bn2.bias : False layer2.3.conv3.weight : False layer2.3.bn3.weight : False layer2.3.bn3.bias : False layer3.0.conv1.weight : False layer3.0.bn1.weight : False layer3.0.bn1.bias : False layer3.0.conv2.weight : False layer3.0.bn2.weight : False layer3.0.bn2.bias : False layer3.0.conv3.weight : False layer3.0.bn3.weight : False layer3.0.bn3.bias : False layer3.0.downsample.0.weight : False layer3.0.downsample.1.weight : False layer3.0.downsample.1.bias : False layer3.1.conv1.weight : False layer3.1.bn1.weight : False layer3.1.bn1.bias : False layer3.1.conv2.weight : False layer3.1.bn2.weight : False layer3.1.bn2.bias : False layer3.1.conv3.weight : False layer3.1.bn3.weight : False

layer3.1.bn3.bias : False layer3.2.conv1.weight : False laver3.2.bn1.weight : False laver3.2.bn1.bias : False layer3.2.conv2.weight : False layer3.2.bn2.weight : False layer3.2.bn2.bias : False layer3.2.conv3.weight : False layer3.2.bn3.weight : False layer3.2.bn3.bias : False layer3.3.conv1.weight : False layer3.3.bn1.weight : False laver3.3.bn1.bias : False layer3.3.conv2.weight : False layer3.3.bn2.weight : False layer3.3.bn2.bias : False layer3.3.conv3.weight : False layer3.3.bn3.weight : False layer3.3.bn3.bias : False layer3.4.conv1.weight : False layer3.4.bn1.weight : False layer3.4.bn1.bias : False layer3.4.conv2.weight : False layer3.4.bn2.weight : False layer3.4.bn2.bias : False layer3.4.conv3.weight : False layer3.4.bn3.weight : False layer3.4.bn3.bias : False layer3.5.conv1.weight : False layer3.5.bn1.weight : False layer3.5.bn1.bias : False layer3.5.conv2.weight : False layer3.5.bn2.weight : False layer3.5.bn2.bias : False layer3.5.conv3.weight : False layer3.5.bn3.weight : False layer3.5.bn3.bias : False layer4.0.conv1.weight : False layer4.0.bn1.weight : False layer4.0.bn1.bias : False layer4.0.conv2.weight : False layer4.0.bn2.weight : False laver4.0.bn2.bias : False layer4.0.conv3.weight : False layer4.0.bn3.weight : False layer4.0.bn3.bias : False

```
layer4.0.downsample.0.weight : False
layer4.0.downsample.1.weight : False
layer4.0.downsample.1.bias : False
layer4.1.conv1.weight : False
layer4.1.bn1.weight : False
layer4.1.bn1.bias : False
layer4.1.conv2.weight : False
layer4.1.bn2.weight : False
layer4.1.bn2.bias : False
layer4.1.conv3.weight : False
layer4.1.bn3.weight : False
layer4.1.bn3.bias : False
layer4.2.conv1.weight : False
layer4.2.bn1.weight : False
layer4.2.bn1.bias : False
layer4.2.conv2.weight : False
layer4.2.bn2.weight : False
layer4.2.bn2.bias : False
layer4.2.conv3.weight : False
layer4.2.bn3.weight : False
layer4.2.bn3.bias : False
fc.weight : True
fc.bias : True
```

