

Discrete Empirical Interpolation Method (DEIM) and Q-DEIM

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1 Introduction

As introduced in [1], DEIM is a technique for model reduction, with a purpose to determine a subset of relevant points in a model that give the most necessary information about the function. This subset of points can then be used as interpolation points, to reconstruct a function based on the given data points. This is essentially a method for parameterizing equations by a set of parameters θ .

this is an approach to approximate functions of the form $f(x, \theta)$, where

- $\{x_i\}_{i=1, \dots, N}$ is a set of N spatial coordinates, where each $x_i \in \mathbb{R}^d$ ($i = 1, \dots, N$), for some $d \in \mathbb{N}$.
- $\{\theta_j\}_{j=1, \dots, M}$ is a set of M parameters, where each $\theta_j \in \mathbb{R}^p$ ($j = 1, \dots, M$), for some $p \in \mathbb{N}$.

For a fixed $j = 1, \dots, M$, let $\underline{f}(\theta_j) = [f(x_1, \theta_j) \ f(x_2, \theta_j) \ \dots \ f(x_N, \theta_j)]^T \in \mathbb{R}^N$ be a vector-valued function. Furthermore, consider two matrices $\mathbf{W} \in \mathbb{R}^{N \times k}$, $\mathbf{S} \in \mathbb{R}^{N \times k}$, such that $\text{rank}(\mathbf{S}^T \mathbf{W}) = \text{rank}(\mathbf{W}^T \mathbf{S}) = k$, where k is the number of measurements needed,

- $\mathbf{W} \in \mathbb{R}^{N \times k}$ is a matrix with a set of orthonormal columns,
- $\mathbf{S} \in \mathbb{R}^{N \times k}$ is a matrix with columns from the $N \times N$ identity matrix.

Define

$$\mathcal{P} \equiv \mathbf{W}(\mathbf{S}^T \mathbf{W})^{-1} \mathbf{S}^T \quad (1)$$

The goal is to recover (or approximate) the vector-valued function $\underline{f}(\theta_j)$ satisfying

$$\underline{f}(\theta_j) \approx \mathcal{P} \underline{f}(\theta_j) \text{ for } j = 1, \dots, M \quad (2)$$

2 Special cases

Specifically, as outlined in Definition 3.1 in [3], consider $\mathbf{S} = \mathbf{I}(:, \mathbf{p}) \in \mathbb{R}^{N \times k}$, where \mathbf{p} is a set of k distinct indices ($1 \leq k \leq N$). The followings are true:

1. $\mathbf{S}^T \underline{f}(\theta_j) = [f(x_1, \theta_j) \ \dots \ f(x_k, \theta_j)]^T \in \mathbb{R}^k$.

In this case, from equation (2), the information of $\underline{f}(\theta_j)$ on the left hand side is given by a subset of k points $\{x_i\}_{i=1, \dots, k}$.

2. $\mathcal{P} \equiv \mathbf{W}(\mathbf{S}^T \mathbf{W})^{-1} \mathbf{S}^T$ in equation (1) is an oblique objection [3]. Thus, $\mathcal{P}^2 = \mathcal{P}$,
since $\mathcal{P}^2 = (\mathbf{W}(\mathbf{S}^T \mathbf{W})^{-1} \mathbf{S}^T)(\mathbf{W}(\mathbf{S}^T \mathbf{W})^{-1} \mathbf{S}^T) = \mathbf{W}(\mathbf{S}^T \mathbf{W})^{-1} (\mathbf{S}^T \mathbf{W})(\mathbf{S}^T \mathbf{W})^{-1} \mathbf{S}^T$, by associativity.
3. Additionally, from [3], $\mathcal{P} \equiv \mathbf{W}(\mathbf{S}^T \mathbf{W})^{-1} \mathbf{S}^T$ in equation (1) is also called an interpolatory projection, which has the following property: For any $\mathbf{z} \in \mathbb{R}^N$, $\mathbf{z}(\mathbf{p}) = (\mathcal{P}\mathbf{z})(\mathbf{p})$.

Proof.

