



## **digitizerNETBOX**

**DN2.59x-xx**

**DN6.59x-xx**

**Ethernet/LXI remote high speed digitizer  
with 16 bit resolution**

**Hardware Manual  
Software Driver Manual**

**English version**

**October 22, 2020**

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## **Introduction**

### **Preface**

This manual provides detailed information on the hardware features of your Spectrum instrument. This information includes technical data, specifications, block diagrams and a connector description.

In addition, this guide takes you through the process of installing and recognizing your hardware and also describes the installation of the delivered driver package for each operating system.

Finally this manual provides you with the complete software information of the hardware and the related driver. The reader of this manual will be able to control the instrument from any PC system with one of the supported operating systems and one of the supported operating software packages.

Please note that this manual provides no description for specific driver parts such as those for IVI, LabVIEW or MATLAB. These driver manuals are available on USB-Stick or on the Spectrum website.

For any new information on the board as well as new available options or memory upgrades please contact our website [www.spectrum-instrumentation.com](http://www.spectrum-instrumentation.com). You will also find the current driver package with the latest bug fixes and new features on our site.

**Please read this manual carefully before you install any hardware or software. Spectrum is not responsible for any hardware failures resulting from incorrect usage.**



### **General Information**

The DN2.59x series allows recording of up to 16 channels in the medium to high-speed segment and with the DN6.59x series up to 48 channels in one instrument are available.

Due to the proven design a wide variety of 16 bit digitizerNETBOX products can be offered. These products are available in several versions and different speed grades making it possible for the user to find a individual solution.

The digitizerNETBOX products can be used with maximum sample rates of up to 20 MS/s, 40 MS/s or 125 MS/s using either four up to 48 single-ended (SE) channels or two up to 24 differential channels. The installed memory of up to 1 GSamp per DN2 digitizer unit or up to 3 GSamp per DN6 digitizer unit will be used for fast data recording. It can completely be used by the current active channels. If using slower data rates the memory can be switched to a FIFO buffer and data will be transferred online over Ethernet to the PC memory or to hard disk.

**Application examples: Laboratory equipment, Super-sonics, LDA/PDA, Radar, Spectroscopy.**

### **digitizerNETBOX Overview**

The series of digitizerNETBOX products are remote powerful digitizer instruments with GBit Ethernet connection following the LXI Core 2011 standard. The proven internal digitizer modules, a stable chassis, an embedded remote controller, sufficient air cooling and standard BNC connectors form an unique instrument that opens a lot of new application areas.

The digitizerNETBOX can be either directly connected to a PC or Laptop or it can be connected to a company/institute LAN and can be accessed from any PC within that LAN. Using the digitizerNETBOX offers the following benefits and new possibilities compared to digitizer plug-in cards:

- Use a powerful digitizer without opening the PC and without mounting hardware inside the PC.
- Share the digitizer within a group of engineers that only need the instrument from time to time.
- Place the digitizer directly near the signal sources and control it remotely from the desk.
- Use the instrument at different location without moving a complete system. One just needs the digitizerNETBOX, a few cables and a Laptop.
- Use the digitizer as a mobile data acquisition device with the DC power option (DN2.xxx only).



### **Internal Digitizer Modules**

The digitizerNETBOX products internally consist of either digitizer modules that are accessed and programmed in a similar way as the Spectrum digitizer cards themselves.

 **Accessing the digitizerNETBOX by software therefore is nearly identical to accessing the same plug-in cards. Throughout the manual all programming and software usage will be described for the internal digitizer modules.**

## **Differences between plain cards and digitizer modules inside the digitizerNETBOX**

Feature	Plain M2i-Express Card	Installed inside digitizerNETBOX <b>DN2.20x, DN2.46x, DN2.47x, DN2.48x, DN2.49x</b>	Installed inside digitizerNETBOX <b>DN6.20x, DN6.46x, DN6.49x</b>
Trigger Input B	Only available as part of option BaseXIO	Available as standard	Available as standard
Timestamp	Only available as part of option BaseXIO	Available as standard	Available as standard
Reference Clock Input			
Option BaseXIO	Option can be ordered with purchase	Not available	Not available
Option Star-Hub	Option can be ordered and allows to connect 5 or 16 cards	Option installed internally in all digitizerNETBOXes with two internal modules	Option installed internally in all models
Standard Memory	512 MSamples/256 MSamples per card (for 8bit / 16bit samples)	1 GSamples/512 MSamples per module (for 8bit / 16bit samples)	1 GSamples/512 MSamples per module (for 8bit / 16bit samples)
Maximum Memory	2 GSamples/1 GSamples per card (for 8bit / 16bit samples)	2 GSamples/1 GSamples per module (for 8bit / 16bit samples)	2 GSamples/1 GSamples per module (for 8bit / 16bit samples)
Feature	Plain M4i-Express Card	Installed inside digitizerNETBOX <b>DN2.22x and DN2.44x</b>	Installed inside digitizerNETBOX <b>DN6.22x and DN6.44x</b>
Option Star-Hub	Option can be ordered and allows to connect 8 cards	Option installed internally in all digitizerNETBOXes with two internal modules	Option installed internally in all models
Standard Memory	4 GSamples per card: M4i.22xx 2 GSamples per card: M4i.44xx	4 GSamples per module in DN2.22x 2 GSamples per module in DN2.44x	4 GSamples per module in DN6.22x 2 GSamples per module in DN6.44x
Maximum Memory	4 GSamples per card: M4i.22xx 2 GSamples per card: M4i.44xx	4 GSamples per module in DN2.22x 2 GSamples per module in DN2.44x	4 GSamples per module in DN6.22x 2 GSamples per module in DN6.44x
Feature	Plain M2p-Express Card	Installed inside digitizerNETBOX <b>DN2.59x</b>	Installed inside digitizerNETBOX <b>DN6.59x</b>
Option Star-Hub	Option can be ordered and allows to connect either 6 or 16 cards	Option installed internally in all models with two internal modules	Option installed internally in all models
Standard Memory	512 MSamples per card	512 MSamples per module	512 MSamples per module
Maximum Memory	512 MSamples per card	512 MSamples per module	512 MSamples per module

## Overview of digitizer modules inside the DN2.59x and DN6.59x digitizerNETBOX

digitizerNETBOX model	Resolution	Single-Ended / Differential	Max Speed	Number of Modules	Digitizer Module Type	Internal Star-Hub	Aux signals on Module	Memory per module	Max memory per module
<b>DN2</b>									
DN2.591-04	16 Bit	4 x SE / 4 x Diff	5 MS/s	1 module	M2p.5916-x4	-	INST0	512 MSamples	512 MSamples
DN2.591-08	16 Bit	8 x SE / 4 x Diff	5 MS/s	1 module	M2p.5913-x4	-	INST0	512 MSamples	512 MSamples
DN2.591-16	16 Bit	16 x SE / 8 x Diff	5 MS/s	2 modules	M2p.5913-x4	yes	INST1	512 MSamples	512 MSamples
DN2.592-04	16 Bit	4 x SE / 4 x Diff	20 MS/s	1 module	M2p.5926-x4	-	INST0	512 MSamples	512 MSamples
DN2.592-08	16 Bit	8 x SE / 4 x Diff	20 MS/s	1 module	M2p.5923-x4	-	INST0	512 MSamples	512 MSamples
DN2.592-16	16 Bit	16 x SE / 8 x Diff	20 MS/s	2 modules	M2p.5923-x4	yes	INST1	512 MSamples	512 MSamples
DN2.593-04	16 Bit	4 x SE / 4 x Diff	40 MS/s	1 module	M2p.5936-x4	-	INST0	512 MSamples	512 MSamples
DN2.593-08	16 Bit	8 x SE / 4 x Diff	40 MS/s	1 module	M2p.5933-x4	-	INST0	512 MSamples	512 MSamples
DN2.593-16	16 Bit	16 x SE / 8 x Diff	40 MS/s	2 modules	M2p.5933-x4	yes	INST1	512 MSamples	512 MSamples
DN2.596-04	16 Bit	4 x SE / 4 x Diff	125 MS/s ( 4 Ch)	1 module	M2p.5966-x4	-	INST0	512 MSamples	512 MSamples
DN2.596-08	16 Bit	8 x SE / 4 x Diff	125 MS/s ( 4 Ch) 80 MS/s ( 8 Ch)	1 module	M2p.5968-x4	-	INST0	512 MSamples	512 MSamples
DN2.596-16	16 Bit	16 x SE / 8 x Diff	125 MS/s ( 8 Ch) 80 MS/s (16 Ch)	2 modules	M2p.5968-x4	yes	INST1	512 MSamples	512 MSamples
<b>DN6</b>									
DN6.591-24	16 Bit	24 x SE / 12 x Diff	5 MS/s	3 modules	M2p.5913-x4	yes	INST0	512 MSamples	512 MSamples
DN6.591-32	16 Bit	32 x SE / 16 x Diff	5 MS/s	4 modules	M2p.5913-x4	yes	INST0	512 MSamples	512 MSamples
DN6.591-40	16 Bit	40 x SE / 20 x Diff	5 MS/s	5 modules	M2p.5913-x4	yes	INST1	512 MSamples	512 MSamples
DN6.591-48	16 Bit	48 x SE / 24 x Diff	5 MS/s	6 modules	M2p.5913-x4	yes	INST2	512 MSamples	512 MSamples
DN6.592-24	16 Bit	24 x SE / 12 x Diff	20 MS/s	3 modules	M2p.5923-x4	yes	INST0	512 MSamples	512 MSamples
DN6.592-32	16 Bit	32 x SE / 16 x Diff	20 MS/s	4 modules	M2p.5923-x4	yes	INST0	512 MSamples	512 MSamples
DN6.592-40	16 Bit	40 x SE / 20 x Diff	20 MS/s	5 modules	M2p.5923-x4	yes	INST1	512 MSamples	512 MSamples
DN6.592-48	16 Bit	48 x SE / 24 x Diff	20 MS/s	6 modules	M2p.5923-x4	yes	INST2	512 MSamples	512 MSamples
DN6.593-24	16 Bit	24 x SE / 12 x Diff	40 MS/s	3 modules	M2p.5933-x4	yes	INST0	512 MSamples	512 MSamples
DN6.593-32	16 Bit	32 x SE / 16 x Diff	40 MS/s	4 modules	M2p.5933-x4	yes	INST0	512 MSamples	512 MSamples
DN6.593-40	16 Bit	40 x SE / 20 x Diff	40 MS/s	5 modules	M2p.5933-x4	yes	INST1	512 MSamples	512 MSamples
DN6.593-48	16 Bit	48 x SE / 24 x Diff	40 MS/s	6 modules	M2p.5933-x4	yes	INST2	512 MSamples	512 MSamples
DN6.596-24	16 Bit	24 x SE / 12 x Diff	125 MS/s (12 Ch) 80 MS/s (24 Ch)	3 modules	M2p.5968-x4	yes	INST0	512 MSamples	512 MSamples
DN6.596-32	16 Bit	32 x SE / 16 x Diff	125 MS/s (16 Ch) 80 MS/s (32 Ch)	4 modules	M2p.5968-x4	yes	INST0	512 MSamples	512 MSamples
DN6.596-40	16 Bit	40 x SE / 20 x Diff	125 MS/s (20 Ch) 80 MS/s (40 Ch)	5 modules	M2p.5968-x4	yes	INST1	512 MSamples	512 MSamples
DN6.596-48	16 Bit	48 x SE / 24 x Diff	125 MS/s (48 Ch) 80 MS/s (24 Ch)	6 modules	M2p.5968-x4	yes	INST2	512 MSamples	512 MSamples

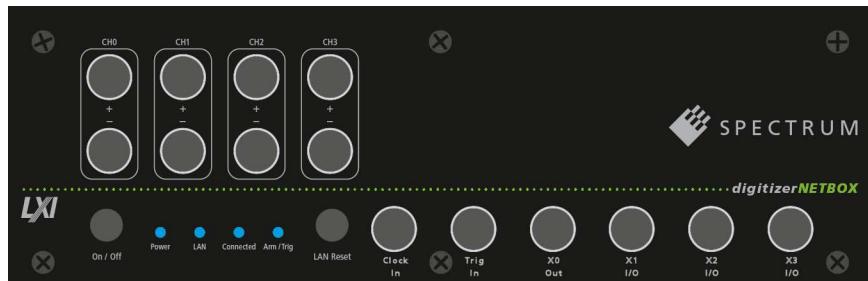
As an example: a DN2.592-16 would be recognized and programmed inside the software as 2 cards of M2p.5923-x4 and 1 Star-Hub.

The auxiliary signals (such as clock, trigger, etc.) are connected to one card only, which is the one carrying the Internal Star-Hub. That device must be addressed for any external clock, trigger, etc. related setup.

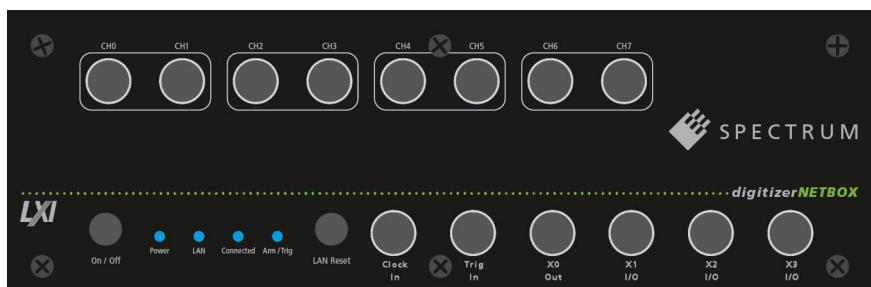
## Different models of the DN2.59x series

The following overview shows the different available models of the DN2.59x series. They differ in the number of internally mounted digitizer modules and the number of available channels.

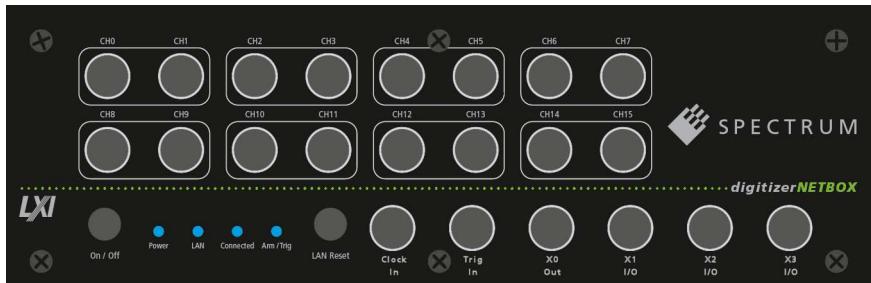
- **DN2.591-04**
- **DN2.592-04**
- **DN2.593-04**
- **DN2.596-04**



- **DN2.591-08**
- **DN2.592-08**
- **DN2.593-08**
- **DN2.596-08**



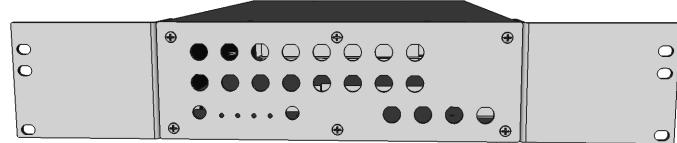
- **DN2.591-16**
- **DN2.592-16**
- **DN2.593-16**
- **DN2.596-16**



## Additional options for DN2 products

### **19" Rack Mount Kit**

The rack mount kit allows to mount the digitizerNETBOX/generatorNETBOX into a standard 19" rack. The digitizerNETBOX/generatorNETBOX DN2 requires two height units of the 19" rack.



Multiple digitizerNETBOX/generatorNETBOX products can be mounted one on top of the other.

It is not possible to mount two digitizerNETBOX/generatorNETBOX DN2 products side by side into one 19" slot.

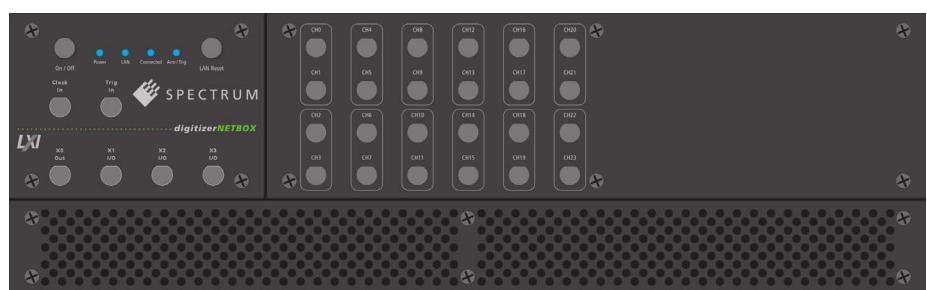
### **DC Power Supply**

The DC power supply option is factory mounted and allows the connection of a DC source directly to the digitizerNETBOX/generatorNETBOX.

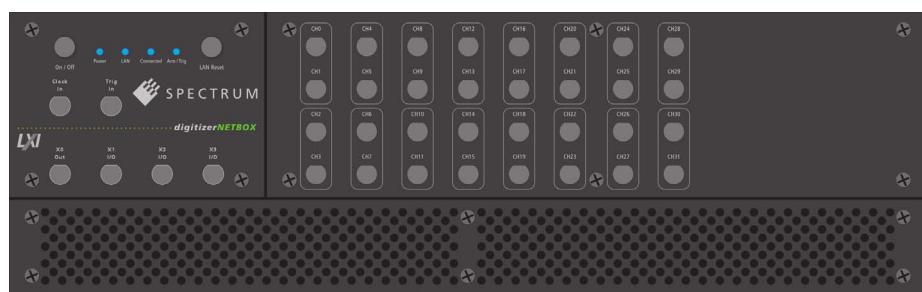
## Different models of the DN6.59x series

The following overview shows the different available models of the DN6.59x series. They differ in the number of internally mounted digitizer modules and the number of available channels.

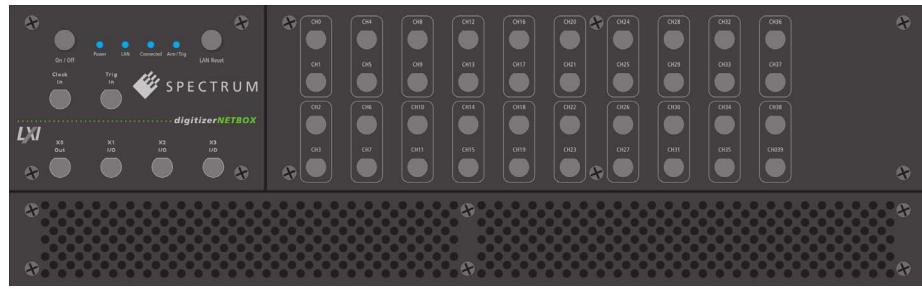
- **DN6.591-24**
- **DN6.592-24**
- **DN6.593-24**
- **DN6.596-24**



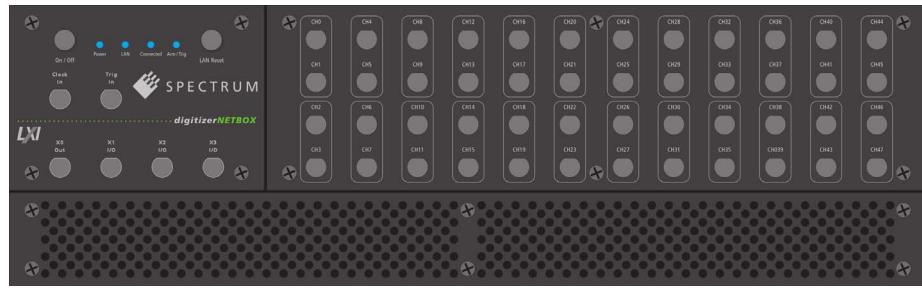
- **DN6.591-32**
- **DN6.592-32**
- **DN6.593-32**
- **DN6.596-32**



- **DN6.591-40**
- **DN6.592-40**
- **DN6.593-40**
- **DN6.596-40**



- **DN6.591-48**
- **DN6.592-48**
- **DN6.593-48**
- **DN6.596-48**



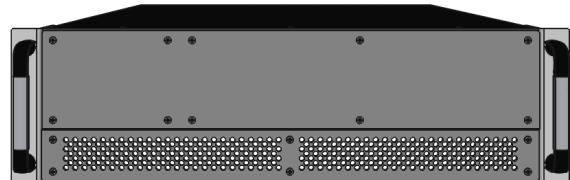
## Additional options for DN6 products

### **19" Rack Mount Kit**

The rack mount kit allows to mount the digitizerNETBOX/generatorNETBOX into a standard 19" rack.

The device then requires three height units within the 19" rack.

Multiple digitizerNETBOX/generatorNETBOX products can be mounted one on top of the other.



## **AC Cable Options**

The system is delivered with a connection cable meeting your countries power connection. Other power cables can be ordered separately to connect your products with your local power connection system. A comprehensive list of all world-wide power plugs in use can be found on the IEC (International Electrotechnical Commission) website: <http://www.iec.ch/worldplugs/>

The following power cable options are available from Spectrum:

### **001: Universal Type for IEC Plug Type E and Type F**

The power cable is suitable for Continental Europe, Korea and others.

Cab-Pwr-001: 180 cm cable to CEE 7/VII



### **002: IEC Plug Type B**

The power cable complies to standards UL 62 and UL 1581 and is suitable for US, Canada, Taiwan and others.

Cab-Pwr-002: 180 cm cable for NEMA5-15P



### **003: IEC Plug Type G**

The power cable is suitable for United Kingdom, Ireland, Hong Kong, Saudi Arabia and others.

Cab-Pwr-003: 180 cm cable to BS 1363A



### **004: IEC Plug Type J**

The power cable is suitable for Switzerland and others.

Cab-Pwr-004: 180 cm cable for SEV type 12



### **005: IEC Plug Type I**

The power cable is suitable for Mainland China, Australia, New Zealand, Argentina and others.

Cab-Pwr-005: 180 cm cable for AS 3112



### **006: IEC Plug Type M**

The power cable is suitable for India, Singapore, South Africa and others.

Cab-Pwr-006: 180 cm cable for IEC 83-B



### **007: IEC Plug Type K**

The power cable is suitable for Denmark and others.

Cab-Pwr-007: 180 cm cable for SR 107-2-D



### **008: IEC Plug Type H**

The power cable is suitable for Israel.

Cab-Pwr-008: 180 cm cable for SI 32



### **009: IEC Plug Type B**

The power cable complies to standard JIS C3306 and is suitable for Japan.

Cab-Pwr-009: 180 cm cable for NEMA5-15P



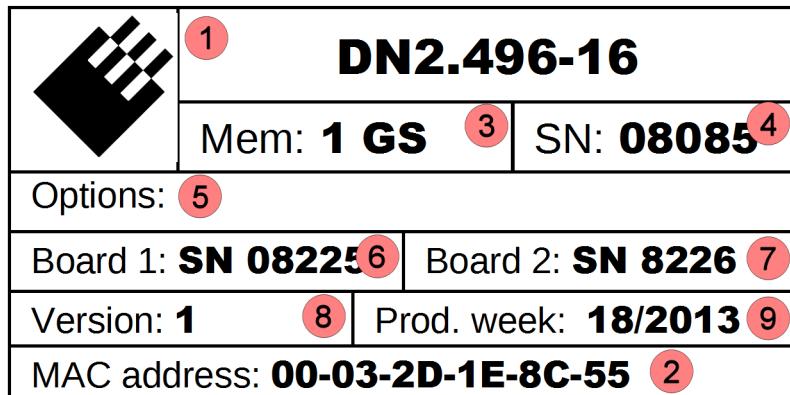
### **010: IEC Plug Type L**

The power cable is suitable for Italy, Chile and others.

Cab-Pwr-010: 180 cm cable for CEI 23-16



## The Spectrum type plate



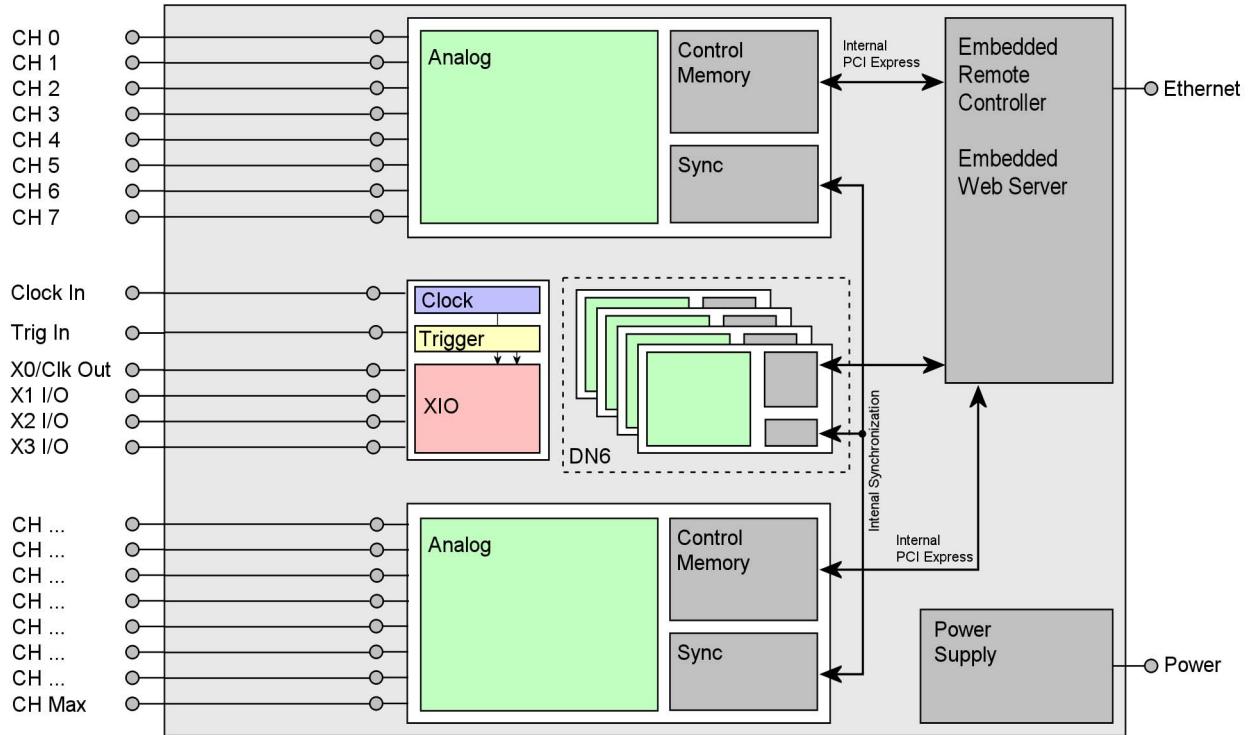
The Spectrum type plate, which consists of the following components, can be found on the back of all netbox products. Please check whether the printed information is the same as the information on your delivery note. All this information can also be read out by software:

- 1 The digitizerNETBOX/generatorNETBOX type, consisting of the abbreviation for the digitizerNETBOX/generatorNETBOX chassis type (DN2 in this example), the model type (496 in this example) and the number of channels (16 in this example)
- 2 The MAC address of the device. The MAX address is fixed and cannot be changed by the user. To check the MAC address by software one can use the integrated web pages of the digitizerNETBOX/generatorNETBOX.
- 3 The installed complete data acquisition memory of the digitizerNETBOX/generatorNETBOX. As in our example there are two internal digitizer/generator modules installed the memory is shared between them. Each internal digitizer/generator module has 512 MSamples installed.
- 4 The serial number of the digitizerNETBOX/generatorNETBOX itself. This is the serial number also found on the delivery note.
- 5 Installed options of the digitizerNETBOX/generatorNETBOX.
- 6 The serial number of the first internal digitizer/generator module.
- 7 The serial number of the second internal digitizer/generator module.
- 8 The hardware version of the digitizerNETBOX/generatorNETBOX. The hardware and firmware versions of the installed digitizer/generator modules are found using the Spectrum Control Center.
- 9 The date of production of the digitizerNETBOX/generatorNETBOX consisting of the calendar week and the year.

**Please always supply us with the above information, especially the serial number in case of support request. That allows us to answer your questions as soon as possible. Thank you.**

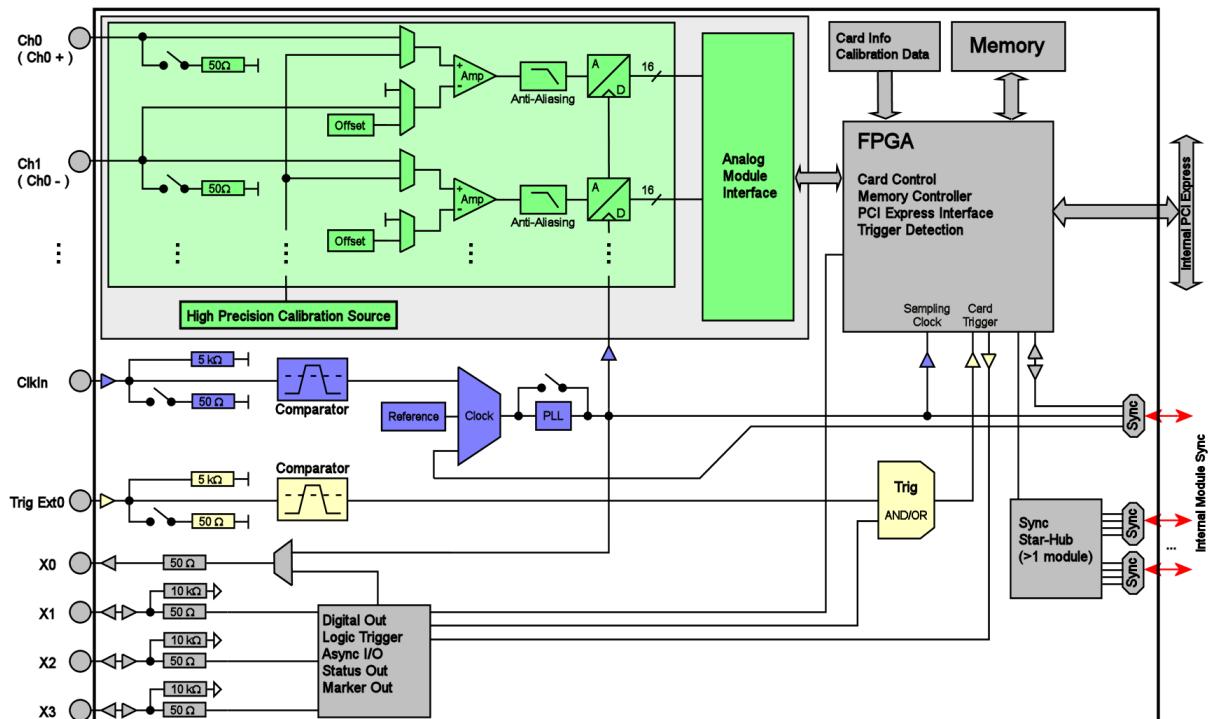
## Hardware information

### Block diagram of digitizerNETBOX DN2.59x and DN6.59x:



- The number of maximum channels and internal digitizer modules and existence of a synchronization Star-Hub is model dependent.
- The internal module to which the auxiliary I/O lines are connected is model dependent. Consult „Internal Digitizer modules“ chapter.

### Block diagram of a single internal digitizer module:



## **DN2 / DN6 Technical Data**

### **Analog Inputs**

Resolution	16 bit (can be reduced to acquire simultaneous digital inputs)
Input Range	$\pm 200 \text{ mV}$ , $\pm 500 \text{ mV}$ , $\pm 1 \text{ V}$ , $\pm 2 \text{ V}$ , $\pm 5 \text{ V}$ , $\pm 10 \text{ V}$
Input Type	Single-ended or True Differential
Input Offset (single-ended)	programmable to $\pm 100\%$ of input range in steps of 1%
ADC Differential non linearity (DNL)	591x: $\pm 0.2/\pm 0.8 \text{ LSB}$ (typ./max.) 592x: $\pm 0.2/\pm 0.8 \text{ LSB}$ (typ./max.) 593x, 8x3: $\pm 0.5/\pm 0.9 \text{ LSB}$ (typ./max.) 594x: $\pm 0.5/\pm 0.9 \text{ LSB}$ (typ./max.) 596x, 8x6: $\pm 0.5/\pm 0.9 \text{ LSB}$ (typ./max.)  591x: $\pm 1.0/\pm 2.3 \text{ LSB}$ (typ./max.) 592x: $\pm 1.0/\pm 2.3 \text{ LSB}$ (typ./max.) 593x, 803, 813: $\pm 2.0/\pm 7.5 \text{ LSB}$ (typ./max.) 594x: $\pm 2.0/\pm 7.5 \text{ LSB}$ (typ./max.) 596x, 806, 816: $\pm 2.0/\pm 7.5 \text{ LSB}$ (typ./max.)
ADC Integral non linearity (INL)	ADC only
Offset error (full speed), DC signal	after warm-up and calibration $\leq 0.1\%$ of range
Gain error (full speed), DC signal	after warm-up and calibration $\leq 0.1\%$ of reading
AC accuracy	1 kHz signal $\leq 0.3\%$ of reading
AC accuracy	50 kHz signal $\leq 0.5\%$ of reading
Crosstalk: Signal 1 MHz, $50 \Omega$	range $\leq \pm 1\text{V}$ $\leq 95 \text{ dB}$ on adjacent channels range $\geq \pm 2\text{V}$ $\leq 90 \text{ dB}$ on adjacent channels
Crosstalk: Signal 10 MHz, $50 \Omega$	range $\leq \pm 1\text{V}$ $\leq 87 \text{ dB}$ on adjacent channels range $\geq \pm 2\text{V}$ $\leq 85 \text{ dB}$ on adjacent channels
Analog Input impedance	software programmable $50 \Omega / 1 \text{ M}\Omega    30 \text{ pF}$
Analog input coupling	fixed DC
Over voltage protection	range $\leq \pm 1\text{V}$ $\pm 5 \text{ V}$ ( $1 \text{ M}\Omega$ ), $3.5 \text{ Vrms}$ ( $50 \Omega$ )
Over voltage protection	range $\geq \pm 2\text{V}$ $\pm 50 \text{ V}$ ( $1 \text{ M}\Omega$ ), $5 \text{ Vrms}$ ( $50 \Omega$ )
Anti-Aliasing Filter (digital filtering active)	591x (5 MS/s) Digital Anti-Aliasing filter at 40% of sampling rate. Examples: 5 MS/s sampling rate -> anti-aliasing filter at 2 MHz 1 MS/s sampling rate -> anti-aliasing filter at 400 kHz
Anti-Aliasing Filter (standard)	591x (5 MS/s) fixed 2.5 MHz 3rd order butterworth alike 592x (20 MS/s) fixed 10 MHz 3rd order butterworth alike 593x (40 MS/s) fixed 20 MHz 3rd order butterworth alike 594x (80 MS/s) fixed 40 MHz 3rd order butterworth alike 596x (125 MS/s) fixed 60 MHz 3rd order butterworth alike
CMRR (Common Mode Rejection Ratio)	range $\leq \pm 1\text{V}$ 100 kHz: 75 dB, 1 MHz: 60 dB, 10 MHz: 40 dB
CMRR (Common Mode Rejection Ratio)	range $\geq \pm 2\text{V}$ 100 kHz: 55 dB, 1 MHz: 52 dB, 10 MHz: 50 dB
Maximum Common Mode Voltage	Input Range $\pm 200 \text{ mV}$ $\pm 500 \text{ mV}$ $\pm 1 \text{ V}$ $\pm 2 \text{ V}$ $\pm 5 \text{ V}$ $\pm 10 \text{ V}$
Differential Input	VCM $\pm 900 \text{ mV}$ $\pm 2.25 \text{ V}$ $\pm 2.25 \text{ V}$ $\pm 9 \text{ V}$ $\pm 22.5 \text{ V}$ $\pm 22.5 \text{ V}$
Channel selection (single-ended inputs)	software programmable 1, 2, 4 or 8 channels (maximum is model dependent)
Channel selection (true differential inputs)	software programmable 1, 2 or 4 channels (maximum is model dependent)

### **Trigger**

Available trigger modes	software programmable	Channel Trigger, External, Software, Window, Pulse, Re-Arm, Spike, Or/And, Delay
Trigger level resolution	software programmable	14 bit
Trigger edge	software programmable	Rising edge, falling edge or both edges
Trigger pulse width	software programmable	0 to [4G - 1] samples in steps of 1 sample
Trigger delay	software programmable	0 to [4G - 1] samples in steps of 1 samples
Trigger holdoff (for Multi, ABA, Gate)	software programmable	0 to [4G - 1] samples in steps of 1 samples
Multi, ABA, Gate: re-arm time	software programmable	< 40 samples (+ programmed pretrigger + programmed holdoff)
Pretrigger at Multi, ABA, Gate, FIFO	software programmable	8 up to [32 kSamples / number of active channels] in steps of 8
Posttrigger	software programmable	8 up to [8G - 4] samples in steps of 8 (defining pretrigger in standard scope mode)
Memory depth	software programmable	16 up to [installed memory / number of active channels] samples in steps of 8
Multiple Recording/ABA segment size	software programmable	8 up to [installed memory / number of active channels] samples in steps of 8
Internal/External trigger accuracy	software programmable	1 sample
Timestamp modes	software programmable	Standard, Startreset, external reference clock on X1 (e.g. PPS from GPS, IRIG-B)
Data format		Std., Startreset: 64 bit counter, increments with sample clock (reset manually or on start) RefClock: 24 bit upper counter (increment with RefClock) 40 bit lower counter (increments with sample clock, reset with RefClock)
Extra data	software programmable	none, acquisition of X1/X2/X3 inputs at trigger time, trigger source (for OR trigger)
Size per stamp		128 bit = 16 bytes
External trigger		<b>X1, X2, X3</b>
External trigger type		Single level comparator 3.3V LVTT logic inputs
External trigger impedance	software programmable	$50 \Omega / 5 \text{k}\Omega$ For electrical specifications refer to External trigger input level $\pm 5 \text{ V}$ ( $5 \text{k}\Omega$ ), $\pm 2.5 \text{ V}$ ( $50 \text{ }\Omega$ ), External trigger over voltage protection $\pm 20 \text{ V}$ ( $5 \text{k}\Omega$ ), $5 \text{ Vrms}$ ( $50 \text{ }\Omega$ ) External trigger sensitivity (minimum required signal swing) $200 \text{ mVpp}$
External trigger level	software programmable	$\pm 5 \text{ V}$ in steps of 1 mV
External trigger bandwidth	50 $\Omega$	DC to 400 MHz n.a. 5 $\text{k}\Omega$ DC to 300 MHz DC to 125 MHz
Minimum external trigger pulse width		$\geq 2$ samples $\geq 2$ samples

### **Multi Purpose I/O lines**

Number of multi purpose output lines	one, named X0
Number of multi purpose input/output lines	three, named X1, X2, X3
Multi Purpose line	<b>X0</b>
Input: available signal types	n.a.
Input: signal levels	n.a.
Input: impedance	n.a.
Input: maximum voltage level	n.a.
Input: maximum bandwidth	n.a.
Output: available signal types	software programmable
Output: impedance	Run-, Arm-, Trigger-Output, Asynchronous Digital-Out, ADC Clock Output
Output: drive strength	50 Ω
Output: type / signal levels	Capable of driving 50 Ω loads, maximum drive strength ±48 mA
Output: update rate (synchronous modes)	3.3V LVTTL, TTL compatible for high impedance loads sampling clock
	<b>X1, X2, X3</b>
	Synchronous Digital-In, Asynchronous Digital-In, Timestamp Reference Clock, Logic trigger
	3.3 V LVTTL
	10 kΩ to 3.3 V
	-0.5 V to +4.0 V
	125 MHz
	Run-, Arm-, Trigger-Output, Asynchronous Digital-Out

### **Option DN2.59x-08-Dig**

Number of additional multi-purpose I/O lines	8 (X4 to X11)
Input: signal levels	3.3 V LVTTL
Input: impedance	10 kΩ to 3.3 V
Input: maximum voltage level	-0.5 V to +4.0 V
Input: maximum bandwidth	125 MHz
Input: available signal types	software programmable
Output: available signal types	software programmable
Output: update rate (synchronous modes)	Syncronous Digital-In, Asynchronous Digital-In Run-, Arm-, Trigger-Output, Asynchronous Digital-Out sampling clock
Output: type / signal levels	3.3V LVTTL, TTL compatible for high impedance loads
Output: impedance	50 Ω
Output: drive strength	Capable of driving 50 Ω loads, maximum drive strength ±48 mA

### **Clock**

Clock Modes	software programmable	internal PLL, external clock, external reference clock, sync see „Clock Limitations and Bandwidth“ table below
Internal clock range (PLL mode)	software programmable	≤ ±1.0 ppm (at time of calibration in production)
Internal clock accuracy	after warm-up	≤ ±0.5 ppm / year
Internal clock aging		1 Hz
PLL clock setup granularity (int. or ext. reference)		128 kHz up to 125 MHz
External reference clock range	software programmable	4.3 ns
Direct external clock to internal clock delay		see „Clock Limitations and Bandwidth“ table below
Direct external clock range		see „Clock Limitations and Bandwidth“ table below
Direct external clock minimum LOW/HIGH time		Single level comparator
External clock type		±5 V (5 kΩ), ±2.5 V (50 Ω), 50 Ω / 5 kΩ
External clock input level		±20 V (5 kΩ), 5 Vrms (50 Ω) 200 mVpp
External clock input impedance	software programmable	±5 V in steps of 1 mV rising edge used
External clock over voltage protection		45% - 55%
External clock sensitivity (minimum required signal swing)		Available via Multi Purpose output X0. Refer to „Multi Purpose I/O lines“ section. N being a multiplier (1, 2, 3, 4, 5, ... Max) of the card with the currently slowest sampling clock. The card maximum (see „Clock Limitations and Bandwidth“ table below) must not be exceeded.
External clock level	software programmable	8 up to (64k - 8) in steps of 8
External clock edge		< 200 ps (typical)
External reference clock input duty cycle		< 100 ps (typical)
Clock output electrical specification		
Synchronization clock multiplier „N“ for different clocks on synchronized cards	software programmable	
ABA mode clock divider for slow clock	software programmable	
Channel to channel skew on one card		
Skew between star-hub synchronized cards		

### **Connectors**

Analog Inputs	9 mm BNC female (one for each single-ended input)	Cable-Type: Cab-9m-xx-xx
Trigger Input	9 mm BNC female	Cable-Type: Cab-9m-xx-xx
Clock/Reference Clock Input	9 mm BNC female	Cable-Type: Cab-9m-xx-xx
Clock Output, Multi-Purpose X0	9 mm BNC female	Cable-Type: Cab-9m-xx-xx
Multi-Purpose I/O X1, X2, X3	Programmable Direction	9 mm BNC female Cable-Type: Cab-9m-xx-xx

**Option digitizerNETBOX/generatorNETBOX embedded server (DN2.xxx-Emb, DN6.xxx-Emb)**

CPU	Intel Quad Core 2 GHz
System memory	4 GByte RAM
System data storage	Internal 128 GByte SSD
Development access	Remote Linux command shell (ssh), no graphical interface (GUI) available
Accessible Hardware	Full access to Spectrum instruments, LAN, front panel LEDs, RAM, SSD
Integrated operating system	OpenSuse 12.2 with kernel 4.4.7.
Internal PCIe connection	DN2.20, DN2.46, DN2.47, DN2.49, DN2.59, DN2.60, DN2.65 DN6.46, DN6.49, DN6.59, DN6.65 DN2.22, DN2.44, DN2.66 DN6.22, DN6.44, DN6.66
	PCIe x1, Gen1
	PCIe x1, Gen2

**Ethernet specific details**

LAN Connection	Standard RJ45
LAN Speed	Auto Sensing: GBit Ethernet, 100BASE-T, 10BASE-T
LAN IP address	DHCP (IPv4) with AutoIP fall-back (169.254.x.y), fixed IP (IPv4)
Sustained Streaming speed	programmable DN2.20, DN2.46, DN2.47, DN2.49, DN2.60 up to 70 MByte/s DN6.46, DN6.49 DN2.59, DN2.65, DN2.22, DN2.44, DN2.66 up to 100 MByte/s DN6.59, DN6.65, DN6.22, DN6.44, DN6.66
Used TCP/UDP Ports	Webserver: 80 mDNS Daemon: 5353 VISA Discovery Protocol: 111, 9757 UPNP Daemon: 1900 Spectrum Remote Server: 1026, 5025

**Power connection details**

Mains AC power supply	Input voltage: 100 to 240 VAC, 50 to 60 Hz
AC power supply connector	IEC 60320-1-C14 [PC standard coupler]
Power supply cord	power cord included for Schuko contact (CEE 7/7)

**Serial connection details (DN2.xxx with hardware ≥ V11)**

Serial connection (RS232)	For diagnostic purposes only. Do not use, unless being instructed by a Spectrum support agent.
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**Certification, Compliance, Warranty**

EMC Immunity	Compliant with CE Mark
EMC Emission	Compliant with CE Mark
Product warranty	5 years starting with the day of delivery
Software and firmware updates	Life-time, free of charge

**Clock Limitations and Bandwidth**

	M2p.591x, DN2.591-xx DN6.591-xx	M2p.592x, DN2.592-xx DN6.592-xx	M2p.593x DN2.593-xx DN6.593-xx DN2.803-xx DN2.813-xx	M2p.594x	M2p.596x DN2.596-xx DN6.596-xx DN2.806-xx DN2.816-xx
max internal clock (non-synchronized cards)	5 MS/s	20 MS/s	40 MS/s	80 MS/s	125 MS/s
min internal clock (non-synchronized cards)	1 kS/s	1 kS/s	1 kS/s	1 kS/s	1 kS/s
max internal clock (cards synchronized via star-hub)	5 MS/s	20 MS/s	40 MS/s	80 MS/s	125 MS/s
min internal clock (cards synchronized via star-hub)	128 kS/s	128 kS/s	128 kS/s	128 kS/s	128 kS/s
max direct external clock	5 MS/s	20 MS/s	40 MS/s	80 MS/s	125 MS/s
min direct external clock	1 MS/s	1 MS/s	1 MS/s	1 MS/s	1 MS/s
min direct external clock LOW time	25 ns	25 ns	4 ns	4 ns	4 ns
min direct external clock HIGH time	25 ns	25 ns	4 ns	4 ns	4 ns
-3 dB analog input bandwidth	> 2.0 MHz	> 10 MHz	> 20 MHz	> 40 MHz	> 60 MHz
-3 dB analog input bandwidth, digital filter de-activated	> 2.5 MHz	n.a.	n.a.	n.a.	n.a.

**RMS Noise Level (Zero Noise), typical figures**

M2p.591x, DN2.591-xx, DN6.591-xx digital filtering active						
Input Range	±200 mV	±500 mV	±1	±2 V	±5 V	±10 V
Voltage resolution	6.1 µV	15.3 µV	30.5 µV	61.0 µV	152.6 µV	305.2 µV
50 Ω	<1.5 LSB	<10 µV	<1.2 LSB	<19 µV	<1.0 LSB	<31 µV
1 MΩ	<1.5 LSB	<10 µV	<1.2 LSB	<19 µV	<1.0 LSB	<31 µV
M2p.592x, DN2.592-xx, DN6.592-xx						
Input Range	±200 mV	±500 mV	±1	±2 V	±5 V	±10 V
Voltage resolution	6.1 µV	15.3 µV	30.5 µV	61.0 µV	152.6 µV	305.2 µV
50 Ω	<4.0 LSB	<25 µV	<2.6 LSB	<40 µV	<2.1 LSB	<65 µV
1 MΩ	<4.5 LSB	<28 µV	<3.0 LSB	<46 µV	<2.5 LSB	<107 µV

M2p.593x, DN2.593-xx, DN6.593-xx, DN2.803-xx, DN2.813-xx												
Input Range	±200 mV	±500 mV	±1	±2 V	±5 V	±10 V						
Voltage resolution	6.1 µV	15.3 µV	30.5 µV	61.0 µV	152.6 µV	305.2 µV						
50 Ω	<6.0 LSB	<37 µV	<5.0 LSB	<77 µV	<4.5 LSB	<138 µV	<6.5 LSB	<397 µV	<5.0 LSB	<763 µV	<4.5 LSB	<1.4 mV
1 MΩ	<6.5 LSB	<40 µV	<5.0 LSB	<77 µV	<4.5 LSB	<138 µV	<6.5 LSB	<397 µV	<5.0 LSB	<763 µV	<4.5 LSB	<1.4 mV

	M2p.594x											
Input Range	±200 mV	±500 mV	±1	±2 V	±5 V	±10 V						
Voltage resolution	6.1 µV	15.3 µV	30.5 µV	61.0 µV	152.6 µV	305.2 µV						
50 Ω	<7.0 LSB	<43 µV	<5.5 LSB	<85 µV	<4.5 LSB	<138 µV	<7.5 LSB	<458 µV	<5.5 LSB	<840 µV	<4.5 LSB	<1.4 mV
1 MΩ	<7.5 LSB	<46 µV	<5.8 LSB	<89 µV	<4.5 LSB	<138 µV	<7.7 LSB	<470 µV	<5.8 LSB	<886 µV	<4.5 LSB	<1.4 mV

M2p.596x, DN2.596-xx, DN6.596-xx, DN2.806-xx, DN2.816-xx												
Input Range	±200 mV	±500 mV	±1	±2 V	±5 V	±10 V						
Voltage resolution	6.1 µV	15.3 µV	30.5 µV	61.0 µV	152.6 µV	305.2 µV						
50 Ω	<9.0 LSB	<55 µV	<6.8 LSB	<104 µV	<5.5 LSB	<168 µV	<9.0 LSB	<550 µV	<6.8 LSB	<1.1 mV	<5.5 LSB	<1.7 mV
1 MΩ	<9.5 LSB	<58 µV	<7.1 LSB	<109 µV	<5.5 LSB	<168 µV	<9.5 LSB	<580 µV	<7.1 LSB	<1.1 mV	<5.5 LSB	<1.7 mV

## Dynamic Parameters, typical figures

M2p.591x, DN2.591-xx, DN6.591-xx digital filtering active									
Test - sampling rate	5 MS/s								
	±200 mV		±500 mV		±1 V		±2 V		
Input Range	20 kHz	1 MHz	20 kHz	1 MHz	20 kHz	1 MHz	20 kHz	1 MHz	
Test Signal Frequency									
SNR (typ)	≥ 83.5 dB	≥ 82.8 dB	≥ 85.0 dB	≥ 84.9 dB	≥ 86.2 dB	≥ 85.7 dB	n.a.	n.a.	
THD (typ)	(≤ 84.4 dB)	≤ 93.5 dB	(≤ 86.3 dB)	≤ 93.1 dB	(≤ 86.9 dB)	≤ 91.8 dB	n.a.	n.a.	
SFDR (typ), excl. harm.	≥ 103.0 dB	≥ 103.0 dB	≥ 104.0 dB	≥ 107.0 dB	≥ 103.0 dB	≥ 107.0 dB	n.a.	n.a.	
ENOB (based on SNR)	≥ 13.6 LSB	≥ 13.4 LSB	≥ 13.8 LSB	≥ 13.8 LSB	≥ 14.0 LSB	≥ 13.9 LSB	n.a.	n.a.	
ENOB (based on SINAD)	≥ 13.1 LSB	≥ 13.4 LSB	≥ 13.4 LSB	≥ 13.7 LSB	≥ 13.6 LSB	≥ 13.8 LSB	n.a.	n.a.	