Train the model and save into history3.

```
In [ ]: history3 = train(net3, num_epochs=30, lr=0.01, momentum=0.8)
```

```
[Epoch 1/30 Iter
                     32/32]: train loss = 2.0736
[Epoch 2/30 Iter
                     32/32]: train loss = 1.6097
[Epoch 3/30 Iter
                     32/32]: train loss = 1.3621
[Epoch 4/30 Iter
                     32/32]: train loss = 1.2497
[Epoch 5/30 Iter
                     32/32]: train loss = 1.1367
[Epoch 6/30 Iter
                     32/32]: train loss = 1.0983
[Epoch 7/30 Iter
                     32/32]: train loss = 1.0367
[Epoch 8/30 Iter
                     32/32]: train loss = 0.9963
[Epoch 9/30 Iter
                     32/32]: train loss = 0.9157
[Epoch 10/30 Iter
                     32/32]: train loss = 0.9017
[Epoch 11/30 Iter
                     32/32]: train loss = 0.9024
[Epoch 12/30 Iter
                     32/32]: train loss = 0.8587
[Epoch 13/30 Iter
                     32/32]: train loss = 0.8654
[Epoch 14/30 Iter
                     32/32]: train loss = 0.8663
                     32/32]: train loss = 0.7999
[Epoch 15/30 Iter
[Epoch 16/30 Iter
                     32/32]: train loss = 0.7995
[Epoch 17/30 Iter
                     32/32]: train loss = 0.7702
[Epoch 18/30 Iter
                     32/32]: train loss = 0.7750
[Epoch 19/30 Iter
                     32/32]: train loss = 0.7872
                     32/32]: train loss = 0.7529
[Epoch 20/30 Iter
[Epoch 21/30 Iter
                     32/32]: train loss = 0.7194
[Epoch 22/30 Iter
                     32/32]: train loss = 0.7264
[Epoch 23/30 Iter
                     32/32]: train loss = 0.7533
[Epoch 24/30 Iter
                     32/32]: train loss = 0.7054
[Epoch 25/30 Iter
                     32/32]: train loss = 0.7212
[Epoch 26/30 Iter
                     32/32]: train loss = 0.7063
[Epoch 27/30 Iter
                     32/32]: train loss = 0.6903
[Epoch 28/30 Iter
                     32/32]: train loss = 0.6863
[Epoch 29/30 Iter
                     32/32]: train_loss = 0.6490
[Epoch 30/30 Iter
                     32/32]: train loss = 0.6389
Evaluate the model
evaluate(net3)
Accuracy = 68.90\%
```

Model 4: Finetuning the top few layers

In []:

We can also tune the top few layers of the network. The following tunes all the layers in the block layer 4 as well as the fc layer.

```
In [ ]: # Load the pretrained model
net4 = build_network(weights='IMAGENET1K_V2')
```

Then, we freeze all tha layers except for layer4 and fc layers

```
In [ ]: for name, param in net4.named_parameters():
    if not any(name.startswith(ext) for ext in ['layer4', 'fc']):
        param.requires_grad = False

In [ ]: for name, param in net4.named_parameters():
        print(name, ':', param.requires_grad)
```

conv1.weight : False bn1.weight : False bn1.bias : False laver1.0.conv1.weight : False layer1.0.bn1.weight : False layer1.0.bn1.bias : False layer1.0.conv2.weight : False layer1.0.bn2.weight : False layer1.0.bn2.bias : False layer1.0.conv3.weight : False layer1.0.bn3.weight : False layer1.0.bn3.bias : False laver1.0.downsample.0.weight : False layer1.0.downsample.1.weight : False layer1.0.downsample.1.bias : False layer1.1.conv1.weight : False layer1.1.bn1.weight : False layer1.1.bn1.bias : False layer1.1.conv2.weight : False layer1.1.bn2.weight : False layer1.1.bn2.bias : False layer1.1.conv3.weight : False layer1.1.bn3.weight : False layer1.1.bn3.bias : False layer1.2.conv1.weight : False layer1.2.bn1.weight : False layer1.2.bn1.bias : False layer1.2.conv2.weight : False layer1.2.bn2.weight : False layer1.2.bn2.bias : False layer1.2.conv3.weight : False layer1.2.bn3.weight : False layer1.2.bn3.bias : False layer2.0.conv1.weight : False layer2.0.bn1.weight : False layer2.0.bn1.bias : False layer2.0.conv2.weight : False layer2.0.bn2.weight : False layer2.0.bn2.bias : False layer2.0.conv3.weight : False layer2.0.bn3.weight : False layer2.0.bn3.bias : False layer2.0.downsample.0.weight : False layer2.0.downsample.1.weight : False layer2.0.downsample.1.bias : False layer2.1.conv1.weight : False

