### Simple vector field divergence analysis

Divergence of a vector field F is the dot product of the delta operator with F.

$$divF = \nabla \cdot F = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y}$$

Goal: Understand how divergence is calculated and implemented in MATLAB.

In this MATLAB notebook, we also look at the Laplacian and curl of the vector field. However, this is a side note of this notebook.

### Section 1: Testing source point using minimally required flow line

Let's look at flow lines that are straight lines directed away from the origin.

We see here that divergence is 2 everywhere, meaning that the space is homogeneously expanding to twice its size everywhere.

#### What if we have vectors pointing towards and away from the origin at the same time?

What if we reduce the number of datapoint? The function will not have enough datapoints to compute divergence

```
[X,Y] = meshgrid(-1:1:1);
X([1 3 5 7 9]) = NaN;
Y([1 3 5 7 9]) = NaN;
dX = X;
dY = Y;
Divergence1 = divergence(X,Y,dX,dY)

Divergence1 = 3x3
    NaN    NaN
```

We see here that divergence cannot be computed, because for each available datapoint, its neighbor is missing.

#### What if we use the Laplacian instead?

The Laplacian measures the curvature and variation of the vector field, while the divergence measures the flow of the vector field.

```
[X,Y] = meshgrid(-1:1:1);
dX = X; dY = Y;
lap_dX = del2(dX)
lap_dX = 3x3
   0 0
             0
   0
       0
             0
   0 0
lap_dY = del2(dY)
lap_dY = 3x3
             0
   0 0
   0
        0
             0
    0
subplot(1,2,1);imagesc(lap_dX); title('Laplacian of X')
subplot(1,2,2);imagesc(lap_dY); title('Laplacian of Y'); colorbar
```

We see here that the Laplacian is 0 everywhere, because there is no curvature or variation in the vector field.

## Section 2: Testing a vector field with a source fixed point (left) and a sink fixed point (right)

Let's create a function Z2 to create our vector field with source and sink.

```
spacing = 0.2;
[X2,Y2] = meshgrid(-2:spacing:2);
Z2 = X2.*exp(-X2.^2 - Y2.^2);
[DX2,DY2] = gradient(Z2,spacing);

% Display the gradient vectors.
figure, quiver(X2,Y2,DX2,DY2); hold on
contour(X2,Y2,Z2); axis equal
xlabel('x'); ylabel('y'); title('The contour represent the isobar coming from function
hold off
```

```
% Calculate & visualize divergence
Dtest2 = divergence(X2,Y2,DX2,DY2);

figure, quiver(X2,Y2,DX2,DY2); hold on
axis equal
xlabel('x'); ylabel('y'); title('Divergence is noted on the isobar')
contour(X2,Y2,Dtest2,'ShowText','on')
hold off
```

#### Checking its Laplacian:

```
lap_dX2 = del2(DX2);
lap_dY2 = del2(DY2);
lap_d2 = lap_dX2 + lap_dY2;
subplot(1,3,1); imagesc(lap_dX2); title('Laplacian of X'); colorbar
subplot(1,3,2); imagesc(lap_dY2); title('Laplacian of Y')
subplot(1,3,3); imagesc(lap_d2); title('Laplacian of F');
```

```
figure, quiver(X2,Y2,DX2,DY2); hold on
axis equal
xlabel('x'); ylabel('y'); title('Laplacian is noted on the isobar')
contour(X2,Y2,lap_d2,'ShowText','on')
hold off
```

The Laplacian is hard to visualize, but one can imagine it here as measuring the concavity of the surface, or the magnitude of the divergence compared to its neighbor. Imagine here we are looking down at a mountain with two valleys, the mountain peak has strongly negative Laplacian, indicating the surrounding divergence is smaller than the peak's divergence. The valleys are vice versa.