	M2p.591x, DN2.591-xx, DN6.591-xx digital filtering active							
Test - sampling rate	3 MS/s		1 MS/s		500 kS/s		200 kS/s	
Input Range	±200 mV	±1 V	±200 mV	±1 V	±200 mV	±1 V	±200 mV	±1 V
Test Signal Frequency	20 kHz		20 kHz		20 kHz		20 kHz	
Input bandwidth due to digital filter	1.2 MHz		400 kHz		200 kHz		80 kHz	
SNR (typ)	≥ 85.3 dB	≥ 86.6 dB	≥ 87.2 dB	≥ 89.1 dB	≥ 86.2 dB	≥ 89.7 dB	≥ 86.4 dB	≥ 89.4 dB
THD (typ)	(≤ 88.9 dB)	(≤ -88.5 dB)	(≤ 86.4 dB)	(≤ -88.6 dB)	(≤ 86.9 dB)	(≤ -90.8 dB)	(≤ 89.7 dB)	(≤ -93.8 dB)
SFDR (typ), excl. harm.	≥ 103.1 dB	≥ 103.6 dB	≥ 102.8 dB	≥ 105.6 dB	≥ 103.1 dB	≥ 103.1 dB	≥ 103.1 dB	≥ 103.5 dB
ENOB (based on SNR)	≥ 13.9 LSB	≥ 14.1 LSB	≥ 14.2 LSB	≥ 14.5 LSB	≥ 14.0 LSB	≥ 14.6 LSB	≥ 14.1 LSB	≥ 14.6 LSB
ENOB (based on SINAD)	≥ 13.5 LSB	≥ 13.7 LSB	≥ 13.6 LSB	≥ 14.0 LSB	≥ 13.6 LSB	≥ 14.2 LSB	≥ 13.8 LSB	≥ 14.3 LSB

(20 kHz measurements are missing the correct bandpass filter and therefore show a larger THD that is coming from the generator)

	M2p.592x, DN2.592-xx, DN6.592-xx							
Test - sampling rate	20 MS/s							
Input Range	±200 mV		±500 mV		±1 V		±2 V	
Test Signal Frequency	1 MHz	n.a.	1 MHz	n.a.	1 MHz	n.a.	1 MHz	n.a.
SNR (typ)	≥ 77.2 dB	n.a.	≥ 79.8 dB	n.a.	≥ 81.0 dB	n.a.	≥ 75.0 dB	n.a.
THD (typ)	≤ 92.5 dB	n.a.	≤ -92.8 dB	n.a.	≤ -89.5 dB	n.a.	≤ -76.5 dB	n.a.
SFDR (typ), excl. harm.	≥ 103.0 dB	n.a.	≥ 103.0 dB	n.a.	≥ 105.0 dB	n.a.	≥ 93.0 dB	n.a.
ENOB (based on SNR)	≥ 12.5 LSB	n.a.	≥ 13.0 LSB	n.a.	≥ 13.2 LSB	n.a.	≥ 12.2 LSB	n.a.
ENOB (based on SINAD)	≥ 12.5 LSB	n.a.	≥ 13.0 LSB	n.a.	≥ 13.1 LSB	n.a.	≥ 11.8 LSB	n.a.

M2p.593x, DN2.593-xx, DN6.593-xx, DN2.803-xx, DN2.813-xx								
Test - sampling rate	40 MS/s							
	$\pm 200$ mV		$\pm 500$ mV		$\pm 1$		$\pm 2$ V	
Input Range	1 MHz	10 MHz						
Test Signal Frequency	1 MHz	10 MHz						
SNR (typ)	$\geq 73.0$ dB	$\geq 72.6$ dB	$\geq 74.6$ dB	$\geq 74.4$ dB	$\geq 75.3$ dB	$\geq 75.3$ dB	$\geq 71.9$ dB	$\geq 71.8$ dB
THD (typ)	$\leq -87.8$ dB	$\leq -67.0$ dB	$\leq -89.0$ dB	$\leq -67.0$ dB	$\leq -86.1$ dB	$\leq -67.2$ dB	$\leq -79.0$ dB	$\leq -67.2$ dB
SFDR (typ), excl. harm.	$\geq 98.3$ dB	$\geq 96.5$ dB	$\geq 98.8$ dB	$\geq 99.5$ dB	$\geq 101.0$ dB	$\geq 100.0$ dB	$\geq 81.7$ dB	$\geq 91.3$ dB
ENOB (based on SNR)	$\geq 11.8$ LSB	$\geq 11.8$ LSB	$\geq 12.1$ LSB	$\geq 12.0$ LSB	$\geq 12.2$ LSB	$\geq 12.2$ LSB	$\geq 11.7$ LSB	$\geq 11.6$ LSB
ENOB (based on SINAD)	$\geq 11.8$ LSB	$\geq 10.7$ LSB	$\geq 12.1$ LSB	$\geq 10.7$ LSB	$\geq 12.2$ LSB	$\geq 10.8$ LSB	$\geq 11.6$ LSB	$\geq 10.7$ LSB

	M2p.594x							
Test - sampling rate	80 MS/s							
Input Range	$\pm 200$ mV		$\pm 500$ mV		$\pm 1$		$\pm 2$ V	
Test Signal Frequency	1 MHz	10 MHz						
SNR (typ)	$\geq 70.6$ dB	$\geq 70.5$ dB	$\geq 72.9$ dB	$\geq 72.8$ dB	$\geq 74.2$ dB	$\geq 74.2$ dB	$\geq 69.8$ dB	$\geq 69.8$ dB
THD (typ)	$\leq -87.3$ dB	$\leq -76.9$ dB	$\leq -86.6$ dB	$\leq -76.3$ dB	$\leq -84.8$ dB	$\leq -70.1$ dB	$\leq -79.0$ dB	$\leq -77.9$ dB
SFDR (typ), excl. harm.	$\geq 97.5$ dB	$\geq 105.0$ dB	$\geq 101.0$ dB	$\geq 104.0$ dB	$\geq 100.0$ dB	$\geq 100.0$ dB	$\geq 96.9$ dB	$\geq 96.6$ dB

	<b>M2p.594x</b>							
ENOB (based on SNR)	$\geq 11.4$ LSB	$\geq 11.4$ LSB	$\geq 11.8$ LSB	$\geq 11.8$ LSB	$\geq 12.0$ LSB	$\geq 12.0$ LSB	$\geq 12.0$ LSB	$\geq 11.2$ LSB
ENOB (based on SINAD)	$\geq 11.4$ LSB	$\geq 11.3$ LSB	$\geq 11.8$ LSB	$\geq 11.5$ LSB	$\geq 12.0$ LSB	$\geq 11.1$ LSB	$\geq 11.2$ LSB	$\geq 11.2$ LSB

	<b>M2p.596x, DN2.596-xx, DN6.596-xx, DN2.806-xx, DN2.816-xx</b>											
Test - sampling rate	125 MS/s											
Input Range	$\pm 200$ mV			$\pm 500$ mV			$\pm 1$ V			$\pm 2$ V		
Test Signal Frequency	1 MHz	10 MHz	40 MHz	1 MHz	10 MHz	40 MHz	1 MHz	10 MHz	40 MHz	1 MHz	10 MHz	40 MHz
SNR (typ)	$\geq 68.1$ dB	$\geq 66.2$ dB	$\geq 65.5$ dB	$\geq 70.5$ dB	$\geq 69.9$ dB	$\geq 68.7$ dB	$\geq 73.3$ dB	$\geq 72.7$ dB	$\geq 71.5$ dB	$\geq 67.8$ dB	$\geq 65.8$ dB	$\geq 65.1$ dB
THD (typ)	$\leq -81.5$ dB	$\leq -74.5$ dB	$\leq -53.7$ dB	$\leq -82.5$ dB	$\leq -77.6$ dB	$\leq -55.3$ dB	$\leq -83.3$ dB	$\leq -68.9$ dB	$\leq -57.3$ dB	$\leq -78.0$ dB	$\leq -75.6$ dB	$\leq -53.7$ dB
SFDR (typ), excl. harm.	$\geq 95.0$ dB	$\geq 93.4$ dB	$\geq 92.3$ dB	$\geq 97.5$ dB	$\geq 96.8$ dB	$\geq 94.0$ dB	$\geq 98.5$ dB	$\geq 98.1$ dB	$\geq 96.4$ dB	$\geq 91.5$ dB	$\geq 89.0$ dB	$\geq 89.0$ dB
ENOB (based on SNR)	$\geq 11.0$ LSB	$\geq 10.7$ LSB	$\geq 10.6$ LSB	$\geq 11.4$ LSB	$\geq 11.3$ LSB	$\geq 11.1$ LSB	$\geq 11.8$ LSB	$\geq 11.8$ LSB	$\geq 11.6$ LSB	$\geq 11.0$ LSB	$\geq 10.6$ LSB	$\geq 10.5$ LSB
ENOB (based on SINAD)	$\geq 11.0$ LSB	$\geq 10.6$ LSB	$\geq 8.6$ LSB	$\geq 11.4$ LSB	$\geq 11.1$ LSB	$\geq 8.9$ LSB	$\geq 11.7$ LSB	$\geq 11.0$ LSB	$\geq 9.2$ LSB	$\geq 10.9$ LSB	$\geq 10.6$ LSB	$\geq 8.6$ LSB

Dynamic parameters are measured at  $\pm 1$  V input range (if no other range is stated) and  $50\Omega$  termination with the samplerate specified in the table. Measured parameters are averaged 20 times to get typical values. Test signal is a pure sine wave generated by a signal generator and a matching bandpass filter. Amplitude is >99% of FSR. SNR and RMS noise parameters may differ depending on the quality of the used PC. SNR = Signal to Noise Ratio, THD = Total Harmonic Distortion, SFDR = Spurious Free Dynamic Range, SINAD = Signal Noise and Distortion, ENOB = Effective Number of Bits.

## **DN2 specific Technical Data**

## **Environmental and Physical Details DN2.xxx**

Dimension of Chassis without connectors or bumpers	L x W x H	366 mm x 267 mm x 87 mm
Dimension of Chassis with 19" rack mount option	L x W x H	366 mm x 482.6 mm x 87 mm (2U height)
Weight (1 internal acquisition/generation module)		6.3 kg, with rack mount kit: 6.8 kg
Weight (2 internal acquisition/generation modules)		6.7 kg, with rack mount kit 7.2 kg
Warm up time		20 minutes
Operating temperature		0°C to 40°C
Storage temperature		-10°C to 70°C
Humidity		10% to 90%
Dimension of packing (single DN2)	L x W x H	470 mm x 390 mm x 180 mm
Volume weight of Packing (single DN2)		7.0 kgs

### **Power Consumption**

	<b>230 VAC</b>	<b>12 VDC</b>	<b>24 VDC</b>
2 + 2 channel versions			
4 + 4 channel versions			
8 + 8 channel versions			

MTBF

MTBF

TBD

## **DN6 specific Technical Data**

## **Environmental and Physical Details DN6.xxx**

Dimension of Chassis without connectors or bumpers	L x W x H	464 mm x 431 mm x 131 mm
Dimension of Chassis with 19" rack mount option	L x W x H	464 mm x TBD mm x 131 mm (3U height)
Weight (3 internal acquisition/generation modules)		12.1 kg, with rack mount kit: TBD kg
Weight (4 internal acquisition/generation modules)		12.5 kg, with rack mount kit: TBD kg
Weight (5 internal acquisition/generation modules)		12.9 kg, with rack mount kit: TBD kg
Weight (6 internal acquisition/generation modules)		13.4 kg, with rack mount kit: TBD kg
Warm up time		10 minutes
Operating temperature		0°C to 40°C
Storage temperature		-10°C to 70°C
Humidity		10% to 90%
Dimension of packing (single DN6)	L x W x H	580 mm x 580 mm x 280 mm
Volume weight of Packing (single DN6)		19.0 kgs

### **Power Consumption**

	<b>230 VAC</b>	
24 channel versions, standard memory	TBD	TBD
32 channel versions, standard memory	TBD	TBD
40 channel versions, standard memory	TBD	TBD
48 channel versions, standard memory	TBD	TBD

MTBF

MTBF

TBD hours

## DN2 Order Information

The digitizerNETBOX is equipped with a large internal memory for data storage and supports standard acquisition (Scope), FIFO acquisition (streaming), Multiple Recording, Gated Sampling, ABA mode and Timestamps. Operating system drivers for Windows/Linux 32 bit and 64 bit, drivers and examples for C/C++, IVI (Scope and Digitizer class), LabVIEW (Windows), MATLAB (Windows and Linux), .NET, Delphi, Java, Python and a Professional license of the oscilloscope software SBench 6 are included.

The system is delivered with a connection cable meeting your countries power connection. Additional power connections with other standards are available as option.

### **digitizerNETBOX DN2 - Ethernet/LXI Interface**

Order no.	A/D Resolution	Bandwidth	Memory	Single-Ended Inputs	Differential Inputs	
DN2.591-04	16 Bit	2.5 MHz	1 x 512 MSamples	4 channels 5 MS/s	4 channels 5 MS/s	
DN2.591-08	16 Bit	2.5 MHz	1 x 512 MSamples	8 channels 5 MS/s	4 channels 5 MS/s	
DN2.591-16	16 Bit	2.5 MHz	2 x 512 MSamples	16 channels 5 MS/s	8 channels 5 MS/s	
DN2.592-04	16 Bit	10 MHz	1 x 512 MSamples	4 channels 20 MS/s	4 channels 20 MS/s	
DN2.592-08	16 Bit	10 MHz	1 x 512 MSamples	8 channels 20 MS/s	4 channels 20 MS/s	
DN2.592-16	16 Bit	10 MHz	2 x 512 MSamples	16 channels 20 MS/s	8 channels 20 MS/s	
DN2.593-04	16 Bit	20 MHz	1 x 512 MSamples	4 channels 40 MS/s	4 channels 40 MS/s	
DN2.593-08	16 Bit	20 MHz	1 x 512 MSamples	8 channels 40 MS/s	4 channels 40 MS/s	
DN2.593-16	16 Bit	20 MHz	2 x 512 MSamples	16 channels 40 MS/s	8 channels 40 MS/s	
DN2.596-04	16 Bit	60 MHz	1 x 512 MSamples	4 channels 125 MS/s	4 channels 125 MS/s	
DN2.596-08	16 Bit	60 MHz	1 x 512 MSamples	4 channels 80 MS/s	4 channels 125 MS/s	
DN2.596-16	16 Bit	60 MHz	2 x 512 MSamples	8 channels 125 MS/s	8 channels 125 MS/s	
				16 channels 80 MS/s		

### **Digital Options**

Order no.	Option
DN2.59x-08-Dig	Only available for 8 channel models DN2.59x-08. The option gives 8 additional digital inputs with multiple data formats. All 8 digital inputs are available on BNC connector on the front panel.

### **Options**

Order no.	Option
DN2.xxx-Rack	19" rack mounting set for self mounting
DN2.xxx-Emb	Extension to Embedded Server: CPU, more memory, SSD. Access via remote Linux secure shell (ssh)
DN2.xxx-DC12	12 VDC internal power supply. Replaces AC power supply. Accepts 9 V to 18 V DC input. Screw terminals.
DN2.xxx-DC24	24 VDC internal power supply. Replaces AC power supply. Accepts 18 V to 36 V DC input. Screw terminals
DN2.xxx-BTPWR	Boot on Power On: the digitizerNETBOX/generatorNETBOX/hybridNETBOX automatically boots if power is switched on.

### **Calibration**

Order no.	Option
DN2.xxx-Recal	Recalibration of complete digitizerNETBOX/generatorNETBOX/hybridNETBOX DN2 including calibration protocol

### **BNC Cables**

The standard adapter cables are based on RG174 cables and have a nominal attenuation of 0.3 dB/m at 100 MHz.

for Connections	Connection	Length	to SMA male	to SMA female	to BNC male	to SMB female	
All	BNC male	80 cm	Cab-3mA-9m-80	Cab-3fA-9m-80	Cab-9m-9m-80	Cab-3f-9m-80	
All	BNC male	200 cm	Cab-3mA-9m-200	Cab-3fA-9m-200	Cab-9m-9m-200	Cab-3f-9m-200	

## DN6 Order Information

The digitizerNETBOX is equipped with a large internal memory for data storage and supports standard acquisition (Scope), FIFO acquisition (streaming), Multiple Recording, Gated Sampling, ABA mode and Timestamps. Operating system drivers for Windows/Linux 32 bit and 64 bit, drivers and examples for C/C++, IVI (Scope and Digitizer class), LabVIEW (Windows), MATLAB (Windows and Linux), .NET, Delphi, Java, Python and a Professional license of the oscilloscope software SBench 6 are included.

The system is delivered with a connection cable meeting your countries power connection. Additional power connections with other standards are available as option.

### **digitizerNETBOX DN6 - Ethernet/LXI Interface**

Order no.	A/D Resolution	Bandwidth	Memory	Single-Ended Inputs	Differential Inputs	
DN6.591-24	16 Bit	2.5 MHz	3 x 512 MSamples	24 channels 5 MS/s	12 channels 5 MS/s	
DN6.591-32	16 Bit	2.5 MHz	4 x 512 MSamples	32 channels 5 MS/s	16 channels 5 MS/s	
DN6.591-40	16 Bit	2.5 MHz	5 x 512 MSamples	40 channels 5 MS/s	20 channels 5 MS/s	
DN6.591-48	16 Bit	2.5 MHz	6 x 512 MSamples	48 channels 5 MS/s	24 channels 5 MS/s	
DN6.592-24	16 Bit	10 MHz	3 x 512 MSamples	24 channels 20 MS/s	12 channels 20 MS/s	
DN6.592-32	16 Bit	10 MHz	4 x 512 MSamples	32 channels 20 MS/s	16 channels 20 MS/s	
DN6.592-40	16 Bit	10 MHz	5 x 512 MSamples	40 channels 20 MS/s	20 channels 20 MS/s	
DN6.592-48	16 Bit	10 MHz	6 x 512 MSamples	48 channels 20 MS/s	24 channels 20 MS/s	
DN6.593-24	16 Bit	20 MHz	3 x 512 MSamples	24 channels 40 MS/s	12 channels 40 MS/s	
DN6.593-32	16 Bit	20 MHz	4 x 512 MSamples	32 channels 40 MS/s	16 channels 40 MS/s	
DN6.593-40	16 Bit	20 MHz	5 x 512 MSamples	40 channels 40 MS/s	20 channels 40 MS/s	
DN6.593-48	16 Bit	20 MHz	6 x 512 MSamples	48 channels 40 MS/s	24 channels 40 MS/s	
DN6.596-24	16 Bit	60 MHz	3 x 512 MSamples	12 channels 125 MS/s 24 channels 80 MS/s	12 channels 125 MS/s	
DN6.596-32	16 Bit	60 MHz	4 x 512 MSamples	16 channels 125 MS/s 32 channels 80 MS/s	16 channels 125 MS/s	
DN6.596-40	16 Bit	60 MHz	5 x 512 MSamples	20 channels 125 MS/s 40 channels 80 MS/s	20 channels 125 MS/s	
DN6.596-48	16 Bit	60 MHz	6 x 512 MSamples	24 channels 125 MS/s 48 channels 80 MS/s	24 channels 125 MS/s	

### **Options**

Order no.	Option
DN6.xxx-Rack	19" rack mounting set for self mounting
DN6.xxx-Emb	Extension to Embedded Server: CPU, more memory, SSD. Access via remote Linuxs secure shell (ssh)
DN6.xxx-BTPWR	Boot on Power On: the digitizerNETBOX/generatorNETBOX automatically boots if power is switched on.

### **BNC Cables**

The standard adapter cables are based on RG174 cables and have a nominal attenuation of 0.3 dB/m at 100 MHz.

for Connections	Connection	Length	to SMA male	to SMA female	to BNC male	to SMB female	
All	BNC male	80 cm	Cab-3mA-9m-80	Cab-3fA-9m-80	Cab-9m-9m-80	Cab-3f-9m-80	
All	BNC male	200 cm	Cab-3mA-9m-200	Cab-3fA-9m-200	Cab-9m-9m-200	Cab-3f-9m-200	

## Hardware Installation

### Warnings

#### **ESD Precautions**

The digitizerNETBOX/generatorNETBOX products internally contain electronic components that can be damaged by electrostatic discharge (ESD). The grounded chassis itself gives a very good protection against ESD.

**Before installing the board in your system or protective conductive packaging, discharge yourself by touching a grounded bare metal surface or approved anti-static mat before picking up this ESD sensitive product.**



#### **Opening the Chassis**

There are no components inside the chassis that need any operating by the user. In contrary there are a lot of components that may be harmed when operated unproperly by a user.

**As Spectrum only gives a warranty on the complete instrument, opening the chassis will make you loose the warranty.**

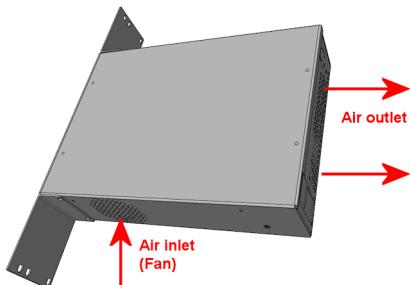


#### **Cooling Precautions**

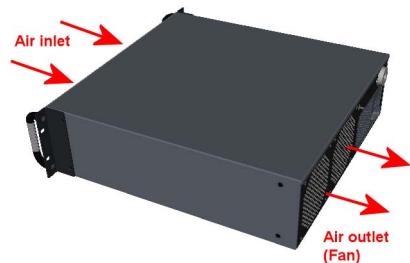
The high performance digitizers/generators of the digitizerNETBOX/generatorNETBOX operate with components having very high power consumption. Therefore the digitizerNETBOX/generatorNETBOX models have sufficient cooling fans.

Make sure that the air inlets and air outlets are free and uncovered and in case of a DN6 ensure that the installed filters at the inlet are cleaned regularly.

#### **DN2 airflow:**



#### **DN6 airflow:**



#### **Sources of noise**

The digitizerNETBOX/generatorNETBOX is using electrical components with very high resolution and high sensitivity. The signal inputs will acquire your signals with a high quality but will also collect spurious noise signals from various sources - especially if using the inputs in high impedance mode. To minimize this effect the cabling must be made with care.

**Keep away the cables from any sources that may inject noise into the signals like other instruments, crossing or even worse running in parallel with other cables with high frequency signals on them. If possible use differential signalling to minimize the effects of injected noise.**



**A standard GND screw on the back of the chassis allows to connect the metal chassis to measurement ground to reduce noise based on ground loops and ground level differences.**



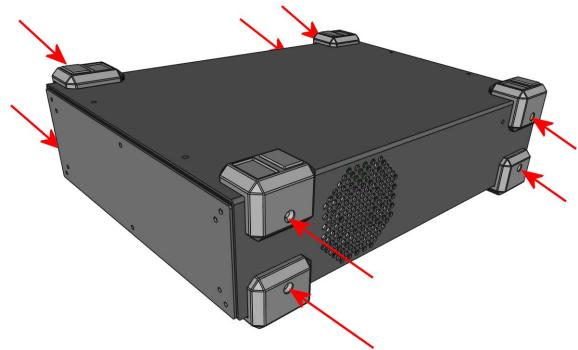
## **Installing 19" rack mount option for DN2**

This option has to be ordered separately. It can be ordered together with the digitizerNETBOX/generatorNETBOX at the time of purchase or it can be ordered later on, if it is becoming necessary to mount the digitizerNETBOX/generatorNETBOX into a 19" rack. In any case the digitizerNETBOX/generatorNETBOX comes pre-configured as a standalone unit, which has then to manually be converted to the rackmount configuration by the user.

### **Step 1**

The rackmount option comes with the required Torx T20 size screw driver to un-mount the default screws holding the bumper feet.

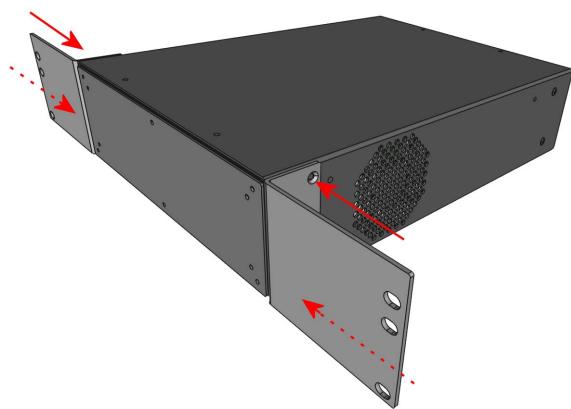
Unscrew these 8 Torx T20 screws with the provided screw driver and keep them together with the un-mounted bumpers for possible later use in case the rackmount option shall be un-mounted again in the future.



### **Step 2**

Mount the 19" rack mount extension using the four phillips-head screws that are also provided with each rack mount extension. Two screws are required for each rack mounting bracket.

Care should be taken to not overtighten the screws.



## **Installing 19" rack mount option for DN6**

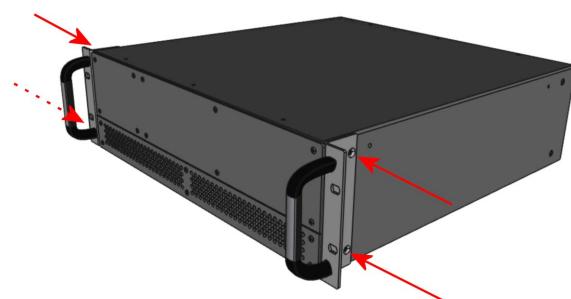
Installing the rack mount extension for the DN6 series follows the same principles as for the DN2 models shown above.

### **Step 1**

Unscrew the existing bumper corner pieces with the provided screw driver and keep them together with the un-mounted bumpers for possible later use in case the rackmount option shall be un-mounted again in the future.

### **Step 2**

Mount the 19" rack mount extension using the four phillips-head screws that are also provided with each rack mount extension. Two screws are required for each rack mounting bracket. Care should be taken to not overtighten the screws.



**In addition to using the provided rack mount extension for fastening the DN6 device within the 19" rack, the user must take additional measures, suitable for the used rack, to provide adequate mechanical support at the backside of the device.**

**This support is required for DN6 devices due to their higher weight compared to DN2 devices.**

## Setup of digitizerNETBOX/generatorNETBOX

### Connections

First of all the digitizerNETBOX/generatorNETBOX needs to be connected to both power line and LAN environment:

#### Power

Connect the power line cable to a matching power source. First connect the cable to the digitizerNETBOX/generatorNETBOX, second connect the cable to the power plug. Please check the technical data section to see the requirements for the power supply.

**If using a DC power option please be sure to have the external DC power source switched off while connecting the power lines. Only switch on the power supply after all connections have been done and are checked.**



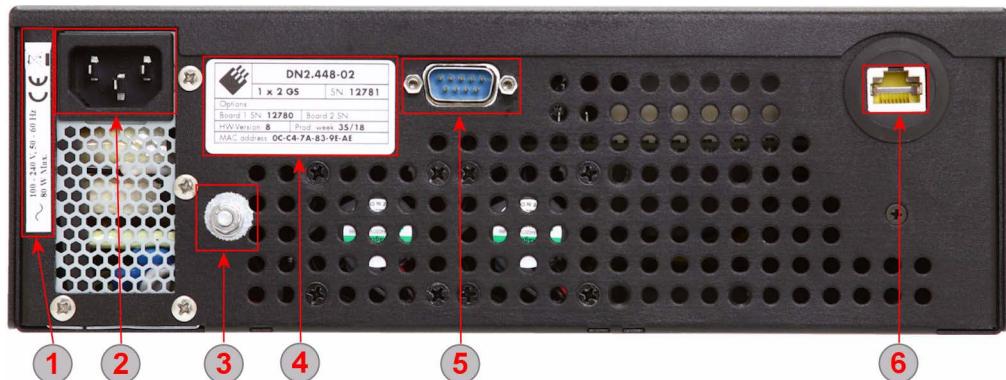
#### Ethernet

Connect the digitizerNETBOX/generatorNETBOX to either your company LAN or directly to your PC. Please use a standard Cat-5 or better Ethernet cable for the connection.

### Back Side DN2

The right hand picture shows the back side of one digitizerNET-BOX/generatorNETBOX with standard AC power supply. The different power supply options are described later in this chapter. The picture is taken from a digitizerNET-BOX hardware revision V11. Older versions do look differently.

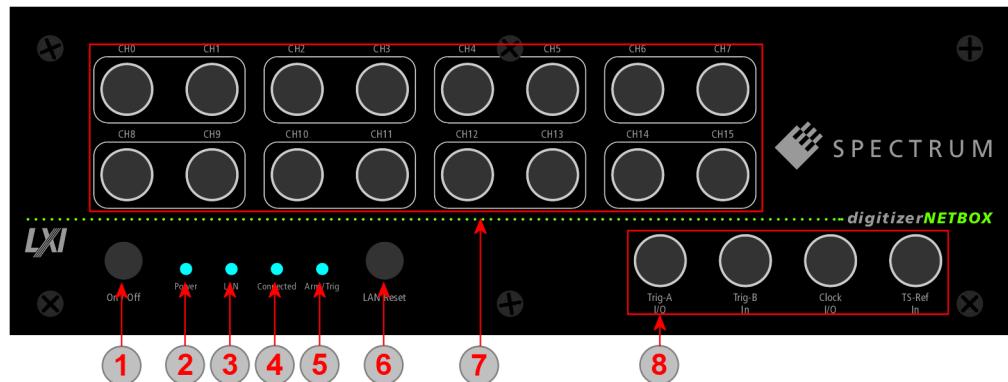
Please see the table below for a description of the different marked areas:



Area	Name	Description
1	Power Label	The label shows the power specification in detail. Please check the listed specification before connecting the power line
2	Power Connector (AC)	Standard three pole power connector. A matching power cable is included in the delivery. Separate power cables for other country standards are available upon request.
3	GND Screw	This screw is directly connected to Chassis ground and can be used to add a low resistance ground connection to the system
4	Type plate	The type plate shows exact type, option, serial number, versions and production week. A more detailed description of the type plate is found in a separate chapter of the manual
5	Debug Port (DSUB)	This port is for debug purposes only. Please only connect a cable when asked by the Spectrum support group. The debug connector is a feature of hardware revision V11 and is not available on earlier versions
6	LAN Connection	A standard Ethernet port. Please connect the device with your PC/Laptop or company LAN before start

### Front Panel DN2

The right-hand drawing gives you an overview on one digitizerNETBOX DN2 front panel. Depending on the version of the digitizerNETBOX or generatorNETBOX you have the area 7 may differ in terms of number of channels or grouping of the channels.

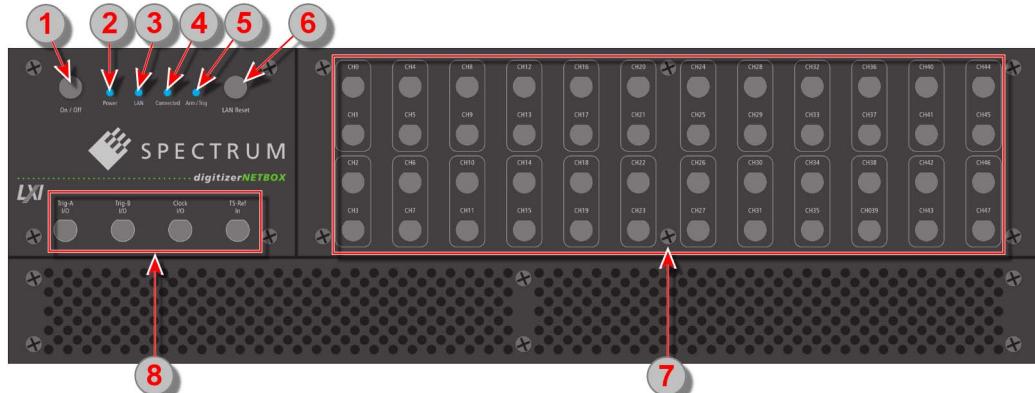


In area 8 a version with 4 BNC connectors is shown. Other versions with 5 SMA, 6 BNC or 7 SMA connectors are also available. Please see the table below for the different connections.

Area	Name	Status	Description
1	Power On/Off	press while device stopped short press while device is running long press while device is running	digitizerNETBOX/generatorNETBOX is started digitizerNETBOX/generatorNETBOX is closing the embedded controller and is going into standby mode digitizerNETBOX/generatorNETBOX is aborted and is going into standby. Please only use this stop method if the digitizerNETBOX/generatorNETBOX is not responding
2	Power LED	LED off LED orange LED green	no power connected to the device power is connected, device is in standby mode device has started and is working
3	LAN LED	LED off LED red LED green LED green flashing	Only off during boot up, turning to either red or green afterwards. If permanently off, contact support. Error while trying to get a LAN connection Device is connected to LAN. Device is connected to LAN. Flashing indicates LAN ID (see webserver)
4	Connected LED	LED off LED green	Device is not in use Device is in use by other PC
5	Arm/Trigger	LED off LED green	No trigger detected, device is waiting for trigger event, or not armed at all Trigger detected, acquisition is running or already finished
6	LAN Reset	press once	Does a reset of the LAN settings to default state. The reset button needs to be pressed for 4 seconds to issue the reset. The reset command is then issued immediatley independent of the current run state of the device.
7	Signal Connections		Connect your input signals here. For differential connections use even channels for positive phase and odd channels for negative phase.
8	Control Connections (4 BNC connector version, for M2i module based products)	Trig-A I/O Trig-B In Clock I/O TS-Ref In	Trigger A with programmable input or output. This is the main external trigger Trigger B, input only. This trigger is referenced in the manual as TRIG_XIO0 Clock with programmable input or output Timestamp Reference Clock Input
8	Control Connections (5 SMA connector version, for M3i module based products)	Clock In Clock Out Trig-A In Trig-B I/O TS_Ref In	External clock input External clock output Trigger A, input only. This is the main external trigger. The trigger line is reference in the manual as EXTO Trigger B/Multi Purpose X0 with programmable direction. The connection is referenced in the manual as X0 Timestamp Reference Clock Input
8	Control Connections (6 BNC connector version, for M2p module based products)	Clock In Trig In X0 Out X1 I/O X2 I/O X3 I/O	External clock input Trigger, input only. This is the main external trigger. The trigger line is reference in the manual as EXTO Multi Purpose X0, output only. Clock output available. The connection is referenced in the manual as X0 Multi Purpose X1 with programmable direction. The connection is referenced in the manual as X1 Multi Purpose X2 with programmable direction. The connection is referenced in the manual as X2 Multi Purpose X3 with programmable direction. The connection is referenced in the manual as X3
8	Control Connections (7 SMA connector version, for M4i module based products)	Clock In Clock Out Trig0 In Trig1 In X0 I/O X1 I/O X2 I/O	External clock input External clock output Trigger 0, input only. This is the main external trigger. The trigger line is reference in the manual as EXTO Trigger 1, input only. This is the secondary external trigger. This line is reference in the manual as EXT1 Multi Purpose X0 with programmable direction. The connection is referenced in the manual as X0 Multi Purpose X1 with programmable direction. The connection is referenced in the manual as X1 Multi Purpose X2 with programmable direction. The connection is referenced in the manual as X2

## Front Panel DN6

The right-hand drawing gives you an overview on one digitizerNETBOX DN6 front panel. Depending on the version of the digitizerNETBOX or generatorNETBOX you have, the area 7 may differ in terms of number of channels or grouping of the channels.



In area 8 a version with 4 BNC connectors is shown. Other versions with 5 SMA, 6 BNC or 7 SMA connectors are also available. Please see the table below for the different connections.

Area	Name	Status	Description
1	Power On/Off	press while device stopped short press while device is running long press while device is running	digitizerNETBOX/generatorNETBOX is started digitizerNETBOX/generatorNETBOX is closing the embedded controller and is going into standby mode digitizerNETBOX/generatorNETBOX is aborted and is going into standby. Please only use this stop method if the digitizerNETBOX/generatorNETBOX is not responding
2	Power LED	LED off LED orange LED green	no power connected to the device power is connected, device is in standby mode device has started and is working
3	LAN LED	LED off LED red LED green LED green flashing	Only off during boot up, turning to either red or green afterwards. If permanently off, contact support. Error while trying to get a LAN connection. Device is connected to LAN. Device is connected to LAN. Flashing indicates LAN ID (see webserver).

Area	Name	Status	Description
④	Connected LED	LED off LED green	Device is not in use Device is in use by other PC
⑤	Arm/Trigger	LED off LED green	No trigger detected, device is waiting for trigger event, or not armed at all Trigger detected, acquisition is running or already finished
⑥	LAN Reset	press once	Does a reset of the LAN settings to default state. The reset button needs to be pressed for 4 seconds to issue the reset. The reset command is then issued immediately independent of the current run state of the device.
⑦	Signal Connections		Connect your input signals here. For differential connections use even channels for positive phase and odd channels for negative phase.
⑧	Control Connections (4 BNC connector version, for M2i module based products)	Trig-A I/O Trig-B In Clock I/O TS-Ref In	Trigger A with programmable input or output. This is the main external trigger Trigger B, input only. This trigger is referenced in the manual as TRIG_XIO0 Clock with programmable input or output Timestamp Reference Clock Input
⑧	Control Connections (6 BNC connector version, for M2p module based products)	Clock In Trig In X0 Out X1 I/O X2 I/O X3 I/O	External clock input Trigger, input only. This is the main external trigger. The trigger line is reference in the manual as EXT0 Multi Purpose X0, output only. Clock output available. The connection is referenced in the manual as X0 Multi Purpose X1 with programmable direction. The connection is referenced in the manual as X1 Multi Purpose X2 with programmable direction. The connection is referenced in the manual as X2 Multi Purpose X3 with programmable direction. The connection is referenced in the manual as X3
⑧	Control Connections (7 SMA connector version, for M4i module based products)	Clock In Clock Out Trig0 In Trig1 In X0 I/O X1 I/O X2 I/O	External clock input External clock output Trigger 0, input only. This is the main external trigger. The trigger line is reference in the manual as EXT0 Trigger 1, input only. This is the secondary external trigger. This line is reference in the manual as EXT1 Multi Purpose X0 with programmable direction. The connection is referenced in the manual as X0 Multi Purpose X1 with programmable direction. The connection is referenced in the manual as X1 Multi Purpose X2 with programmable direction. The connection is referenced in the manual as X2

## Ethernet Default Settings

The digitizerNETBOX/generatorNETBOX is started with the following Ethernet configuration:

Setting	Default Setup
DHCP	enabled
Auto IP	enabled
Host Name	Default hostname as netbox type + serial number      Example: DN2_465-08_sn8085

## **Detecting the digitizerNETBOX**

Before accessing the digitizerNETBOX/generatorNETBOX one has to determine the IP address of the digitizerNETBOX/generatorNETBOX. Normally that can be done using one of the two methods described below:

### **Discovery Function**

The digitizerNETBOX/generatorNETBOX responds to the VISA described Discovery function. The next chapter will show how to install and use the Spectrum control center to execute the discovery function and to find the Spectrum hardware. As the discovery function is a standard feature of all LXI devices there are other software packages that can find the digitizerNETBOX/generatorNETBOX using the discovery function:

- Spectrum control center (limited to Spectrum remote products)
- free LXI System Discovery Tool from the LXI consortium ([www.lxistandard.org](http://www.lxistandard.org))
- Measurement and Automation Explorer from National Instruments (NI MAX)
- Keysight Connection Expert from Keysight Technologies

Additionally the discovery procedure can also be started from ones own specific application:

```
#define TIMEOUT_DISCOVERY 5000 // timeout value in ms

const uint32 dwMaxNumRemoteCards = 50;

char* pszVisa[dwMaxNumRemoteCards] = { NULL };
char* pszIdn[dwMaxNumRemoteCards] = { NULL };

const uint32 dwMaxIdnStringLen = 256;
const uint32 dwMaxVisaStringLen = 50;

// allocate memory for string list
for (uint32 i = 0; i < dwMaxNumRemoteCards; i++)
{
    pszVisa[i] = new char [dwMaxVisaStringLen];
    pszIdn[i] = new char [dwMaxIdnStringLen];
    memset (pszVisa[i], 0, dwMaxVisaStringLen);
    memset (pszIdn[i], 0, dwMaxIdnStringLen);
}

// first make discovery - check if there are any LXI compatible remote devices
dwError = spcm_dwDiscovery ((char**)pszVisa, dwMaxNumRemoteCards, dwMaxVisaStringLen, TIMEOUT_DISCOVERY);

// second: check from which manufacturer the devices are
spcm_dwSendIDNRequest ((char**)pszIdn, dwMaxNumRemoteCards, dwMaxIdnStringLen);

// Use the VISA strings of these devices with Spectrum as manufacturer
// for accessing remote devices without previous knowledge of their IP address
```

### **Finding the digitizerNETBOX/generatorNETBOX in the network**

As the digitizerNETBOX/generatorNETBOX is a standard network device it has its own IP address and host name and can be found in the computer network. The standard host name consist of the model type and the serial number of the digitizerNETBOX/generatorNETBOX. The serial number is also found on the type plate on the back of the digitizerNETBOX/generatorNETBOX chassis.

As default DHCP (IPv4) will be used and an IP address will be automatically set. In case no DHCP server is found, an IP will be obtained using the AutoIP feature. This will lead to an IPv4 address of 169.254.x.y (with x and y being assigned to a free IP in the network) using a subnet mask of 255.255.0.0.

The default IP setup can also be restored, by using the „LAN Reset“ button on the device.

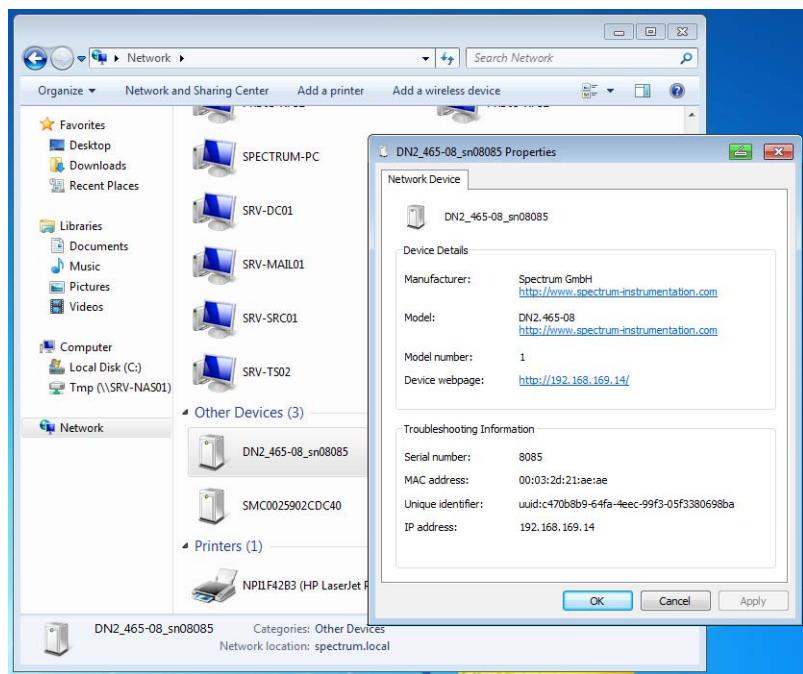
If a fixed IP address should be used instead, the parameters need to be set according to the current LAN requirements.

### **Windows 7, Windows 8, Windows 10**

Under Windows 7, Windows 8 and Windows 10 the digitizerNETBOX and generatorNETBOX devices are listed under the „other devices“ tree with their given host name.

A right click on the digitizerNETBOX or generatorNETBOX device opens the properties window where you find further information on the device including the IP address.

From here it is possible to go the website of the device where all necessary information are found to access the device from software.



### **Troubleshooting**

If the above methods do not work please try one of the following steps:

- Ask your network administrator for the IP address of the digitizerNETBOX/generatorNETBOX and access it directly over the IP address.
- Check your local firewall whether it allows access to the device and whether it allows to access the ports listed in the technical data section.
- Check with your network administrator whether the subnet, the device and the ports that are listed in the technical data section are accessible from your system due to company security settings.

## **Software Driver Installation**

Before using the digitizerNETBOX/generatorNETBOX a software package and the appropriate API drivers must be installed that matches the operating system. The installation is done in different ways depending on the used operating system. The driver that is on USB-Stick supports all products of the digitizerNETBOX/generatorNETBOX family as well as all cards of the M2i/M3i/M4i/M4x/M2p series. That means that you can use the same driver for all products of these families.

## **Needed Software for operating**

The digitizerNETBOX/generatorNETBOX comes fully installed and ready to start. However to operate the digitizerNETBOX or generatorNETBOX from the client PC there need to be some software packages to be installed there:

### **Spectrum driver API**

The Spectrum API is installed automatically under Windows when installing the Card Control Center. Under Linux it is necessary to install the matching driver API for your Linux client system before installing the Card Control Center.

### **Spectrum Card Control Center**

This software is the maintenance tool for all Spectrum products. In here the digitizerNETBOX/generatorNETBOX can be searched inside the LAN (Discovery function), all hardware information is found, updates and product tests can be done. The Card Control Center and all of its functions are explained in greater detail later on in this manual.

The card control center is available for Windows and Linux, both 32 bit and 64 bit (Windows 32 bit version also runs on WOW64)

### **SBench 6**

SBench 6 allows to operate the digitizerNETBOX/generatorNETBOX in all hardware modes, displays data, streams to hard disk and allows to make calculations and exports. The digitizerNETBOX/generatorNETBOX is equipped with a full SBench 6 Professional license. Even if you want to operate the digitizerNETBOX/generatorNETBOX from your self written software it is recommended that you install SBench 6 to do first hardware tests and to validate your own software results with the software from the hardware manufacturer. For SBench 6 a dedicated manual is installed with the software package.

SBench 6 is available for Windows and Linux, both 32 bit and 64 bit (Windows 32 bit version also runs on WOW64)

### **Examples and Drivers**

If you intend to operate the digitizerNETBOX/generatorNETBOX from a self written program, be it IVI based, C++, C#, LabVIEW, MATLAB or something else, it is necessary to install the matching drivers and examples for the platform you want to run.

## **Location**

The needed software for operating the digitizerNETBOX/generatorNETBOX can be found on three different locations. Please choose the one most convenient for you.

### **Install software packages from USB-Stick**

The USB-Stick that is delivered together with the digitizerNETBOX/generatorNETBOX contains the complete software and documentation package that is available for your digitizerNETBOX/generatorNETBOX. You find the software packages at the following locations on the USB-Stick:

Software Package	Operating System	Location
Card Control Center	Windows	\Install\Win
SBench 6	Windows	\Install\Win
LabVIEW, MATLAB, IVI	Windows	\Install\Win
C++, C#, VB.NET, Delphi, Python, Java, LabWindows/CVI...	Windows	\Examples\...
Driver API	Linux	/Driver/linux/install_libonly.sh
Card Control Center	Linux	/Install/linux/SBench6
SBench 6	Linux	/Install/linux/spcm_control_center
MATLAB (64bit only)	Linux	/Install/linux
C++, Python, Java	Linux	/Examples/...

### **Install software packages from the internet**

All software packages are found on the download page under [www.spectrum-instrumentation.com](http://www.spectrum-instrumentation.com)

In here the latest versions and updates are available.

### **Install software packages from the digitizerNETBOX/generatorNETBOX**

For easy installation or for installation on machines that don't have access to a USB thumb drive, all software packages are also available for download directly from the digitizerNETBOX/generatorNETBOX.

Please go to the download page of the integrated webserver and download and execute the software packages.

## **Linux**

### **Overview**

The Spectrum M2i/M3i/M4i/M4x/M2p cards and digitizerNETBOX/generatorNETBOX products are delivered with Linux drivers suitable for Linux installations based on kernel 2.6, 3.x, 4.x or 5.x, single processor (non-SMP) and SMP systems, 32 bit and 64 bit systems. As each Linux distribution contains different kernel versions and different system setup it is in nearly every case necessary, to have a directly matching kernel driver for card level products to run it on a specific system. For digitizerNETBOX/generatorNETBOX products the library is sufficient and no kernel driver has to be installed.

Spectrum delivers pre-compiled kernel driver modules for a number of common distributions with the cards. You may try to use one of these kernel modules for different distributions which have a similar kernel version. Unfortunately this won't work in most cases as most Linux system refuse to load a driver which is not exactly matching. In this case it is possible to get the kernel driver sources from Spectrum. Please contact your local sales representative to get more details on this procedure.