For any $\mathbf{z} \in \mathbb{R}^N$, $\mathbf{z}(\mathbf{p}) \in \mathbb{R}^k$ is the vector with k rows corresponding to the k indices given, and thus, $\mathbf{z}(\mathbf{p}) = \mathbf{S}^T \mathbf{z}$.

Similarly, since $\mathcal{P}\mathbf{z} \in \mathbb{R}^N$, $(\mathcal{P}\mathbf{z})(\mathbf{p}) = \mathbf{S}^T \mathcal{P}\mathbf{z}$.

Finally, $\mathbf{S}^T = \mathbf{S}^T \mathcal{P}$, since $\mathbf{S}^T \mathcal{P} = (\mathbf{S}^T \mathbf{W})(\mathbf{S}^T \mathbf{W})^{-1} \mathbf{S}^T$ by associativity.

Therefore, $\mathbf{z}(\mathbf{p}) = (\mathcal{P}\mathbf{z})(\mathbf{p})$. □

4. If $\mathbf{W} \in \mathbb{R}^{N \times k}$ is partitioned as follow:

$$\mathbf{W} = \begin{bmatrix} \mathbf{W}_1 \\ \mathbf{W}_2 \end{bmatrix}, \text{ where } \mathbf{W}_1 \in \mathbb{R}^{k \times k} \text{ and } \mathbf{W}_2 \in \mathbb{R}^{(n-k) \times k}, \text{ such that } \mathbf{S}^T \mathbf{W} = \mathbf{W}_1.$$

$$\text{Then, } \mathcal{P} \equiv \mathbf{W}(\mathbf{S}^T \mathbf{W})^{-1} \mathbf{S}^T = \begin{bmatrix} \mathbf{W}_1 \\ \mathbf{W}_2 \end{bmatrix} \mathbf{W}_1^{-1} \mathbf{S}^T = \begin{bmatrix} \mathbf{W}_1 \mathbf{W}_1^{-1} \\ \mathbf{W}_2 \mathbf{W}_1^{-1} \end{bmatrix} \mathbf{S}^T = \begin{bmatrix} \mathbf{I}_k & \mathbf{0}_{k \times (N-k)} \\ \mathbf{W}_2 \mathbf{W}_1^{-1} & \mathbf{0}_{(N-k) \times (N-k)} \end{bmatrix}.$$

3 Algorithm

An algorithm to choose $\mathbf{W} \in \mathbb{R}^{N \times k}$ and $\mathbf{S} \in \mathbb{R}^{N \times k}$ (from [2]):

1. To compute the basis $\mathbf{W} \in \mathbb{R}^{N \times k}$:

First, generate a training set of parameters $\{\theta_j\}_{j=1, \dots, M}$.

Consider the snapshot matrix $\mathcal{M} = [\underline{f}(\theta_1) \ \dots \ \underline{f}(\theta_M)] \in \mathbb{R}^{N \times M}$,

where $\underline{f}(\theta_j) = [f(x_1, \theta_j) \ f(x_2, \theta_j) \ \dots \ f(x_N, \theta_j)]^T \in \mathbb{R}^N$ is a vector-valued function, for $j = 1, \dots, M$.

Then, compute the left singular vectors corresponding to the k largest singular values.

In other words, from the SVD of \mathcal{M} such that $\mathcal{M} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T$, choose $\mathbf{W} = \mathbf{U}(:, 1:k)$.

Notice that this method is similar to Principal Component Analysis (PCA).

2. To compute the subset $\mathbf{S} \in \mathbb{R}^{N \times k}$:

As outlined in [2], we can compute the matrix \mathbf{S} by using Column Pivoting QR (CPQR), or Strong Rank Revealing QR (SRRQR) for \mathbf{W}^T .

Since $\mathbf{W}^T \in \mathbb{R}^{k \times N}$, from the result in CPQR, (or SRRQR), $\mathbf{W}^T \begin{bmatrix} \mathbf{\Pi}_1 & \mathbf{\Pi}_2 \end{bmatrix} = \mathbf{Q}_1 \begin{bmatrix} \mathbf{R}_{11} & \mathbf{R}_{12} \end{bmatrix}$, choose $\mathbf{S} = \mathbf{\Pi}_1$.

References

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