# Section 3: Testing a rotating vector field without any source or sink fixed point

```
% Divergence of rotating vector field
[X3,Y3] = meshgrid(-pi:pi/8:pi,-pi:pi/8:pi);
U3 = sin(Y3); % change in X
V3 = cos(X3); % change in Y
figure, quiver(X3,Y3,U3,V3,'r') % r makes the field red
```

```
D3 = divergence(X3,Y3,U3,V3)
D3 = 17 \times 17
                                                              0 ...
                                 0
    0
        0
            0
                  0
                       0
                            Ω
                                      Ω
                                           Ω
                                                0
                                                     0
                                                          0
    0
        0
             0
                  0
                       0
                            0
                                 0
                                      0
                                           0
                                                0
                                                     0
                                                         0
                                                              0
    0
        0
             0
                  0
                       0
                            0
                                 0
                                      0
                                           0
                                                0
                                                     0
                                                          0
                                                              0
    0
        0
             0
                  0
                       0
                            0
                                 0
                                      0
                                           0
                                               0
                                                    0
                                                         0
                                                              0
    0
        0
             0
                  0
                       0
                            0
                                 0
                                      0
    0
        Ω
             Ω
                  Ω
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                            Ω
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                                      Ω
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        Ω
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    0
        0
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                                                              0
        0
             0
                  0
    0
                       0
                            0
                                      0
                                                         0
                                                              0
                                 Ω
                                           Ω
                                               Ω
                                                    Ω
    0
       0 0 0 0
                           0
                                 0
                                      Ω
                                                              Ω
```

Divergence is 0, showing that the field is neither a source nor a sink of fluid on average over the region.

#### **Checking its Laplacian:**

```
lap_V3 = del2(V3); % change in Y
lap_U3 = del2(U3); % change in X
lap_d3 = lap_U3 + lap_V3;
subplot(1,3,1); imagesc(lap_V3); title('Laplacian of Y')
subplot(1,3,2); imagesc(lap_U3); title('Laplacian of X')
subplot(1,3,3); imagesc(lap_d3); title('Laplacian of F')
```

```
figure, quiver(X3,Y3,U3,V3,'r'); hold on
axis equal
xlabel('x'); ylabel('y'); title('Laplacian is noted on the isobar')
contour(X3,Y3,lap_d3,'ShowText','on')
hold off
```

The Laplacian tells us the the curvature and variation of the vector field. We can see here that at the center of rotation, there is no change in curvature or variation, hence the Laplacian is 0.

For rotating vector field, it may be more informative to find the numerical curl and angular velocity.

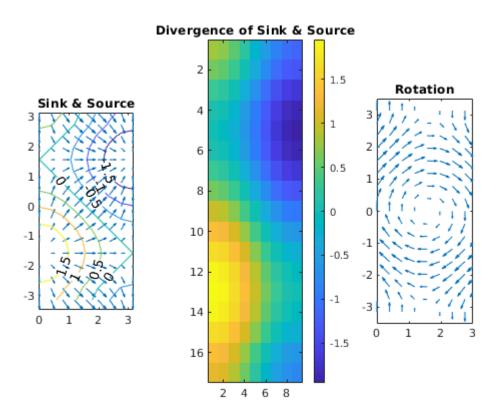
```
[curlz,cav] = curl(X3,Y3,U3,V3);
figure, quiver(X3,Y3,U3,V3,'r'); hold on
axis equal
```

```
xlabel('x'); ylabel('y'); title('The curl is noted on the isobar')
contour(X3,Y3,curlz,'ShowText','on')
hold off
```