The Standard delivery contains the pre-compiled kernel driver modules for the most popular Linux distributions, like Suse, Debian, Fedora and Ubuntu. The list with all pre-compiled and readily supported distributions and their respective kernel version can be found under:

<http://spectrum-instrumentation.com/en/supported-linux-distributions> or via the shown QR code.

The Linux drivers have been tested with all above mentioned distributions by Spectrum. Each of these distributions has been installed with the default setup using no kernel updates. A lot more different distributions are used by customers with self compiled kernel driver modules.



### **Standard Driver Installation**

The driver is delivered as installable kernel modules together with libraries to access the kernel driver. The installation script will help you with the installation of the kernel module and the library.

**This installation is only needed if you are operating real locally installed cards. For software emulated demo cards, remotely installed cards or for digitizerNETBOX/generatorNETBOX products it is only necessary to install the libraries without a kernel as explained further below.**



#### **Login as root**

It is necessary to have the root rights for installing a driver.

#### **Call the install.sh <install path> script**

This script will install the kernel module and some helper scripts to a given directory. If you do not specify a directory it will use your home directory as destination. It is possible to move the installed driver files later to any other directory.

The script will give you a list of matching kernel modules. Therefore it checks for the system width (32 bit or 64 bit) and the processor (single or smp). The script will only show matching kernel modules. Select the kernel module matching your system. The script will then do the following steps:

- copy the selected kernel module to the install directory (spcm.o or spcm.ko)
- copy the helper scripts to the install directory (spcm\_start.sh and spcm\_end.sh)
- copy and rename the matching library to /usr/lib (/usr/lib/libspcm\_linux.so)

#### **Udev support**

Once the driver is loaded it automatically generates the device nodes under /dev. The cards are automatically named to /dev/spcm0, /dev/spcm1, ...

You may use all the standard naming and rules that are available with udev.

#### **Start the driver**

Starting the driver can be done with the spcm\_start.sh script that has been placed in the install directory. If udev is installed the script will only load the driver. If no udev is installed the start script will load the driver and make the required device nodes /dev/spcm0... for accessing the drivers. Please keep in mind that you need root rights to load the kernel module and to make the device nodes!

Using the dedicated start script makes sure that the device nodes are matching your system setup even if new hardware and drivers have been added in between. Background: when loading the device driver it gets assigned a „major“ number that is used to access this driver. All device nodes point to this major number instead of the driver name. The major numbers are assigned first come first served. This means that installing new hardware may result in different major numbers on the next system start.

### **Get first driver info**

After the driver has been loaded successfully some information about the installed boards can be found in the /proc/spcm\_cards file. Some basic information from the on-board EEPROM is listed for every card.

```
cat /proc/spcm_cards
```

### **Stop the driver**

You may want to unload the driver and clean up all device nodes. This can be done using the spcm\_end.sh script that has also been placed in the install directory

### **Standard Driver Update**

A driver update is done with the same commands as shown above. Please make sure that the driver has been stopped before updating it. To stop the driver you may use the spcm\_end.sh script.

### **Compilation of kernel driver sources (optional and local cards only)**

The driver sources are only available for existing customers upon special request. Please send an email to Support@spec.de to receive the kernel driver sources. The driver sources are not part of the standard delivery. The driver source package contains only the sources of the kernel module, not the sources of the library.

Please do the following steps for compilation and installation of the kernel driver module:

#### **Login as root**

It is necessary to have the root rights for installing a driver.

#### **Call the compile script make spcm linux kerneldrv.sh**

This script will examine the type of system you use and compile the kernel with the correct settings. If using a kernel 2.4 the makefile expects two symbolic links in your system:

- /usr/src/linux pointing to the correct kernel source directory
- /usr/src/linux/.config pointing to the currently used kernel configuration

The compile script will then automatically call the install script and install the just compiled kernel module in your home directory. The rest of the installation procedure is similar as explained above.

### **Update of a self compiled kernel driver**

If the kernel driver has changed, one simply has to perform the same steps as shown above and recompile the kernel driver module. However the kernel driver module isn't changed very often.

Normally an update only needs new libraries. To update the libraries only you can either download the full Linux driver (spcm\_linux\_drv\_v123b4567) and only use the libraries out of this or one downloads the library package which is much smaller and doesn't contain the pre-compiled kernel driver module (spcm\_linux\_lib\_v123b4567).

The update is done with a dedicated script which only updates the library file. This script is present in both driver archives:

```
sh install_libonly.sh
```

### **Installing the library only without a kernel (for remote devices)**

The kernel driver module only contains the basic hardware functions that are necessary to access locally installed card level products. The main part of the driver is located inside a dynamically loadable library that is delivered with the driver. This library is available in 3 different versions:

- spcm\_linux\_32bit\_stdc++6.so - supporting libstdc++.so.6 on 32 bit systems
- spcm\_linux\_64bit\_stdc++6.so - supporting libstdc++.so.6 on 64 bit systems

The matching version is installed automatically in the /usr/lib directory by the kernel driver install script for card level products. The library is renamed for easy access to libspcm\_linux.so.

For digitizerNETBOX/generatorNETBOX products and also for evaluating or using only the software simulated demo cards the library is installed with a separate install script:

```
sh install_libonly.sh
```

To access the driver library one must include the library in the compilation:

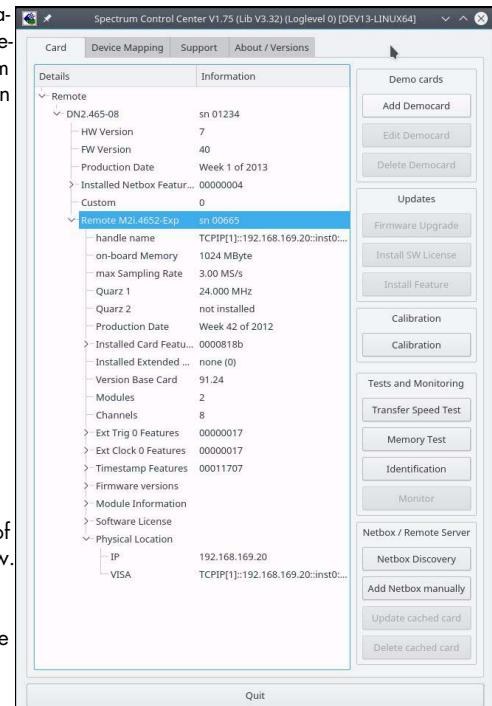
```
gcc -o test_prg -lspcm_linux test.cpp
```

To start programming the cards under Linux please use the standard C/C++ examples which are all running under Linux and Windows.

## Control Center

The Spectrum Control Center is also available for Linux and needs to be installed separately. The features of the Control Center are described in a later chapter in deeper detail. The Control Center has been tested under all Linux distributions for which Spectrum delivers pre-compiled kernel modules. The following packages need to be installed to run the Control Center:

- X-Server
- expat
- freetype
- fontconfig
- libpng
- libspcm\_linux (the Spectrum linux driver library)



## Installation

Use the supplied packages in either \*.deb or \*.rpm format found in the driver section of the USB-Stick by double clicking the package file root rights from a X-Windows window.

The Control Center is installed under KDE, Gnome or Unity in the system/system tools section. It may be located directly in this menu or under a „More Programs“ menu. The final location depends on the used Linux distribution. The program itself is installed as /usr/bin/spcmcontrol and may be started directly from here.

## Manual Installation

To manually install the Control Center, first extract the files from the rpm matching your distribution:

```
rpm2cpio spcmcontrol-{Version}.rpm > ~/spcmcontrol-{Version}.cpio
cd ~/
cpio -id < spcmcontrol-{Version}.cpio
```

You get the directory structure and the files contained in the rpm package. Copy the binary spcmcontrol to /usr/bin. Copy the .desktop file to /usr/share/applications. Run ldconfig to update your systems library cache. Finally you can run spcmcontrol.

## Troubleshooting

If you get a message like the following after starting spcmcontrol:

```
spcm_control: error while loading shared libraries: libz.so.1: cannot open shared object file: No such file
or directory
```

Run ldd spcm\_control in the directory where spcm\_control resides to see the dependencies of the program. The output may look like this:

```
libXext.so.6 => /usr/X11R6/lib/libXext.so.6 (0x4019e000)
libX11.so.6 => /usr/X11R6/lib/libX11.so.6 (0x401ad000)
libz.so.1 => not found
libdl.so.2 => /lib/libdl.so.2 (0x402ba000)
libpthread.so.0 => /lib/tls/libpthread.so.0 (0x402be000)
libstdc++.so.6 => /usr/lib/libstdc++.so.6 (0x402d0000)
```

As seen in the output, one of the libraries isn't found inside the library cache of the system. Be sure that this library has been properly installed. You may then run ldconfig. If this still doesn't help please add the library path to /etc/ld.so.conf and run ldconfig again.

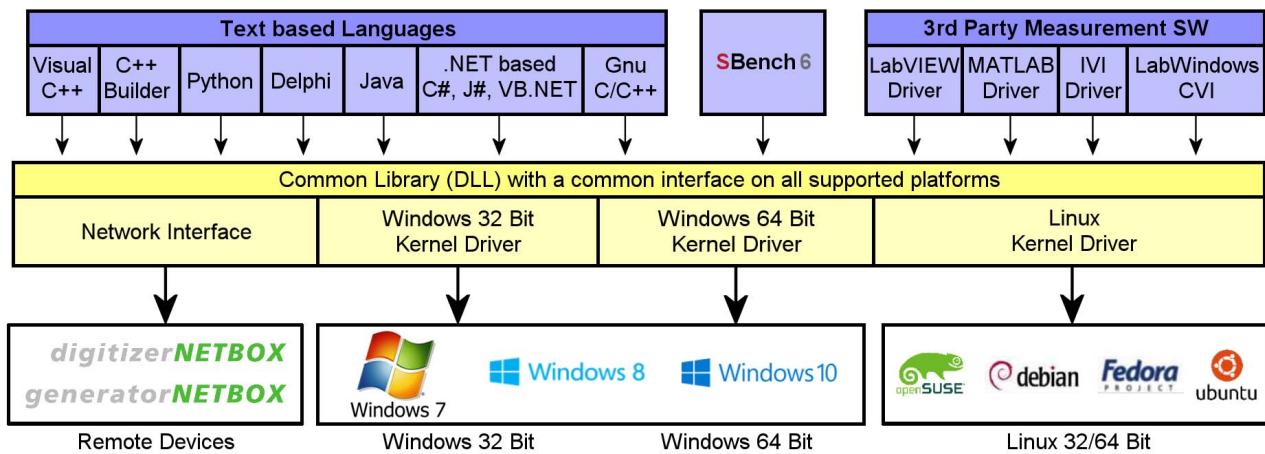
If the libspcm\_linux.so is quoted as missing please make sure that you have installed the card driver properly before. If any other library is stated as missing please install the matching package of your distribution.

## Software

This chapter gives you an overview about the structure of the drivers and the software, where to find and how to use the examples. It shows in detail, how the drivers are included using different programming languages and deals with the differences when calling the driver functions from them.

**⚠ This manual only shows the use of the standard driver API. For further information on programming drivers for third-party software like LabVIEW, MATLAB or IVI an additional manual is required that is available on USB-Stick or by download on the internet.**

## Software Overview



The Spectrum drivers offer you a common and fast API for using all of the board hardware features. This API is the same on all supported operating systems. Based on this API one can write own programs using any programming language that can access the driver API. This manual describes in detail the driver API, providing you with the necessary information to write your own programs. The drivers for third-party products like LabVIEW or MATLAB are also based on this API. The special functionality of these drivers is not subject of this document and is described with separate manuals available on the USB-Stick or on the website.

## Card Control Center

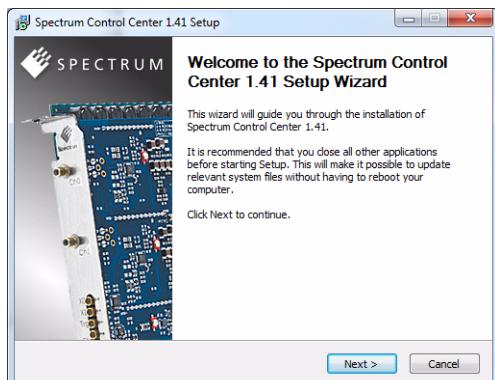
A special card control center is available on USB-Stick and from the internet for all Spectrum M2i/M3i/M4i/M4x/M2p cards and for all digitizerNETBOX or generatorNETBOX products. Windows users find the Control Center installer on the USB-Stick under „Install\win\spcmcontrol\_install.exe“.

Linux users find the versions for the different stdc++ libraries under /Install/linux/spcm\_control\_center/ as RPM packages.

When using a digitizerNETBOX/generatorNETBOX the Card Control Center installers for Windows and Linux are also directly available from the integrated webserver.

The Control Center under Windows and Linux is available as an executive program. Under Windows it is also linked as a system control and can be accessed directly from the Windows control panel. Under Linux it is also available from the KDE System Settings, the Gnome or Unity Control Center. The different functions of the Spectrum card control center are explained in detail in the following passages.

**💡 To install the Spectrum Control Center you will need to be logged in with administrator rights for your operating system. On all Windows versions, starting with Windows Vista, installations with enabled UAC will ask you to start the installer with administrative rights (run as administrator).**



## **Discovery of Remote Cards and digitizerNETBOX/generatorNETBOX products**

The Discovery function helps you to find and identify the Spectrum LXI instruments like digitizerNETBOX/generatorNETBOX available to your computer on the network. The Discovery function will also locate Spectrum card products handled by an installed Spectrum Remote Server somewhere on the network. The function is not needed if you only have locally installed cards.

Please note that only remote products are found that are currently not used by another program. Therefore in a bigger network the number of Spectrum products found may vary depending on the current usage of the products.

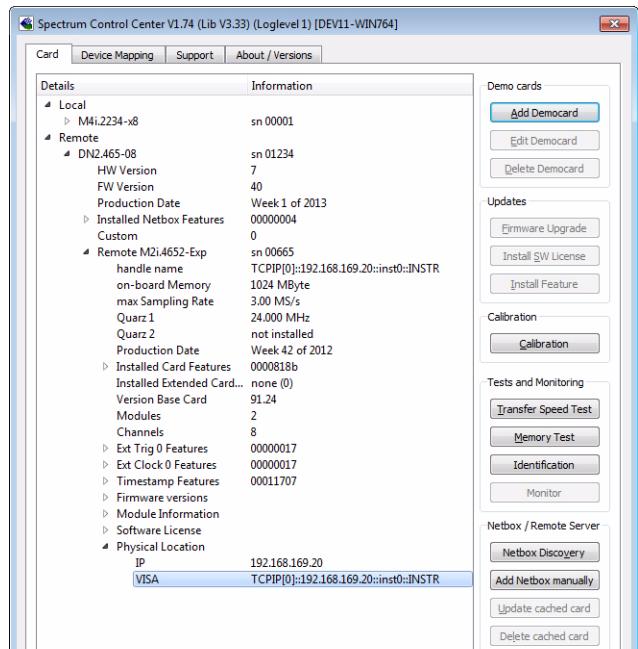
Execute the Discovery function by pressing the „Discovery“ button. There is no progress window shown. After the discovery function has been executed the remotely found Spectrum products are listed under the node Remote as separate card level products. Inhere you find all hardware information as shown in the next topic and also the needed VISA resource string to access the remote card.

Please note that these information is also stored on your system and allows Spectrum software like SBench 6 to access the cards directly once found with the Discovery function.

After closing the control center and re-opening it the previously found remote products are shown with the prefix cached, only showing the card type and the serial number. This is the stored information that allows other Spectrum products to access previously found cards. Using the „Update cached cards“ button will try to re-open these cards and gather information of it. Afterwards the remote cards may disappear if they're in use from somewhere else or the complete information of the remote products is shown again.

## **Enter IP Address of digitizerNETBOX/generatorNETBOX manually**

If for some reason an automatic discovery is not suitable, such as the case where the remote device is located in a different subnet, it can also be manually accessed by its type and IP address.



## **Wake On LAN of digitizerNETBOX/generatorNETBOX**

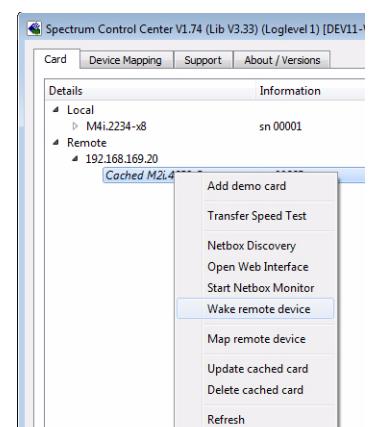
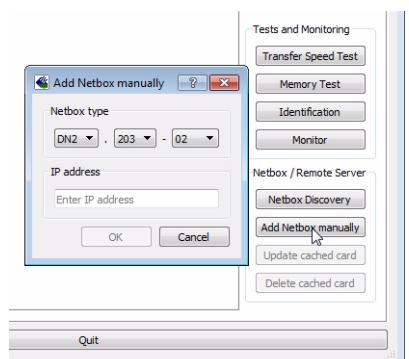
Cached digitizerNETBOX/generatorNETBOX products that are currently in standby mode can be woken up by using the „Wake remote device“ entry from the context menu.

The Control Center will broadcast a standard Wake On LAN „Magic Packet“, that is sent to the device's MAC address.

It is also possible to use any other Wake On LAN software to wake a digitizerNETBOX by sending such a „Magic Packet“ to the MAC address, which must be then entered manually.

It is also possible to wake a digitizerNETBOX/generatorNETBOX from your own application software by using the SPC\_NETBOX\_WAKEONLAN register. To wake a digitizerNETBOX/generatorNETBOX with the MAC address „00:03:2d:20:48“, the following command can be issued:

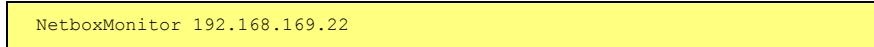
```
spcm_dwSetParam_i64 (NULL, SPC_NETBOX_WAKEONLAN, 0x00032d2048ec);
```



## **Netbox Monitor**

The Netbox Monitor permanently monitors whether the digitizerNETBOX/generatorNETBOX is still available through LAN. This tool is helpful if the digitizerNETBOX is located somewhere in the company LAN or located remotely or directly mounted inside another device. Starting the Netbox Monitor can be done in two different ways:

- Starting manually from the Spectrum Control Center using the context menu as shown above
- Starting from command line. The Netbox Monitor program is automatically installed together with the Spectrum Control Center and is located in the selected install folder. Using the command line tool one can place a simple script into the autostart folder to have the Netbox Monitor running automatically after system boot. The command line tool needs the IP address of the digitizerNETBOX/generatorNETBOX to monitor:



The Netbox Monitor is shown as a small window with the type of digitizerNETBOX/generatorNETBOX in the title and the IP address under which it is accessed in the window itself. The Netbox Monitor runs completely independent of any other software and can be used in parallel to any application software. The background of the IP address is used to display the current status of the device. Pressing the Escape key or alt + F4 (Windows) terminates the Netbox Monitor permanently.

DN2.462-08...  
192.168.169.22

After starting the Netbox Monitor it is also displayed as a tray icon under Windows. The tray icon itself shows the status of the digitizerNETBOX/generatorNETBOX as a color. Please note that the tray icon may be hidden as a Windows default and need to be set to visible using the Windows tray setup.



Left clicking on the tray icon will hide/show the small Netbox Monitor status window. Right clicking on the tray icon as shown in the picture on the right will open up a context menu. In here one can again select to hide/show the Netbox Monitor status window, one can directly open the web interface from here or quit the program (including the tray icon) completely.

The checkbox „Show Status Message“ controls whether the tray icon should emerge a status message on status change. If enabled (which is default) one is notified with a status message if for example the LAN connection to the digitizerNETBOX/generatorNETBOX is lost.

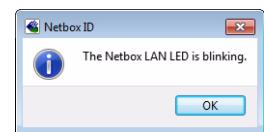
The status colors:

- Green: digitizerNETBOX/generatorNETBOX available and accessible over LAN
- Cyan: digitizerNETBOX/generatorNETBOX is used from my computer
- Yellow: digitizerNETBOX/generatorNETBOX is used from a different computer
- Red: LAN connection failed, digitizerNETBOX/generatorNETBOX is no longer accessible

## **Device identification**

Pressing the *Identification* button helps to identify a certain device in either a remote location, such as inside a 19" rack where the back of the device with the type plate is not easily accessible, or a local device installed in a certain slot. Pressing the button starts flashing a visible LED on the device, until the dialog is closed, for:

- On a digitizerNETBOX or generatorNETBOX: the LAN LED light on the front plate of the device
- On local or remote M4i, M4x or M2p card: the indicator LED on the card's bracket

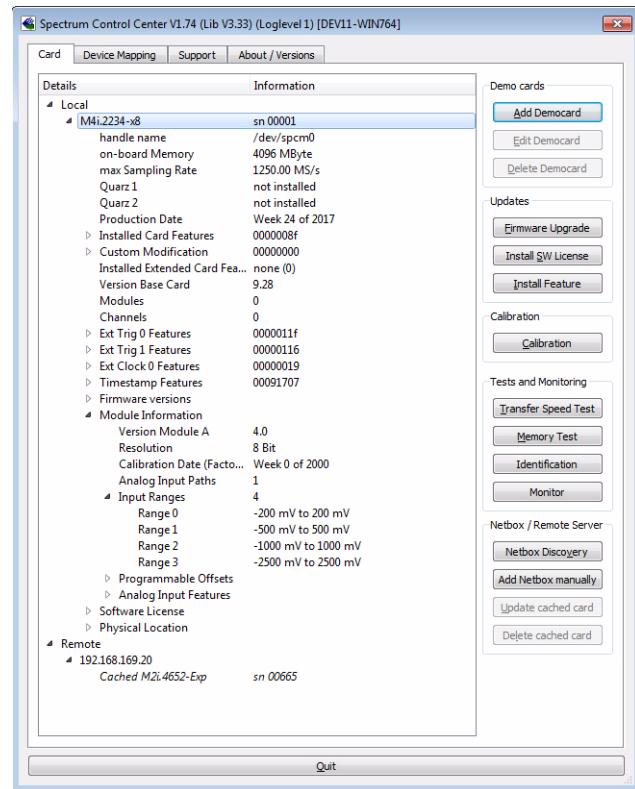


This feature is not available for M2i/M3i cards, either local or remote, other than inside a digitizerNETBOX or generatorNETBOX.

## Hardware information

Through the control center you can easily get the main information about all the installed Spectrum hardware. For each installed card there is a separate tree of information available. The picture shows the information for one installed card by example. This given information contains:

- Basic information as the type of card, the production date and its serial number, as well as the installed memory, the hardware revision of the base card, the number of available channels and installed acquisition modules.
- Information about the maximum sampling clock and the available quartz clock sources.
- The installed features/options in a sub-tree. The shown card is equipped for example with the option Multiple Recording, Gated Sampling, Timestamp and ABA-mode.
- Detailed Information concerning the installed acquisition modules. In case of the shown analog acquisition card the information consists of the module's hardware revision, of the converter resolution and the last calibration date as well as detailed information on the available analog input ranges, offset compensation capabilities and additional features of the inputs.



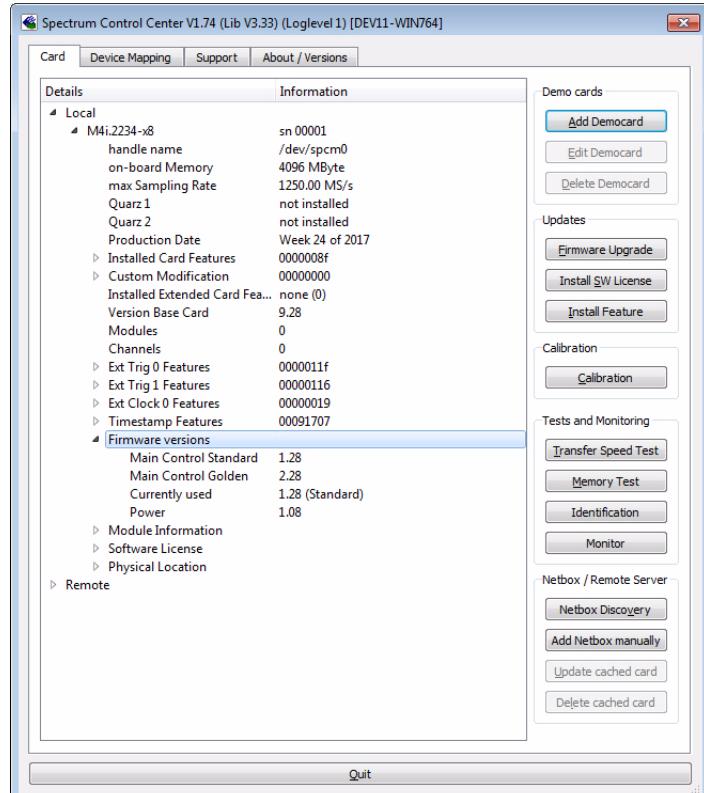
## Firmware information

Another sub-tree is informing about the cards firmware version. As all Spectrum cards consist of several programmable components, there is one firmware version per component.

Nearly all of the components firmware can be updated by software. The only exception is the configuration device, which only can receive a factory update.

The procedure on how to update the firmware of your Spectrum card with the help of the card control center is described in a dedicated section later on.

The procedure on how to update the firmware of your digitizerNETBOX/generatorNETBOX with the help of the integrated Webserver is described in a dedicated chapter later on.

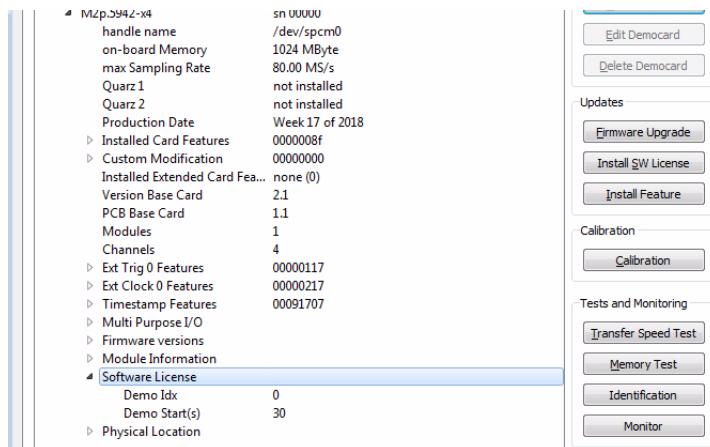


## Software License information

This sub-tree is informing about installed possible software licenses.

As a default all cards come with the demo professional license of SBench6, that is limited to 30 starts of the software with all professional features unlocked.

The number of demo starts left can be seen here.



## Driver information

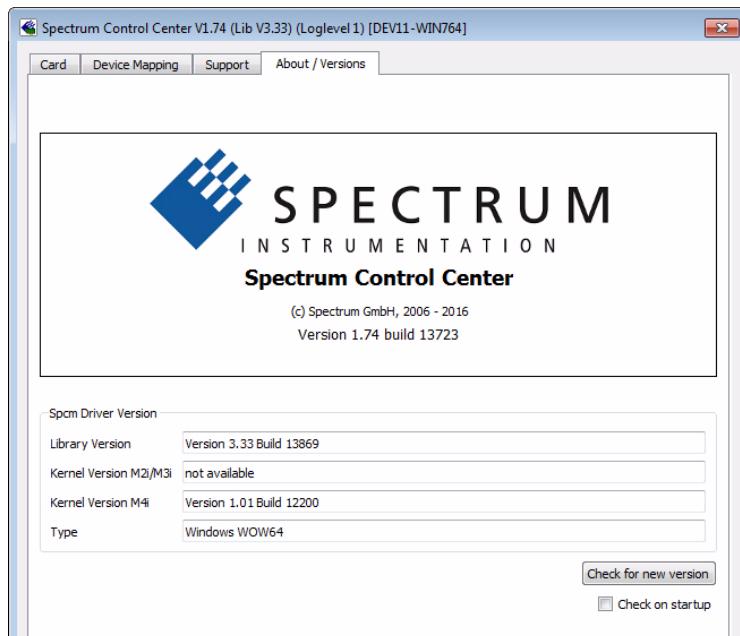
The Spectrum card control center also offers a way to gather information on the installed and used Spectrum driver.

The information on the driver is available through a dedicated tab, as the picture is showing in the example.

The provided information informs about the used type, distinguishing between Windows or Linux driver and the 32 bit or 64 bit type.

It also gives direct information about the version of the installed Spectrum kernel driver, separately for M2i/ M3i cards and M4i/M4x/M2p cards and the version of the library (which is the \*.dll file under Windows).

The information given here can also be found under Windows using the device manager from the control panel. For details in driver details within the control panel please stick to the section on driver installation in your hardware manual.

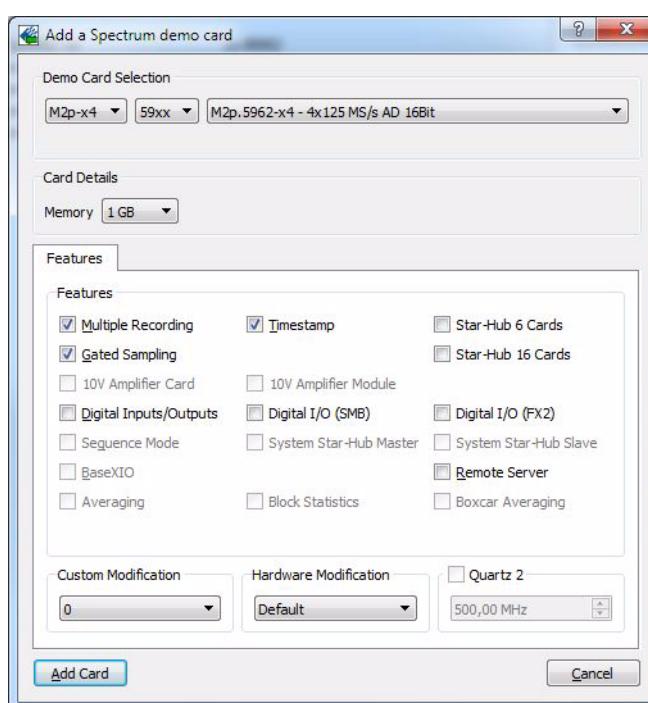


## Installing and removing Demo cards

With the help of the card control center one can install demo cards in the system. A demo card is simulated by the Spectrum driver including data production for acquisition cards. As the demo card is simulated on the lowest driver level all software can be tested including SBench, own applications and drivers for third-party products like LabVIEW. The driver supports up to 64 demo cards at the same time. The simulated memory as well as the simulated software options can be defined when adding a demo card to the system.

Please keep in mind that these demo cards are only meant to test software and to show certain abilities of the software. They do not simulate the complete behavior of a card, especially not any timing concerning trigger, recording length or FIFO mode notification. The demo card will calculate data every time directly after been called and give it to the user application without any more delay. As the calculation routine isn't speed optimized, generating demo data may take more time than acquiring real data and transferring them to the host PC.

Installed demo cards are listed together with the real hardware in the main information tree as described above. Existing demo cards can be deleted by clicking the related button. The demo card details can be edited by using the edit button. It is for example possible to virtually install additional feature to one card or to change the type to test with a different number of channels.



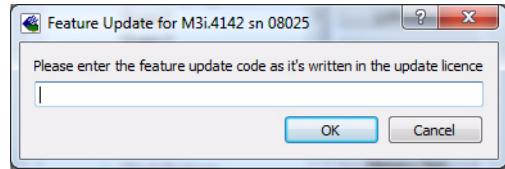


**For installing demo cards on a system without real hardware simply run the Control Center installer. If the installer is not detecting the necessary driver files normally residing on a system with real hardware, it will simply install the Spcm\_driver.**

### **Feature upgrade**

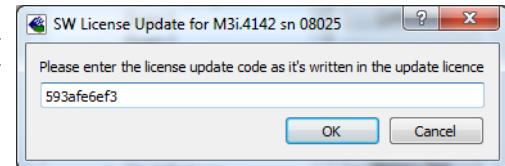
All optional features of the M2i/M3i/M4i/M4x/M2p cards that do not require any hardware modifications can be installed on fielded cards. After Spectrum has received the order, the customer will get a personalized upgrade code. Just start the card control center, click on „install feature“ and enter that given code. After a short moment the feature will be installed and ready to use. No restart of the host system is required.

For details on the available options and prices please contact your local Spectrum distributor.



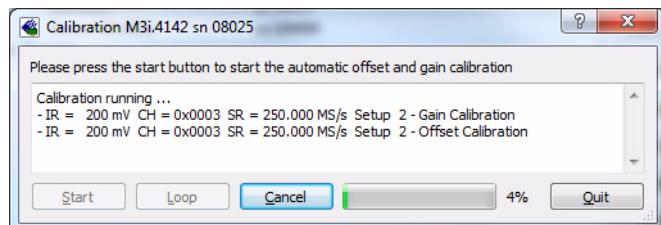
### **Software License upgrade**

The software license for SBench 6 Professional is installed on the hardware. If ordering a software license for a card that has already been delivered you will get an upgrade code to install that software license. The upgrade code will only match for that particular card with the serial number given in the license. To install the software license please click the „Install SW License“ button and type in the code exactly as given in the license.



### **Performing card calibration**

The card control center also provides an easy way to access the automatic card calibration routines of the Spectrum A/D converter cards. Depending on the used card family this can affect offset calibration only or also might include gain calibration. Please refer to the dedicated chapter in your hardware manual for details.

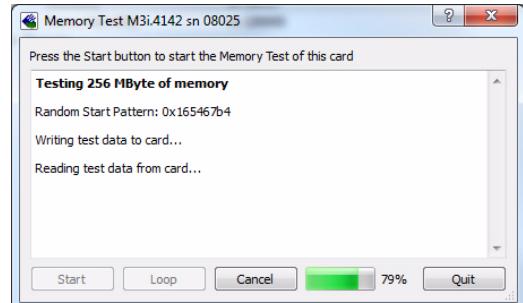


### **Performing memory test**

The complete on-board memory of the Spectrum M2i/M3i/M4i/M4x/M2p cards can be tested by the memory test included with the card control center.

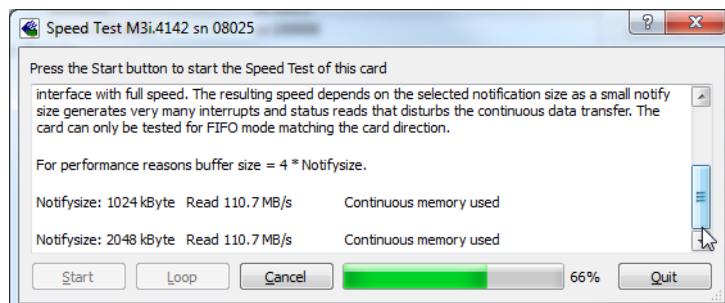
When starting the test, randomized data is generated and written to the on-board memory. After a complete write cycle all the data is read back and compared with the generated pattern.

Depending on the amount of installed on-board memory, and your computer's performance this operation might take a while.



### **Transfer speed test**

The control center allows to measure the bus transfer speed of an installed Spectrum card. Therefore different setup is run multiple times and the overall bus transfer speed is measured. To get reliable results it is necessary that you disable debug logging as shown below. It is also highly recommended that no other software or time-consuming background threads are running on that system. The speed test program runs the following two tests:



- Repetitive Memory Transfers: single DMA data transfers are repeated and measured. This test simulates the measuring of pulse repetition frequency when doing multiple single-shots. The test is done using different block sizes. One can estimate the transfer in relation to the transferred data size on multiple single-shots.
- FIFO mode streaming: this test measures the streaming speed in FIFO mode. The test can only use the same direction of transfer the card has been designed for (card to PC=read for all DAQ cards, PC to card=write for all generator cards and both directions for I/O cards). The streaming speed is tested without using the front-end to measure the maximum bus speed that can be reached. The Speed in FIFO mode depends on the selected notify size which is explained later in this manual in greater detail.

The results are given in MB/s meaning MByte per second. To estimate whether a desired acquisition speed is possible to reach one has to calculate the transfer speed in bytes. There are a few things that have to be put into the calculation:

- 12, 14 and 16 bit analog cards need two bytes for each sample.
- 16 channel digital cards need 2 bytes per sample while 32 channel digital cards need 4 bytes and 64 channel digital cards need 8 bytes.
- The sum of analog channels must be used to calculate the total transfer rate.
- The figures in the Speed Test Utility are given as MBytes, meaning  $1024 * 1024$  Bytes, 1 MByte = 1048576 Bytes

As an example running a card with 2 14 bit analog channels with 28 MHz produces a transfer rate of [2 channels \* 2 Bytes/Sample \* 28000000] = 112000000 Bytes/second. Taking the above figures measured on a standard 33 MHz PCI slot the system is just capable of reaching this transfer speed:  $108.0$  MB/s =  $108 * 1024 * 1024 = 113246208$  Bytes/second.

Unfortunately it is not possible to measure transfer speed on a system without having a Spectrum card installed.

## **Debug logging for support cases**

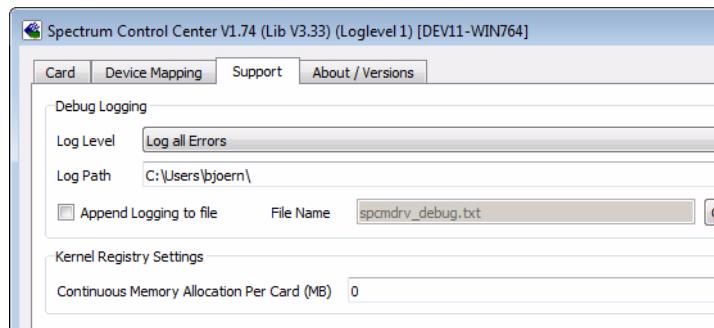
For answering your support questions as fast as possible, the setup of the card, driver and firmware version and other information is very helpful.

Therefore the card control center provides an easy way to gather all that information automatically.

Different debug log levels are available through the graphical interface. By default the log level is set to „no logging“ for maximum performance.

The customer can select different log levels and the path of the generated ASCII text file. One can also decide to delete the previous log file first before creating a new one automatically or to append different logs to one single log file.

** For maximum performance of your hardware, please make sure that the debug logging is set to „no logging“ for normal operation. Please keep in mind that a detailed logging in append mode can quickly generate huge log files.**



## **Device mapping**

Within the „Device mapping“ tab of the Spectrum Control Center, one can enable the re-mapping of Spectrum devices, be it either local cards, remote instruments such as a digitizerNETBOX or generatorNETBOX or even cards in a remote PC and accessed via the Spectrum remote server option.

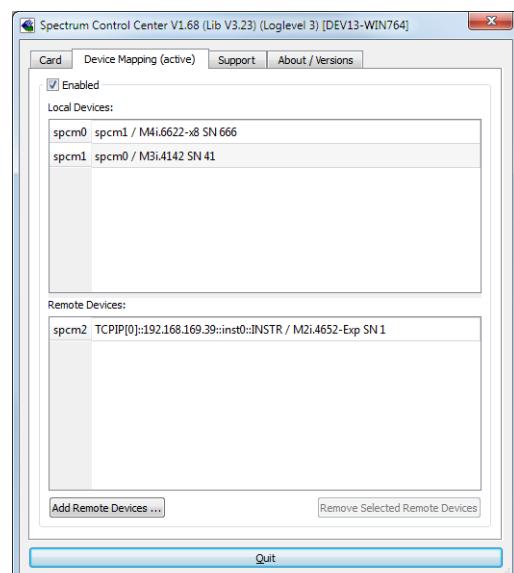
In the left column the re-mapped device name is visible that is given to the device in the right column with its original un-mapped device string.

In this example the two local cards „spcm0“ and „spcm1“ are re-mapped to „spcm1“ and „spcm0“ respectively, so that their names are simply swapped.

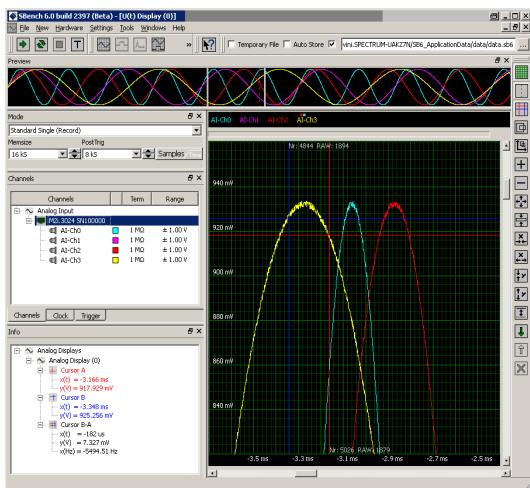
The remote digitizerNETBOX device is mapped to spcm2.

The application software can then use the re-mapped name for simplicity instead of the quite long VISA string.

Changing the order of devices within one group (either local cards or remote devices) can simply be accomplished by dragging&dropping the cards to their desired position in the same table.



## Accessing the hardware with SBench 6



After the installation of the cards and the drivers it can be useful to first test the card function with a ready to run software before starting with programming. If accessing a digitizerNETBOX/generatorNETBOX a full SBench 6 Professional license is installed on the system and can be used without any limitations. For plug-in card level products a base version of SBench 6 is delivered with the card on USB-Stick also including a 30 starts Professional demo version for plain card products. If you already have bought a card prior to the first SBench 6 release please contact your local dealer to get a SBench 6 Professional demo version. All digitizerNETBOX/generatorNETBOX products come with a pre-installed full SBench 6 Professional.

SBench 6 supports all current acquisition and generation cards and digitizerNETBOX/generatorNETBOX products from Spectrum. Depending on the used product and the software setup, one can use SBench as a digital storage oscilloscope, a spectrum analyzer, a signal generator, a pattern generator, a logic analyzer or simply as a data recording front end. Different export and import formats allow the use of SBench 6 together with a variety of other programs.

On the USB-Stick you'll find an install version of SBench 6 in the directory „/Install/SBench6“.

The current version of SBench 6 is available free of charge directly from the Spectrum website: [www.spectrum-instrumentation.com](http://www.spectrum-instrumentation.com). Please go to the download section and get the latest version there.

SBench 6 has been designed to run under Windows 7, Windows 8 and Windows 10 as well as Linux using KDE, Gnome or Unity Desktop.

## C/C++ Driver Interface

C/C++ is the main programming language for which the drivers have been designed for. Therefore the interface to C/C++ is the best match. All the small examples of the manual showing different parts of the hardware programming are done with C. As the libraries offer a standard interface it is easy to access the libraries also with other programming languages like Delphi, Basic, Python or Java . Please read the following chapters for additional information on this.

### Header files

The basic task before using the driver is to include the header files that are delivered on USB-Stick together with the board. The header files are found in the directory /Driver/c\_header. Please don't change them in any way because they are updated with each new driver version to include the new registers and new functionality.

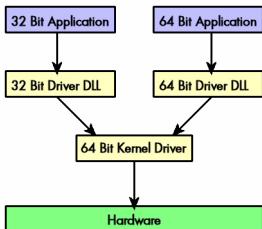
dlltyp.h	Includes the platform specific definitions for data types and function declarations. All data types are based on these definitions. The use of this type definition file allows the use of examples and programs on different platforms without changes to the program source. The header file supports Microsoft Visual C++, Borland C++ Builder and GNU C/C++ directly. When using other compilers it might be necessary to make a copy of this file and change the data types according to this compiler.
regs.h	Defines all registers and commands which are used in the Spectrum driver for the different boards. The registers a board uses are described in the board specific part of the documentation. This header file is common for all cards. Therefore this file also contains a huge number of registers used on other card types than the one described in this manual. Please stick to the manual to see which registers are valid for your type of card.
spcm_drv.h	Defines the functions of the used SpcM driver. All definitions are taken from the file dlltyp.h. The functions themselves are described below.
spcerr.h	Contains all error codes used with the Spectrum driver. All error codes that can be given back by any of the driver functions are also described here briefly. The error codes and their meaning are described in detail in the appendix of this manual.

Example for including the header files:

```
// ----- driver includes -----
#include "dlltyp.h"           // 1st include
#include "regs.h"              // 2nd include
#include "spcerr.h"             // 3rd include
#include "spcm_drv.h"           // 4th include
```

**! Please always keep the order of including the four Spectrum header files. Otherwise some or all of the functions do not work properly or compiling your program will be impossible!**

## **General Information on Windows 64 bit drivers**



After installation of the Spectrum 64 bit driver there are two general ways to access the hardware and to develop applications. If you're going to develop a real 64 bit application it is necessary to access the 64 bit driver dll (spcm\_win64.dll) as only this driver dll is supporting the full 64 bit address range.

But it is still possible to run 32 bit applications or to develop 32 bit applications even under Windows 64 bit. Therefore the 32 bit driver dll (spcm\_win32.dll) is also installed in the system. The Spectrum SBench5 software is for example running under Windows 64 bit using this driver. The 32 bit dll of course only offers the 32 bit address range and is therefore limited to access only 4 GByte of memory. Beneath both drivers the 64 bit kernel driver is running.

Mixing of 64 bit application with 32 bit dll or vice versa is not possible.

## **Microsoft Visual C++ 6.0, 2005 and newer 32 Bit**

### **Include Driver**

The driver files can be directly included in Microsoft C++ by simply using the library file spcm\_win32\_msvcpp.lib that is delivered together with the drivers. The library file can be found on the USB-Stick in the path /examples/c\_cpp/c\_header. Please include the library file in your Visual C++ project as shown in the examples. All functions described below are now available in your program.

### **Examples**

Examples can be found on USB-Stick in the path /examples/c\_cpp. This directory includes a number of different examples that can be used with any card of the same type (e.g. A/D acquisition cards, D/A acquisition cards). You may use these examples as a base for own programming and modify them as you like. The example directories contain a running workspace file for Microsoft Visual C++ 6.0 (\*.dsw) as well as project files for Microsoft Visual Studio 2005 and newer (\*.vcproj) that can be directly loaded or imported and compiled. There are also some more board type independent examples in separate subdirectory. These examples show different aspects of the cards like programming options or synchronization and can be combined with one of the board type specific examples.

As the examples are build for a card class there are some checking routines and differentiation between cards families. Differentiation aspects can be number of channels, data width, maximum speed or other details. It is recommended to change the examples matching your card type to obtain maximum performance. Please be informed that the examples are made for easy understanding and simple showing of one aspect of programming. Most of the examples are not optimized for maximum throughput or repetition rates.

## **Microsoft Visual C++ 2005 and newer 64 Bit**

Depending on your version of the Visual Studio suite it may be necessary to install some additional 64 bit components (SDK) on your system. Please follow the instructions found on the MSDN for further information.

### **Include Driver**

The driver files can be directly included in Microsoft C++ by simply using the library file spcm\_win64\_msvcpp.lib that is delivered together with the drivers. The library file can be found on the USB-Stick in the path /examples/c\_cpp/c\_header. All functions described below are now available in your program.

## **C++ Builder 32 Bit**

### **Include Driver**

The driver files can be easily included in C++ Builder by simply using the library file spcm\_win32\_bcppb.lib that is delivered together with the drivers. The library file can be found on the USB-Stick in the path /examples/c\_cpp/c\_header. Please include the library file in your C++ Builder project as shown in the examples. All functions described below are now available in your program.

### **Examples**

The C++ Builder examples share the sources with the Visual C++ examples. Please see above chapter for a more detailed documentation of the examples. In each example directory are project files for Visual C++ as well as C++ Builder.

## **Linux Gnu C/C++ 32/64 Bit**

### **Include Driver**

The interface of the linux drivers does not differ from the windows interface. Please include the spcm\_linux.lib library in your makefile to have access to all driver functions. A makefile may look like this:

```
COMPILER = gcc
EXECUTABLE = test_prg
LIBS = -lspcm_linux

OBJECTS = test.o\
          test2.o

all: $(EXECUTABLE)

$(EXECUTABLE): $(OBJECTS)
    $(COMPILER) $(CFLAGS) -o $(EXECUTABLE) $(LIBS) $(OBJECTS)

%.o: %.cpp
    $(COMPILER) $(CFLAGS) -o $*.o -c $*.cpp
```

### **Examples**

The Gnu C/C++ examples share the source with the Visual C++ examples. Please see above chapter for a more detailed documentation of the examples. Each example directory contains a makefile for the Gnu C/C++ examples.

## **C++ for .NET**

Please see the next chapter for more details on the .NET inclusion.

## **Other Windows C/C++ compilers 32 Bit**

### **Include Driver**

To access the driver, the driver functions must be loaded from the 32 bit driver DLL. Most compilers offer special tools to generate a matching library (e.g. Borland offers the implib tool that generates a matching library out of the windows driver DLL). If such a tool is available it is recommended to use it. Otherwise the driver functions need to be loaded from the dll using standard Windows functions. There is one example in the example directory /examples/c\_cpp/dll\_loading that shows the process.

Example of function loading:

```
hDLL = LoadLibrary ("spcm_win32.dll"); // Load the 32 bit version of the Spcm driver
pfn_spcm_hOpen = (SPCM_HOPEN*) GetProcAddress (hDLL, "_spcm_hOpen@4");
pfn_spcm_vClose = (SPCM_VCLOSE*) GetProcAddress (hDLL, "_spcm_vClose@4");
```

## **Other Windows C/C++ compilers 64 Bit**

### **Include Driver**

To access the driver, the driver functions must be loaded from the 64 bit the driver DLL. Most compilers offer special tools to generate a matching library (e.g. Borland offers the implib tool that generates a matching library out of the windows driver DLL). If such a tool is available it is recommended to use it. Otherwise the driver functions need to be loaded from the dll using standard Windows functions. There is one example in the example directory /examples/c\_cpp/dll\_loading that shows the process for 32 bit environments. The only line that needs to be modified is the one loading the DLL:

Example of function loading:

```
hDLL = LoadLibrary ("spcm_win64.dll"); // Modified: Load the 64 bit version of the Spcm driver here
pfn_spcm_hOpen = (SPCM_HOPEN*) GetProcAddress (hDLL, "spcm_hOpen");
pfn_spcm_vClose = (SPCM_VCLOSE*) GetProcAddress (hDLL, "spcm_vClose");
```

## **Driver functions**

The driver contains seven main functions to access the hardware.