layer2.1.bn1.weight : False laver2.1.bn1.bias : False laver2.1.conv2.weight : False laver2.1.bn2.weight : False layer2.1.bn2.bias : False layer2.1.conv3.weight : False layer2.1.bn3.weight : False layer2.1.bn3.bias : False layer2.2.conv1.weight : False layer2.2.bn1.weight : False layer2.2.bn1.bias : False layer2.2.conv2.weight : False layer2.2.bn2.weight : False layer2.2.bn2.bias : False layer2.2.conv3.weight : False layer2.2.bn3.weight : False layer2.2.bn3.bias : False layer2.3.conv1.weight : False layer2.3.bn1.weight : False layer2.3.bn1.bias : False layer2.3.conv2.weight : False layer2.3.bn2.weight : False layer2.3.bn2.bias : False layer2.3.conv3.weight : False layer2.3.bn3.weight : False layer2.3.bn3.bias : False layer3.0.conv1.weight : False layer3.0.bn1.weight : False layer3.0.bn1.bias : False layer3.0.conv2.weight : False layer3.0.bn2.weight : False layer3.0.bn2.bias : False layer3.0.conv3.weight : False layer3.0.bn3.weight : False layer3.0.bn3.bias : False layer3.0.downsample.0.weight : False layer3.0.downsample.1.weight : False layer3.0.downsample.1.bias : False layer3.1.conv1.weight : False layer3.1.bn1.weight : False layer3.1.bn1.bias : False layer3.1.conv2.weight : False layer3.1.bn2.weight : False layer3.1.bn2.bias : False layer3.1.conv3.weight : False layer3.1.bn3.weight : False

layer3.1.bn3.bias : False layer3.2.conv1.weight : False laver3.2.bn1.weight : False laver3.2.bn1.bias : False layer3.2.conv2.weight : False layer3.2.bn2.weight : False layer3.2.bn2.bias : False layer3.2.conv3.weight : False layer3.2.bn3.weight : False layer3.2.bn3.bias : False layer3.3.conv1.weight : False layer3.3.bn1.weight : False laver3.3.bn1.bias : False layer3.3.conv2.weight : False layer3.3.bn2.weight : False layer3.3.bn2.bias : False layer3.3.conv3.weight : False layer3.3.bn3.weight : False layer3.3.bn3.bias : False layer3.4.conv1.weight : False layer3.4.bn1.weight : False layer3.4.bn1.bias : False layer3.4.conv2.weight : False layer3.4.bn2.weight : False layer3.4.bn2.bias : False layer3.4.conv3.weight : False layer3.4.bn3.weight : False layer3.4.bn3.bias : False layer3.5.conv1.weight : False layer3.5.bn1.weight : False layer3.5.bn1.bias : False layer3.5.conv2.weight : False layer3.5.bn2.weight : False layer3.5.bn2.bias : False layer3.5.conv3.weight : False layer3.5.bn3.weight : False layer3.5.bn3.bias : False layer4.0.conv1.weight : True layer4.0.bn1.weight : True layer4.0.bn1.bias : True layer4.0.conv2.weight : True layer4.0.bn2.weight : True laver4.0.bn2.bias : True layer4.0.conv3.weight : True layer4.0.bn3.weight : True layer4.0.bn3.bias : True

```
layer4.0.downsample.0.weight : True
layer4.0.downsample.1.weight : True
layer4.0.downsample.1.bias : True
layer4.1.conv1.weight : True
layer4.1.bn1.weight : True
layer4.1.bn1.bias : True
layer4.1.conv2.weight : True
layer4.1.bn2.weight : True
layer4.1.bn2.bias : True
layer4.1.conv3.weight : True
layer4.1.bn3.weight : True
layer4.1.bn3.bias : True
layer4.2.conv1.weight : True
layer4.2.bn1.weight : True
layer4.2.bn1.bias : True
layer4.2.conv2.weight : True
layer4.2.bn2.weight : True
layer4.2.bn2.bias : True
layer4.2.conv3.weight : True
layer4.2.bn3.weight : True
layer4.2.bn3.bias : True
fc.weight : True
fc.bias : True
```