### Section 4: Testing vector fields with again, sink and source, and rotation

```
[X4,Y4] = meshgrid(0:pi/8:pi,-pi:pi/8:pi);
U4_1 = \sin(X4); V4_1 = \cos(Y4);
U4 \ 2 = \sin(Y4); \ V4 \ 2 = \cos(X4);
Dleft = divergence(X4, Y4, U4_1, V4_1)
Dleft = 17 \times 9
                                          -0.1791
          1.0942 0.8829
                          0.5668
                                   0.1938
                                                  -0.4952 -0.7065 •••
   1.1683
   1.3474
          1.2732 1.0620
                           0.7458
                                   0.3729
                                           0.0000 -0.3161 -0.5274
   1.6636
         1.5894 1.3781 1.0620
                                  0.6891 0.3161 0.0000 -0.2112
   1.8748
         1.8006 1.5894 1.2732 0.9003 0.5274 0.2112 0.0000
         1.8748 1.6636 1.3474 0.9745 0.6016 0.2854 0.0742
   1.9490
   1.8748 1.8006 1.5894 1.2732 0.9003 0.5274 0.2112
                                                             0
                                                   0 -0.2112
   1.6636 1.5894 1.3781 1.0620 0.6891 0.3161
   1.3474 1.2732 1.0620 0.7458 0.3729 0.3161 -0.5274
   0.9745 0.9003 0.6891 0.3729
                                   0 -0.3729 -0.6891 -0.9003
   0.6016 \qquad 0.5274 \qquad 0.3161 \qquad 0.0000 \quad -0.3729 \quad -0.7458 \quad -1.0620 \quad -1.2732
Dright= divergence(X4,Y4,U4_2,V4_2)
Dright = 17 \times 9
                                 0
                                      0
                                           0
    Ω
        Ω
             Ω
                  Ω
                       Ω
                            Ω
    0
         0
             0
                  0
                       0
                            0
                                 0
                                      0
                                           0
    0
        0
             0
                  0
                       0
                            0
                                 0
                                      0
                                           0
        0
            0
    Ω
                  Ω
                       Ω
                            Ω
                                 Ω
                                      Ω
                                           Ω
            0
    0
       0
                  Ω
                       Ω
                            Ω
                                 Ω
                                      Ω
                                           0
    0
       0
            0
                 0
                       Ω
                            Ω
                                Ω
                                      Ω
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            0
                 0
                      0
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                                0
                                      0
                                           0
    0
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            0
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                           0
                                0
                                      Ω
                                           0
    0
       0 0 0
                      0
                           0
                               0
                                      0
                                           0
    0
tiledlayout(1,3)
ax1 = nexttile;
quiver(ax1, X4, Y4, U4_1, V4_1)
axis equal
title(ax1,'Sink & Source')
hold on
contour(X4,Y4,Dleft,'ShowText','on')
hold off
nexttile; imagesc(flipud(Dleft)); colorbar % flipping matrix for display purpose
title('Divergence of Sink & Source')
ax3 = nexttile;
quiver(ax3, X4, Y4, U4_2, V4_2)
```

```
axis equal
ylim([-3.5 3.5]); xlim([0 3])
title(ax3,'Rotation')
```



# Section 5: Test how divergence function handle missing data (represented by NaN)

```
[X5,Y5] = meshgrid(-2*pi:pi/8:2*pi,-2*pi:pi/8:2*pi);
U5 = sin(X5);
V5 = cos(Y5);

figure
subplot(2,2,1); imagesc(X5); title('X')
subplot(2,2,2); imagesc(Y5); title('Y')
subplot(2,2,3); imagesc(U5); title('dX')
subplot(2,2,4); imagesc(V5); title('dY')
```

```
D5 = divergence(X5,Y5,U5,V5);
figure, imagesc(D5); title('Divergence')
```

```
X5_2 = X5; X5_2(5:2:15,5:2:15) = NaN;
Y5_2 = Y5; Y5_2(5:2:15,5:2:15) = NaN;
U5_2 = sin(X5_2);
```

```
V5_2 = cos(Y5_2);
figure
subplot(2,2,1); imagesc(X5_2); title('X')
subplot(2,2,2); imagesc(Y5_2); title('Y')
subplot(2,2,3); imagesc(U5_2); title('dX')
subplot(2,2,4); imagesc(V5_2); title('dY')
```

```
D5_2 = divergence(X5_2, Y5_2, U5_2, V5_2)
D5_2 = 33 \times 33
                                         -0.5668 -0.8829
  0.7807
         0.7065 0.4952 0.1791 -0.1938
                                                         -1.0942 •••
   0.6016
         -0.7458 -1.0620 -1.2732
   0.2854 0.2112 -0.0000 -0.3161 -0.6891
                                         -1.0620 -1.3781 -1.5894
   0.0742 \quad -0.0000 \quad -0.2112 \quad -0.5274
                                         -1.2732
                                                    NaN -1.8006
                                    NaN
      0 -0.0742 -0.2854
                            NaN -0.9745
                                            NaN -1.6636
                                                            NaN
  0.0742
           0 -0.2112 -0.5274
                                   NaN
                                         -1.2732
                                                    NaN -1.8006
  0.2854 0.2112 0.0000
                            NaN -0.6891
                                           NaN -1.3781
                                                            NaN
  0.6016 0.5274 0.3161
                             0
                                    NaN -0.7458
                                                   NaN -1.2732
  0.9745
         0.9003 0.6891
                            NaN
                                 0.0000
                                          NaN
                                                -0.6891
                                                            NaN
                        0.7458
  1.3474
          1.2732 1.0620
                                    NaN
                                             0
                                                    NaN
                                                        -0.5274
figure, imagesc(D5_2); title('Divergence, with NaN')
```

```
X5_3 = X5; X5_3(5:2:15,5:2:15) = eps;
Y5_3 = Y5; Y5_3(5:2:15,5:2:15) = eps;
U5_3 = sin(X5_3);
V5_3 = cos(Y5_3);
figure
subplot(2,2,1); imagesc(X5_3); title('X')
subplot(2,2,2); imagesc(Y5_3); title('Y')
subplot(2,2,3); imagesc(U5_3); title('dX')
subplot(2,2,4); imagesc(V5_3); title('dY')
```

```
D5_3 = divergence(X5_3,Y5_3,U5_3,V5_3);
figure, imagesc(D5_3); title('Divergence, with epsilon')
```

```
X5_4 = X5; X5_4(5:2:15,5:2:15) = 0;
Y5_4 = Y5; Y5_4(5:2:15,5:2:15) = 0;
U5_4 = sin(X5_4);
V5_4 = cos(Y5_3);
figure, tiledlayout(1,3)
subplot(2,2,1); imagesc(X5_4); title('X')
subplot(2,2,2); imagesc(Y5_4); title('Y')
subplot(2,2,3); imagesc(U5_4); title('dX')
subplot(2,2,4); imagesc(V5_4); title('dY')
```

```
D5_4 = divergence(X5_4,Y5_4,U5_4,V5_4);
figure, imagesc(D5_4); title('Divergence, with epsilon')
```