### **Own types used by our drivers**

To simplify the use of the header files and our examples with different platforms and compilers and to avoid any implicit type conversions we decided to use our own type declarations. This allows us to use platform independent and universal examples and driver interfaces. If you do not stick to these declarations please be sure to use the same data type width. However it is strongly recommended that you use our defined

type declarations to avoid any hard to find errors in your programs. If you're using the driver in an environment that is not natively supported by our examples and drivers please be sure to use a type declaration that represents a similar data width

Declaration	Type
int8	8 bit signed integer (range from -128 to +127)
int16	16 bit signed integer (range from -32768 to 32767)
int32	32 bit signed integer (range from -2147483648 to 2147483647)
int64	64 bit signed integer (full range)
drv_handle	handle to driver, implementation depends on operating system platform

Declaration	Type
uint8	8 bit unsigned integer (range from 0 to 255)
uint16	16 bit unsigned integer (range from 0 to 65535)
uint32	32 bit unsigned integer (range from 0 to 4294967295)
uint64	64 bit unsigned integer (full range)

### **Notation of variables and functions**

In our header files and examples we use a common and reliable form of notation for variables and functions. Each name also contains the type as a prefix. This notation form makes it easy to see implicit type conversions and minimizes programming errors that result from using incorrect types. Feel free to use this notation form for your programs also-

Declaration	Notation
int8	byName (byte)
int16	nName
int32	lName (long)
int64	llName (long long)
int32*	pName (pointer to long)

Declaration	Notation
uint8	cName (character)
uint16	wName (word)
uint32	dwName (double word)
uint64	qwName (quad word)
char	szName (string with zero termination)

### **Function spcm\_hOpen**

This function initializes and opens an installed card supporting the new SpcM driver interface, which at the time of printing, are all cards of the M2i/M3i/M4i/M4x/M2p series and the related digitizerNETBOX/generatorNETBOX devices. The function returns a handle that has to be used for driver access. If the card can't be found or the loading of the driver generated an error the function returns a NULL. When calling this function all card specific installation parameters are read out from the hardware and stored within the driver. It is only possible to open one device by one software as concurrent hardware access may be very critical to system stability. As a result when trying to open the same device twice an error will be raised and the function returns NULL.

Function spcm\_hOpen (const char\* szDeviceName):

```
drv_handle _stdcall spcm_hOpen (           // tries to open the device and returns handle or error code
    const char* szDeviceName);           // name of the device to be opened
```

Under Linux the device name in the function call needs to be a valid device name. Please change the string according to the location of the device if you don't use the standard Linux device names. The driver is installed as default under /dev/spcm0, /dev/spcm1 and so on. The kernel driver numbers the devices starting with 0.

Under Windows the only part of the device name that is used is the tailing number. The rest of the device name is ignored. Therefore to keep the examples simple we use the Linux notation in all our examples. The tailing number gives the index of the device to open. The Windows kernel driver numbers all devices that it finds on boot time starting with 0.

Example for local installed cards

```
drv_handle hDrv;                      // returns the handle to the opened driver or NULL in case of error
hDrv = spcm_hOpen ("/dev/spcm0");      // string to the driver to open
if (!hDrv)
    printf ("open of driver failed\n");
```

Example for digitizerNETBOX/generatorNETBOX and remote installed cards

```
drv_handle hDrv;                      // returns the handle to the opened driver or NULL in case of error
hDrv = spcm_hOpen ("TCPIP::192.168.169.14::INST0::INSTR");
if (!hDrv)
    printf ("open of driver failed\n");
```

If the function returns a NULL it is possible to read out the error description of the failed open function by simply passing this NULL to the error function. The error function is described in one of the next topics.

### **Function spcm\_vClose**

This function closes the driver and releases all allocated resources. After closing the driver handle it is not possible to access this driver any more. Be sure to close the driver if you don't need it any more to allow other programs to get access to this device.

Function spcm\_vClose:

```
void _stdcall spcm_vClose (           // closes the device
    drv_handle hDevice);           // handle to an already opened device
```

Example:

```
spcm_vClose (hDrv);
```

### **Function spcm\_dwSetParam**

All hardware settings are based on software registers that can be set by one of the functions spcm\_dwSetParam. These functions set a register to a defined value or execute a command. The board must first be initialized by the spcm\_hOpen function. The parameter lRegister must have a valid software register constant as defined in regs.h. The available software registers for the driver are listed in the board specific part of the documentation below. The function returns a 32 bit error code if an error occurs. If no error occurs the function returns ERR\_OK, what is zero.

Function spcm\_dwSetParam

```
uint32 __stdcall spcm_dwSetParam_i32 ( // Return value is an error code
    drv_handle hDevice,                // handle to an already opened device
    int32     lRegister,               // software register to be modified
    int32     lValue);                 // the value to be set

uint32 __stdcall spcm_dwSetParam_i64m ( // Return value is an error code
    drv_handle hDevice,                // handle to an already opened device
    int32     lRegister,               // software register to be modified
    int32     lValueHigh,              // upper 32 bit of the value. Containing the sign bit !
    uint32    dwValueLow);             // lower 32 bit of the value.

uint32 __stdcall spcm_dwSetParam_i64 ( // Return value is an error code
    drv_handle hDevice,                // handle to an already opened device
    int32     lRegister,               // software register to be modified
    int64     llValue);                // the value to be set
```

Example:

```
if (spcm_dwSetParam_i64 (hDrv, SPC_MEMSIZE, 16384) != ERR_OK)
    printf ("Error when setting memory size\n");
```

This example sets the memory size to 16 kSamples (16384). If an error occurred the example will show a short error message

### **Function spcm\_dwGetParam**

All hardware settings are based on software registers that can be read by one of the functions spcm\_dwGetParam. These functions read an internal register or status information. The board must first be initialized by the spcm\_hOpen function. The parameter lRegister must have a valid software register constant as defined in the regs.h file. The available software registers for the driver are listed in the board specific part of the documentation below. The function returns a 32 bit error code if an error occurs. If no error occurs the function returns ERR\_OK, what is zero.

Function spcm\_dwGetParam

```
uint32 __stdcall spcm_dwGetParam_i32 ( // Return value is an error code
    drv_handle hDevice,                // handle to an already opened device
    int32     lRegister,               // software register to be read out
    int32*    plValue);                // pointer for the return value

uint32 __stdcall spcm_dwGetParam_i64m ( // Return value is an error code
    drv_handle hDevice,                // handle to an already opened device
    int32     lRegister,               // software register to be read out
    int32*    plValueHigh,              // pointer for the upper part of the return value
    uint32*   pdwValueLow);             // pointer for the lower part of the return value

uint32 __stdcall spcm_dwGetParam_i64 ( // Return value is an error code
    drv_handle hDevice,                // handle to an already opened device
    int32     lRegister,               // software register to be read out
    int64*    pllValue);                // pointer for the return value
```

Example:

```
int32 lSerialNumber;
spcm_dwGetParam_i32 (hDrv, SPC_PCISERIALNO, &lSerialNumber);
printf ("Your card has serial number: %05d\n", lSerialNumber);
```

The example reads out the serial number of the installed card and prints it. As the serial number is available under all circumstances there is no error checking when calling this function.

### **Different call types of spcm\_dwSetParam and spcm\_dwGetParam: i32, i64, i64m**

The three functions only differ in the type of the parameters that are used to call them. As some of the registers can exceed the 32 bit integer range (like memory size or post trigger) it is recommended to use the \_i64 function to access these registers. However as there are some

programs or compilers that don't support 64 bit integer variables there are two functions that are limited to 32 bit integer variables. In case that you do not access registers that exceed 32 bit integer please use the \_i32 function. In case that you access a register which exceeds 64 bit value please use the \_i64m calling convention. Inhere the 64 bit value is split into a low double word part and a high double word part. Please be sure to fill both parts with valid information.

If accessing 64 bit registers with 32 bit functions the behavior differs depending on the real value that is currently located in the register. Please have a look at this table to see the different reactions depending on the size of the register:

<b>Internal register</b>	<b>read/write</b>	<b>Function type</b>	<b>Behavior</b>
32 bit register	read	spcm_dwGetParam_i32	value is returned as 32 bit integer in pValue
32 bit register	read	spcm_dwGetParam_i64	value is returned as 64 bit integer in pValue
32 bit register	read	spcm_dwGetParam_i64m	value is returned as 64 bit integer, the lower part in pValueLow, the upper part in pValueHigh. The upper part can be ignored as it's only a sign extension
32 bit register	write	spcm_dwSetParam_i32	32 bit value can be directly written
32 bit register	write	spcm_dwSetParam_i64	64 bit value can be directly written, please be sure not to exceed the valid register value range
32 bit register	write	spcm_dwSetParam_i64m	32 bit value is written as lValueLow, the value lValueHigh needs to contain the sign extension of this value. In case of lValueLow being a value >= 0 lValueHigh can be 0, in case of lValueLow being a value < 0, lValueHigh has to be -1.
64 bit register	read	spcm_dwGetParam_i32	If the internal register has a value that is inside the 32 bit integer range (-2G up to (2G - 1)) the value is returned normally. If the internal register exceeds this size an error code ERR_EXCEEDSINT32 is returned. As an example: reading back the installed memory will work as long as this memory is < 2 GByte. If the installed memory is >= 2 GByte the function will return an error.
64 bit register	read	spcm_dwGetParam_i64	value is returned as 64 bit integer value in pValue independent of the value of the internal register.
64 bit register	read	spcm_dwGetParam_i64m	the internal value is split into a low and a high part. As long as the internal value is within the 32 bit range, the low part pValueLow contains the 32 bit value and the upper part pValueHigh can be ignored. If the internal value exceeds the 32 bit range it is absolutely necessary to take both value parts into account.
64 bit register	write	spcm_dwSetParam_i32	the value to be written is limited to 32 bit range. If a value higher than the 32 bit range should be written, one of the other function types need to be used.
64 bit register	write	spcm_dwSetParam_i64	the value has to be split into two parts. Be sure to fill the upper part lValueHigh with the correct sign extension even if you only write a 32 bit value as the driver every time interprets both parts of the function call.
64 bit register	write	spcm_dwSetParam_i64m	the value can be written directly independent of the size.

### **Function spcm\_dwGetContBuf**

This function reads out the internal continuous memory buffer in bytes, in case one has been allocated. If no buffer has been allocated the function returns a size of zero and a NULL pointer. You may use this buffer for data transfers. As the buffer is continuously allocated in memory the data transfer will speed up by up to 15% - 25%, depending on your specific kind of card. Please see further details in the appendix of this manual.

```
uint32 __stdcall spcm_dwGetContBuf_i64 ( // Return value is an error code
    drv_handle hDevice,           // handle to an already opened device
    uint32 dwBufType,             // type of the buffer to read as listed above under SPCM_BUF_XXXX
    void** ppvDataBuffer,         // address of available data buffer
    uint64* pqwContBufLen);       // length of available continuous buffer

uint32 __stdcall spcm_dwGetContBuf_i64m ( // Return value is an error code
    drv_handle hDevice,           // handle to an already opened device
    uint32 dwBufType,             // type of the buffer to read as listed above under SPCM_BUF_XXXX
    void** ppvDataBuffer,         // address of available data buffer
    uint32* pdwContBufLenH,        // high part of length of available continuous buffer
    uint32* pdwContBufLenL);       // low part of length of available continuous buffer
```

 **These functions have been added in driver version 1.36. The functions are not available in older driver versions.**

 **These functions also only have effect on locally installed cards and are neither useful nor usable with any digitizerNETBOX or generatorNETBOX products, because no local kernel driver is involved in such a setup. For remote devices these functions will return a NULL pointer for the buffer and 0 Bytes in length.**

### **Function spcm\_dwDefTransfer**

The spcm\_dwDefTransfer function defines a buffer for a following data transfer. This function only defines the buffer, there is no data transfer performed when calling this function. Instead the data transfer is started with separate register commands that are documented in a later chapter. At this position there is also a detailed description of the function parameters.

Please make sure that all parameters of this function match. It is especially necessary that the buffer address is a valid address pointing to memory buffer that has at least the size that is defined in the function call. Please be informed that calling this function with non valid parameters may crash your system as these values are base for following DMA transfers.

The use of this function is described in greater detail in a later chapter.

**Function spcm\_dwDefTransfer**

```

uint32 __stdcall spcm_dwDefTransfer_i64m// Defines the transfer buffer by 2 x 32 bit unsigned integer
drv_handle hDevice, // handle to an already opened device
uint32 dwBufType, // type of the buffer to define as listed above under SPCM_BUF_XXXX
uint32 dwDirection, // the transfer direction as defined above
uint32 dwNotifySize, // no. of bytes after which an event is sent (0=end of transfer)
void* pvDataBuffer, // pointer to the data buffer
uint32 dwBrdOffsH, // high part of offset in board memory
uint32 dwBrdOffsL, // low part of offset in board memory
uint32 dwTransferLenH, // high part of transfer buffer length
uint32 dwTransferLenL); // low part of transfer buffer length

uint32 __stdcall spcm_dwDefTransfer_i64 // Defines the transfer buffer by using 64 bit unsigned integer values
drv_handle hDevice, // handle to an already opened device
uint32 dwBufType, // type of the buffer to define as listed above under SPCM_BUF_XXXX
uint32 dwDirection, // the transfer direction as defined above
uint32 dwNotifySize, // no. of bytes after which an event is sent (0=end of transfer)
void* pvDataBuffer, // pointer to the data buffer
uint64 qwBrdOffs, // offset for transfer in board memory
uint64 qwTransferLen); // buffer length

```

This function is available in two different formats as the spcm\_dwGetParam and spcm\_dwSetParam functions are. The background is the same. As long as you're using a compiler that supports 64 bit integer values please use the \_i64 function. Any other platform needs to use the \_i64m function and split offset and length in two 32 bit words.

**Example:**

```

int16* pnBuffer = (int16*) pvAllocMemPageAligned (16384);
if (spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_DATA, SPCM_DIR_CARDTOPC, 0, (void*) pnBuffer, 0, 16384) != ERR_OK)
    printf ("DefTransfer failed\n");

```

The example defines a data buffer of 8 kSamples of 16 bit integer values = 16 kByte (16384 byte) for a transfer from card to PC memory. As notify size is set to 0 we only want to get an event when the transfer has finished.

**Function spcm\_dwInvalidateBuf**

The invalidate buffer function is used to tell the driver that the buffer that has been set with spcm\_dwDefTransfer call is no longer valid. It is necessary to use the same buffer type as the driver handles different buffers at the same time. Call this function if you want to delete the buffer memory after calling the spcm\_dwDefTransfer function. If the buffer already has been transferred after calling spcm\_dwDefTransfer it is not necessary to call this function. When calling spcm\_dwDefTransfer any further defined buffer is automatically invalidated.

**Function spcm\_dwInvalidateBuf**

```

uint32 __stdcall spcm_dwInvalidateBuf ( // invalidate the transfer buffer
drv_handle hDevice, // handle to an already opened device
uint32 dwBufType); // type of the buffer to invalidate as
// listed above under SPCM_BUF_XXXX

```

**Function spcm\_dwGetErrorInfo**

The function returns complete error information on the last error that has occurred. The error handling itself is explained in a later chapter in greater detail. When calling this function please be sure to have a text buffer allocated that has at least ERRORTEXTLEN length. The error text function returns a complete description of the error including the register/value combination that has raised the error and a short description of the error details. In addition it is possible to get back the error generating register/value for own error handling. If not needed the buffers for register/value can be left to NULL.

**Note that the timeout event (ERR\_TIMEOUT) is not counted as an error internally as it is not locking the driver but as a valid event. Therefore the GetErrorInfo function won't return the timeout event even if it had occurred in between. You can only recognize the ERR\_TIMEOUT as a direct return value of the wait function that was called.**



**Function spcm\_dwGetErrorInfo**

```

uint32 __stdcall spcm_dwGetErrorInfo_i32 (
drv_handle hDevice, // handle to an already opened device
uint32* pdwErrorReg, // address of the error register (can be zero if not of interest)
int32* plErrorValue, // address of the error value (can be zero if not of interest)
char pszErrorTextBuffer[ERRORTEXTLEN]); // text buffer for text error

```

Example:

```
char szErrorBuf[ERRORTEXTLEN];
if (spcm_dwSetParam_i64 (hDrv, SPC_MEMSIZE, -1))
{
    spcm_dwGetErrorInfo_i32 (hDrv, NULL, NULL, szErrorBuf);
    printf ("Set of memsize failed with error message: %s\n", szErrorBuf);
}
```

## **Delphi (Pascal) Programming Interface**

### **Driver interface**

The driver interface is located in the sub-directory d\_header and contains the following files. The files need to be included in the delphi project and have to be put into the „uses“ section of the source files that will access the driver. Please do not edit any of these files as they're regularly updated if new functions or registers have been included.

#### **file spcm\_win32.pas**

The file contains the interface to the driver library and defines some needed constants and variable types. All functions of the delphi library are similar to the above explained standard driver functions:

```
// ----- device handling functions -----
function spcm_hOpen (strName: pchar): int32; stdcall; external 'spcm_win32.dll' name '_spcm_hOpen@4';
procedure spcm_vClose (hDevice: int32); stdcall; external 'spcm_win32.dll' name '_spcm_vClose@4';

function spcm_dwGetErrorInfo_i32 (hDevice: int32; var lErrorReg, lErrorValue: int32; strError: pchar): uint32;
stdcall; external 'spcm_win32.dll' name '_spcm_dwGetErrorInfo_i32@16'

// ----- register access functions -----
function spcm_dwSetParam_i32 (hDevice, lRegister, lValue: int32): uint32;
stdcall; external 'spcm_win32.dll' name '_spcm_dwSetParam_i32@12';

function spcm_dwSetParam_i64 (hDevice, lRegister: int32; l1Value: int64): uint32;
stdcall; external 'spcm_win32.dll' name '_spcm_dwSetParam_i64@16';

function spcm_dwGetParam_i32 (hDevice, lRegister: int32; var plValue: int32): uint32;
stdcall; external 'spcm_win32.dll' name '_spcm_dwGetParam_i32@12';

function spcm_dwGetParam_i64 (hDevice, lRegister: int32; var pl1Value: int64): uint32;
stdcall; external 'spcm_win32.dll' name '_spcm_dwGetParam_i64@12';

// ----- data handling -----
function spcm_dwDefTransfer_i64 (hDevice, dwBufType, dwDirection, dwNotifySize: int32; pvDataBuffer: Pointer;
l1BrdOffs, l1TransferLen: int64): uint32;
stdcall; external 'spcm_win32.dll' name '_spcm_dwDefTransfer_i64@36';

function spcm_dwInvalidateBuf (hDevice, lBuffer: int32): uint32;
stdcall; external 'spcm_win32.dll' name '_spcm_dwInvalidateBuf@8';
```

The file also defines types used inside the driver and the examples. The types have similar names as used under C/C++ to keep the examples more simple to understand and allow a better comparison.

#### **file SpcRegs.pas**

The SpcRegs.pas file defines all constants that are used for the driver. The constant names are the same names as used under the C/C++ examples. All constants names will be found throughout this hardware manual when certain aspects of the driver usage are explained. It is recommended to only use these constant names for better visibility of the programs:

```
const SPC_M2CMD = 100; { write a command }
const M2CMD_CARD_RESET = $00000001; { hardware reset }
const M2CMD_CARD_WRITESETUP = $00000002; { write setup only }
const M2CMD_CARD_START = $00000004; { start of card (including writesetup) }
const M2CMD_CARD_ENABLETRIGGER = $00000008; { enable trigger engine }
...
```

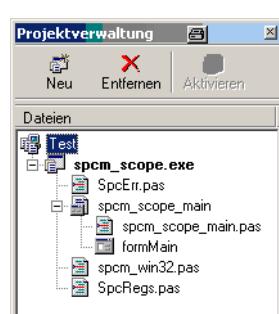
#### **file SpcErr.pas**

The SpeErr.pas file contains all error codes that may be returned by the driver.

### **Including the driver files**

To use the driver function and all the defined constants it is necessary to include the files into the project as shown in the picture on the right. The project overview is taken from one of the examples delivered on USB-Stick. Besides including the driver files in the project it is also necessary to include them in the uses section of the source files where functions or constants should be used:

```
uses
  Windows, Messages, SysUtils, Classes, Graphics, Controls, Forms, Dialogs,
  StdCtrls, ExtCtrls,
  SpcRegs, SpcErr, spcm_win32;
```



## Examples

Examples for Delphi can be found on USB-Stick in the directory /examples/delphi. The directory contains the above mentioned delphi header files and a couple of universal examples, each of them working with a certain type of card. Please feel free to use these examples as a base for your programs and to modify them in any kind.

### **spcm\_scope**

The example implements a very simple scope program that makes single acquisitions on button pressing. A fixed setup is done inside the example. The spcm\_scope example can be used with any analog data acquisition card from Spectrum. It covers cards with 1 byte per sample (8 bit resolution) as well as cards with 2 bytes per sample (12, 14 and 16 bit resolution)

The program shows the following steps:

- Initialization of a card and reading of card information like type, function and serial number
- Doing a simple card setup
- Performing the acquisition and waiting for the end interrupt
- Reading of data, re-scaling it and displaying waveform on screen

## **.NET programming languages**

### **Library**

For using the driver with a .NET based language Spectrum delivers a special library that encapsulates the driver in a .NET object. By adding this object to the project it is possible to access all driver functions and constants from within your .NET environment.

There is one small console based example for each supported .NET language that shows how to include the driver and how to access the cards. Please combine this example with the different standard examples to get the different card functionality.

### **Declaration**

The driver access methods and also all the type, register and error declarations are combined in the object Spcm and are located in one of the two DLLs either SpcmDrv32.NET.dll or SpcmDrv64.NET.dll delivered with the .NET examples.



**For simplicity, either file is simply called „SpcmDrv.NET.dll“ in the following passages and the actual file name must be replaced with either the 32bit or 64bit version according to your application.**

Spectrum also delivers the source code of the DLLs as a C# project. These sources are located in the directory SpcmDrv.NET.

```
namespace Spcm
{
    public class Drv
    {
        [DllImport("spcm_win32.dll")]public static extern IntPtr spcm_hOpen (string szDeviceName);
        [DllImport("spcm_win32.dll")]public static extern void spcm_vClose (IntPtr hDevice);
    ...
    public class CardType
    {
        public const int TYP_M2I2020          = unchecked ((int)0x00032020);
        public const int TYP_M2I2021          = unchecked ((int)0x00032021);
        public const int TYP_M2I2025          = unchecked ((int)0x00032025);
    ...
    public class Regs
    {
        public const int SPC_M2CMD           = unchecked ((int)100);
        public const int M2CMD_CARD_RESET    = unchecked ((int)0x00000001);
        public const int M2CMD_CARD_WRITESETUP = unchecked ((int)0x00000002);
    ...
}
```

### **Using C#**

The SpcmDrv.NET.dll needs to be included within the Solution Explorer in the References section. Please use right mouse and select „AddReference“. After this all functions and constants of the driver object are available.

Please see the example in the directory CSharp as a start:

```
// ----- open card -----
hDevice = Drv.spcm_hOpen("/dev/spcm0");
if ((int)hDevice == 0)
{
    Console.WriteLine("Error: Could not open card\n");
    return 1;
}

// ----- get card type -----
dwErrorCode = Drv.spcm_dwGetParam_i32(hDevice, Regs.SPC_PCITYP, out lCardType);
dwErrorCode = Drv.spcm_dwGetParam_i32(hDevice, Regs.SPC_PCISERIALNR, out lSerialNumber);
```

Example for digitizerNETBOX/generatorNETBOX and remotely installed cards:

```
// ----- open remote card -----
hDevice = Drv.spcm_hOpen("TCPIP::192.168.169.14::INST0::INSTR");
```

## **Using Managed C++/CLI**

The SpcmDrv.NET.dll needs to be included within the project options. Please select „Project“ - „Properties“ - „References“ and finally „Add new Reference“. After this all functions and constants of the driver object are available.

Please see the example in the directory CppCLR as a start:

```
// ----- open card -----
hDevice = Drv::spcm_hOpen("/dev/spcm0");
if ((int)hDevice == 0)
{
    Console::WriteLine("Error: Could not open card\n");
    return 1;
}

// ----- get card type -----
dwErrorCode = Drv::spcm_dwGetParam_i32(hDevice, Regs::SPC_PCITYP, lCardType);
dwErrorCode = Drv::spcm_dwGetParam_i32(hDevice, Regs::SPC_PCISERIALNR, lSerialNumber);
```

Example for digitizerNETBOX/generatorNETBOX and remotely installed cards:

```
// ----- open remote card -----
hDevice = Drv::spcm_hOpen("TCPIP::192.168.169.14::INST0::INSTR");
```

## **Using VB.NET**

The SpcmDrv.NET.dll needs to be included within the project options. Please select „Project“ - „Properties“ - „References“ and finally „Add new Reference“. After this all functions and constants of the driver object are available.

Please see the example in the directory VB.NET as a start:

```
' ----- open card -----
hDevice = Drv.spcm_hOpen("/dev/spcm0")

If (hDevice = 0) Then
    Console.WriteLine("Error: Could not open card\n")
Else

    ' ----- get card type -----
    dwError = Drv.spcm_dwGetParam_i32(hDevice, Regs.SPC_PCITYP, lCardType)
    dwError = Drv.spcm_dwGetParam_i32(hDevice, Regs.SPC_PCISERIALNR, lSerialNumber)
```

Example for digitizerNETBOX/generatorNETBOX and remotely installed cards:

```
' ----- open remote card -----
hDevice = Drv.spcm_hOpen("TCPIP::192.168.169.14::INST0::INSTR")
```

## **Using J#**

The SpcmDrv.NET.dll needs to be included within the Solution Explorer in the References section. Please use right mouse and select „AddReference“. After this all functions and constants of the driver object are available.

Please see the example in the directory JSharp as a start:

```
// ----- open card -----
hDevice = Drv.spcm_hOpen("/dev/spcm0");

if (hDevice.ToInt32() == 0)
    System.out.println("Error: Could not open card\n");
else
{
    // ----- get card type -----
    dwErrorCode = Drv.spcm_dwGetParam_i32(hDevice, Regs.SPC_PCITYP, lCardType);
    dwErrorCode = Drv.spcm_dwGetParam_i32(hDevice, Regs.SPC_PCISERIALNR, lSerialNumber);
```

Example for digitizerNETBOX/generatorNETBOX and remotely installed cards:

```
' ----- open remote card -----
hDevice = Drv.spcm_hOpen("TCPIP::192.168.169.14::INST0::INSTR")
```

## **Python Programming Interface and Examples**

### **Driver interface**

The driver interface contains the following files. The files need to be included in the python project. Please do not edit any of these files as they are regularly updated if new functions or registers have been included. To use pypcm you need either python 2 (2.4, 2.6 or 2.7) or python 3 (3.x) and ctype, which is included in python 2.6 and newer and needs to be installed separately for Python 2.4.

#### **file pypcm.py**

The file contains the interface to the driver library and defines some needed constants. All functions of the python library are similar to the above explained standard driver functions and use ctypes as input and return parameters:

```
# ----- Windows -----
spcmDll = windll.LoadLibrary ("c:\\windows\\system32\\spcm_win32.dll")

# load spcm_hOpen
spcm_hOpen = getattr (spcmDll, "_spcm_hOpen@4")
spcm_hOpen.argtype = [c_char_p]
spcm_hOpen.restype = drv_handle

# load spcm_vClose
spcm_vClose = getattr (spcmDll, "_spcm_vClose@4")
spcm_vClose.argtype = [drv_handle]
spcm_vClose.restype = None

# load spcm_dwGetErrorInfo
spcm_dwGetErrorInfo_i32 = getattr (spcmDll, "_spcm_dwGetErrorInfo_i32@16")
spcm_dwGetErrorInfo_i32.argtype = [drv_handle, ptr32, ptr32, c_char_p]
spcm_dwGetErrorInfo_i32.restype = uint32

# load spcm_dwGetParam_i32
spcm_dwGetParam_i32 = getattr (spcmDll, "_spcm_dwGetParam_i32@12")
spcm_dwGetParam_i32.argtype = [drv_handle, int32, ptr32]
spcm_dwGetParam_i32.restype = uint32

# load spcm_dwGetParam_i64
spcm_dwGetParam_i64 = getattr (spcmDll, "_spcm_dwGetParam_i64@12")
spcm_dwGetParam_i64.argtype = [drv_handle, int32, ptr64]
spcm_dwGetParam_i64.restype = uint32

# load spcm_dwSetParam_i32
spcm_dwSetParam_i32 = getattr (spcmDll, "_spcm_dwSetParam_i32@12")
spcm_dwSetParam_i32.argtype = [drv_handle, int32, int32]
spcm_dwSetParam_i32.restype = uint32

# load spcm_dwSetParam_i64
spcm_dwSetParam_i64 = getattr (spcmDll, "_spcm_dwSetParam_i64@16")
spcm_dwSetParam_i64.argtype = [drv_handle, int32, int64]
spcm_dwSetParam_i64.restype = uint32

# load spcm_dwSetParam_i64m
spcm_dwSetParam_i64m = getattr (spcmDll, "_spcm_dwSetParam_i64m@16")
spcm_dwSetParam_i64m.argtype = [drv_handle, int32, int32, int32]
spcm_dwSetParam_i64m.restype = uint32

# load spcm_dwDefTransfer_i64
spcm_dwDefTransfer_i64 = getattr (spcmDll, "_spcm_dwDefTransfer_i64@36")
spcm_dwDefTransfer_i64.argtype = [drv_handle, uint32, uint32, uint32, c_void_p, uint64, uint64]
spcm_dwDefTransfer_i64.restype = uint32

spcm_dwInvalidateBuf = getattr (spcmDll, "_spcm_dwInvalidateBuf@8")
spcm_dwInvalidateBuf.argtype = [drv_handle, uint32]
spcm_dwInvalidateBuf.restype = uint32

# ----- Linux -----
# use cdll because all driver access functions use cdecl calling convention under linux
spcmDll = cdll.LoadLibrary ("libspcm_linux.so")

# the loading of the driver access functions is similar to windows:

# load spcm_hOpen
spcm_hOpen = getattr (spcmDll, "spcm_hOpen")
spcm_hOpen.argtype = [c_char_p]
spcm_hOpen.restype = drv_handle

# ...
```

### **file regs.py**

The regs.py file defines all constants that are used for the driver. The constant names are the same names compared to the C/C++ examples. All constant names will be found throughout this hardware manual when certain aspects of the driver usage are explained. It is recommended to only use these constant names for better readability of the programs:

```
SPC_M2CMD = 1001                                # write a command
M2CMD_CARD_RESET = 0x000000011                     # hardware reset
M2CMD_CARD_WRITESETUP = 0x000000021                # write setup only
M2CMD_CARD_START = 0x000000041                     # start of card (including writesetup)
M2CMD_CARD_ENABLEtrigger = 0x000000081              # enable trigger engine
...
...
```

### **file spcerr.py**

The spcerr.py file contains all error codes that may be returned by the driver.

## **Examples**

Examples for Python can be found on USB-Stick in the directory /examples/python. The directory contains the above mentioned header files and some examples, each of them working with a certain type of card. Please feel free to use these examples as a base for your programs and to modify them in any kind.

**When allocating the buffer for DMA transfers, use the following function to get a mutable character buffer:  
ctypes.create\_string\_buffer(init\_or\_size[, size])**

## **Java Programming Interface and Examples**

### **Driver interface**

The driver interface contains the following Java files (classes). The files need to be included in your Java project. Please do not edit any of these files as they are regularly updated if new functions or registers have been included. The driver interface uses the Java Native Access (JNA) library.

This library is licensed under the LGPL (<https://www.gnu.org/licenses/lgpl-3.0.en.html>) and has also to be included to your Java project.

To download the latest jna.jar package and to get more information about the JNA project please check the projects GitHub page under: <https://github.com/java-native-access/jna>

The following files can be found in the „SpcmDrv” folder of your Java examples install path.

### **SpcmDrv32.java / SpcmDrv64.java**

The files contain the interface to the driver library and defines some needed constants. All functions of the driver interface are similar to the above explained standard driver functions. Use the SpcmDrv32.java for 32 bit and the SpcmDrv64.java for 64 bit projects:

```
...
public interface SpcmWin64 extends StdCallLibrary {
    SpcmWin64 INSTANCE = (SpcmWin64)Native.loadLibrary ("spcm_win64", SpcmWin64.class);

    int spcm_hOpen (String sDeviceName);
    void spcm_vClose (int hDevice);
    int spcm_dwSetParam_i64 (int hDevice, int lRegister, long llValue);
    int spcm_dwGetParam_i64 (int hDevice, int lRegister, LongByReference pllValue);
    int spcm_dwDefTransfer_i64 (int hDevice, int lBufType, int lDirection, int lNotifySize,
                                Pointer pDataBuffer, long llBrdOffs, long llTransferLen);
    int spcm_dwInvalidateBuf (int hDevice, int lBufType);
    int spcm_dwGetErrorInfo_i32 (int hDevice, IntByReference plErrorReg,
                                IntByReference plErrorValue, Pointer sErrorTextBuffer);
}
...
```

### **SpcmRegs.java**

The SpcmRegs class defines all constants that are used for the driver. The constants names are the same names compared to the C/C++ examples. All constant names will be found throughout this hardware manual when certain aspects of the driver usage are explained. It is recommended to only use these constant names for better readability of the programs:

```
...
public static final int SPC_M2CMD = 100;
public static final int M2CMD_CARD_RESET = 0x00000001;
public static final int M2CMD_CARD_WRITESETUP = 0x00000002;
public static final int M2CMD_CARD_START = 0x00000004;
public static final int M2CMD_CARD_ENABLETRIGGER = 0x00000008;
...
```

### **SpcmErrors.java**

The SpcmErrors class contains all error codes that may be returned by the driver.

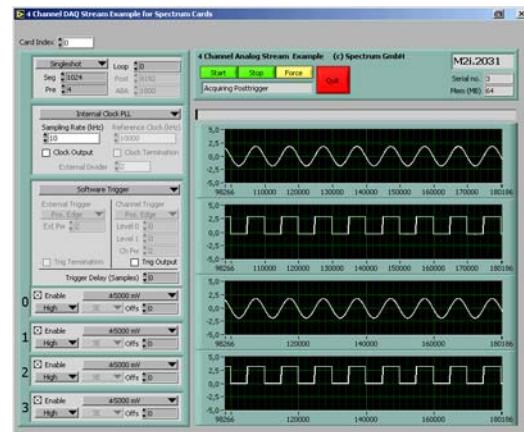
### **Examples**

Examples for Java can be found on USB-Stick in the directory /examples/java. The directory contains the above mentioned header files and some examples, each of them working with a certain type of card. Please feel free to use these examples as a base for your programs and to modify them in any kind.

## LabVIEW driver and examples

A full set of drivers and examples is available for LabVIEW for Windows. LabVIEW for Linux is currently not supported. The LabVIEW drivers have their own manual. The LabVIEW drivers, examples and the manual are found on the USB-Stick that has been included in the delivery. The latest version is also available on our webpage [www.spectrum-instrumentation.com](http://www.spectrum-instrumentation.com)

Please follow the description in the LabVIEW manual for installation and usage of the LabVIEW drivers for this card.

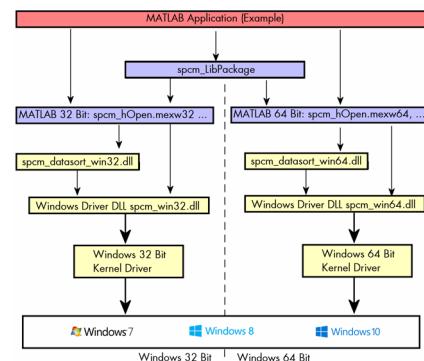


## MATLAB driver and examples

A full set of drivers and examples is available for Mathworks MATLAB for Windows (32 bit and 64 bit versions) and also for MATLAB for Linux (64 bit version). There is no additional toolbox needed to run the MATLAB examples and drivers.

The MATLAB drivers have their own manual. The MATLAB drivers, examples and the manual are found on the USB-Stick that has been included in the delivery. The latest version is also available on our webpage [www.spectrum-instrumentation.com](http://www.spectrum-instrumentation.com)

Please follow the description in the MATLAB manual for installation and usage of the MATLAB drivers for this card.

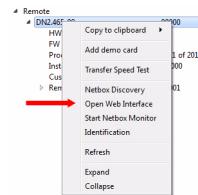


## Integrated Webserver

The digitizerNETBOX/generatorNETBOX has an integrated webserver following the LXI standards. The web pages give information about the device, allows to set up ethernet details or make firmware updates.

The webserver can be reached in three different ways:

- Directly by typing the IP address into the URL field of a Web Browser.
- By selecting it from the Spectrum Control Center via the context menu on the remote device node (as shown on the screen shot on the right).
- On Windows machines (starting with Windows 7) on the device properties page, as described in the section „Finding the digitizerNETBOX in the network“ earlier in this manual.



### Home Screen

The home screen gives an overview about the instrument showing all main information:

Name	Description
Instrument Model	The specific model code of your digitizerNETBOX or generatorNETBOX
Manufacturer	Manufacturer of the device - Spectrum GmbH
Serial Number	The unique serial number of the product. The serial number is also found on the type plate on the back of the chassis of the digitizerNETBOX/generatorNETBOX.
Description	A free definable description of the specific device that you can edit by yourself in the LAN configuration page. It is recommended to include the location of the device and any other information that helps your network administrator.
LXI Features	Listing the supported LXI features
LXI Version	Listing the used LXI specification for designing this device
Host Name	The host name given by the DNS server. If the DNS server does not generate a host name, the IP address is shown
mDNS Host Name	The internal mDNS host name which allows to find the device in the network environment. The mDNS host name can also be changed in the LAN configuration page
MAC Address	The unique MAC address of the device which can also be found on the type plate on the back of the device
TCP/IP Address	The current TCP/IP address as given by the DNS
Firmware revision	The revision of the installed firmware files for the digitizerNETBOX/generatorNETBOX itself. The integrated digitizer modules have their own firmware versioning and can be read out by the Spectrum control center
Software Revision	The software revision of the integrated remote server software
Instrument Address String (VISA)	The instrument address string following the VISA notation. Using this address string one can access the digitizerNETBOX/generatorNETBOX from the software. The integrated digitizer modules are numbered starting with INST0 (example: TCPIP::192.168.169.14::INST0::INSTR)
LAN ID Indicator	Pressing this button starts flashing the LAN LED light on the front plate of the device. This helps to find the device inside a 19" rack where the back of the device with the type plate is not easily accessible.

Welcome	
Instrument Model	DN2.465-08
Manufacturer	Spectrum GmbH
Serial Number	1234
Description	digitizerNETBOX
LXI Features	LXI Core 2011
LXI Version	LXI Device Specification 2011 rev. 1.4
Host Name	192.168.169.23
mDNS Host Name	digitizerNETBOX.local
MAC Address	0C:C4:7A:B3:C2:A2
TCP/IP Address	192.168.169.23
Firmware Revision	62
Software Revision	5.17.17117
Instrument Address String [VISA]	TCPIP::192.168.169.23::INSTR
LAN ID Indicator	<input checked="" type="button"/> Enable

digitizerNETBOX DN2.465-08 sn1234

### LAN Configuration

The LAN configuration page allows to change the LAN configuration of the device. This page is password protected if a password is given in the security page.

Name	Description
Host Name	The official host name as given by the DNS
mDNS Host Name	The local host name which can be changed here
Domain	The domain in which the digitizerNETBOX is placed if the DNS server has filled this information correctly
Description	The device description which can be changed here
DHCP	DHCP (Dynamic Host Configuration Protocol) setting
IP Address	The current IP address as given by the DHCP server (DHCP enable) or entered manually
Subnet Mask	The current subnet mask as given by the DHCP server (DHCP enable) or entered manually
Default Gateway	The current default gateway address as given by the DHCP server (DHCP enable) or entered manually
DNS Server(s)	The current DNS server address as given by the DHCP server (DHCP enable) or entered manually

Home
LAN Configuration
Status
Security
Documentation
Firmware Update
Power
Downloads
Logging
Access
Contact
Debug

Current Network Configuration	
Host Name	192.168.169.23
mDNS Host Name	digitizerNETBOX.local
Domain	
Description	digitizerNETBOX
DHCP	enabled
IP Address	192.168.169.23
Subnet Mask	255.255.255.0
Default Gateway	192.168.169.250
DNS Server(s)	192.168.169.202
<input type="button"/> Edit configuration	

As default DHCP (IPv4) will be used and an IP address will be automatically set. In case no DHCP server is found, an IP will be obtained using the AutoIP feature. This will lead to an IPv4 address of 169.254.x.y (with x and y being assigned to a free IP in the network) using a subnet mask of 255.255.0.0.

The default IP setup can also be restored, by using the „LAN Reset“ button on the device.

If a fixed IP address should be used instead, the parameters need to be set according to the current LAN requirements.

Pressing the „edit configuration“ button will issue a new edit page. If a password is given in the security pages the password must be entered before the edit screen is available

Name	Description
Host Name	Enter a new host name for the mDNS host name. Please note that host names can only contain letters, numbers, minus and underscore, no dots or blanks are allowed
Domain	The domain in which the digitizerNETBOX/generatorNETBOX is placed
Submit Button	After review this button submits the changes and changes host name and description permanently
Reset Button	Discards the changes and returns host name and description to the previous values.
TCP/IP Mode	Select between DHCP + AutoIP to have all configuration done automatically or Manual to enter all IP related settings manual.
IP Address	Only available if manual TCP/IP mode is selected
Subnet Mask	Only available if manual TCP/IP mode is selected
Default Gateway	Only available if manual TCP/IP mode is selected
DNS Server(s)	Only available if manual TCP/IP mode is selected
Submit Button	Submits the changes. If you set the IP details manually please be sure that your device is adressable within your network. In case of a failure the LAN reset button on the front page of the device will set back the LAN configuration to DHCP
Reset Button	Discards the changes and returns IP settings to the previous values

The screenshot shows the LAN Configuration page with the following fields:

- Network Configuration**
  - Host Name: DN2\_465-08\_sn1234
  - Domain: Spectrum GmbH,DN2.465-08,1234,
  - Attention: Leaving a field empty will set the default value
- Network Configuration**
  - TCP/IP Mode:  DHCP + AutoIP  Manual
  - IP Address: 192 . 168 . 169 . 23
  - Subnet Mask: 255 . 255 . 255 . 0
  - Default Gateway: 192 . 168 . 169 . 250
  - DNS Server(s): 192 . 168 . 169 . 202

At the bottom right, it says *digitizerNETBOX DN2.465-08 sn1234*.

## Status

Shows the internal device status. For each internal digitizer/generator module the status whether the module is available or locked by a user is shown. A digitizer/generator module is locked as soon as it is opened from any software on any PC.

In case the instrument is locked, the IP address of the current control PC can be obtained here.

Also the current temperature will be displayed here. DN6.xxxx models of either the digitizerNETBOX or generatorNETBOX will also display the case fan speed here as well (not shown on screen shot).

The screenshot shows the Status page with the following information:

- Status**: TCPIP::192.168.169.23::inst0::INSTR available
- Temperature**: CPU +45.0°C / +113.0°F

## Security

Allows to set a password to protect the device from changes. The password secures access to LAN configuration, power settings like reboot or power down and firmware updates of the instrument. As default no password is set for the configuration.

To change the password the old password has to be entered once and the new password twice to avoid typing errors.

In case of a lost password the LAN reset button on the front plate of the digitizerNETBOX/generatorNETBOX will delete the password and set the complete device to the default stage again.

The screenshot shows the Security page with the following fields:

- Security**
  - Old Password: [REDACTED]
  - New Password: [REDACTED]
  - Repeat New Password: [REDACTED]

At the bottom left, it says *digitizerNETBOX DN2.465-08 sn1234*.

## Documentation

All related documents for the device that may be needed to operate the digitizerNETBOX/generatorNETBOX or to program it are available by download as pdf documents from here.

The screenshot shows the Documentation page with the following links:

- Documentation**
  - Manual: [DN2.46x](#)
  - Datasheet: [DN2.46x](#)
  - Homepage: [www.spectrum-instrumentation.com](http://www.spectrum-instrumentation.com)

## Firmware Update

The complete firmware of the device can be updated with a single firmware update file which is available for download directly here by clicking the „check online“ button or on the Spectrum webpage [www.spectrum-instrumentation.com](http://www.spectrum-instrumentation.com). The firmware file contains update files for the following parts:

- firmware files of the integrated digitizer/generator modules
- drivers for the digitizer/generator modules
- software and setup of the underlying operating system
- webserver and integrated web pages and manuals
- remote server software
- initialization scripts and tools

**Firmware Update**  
Please select the firmware archive:  Durchsuchen... Keine Datei ausgewählt.

**New Firmware**

## Power

From here the digitizerNETBOX/generatorNETBOX can be remotely shut down or remotely rebooted. Please make sure that no software is currently accessing the digitizerNETBOX or generatorNETBOX before using any of these power options.

**Power settings**

## Downloads

The webserver gives access to all necessary software components for download. All these software installers are also available on the USB-Stick that is delivered with the digitizerNETBOX/generatorNETBOX and on the internet.

**Downloads**

**Windows**  
SBench 6 [32Bit](#) [64Bit](#)  
Control Center & Driver [32Bit](#) [64Bit](#)

**LINUX**  
SBench 6 [32Bit RPM](#) [64Bit RPM](#) [32Bit DEB](#) [64Bit DEB](#)  
Control Center [32 & 64Bit](#)  
Driver [32 & 64Bit](#)

## Logging

This is a debug setting only. You shouldn't change any of these settings unless our support team requested you to do so. Operating the digitizerNETBOX/generatorNETBOX with log-level „Log all“ will slow down the operation as each single call is logged as a text entry in the internal log file.

These debug log settings are similar to the ones described in the chapter about the Spectrum control center. Using this logging the internal communication between the remote server and the locally installed Spectrum driver is logged.

Please note that some digitizerNETBOX/generatorNETBOX products (having only one internal digitizer/generator installed) show an error message „KernelOpen /dev/spcm1 failed“. This error message is not an error but simply the remote server trying to open the second internal digitizer that isn't installed.

**Logging**  
DO NOT CHANGE ANYTHING HERE UNLESS YOU HAVE BEEN PROMPTED TO!

On-board Log Level:   Append logging to file

00000.000 e: Thu Dec 17 11:46:59 2015

..... *[Large empty text input field]* .....

..... *digitizerNETBOX DN2.465-08 sn1234* .....

## Access

In here it is possible to restrict the access to the digitizerNETBOX/generatorNETBOX to certain IP addresses. As long as the access list is clear, everybody who has a TCP/IP connection to the digitizerNETBOX/generatorNETBOX can get control of it and use it with any software like SBench 6.

Use the add IP to list field with the submit button to add an IP address to the list. As a default your current IP address is shown in the entry field.

After having setup an access list everybody else who is not on the access restricted IP list can still see the digitizerNETBOX or generatorNETBOX in the network and use the discovery function but access to the internal digitizers/generators is restricted and no longer possible.

Use this option together with the password option to completely secure the digitizerNETBOX/generatorNETBOX from unwanted access.

## Embedded Server

The embedded server is an option and is only available if ordered with and installed on your particular digitizerNET-BOX/generatorNETBOX. Please see the dedicated Embedded Server Option chapter for more information on this feature.

Using the „Reset password“ button the password for the user „embedded“ is reset to the default password which is also „embedded“

The autostart feature allows the user to automatically start scripts, programs or services on the device during boot process. If something fails with the start, the autostart feature can be disabled using the „Autostart [Disable]“ button. After fixing the automatically starting programs one can enable the autostart feature again.

## Login/Logout

As soon as a password has been entered in the security settings a login/logout command is available from the webpage menu.

After entering the password once the login stays valid until a logout or until closing the web browser.

## IVI Driver

The IVI Foundation is an open consortium founded in 1998 to promote standards for programming test instruments. Composed primarily of instrument manufacturers, end-users, software vendors, and system integrators, the Foundation strives to create specifications that govern the development of instrument drivers.

-> <http://IVIfoundation.org>

## About IVI

The IVI standards define an open driver architecture, a set of instrument classes, and shared software components. Together these provide critical elements needed for instrument interchangeability.