Train the model and save into history4.

```
In [ ]: history4 = train(net4, num_epochs=30, lr=0.01, momentum=0.8)
```

```
[Epoch 1/30 Iter
                     32/32]: train loss = 2.0133
[Epoch 2/30 Iter
                     32/32]: train loss = 1.2797
[Epoch 3/30 Iter
                     32/321: train loss = 0.9507
[Epoch 4/30 Iter
                     32/32]: train loss = 0.7146
[Epoch 5/30 Iter
                     32/32]: train loss = 0.6157
[Epoch 6/30 Iter
                     32/32]: train loss = 0.4763
[Epoch 7/30 Iter
                     32/32]: train loss = 0.4160
[Epoch 8/30 Iter
                     32/32]: train loss = 0.3392
[Epoch 9/30 Iter
                     32/32]: train loss = 0.3121
[Epoch 10/30 Iter
                     32/32]: train loss = 0.2908
[Epoch 11/30 Iter
                     32/32]: train loss = 0.1961
[Epoch 12/30 Iter
                     32/32]: train loss = 0.2080
[Epoch 13/30 Iter
                     32/32]: train loss = 0.1907
[Epoch 14/30 Iter
                     32/32]: train loss = 0.1722
[Epoch 15/30 Iter
                     32/32]: train loss = 0.1200
[Epoch 16/30 Iter
                     32/32]: train loss = 0.1057
[Epoch 17/30 Iter
                     32/32]: train loss = 0.0885
[Epoch 18/30 Iter
                     32/32]: train loss = 0.0946
[Epoch 19/30 Iter
                     32/32]: train loss = 0.0897
                     32/32]: train loss = 0.0970
[Epoch 20/30 Iter
[Epoch 21/30 Iter
                     32/32]: train loss = 0.0947
[Epoch 22/30 Iter
                     32/32]: train loss = 0.0927
[Epoch 23/30 Iter
                     32/32]: train loss = 0.0659
[Epoch 24/30 Iter
                     32/32]: train loss = 0.0653
[Epoch 25/30 Iter
                     32/32]: train loss = 0.0803
[Epoch 26/30 Iter
                     32/32]: train loss = 0.0768
[Epoch 27/30 Iter
                     32/32]: train loss = 0.0575
[Epoch 28/30 Iter
                     32/32]: train loss = 0.0389
[Epoch 29/30 Iter
                     32/32]: train_loss = 0.0831
[Epoch 30/30 Iter
                     32/32]: train loss = 0.0705
```

Evaluate the model

```
In [ ]: evaluate(net4)
```

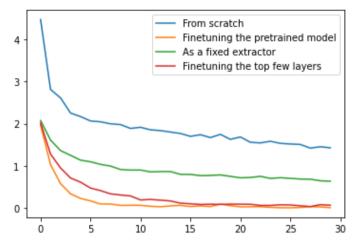
Accuracy = 76.20%

Plotting training loss

Lastly, we plot the training loss history for each of the training schemes above.

```
In [ ]: import matplotlib.pyplot as plt
    plt.plot(history1, label='From scratch')
```

```
plt.plot(history2, label='Finetuning the pretrained model')
plt.plot(history3, label='As a fixed extractor')
plt.plot(history4, label='Finetuning the top few layers')
plt.legend()
plt.show()
```



Exercise

You can try with different network architectures (e.g., EfficientNet-B0) and see if it results in higher test accuracy.

The list of all pre-trained models in PyTorch is listed in this Table.