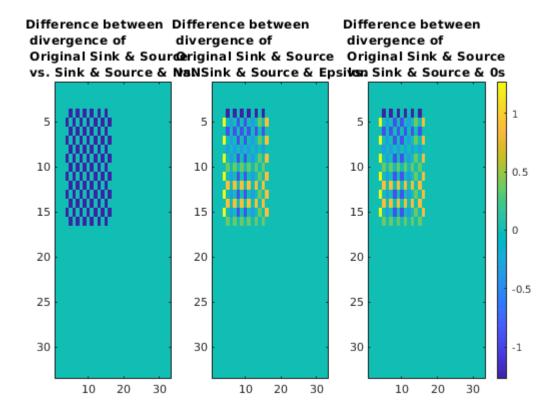
```
subplot(2,2,1)
quiver(X5,Y5,U5,V5)
axis equal
title('Sink & Source')
hold on
contour(X5,Y5,D5,'ShowText','on')
hold off
subplot(2,2,2)
quiver(X5_2,Y5_2,U5_2,V5_2)
axis equal
title('Sink & Source & NaNs')
hold on
contour(X5_2,Y5_2,D5_2,'ShowText','on')
hold off
subplot(2,2,3)
quiver(X5_3,Y5_3,U5_3,V5_3)
axis equal
title('Sink & Source & Epsilon')
hold on
contour(X5_3,Y5_3,D5_3,'ShowText','on')
hold off
subplot(2,2,4)
quiver(X5_4,Y5_4,U5_4,V5_4)
axis equal
title('Sink & Source & Os')
hold on
contour(X5_4,Y5_4,D5_4,'ShowText','on')
hold off
```

```
figure

subplot(2,2,1); imagesc(D5); title('Divergence of \newline Original Sink & Source')
subplot(2,2,2); imagesc(D5_2); title('Divergence of \newline Sink & Source & NaN')
subplot(2,2,3); imagesc(D5_3); title('Divergence of \newline Sink & Source & Epsilon')
subplot(2,2,4); imagesc(D5_4); title('Divergence of \newline Sink & Source & Os')
```

```
figure, tiledlayout(1,3)
diffNan = D5 - D5_2;
diffEps = D5 - D5_3;
diff0 = D5 - D5_4;
```

nexttile; imagesc(diffNan); title('Difference between \newline divergence of \newline (nexttile; imagesc(diffEps); title('Difference between \newline divergence of \newline (nexttile; imagesc(diff0); title('Difference between \newline divergence of \newline Oricolorbar



In conclusion, divergence D is a scalar that denote the changes in a vector field.

D > 0: source of flow (expansion)

D < 0: sink of flow (contraction)

D = 0: neither sink nor source (i.e., rotation, etc.)

Contour line in MATLAB only shows part of the divergence, rounds numbers, and extrapolate in between numbers.

In MATLAB, NaN is considered missing data and divergence will not be calculated.