### Benefits

IVI offers several benefits to measurement system designers:

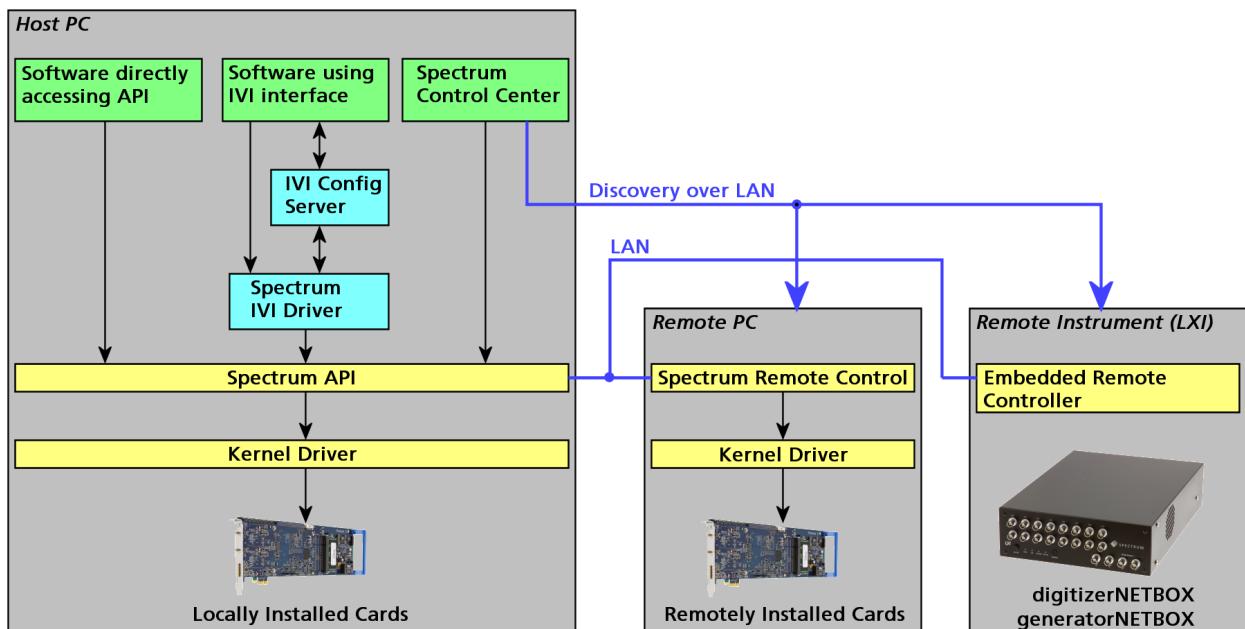
- IVI's defined Application Programming Interfaces (APIs) standardize common measurement functions reducing the time needed to learn a new IVI instrument.
- Instrument simulation allows developers to run code without an instrument. This feature reduces the need for sometimes scarce measurement hardware resources and it can simplify testing of measurement applications.
- IVI drivers feature enhanced ease of use in popular Application Development Environments. IVI's standard APIs, combined with IVI driver wrappers where appropriate, provide fast, intuitive access to driver functions.
- IVI drivers provide for interchangeability. Interchangeability reduces the time and effort needed to integrate measurement devices into new or existing systems

### Interchangeability

Systems designed with IVI drivers enjoy the benefits of standardized code that can be interchanged into other systems. This code also supports interchange of measurement devices – helping to prevent hardware obsolescence. Interchangeability is supported on three levels: The IVI architecture specifications allow architectural interchangeability – that is a standard driver architecture that can be reused. The class specifications provide syntactic interchangeability which supports instrument exchange with minimal code changes. The highest level of interchangeability is achieved by using the IVI signal specifications.

## General Concept of the Spectrum IVI driver

The Spectrum IVI driver is based on the standard Spectrum API and can be used with any Spectrum products specified below in the supported hardware chapter. The Spectrum products to be accessed with the IVI driver can be locally installed data acquisition cards, remotely installed data acquisition cards or remote LXI instruments like a digitizerNETBOX or generatorNETBOX.



## **Supported Spectrum Hardware**

All Spectrum analog data acquisition hardware based on the SPCM driver structure is supported by the IVI driver. There is only one IVI driver for all hardware.

### **Supported data acquisition card families:**

- M2i.20xx and M2i.20xx-exp family
- M3i.21xx and M3i.21xx-exp family
- M4i.22xx-x8 and M4x.22xx-x4 family
- M2i.30xx and M2i.30xx-exp family
- M2i.31xx and M2i.31xx-exp family
- M3i.32xx and M3i.32xx-exp family
- M2i.40xx and M2i.40xx-exp family
- M3i.41xx and M3i.41xx-exp family
- M4i.44xx-x8 and M4x.44xx-x4 family
- M2i.46xx and M2i.46xx-exp family
- M2i.47xx and M2i.47xx-exp family
- M3i.48xx and M3i.48xx-exp family
- M2i.49xx and M2i.49xx-exp family
- M2p.59xx-x4 family
- M2p.65xx-x4 family
- M2i.60xx and M2i.60xx-exp family
- M4i.66xx-x8 and M4x.66xx-x4 family

### **Supported digitizerNETBOX families**

- DN2.20x-xx family
- DN2.22x-xx and DN6.22x-xx family
- DN2.44x-xx and DN6.44x-xx family
- DN2.46x-xx and DN6.46x-xx family
- DN2.49x-xx and DN6.49x-xx family
- DN2.59x-xx and DN6.59x-xx family

### **Supported generatorNETBOX families**

- DN2.60x-xx family
- DN2.65x-xx and DN6.65x-xx family
- DN2.66x-xx and DN6.66x-xx family

## **IVI Compliance**

General information on the Spectrum IVI driver:

IVI class specification version	Version 3.3
IVI-C interface	supported
IVI-COM interface	supported
IVI.NET interface	not supported

The following IVI classes are supported by different instrument types:

IVI Class	Supported by Spectrum hardware	IVI specific driver function prefix
IVIScope	Supported by all digitizerNETBOX devices and analog data acquisition cards listed above	SpecScope_
IVIDigitizer	Supported by all digitizerNETBOX devices and analog data acquisition cards listed above	SpecDigitizer_
IVIFgen	Supported by all generatorNETBOX devices and analog data generator cards listed above	SpecFGen_

## **Supported Operating Systems**

32 bit operating systems	64 bit operating systems
Windows 7	Windows 7
Windows 8	Windows 8
Windows 10	Windows 10

## Supported Standard Driver Features

Feature	Supported	Description of the Feature
State caching	yes standard feature of the API which is permanently active	To minimize the number of I/O calls needed to configure an instrument to a new state, IVI specific drivers may implement state caching. IVI specific drivers can choose to implement state caching for all, some, or none of the instrument settings. If the user enables state caching and the IVI specific driver implements caching for hardware configuration attributes, driver functions perform instrument I/O when the current state of the instrument settings is different from what the user requests.
Range checking	yes standard feature of the API which is permanently active	If range checking is enabled, an IVI specific driver checks that input parameters are within the valid range for the instrument.
Instrument Status Checking	yes standard feature of the API which is permanently active	If instrument status checking is enabled, an IVI specific driver automatically checks the status of the instrument after most operations. If the instrument indicates that it has an error, the driver returns a special error code. The user then calls the Error Query function to retrieve the instrument specific error code from the instrument.
Multithread Safety	yes	IVI drivers are multithread safe. Multithread safety means that multiple threads in the same process can use the same IVI driver session and that different sessions of the same IVI driver can run simultaneously on different threads.
Simulation	yes	If simulation is enabled, an IVI specific driver does not perform instrument I/O, and the driver creates simulated data for output parameters. This allows the user to execute instrument driver calls in the application program even though the instrument is not available.

## IVIScope Supported Class Capabilities

Feature	Supported	Description of Feature
IVIScopeBase	yes	Base Capabilities of the IVIScope specification. This group includes the capability to acquire waveforms using edge triggering.
IVIScopeInterpolation	no	Extension: IVIScope with the ability to configure the oscilloscope to interpolate missing points in a waveform.
IVIScopeTVTrigger	no	Extension: IVIScope with the ability to trigger on standard television signals.
IVIScopeRuntTrigger	no	Extension: IVIScope with the ability to trigger on runts.
IVIScopeGlitchTrigger	no	Extension: IVIScope with the ability to trigger on glitches.
IVIScopeWidthTrigger	no	Extension: IVIScope with the ability to trigger on a variety of conditions regarding pulse widths.
IVIScopeAClineTrigger	no	Extension: IVIScope with the ability to trigger on zero crossings of a network supply voltage.
IVIScopeWaveformMeas	no	Extension: IVIScope with the ability to calculate waveform measurements, such as rise time or frequency.
IVIScopeMinMaxWaveform	no	Extension: IVIScope with the ability to acquire a minimum and maximum waveforms that correspond to the same time range.
IVIScopeProbeAutoSense	no	Extension: IVIScope with the ability to automatically sense the probe attenuation of an attached probe.
IVIScopeContinuous Acquisition	no	Extension: IVIScope with the ability to continuously acquire data from the input and display it on the screen.
IVIScopeAverage Acquisition	no	Extension: IVIScope with the ability to create a waveform that is the average of multiple waveform acquisitions.
IVIScopeSampleMode	no	Extension: IVIScope with the ability to return the actual sample mode.
IVIScopeTrigger Modifier	no	Extension: IVIScope with the ability to modify the behavior of the triggering subsystem in the absence of a expected trigger.
IVIScopeAutoSetup	no	Extension: IVIScope with the automatic configuration ability.

## IVIDigitizer Supported Class Capabilities

Feature	Supported	Description of Feature
IVIDigitizerBase	yes	Base Capabilities of the IVIDigitizer specification. This group includes the capability to acquire waveforms using edge triggering.
IVIDigitizerMultiRecordAcquisition	yes	Extension: IVIDigitizer with the ability to do multi-record acquisitions.
IVIDigitizerBoardTemperature	no	Extension: IVIDigitizer with the ability to report the temperature of the digitizer.
IVIDigitizerChannelFilter	no	Extension: IVIDigitizer with the ability to control the channel input filter frequency.
IVIDigitizerChannelTemperature	no	Extension: IVIDigitizer with the ability to report the temperature of individual digitizer channels.
IVIDigitizerTimeInterleavedChannels	no	Extension: IVIDigitizer with the ability to combine two or more input channels to achieve higher acquisition rates and/or record lengths.
IVIDigitizerDataInterleavedChannels	no	Extension: IVIDigitizer with the ability to interleave the data from two or more input channels, usually to create complex (I/Q) data.
IVIDigitizerReferenceOscillator	no	Extension: IVIDigitizer with the ability to use an external reference oscillator.
IVIDigitizerSampleClock	yes	Extension: IVIDigitizer with the ability to use an external sample clock.
IVIDigitizerSampleMode	no	Extension: IVIDigitizer with the ability to control whether the digitizer is using real-time or equivalent-time sampling.
IVIDigitizerSelfCalibration	yes	Extension: IVIDigitizer with the ability to perform self calibration.
IVIDigitizerDownconversion	no	Extension: IVIDigitizer with the ability to do frequency translation or downconversion in hardware.
IVIDigitizerArm	no	Extension: IVIDigitizer with the ability to arm on positive or negative edges.
IVIDigitizerMultiArm	no	Extension: IVIDigitizer with the ability to arm on one or more sources.
IVIDigitizerGlitchArm	no	Extension: IVIDigitizer with the ability to arm on glitches.
IVIDigitizerRuntArm	no	Extension: IVIDigitizer with the ability to arm on runts.
IVIDigitizerSoftwareArm	no	Extension: IVIDigitizer with the ability to arm acquisitions.
IVIDigitizerTVArm	no	Extension: IVIDigitizer with the ability to arm on standard TV signals.
IVIDigitizerWidthArm	no	Extension: IVIDigitizer with the ability to arm on a variety of conditions regarding pulse widths.
IVIDigitizerWindowArm	no	Extension: IVIDigitizer with the ability to arm on signals entering or leaving a defined voltage range.
IVIDigitizerTriggerModifier	no	Extension: IVIDigitizer with the ability to perform an alternative triggering function in the event that the specified trigger event doesn't occur.
IVIDigitizerMultiTrigger	yes	Extension: IVIDigitizer with the ability to trigger on one or more sources.
IVIDigitizerPretriggerSamples	yes	Extension: IVIDigitizer with the ability to specify a number of samples to fill up the data buffer with pre-trigger data.
IVIDigitizerTriggerHoldoff	no	Extension: IVIDigitizer with the ability to specify a length of time after the digitizer detects a trigger during which the digitizer ignores additional triggers.
IVIDigitizerGlitchTrigger	no	Extension: IVIDigitizer with the ability to trigger on glitches.
IVIDigitizerRuntTrigger	no	Extension: IVIDigitizer with the ability to trigger on runts.
IVIDigitizerSoftwareTrigger	no	Extension: IVIDigitizer with the ability to trigger acquisitions.
IVIDigitizerTVTrigger	no	Extension: IVIDigitizer with the ability to trigger on standard television signals.
IVIDigitizerWidthTrigger	no	Extension: IVIDigitizer with the ability to trigger on a variety of conditions regarding pulse widths.
IVIDigitizerWindowTrigger	yes	Extension: IVIDigitizer with the ability to trigger on signals entering or leaving a defined voltage range.

## **IVIFGen Supported Class Capabilities**

Feature	Supported	Description of Feature
IVIFgenBase	yes	Base Capabilities.
IVIFgenArbFrequency	no	Extension: IVIFgen with the ability to generate arbitrary waveforms with user-defined sample rate.
IVIFgenArbWfm	yes	Extension: IVIFgen with the ability to generate user-defined arbitrary waveforms.
IVIFgenArbSeq	no	Extension: IVIFgen with the ability to generate of arbitrary sequences
IVIFgenBurst	no	Extension: IVIFgen with the ability to generate discrete numbers of waveform cycles.
IVIFgenInternalTrigger	no	Extension: IVIFgen with the ability to use internally generated triggers
IVIFgenModulateAM	no	Extension: IVIFgen with the ability to apply amplitude modulation to an output signal
IVIFgenModulateFM	no	Extension: IVIFgen with the ability to apply frequency modulation to an output signal
IVIFgenSoftwareTrigger	no	Extension: IVIFgen with the ability to generate signals based on software triggers
IVIFgenStdFunc	yes	Extension: IVIFgen with the ability to generate standard waveforms
IVIFgenTrigger	no	Extension: IVIFgen with the ability to use user-definable trigger sources

## **Find more Information on IVI**

The official IVI foundation webpage offers a lot of additional information on setup and programming of the IVI drivers using different environments.

### **General Information on IVI**

-><http://ivifoundation.org>

The website of the IVI foundation offers several documents and detailed explanations for the usage of IVI drivers and the benefits.

### **IVI Getting Started Guides and Videos**

-> <http://ivifoundation.org/resources/default.aspx>

In here you find getting started guides and videos for different environments:

- Using IVI with Visual C++
- Using IVI Visual C# and Visual Basic .NET
- Using IVI with LabVIEW
- Using IVI with LabWindows/CVI
- Using IVI with MATLAB
- Using IVI with Measure Foundry
- Using IVI with Visual Basic 6.0
- Using IVI with Keysight VEE Pro

## **Installation**

### **Installer**

The Spectrum IVI Driver Installer is shipped as an executable containing all IVI related software parts. There is only one installer for both 32 bit and 64 bit environments. The installer automatically detects the components that are necessary to install.

 **Please be sure to have the latest drivers available. You find the current driver archives on the Spectrum webpage [www.spectrum-instrumentation.com](http://www.spectrum-instrumentation.com) available for download.**

### **Shared Components**

To improve users' experience when they combine drivers and other software from various vendors, it is important to have some key software components common to all implementations. In order to accomplish this, the IVI Foundation provides a standard set of shared components that must be used by all compliant drivers and ancillary software. These components provide services to drivers and driver clients that need to be common to all drivers, for instance, the administration of system-wide configuration.

The IVI shared components are available directly at the IVI Foundation homepage [www.ivifoundation.org](http://www.ivifoundation.org). Please download the latest version of the IVI shared components there.

The IVI Shared Component installer creates a directory structure to house the IVI Shared Components as well as IVI drivers themselves. The root of this directory structure is referred to as the IVI install directory [IVIInstallDir] and is typically located under [program files]\IVI Foundation\IVI.

### **Installation Procedure**

Please stick to this installation order to avoid any problems with the drivers:

### **Spectrum Card locally installed**

- Install card into the system as described in the hardware manual
- Start the system and let Windows install the hardware driver from USB-Stick or from your download folder
- Install the Spectrum Control Center
- Install the IVI shared components from [www.ivifoundation.org](http://www.ivifoundation.org)
- Install the IVI driver package

### **Spectrum Card remotely installed**

- Install card into the remote system as described in the hardware manual
- Start the remote system and let Windows install the hardware driver from USB-Stick or from your download folder
- Install the Spectrum Remote Package onto the remote PC as described in the manual
- Install the Spectrum Control Center on the host system
- Setup the remote connection inside the Control Center as described in the hardware manual
- Install the IVI shared components from [www.ivifoundation.org](http://www.ivifoundation.org)
- Install the IVI driver package on the host system

### **Spectrum digitizerNETBOX/generatorNETBOX remotely controlled**

- Connect the digitizerNETBOX/generatorNETBOX to your LAN or directly to your host PC
- Install the Spectrum Control Center on the host system
- Setup the remote connection inside the Control Center as described in the hardware manual
- Install the IVI shared components from [www.ivifoundation.org](http://www.ivifoundation.org)
- Install the IVI driver package on the host system

### **No Spectrum hardware available, only simulated cards**

- Install the Spectrum Control Center on the system
- Setup one or more demo cards inside the Spectrum Control Center
- Install the IVI shared components from [www.ivifoundation.org](http://www.ivifoundation.org)
- Install the IVI driver package on the host system

### **Installation of the IVI driver package**

Please start the installation by doubleclicking the install file

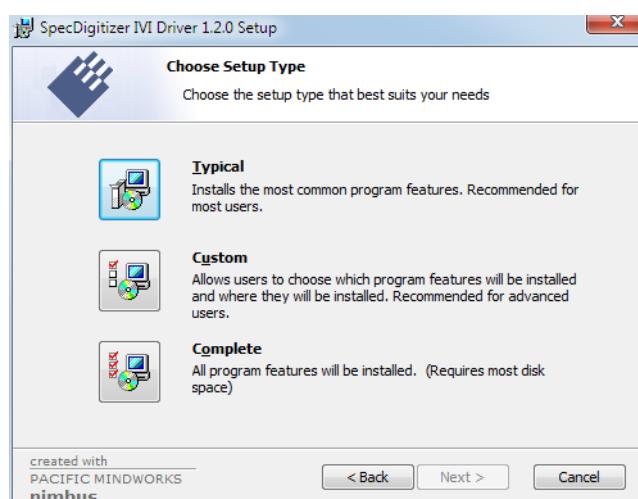
There is one installer for the IVI scope class driver and one installer for the IVI digitizer class driver. You may install one of them or both.



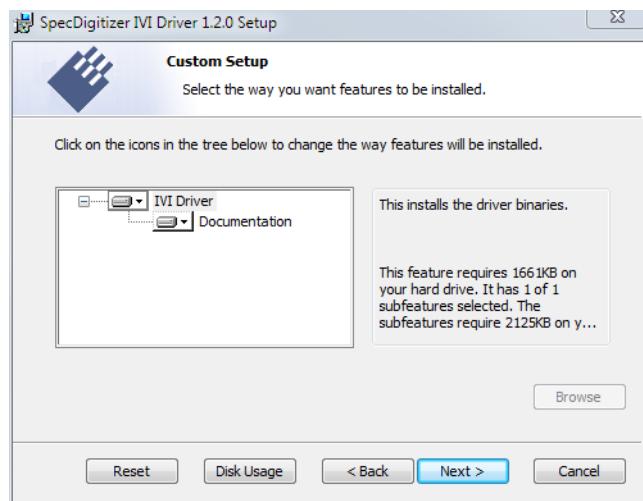
Select the setup type for the installation:

- Typical setup will install the most common program features
- Custom setup allows user to choose which program features will be installed.
- Complete setup will install all prgra. features.

Typical and Complete setup runs without any further user interaction and install the needed components of the driver.



The custom setup allows users to deselect certain parts of the driver package



## **Configuration Store**

### **General Information**

The IVI Configuration Server is the run-time module that is responsible for providing system database services to IVI based measurement system applications. Specifically, it provides system initialization and configuration information. The IVI Configuration Server is used by several of the IVI compliant modules. For instance, the Configuration Server indicates which physical instrument and IVI driver will be used by a particular application to provide a particular measurement capability.

Since a typical system intermixes instruments and drivers from multiple vendors this system configuration service needs to be accessed in a vendor independent fashion. Therefore, the IVI Configuration Server is an IVI shared component (that is, the code is owned by the IVI Foundation). The IVI Configuration Server is provided by the IVI Foundation because the architecture requires a single Configuration Server be installed on any system, therefore having a single shared implementation eliminates potential conflicts from divergent implementations.

The IVI Configuration Server is a single executable and one or more XML configuration stores (databases) made up of the following basic components:

- The physical database (known as the configuration store). A physical configuration store is a single XML file. APIs are available to read and write the data to arbitrary files, thus providing complex applications with the ability to directly manage system configurations.
- The API (and its implementation) used to read information from the configuration store(s). The IVI modules typically use this API when they are instantiated and configured.
- The API (and its implementation) to write information to the configuration store(s). This API is typically used by GUI or other applications that set up the initial configuration.
- The API (and its implementation) used to bind an instance of the Configuration Server code to a particular copy of the configuration information stored on a system. This includes appropriate algorithms for gaining access to the master configuration store.

### **Repeated Capabilities**

In many instruments there are capabilities that are duplicated either identically or very similarly across the instrument. Such capabilities are called repeated capabilities. The IVI class-compliant APIs represent repeated capabilities by a parameter that indicates which instance of the duplicate capability this function is intended to access. The IVI C APIs include this parameter as an additional parameter to function calls.

The IVI Configuration Server provides a way for software modules to publish the functionality that is duplicated and the strings that the software module recognizes to access the repeated capabilities. The IVI Configuration Server also provides a way for the client to supply aliases for the physical identifiers recognized by the drivers.

The Spectrum IVI driver for example uses the channel index as repeated capability allowing to give channel names as an identifier.

# Programming the Board

## Overview

The following chapters show you in detail how to program the different aspects of the board. For every topic there's a small example. For the examples we focused on Visual C++. However as shown in the last chapter the differences in programming the board under different programming languages are marginal. This manual describes the programming of the whole hardware family. Some of the topics are similar for all board versions. But some differ a little bit from type to type. Please check the given tables for these topics and examine carefully which settings are valid for your special kind of board.

## Register tables

The programming of the boards is totally software register based. All software registers are described in the following form:

Register	Value	Direction	Description
SPC_M2CMD	100	w	Command register of the board.
M2CMD_CARD_START	4h		Starts the board with the current register settings.
M2CMD_CARD_STOP	40h		Stops the board manually.

Any constants that can be used to program the register directly are shown inserted beneath the register table.

The decimal or hexadecimal value of the constant, also found in the regs.h file. Hexadecimal values are indicated with an „h“ at the end. This value must be used with all programs or compilers that cannot use the header file directly.

Short description of the use of this constant.

If no constants are given below the register table, the dedicated register is used as a switch. All such registers are activated if written with a "1" and deactivated if written with a "0".



## Programming examples

In this manual a lot of programming examples are used to give you an impression on how the actual mentioned registers can be set within your own program. All of the examples are located in a separated colored box to indicate the example and to make it easier to differ it from the describing text.

All of the examples mentioned throughout the manual are written in C/C++ and can be used with any C/C++ compiler for Windows or Linux.

### Complete C/C++ Example

```
#include "../c_header/dlltyp.h"
#include "../c_header/regs.h"
#include "../c_header/spcm_drv.h"

#include <stdio.h>

int main()
{
    drv_handle hDrv;
    int32 lCardType;

    hDrv = spcm_hOpen ("/dev/spcm0");
    if (!hDrv)
        return -1;

    spcm_dwGetParam_i32 (hDrv, SPC_PCITYP, &lCardType);           // simple command, read out of card type
    printf ("Found Card M2i/M3i/M4i/M4x/M2p.%04x in the system\n", lCardType & TYP_VERSIONMASK);
    spcm_vClose (hDrv);

    return 0;
}
```

## Initialization

Before using the card it is necessary to open the kernel device to access the hardware. It is only possible to use every device exclusively using the handle that is obtained when opening the device. Opening the same device twice will only generate an error code. After ending the driver use the device has to be closed again to allow later re-opening. Open and close of driver is done using the spcm\_hOpen and spcm\_vClose function as described in the "Driver Functions" chapter before.

### Open/Close Example

```
drv_handle hDrv; // the handle of the device

hDrv = spcm_hOpen ("/dev/spcm0"); // Opens the board and gets a handle
if (!hDrv) // check whether we can access the card
{
    printf "Open failed\n";
    return -1;
}

... do any work with the driver

spcm_vClose (hDrv);
return 0;
```

## Initialization of Remote Products

The only step that is different when accessing remotely controlled cards or digitizerNETBOXes is the initialization of the driver. Instead of the local handle one has to open the VISA string that is returned by the discovery function. Alternatively it is also possible to access the card directly without discovery function if the IP address of the device is known.

```
drv_handle hDrv; // the handle of the device

hDrv = spcm_hOpen ("TCPIP::192.168.169.14::INSTR"); // Opens the remote board and gets a handle
if (!hDrv) // check whether we can access the card
{
    printf "Open of remote card failed\n";
    return -1;
}

...
```

Multiple cards are opened by indexing the remote card number:

```
hDrv = spcm_hOpen ("TCPIP::192.168.169.14::INSTR"); // Opens the remote board #0
// or alternatively
hDrv = spcm_hOpen ("TCPIP::192.168.169.14::INST0::INSTR"); // Opens the remote board #0
// all other boards require an index:
hDrv = spcm_hOpen ("TCPIP::192.168.169.14::INST1::INSTR"); // Opens the remote board #1
hDrv = spcm_hOpen ("TCPIP::192.168.169.14::INST2::INSTR"); // Opens the remote board #2
```

## Error handling

If one action caused an error in the driver this error and the register and value where it occurs will be saved.

 **The driver is then locked until the error is read out using the error function spcm\_dwGetErrorInfo\_i32. Any calls to other functions will just return the error code ERR\_LASTERR showing that there is an error to be read out.**

This error locking functionality will prevent the generation of unseen false commands and settings that may lead to totally unexpected behavior. For sure there are only errors locked that result on false commands or settings. Any error code that is generated to report a condition to the user won't lock the driver. As example the error code ERR\_TIMEOUT showing that the a timeout in a wait function has occurred won't lock the driver and the user can simply react to this error code without reading the complete error function.

As a benefit from this error locking it is not necessary to check the error return of each function call but just checking the error function once at the end of all calls to see where an error occurred. The enhanced error function returns a complete error description that will lead to the call that produces the error.

Example for error checking at end using the error text from the driver:

```
char szErrorText[ERRORTEXTLEN];

spcm_dwSetParam_i64 (hDrv, SPC_SAMPLERATE, 1000000);           // correct command
spcm_dwSetParam_i64 (hDrv, SPC_MEMSIZE, -345);                 // faulty command
spcm_dwSetParam_i64 (hDrv, SPC_POSTTRIGGER, 1024);            // correct command
if (spcm_dwGetErrorInfo_i32 (hDrv, NULL, NULL, szErrorText) != ERR_OK)
{
    printf (szErrorText);                                       // print the error text
    spcm_vClose (hDrv);                                         // close the driver
    exit (0);                                                 // and leave the program
}
```

This short program then would generate a printout as:

```
Error occurred at register SPC_MEMSIZE with value -345: value not allowed
```

**All error codes are described in detail in the appendix. Please refer to this error description and the description of the software register to examine the cause for the error message.**



Any of the parameters of the spcm\_dwGetErrorInfo\_i32 function can be used to obtain detailed information on the error. If one is not interested in parts of this information it is possible to just pass a NULL (zero) to this variable like shown in the example. If one is not interested in the error text but wants to install its own error handler it may be interesting to just read out the error generating register and value.

Example for error checking with own (simple) error handler:

```
uint32 dwErrorReg;
int32 lErrorCode;
uint32 dwErrorCode;

spcm_dwSetParam_i64 (hDrv, SPC_SAMPLERATE, 1000000);           // correct command
spcm_dwSetParam_i64 (hDrv, SPC_MEMSIZE, -345);                 // faulty command
spcm_dwSetParam_i64 (hDrv, SPC_POSTTRIGGER, 1024);            // correct command
dwErrorCode = spcm_dwGetErrorInfo_i32 (hDrv, &dwErrorReg, &lErrorCode, NULL); // check for an error
if (dwErrorCode)
{
    printf ("Errorcode: %d in register %d at value %d\n", lErrorCode, dwErrorReg, lErrorValue);
    spcm_vClose (hDrv);                                         // close the driver
    exit (0);                                                 // and leave the program
}
```

## Gathering information from the card

When opening the card the driver library internally reads out a lot of information from the on-board eeprom. The driver also offers additional information on hardware details. All of this information can be read out and used for programming and documentation. This chapter will show all general information that is offered by the driver. There is also some more information on certain parts of the card, like clock machine or trigger machine, that is described in detail in the documentation of that part of the card.

All information can be read out using one of the spcm\_dwGetParam functions. Please stick to the "Driver Functions" chapter for more details on this function.

### Card type

The card type information returns the specific card type that is found under this device. When using multiple cards in one system it is highly recommended to read out this register first to examine the ordering of cards. Please don't rely on the card ordering as this is based on the BIOS, the bus connections and the operating system.

Register	Value	Direction	Description
SPC_PCITYP	2000	read	Type of board as listed in the table below.

One of the following values is returned, when reading this register. Each card has its own card type constant defined in regs.h. Please note that when reading the card information as a hex value, the lower word shows the digits of the card name while the upper word is a indication for the used bus type.

Card type	Card type as defined in regs.h	Value hexadecimal	Value decimal	Card type	Card type as defined in regs.h	Value hexadecimal	Value decimal
M2p.5911-x4	TYP_M2P5911_X4	95911h	612625				
M2p.5912-x4	TYP_M2P5912_X4	95912h	612626				
M2p.5916-x4	TYP_M2P5916_X4	95916h	612630				
M2p.5913-x4	TYP_M2P5913_X4	95913h	612627				
M2p.5920-x4	TYP_M2P5920_X4	95920h	612640	M2p.5940-x4	TYP_M2P5940_X4	95940h	612672
M2p.5921-x4	TYP_M2P5921_X4	95921h	612641	M2p.5941-x4	TYP_M2P5941_X4	95941h	612673
M2p.5922-x4	TYP_M2P5922_X4	95922h	612642	M2p.5942-x4	TYP_M2P5942_X4	95942h	612674
M2p.5926-x4	TYP_M2P5926_X4	95926h	612646	M2p.5946-x4	TYP_M2P5946_X4	95946h	612678
M2p.5923-x4	TYP_M2P5923_X4	95923h	612643	M2p.5943-x4	TYP_M2P5943_X4	95943h	612675
M2p.5930-x4	TYP_M2P5930_X4	95930h	612656	M2p.5960-x4	TYP_M2P5960_X4	95960h	612704
M2p.5931-x4	TYP_M2P5931_X4	95931h	612657	M2p.5961-x4	TYP_M2P5961_X4	95961h	612705
M2p.5932-x4	TYP_M2P5932_X4	95932h	612658	M2p.5962-x4	TYP_M2P5962_X4	95962h	612706
M2p.5936-x4	TYP_M2P5936_X4	95936h	612662	M2p.5966-x4	TYP_M2P5966_X4	95966h	612710
M2p.5933-x4	TYP_M2P5933_X4	95933h	612659	M2p.5963-x4	TYP_M2P5963_X4	95963h	612707

## Hardware and PCB version

Since all of the boards from Spectrum are modular boards, they consist of one base board and one piggy-back front-end module and eventually of an extension module like the star-hub. Each of these three kinds of hardware has its own version register. Normally you do not need this information but if you have a support question, please provide the revision together with it.

Register	Value	Direction	Description
SPC_PCIVERSION	2010	read	Base card version: the upper 16 bit show the hardware version, the lower 16 bit show the firmware version.
SPC_BASEPCBVERSION	2014	read	Base card PCB version: the lower 16 bit are divided into two 8 bit values containing pre/post decimal point version information. For example a lower 16 bit value of 0106h represents a PCB version V1.6. The upper 16 bit are always zero.
SPC_PCIMODULEVERSION	2012	read	Module version: the upper 16 bit show the hardware version, the lower 16 bit show the firmware version.
SPC_MODULEAPCBVERSION	2015	read	Module A PCB version: the lower 16 bit are divided into two 8 bit values containing pre/post decimal point version information. For example a lower 16 bit value of 0106h represents a PCB version V1.6. The upper 16 bit are always zero.
SPC_MODULEBPCBVERSION	2016	read	Module B PCB version: the lower 16 bit are divided into two 8 bit values containing pre/post decimal point version information. For example a lower 16 bit value of 0106h represents a PCB version V1.6. The upper 16 bit are always zero.

If your board has an additional piggy-back extension module mounted you can get the hardware version with the following register.

Register	Value	Direction	Description
SPC_PCIEVERSION	2011	read	Extension module version: the upper 16 bit show the hardware version, the lower 16 bit show the firmware version.
SPC_EXTPCBVERSION	2017	read	Extension module PCB version: the lower 16 bit are divided into two 8 bit values containing pre/post decimal point version information. For example a lower 16 bit value of 0106h represents a PCB version V1.6. The upper 16 bit are always zero.

If your board has an additional digital I/O extension module mounted (option -DigSMB or -DigFX2) you can get the hardware version with the following register.

Register	Value	Direction	Description
SPC_PCIDIGVERSION	2018	read	Digital I/O module version: the upper 16 bit show the hardware version, the lower 16 bit show the firmware version.
SPC_DIGPCBVERSION	2019	read	Digital I/O module PCB version: the lower 16 bit are divided into two 8 bit values containing pre/post decimal point version information. For example a lower 16 bit value of 0106h represents a PCB version V1.6. The upper 16 bit are always zero.

## Firmware versions

All the cards from Spectrum typically contain multiple programmable devices such as FPGAs, CPLDs and the like. Each of these have their own dedicated firmware version. This version information is readable for each device through the various version registers. Normally you do

not need this information but if you have a support question, please provide us with this information. Please note that number of devices and hence the readable firmware information is card series dependent:

<b>Register</b>	<b>Value</b>	<b>Direction</b>	<b>Description</b>	<b>Available for</b>				
				<b>M2i</b>	<b>M3i</b>	<b>M4i</b>	<b>M4x</b>	<b>M2p</b>
SPCM_FW_CTRL	210000	read	Main control FPGA version: the upper 16 bit show the firmware type, the lower 16 bit show the firmware version. For the standard release firmware, the type has always a value of 1.	X	X	X	X	X
SPCM_FW_CTRL_GOLDEN	210001	read	Main control FPGA golden version: the upper 16 bit show the firmware type, the lower 16 bit show the firmware version. For the golden (recovery) firmware, the type has always a value of 2.	-	-	X	X	X
SPCM_FW_CLOCK	210010	read	Clock distribution version: the upper 16 bit show the firmware type, the lower 16 bit show the firmware version. For the standard release firmware, the type has always a value of 1.	X	-	-	-	-
SPCM_FW_CONFIG	210020	read	Configuration controller version: the upper 16 bit show the firmware type, the lower 16 bit show the firmware version. For the standard release firmware, the type has always a value of 1.	X	X	-	-	-
SPCM_FW_MODULEA	210030	read	Front-end module A version: the upper 16 bit show the firmware type, the lower 16 bit show the firmware version. For the standard release firmware, the type has always a value of 1.	X	X	X	X	X
SPCM_FW_MODULEB	210031	read	Front-end module B version: the upper 16 bit show the firmware type, the lower 16 bit show the firmware version. For the standard release firmware, the type has always a value of 1. The version is zero if no second front-end module is installed on the card.	X	-	-	-	X
SPCM_FW_MODEXTRA	210050	read	Extension module (Star-Hub) version: the upper 16 bit show the firmware type, the lower 16 bit show the firmware version. For the standard release firmware, the type has always a value of 1. The version is zero if no extension module is installed on the card.	X	X	X	-	X
SPCM_FW_POWER	210060	read	Power controller version: the upper 16 bit show the firmware type, the lower 16 bit show the firmware version. For the standard release firmware, the type has always a value of 1.	-	-	X	X	X

Cards that do provide a golden recovery image for the main control FPGA, the currently booted firmware can additionally read out:

<b>Register</b>	<b>Value</b>	<b>Direction</b>	<b>Description</b>	<b>Available for</b>				
				<b>M2i</b>	<b>M3i</b>	<b>M4i</b>	<b>M4x</b>	<b>M2p</b>
SPCM_FW_CTRL_ACTIVE	210002	read	Cards that do provide a golden (recovery) firmware additionally have a register to read out the version information of the currently loaded firmware version string, do determine if it is standard or golden.  The hexadecimal 32bit format is: TVVVUUUU  T: the currently booted type (1: standard, 2: golden) V: the version U: unused, in production versions always zero	-	-	X	X	X

## Production date

This register informs you about the production date, which is returned as one 32 bit long word. The lower word is holding the information about the year, while the upper word informs about the week of the year.

<b>Register</b>	<b>Value</b>	<b>Direction</b>	<b>Description</b>
SPC_PCIDATE	2020	read	Production date: week in bits 31 to 16, year in bits 15 to 0

The following example shows how to read out a date and how to interpret the value:

```
spcm_dwGetParam_i32 (hDrv, SPC_PCIDATE, &lProdDate);
printf ("Production: week %d of year %d\n", (lProdDate >> 16) & 0xffff, lProdDate & 0xffff);
```

## Last calibration date (analog cards only)

This register informs you about the date of the last factory calibration. When receiving a new card this date is similar to the delivery date when the production calibration is done. When returning the card to calibration this information is updated. This date is not updated when just doing an on-board calibration by the user. The date is returned as one 32 bit long word. The lower word is holding the information about the year, while the upper word informs about the week of the year.

<b>Register</b>	<b>Value</b>	<b>Direction</b>	<b>Description</b>
SPC_CALIBDATE	2025	read	Last calibration date: week in bit 31 to 16, year in bit 15 to 0

## **Serial number**

This register holds the information about the serial number of the board. This number is unique and should always be sent together with a support question. Normally you use this information together with the register SPC\_PCITYP to verify that multiple measurements are done with the exact same board.

Register	Value	Direction	Description
SPC_PCISERIALNO	2030	read	Serial number of the board

## **Maximum possible sampling rate**

This register gives you the maximum possible sampling rate the board can run. The information provided here does not consider any restrictions in the maximum speed caused by special channel settings. For detailed information about the correlation between the maximum sampling rate and the number of activated channels please refer to the according chapter.

Register	Value	Direction	Description
SPC_PCISAMPLERATE	2100	read	Maximum sampling rate in Hz as a 64 bit integer value

## **Installed memory**

This register returns the size of the installed on-board memory in bytes as a 64 bit integer value. If you want to know the amount of samples you can store, you must regard the size of one sample of your card. All 8 bit A/D and D/A cards use only one byte per sample, while all other A/D and D/A cards with 12, 14 and 16 bit resolution use two bytes to store one sample. All digital cards need one byte to store 8 data bits.

Register	Value	Direction	Description
SPC_PCIMEMSIZE	2110	read _i32	Installed memory in bytes as a 32 bit integer value. Maximum return value will 1 GByte. If more memory is installed this function will return the error code ERR_EXCEEDINT32.
SPC_PCIMEMSIZE	2110	read _i64	Installed memory in bytes as a 64 bit integer value

The following example is written for a „two bytes“ per sample card (12, 14 or 16 bit board), on any 8 bit card memory in MSamples is similar to memory in MBytes.

```
spcm_dwGetParam_i64 (hDrv, SPC_PCIMEMSIZE, &llInstMemsize);
printf ("Memory on card: %d MBytes\n", (int32) (llInstMemsize /1024/1024));
printf (" : %d MSamples\n", (int32) (llInstMemsize /1024/1024/2));
```

## **Installed features and options**

The SPC\_PCIFEATURES register informs you about the features, that are installed on the board. If you want to know about one option being installed or not, you need to read out the 32 bit value and mask the interesting bit. In the table below you will find every feature that may be installed on a M2i/M3i/M4i/M4x/M2p card. Please refer to the ordering information to see which of these features are available for your card series.

Register	Value	Direction	Description
SPC_PCIFEATURES	2120	read	PCI feature register. Holds the installed features and options as a bitfield. The read value must be masked out with one of the masks below to get information about one certain feature.
SPCM_FEAT_MULTI	1h		Is set if the feature Multiple Recording / Multiple Replay is available.
SPCM_FEAT_GATE	2h		Is set if the feature Gated Sampling / Gated Replay is available.
SPCM_FEAT_DIGITAL	4h		Is set if the feature Digital Inputs / Digital Outputs is available.
SPCM_FEAT_TIMESTAMP	8h		Is set if the feature Timestamp is available.
SPCM_FEAT_STARHUB6_EXTM	20h		Is set on the card, that carries the star-hub extension or piggy-back module for synchronizing up to 6 cards (M2p).
SPCM_FEAT_STARHUB8_EXTM	20h		Is set on the card, that carries the star-hub extension or piggy-back module for synchronizing up to 8 cards (M4i).
SPCM_FEAT_STARHUB4	20h		Is set on the card, that carries the star-hub piggy-back module for synchronizing up to 4 cards (M3i).
SPCM_FEAT_STARHUB5	20h		Is set on the card, that carries the star-hub piggy-back module for synchronizing up to 5 cards (M2i).
SPCM_FEAT_STARHUB16_EXTM	40h		Is set on the card, that carries the star-hub piggy-back module for synchronizing up to 16 cards (M2p).
SPCM_FEAT_STARHUB8	40h		Is set on the card, that carries the star-hub piggy-back module for synchronizing up to 8 cards (M3i).
SPCM_FEAT_STARHUB16	40h		Is set on the card, that carries the star-hub piggy-back module for synchronizing up to 16 cards (M2i).
SPCM_FEAT_ABA	80h		Is set if the feature ABA mode is available.
SPCM_FEAT_BASEXIO	100h		Is set if the extra BaseXIO option is installed. The lines can be used for asynchronous digital I/O, extra trigger or timestamp reference signal input.
SPCM_FEAT_AMPLIFIER_10V	200h		Arbitrary Waveform Generators only: card has additional set of calibration values for amplifier card.
SPCM_FEAT_STARHUBSYSSMASTER	400h		Is set in the card that carries a System Star-Hub Master card to connect multiple systems (M2i).
SPCM_FEAT_DIFFMODE	800h		M2i,30xx series only: card has option -diff installed for combining two SE channels to one differential channel.
SPCM_FEAT_SEQUENCE	1000h		Only available for output cards or I/O cards: Replay sequence mode available.
SPCM_FEAT_AMPMODULE_10V	2000h		Is set on the card that has a special amplifier module for mounted (M2i,60xx/61xx only).
SPCM_FEAT_STARHUBSYSSLAVE	4000h		Is set in the card that carries a System Star-Hub Slave module to connect with System Star-Hub master systems (M2i).
SPCM_FEAT_NETBOX	8000h		The card is physically mounted within a digitizerNETBOX or generatorNETBOX.
SPCM_FEAT_REMOTE SERVER	10000h		Support for the Spectrum Remote Server option is installed on this card.

SPCM_FEAT_SCAPP	20000h	Support for the SCAPP option allowing CUDA RDMA access to supported graphics cards for GPU calculations (M4i and M2p)
SPCM_FEAT_DIG16_SMB	40000h	M2p: Set if option M2p.xxxx-DigSMB is installed, adding 16 additional digital I/Os via SMB connectors.
SPCM_FEAT_DIG16_FX2	80000h	M2p: Set if option M2p.xxxx-DigFX2 is installed, adding 16 additional digital I/Os via FX2 multipin connectors.
SPCM_FEAT_DIGITALBWFILTER	100000h	A digital (boxcar) bandwidth filter is available that can be globally enabled/disabled for all channels.
SPCM_FEAT_CUSTOMMOD_MASK	F0000000h	The upper 4 bit of the feature register is used to mark special custom modifications. This is only used if the card has been specially customized. Please refer to the extra documentation for the meaning of the custom modifications. (M2i/M3i). For M4i, M4x and M2p cards see „Custom modifications“ chapter instead.

The following example demonstrates how to read out the information about one feature.

```
spcm_dwGetParam_i32 (hDrv, SPC_PCIFEATURES, &lFeatures);
if (lFeatures & SPCM_FEAT_DIGITAL)
    printf("Option digital inputs/outputs is installed on your card");
```

The following example demonstrates how to read out the custom modification code.

```
spcm_dwGetParam_i32 (hDrv, SPC_PCIFEATURES, &lFeatures);
lCustomMod = (lFeatures >> 28) & 0xF;
if (lCustomMod != 0)
    printf("Custom modification no. %d is installed.", lCustomMod);
```

### **Installed extended Options and Features**

Some cards (such as M4i/M4x/M2p cards) can have advanced features and options installed. This can be read out with the following register:

Register	Value	Direction	Description
SPC_PCIEXTFEATURES	2121	read	PCI extended feature register. Holds the installed extended features and options as a bitfield. The read value must be masked out with one of the masks below to get information about one certain feature.
SPCM_FEAT_EXTFW_SEGSTAT	1h		Is set if the firmware option „Block Statistics“ is installed on the board, which allows certain statistics to be on-board calculated for data being recorded in segmented memory modes, such as Multiple Recording or ABA.
SPCM_FEAT_EXTFW_SEGAVERAGE	2h		Is set if the firmware option „Block Average“ is installed on the board, which allows on-board hardware averaging of data being recorded in segmented memory modes, such as Multiple Recording or ABA.
SPCM_FEAT_EXTFW_BOXCAR	4h		Is set if the firmware mode „Boxcar Average“ is supported in the installed firmware version.

### **Miscellaneous Card Information**

Some more detailed card information, that might be useful for the application to know, can be read out with the following registers:

Register	Value	Direction	Description
SPC_MIINST_MODULES	1100	read	Number of the installed front-end modules on the card.
SPC_MIINST_CHPERMODULE	1110	read	Number of channels installed on one front-end module.
SPC_MIINST_BYTESPERSAMPLE	1120	read	Number of bytes used in memory by one sample.
SPC_MIINST_BITSPERSAMPLE	1125	read	Resolution of the samples in bits.
SPC_MIINST_MAXADCVALUE	1126	read	Decimal code of the full scale value.
SPC_MIINST_MINEXTCLOCK	1145	read	Minimum external clock that can be fed in for direct external clock (if available for card model).
SPC_MIINST_MAXEXTCLOCK	1146	read	Maximum external clock that can be fed in for direct external clock (if available for card model).
SPC_MIINST_MINEXTREFCLOCK	1148	read	Minimum external clock that can be fed in as a reference clock.
SPC_MIINST_MAXEXTREFCLOCK	1149	read	Maximum external clock that can be fed in as a reference clock.
SPC_MIINST_ISDEMOCARD	1175	read	Returns a value other than zero, if the card is a demo card.

### **Function type of the card**

This register returns the basic type of the card:

Register	Value	Direction	Description
SPC_FNCTYPE	2001	read	Gives information about what type of card it is.
SPCM_TYPE_AI	1h		Analog input card (analog acquisition; the M2i.4028 and M2i.4038 also return this value)
SPCM_TYPE_AO	2h		Analog output card (arbitrary waveform generators)
SPCM_TYPE_DI	4h		Digital input card (logic analyzer card)
SPCM_TYPE_DO	8h		Digital output card (pattern generators)
SPCM_TYPE_DIO	10h		Digital I/O (input/output) card, where the direction is software selectable.

## Used type of driver

This register holds the information about the driver that is actually used to access the board. Although the driver interface doesn't differ between Windows and Linux systems it may be of interest for a universal program to know on which platform it is working.

Register	Value	Direction	Description
SPC_GETDRVTYPE	1220	read	Gives information about what type of driver is actually used
DRVTYP_LINUX32	1		Linux 32bit driver is used
DRVTYP_WDM32	4		Windows WDM 32bit driver is used (XP/Vista/Windows 7/Windows 8/Windows 10).
DRVTYP_WDM64	5		Windows WDM 64bit driver is used by 64bit application (XP64/Vista/Windows 7/Windows 8/Windows 10).
DRVTYP_WOW64	6		Windows WDM 64bit driver is used by 32bit application (XP64/Vista/Windows 7/Windows 8/Windows 10).
DRVTYP_LINUX64	7		Linux 64bit driver is used

## Driver version

This register holds information about the currently installed driver library. As the drivers are permanently improved and maintained and new features are added user programs that rely on a new feature are requested to check the driver version whether this feature is installed.

Register	Value	Direction	Description
SPC_GETDRVVERSION	1200	read	Gives information about the driver library version

The resulting 32 bit value for the driver version consists of the three version number parts shown in the table below:

Driver Major Version	Driver Minor Version	Driver Build
8 Bit wide: bit 24 to bit 31	8 Bit wide, bit 16 to bit 23	16 Bit wide, bit 0 to bit 15

## Kernel Driver version

This register informs about the actually used kernel driver. Windows users can also get this information from the device manager. Please refer to the „Driver Installation“ chapter. On Linux systems this information is also shown in the kernel message log at driver start time.

Register	Value	Direction	Description
SPC_GETKERNELVERSION	1210	read	Gives information about the kernel driver version.

The resulting 32 bit value for the driver version consists of the three version number parts shown in the table below:

Driver Major Version	Driver Minor Version	Driver Build
8 Bit wide: bit 24 to bit 31	8 Bit wide, bit 16 to bit 23	16 Bit wide, bit 0 to bit 15

The following example demonstrates how to read out the kernel and library version and how to print them.

```
spcm_dwGetParam_i32 (hDrv, SPC_GETDRVVERSION, &lLibVersion);
spcm_dwGetParam_i32 (hDrv, SPC_GETKERNELVERSION, &lKernelVersion);
printf("Kernel V %d.%d build %d\n", lKernelVersion >> 24, (lKernelVersion >> 16) & 0xff, lKernelVersion & 0xffff);
printf("Library V %d.%d build %d\n", lLibVersion >> 24, (lLibVersion >> 16) & 0xff, lLibVersion & 0xffff);
```

This small program will generate an output like this:

```
Kernel V 1.11 build 817
Library V 1.1 build 854
```

## Custom modifications

Since all of the boards from Spectrum are modular boards, they consist of one base board and one piggy-back front-end module and eventually of an extension module like the Star-Hub. Each of these three kinds of hardware has its own version register. Normally you do not need this information but if you have a support question, please provide the revision together with it.

Register	Value	Direction	Description
SPCM_CUSTOMMOD	3130	read	Dedicated feature register used to mark special custom modifications of the base card and/or the front-end module and/or the Star-Hub module. This is only used if the card has been specially customized. Please refer to the extra documentation for the meaning of the custom modifications.  This register is supported for all M4i, M4x, M2p and digitizerNETBOX/generatorNETBOX based upon these series.
SPCM_CUSTOMMOD_BASE_MASK	00000FFh		Mask for the custom modification of the base card.
SPCM_CUSTOMMOD_MODULE_MASK	0000FF00h		Mask for the custom modification of the front-end module(s).
SPCM_CUSTOMMOD_STARHUB_MASK	00FF0000h		Mask out custom modification of the Star-Hub module.

## Reset

Every Spectrum card can be reset by software. Concerning the hardware, this reset is the same as the power-on reset when starting the host computer. In addition to the power-on reset, the reset command also brings all internal driver settings to a defined default state. A software reset is automatically performed, when the driver is first loaded after starting the host system.

**It is recommended, that every custom written program performs a software reset first, to be sure that the driver is in a defined state independent from possible previous setting.**



Performing a board reset can be easily done by the related board command mentioned in the following table.

Register	Value	Direction	Description
SPC_M2CMD	100	w	Command register of the board.
M2CMD_CARD_RESET	1h		A software and hardware reset is done for the board. All settings are set to the default values. The data in the board's on-board memory will be no longer valid. Any output signals like trigger or clock output will be disabled.

## **digitizerNETBOX/generatorNETBOX specific registers**

Information about the digitizerNETBOX/generatorNETBOX, in which the card is installed, can be read out via the card handle.

The following digitizerNETBOX/generatorNETBOX specific information registers can be used:

Register	Value	Direction	Description
SPC_NETBOX_TYPE	400000	read	Hex coded version of the digitizerNETBOX/generatorNETBOX, example 02490110h: bit 24 to 31: Series: example 02h = DN2 bit 16 to 23: Family: example 49h = 49 bit 8 to 15: Speed grade: example 01h = 1 bit 0 to 7: Channels: example 10h = 16 Decoded example: DN2.491-16
SPC_NETBOX_SERIALNO	400001	read	Serial number of the digitizerNETBOX/generatorNETBOX itself. In most cases the serial numbers of the digitizerNETBOX/generatorNETBOX and the embedded cards are consecutive but there is no guarantee for this.
SPC_NETBOX_PRODUCTIONDATE	400002	read	Production date: week in bit 31 to 16, year in bit 15 to 0
SPC_NETBOX_HVVERSION	400003	read	The hardware version of the digitizerNETBOX/generatorNETBOX products
SPC_NETBOX_SWVERSION	400004	read	The software version of the installed remote server
SPC_NETBOX_FEATURES	400005	read	Features of the digitizerNETBOX/generatorNETBOX. Holds the installed features and options as a bitfield. The read value must be masked out with one of the masks below to get information about one certain feature.
NETBOX_FEAT_DCPOWER	1h		Is set if one of the DC power options are installed in the system.
NETBOX_FEAT_BOOTATPOWERON	2h		Is set if the special feature automatic boot on power on is installed. This would allow remote devices to automatically reboot after a failure of the power supply.
NETBOX_FEAT_EMBEDDED SERVER	4h		Is set if the option Embedded Server is installed.

Register	Value	Direction	Description
SPC_NETBOX_CUSTOM	400006	read	Custom code for custom modifications of the digitizerNETBOX/generatorNETBOX.
SPC_NETBOX_WAKEONLAN	400007	write	This command is issued to wake a digitizerNETBOX/generatorNETBOX that is currently in standby-mode with a special wake-on-lan message. Please note that the card handle is NULL in this case as there is no opened card here. The argument is the MAC address of that device
SPC_NETBOX_MACADDRESS	400008	read	Reads out the MAC address of the digitizerNETBOX/generatorNETBOX.
SPC_NETBOX_LANIDFLASH	400009	write	By writing 1 to this register, one can start the automatic flashing of the LAN Id to detect a particular digitizerNETBOX/generatorNETBOX that is installed in a Rack of multiple digitizerNETBOX or generatorNETBOX devices. Writing a 0 to this register will stop the flashing again.
SPC_NETBOX_TEMPERATURE	400010	read	Read out the temperature inside the digitizerNETBOX/generatorNETBOX (same as displayed in the webinterface status information) in Kelvin.
SPC_NETBOX_SHUTDOWN	400011	write	Remotely shut down the digitizerNETBOX/generatorNETBOX. Value must be set to 0.
SPC_NETBOX_RESTART	400012	write	Remotely restart the digitizerNETBOX/generatorNETBOX. Value must be set to 0.
SPC_NETBOX_FANSPEED0	400013	read	DN2: Read out the current cooling fan speed of main fan (right side) DN6: Read out the current cooling fan speed of the power supply fan
SPC_NETBOX_FANSPEED1	400014	read	DN2: not used DN6: Read out the current cooling fan speed of the outer auxiliary fan

## Analog Inputs

### Channel Selection

One key setting that influences all other possible settings is the channel enable register. A unique feature of the Spectrum cards is the possibility to program the number of channels you want to use. All on-board memory can then be used by these activated channels.

This description shows you the channel enable register for the complete card family. However, your specific board may have less channels depending on the card type that you have purchased and therefore does not allow you to set the maximum number of channels shown here.

Register	Value	Direction	Description
SPC_CHENABLE	11000	read/write	Sets the channel enable information for the next board run.
	hex.	dec.	
CHANNEL0	1h	1	Activates channel 0
CHANNEL1	2h	2	Activates channel 1
CHANNEL2	4h	4	Activates channel 2
CHANNEL3	8h	8	Activates channel 3
CHANNEL4	10h	16	Activates channel 4
CHANNEL5	20h	32	Activates channel 5
CHANNEL6	40h	64	Activates channel 6
CHANNEL7	80h	128	Activates channel 7

The channel enable register is set as a bitmap. That means that one bit of the value corresponds to one channel to be activated. To activate more than one channel the values have to be combined by a bitwise OR.

### Single-ended inputs

#### 1 single-ended channel enabled

Any one of the installed channels can be enabled. The following table shows example settings for the channel enable register:

Channels to activate								Installed channels on card				Value to program		
Ch0	Ch1	Ch2	Ch3	Ch4	Ch5	Ch6	Ch7	1	2	4	8	Constant from regs.h	hex	decimal
X			X					X	X	X	X	CHANNEL0	1h	1
						X		n.a.	n.a.	X	X	CHANNEL3	8h	8
							X	n.a.	n.a.	n.a.	X	CHANNEL6	40h	64

#### 2 single-ended channels enabled

Any two of the installed channels can be enabled. The following table shows three example settings for the channel enable register:

Channels to activate								Installed channels on card				Value to program		
Ch0	Ch1	Ch2	Ch3	Ch4	Ch5	Ch6	Ch7	1	2	4	8	Constant from regs.h	hex	decimal
X	X							n.a.	X	X	X	CHANNEL0   CHANNEL1	3h	3
X		X						n.a.	n.a.	X	X	CHANNEL1   CHANNEL3	Ah	10
	X			X			X	n.a.	n.a.	n.a.	X	CHANNEL3   CHANNEL7	88h	136

#### 4 single-ended channels enabled

Any four of the installed channels can be enabled. The following table shows three example settings for the channel enable register:

Channels to activate								Installed channels on card				Value to program		
Ch0	Ch1	Ch2	Ch3	Ch4	Ch5	Ch6	Ch7	1	2	4	8	Constant from regs.h	hex	decimal
X	X	X	X					n.a.	n.a.	X	X	CHANNEL0   CHANNEL1   CHANNEL2   CHANNEL3	Fh	15
X		X	X	X				n.a.	n.a.	n.a.	X	CHANNEL1   CHANNEL3   CHANNEL4   CHANNEL7	9Ah	154
	X	X		X	X	X	X	n.a.	n.a.	n.a.	X	CHANNEL2   CHANNEL3   CHANNEL6   CHANNEL7	CCh	204

#### 8 single-ended channels enabled

Channels to activate								Installed channels on card				Value to program		
Ch0	Ch1	Ch2	Ch3	Ch4	Ch5	Ch6	Ch7	1	2	4	8	Constant from regs.h	hex	decimal
X	X	X	X	X	X	X	X	n.a.	n.a.	n.a.	X	CHANNEL0   CHANNEL1   CHANNEL2   CHANNEL3   CHANNEL4   CHANNEL5   CHANNEL6   CHANNEL7	FFh	255

**Any channel activation mask that tries to enables a number of channels other than one, two, four or eight channels is not valid. If programming an other channel activation, the driver will return with an error code `ERR_VALUE`.**



Example showing how to activate 4 single-ended channels:

```
spcm_dwSetParam_i32 (hDrv, SPC_CHENABLE, CHANNEL0 | CHANNEL1 | CHANNEL2 | CHANNEL3);
```

To help user programs it is also possible to read out the number of activated channels that correspond to the currently programmed bitmap.

Register	Value	Direction	Description
SPC_CHCOUNT	11001	read	Reads back the number of currently activated channels.

Reading out the channel enable information can be done directly after setting it or later like this:

```
spcm_dwSetParam_i32 (hDrv, SPC_CHENABLE, CHANNEL0 | CHANNEL1);
spcm_dwGetParam_i32 (hDrv, SPC_CHENABLE, &lActivatedChannels);
spcm_dwGetParam_i32 (hDrv, SPC_CHCOUNT, &lChCount);

printf ("Activated channels bitmask is: 0x%08x\n", lActivatedChannels);
printf ("Number of activated channels with this bitmask: %d\n", lChCount);
```

Assuming that the two channels are available on your card the program will have the following output:

```
Activated channels bitmask is: 0x00000003
Number of activated channels with this bitmask: 2
```

## Differential Inputs

In addition to the normal single-ended inputs this board is also equipped with true differential inputs.

On card models, that offer more single-ended channels than differential channels (M2p.59x2 and M2p.59x3) the card will, when using channels in differential mode, use two adjacent single-ended inputs and combine them to one true-differential channel. The channel with the even number (Ch0, Ch2, Ch4 or Ch6) will be the input for the positive phase (+) and the channel with the next higher odd number (Ch1, Ch3, Ch5 or Ch7) will be used for the negative phase (-).

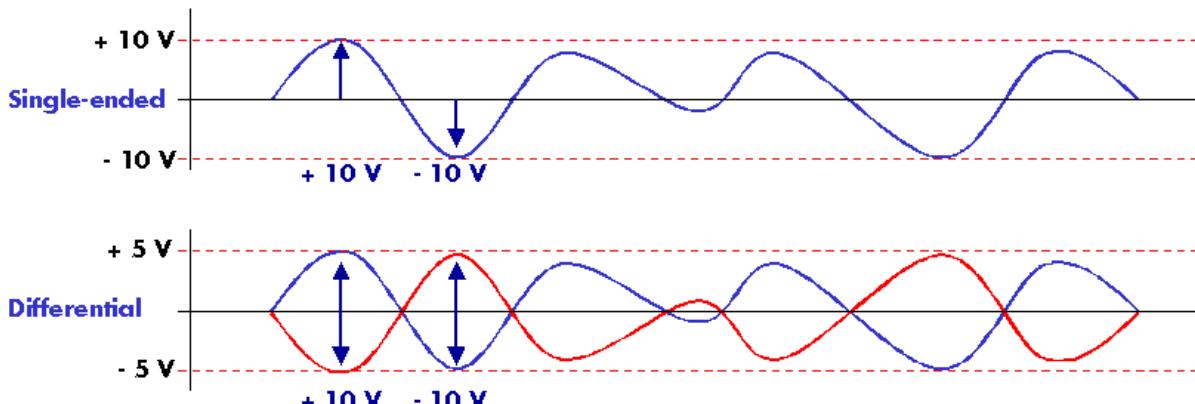
On card models that offer the same number of differential as single-ended channels (M2p.59x0, M2p.59x2 and M2p.59x6) each channel has two dedicated inputs one for the positive phase (+) and one for the negative phase (-) of the true-differential channel.

When the inputs are used in differential mode the A/D converter measures the difference between the two lines with regards to system ground. The connector for the positive signal (channel x) is used in single-ended and in differential mode, while the connector for the negative input (channel (x+1)) is used in differential mode for the negative phase.



**Even in differential mode the inputs relate to system ground. The inputs are not isolated, so no connection to levels above the maximum input voltage is allowed !**

The following drawing shows the difference (also in the meaning of the maximum amplitude) between single-ended and differential input:



**As you can see in the block diagram mentioned earlier in this manual, the internal conversion from differential to single ended is done after the offset correction stage. As a result all the offset settings mentioned before can only be used with single-ended inputs.**

You can change between single-ended and differential mode separately for every even input channel by setting the relating register shown in one of the following tables:

**M2p.59x2, M2p.59x3:**

Register	Value	Direction	Description
SPC_DIFF0	30040	r/w	Set channel 0 to differential mode using channel 1 as negative input. The default mode is single-ended.
SPC_DIFF2	30240	r/w	Set channel 2 to differential mode using channel 3 as negative input. The default mode is single-ended.
SPC_DIFF4	30440	r/w	Set channel 4 to differential mode using channel 5 as negative input. The default mode is single-ended.
SPC_DIFF6	30640	r/w	Set channel 6 to differential mode using channel 7 as negative input. The default mode is single-ended.

**M2p.59x0, M2p.59x1, M2p.59x6:**

Register	Value	Direction	Description
SPC_DIFF0	30040	r/w	Set channel 0 to differential mode. The default mode is single-ended.
SPC_DIFF1	30140	r/w	Set channel 1 to differential mode. The default mode is single-ended.
SPC_DIFF2	30240	r/w	Set channel 2 to differential mode. The default mode is single-ended.
SPC_DIFF3	30340	r/w	Set channel 3 to differential mode. The default mode is single-ended.

**1 differential channel enabled**

The following table shows all allowed settings for the channel enable register when only activating one channel

Channels to activate								Card Types				Value to program		SPC_DIFFx register to be enabled	
0	1	2	3	4	5	6	7	59x0	59x1	59x6	59x2	59x3	Constant from reg.h	hex	decimal
X	X	X	X	X	X	X	X	X	X	X	X	X	CHANNEL0   CHANNEL1	01h	1
								n.a.	X	X	n.a.	n.a.	CHANNEL1	02h	2
								n.a.	n.a.	X	X	X	CHANNEL2	04h	4
								n.a.	n.a.	X	n.a.	n.a.	CHANNEL3	08h	8
								n.a.	n.a.	n.a.	n.a.	X	CHANNEL4	10h	16
								n.a.	n.a.	n.a.	n.a.	n.a.	CHANNEL5	20h	32
								n.a.	n.a.	n.a.	n.a.	X	CHANNEL6	40h	64
								n.a.	n.a.	n.a.	n.a.	n.a.	CHANNEL7	80h	128

**2 differential Channels enabled**

The following table show all allowed settings for the channel enable register when activating two channels

Channels to activate								Card Types				Value to program		SPC_DIFFx register to be enabled	
0	1	2	3	4	5	6	7	59x0	59x1	59x6	59x2	59x3	Constant from reg.h	hex	decimal
X	X	X	X	X	X	X	X	n.a.	X	X	n.a.	n.a.	CHANNEL0   CHANNEL1	03h	3
X	X	X	X	X	X	X	X	n.a.	n.a.	X	X	X	CHANNEL0   CHANNEL2	05h	5
X	X	X	X	X	X	X	X	n.a.	n.a.	X	n.a.	n.a.	CHANNEL0   CHANNEL3	09h	9
X	X	X	X	X	X	X	X	n.a.	n.a.	n.a.	n.a.	X	CHANNEL0   CHANNEL4	11h	17
X	X	X	X	X	X	X	X	n.a.	n.a.	n.a.	n.a.	X	CHANNEL0   CHANNEL6	41h	65
X	X	X	X	X	X	X	X	n.a.	n.a.	n.a.	n.a.	n.a.	CHANNEL1   CHANNEL2	06h	6
X	X	X	X	X	X	X	X	n.a.	n.a.	n.a.	n.a.	n.a.	CHANNEL1   CHANNEL3	0Ah	10
X	X	X	X	X	X	X	X	n.a.	n.a.	n.a.	n.a.	n.a.	CHANNEL2   CHANNEL3	0Ch	12
X	X	X	X	X	X	X	X	n.a.	n.a.	n.a.	n.a.	X	CHANNEL2   CHANNEL4	14h	20
X	X	X	X	X	X	X	X	n.a.	n.a.	n.a.	n.a.	X	CHANNEL2   CHANNEL6	44h	68
								n.a.	n.a.	n.a.	n.a.	X	CHANNEL4   CHANNEL6	50h	80

**4 differential channels enabled**

The following table show all allowed settings for the channel enable register when activating four channels

Channels to activate								Card Types				Value to program		SPC_DIFFx register to be enabled	
0	1	2	3	4	5	6	7	59x0	59x1	59x6	59x2	59x3	Constant from reg.h	hex	decimal
X	X	X	X	X	X	X	X	n.a.	n.a.	X	n.a.	n.a.	CHANNEL0   CHANNEL1   CHANNEL2   CHANNEL3	0Fh	15
X	X	X	X	X	X	X	X	n.a.	n.a.	n.a.	X	n.a.	CHANNEL0   CHANNEL2   CHANNEL4   CHANNEL6	55h	85

**Mixed single-ended and differential inputs**

It is also possible to have a mixed setup of differential and single-ended channels. If in any of the above shown differential channel combination one or multiple channels should be single-ended instead, simply do not set the related SPC\_DIFFx register.

**Important note on channel selection**

**As some of the manuals passages are used in more than one hardware manual most of the registers and channel settings throughout this handbook are described for the maximum number of possible channels that are available on one card of the current series. There can be less channels on your actual type of board or bus-system. Please refer to the technical data section to get the actual number of available channels.**



## Setting up the inputs

### Input ranges

This analog acquisition board uses separate input amplifiers and converters on each channel. This gives you the possibility to set up the desired and concerning your application best suiting input range also separately for each channel. The input ranges can easily be set by the corresponding input registers. The table below shows the available input registers and possible standard ranges for your type of board. As there are also modified version available with different input ranges it is recommended to read out the currently available input ranges as shown later in this chapter.

Register	Value	Direction	Description
SPC_AMP0	30010	r/w	Defines the input range of channel0.
SPC_AMP1	30110	r/w	Defines the input range of channel1.
SPC_AMP2	30210	r/w	Defines the input range of channel2.
SPC_AMP3	30310	r/w	Defines the input range of channel3.
SPC_AMP4	30410	r/w	Defines the input range of channel4.
SPC_AMP5	30510	r/w	Defines the input range of channel5.
SPC_AMP6	30610	r/w	Defines the input range of channel6.
SPC_AMP7	30710	r/w	Defines the input range of channel7.
	200		± 200 mV calibrated input range for the appropriate channel.
	500		± 500 mV calibrated input range for the appropriate channel.
	1000		± 1 V calibrated input range for the appropriate channel.
	2000		± 2 V calibrated input range for the appropriate channel.
	5000		± 5 V calibrated input range for the appropriate channel.
	10000		± 10 V calibrated input range for the appropriate channel.

Universal software that handles different card types can read out how many different input ranges are available on the actual board for each channel. This information can be obtained by using the read-only register shown in the table below.

Register	Value	Direction	Description
SPC_READIRCOUNT	3000	read	Informs about the number of the board's calibrated input ranges.

Additionally one can read out the minimum and the maximum value of each input range as shown in the table below. The number of input ranges is read out with the above shown register.

Register	Value	Direction	Description
SPC_READRANGEMIN0	4000	read	Gives back the minimum value of input range 0 in mV.
SPC_READRANGEMIN1	4001	read	Gives back the minimum value of input range 1 in mV.
SPC_READRANGEMIN2	4002	read	Gives back the minimum value of input range 2 in mV.
...	...	read	...
SPC_READRANGEMAX0	4100	read	Gives back the maximum value of input range 0 in mV.
SPC_READRANGEMAX1	4101	read	Gives back the maximum value of input range 1 in mV.
SPC_READRANGEMAX2	4102	read	Gives back the maximum value of input range 2 in mV.
...	...	...	...

The following example reads out the number of available input ranges and reads and prints the minimum and maximum value of all input ranges.

```

spcm_dwGetParam_i32 (hDrv, SPC_READIRCOUNT, &lNumberOfRanges);
for (i = 0; i < lNumberOfRanges; i++)
{
    spcm_dwGetParam_i32 (hDrv, SPC_READRANGEMIN0 + i, &lMinimumInputRange);
    spcm_dwGetParam_i32 (hDrv, SPC_READRANGEMAX0 + i, &lMaximumInputRange);
    printf ("Range %d: %d mV to %d mV\n", i, lMinimumInputRange, lMaximumInputRange);
}

```

## Input offset

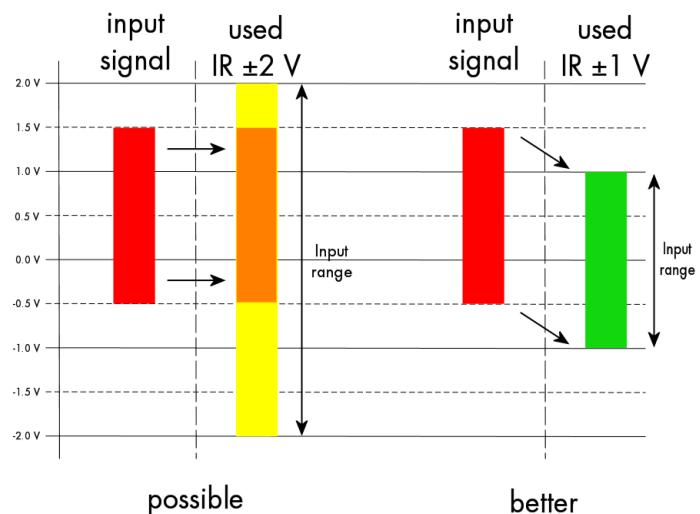
In most cases the external signals will not be symmetrically related to ground. If you want to acquire such asymmetrical signals, it is possible to use the smallest input range that matches the biggest absolute signal amplitude without exceeding the range.

The figure at the right shows this possibility. But in this example you would leave half of the possible resolution unused.

It is much more efficient if you shift the signal on-board to be as symmetrical as possible and to acquire it within the best possible range.

This results in a much better use of the converters resolution.

On this acquisition boards from Spectrum you have the possibility to adjust the input offset separately for each channel.



The example in the right figure shows signals with a range of  $\pm 1.0$  V that have offsets up to  $\pm 1.0$  V. So related to the desired input range these signals have offsets of  $\pm 100\%$ .

For compensating such offsets you can use the offset register for each channel separately. If you want to compensate the  $+100\%$  offset of the outer left signal, you would have to set the offset to  $-100\%$  to compensate it.

As the offset levels are relatively to the related input range, you have to calculate and set your offset again when changing the input's range.

The table below shows the offset registers and the possible offset ranges for your specific type of board.



Register	Value	Direction	Description	Offset range
SPC_OFFS0	30000	r/w	Defines the input's offset and therefore shifts the input of channel0.	$\pm 100\%$ in steps of 1 %
SPC_OFFS1	30100	r/w	Defines the input's offset and therefore shifts the input of channel1.	$\pm 100\%$ in steps of 1 %
SPC_OFFS2	30200	r/w	Defines the input's offset and therefore shifts the input of channel2.	$\pm 100\%$ in steps of 1 %
SPC_OFFS3	30300	r/w	Defines the input's offset and therefore shifts the input of channel3.	$\pm 100\%$ in steps of 1 %
SPC_OFFS4	30400	r/w	Defines the input's offset and therefore shifts the input of channel4.	$\pm 100\%$ in steps of 1 %
SPC_OFFS5	30500	r/w	Defines the input's offset and therefore shifts the input of channel5.	$\pm 100\%$ in steps of 1 %
SPC_OFFS6	30600	r/w	Defines the input's offset and therefore shifts the input of channel6.	$\pm 100\%$ in steps of 1 %
SPC_OFFS7	30700	r/w	Defines the input's offset and therefore shifts the input of channel7.	$\pm 100\%$ in steps of 1 %

When writing a program that should run with different board families it is useful to just read-out the possible offset than can be programmed. You can use the following read only register to get the possible programmable offset range in percent

Register	Value	Direction	Description
SPC_READOFFSMIN0	4200	read	Minimum programmable offset for input range 0 in percent
SPC_READOFFSMAX0	4100	read	Maximum programmable offset for input range 0 in percent
SPC_READOFFSMIN1	4201	read	Minimum programmable offset for input range 1 in percent
SPC_READOFFSMAX1	4101	read	Maximum programmable offset for input range 1 in percent
..	...	...	...

To give you an example how the registers of the input range and the input offset are to be used, the following example shows a setup to match all of the four signals in the second input offset figure to match the desired input range. Therefore every one of the four channels is set to the input range of  $\pm 1.0$  V. After that the four offset settings are set exactly as the offsets to be compensated, but with the opposite sign. The result is, that all four channels perfectly match the chosen input range.

Please note that this is a general example and the number of input channels may not match the number of channels of your card.

```
spcm_dwSetParam_i32 (hDrv, SPC_AMP0 , 1000); // Set up channel0 to the range of ± 1.0 V
spcm_dwSetParam_i32 (hDrv, SPC_AMP1 , 1000); // Set up channel1 to the range of ± 1.0 V
spcm_dwSetParam_i32 (hDrv, SPC_AMP2 , 1000); // Set up channel2 to the range of ± 1.0 V
spcm_dwSetParam_i32 (hDrv, SPC_AMP3 , 1000); // Set up channel3 to the range of ± 1.0 V

spcm_dwSetParam_i32 (hDrv, SPC_OFFSET0, -100); // Set the input offset to get the signal symmetrically to 0.0 V
spcm_dwSetParam_i32 (hDrv, SPC_OFFSET1, -50);
spcm_dwSetParam_i32 (hDrv, SPC_OFFSET2, 50);
spcm_dwSetParam_i32 (hDrv, SPC_OFFSET3, 100);
```

## **Input termination**

All inputs of Spectrum's analog boards can be terminated separately with 50 Ohm by software programming. If you do so, please make sure that your signal source is able to deliver the higher output currents. If no termination is used, the inputs have an impedance of 1 Mega-ohm. The following table shows the corresponding register to set the input termination.

Register	Value	Direction	Description
SPC_50OHM0	30030	r/w	A „1“ sets the 50 ohm termination for channel0. A „0“ sets the termination to 1 MΩ.
SPC_50OHM1	30130	r/w	A „1“ sets the 50 ohm termination for channel1. A „0“ sets the termination to 1 MΩ.
SPC_50OHM2	30230	r/w	A „1“ sets the 50 ohm termination for channel2. A „0“ sets the termination to 1 MΩ.
SPC_50OHM3	30330	r/w	A „1“ sets the 50 ohm termination for channel3. A „0“ sets the termination to 1 MΩ.
SPC_50OHM4	30430	r/w	A „1“ sets the 50 ohm termination for channel4. A „0“ sets the termination to 1 MΩ.
SPC_50OHM5	30530	r/w	A „1“ sets the 50 ohm termination for channel5. A „0“ sets the termination to 1 MΩ.
SPC_50OHM6	30630	r/w	A „1“ sets the 50 ohm termination for channel6. A „0“ sets the termination to 1 MΩ.
SPC_50OHM7	30730	r/w	A „1“ sets the 50 ohm termination for channel7. A „0“ sets the termination to 1 MΩ.

## **M2p.591x Digital bandwidth filter**

The cards of the M2p.591x series provide a digital (boxcar) bandwidth filter for enhancing the signal-to-noise ratio, which is enabled by default. This reduces the available bandwidth digitally below the value otherwise defined by the anti-aliasing filter. In situations where the full nyquist bandwidth is required or undersampling of the inputs is required (for the second nyquist zone), this feature can be disabled manually:

Register	Value	Direction	Description
SPC_DIGITALBWFILTER	100100	r/w	A „1“ enables the digital BW filter, a „0“ disables it. As default the filter is active.

 **Because the digital bandwidth filter of the M2p.591x cards does require the generation of a higher internal ADC sample rate, it is not available when using direct external clocking (clock mode SPC\_CM\_EXTERNAL). Please see clock mode chapter for details.**

## **Automatic on-board calibration of the offset and gain settings**

All of the channels are calibrated in factory before the board is shipped. These values are stored in the on-board EEPROM under the default settings. If you have asymmetrical signals, you can adjust the offset easily with the corresponding registers of the inputs as shown before.

To start the automatic offset adjustment, simply write the register, mentioned in the following table.

 **Before you start an automatic offset adjustment make sure, that no signal is connected to any input. Leave all the input connectors open and then start the adjustment. All the internal settings of the driver are changed, while the automatic offset compensation is in progress.**

Register	Value	Direction	Description
SPC_ADJ_AUTOADJ	50020	write	Performs the automatic offset compensation in the driver either for all input ranges or only the actual.
ADJ_ALL	0		Automatic offset adjustment for all input ranges.

As all settings are temporarily stored in the driver, the automatic adjustment will only affect these values. After exiting your program, all calibration information will be lost. To give you a possibility to save your own settings, most Spectrum card have at least one set of user settings that can be saved within the on-board EEPROM. The default settings of the offset and gain values are then read-only and cannot be written to the EEPROM by the user. If the card has no user settings the default settings may be overwritten.

You can easily either save adjustment settings to the EEPROM with SPC\_ADJ\_SAVE or recall them with SPC\_ADJ\_LOAD. These two registers are shown in the table below. The values for these EEPROM access registers are the sets that can be stored within the EEPROM. The amount

of sets available for storing user offset settings depends on the type of board you use. The table below shows all the EEPROM sets, that are available for your board.

Register	Value	Direction	Description
SPC_ADJ_LOAD	50000	write	Loads the specified set of settings from the EEPROM. The default settings are automatically loaded, when the driver is started.
		read	Reads out, what kind of settings have been loaded last.
SPC_ADJ_SAVE	50010	write	Stores the current settings to the specified set in the EEPROM.
		read	Reads out, what kind of settings have been saved last.
ADJ_DEFAULT	0		Default settings, no user settings available

If you want to make an offset and gain adjustment on all the channels and store the data to the ADJ\_DEFAULT set of the EEPROM you can do this the way, the following example shows.

```
spcm_dwSetParam_i32 (hDrv, SPC_ADJ_AUTOADJ,      ADJ_ALL ); // Activate offset/gain adjustment on all channels
spcm_dwSetParam_i32 (hDrv, SPC_ADJ_SAVE ,        ADJ_DEFAULT); // and store values to DEFAULT set in the EEPROM
```

## Read out of input features

The analog inputs of the different cards do have different features implemented, that can be read out to make the software more general. If you only operate one single card type in your software it is not necessary to read out these features.

Please note that the following table shows all input features settings that are available throughout all Spectrum acquisition cards. Some of these features are not installed on your specific hardware.

Register	Value	Direction	Description
SPC_READAIFEATURS	3101	read	Returns a bit map with the available features of the analog input path. The possible return values are listed below.
SPCM_AI_TERM	00000001h		Programmable input termination available, otherwise the termination is fixed in value.
SPCM_AI_SE	00000002h		Input is single-ended. If available together with SPC_AI_DIFF or SPCM_AI_DIFFMUX: input type is software selectable.
SPCM_AI_DIFF	00000004h		Input is differential. If available together with SPC_AI_SE: input type is software selectable and switching from single-ended to differential does not reduce the number of active channels by combining two single-ended channels.
SPCM_AI_OFFSETPERCENT	00000008h		Input offset programmable in per cent of input range
SPCM_AI_OFFSETMV	00000010h		Input offset programmable in mV
SPCM_AI_OVERRANGEDETECT	00000020h		Programmable overrange detection available
SPCM_AI_DCCOUPLING	00000040h		Input is DC coupled. If available together with AC coupling: coupling is software selectable
SPCM_AI_ACACOUPLING	00000080h		Input is AC coupled. If available together with DC coupling: coupling is software selectable
SPCM_AI_LOWPASS	00000100h		Input has a selectable low pass filter (bandwidth limit)
SPCM_AI_DIFFMUX	00000400h		Input is differential. If available together with SPC_AI_SE: input type is software selectable and switching from single-ended to differential does not reduce the number of active channels due to combining two single-ended channels.
SPCM_AI_AUTOCALOFFS	00001000h		Input offset can be auto calibrated on the card
SPCM_AI_AUTOCALGAIN	00002000h		Input gain can be auto calibrated on the card
SPCM_AI_AUTOCALOFFSNOIN	00004000h		Input offset can auto calibrated on the card if inputs are left open
SPCM_AI_HIGHIMP	00008000h		Input can be high-impedance. When also SPCM_AI_LOWIMP is set, the impedance is software programmable.
SPCM_AI_LOWIMP	00010000h		Input can be low-impedance. When also SPCM_AI_HIGHIMP is set, the impedance is software programmable.
SPCM_AI_INDIVPULSEWIDTH	00100000h		Trigger pulsewidth is individually per channel programmable

## Acquisition modes

Your card is able to run in different modes. Depending on the selected mode there are different registers that each define an aspect of this mode. The single modes are explained in this chapter. Any further modes that are only available if an option is installed on the card is documented in a later chapter.

### Overview

This chapter gives you a general overview on the related registers for the different modes. The use of these registers throughout the different modes is described in the following chapters.

### Setup of the mode

The mode register is organized as a bitmap. Each mode corresponds to one bit of this bitmap. When defining the mode to use, please be sure just to set one of the bits. All other settings will return an error code.

The main difference between all standard and all FIFO modes is that the standard modes are limited to on-board memory and therefore can run with full sampling rate. The FIFO modes are designed to transfer data continuously over the bus to PC memory or to hard disk and can therefore run much longer. The FIFO modes are limited by the maximum bus transfer speed the PC can use. The FIFO mode uses the complete installed on-board memory as a FIFO buffer.

However as you'll see throughout the detailed documentation of the modes the standard and the FIFO mode are similar in programming and behavior and there are only a very few differences between them.

Register	Value	Direction	Description
SPC_CARDMODE	9500	read/write	Defines the used operating mode, a read command will return the currently used mode.
SPC_AVAILCARDMODES	9501	read	Returns a bitmap with all available modes on your card. The modes are listed below.

### Acquisition modes

Mode	Value	Available on	Description
SPC_REC_STD_SINGLE	1h	all cards	Data acquisition to on-board memory for one single trigger event.
SPC_REC_STD_MULTI	2h	all cards	Data acquisition to on-board memory for multiple trigger events. Each recorded segment has the same size. This mode is described in greater detail in a special chapter about the Multiple Recording option.
SPC_REC_STD_GATE	4h	all cards	Data acquisition to on-board memory using an external Gate signal. Acquisition is only done as long as the gate signal has a programmed level. The mode is described in greater detail in a special chapter about the Gated Sampling option.
SPC_REC_STD_ABA	8h	digitizer only	Data acquisition to on-board memory for multiple trigger events. While the multiple trigger events are stored with programmed sampling rate the inputs are sampled continuously with a slower sampling speed. The mode is described in a special chapter about ABA mode option.
SPC_REC_STD_SEGSTATS	10000h	M4i/M4x.2xxx M4i/M4x.44xx DN2/DN6.2xx DN2/DN6.44x digitizer only	Data acquisition to on-board memory for multiple trigger events, using Block/Segment Statistic Module (FPGA firmware Option).
SPC_REC_STD_AVERAGE	20000h	M4i/M4x.2xxx M4i/M4x.44xx DN2/DN6.2xx DN2/DN6.44x digitizer only	Data acquisition to on-board memory for multiple trigger events, using Block Average Module (FPGA firmware Option).
SPC_REC_STD_BOXCAR	800000h	M4i/M4x.44xx DN2/DN6.44x digitizer only	Enables Boxcar Averaging for standard acquisition. Requires digitizer module with firmware version V29 or newer.
SPC_REC_FIFO_SINGLE	10h	all cards	Continuous data acquisition for one single trigger event. The on-board memory is used completely as FIFO buffer.
SPC_REC_FIFO_MULTI	20h	all cards	Continuous data acquisition for multiple trigger events.
SPC_REC_FIFO_GATE	40h	all cards	Continuous data acquisition using an external gate signal.
SPC_REC_FIFO_ABA	80h	digitizer only	Continuous data acquisition for multiple trigger events together with continuous data acquisition with a slower sampling clock.
SPC_REC_FIFO_SEGSTATS	100000h	M4i/M4x.2xxx M4i/M4x.44xx DN2/DN6.2xx DN2/DN6.44x digitizer only	Enables Block/Segment Statistic for FIFO acquisition (FPGA firmware Option).
SPC_REC_FIFO_AVERAGE	200000h	M4i/M4x.2xxx M4i/M4x.44xx DN2/DN6.2xx DN2/DN6.44x digitizer only	Enables Block Averaging for FIFO acquisition (FPGA firmware Option).
SPC_REC_FIFO_BOXCAR	1000000h	M4i/M4x.44xx DN2/DN6.44x digitizer only	Enables Boxcar Averaging for FIFO acquisition. Requires digitizer module firmware version V29 or newer.
SPC_REC_FIFO_SINGLE_MONITOR	2000000h	digitizer only	Combination of SPC_REC_FIFO_SINGLE mode with additional slower sampling clock data stream for monitoring purposes (same as A-data of SPC_REC_FIFO_ABA mode).

## Commands

The data acquisition/data replay is controlled by the command register. The command register controls the state of the card in general and also the state of the different data transfers. Data transfers are explained in an extra chapter later on.

The commands are split up into two types of commands: execution commands that fulfill a job and wait commands that will wait for the occurrence of an interrupt. Again the commands register is organized as a bitmap allowing you to set several commands together with one call. As not all of the command combinations make sense (like the combination of reset and start at the same time) the driver will check the given command and return an error code ERR\_SEQUENCE if one of the given commands is not allowed in the current state.

Register	Value	Direction	Description
SPC_M2CMD	100	write only	Executes a command for the card or data transfer.

### Card execution commands

M2CMD_CARD_RESET	1h	Performs a hard and software reset of the card as explained further above.
M2CMD_CARD_WRITESETUP	2h	Writes the current setup to the card without starting the hardware. This command may be useful if changing some internal settings like clock frequency and enabling outputs.
M2CMD_CARD_START	4h	Starts the card with all selected settings. This command automatically writes all settings to the card if any of the settings has been changed since the last one was written. After card has been started, only some of the settings might be changed while the card is running, such as e.g. output level and offset for D/A replay cards.
M2CMD_CARD_ENABLETRIGGER	8h	The trigger detection is enabled. This command can be either sent together with the start command to enable trigger immediately or in a second call after some external hardware has been started.
M2CMD_CARD_FORCE_TRIGGER	10h	This command forces a trigger even if none has been detected so far. Sending this command together with the start command is similar to using the software trigger.
M2CMD_CARD_DISABLETRIGGER	20h	The trigger detection is disabled. All further trigger events are ignored until the trigger detection is again enabled. When starting the card the trigger detection is started disabled.
M2CMD_CARD_STOP	40h	Stops the current run of the card. If the card is not running this command has no effect.

### Card wait commands

These commands do not return until either the defined state has been reached which is signaled by an interrupt from the card or the timeout counter has expired. If the state has been reached the command returns with an ERR\_OK. If a timeout occurs the command returns with ERR\_TIMEOUT. If the card has been stopped from a second thread with a stop or reset command, the wait function returns with ERR\_ABORT.

M2CMD_CARD_WAITPREFULL	1000h	Acquisition modes only: the command waits until the pretrigger area has once been filled with data. After pretrigger area has been filled the internal trigger engine starts to look for trigger events if the trigger detection has been enabled.
M2CMD_CARD_WAITTRIGGER	2000h	Waits until the first trigger event has been detected by the card. If using a mode with multiple trigger events like Multiple Recording or Gated Sampling there only the first trigger detection will generate an interrupt for this wait command.
M2CMD_CARD_WAITREADY	4000h	Waits until the card has completed the current run. In an acquisition mode receiving this command means that all data has been acquired. In a generation mode receiving this command means that the output has stopped.

### Wait command timeout

If the state for which one of the wait commands is waiting isn't reached any of the wait commands will either wait forever if no timeout is defined or it will return automatically with an ERR\_TIMEOUT if the specified timeout has expired.

Register	Value	Direction	Description
SPC_TIMEOUT	295130	read/write	Defines the timeout for any following wait command in a millisecond resolution. Writing a zero to this register disables the timeout.

As a default the timeout is disabled. After defining a timeout this is valid for all following wait commands until the timeout is disabled again by writing a zero to this register.

A timeout occurring should not be considered as an error. It did not change anything on the board status. The board is still running and will complete normally. You may use the timeout to abort the run after a certain time if no trigger has occurred. In that case a stop command is necessary after receiving the timeout. It is also possible to use the timeout to update the user interface frequently and simply call the wait function afterwards again.

Example for card control:

```

// card is started and trigger detection is enabled immediately
spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_CARD_START | M2CMD_CARD_ENABLETRIGGER);

// we wait a maximum of 1 second for a trigger detection. In case of timeout we force the trigger
spcm_dwSetParam_i32 (hDrv, SPC_TIMEOUT, 1000);
if (spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_CARD_WAITTRIGGER) == ERR_TIMEOUT)
{
    printf ("No trigger detected so far, we force a trigger now!\n");
    spcm_dwSetParam (hDrv, SPC_M2CMD, M2CMD_CARD_FORCE_TRIGGER);
}

// we disable the timeout and wait for the end of the run
spcm_dwSetParam_i32 (hDrv, SPC_TIMEOUT, 0);
spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_CARD_WAITREADY);
printf ("Card has stopped now!\n");

```

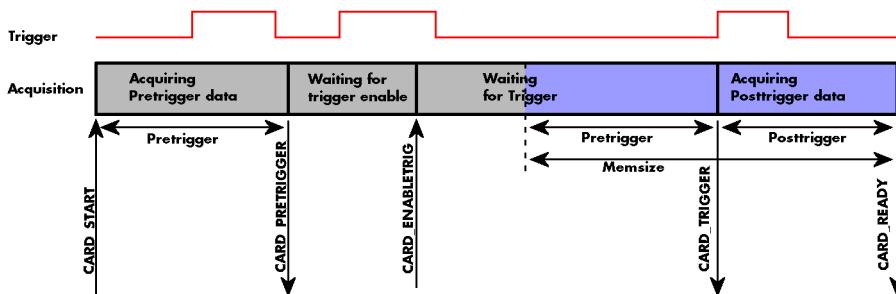
## Card Status

In addition to the wait for an interrupt mechanism or completely instead of it one may also read out the current card status by reading the SPC\_M2STATUS register. The status register is organized as a bitmap, so that multiple bits can be set, showing the status of the card and also of the different data transfers.

Register	Value	Direction	Description
SPC_M2STATUS	110	read only	Reads out the current status information
M2STAT_CARD_PREtrigger	1h		Acquisition modes only: the first pretrigger area has been filled. In Multi/ABA/Gated acquisition this status is set only for the first segment and will be cleared at the end of the acquisition.
M2STAT_CARD_TRIGGER	2h		The first trigger has been detected.
M2STAT_CARD_READY	4h		The card has finished its run and is ready.
M2STAT_CARD_SEGMENT_PRETRG	8h		This flag will be set for each completed pretrigger area including the first one of a Single acquisition. Additionally for a Multi/ABA/Gated acquisition of M4i/M4x/M2p only, this flag will be set when the pretrigger area of a segment has been filled and will be cleared in between segments.

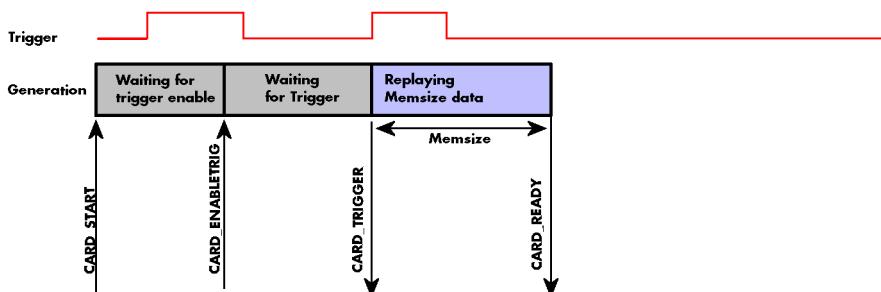
## Acquisition cards status overview

The following drawing gives you an overview of the card commands and card status information. After start of card with M2CMD\_CARD\_START the card is acquiring pretrigger data until one time complete pretrigger data has been acquired. Then the status bit M2STAT\_CARD\_PREtrigger is set. Either the trigger has been enabled together with the start command or the card now waits for trigger enable command M2CMD\_CARD\_ENABLETRIGGER. After receiving this command the trigger engine is enabled and card checks for a trigger event. As soon as the trigger event is received the status bit M2STAT\_CARD\_TRIGGER is set and the card acquires the programmed posttrigger data. After all post trigger data has been acquired the status bit M2STAT\_CARD\_READY is set and data can be read out:



## Generation card status overview

This drawing gives an overview of the card commands and status information for a simple generation mode. After start of card with the M2CMD\_CARD\_START the card is armed and waiting. Either the trigger has been enabled together with the start command or the card now waits for trigger enable command M2CMD\_CARD\_ENABLETRIGGER. After receiving this command the trigger engine is enabled and card checks for a trigger event. As soon as the trigger event is received the status bit M2STAT\_CARD\_TRIGGER is set and the card starts with the data replay. After replay has been finished - depending on the programmed mode - the status bit M2STAT\_CARD\_READY is set and the card stops.



## Data Transfer

Data transfer consists of two parts: the buffer definition and the commands/status information that controls the transfer itself. Data transfer shares the command and status register with the card control commands and status information. In general the following details on the data transfer are valid for any data transfer in any direction:

- The memory size register (SPC\_MEMSIZE) must be programmed before starting the data transfer.
- When the hardware buffer is adjusted from its default (see „Output latency“ section later in this manual), this must be done before defining the transfer buffers in the next step via the spcm\_dwDefTransfer function.
- Before starting a data transfer the buffer must be defined using the spcm\_dwDefTransfer function.
- Each defined buffer is only used once. After transfer has ended the buffer is automatically invalidated.
- If a buffer has to be deleted although the data transfer is in progress or the buffer has at least been defined it is necessary to call the spcm\_dwInvalidateBuf function.

### **Definition of the transfer buffer**

Before any data transfer can start it is necessary to define the transfer buffer with all its details. The definition of the buffer is done with the `spcm_dwDefTransfer` function as explained in an earlier chapter.

```
uint32 __stdcall spcm_dwDefTransfer_i64 ( // Defines the transfer buffer by using 64 bit unsigned integer values
    drv_handle hDevice, // handle to an already opened device
    uint32 dwBufType, // type of the buffer to define as listed below under SPCM_BUF_XXXX
    uint32 dwDirection, // the transfer direction as defined below
    uint32 dwNotifySize, // number of bytes after which an event is sent (0=end of transfer)
    void* pvDataBuffer, // pointer to the data buffer
    uint64 qwBrdOffs, // offset for transfer in board memory
    uint64 qwTransferLen); // buffer length
```

This function is used to define buffers for standard sample data transfer as well as for extra data transfer for additional ABA or timestamp information. Therefore the `dwBufType` parameter can be one of the following:

SPCM_BUF_DATA	1000	Buffer is used for transfer of standard sample data
SPCM_BUF_ABA	2000	Buffer is used to read out slow ABA data. Details on this mode are described in the chapter about the ABA mode option
SPCM_BUF_TIMESTAMP	3000	Buffer is used to read out timestamp information. Details on this mode are described in the chapter about the timestamp option.

The `dwDirection` parameter defines the direction of the following data transfer:

SPCM_DIR_PCTOCARD	0	Transfer is done from PC memory to on-board memory of card
SPCM_DIR_CARDTOPC	1	Transfer is done from card on-board memory to PC memory.
SPCM_DIR_CARDTOGPU	2	RDMA transfer from card memory to GPU memory, SCAPP option needed, Linux only
SPCM_DIR_GPUTOCARD	3	RDMA transfer from GPU memory to card memory, SCAPP option needed, Linux only

**The direction information used here must match the currently used mode. While an acquisition mode is used there's no transfer from PC to card allowed and vice versa. It is possible to use a special memory test mode to come beyond this limit. Set the SPC\_MEMTEST register as defined further below.**



The `dwNotifySize` parameter defines the amount of bytes after which an interrupt should be generated. If leaving this parameter zero, the transfer will run until all data is transferred and then generate an interrupt. Filling in notify size > zero will allow you to use the amount of data that has been transferred so far. The notify size is used on FIFO mode to implement a buffer handshake with the driver or when transferring large amount of data where it may be of interest to start data processing while data transfer is still running. Please see the chapter on handling positions further below for details.

**The Notify size sticks to the page size which is defined by the PC hardware and the operating system. Therefore the notify size must be a multiple of 4 kByte. For data transfer it may also be a fraction of 4k in the range of 16, 32, 64, 128, 256, 512, 1k or 2k. No other values are allowed. For ABA and timestamp the notify size can be 2k as a minimum. If you need to work with ABA or timestamp data in smaller chunks please use the polling mode as described later.**



The `pvDataBuffer` must point to an allocated data buffer for the transfer. Please be sure to have at least the amount of memory allocated that you program to be transferred. If the transfer is going from card to PC this data is overwritten with the current content of the card on-board memory.

**The pvDataBuffer needs to be aligned to a page size (4096 bytes). Please use appropriate software commands when allocating the data buffer. Using a non-aligned buffer may result in data corruption.**



When not doing FIFO mode one can also use the `qwBrdOffs` parameter. This parameter defines the starting position for the data transfer as byte value in relation to the beginning of the card memory. Using this parameter allows it to split up data transfer in smaller chunks if one has acquired a very large on-board memory.

The `qwTransferLen` parameter defines the number of bytes that has to be transferred with this buffer. Please be sure that the allocated memory has at least the size that is defined in this parameter. In standard mode this parameter cannot be larger than the amount of data defined with memory size.

### **Memory test mode**

In some cases it might be of interest to transfer data in the opposite direction. Therefore a special memory test mode is available which allows random read and write access of the complete on-board memory. While memory test mode is activated no normal card commands are processed:

Register	Value	Direction	Description
SPC_MEMTEST	200700	read/write	Writing a 1 activates the memory test mode, no commands are then processed. Writing a 0 deactivates the memory test mode again.

### **Invalidation of the transfer buffer**

The command can be used to invalidate an already defined buffer if the buffer is about to be deleted by user. This function is automatically called if a new buffer is defined or if the transfer of a buffer has completed

```
uint32 __stdcall spcm_dwInvalidateBuf ( // invalidate the transfer buffer
    drv_handle hDevice,           // handle to an already opened device
    uint32     dwBufType);        // type of the buffer to invalidate as listed above under SPCM_BUF_XXXX
```

The `dwBufType` parameter need to be the same parameter for which the buffer has been defined:

SPCM_BUF_DATA	1000	Buffer is used for transfer of standard sample data
SPCM_BUF_ABA	2000	Buffer is used to read out slow ABA data. Details on this mode are described in the chapter about the ABA mode option. The ABA mode is only available on analog acquisition cards.
SPCM_BUF_TIMESTAMP	3000	Buffer is used to read out timestamp information. Details on this mode are described in the chapter about the timestamp option. The timestamp mode is only available on analog or digital acquisition cards.

### **Commands and Status information for data transfer buffers.**

As explained above the data transfer is performed with the same command and status registers like the card control. It is possible to send commands for card control and data transfer at the same time as shown in the examples further below.

Register	Value	Direction	Description
SPC_M2CMD	100	write only	Executes a command for the card or data transfer
M2CMD_DATA_STARTDMA	10000h		Starts the DMA transfer for an already defined buffer. In acquisition mode it may be that the card hasn't received a trigger yet, in that case the transfer start is delayed until the card receives the trigger event
	20000h		Waits until the data transfer has ended or until at least the amount of bytes defined by notify size are available. This wait function also takes the timeout parameter described above into account.
	40000h		Stops a running DMA transfer. Data is invalid afterwards.

The data transfer can generate one of the following status information:

Register	Value	Direction	Description
SPC_M2STATUS	110	read only	Reads out the current status information
M2STAT_DATA_BLOCKREADY	100h		The next data block as defined in the notify size is available. It is at least the amount of data available but it also can be more data.
	200h		The data transfer has completed. This status information will only occur if the notify size is set to zero.
	400h		The data transfer had an overrun (acquisition) or underrun (replay) while doing FIFO transfer.
	800h		An internal error occurred while doing data transfer.

### **Example of data transfer**

```
void* pvData = pvAllocMemPageAligned (1024);

// transfer data from PC memory to card memory (on replay cards) ...
spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_DATA, SPCM_DIR_PCTOCARD , 0, pvData, 0, 1024);
spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_DATA_STARTDMA | M2CMD_DATA_WAITDMA);

// ... or transfer data from card memory to PC memory (acquisition cards)
spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_DATA, SPCM_DIR_CARDTOPC , 0, pvData, 0, 1024);
spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_DATA_STARTDMA | M2CMD_DATA_WAITDMA);

// explicitly stop DMA transfer prior to invalidating buffer
spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_DATA_STOPDMA);
spcm_dwInvalidateBuf (hDrv, SPCM_BUF_DATA);
vFreeMemPageAligned (pvData, 1024);
```

To keep the example simple it does no error checking. Please be sure to check for errors if using these command in real world programs!

 **Users should take care to explicitly send the M2CMD\_DATA\_STOPDMA command prior to invalidating the buffer, to avoid crashes due to race conditions when using higher-latency data transportation layers, such as to remote Ethernet devices.**

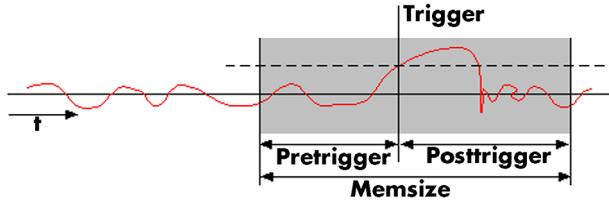
## **Standard Single acquisition mode**

The standard single mode is the easiest and mostly used mode to acquire analog data with a Spectrum acquisition card. In standard single recording mode the card is working totally independent from the PC, after the card setup is done. The advantage of the Spectrum boards is that regardless to the system usage the card will sample with equidistant time intervals.

The sampled and converted data is stored in the on-board memory and is held there for being read out after the acquisition. This mode allows sampling at very high conversion rates without the need to transfer the data into the memory of the host system at high speed.

After the recording is done, the data can be read out by the user and is transferred via the bus into PC memory.

This standard recording mode is the most common mode for all analog and digital acquisition and oscilloscope boards. The data is written to a programmed amount of the on-board memory (mem-size). That part of memory is used as a ring buffer, and recording is done continuously until a trigger event is detected. After the trigger event, a certain programmable amount of data is recorded (post trigger) and then the recording finishes. Due to the continuous ring buffer recording, there are also samples prior to the trigger event in the memory (pretrigger).



**When the card is started the pre trigger area is filled up with data first. While doing this the board's trigger detection is not armed. If you use a huge pre trigger size and a slow sample rate it can take some time after starting the board before a trigger event will be detected.**



### **Card mode**

The card mode has to be set to the correct mode SPC\_REC\_STD\_SINGLE.

Register	Value	Direction	Description
SPC_CARDMODE	9500	read/write	Defines the used operating mode, a read command will return the currently used mode.
SPC_REC_STD_SINGLE	1h		Data acquisition to on-board memory for one single trigger event.

### **Memory, Pre- and Posttrigger**

At first you have to define, how many samples are to be recorded at all and how many of them should be acquired after the trigger event has been detected.

Register	Value	Direction	Description
SPC_MEMSIZE	10000	read/write	Sets the memory size in samples per channel.
SPC_POSTTRIGGER	10100	read/write	Sets the number of samples to be recorded per channel after the trigger event has been detected.

You can access these settings by the register SPC\_MEMSIZE, which sets the total amount of data that is recorded, and the register SPC\_POSTTRIGGER, that defines the number of samples to be recorded after the trigger event has been detected. The size of the pretrigger results on the simple formula:

**pretrigger = memsize - posttrigger**

The maximum memsize that can be used for recording is of course limited by the installed amount of memory and by the number of channels to be recorded. Please have a look at the topic "Limits of pre, post memsize, loops" later in this chapter.

### **Example**

The following example shows a simple standard single mode data acquisition setup with the read out of data afterwards. To keep this example simple there is no error checking implemented.

```

int32 lMemsize = 16384; // recording length is set to 16 kSamples
spcm_dwSetParam_i32 (hDrv, SPC_CHENABLE, CHANNEL0); // only one channel activated
spcm_dwSetParam_i32 (hDrv, SPC_CARDMODE, SPC_REC_STD_SINGLE); // set the standard single recording mode
spcm_dwSetParam_i64 (hDrv, SPC_MEMSIZE, lMemsize); // recording length
spcm_dwSetParam_i64 (hDrv, SPC_POSTTRIGGER, 8192); // samples to acquire after trigger = 8k

// now we start the acquisition and wait for the interrupt that signalizes the end
spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_CARD_START | M2CMD_CARD_ENABLEtrigger | M2CMD_CARD_WAITREADY);

void* pvData = pvAllocMemPageAligned (2 * lMemsize); // assuming 2 bytes per sample

// read out the data
spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_DATA, SPCM_DIR_CARDTOPC , 0, pvData, 0, 2 * lMemsize);
spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_DATA_STARTDMA | M2CMD_DATA_WAITDMA);

```

## FIFO Single acquisition mode

The FIFO single mode does a continuous data acquisition using the on-board memory as a FIFO buffer and transferring data continuously to PC memory. One can make on-line calculations with the acquired data, store the data continuously to disk for later use or even have a data logger functionality with on-line data display.

### Card mode

The card mode has to be set to the correct mode SPC\_REC\_FIFO\_SINGLE.

Register	Value	Direction	Description
SPC_CARDMODE	9500	read/write	Defines the used operating mode, a read command will return the currently used mode.
SPC_REC_FIFO_SINGLE	10h		Continuous data acquisition to PC memory. Complete on-board memory is used as FIFO buffer.

### Length and Pretrigger

Even in FIFO mode it is possible to program a pretrigger area. In general FIFO mode can run forever until it is stopped by an explicit user command or one can program the total length of the transfer by two counters Loop and Segment size

Register	Value	Direction	Description
SPC_PRETRIGGER	10030	read/write	Programs the number of samples to be acquired before the trigger event detection
SPC_SEGMENTSIZE	10010	read/write	Length of segments to acquire.
SPC_LOOPS	10020	read/write	Number of segments to acquire in total. If set to zero the FIFO mode will run continuously until it is stopped by the user.

The total amount of samples per channel that is acquired can be calculated by [SPC\_LOOPS \* SPC\_SEGMENTSIZE]. Please stick to the below mentioned limitations of the registers.

### Difference to standard single acquisition mode

The standard modes and the FIFO modes differ not very much from the programming side. In fact one can even use the FIFO mode to get the same behavior like the standard mode. The buffer handling that is shown in the next chapter is the same for both modes.

#### Pretrigger

When doing standard single acquisition memory is used as a circular buffer and the pre trigger can be up to the [installed memory] - [minimum post trigger]. Compared to this the pre trigger in FIFO mode is limited by a special pre trigger FIFO and hence considerably shorter.

#### Length of acquisition.

In standard mode the acquisition length is defined before the start and is limited to the installed on-board memory whilst in FIFO mode the acquisition length can either be defined or it can run continuously until user stops it.

### Example FIFO acquisition

The following example shows a simple FIFO single mode data acquisition setup with the read out of data afterwards. To keep this example simple there is no error checking implemented.

```

spcm_dwSetParam_i32 (hDrv, SPC_CHENABLE, CHANNEL0);                                // only one channel activated
spcm_dwSetParam_i32 (hDrv, SPC_CARDMODE, SPC_REC_FIFO_SINGLE);                      // set the FIFO single recording mode
spcm_dwSetParam_i64 (hDrv, SPC_PRETRIGGER, 1024);                                 // 1 kSample of data before trigger

// in FIFO mode we need to define the buffer before starting the transfer
void* pvData = pvAllocMemPageAligned (llBufsizeInSamples * 2);                     // 2 bytes per sample
spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_DATA, SPCM_DIR_CARDTOPC, 4096,
                        pvData, 0, 2 * llBufsizeInSamples);

// now we start the acquisition and wait for the first block
dwError = spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_CARD_START | M2CMD_CARD_ENABLETRIGGER);
dwError = spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_DATA_STARTDMA | M2CMD_DATA_WAITDMA);

// we acquire data in a loop. As we defined a notify size of 4k we'll get the data in >=4k chunks
llTotalBytes = 0;
while (!dwError)
{
    spcm_dwGetParam_i64 (hDrv, SPC_DATA_AVAIL_USER_LEN, &llAvailBytes); // read out the available bytes
    llTotalBytes += llAvailBytes;

    // here is the right position to do something with the data (printf is limited to 32 bit variables)
    printf ("Currently Available: %lld, total: %lld\n", llAvailBytes, llTotalBytes);

    // now we free the number of bytes and wait for the next buffer
    spcm_dwSetParam_i64 (hDrv, SPC_DATA_AVAIL_CARD_LEN, llAvailBytes);
    dwError = spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_DATA_WAITDMA);
}

```

## Limits of pre trigger, post trigger, memory size

The maximum memory size parameter is only limited by the number of activated channels and by the amount of installed memory. Please keep in mind that each samples needs 2 bytes of memory to be stored. Minimum memory size as well as minimum and maximum post trigger limits are independent of the activated channels or the installed memory.

Due to the internal organization of the card memory there is a certain stepsize when setting these values that has to be taken into account. The following table gives you an overview of all limits concerning pre trigger, post trigger, memory size, segment size and loops. The table shows all values in relation to the installed memory size in samples. If more memory is installed the maximum memory size figures will increase according to the complete installed memory

Activated Channels	Used Mode	Memory size SPC_MEMSIZE			Pre trigger SPC_PRETRIGGER			Post trigger SPC_POSTTRIGGER			Segment size SPC_SEGMENTSIZE			Loops SPC_LOOPS		
		Min	Max	Step	Min	Max	Step	Min	Max	Step	Min	Max	Step	Min	Max	Step
1 Ch	Standard Single	16	Mem	8	8	Mem - 8	8	8	8G - 8	8	not used			not used		
	Standard Multi/ABA	16	Mem	8	8	32k	8	8	Mem - 8	8	16	Mem	8	not used		
	Standard Gate	16	Mem	8	8	32k	8	8	Mem - 8	8	not used			not used		
	FIFO Single	not used			8	32k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1
	FIFO Multi/ABA	not used			8	32k	8	8	8G - 8	8	16	pre+post	8	0 (∞)	4G - 1	1
	FIFO Gate	not used			8	32k	8	8	8G - 8	8	not used			0 (∞)	4G - 1	1
2 Ch	Standard Single	16	Mem/2	8	8	Mem/2 - 8	8	8	8G - 8	8	not used			not used		
	Standard Multi/ABA	16	Mem/2	8	8	16k	8	8	Mem/2 - 8	8	16	Mem/2	8	not used		
	Standard Gate	16	Mem/2	8	8	16k	8	8	Mem/2 - 8	8	not used			not used		
	FIFO Single	not used			8	16k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1
	FIFO Multi/ABA	not used			8	16k	8	8	8G - 8	8	16	pre+post	8	0 (∞)	4G - 1	1
	FIFO Gate	not used			8	16k	8	8	8G - 8	8	not used			0 (∞)	4G - 1	1
4 Ch	Standard Single	16	Mem/4	8	8	Mem/4 - 8	8	8	8G - 16	8	not used			not used		
	Standard Multi/ABA	16	Mem/4	8	8	8k	8	8	Mem/4 - 8	8	16	Mem/4	8	not used		
	Standard Gate	16	Mem/4	8	8	8k	8	8	Mem/4 - 8	8	not used			not used		
	FIFO Single	not used			8	8k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1
	FIFO Multi/ABA	not used			8	8k	8	8	8G - 16	8	16	pre+post	8	0 (∞)	4G - 1	1
	FIFO Gate	not used			8	8k	8	8	8G - 16	8	not used			0 (∞)	4G - 1	1
8 Ch	Standard Single	16	Mem/8	8	8	Mem/8 - 8	8	8	8G - 8	8	not used			not used		
	Standard Multi/ABA	16	Mem/8	8	8	4k	8	8	Mem/8 - 8	8	16	Mem/8	8	not used		
	Standard Gate	16	Mem/8	8	8	4k	8	8	Mem/8 - 8	8	not used			not used		
	FIFO Single	not used			8	4k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1
	FIFO Multi/ABA	not used			8	4k	8	8	8G - 16	8	16	pre+post	8	0 (∞)	4G - 1	1
	FIFO Gate	not used			8	4k	8	8	8G - 16	8	not used			0 (∞)	4G - 1	1

All figures listed here are given in samples. An entry of [8G - 16] means [8 GSamples - 16] = 8,589,934,576 samples.

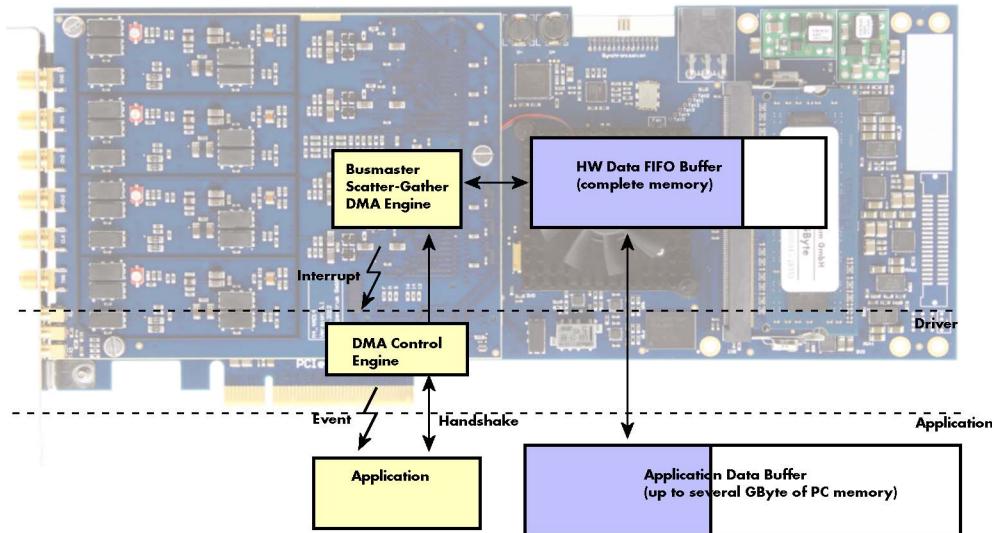
The given memory and memory / divider figures depend on the installed on-board memory as listed below:

Installed Memory	
<b>512 Msample</b>	
Mem	512 Msample
Mem/2	256 Msample
Mem/4	128 Msample
Mem/8	64 Msample

Please keep in mind that this table shows all values at once. Only the absolute maximum and minimum values are shown. There might be additional limitations. Which of these values are programmed depends on the used mode. Please read the detailed documentation of the mode.

## Buffer handling

To handle the huge amount of data that can possibly be acquired with the M4i/M4x/M2p series cards, there is a very reliable two step buffer strategy set up. The on-board memory of the card can be completely used as a real FIFO buffer. In addition a part of the PC memory can be used as an additional software buffer. Transfer between hardware FIFO and software buffer is performed interrupt driven and automatically by the driver to get best performance. The following drawing will give you an overview of the structure of the data transfer handling:



Although an M4i is shown here, this applies to M4x and M2p cards as well. A data buffer handshake is implemented in the driver which allows to run the card in different data transfer modes. The software transfer buffer is handled as one large buffer which is on the one side controlled by the driver and filled automatically by busmaster DMA from/to the hardware FIFO buffer and on the other hand it is handled by the user who set's parts of this software buffer available for the driver for further transfer. The handshake is fulfilled with the following 3 software registers:

Register	Value	Direction	Description
SPC_DATA_AVAIL_USER_LEN	200	read	Returns the number of currently to the user available bytes inside a sample data transfer.
SPC_DATA_AVAIL_USER_POS	201	read	Returns the position as byte index where the currently available data samples start.
SPC_DATA_AVAIL_CARD_LEN	202	write	Writes the number of bytes that the card can now use for sample data transfer again

Internally the card handles two counters, a user counter and a card counter. Depending on the transfer direction the software registers have slightly different meanings:

Transfer direction	Register	Direction	Description
Write to card	SPC_DATA_AVAIL_USER_LEN	read	This register contains the currently available number of bytes that are free to write new data to the card. The user can now fill this amount of bytes with new data to be transferred.
	SPC_DATA_AVAIL_CARD_LEN	write	After filling an amount of the buffer with new data to transfer to card, the user tells the driver with this register that the amount of data is now ready to transfer.
Read from card	SPC_DATA_AVAIL_USER_LEN	read	This register contains the currently available number of bytes that are filled with newly transferred data. The user can now use this data for own purposes, copy it, write it to disk or start calculations with this data.
	SPC_DATA_AVAIL_CARD_LEN	write	After finishing the job with the new available data the user needs to tell the driver that this amount of bytes is again free for new data to be transferred.
Any direction	SPC_DATA_AVAIL_USER_POS	read	The register holds the current byte index position where the available bytes start. The register is just intended to help you and to avoid own position calculation
Any direction	SPC_FILLSIZEPROMILLE	read	The register holds the current fill size of the on-board memory (FIFO buffer) in promille (1/1000) of the full on-board memory. Please note that the hardware reports the fill size only in 1/16 parts of the full memory. The reported fill size is therefore only shown in 1000/16 = 63 promille steps.

Directly after start of transfer the SPC\_DATA\_AVAIL\_USER\_LEN is every time zero as no data is available for the user and the SPC\_DATA\_AVAIL\_CARD\_LEN is every time identical to the length of the defined buffer as the complete buffer is available for the card for transfer.

**⚠ The counter that is holding the user buffer available bytes (SPC\_DATA\_AVAIL\_USER\_LEN) is related to the notify size at the DefTransfer call. Even when less bytes already have been transferred you won't get notice of it in case the notify size is programmed to a higher value.**

### Remarks

- The transfer between hardware FIFO buffer and application buffer is done with scatter-gather DMA using a busmaster DMA controller located on the card. Even if the PC is busy with other jobs data is still transferred until the application data buffer is completely used.
- Even if application data buffer is completely used there's still the hardware FIFO buffer that can hold data until the complete on-board memory is used. Therefore a larger on-board memory will make the transfer more reliable against any PC dead times.
- As you see in the above picture data is directly transferred between application data buffer and on-board memory. Therefore it is absolutely critical to delete the application data buffer without stopping any DMA transfers that are running actually. It is also absolutely criti-

cal to define the application data buffer with an unmatching length as DMA can than try to access memory outside the application data area.

- As shown in the drawing above the DMA control will announce new data to the application by sending an event. Waiting for an event is done internally inside the driver if the application calls one of the wait functions. Waiting for an event does not consume any CPU time and is therefore highly desirable if other threads do a lot of calculation work. However it is not necessary to use the wait functions and one can simply request the current status whenever the program has time to do so. When using this polling mode the announced available bytes still stick to the defined notify size!
- If the on-board FIFO buffer has an overrun (card to PC) or an underrun (PC to card) data transfer is stopped. However in case of transfer from card to PC there is still a lot of data in the on-board memory. Therefore the data transfer will continue until all data has been transferred although the status information already shows an overrun.
- For very small notify sizes, getting best bus transfer performance could be improved by using a „continuous buffer“. This mode is explained in the appendix in greater detail.

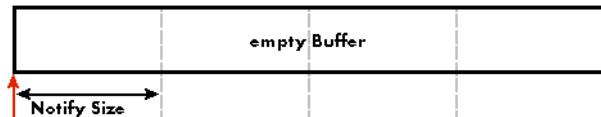
**The Notify size sticks to the page size which is defined by the PC hardware and the operating system. Therefore the notify size must be a multiple of 4 kByte. For data transfer it may also be a fraction of 4k in the range of 16, 32, 64, 128, 256, 512, 1k or 2k. No other values are allowed. For ABA and timestamp the notify size can be 2k as a minimum. If you need to work with ABA or timestamp data in smaller chunks please use the polling mode as described later.**



The following graphs will show the current buffer positions in different states of the transfer. The drawings have been made for the transfer from card to PC. However all the block handling is similar for the opposite direction, just the empty and the filled parts of the buffer are inverted.

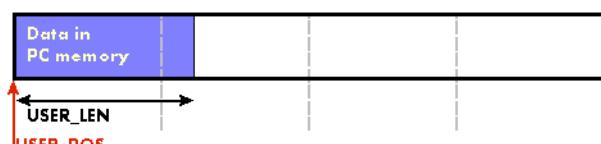
#### **Step 1: Buffer definition**

Directly after buffer definition the complete buffer is empty (card to PC) or completely filled (PC to card). In our example we have a notify size which is 1/4 of complete buffer memory to keep the example simple. In real world use it is recommended to set the notify size to a smaller stepsize.



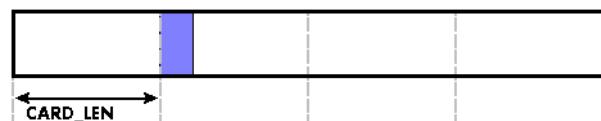
#### **Step 2: Start and first data available**

In between we have started the transfer and have waited for the first data to be available for the user. When there is at least one block of notify size in the memory we get an interrupt and can proceed with the data. Any data that already was transferred is announced. The USER\_POS is still zero as we are right at the beginning of the complete transfer.



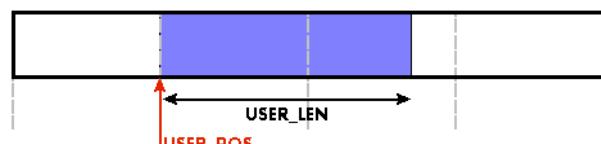
#### **Step 3: set the first data available for card**

Now the data can be processed. If transfer is going from card to PC that may be storing to hard disk or calculation of any figures. If transfer is going from PC to card that means we have to fill the available buffer again with data. After the amount of data that has been processed by the user application we set it available for the card and for the next step.



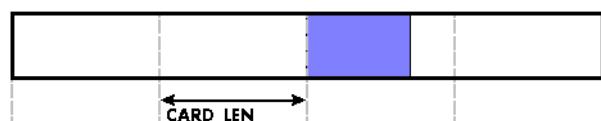
#### **Step 4: next data available**

After reaching the next border of the notify size we get the next part of the data buffer to be available. In our example at the time when reading the USER\_LEN even some more data is already available. The user position will now be at the position of the previous set CARD\_LEN.



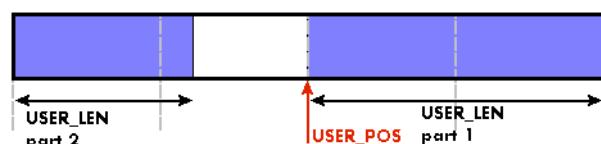
#### **Step 5: set data available again**

Again after processing the data we set it free for the card use. In our example we now make something else and don't react to the interrupt for a longer time. In the background the buffer is filled with more data.



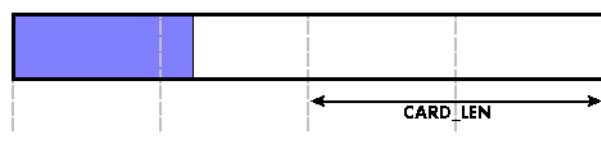
#### **Step 6: roll over the end of buffer**

Now nearly the complete buffer is filled. Please keep in mind that our current user position is still at the end of the data part that we processed and marked in step 4 and step 5. Therefore the data to process now is split in two parts. Part 1 is at the end of the buffer while part 2 is starting with address 0.



#### **Step 7: set the rest of the buffer available**

Feel free to process the complete data or just the part 1 until the end of the buffer as we do in this example. If you decide to process complete buffer please keep in mind the roll over at the end of the buffer.



This buffer handling can now continue endless as long as we manage to set the data available for the card fast enough. The USER\_POS and USER\_LEN for step 8 would now look exactly as the buffer shown in step 2.

**Buffer handling example for transfer from card to PC (Data acquisition)**

```

int8* pcData = (int8*) pvAllocMemPageAligned (llBufferSizeInBytes);

// we now define the transfer buffer with the minimum notify size of one page = 4 kByte
spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_DATA, SPCM_DIR_CARDTOPC, 4096, (void*) pcData, 0, llBufferSizeInBytes);

// we start the DMA transfer
dwError = spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_DATA_STARTDMA);

do
{
    if (!dwError)
    {
        // we wait for the next data to be available. Afte this call we get at least 4k of data to proceed
        dwError = spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_DATA_WAITDMA);

        // if there was no error we can proceed and read out the available bytes that are free again
        spcm_dwGetParam_i64 (hDrv, SPC_DATA_AVAIL_USER_LEN, &llAvailBytes);
        spcm_dwGetParam_i64 (hDrv, SPC_DATA_AVAIL_USER_POS, &llBytePos);

        printf ("We now have %lld new bytes available\n", llAvailBytes);
        printf ("The available data starts at position %lld\n", llBytesPos);

        // we take care not to go across the end of the buffer, handling the wrap-around
        if ((llBytePos + llAvailBytes) >= llBufferSizeInBytes)
            llAvailBytes = llBufferSizeInBytes - llBytePos;

        // our do function gets a pointer to the start of the available data section and the length
        vDoSomething (&pcData[llBytesPos], llAvailBytes);

        // the buffer section is now immediately set available for the card
        spcm_dwSetParam_i64 (hDrv, SPC_DATA_AVAIL_CARD_LEN, llAvailBytes);
    }
}
while (!dwError); // we loop forever if no error occurs

```

**Buffer handling example for transfer from PC to card (Data generation)**

```

int8* pcData = (int8*) pvAllocMemPageAligned (llBufferSizeInBytes);

// before starting transfer we first need to fill complete buffer memory with meaningful data
vDoGenerateData (&pcData[0], llBufferSizeInBytes);

// we now define the transfer buffer with the minimum notify size of one page = 4 kByte
spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_DATA, SPCM_DIR_PCTOCARD, 4096, (void*) pcData, 0, llBufferSizeInBytes);

// and transfer some data to the hardware buffer before the start of the card
spcm_dwSetParam_i32 (hDrv, SPC_DATA_AVAIL_CARD_LEN, llBufferSizeInBytes);
dwError = spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_DATA_STARTDMA | M2CMD_DATA_WAITDMA);

do
{
    if (!dwError)
    {
        // if there was no error we can proceed and read out the current amount of available data
        spcm_dwGetParam_i64 (hDrv, SPC_DATA_AVAIL_USER_LEN, &llAvailBytes);
        spcm_dwGetParam_i64 (hDrv, SPC_DATA_AVAIL_USER_POS, &llBytePos);

        printf ("We now have %lld free bytes available\n", llAvailBytes);
        printf ("The available data starts at position %lld\n", llBytesPos);

        // we take care not to go across the end of the buffer, handling the wrap-around
        if ((llBytePos + llAvailBytes) >= llBufferSizeInBytes)
            llAvailBytes = llBufferSizeInBytes - llBytePos;

        // our do function gets a pointer to the start of the available data section and the length
        vDoGenerateData (&pcData[llBytesPos], llAvailBytes);

        // now we mark the number of bytes that we just generated for replay
        // and wait for the next free buffer
        spcm_dwSetParam_i64 (hDrv, SPC_DATA_AVAIL_CARD_LEN, llAvailBytes);
        dwError = spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_DATA_WAITDMA);
    }
}
while (!dwError); // we loop forever if no error occurs

```

**!** Please keep in mind that you are using a continuous buffer writing/reading that will start again at the zero position if the buffer length is reached. However the DATA\_AVAIL\_USER\_LEN register will give you the complete amount of available bytes even if one part of the free area is at the end of the buffer and the second half at the beginning of the buffer.

## Data organization

Data is organized in a multiplexed way in the transfer buffer. If using 2 channels data of first activated channel comes first, then data of second channel.

Activated Channels	Ch0	Ch1	Ch2	Ch3	Ch4	Ch5	Ch6	Ch7	Samples ordering in buffer memory starting with data offset zero														
1 channel	X								A0	A1	A2	A3	A4	A5	A6	A7	A8	A9	A10	A11	A12	...	
								X	G0	G1	G2	G3	G4	G5	G6	G7	G8	G9	G10	G11	G12	...	
2 channels	X	X							A0	B0	A1	B1	A2	B2	A3	B3	A4	B4	A5	B5	A6	...	
																							...
4 channels	X	X	X	X					A0	B0	C0	D0	A1	B1	C1	D1	A2	B2	C2	D2	A3	...	
																							...
8 channels	X	X	X	X	X	X	X	X	A0	B0	C0	D0	H0	A1	C1	D1	H1	A2	C2	D2	H2	A3	...
																							F1

The samples are re-named for better readability. A0 is sample 0 of channel 0, B4 is sample 4 of channel 1, and so on.

## Sample format

If the card is using 16 bit A/D samples, the are stored in twos complement in the 16 bit data word. 16 bit resolution means that data is ranging from -32768...to...+32767.

Up to three digital inputs (provided via the Multi Purpose I/O lines X1, X2 and X3) can be acquired synchronously and stored within the data samples of any active channel. This will reduce the available resolution of these channel(s) to either 15 bit, 14 bit or 13 bit, depending on the number of incorporated digital lines. For a detailed description on how to enable additional synchronous digital inputs, please see the „Multi Purpose I/O Lines“ section later in this manual.

Any channels that will not store any digital inputs within their samples still provide the full 16 bit resolution. :

Data bit	Standard Mode 16 bit ADC resolution	1 digital input enabled	2 digital inputs enabled	3 digital inputs enabled
		15 bit ADC resolution	14 bit ADC resolution	13 bit ADC resolution
D15	ADx Bit 15 (MSB)	Digital bit 0 (any X input)*	Digital bit 0 (any X input)*	Digital bit 0 (any X input)*
D14	ADx Bit 14	ADx Bit 15 (MSB)	Digital bit 1 (any X input)*	Digital bit 1 (any X input)*
D13	ADx Bit 13	ADx Bit 14	ADx Bit 15 (MSB)	Digital bit 2 (any X input)*
D12	ADx Bit 12	ADx Bit 13	ADx Bit 14	ADx Bit 15 (MSB)
D11	ADx Bit 11	ADx Bit 12	ADx Bit 13	ADx Bit 14
D10	ADx Bit 10	ADx Bit 11	ADx Bit 12	ADx Bit 13
D9	ADx Bit 9	ADx Bit 10	ADx Bit 11	ADx Bit 12
D8	ADx Bit 8	ADx Bit 9	ADx Bit 10	ADx Bit 11
D7	ADx Bit 7	ADx Bit 8	ADx Bit 9	ADx Bit 10
D6	ADx Bit 6	ADx Bit 7	ADx Bit 8	ADx Bit 9
D5	ADx Bit 5	ADx Bit 6	ADx Bit 7	ADx Bit 8
D4	ADx Bit 4	ADx Bit 5	ADx Bit 6	ADx Bit 7
D3	ADx Bit 3	ADx Bit 4	ADx Bit 5	ADx Bit 6
D2	ADx Bit 2	ADx Bit 3	ADx Bit 4	ADx Bit 5
D1	ADx Bit 1	ADx Bit 2	ADx Bit 3	ADx Bit 4
D0	ADx Bit 0 (LSB)	ADx Bit 1 (LSB)	ADx Bit 2 (LSB)	ADx Bit 3 (LSB)

\* Any X-input can be used as a source for that digital channel, except X0, which is output only.

## **Converting ADC samples to voltage values**

The Spectrum driver also contains a register that holds the value of the decimal value of the full scale representation of the installed ADC. This value should be used when converting ADC values (in LSB) into real-world voltage values, because this register also automatically takes any specialities into account, such as slightly reduced ADC resolution with reserved codes for gain/offset compensation.

Register	Value	Direction	Description
SPC_MINST_MAXADCVALUE	1126	read	Contains the decimal code (in LSB) of the ADC full scale value.

In case of a board that uses an 8 bit ADC that provides the full ADC code (without reserving any bits) the returned value would be 128. The peak value for a  $\pm 1.0$  V input range would be 1.0 V (or 1000 mV).

A returned sample value of for example +49 (decimal, two's complement, signed representation) would then convert to:

$$V_{in} = 49 \times \frac{1000 \text{ mV}}{128} = 382.81 \text{ mV}$$

A returned sample value of for example -55 (decimal) would then convert to:

$$V_{in} = -55 \times \frac{1000 \text{ mV}}{128} = -429.69 \text{ mV}$$

 When converting samples that contain any additional data such as for example additional digital channels or overrange bits, this extra information must be first masked out and a proper sign-extension must be performed, before these values can be used as a signed two's complement value for above formulas.

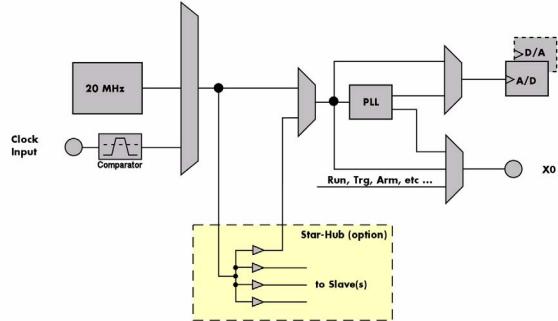
## Clock generation

### Overview

The Spectrum M2p PCI Express (PCIe) cards offer a wide variety of different clock modes to match all the customers needs. All of the clock modes are described in detail with programming examples in this chapter.

The figure is showing an overview of the complete engine used on all M2p cards for clock generation.

The purpose of this chapter is to give you a guide to the best matching clock settings for your specific application and needs.



### Clock Mode Register

The selection of the different clock modes has to be done by the SPC\_CLOCKMODE register. All available modes, can be read out by the help of the SPC\_AVAILCLOCKMODES register.

Register	Value	Direction	Description
SPC_AVAILCLOCKMODES	20201	read	Bitmask, in which all bits of the below mentioned clock modes are set, if available.
SPC_CLOCKMODE	20200	read/write	Defines the used clock mode or reads out the actual selected one.
SPC_CM_INTPLL	1		Enables internal PLL with 20 MHz internal reference for sample clock generation.
SPC_CM_EXTERNAL	8		Enables external clock input for direct sample clock generation.
SPC_CM_EXTRREFCLOCK	32		Enables internal PLL with external reference for sample clock generation.

The different clock modes and all other related or required register settings are described on the following pages.

### The different clock modes

#### Standard internal sample rate (PLL with internal reference)

This is the easiest and most common way to generate a sample rate with no need for additional external clock signals. The sample rate has a very fine resolution, low jitter and a high accuracy. The on-board oscillator acts as a reference to the internal PLL. The specification is found in the technical data section of this manual.

#### Direct external clock

Any clock can be fed in that matches the specification of the board. The external clock signal can be used to synchronize the board on a system clock or to feed in an exact matching sample rate.

#### External reference clock

Any clock can be fed in that matches the specification of the board. The external clock signal can be used to synchronize the board on a system clock or to feed in an exact matching sample rate. The external clock is divided/multiplied using a PLL allowing a wide range of external clock modes.

#### Synchronization Clock (option Star-Hub)

The Star-Hub option allows the synchronization of up to 16 cards of the M2p series from Spectrum with a minimal phase delay between the different cards. The clock is distributed from the master card to all connected cards. As this clock is also available at the PLL input, cards of the same or slower sampling speeds can be synchronized with different sample rates when using the PLL. For details on the synchronization option please take a look at the dedicated chapter in this manual.

### Standard internal sampling clock (PLL)

The internal sampling clock is generated in default mode by a programmable high precision quartz. You need to select the clock mode by the dedicated register shown in the table below:

Register	Value	Direction	Description
SPC_CLOCKMODE	20200	read/write	Defines the used clock mode
SPC_CM_INTPLL	1		Enables internal programmable high precision quartz for sample clock generation

The user does not have to care about how the desired sampling rate is generated by multiplying and dividing internally. You simply write the desired sample rate to the according register shown in the table below and the driver makes all the necessary calculations. If you want to

make sure the sample rate has been set correctly you can also read out the register and the driver will give you back the sampling rate that is matching your desired one best.

Register	Value	Direction	Description
SPC_SAMPLERATE	20000	write	Defines the sample rate in Hz for internal sample rate generation.
		read	Read out the internal sample rate that is nearest matching to the desired one.

Independent of the used clock source it is possible to enable the clock output. The clock will be available on the external clock output connector and can be used to synchronize external equipment with the board.

Register	Value	Direction	Description
SPC_CLOCKOUT	20110	read/write	Writing a „1“ enables clock output on external clock output connector. Writing a „0“ disables the clock output (tristate)
SPC_CLOCKOUTFREQUENCY	20111	read	Allows to read out the frequency of an internally synthesized clock present at the clock output.

Example on writing and reading internal sampling rate

```
spcm_dwSetParam_i32 (hDrv, SPC_CLOCKMODE, SPC_CM_INTPLL); // Enables internal programmable quartz 1
spcm_dwSetParam_i64 (hDrv, SPC_SAMPLERATE, 62500000); // Set internal sampling rate to 62.5 MHz
spcm_dwSetParam_i32 (hDrv, SPC_CLOCKOUT, 1); // enable the clock output of the card
spcm_dwGetParam_i64 (hDrv, SPC_SAMPLERATE, &lSamplerate); // Read back the programmed sample rate and print
printf („Sample rate = %d\n“, lSamplerate); // it. Output should be „Sample rate = 62500000“
```

## Maximum and minimum internal sampling rate

The minimum and the maximum internal sampling rates depend on the specific type of board. Both values can be found in the technical data section of this manual.

## Oversampling

All fast instruments have a minimum clock frequency that is limited by either the manufacturer limit of the used A/D converter or by limiting factors of the clock design. You find this minimum sampling rate specified in the technical data section as minimum native ADC converter clock.

When using one of the above mentioned internal clock modes the driver allows you to program sampling clocks that lie far beneath this minimum sampling clock. To run the instrument properly we use a special oversampling mode where the A/D converter/clock section is within its specification and only the digital part of the card is running with the slower clock. This is completely defined inside the driver and cannot be modified by the user. The following register allows to read out the oversampling factor for further calculation

Register	Value	Direction	Description
SPC_OVERSAMPLINGFACTOR	200123	read only	Returns the oversampling factor for further calculations. If oversampling isn't active a 1 is returned.

**!** When using clock output the sampling clock at the output connector is the real instrument sampling clock and not the programmed slower sampling rate. To calculate the output clock, please just multiply the programmed sampling clock with the oversampling factor read with the above mentioned register.

## Direct external clock

An external clock can be fed in on the external clock connector of the board. This can be any clock, that matches the specification of the card. The external clock signal can be used to synchronize the card on a system clock or to feed in an exact matching sampling rate.

Register	Value	Direction	Description
SPC_CLOCKMODE	20200	read/write	Defines the used clock mode
SPC_CM_EXTERNAL	8		Enables external clock input for direct sample clock generation

The maximum values for the external clock is board dependant and shown in the technical data section.

## Termination of the clock input

If the external connector is used as an input, either for feeding in an external reference clock or for external clocking you can enable a 50 Ohm termination on the board. If the termination is disabled, the impedance is high. Please make sure that your source is capable of driving that current and that it still fulfills the clock input specification as given in the technical data section.

Register	Value	Direction	Description
SPC_CLOCK50OHM	20120	read/write	A „1“ enables the 50 Ohm termination at the external clock connector. Only possible, when using the external connector as an input.

### **Clock threshold level**

The external clock input of the M2p cards allows to set a threshold level in the range of  $\pm 5V$  to adopt the input to different logic standards (such as 1.5V LV TTL, 3.3V LV TTL, 5V TTL etc) as well as to allow to detect an externally AC-coupled clock by setting the level to 0 mV.

The threshold levels for the external clock is to be programmed in mV:

Register	Value	Direction	Description	Range
SPC_CLOCK_AVAILTHRESHOLD_MIN	42423	read	returns the minimum clock threshold level to be programmed in mV	
SPC_CLOCK_AVAILTHRESHOLD_MAX	42424	read	returns the maximum clock threshold level to be programmed in mV	
SPC_CLOCK_AVAILTHRESHOLD_STEP	42425	read	returns the step size of clock threshold level to be programmed in mV	
SPC_CLOCK_THRESHOLD	42410	read/write	Threshold level for clock input	-5000 mV to +5000 mV

Example for setting the external clock threshold level:

```
spcm_dwSetParam_i32 (hDrv, SPC_CLOCK_THRESHOLD, 1500); // set threshold to 1.5V, suitable for 3.3V LVCMOS clock
```

**As the digital bandwidth filter of the M2p.591x cards does require the generation of a higher internal ADC sample rate, it is not available when using direct external clocking (clock mode SPC\_CM\_EXTERNAL). Please see the „Setting up the inputs“ chapter for details on the digital bandwidth filter for these cards.**



### **External reference clock**

If you have an external clock generator with a extremely stable frequency, you can use it as a reference clock. You can connect it to the external clock connector and the PLL will be fed with this clock instead of the internal reference. The following table shows how to enable the reference clock mode:

Register	Value	Direction	Description
SPC_CLOCKMODE	20200	read/write	Defines the used clock mode
SPC_CM_EXTREFCLOCK	32		Enables internal PLL with external reference for sample clock generation

Due to the fact that the driver needs to know the external fed in frequency for an exact calculation of the sampling rate you must set the SPC\_REFERENCECLOCK register accordingly as shown in the table below. The driver automatically then sets the PLL to achieve the desired sampling rate. Please be aware that the PLL has some internal limits and not all desired sampling rates may be reached with every reference clock.

Register	Value	Direction	Description
SPC_REFERENCECLOCK	20140	read/write	Programs the external reference clock in the range as stated in the technical data section..
	External sampling rate in Hz as an integer value		You need to set up this register exactly to the frequency of the external fed in clock.

Example of reference clock:

```
spcm_dwSetParam_i32 (hDrv, SPC_CLOCKMODE, SPC_CM_EXTREFCLOCK); // Set to reference clock mode
spcm_dwSetParam_i32 (hDrv, SPC_REFERENCECLOCK, 10000000); // Reference clock that is fed in is 10 MHz
spcm_dwSetParam_i32 (hDrv, SPC_SAMPLERATE, 25000000); // We want to have 25 MHz as sampling rate
```

**The reference clock must be defined via the SPC\_REFERENCECLOCK register prior to defining the sample rate via the SPC\_SAMPLERATE register to allow the driver to calculate the proper clock settings correctly.**



### **Termination of the clock input**

If the external connector is used as an input, either for feeding in an external reference clock or for external clocking you can enable a 50 Ohm termination on the board. If the termination is disabled, the impedance is high. Please make sure that your source is capable of driving that current and that it still fulfills the clock input specification as given in the technical data section.

Register	Value	Direction	Description
SPC_CLOCK50OHM	20120	read/write	A „1“ enables the 50 Ohm termination at the external clock connector. Only possible, when using the external connector as an input.

### **Clock threshold level**

The external clock input of the M2p cards allows to set a threshold level in the range of  $\pm 5V$  to adopt the input to different logic standards (such as 1.5V LV TTL, 3.3V LV TTL, 5V TTL etc) as well as to allow to detect an externally AC-coupled clock by setting the level to 0 mV.

The threshold levels for the external clock is to be programmed in mV:

Register	Value	Direction	Description	Range
SPC_CLOCK_AVAILTHRESHOLD_MIN	42423	read	returns the minimum clock threshold level to be programmed in mV	
SPC_CLOCK_AVAILTHRESHOLD_MAX	42424	read	returns the maximum clock threshold level to be programmed in mV	
SPC_CLOCK_AVAILTHRESHOLD_STEP	42425	read	returns the step size of clock threshold level to be programmed in mV	
SPC_CLOCK_THRESHOLD	42410	read/write	Threshold level for clock input	-5000 mV to +5000 mV

Example for setting the external clock threshold level:

```
spcm_dwSetParam_i32 (hDrv, SPC_CLOCK_THRESHOLD, 1500); // set threshold to 1.5V, suitable for 3.3V LVCMOS clock
```

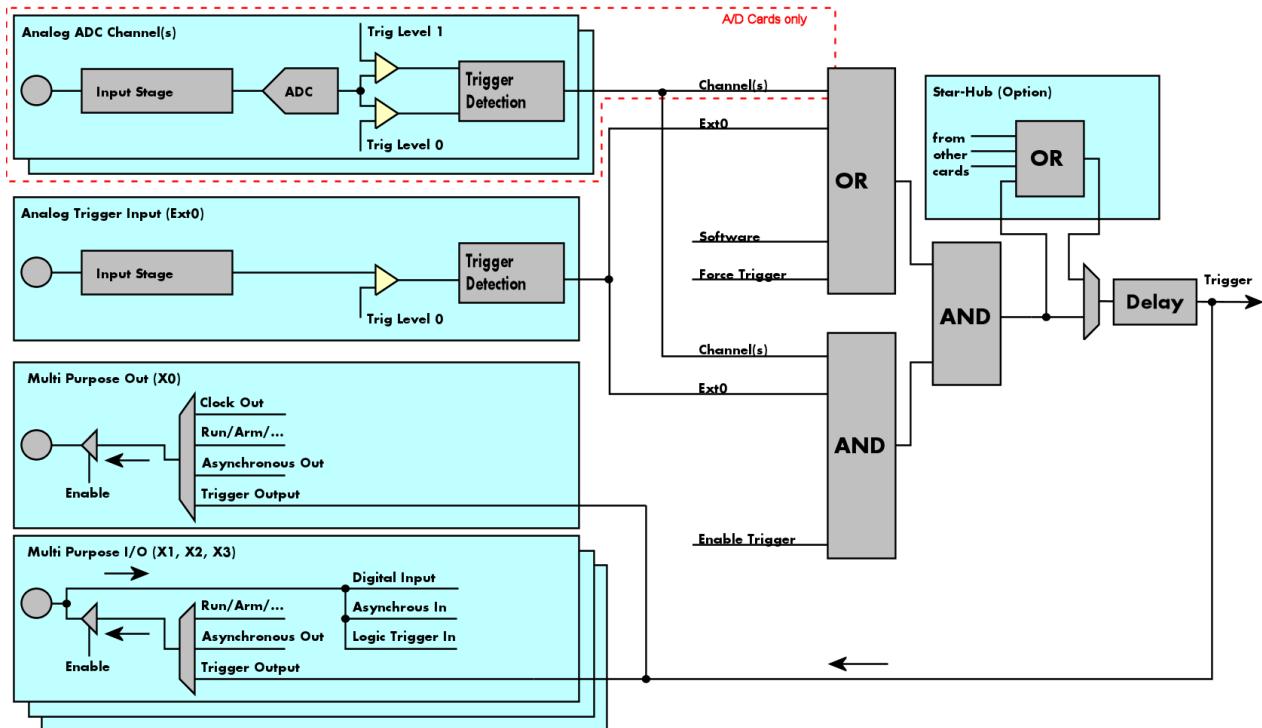
## Trigger modes and appendant registers

### General Description

The trigger modes of the Spectrum M2p series A/D and D/A cards are very extensive and give you the possibility to detect nearly any trigger event you can think of.

You can choose between various external trigger modes as well as internal trigger modes (on analog acquisition cards) including software and channel trigger, depending on your type of board. Many of the channel trigger modes can be independently set for each input channel (on A/D boards only) resulting in a even bigger variety of modes. This chapter is about to explain all of the different trigger modes and setting up the card's registers for the desired mode.

### Trigger Engine Overview



The trigger engine of the M2p card series allows to combine several different trigger sources with OR and AND combination, with a trigger delay or even with an OR combination across several cards when using the Star-Hub option. The above drawing gives a complete overview of the trigger engine and shows all possible features that are available.

On A/D cards each analog input channel has two trigger level comparators to detect edges as well as windowed triggers. All card types have also different external trigger sources. One main trigger source (Ext0) with one analog level comparator. Additionally three multi purpose inputs/outputs can be used as additional logic (TTL) trigger sources as well. These lines can also be software programmed to either inputs or outputs some extended status signals. Additionally one pure multi purpose output is also available for clock and status output.

The Enable trigger allows the user to enable or disable all trigger sources (including channel trigger on A/D cards and external trigger) with a single software command. The enable trigger command will not work on force trigger.

When the card is waiting for a trigger event, either a channel trigger or an external trigger the force trigger command allows to force a trigger event with a single software command. The force trigger overrides the enable trigger command.

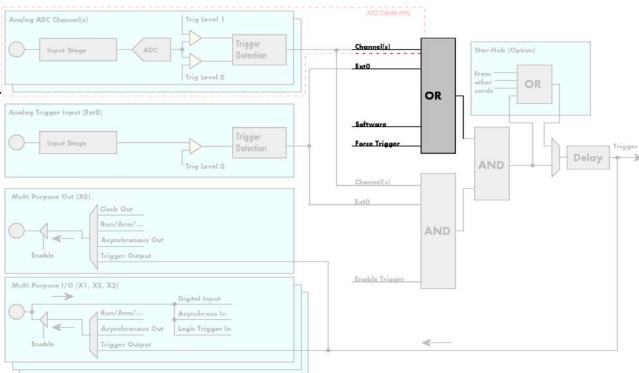
Before the trigger event is finally generated, it is wired through a programmable trigger delay. This trigger delay will also work when used in a synchronized system thus allowing each card to individually delay its trigger recognition.

## Trigger masks

### Trigger OR mask

The purpose of this passage is to explain the trigger OR mask (see left figure) and all the appendant software registers in detail.

The OR mask shown in the overview before as one object, is separated into two parts: a general OR mask for main external trigger (external analog window trigger), the secondary external trigger (external analog comparator trigger, the various PXI triggers (available on M4x PXIe cards only) and software trigger and a channel OR mask.

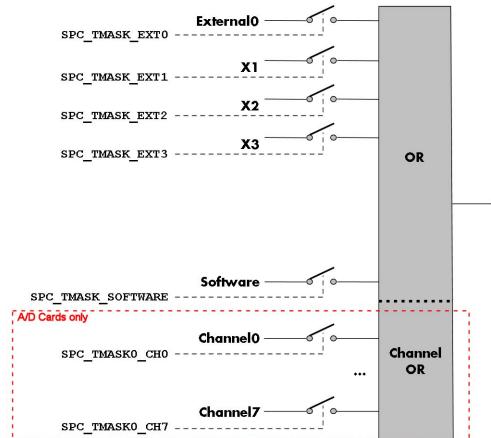


Every trigger source of the M2p series cards is wired to one of the above mentioned OR masks. The user then can program which trigger source will be recognized, and which one won't.

This selection for the general mask is realized with the SPC\_TRIG\_ORMASK register in combination with constants for every possible trigger source.

This selection for the channel mask (A/D cards only) is realized with the SPC\_TRIG\_CHORMASK0 register in combination with constants for every possible channel trigger source.

In either case the sources are coded as a bitfield, so that they can be combined by one access to the driver with the help of a bitwise OR.



The table below shows the relating register for the general OR mask and the possible constants that can be written to it.

Register	Value	Direction	Description
SPC_TRIG_AVAILORMASK	40400	read	Bitmask, in which all bits of the below mentioned sources for the OR mask are set, if available.
SPC_TRIG_ORMASK	40410	read/write	Defines the events included within the trigger OR mask of the card.
SPC_TMASK_NONE	0h		No trigger source selected
SPC_TMASK_SOFTWARE	1h		Enables the software trigger for the OR mask. The card will trigger immediately after start.
SPC_TMASK_EXT0	2h		Enables the external (analog) trigger 0 for the OR mask. The card will trigger if the programmed condition for this input is valid.
SPC_TMASK_EXT1	4h		Enables the X1 (logic) trigger for the OR mask. The card will trigger if the programmed condition for this input is valid.
SPC_TMASK_EXT2	8h		Enables the X2 (logic) trigger for the OR mask. The card will trigger if the programmed condition for this input is valid.
SPC_TMASK_EXT3	10h		Enables the X3 (logic) trigger for the OR mask. The card will trigger if the programmed condition for this input is valid.

**⚠ Please note that as default the SPC\_TRIG\_ORMASK is set to SPC\_TMASK\_SOFTWARE. When not using any trigger mode requiring values in the SPC\_TRIG\_ORMASK register, this mask should explicitly cleared, as otherwise the software trigger will override other modes.**

The following example shows, how to setup the OR mask, for the two external trigger inputs, ORing them together. When using just a single trigger, only this particular trigger must be used in the OR mask register, respectively. As an example a simple edge detection has been chosen for Ext1 input and a window edge detection has been chosen for Ext0 input. The explanation and a detailed description of the different trigger modes for the external trigger inputs will be shown in the dedicated passage within this chapter.

```

spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXT0_LEVEL0, 1800); // External trigger level set to 1.8 V
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXT0_MODE, SPC_TM_POS); // Setting up to detect positive edges

spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXT1_MODE, SPC_TM_NEG); // Setting up X1 logic trigger for falling edges

// Enable both external triggers within the OR mask, by ORing the mask flags together
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK, SPC_TMASK_EXT1 | SPC_TMASK_EXT0);

```

The table below is showing the registers for the channel OR mask (A/D cards only) and the possible constants that can be written to it.

Register	Value	Direction	Description
SPC_TRIG_CH_AVAILORMASKO	40450	read	Bitmask, in which all bits of the below mentioned sources/channels (0...7) for the channel OR mask are set, if available.
SPC_TRIG_CH_ORMASKO	40460	read/write	Includes the analog channels (0...7) within the channel trigger OR mask of the card.
SPC_TMASKO_CH0	00000001h		Enables channel0 for recognition within the channel OR mask.
SPC_TMASKO_CH1	00000002h		Enables channel1 for recognition within the channel OR mask.
SPC_TMASKO_CH2	00000004h		Enables channel2 for recognition within the channel OR mask.
SPC_TMASKO_CH3	00000008h		Enables channel3 for recognition within the channel OR mask.
SPC_TMASKO_CH4	00000010h		Enables channel4 for recognition within the channel OR mask.
SPC_TMASKO_CH5	00000020h		Enables channel5 for recognition within the channel OR mask.
SPC_TMASKO_CH6	00000040h		Enables channel6 for recognition within the channel OR mask.
SPC_TMASKO_CH7	00000080h		Enables channel7 for recognition within the channel OR mask.

The following example shows, how to setup the OR mask for channel trigger. As an example a simple edge detection has been chosen. The explanation and a detailed description of the different trigger modes for the channel trigger modes will be shown in the dedicated passage within this chapter.

```

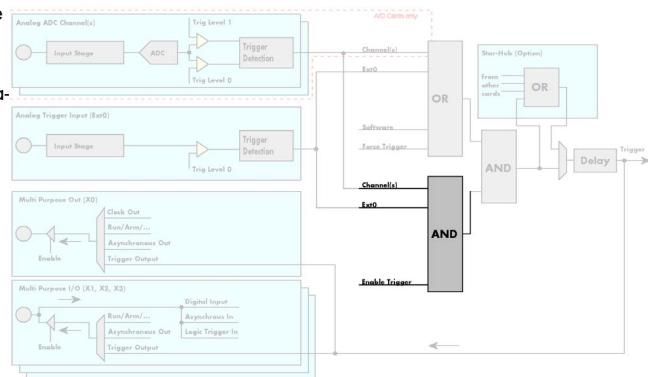
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK, SPC_TMASK_NONE); // disable default software trigger
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_CH_ORMASK0, SPC_TMASK_CH0); // Enable channel0 trigger within the OR mask
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_CH0_LEVEL0, 0); // Trigger level is zero crossing
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_CH0_MODE, SPC_TM_POS); // Setting up channel trigger for rising edges

```

## Trigger AND mask

The purpose of this passage is to explain the trigger AND mask (see left figure) and all the appendant software registers in detail.

The AND mask shown in the overview before as one object, is separated into two parts: a general AND mask for external trigger and software trigger and a channel AND mask.

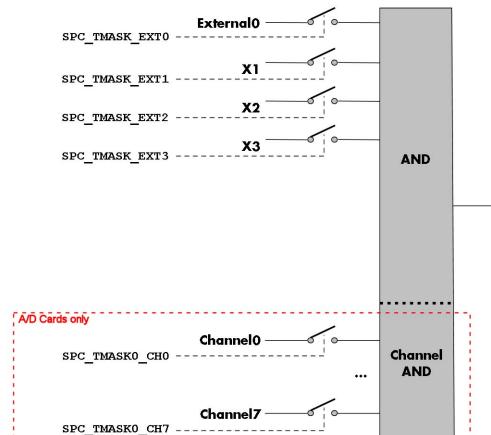


Every trigger source of the M2p series cards except the software trigger is wired to one of the above mentioned AND masks. The user then can program which trigger source will be recognized, and which one won't.

This selection for the general mask is realized with the SPC\_TRIG\_ANDMASK register in combination with constants for every possible trigger source.

This selection for the channel mask (A/D cards only) is realized with the SPC\_TRIG\_CH\_ANDMASKO register in combination with constants for every possible channel trigger source.

In either case the sources are coded as a bitfield, so that they can be combined by one access to the driver with the help of a bitwise OR.



The table below shows the relating register for the general AND mask and the possible constants that can be written to it.

Register	Value	Direction	Description
SPC_TRIG_AVAILANDMASK	40420	read	Bitmask, in which all bits of the below mentioned sources for the AND mask are set, if available.
SPC_TRIG_ANDMASK	40430	read/write	Defines the events included within the trigger AND mask of the card.
SPC_TMASK_NONE	0	No trigger source selected	
SPC_TMASK_EXT0	2h	Enables the external (analog) trigger 0 for the AND mask. The card will trigger if the programmed condition for this input is valid.	
SPC_TMASK_EXT1	4h	Enables the X1 (logic) trigger for the AND mask. The card will trigger if the programmed condition for this input is valid.	
SPC_TMASK_EXT2	8h	Enables the X2 (logic) trigger for the AND mask. The card will trigger if the programmed condition for this input is valid.	
SPC_TMASK_EXT3	10h	Enables the X3 (logic) trigger for the AND mask. The card will trigger if the programmed condition for this input is valid.	

The following example shows, how to setup the AND mask, for an external trigger. As an example a simple high level detection has been chosen. When multiple external triggers shall be combined by AND, both of the external sources must be included in the AND mask register, similar to the OR mask example shown before. The explanation and a detailed description of the different trigger modes for the external trigger inputs will be shown in the dedicated passage within this chapter.

```
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK, SPC_TMASK_NONE); // disable default software trigger
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ANDMASK, SPC_TMASK_EXT0); // Enable external trigger within the AND mask
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXT0_LEVEL0, 2000); // Trigger level is 2.0 V (2000 mV)
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXT0_MODE, SPC_TM_HIGH); // Setting up external trigger for HIGH level
```

The table below is showing the constants for the channel AND mask (A/D cards only) and all the constants for the different channels.

Register	Value	Direction	Description
SPC_TRIG_CH_AVAILANDASK0	40470	read	Bitmask, in which all bits of the below mentioned sources/channels (0...7) for the channel AND mask are set, if available.
SPC_TRIG_CH_ANDMASK0	40480	read/write	Includes the analog or digital channels (0...7) within the channel trigger AND mask of the card.
SPC_TMASK0_CH0	00000001h	Enables channel0 for recognition within the channel OR mask.	
SPC_TMASK0_CH1	00000002h	Enables channel1 for recognition within the channel OR mask.	
SPC_TMASK0_CH2	00000004h	Enables channel2 for recognition within the channel OR mask.	
SPC_TMASK0_CH3	00000008h	Enables channel3 for recognition within the channel OR mask.	
SPC_TMASK0_CH4	00000010h	Enables channel4 for recognition within the channel OR mask.	
SPC_TMASK0_CH5	00000020h	Enables channel5 for recognition within the channel OR mask.	
SPC_TMASK0_CH6	00000040h	Enables channel6 for recognition within the channel OR mask.	
SPC_TMASK0_CH7	00000080h	Enables channel7 for recognition within the channel OR mask.	

The following example shows, how to setup the AND mask for a channel trigger. As an example a simple level detection has been chosen. The explanation and a detailed description of the different trigger modes for the channel trigger modes will be shown in the dedicated passage within this chapter.

```
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK, SPC_TMASK_NONE); // disable default software trigger
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_CH_ANDMASK0, SPC_TMASK_CH0); // Enable channel0 trigger within AND mask
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_CH0_LEVEL0, 0); // channel level to detect is zero level
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_CH0_MODE, SPC_TM_HIGH); // Setting up ch0 trigger for HIGH levels
```

## Software trigger

The software trigger is the easiest way of triggering any Spectrum board. The acquisition or replay of data will start immediately after the card is started and the trigger engine is armed. The resulting delay upon start includes the time the board needs for its setup and the time for recording the pre-trigger area (for acquisition cards).

For enabling the software trigger one simply has to include the software event within the trigger OR mask, as the following table is showing:



Register	Value	Direction	Description
SPC_TRIG_ORMASK	40410	read/write	Defines the events included within the trigger OR mask of the card.
SPC_TMASK_SOFTWARE	1h	Sets the trigger mode to software, so that the recording/replay starts immediately.	

Example for setting up the software trigger:

```
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK, SPC_TMASK_SOFTWARE); // Internal software trigger mode is used
```

## Force- and Enable trigger

In addition to the software trigger (free run) it is also possible to force a trigger event by software while the board is waiting for a real physical trigger event. The forcetrigger command will only have any effect, when the board is waiting for a trigger event. The command for forcing a trigger event is shown in the table below.

Issuing the forcetrigger command will every time only generate one trigger event. If for example using Multiple Recording that will result in only one segment being acquired by forcetrigger. After execution of the forcetrigger command the trigger engine will fall back to the trigger mode that was originally programmed and will again wait for a trigger event.

Register	Value	Direction	Description
SPC_M2CMD	100	write	Command register of the M2i/M3i/M4i/M4x/M2p series cards.
M2CMD_CARD_FORCE_TRIGGER	10h		Forces a trigger event if the hardware is still waiting for a trigger event.

The example shows, how to use the forcetrigger command:

```
spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_CARD_FORCE_TRIGGER); // Force trigger is used.
```

It is also possible to enable (arm) or disable (disarm) the card's whole triggerengine by software. By default the trigger engine is disabled.

Register	Value	Direction	Description
SPC_M2CMD	100	write	Command register of the M2i/M3i/M4i/M4x/M2p series cards.
M2CMD_CARD_ENABLETRIGGER	8h		Enables the trigger engine. Any trigger event will now be recognized.
M2CMD_CARD_DISABLETRIGGER	20h		Disables the trigger engine. No trigger events will be recognized, except force trigger.

The example shows, how to arm and disarm the card's trigger engine properly:

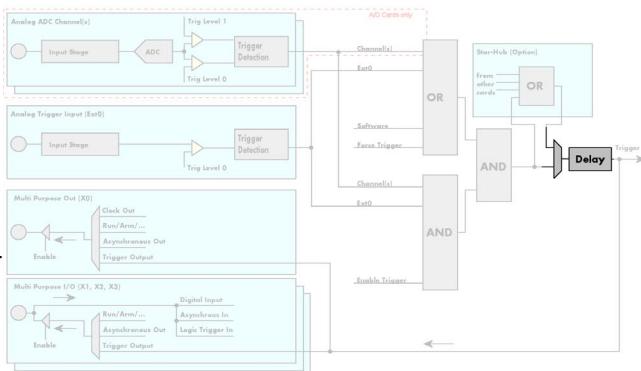
```
spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_CARD_ENABLETRIGGER); // Trigger engine is armed.  
...  
spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_CARD_DISABLETRIGGER); // Trigger engine is disarmed.
```

## Trigger delay

All of the Spectrum M2p series cards allow the user to program an additional trigger delay. As shown in the trigger overview section, this delay is the last element in the trigger chain. Therefore the user does not have to care for the sources when programming the trigger delay.

As shown in the overview the trigger delay is located after the star-hub connection meaning that every M2p card being synchronized can still have its own trigger delay programmed. The Star-Hub will combine the original trigger events before the result is being delayed.

The delay is programmed in samples. The resulting time delay will therefore be [Programmed Delay] / [Sampling Rate].



The following table shows the related register and the possible values. A value of 0 disables the trigger delay.

Register	Value	Direction	Description
SPC_TRIG_AVAILDELAY	40800	read	Contains the maximum available delay as a decimal integer value.
SPC_TRIG_DELAY	40810	read/write	Defines the delay for the detected trigger events.
	0		No additional delay will be added. The resulting internal delay is mentioned in the technical data section.
1...[4G-1] in steps of 1 (16 bit cards)			Defines the additional trigger delay in number of sample clocks. The trigger delay can be programmed up to (4 GSamples - 1) = 4294967295. The stepsize is 1 samples for 16 bit cards.

The example shows, how to use the trigger delay command:

```
spcm_dwSetParam_i64 (hDrv, SPC_TRIG_DELAY, 2000); // A detected trigger event will be  
// delayed for 2000 sample clocks.
```

Using the delay trigger does not affect the ratio between pre trigger and post trigger recorded number of samples, but only shifts the trigger event itself. For changing these values, please take a look in the relating chapter about „Acquisition Modes“.



## Trigger holdoff

All the cards of the Spectrum M2p series allow the user to program a trigger holdoff time when using one of the segmented acquisition or generation modes, such as Multiple Recording/Multiple Replay, ABA Mode (acquisition cards only) or Gated Sampling/Gated Replay. This can be useful when observing and analyzing certain signals that are packetized or bursty in nature.

Using a trigger holdoff will result in an artificially inserted dead-time after each posttrigger area, in which the trigger engine will reject all detected trigger events. The holdoff value is programmed in samples and the resulting holdoff time will therefore be [Programmed Delay] / [Sampling Rate].

The following table shows the related register and the possible values. A value of 0 disables the trigger holdoff.

Register	Value	Direction	Description
SPC_TRIG_AVAILHOLDOFF	40802	read	Contains the maximum available holdoff as a decimal integer value.
SPC_TRIG_HOLDOFF	40811	read/write	Defines the trigger holdoff for the card's trigger engine for segmented modes (Multi, ABA, Gate).
	0		No additional holdoff will be added.
	1...[4G -1] in steps of 1 (16 bit cards)		Defines the trigger holdoff in number of sample clocks. The trigger holdoff can be programmed up to (4 GSamples - 1) = 4294967295. The stepsize is 1 samples for 16 bit cards.

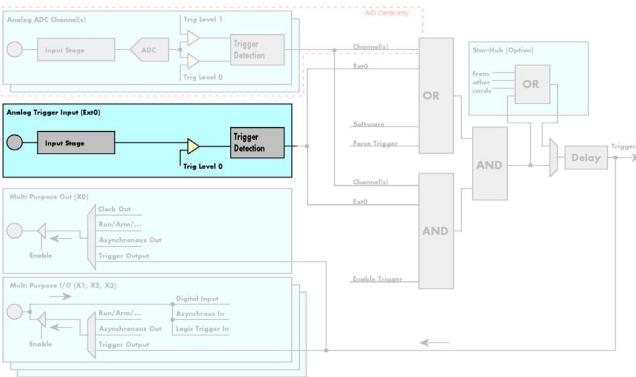
The example shows, how to use the trigger holdoff command:

```
spcm_dwSetParam_i64 (hDrv, SPC_TRIG_HOLDOFF, 2000); // A trigger holdoff is set to 2000
```

## Main analog external trigger (Ext0)

The M2p series has one primary external trigger input consisting of an input stage with programmable either 5 kOhm or 50 Ohm input termination and one comparator that can be programmed in the range of  $\pm 5000$  mV. Using a comparators offers a wide range of different logic levels for the available trigger modes that are support like edge, level.

The external analog trigger can be easily combined with channel trigger or with the additional logic triggers via the multi-purpose I/O lines, when being programmed as an additional external trigger input. The programming of the masks is shown in the chapters above.



## Trigger Mode

Please find the main external (analog) trigger input modes below. A detailed description of the modes follows in the next chapters..

Register	Value	Direction	Description
SPC_TRIG_EXT0_AVAILMODES	40500	read	Bitmask showing all available trigger modes for external 0 (Ext0) = main analog trigger input
SPC_TRIG_EXT0_MODE	40510	read/write	Defines the external trigger mode for the external MMCX connector trigger input. The trigger need to be added to either OR or AND mask input to be activated.
SPC_TM_NONE	00000000h		Channel is not used for trigger detection. This is as with the trigger masks another possibility for disabling channels.
SPC_TM_POS	00000001h		Trigger detection for positive edges (crossing level 0 from below to above)
SPC_TM_NEG	00000002h		Trigger detection for negative edges (crossing level 0 from above to below)
SPC_TM_BOTH	00000004h		Trigger detection for positive and negative edges (any crossing of level 0)
SPC_TM_HIGH	00000008h		Trigger detection for HIGH levels (signal above level 0)
SPC_TM_LOW	00000010h		Trigger detection for LOW levels (signal below level 0)
SPC_TM_POS   SPC_TM_PW_GREATER	4000001h		Sets the trigger mode for external trigger to detect HIGH pulses that are longer than a programmed pulsewidth.
SPC_TM_POS   SPC_TM_PW_SMALLER	2000001h		Sets the trigger mode for external trigger to detect HIGH pulses that are shorter than a programmed pulsewidth.
SPC_TM_NEG   SPC_TM_PW_GREATER	4000002h		Sets the trigger mode for external trigger to detect LOW pulses that are longer than a programmed pulsewidth.
SPC_TM_NEG   SPC_TM_PW_SMALLER	2000002h		Sets the trigger mode for external trigger to detect LOW pulses that are shorter than a programmed pulsewidth.

For all external edge and level trigger modes, the OR mask must contain the corresponding input, as the following table shows:

Register	Value	Direction	Description
SPC_TRIG_ORMASK	40410	read/write	Defines the OR mask for the different trigger sources.
SPC_TMASK_EXT1	4h		Enable secondary external trigger input for the OR mask

## Trigger Input Termination

The external trigger input is a high impedance input with 5 kOhm termination against GND. It is possible to program a 50 Ohm termination by software to terminate fast trigger signals correctly. If you enable the termination, please make sure, that your trigger source is capable to deliver the needed current. Please check carefully whether the source is able to fulfill the trigger input specification given in the technical data section.

Register	Value	Direction	Description
SPC_TRIG_TERM	40110	read/write	A „1“ sets the 50 Ohm termination for external trigger signals. A „0“ sets the high impedance termination

Please note that the signal levels will drop by 50% if using the 50 Ohm termination and your source also has 50 Ohm output impedance (both terminatiors will then work as a 1:2 divider). In that case it will be necessary to reprogram the trigger levels to match the new signal levels. In case of problems receiving a trigger please check the signal level of your source while connected to the terminated input.

## Trigger level

All of the external (analog) trigger modes listed above require a trigger level to be set (except SPC\_TM\_NONE of course). The meaning of the trigger levels is depending on the selected mode and can be found in the detailed trigger mode description that follows.

Trigger level for the external (analog) trigger is to be programmed in mV:

Register	Value	Direction	Description	Range
SPC_TRIG_EXT_AVAIL0_MIN	42340	read	returns the minimum trigger level to be programmed in mV	
SPC_TRIG_EXT_AVAIL0_MAX	42341	read	returns the maximum trigger level to be programmed in mV	
SPC_TRIG_EXT_AVAIL0_STEP	42342	read	returns the step size of trigger level to be programmed in mV	
SPC_TRIG_EXT0_LEVEL0	42320	read/write	Trigger level 0 for external trigger Ext0	-5000 mV to +5000 mV

### Detailed description of the external analog trigger modes

For all external analog trigger modes shown below, either the OR mask or the AND must contain the external trigger to activate the external input as trigger source:

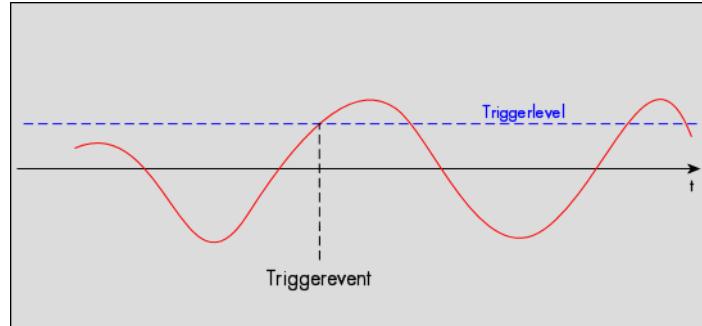
Register	Value	Direction	Description
SPC_TRIG_ORMASK	40410	read/write	Defines the events included within the trigger OR mask of the card.
SPC_TRIG_ANDMASK	40430	read/write	Defines the events included within the trigger AND mask of the card.
SPC_TMASK_EXT0	2h		Enables the main external (analog) trigger 0 for the mask.

The following pages explain the available modes in detail.

#### Trigger on positive edge

The trigger input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the trigger signal from lower values to higher values (rising edge) then the trigger event will be detected.

This edge triggered external trigger mode correspond to the trigger possibilities of usual oscilloscopes.

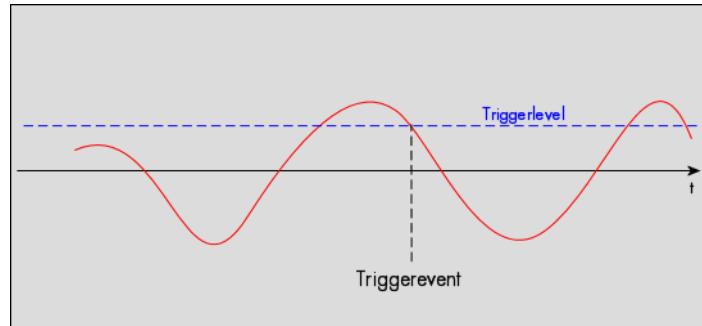


Register	Value	Direction	set to	Value
SPC_TRIG_EXT0_MODE	40510	read/write	SPC_TM_POS	1h
SPC_TRIG_EXT0_LEVEL0	42320	read/write	Set it to the desired trigger level in mV	mV

#### Trigger on negative edge

The trigger input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the trigger signal from higher values to lower values (falling edge) then the trigger event will be detected.

This edge triggered external trigger mode correspond to the trigger possibilities of usual oscilloscopes.

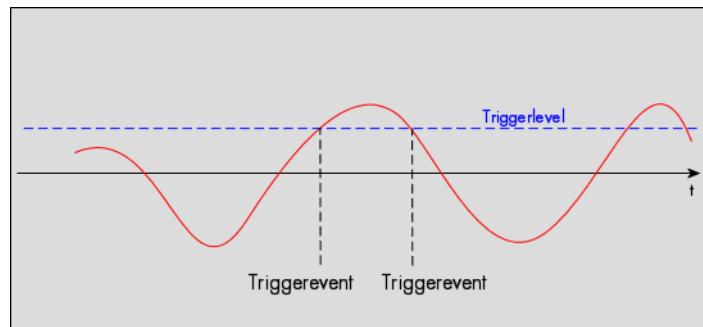


Register	Value	Direction	set to	Value
SPC_TRIG_EXT0_MODE	40510	read/write	SPC_TM_NEG	2h
SPC_TRIG_EXT0_LEVEL0	42320	read/write	Set it to the desired trigger level in mV	mV

### Trigger on positive and negative edge

The trigger input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the trigger signal (either rising or falling edge) the trigger event will be detected.

This edge triggered external trigger mode correspond to the trigger possibilities of usual oscilloscopes.

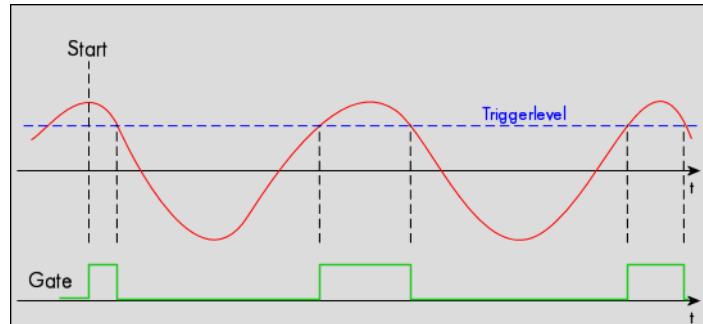


Register	Value	Direction	set to	Value
SPC_TRIG_EXT0_MODE	40510	read/write	SPC_TM_BOTH	4h
SPC_TRIG_EXT0_LEVEL0	42320	read/write	Set it to the desired trigger level in mV	mV

### High level trigger

This trigger mode will generate an internal gate signal that can be useful in conjunction with a second trigger mode to gate that second trigger. If using this mode as a single trigger source the card will detect a trigger event at the time when entering the high level (acting like positive edge trigger) or if the trigger signal is already above the programmed level at the start it will immediately detect a trigger event.

The trigger input is continuously sampled with the selected sample rate. The trigger event will be detected if the trigger input is above the programmed trigger level.

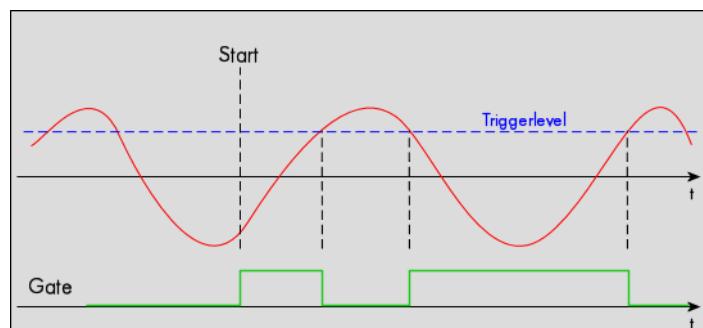


Register	Value	Direction	set to	Value
SPC_TRIG_EXT0_MODE	40510	read/write	SPC_TM_HIGH	00000008h
SPC_TRIG_EXT0_LEVEL0	42320	read/write	Set it to the upper trigger level in mV	mV

### Low level trigger

This trigger mode will generate an internal gate signal that can be useful in conjunction with a second trigger mode to gate that second trigger. If using this mode as a single trigger source the card will detect a trigger event at the time when entering the low level (acting like negative edge trigger) or if the trigger signal is already below the programmed level at the start it will immediately detect a trigger event.

The trigger input is continuously sampled with the selected sample rate. The trigger event will be detected if the trigger input is below the programmed trigger level.

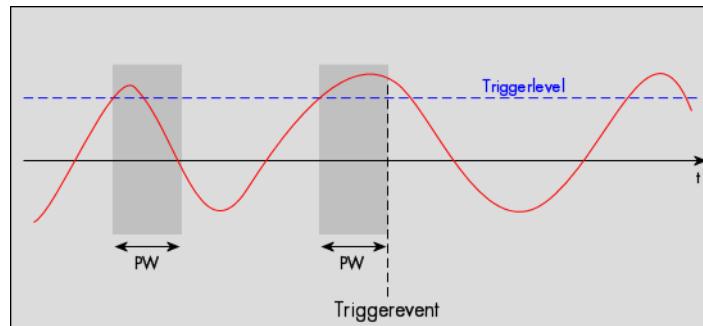


Register	Value	Direction	set to	Value
SPC_TRIG_EXT0_MODE	40510	read/write	SPC_TM_LOW	00000010h
SPC_TRIG_EXT0_LEVEL0	42320	read/write	Set it to the upper trigger level in mV	mV

### **Pulsewidth trigger for long positive pulses**

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal from lower to higher values (rising edge) the pulsewidth counter is started. If the signal crosses the trigger level again in the opposite direction within the the programmed pulselength time, no trigger will be detected. If the pulsewidth counter reaches the programmed amount of samples, without the signal crossing the trigger level in the opposite direction, the triggerevent will be detected.

The pulselength trigger modes for long pulses can be used to prevent the board from triggering on wrong (short) edges in noisy signals.

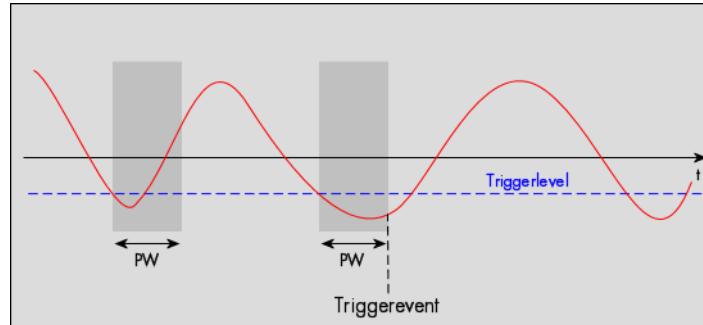


Register	Value	Direction	set to	Value
SPC_TRIG_EXTO_MODE	40510	read/write	SPC_TM_POS   SPC_TM_PW_GREATER	04000001h
SPC_TRIG_EXTO_LEVEL0	42320	read/write	Set it to the desired trigger level in mV	mV
SPC_TRIG_EXTO_PULSEWIDTH	44210	read/write	Sets the pulselength in samples. Values from 2 to [4G -1] are allowed.	2 to [4G -1]

### **Pulsewidth trigger for long negative pulses**

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal from higher to lower values (falling edge) the pulsewidth counter is started. If the signal crosses the trigger level again in the opposite direction within the the programmed pulselength time, no trigger will be detected. If the pulsewidth counter reaches the programmed amount of samples, without the signal crossing the trigger level in the opposite direction, the triggerevent will be detected.

The pulselength trigger modes for long pulses can be used to prevent the board from triggering on wrong (short) edges in noisy signals.

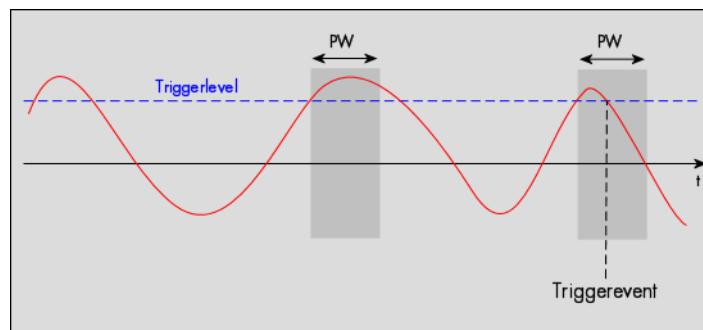


Register	Value	Direction	set to	Value
SPC_TRIG_EXTO_MODE	40510	read/write	SPC_TM_NEG   SPC_TM_PW_GREATER	04000002h
SPC_TRIG_EXTO_LEVEL0	42320	read/write	Set it to the desired trigger level in mV	mV
SPC_TRIG_EXTO_PULSEWIDTH	44210	read/write	Sets the pulselength in samples. Values from 2 to [4G -1] are allowed.	2 to [4G -1]

### **Pulsewidth trigger for short positive pulses**

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal from lower to higher values (rising edge) the pulsewidth counter is started. If the pulsewidth counter reaches the programmed amount of samples, no trigger will be detected.

If the signal does cross the trigger level again within the the programmed pulselength time, a triggerevent will be detected.

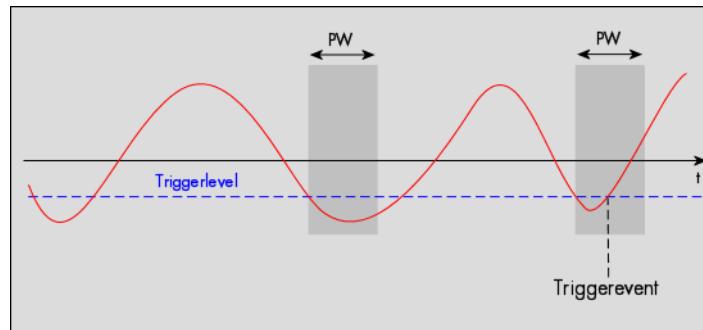


Register	Value	Direction	set to	Value
SPC_TRIG_EXTO_MODE	40510	read/write	SPC_TM_POS   SPC_TM_PW_SMALLER	02000001h
SPC_TRIG_EXTO_LEVEL0	42320	read/write	Set it to the desired trigger level in mV	mV
SPC_TRIG_EXTO_PULSEWIDTH	44210	read/write	Sets the pulselength in samples. Values from 2 to [4G -1] are allowed.	2 to [4G -1]

### Pulsewidth trigger for short negative pulses

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal from higher to lower values (falling edge) the pulsewidth counter is started. If the pulsewidth counter reaches the programmed amount of samples, no trigger will be detected.

If the signal does cross the trigger level again within the the programmed pulsewidth time, a triggerevent will be detected.



Register	Value	Direction	set to	Value
SPC_TRIG_EXT0_MODE	40510	read/write	SPC_TM_NEG   SPC_TM_PW_SMALLER	02000002h
SPC_TRIG_EXT0_LEVEL0	42320	read/write	Set it to the desired trigger level in mV	mV
SPC_TRIG_EXT0_PULSEWIDTH	44210	read/write	Sets the pulsewidth in samples. Values from 2 to [4G -1] are allowed.	2 to [4G -1]

To find out what maximum pulsewidth (in samples) is available, please read out the register shown in the table below:

Register	Value	Direction	Description
SPC_TRIG_EXT_AVAILPULSEWIDTH	44201	read	Contains the maximum possible value for the external trigger pulsewidth counter. Valid for all of the external trigger sources.

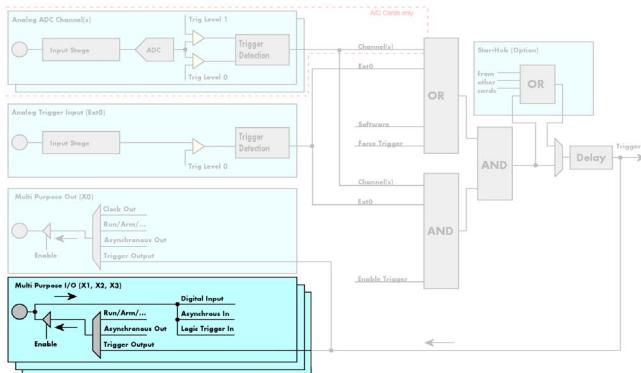
The following example shows, how to setup the card for using pulse width trigger on EXT0 trigger input:

```
// Setting up external X0 TTL trigger to detect low pulses that are below 1500 mV longer than 50 samples ...
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXT0_LEVEL0, 1500);
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXT0_MODE, SPC_TM_NEG | SPC_TM_PW_GREATER);
spcm_dwSetParam_i64 (hDrv, SPC_TRIG_EXT1_PULSEWIDTH, 50);
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK, SPC_TMASK_EXT1); // ... and enable it in OR mask
```

## External logic trigger (X1, X2, X3)

The three multi purpose I/O lines of the M2p series can be set up as additional logic (TTL) triggers.

The external logic triggers can be easily combined with the external analog trigger as well as the channel trigger. The programming of the masks is shown in the chapters above.



## Trigger Mode

Please find the main external (analog) trigger input modes below. A detailed description of the modes follows in the next chapters..

Register	Value	Direction	Description
SPC_TRIG_EXT1_AVAILMODES	40501	read	Bitmask showing all available trigger modes for external 1 (X1) = logic trigger input
SPC_TRIG_EXT2_AVAILMODES	40502	read	Bitmask showing all available trigger modes for external 2 (X2) = logic trigger input
SPC_TRIG_EXT3_AVAILMODES	40503	read	Bitmask showing all available trigger modes for external 3 (X3) = logic trigger input
SPC_TRIG_EXT1_MODE	40511	read/write	Defines the external trigger mode for the external MMCX connector trigger input. The trigger need to be added to either OR or AND mask input to be activated.
SPC_TRIG_EXT2_MODE	40512	read/write	Defines the external trigger mode for the external MMCX connector trigger input. The trigger need to be added to either OR or AND mask input to be activated.
SPC_TRIG_EXT3_MODE	40513	read/write	Defines the external trigger mode for the external MMCX connector trigger input. The trigger need to be added to either OR or AND mask input to be activated.
SPC_TM_NONE	00000000h		Channel is not used for trigger detection. This is as with the trigger masks another possibility for disabling channels.
SPC_TM_POS	00000001h		Sets the trigger mode for external logic (TTL) trigger to detect positive edges.
SPC_TM_NEG	00000002h		Sets the trigger mode for external logic (TTL) trigger to detect negative edges.
SPC_TM_BOTH	00000004h		Sets the trigger mode for external logic (TTL) trigger to detect positive and negative edges
SPC_TM_HIGH	00000008h		Sets the trigger mode for external logic (TTL) trigger to detect HIGH levels.
SPC_TM_LOW	00000010h		Sets the trigger mode for external logic (TTL) trigger to detect LOW levels.
SPC_TM_POS   SPC_TM_PW_GREATER	4000001h		Sets the trigger mode for external logic (TTL) trigger to detect HIGH pulses that are longer than a programmed pulse-width.
SPC_TM_POS   SPC_TM_PW_SMALLER	2000001h		Sets the trigger mode for external logic (TTL) trigger to detect HIGH pulses that are shorter than a programmed pulse-width.
SPC_TM_NEG   SPC_TM_PW_GREATER	4000002h		Sets the trigger mode for external logic (TTL) trigger to detect LOW pulses that are longer than a programmed pulse-width.
SPC_TM_NEG   SPC_TM_PW_SMALLER	2000002h		Sets the trigger mode for external logic (TTL) trigger to detect LOW pulses that are shorter than a programmed pulse-width.

For all external edge and level trigger modes, the OR mask must contain the corresponding input, as the following table shows:

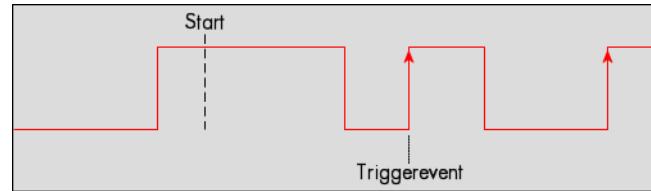
Register	Value	Direction	Description
SPC_TRIG_ORMASK	40410	read/write	Defines the OR mask for the different trigger sources.
SPC_TMASK_EXT1	4h	Enable logic trigger X1 input for the OR mask	
SPC_TMASK_EXT2	8h	Enable logic trigger X2 input for the OR mask	
SPC_TMASK_EXT3	10h	Enable logic trigger X3 input for the OR mask	

## **Detailed description of the logic trigger modes**

### **Positive (rising) edge TTL trigger**

This mode is for detecting the rising edges of an external TTL signal. The board will trigger on the first rising edge that is detected after starting the board. The next triggerevent will then be detected, if the actual recording/replay has finished and the board is armed and waiting for a trigger again.

This mode can be combined with the pulse strech feature to detect pulses that are shorter than the sample period.



Register	Value	Direction	set to	Value
SPC_TRIG_EXT1_MODE	40511	read/write	SPC_TM_POS	
SPC_TRIG_EXT2_MODE	40512			
SPC_TRIG_EXT3_MODE	40513			1h

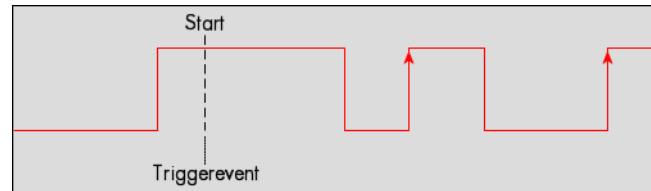
Example on how to set up the board for positive TTL trigger:

```
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXT0_MODE, SPC_TM_POS); // Set up ext. TTL trigger to detect positive edges
```

### **HIGH level TTL trigger**

This mode is for detecting the HIGH levels of an external TTL signal. The board will trigger on the first HIGH level that is detected after starting the board. If this condition is fulfilled when the board is started, a trigger event will be detected.

The next triggerevent will then be detected, if the actual recording/replay has finished and the board is armed and waiting for a trigger again.

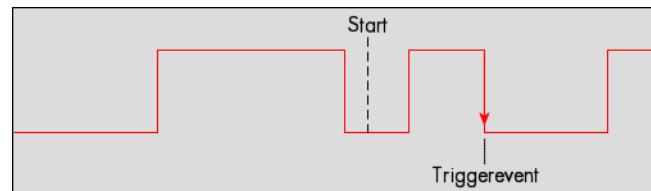


Register	Value	Direction	set to	Value
SPC_TRIG_EXT1_MODE	40511	read/write	SPC_TM_HIGH	
SPC_TRIG_EXT2_MODE	40512			
SPC_TRIG_EXT3_MODE	40513			8h

### **Negative (falling) edge TTL trigger**

This mode is for detecting the falling edges of an external TTL signal. The board will trigger on the first falling edge that is detected after starting the board. The next triggerevent will then be detected, if the actual recording/replay has finished and the board is armed and waiting for a trigger again.

This mode can be combined with the pulse strech feature to detect pulses that are shorter than the sample period.

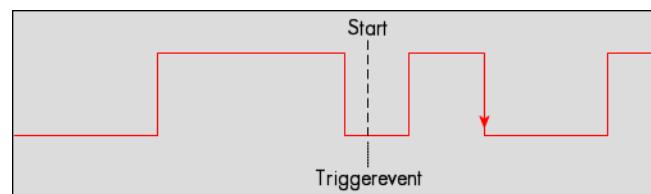


Register	Value	Direction	set to	Value
SPC_TRIG_EXT1_MODE	40511	read/write	SPC_TM_NEG	
SPC_TRIG_EXT2_MODE	40512			
SPC_TRIG_EXT3_MODE	40513			2h

### **LOW level TTL trigger**

This mode is for detecting the LOW levels of an external TTL signal. The board will trigger on the first LOW level that is detected after starting the board. If this condition is fulfilled when the board is started, a trigger event will be detected.

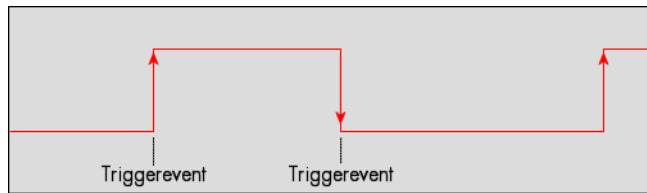
The next triggerevent will then be detected, if the actual recording/replay has finished and the board is armed and waiting for a trigger again.



Register	Value	Direction	set to	Value
SPC_TRIG_EXT1_MODE	40511	read/write	SPC_TM_LOW	
SPC_TRIG_EXT2_MODE	40512			
SPC_TRIG_EXT3_MODE	40513			10h

### **Positive (rising) and negative (falling) edges TTL trigger**

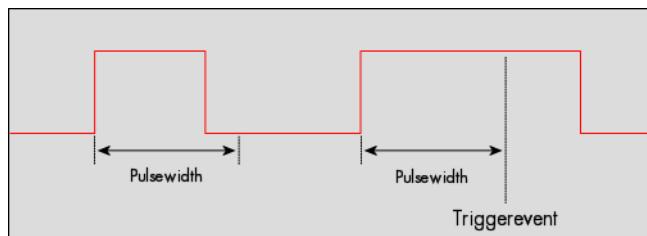
This mode is for detecting the rising and falling edges of an external TTL signal. The board will trigger on the first rising or falling edge that is detected after starting the board. The next trigger-event will then be detected, if the actual recording/replay has finished and the board is armed and waiting for a trigger again.



Register	Value	Direction	set to	Value
SPC_TRIG_EXT1_MODE	40511	read/write	SPC_TM_BOTH	
SPC_TRIG_EXT2_MODE	40512			4h
SPC_TRIG_EXT3_MODE	40513			

### **TTL pulselength trigger for long HIGH pulses**

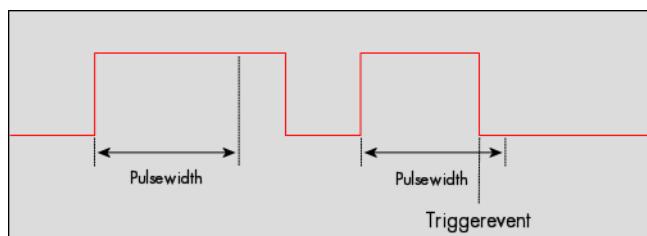
This mode is for detecting HIGH pulses of an external TTL signal that are longer than a programmed pulselength. If the pulse is shorter than the programmed pulselength, no trigger will be detected. The board will trigger on the first pulse matching the trigger condition after starting the board. The next triggerevent will then be detected, if the actual recording/replay has finished and the board is armed and waiting for a trigger again.



Register	Value	Direction	set to	Value
SPC_TRIG_EXT1_PULSEWIDTH	44211	read/write	Sets the pulselength in samples.	2 up to [4G-1]
SPC_TRIG_EXT2_PULSEWIDTH	44212			
SPC_TRIG_EXT3_PULSEWIDTH	44213			
SPC_TRIG_EXT1_MODE	40511	read/write	(SPC_TM_POS   SPC_TM_PW_GREATER)	4000001h
SPC_TRIG_EXT2_MODE	40512			
SPC_TRIG_EXT3_MODE	40513			

### **TTL pulselength trigger for short HIGH pulses**

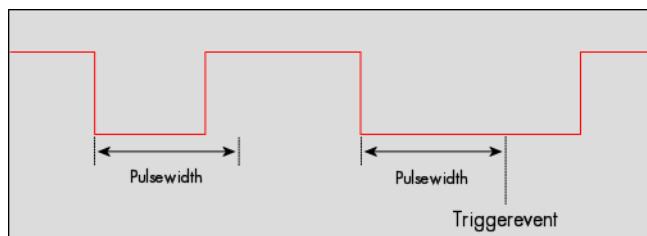
This mode is for detecting HIGH pulses of an external TTL signal that are shorter than a programmed pulselength. If the pulse is longer than the programmed pulselength, no trigger will be detected. The board will trigger on the first pulse matching the trigger condition after starting the board. The next triggerevent will then be detected, if the actual recording/replay has finished and the board is armed and waiting for a trigger again.



Register	Value	Direction	set to	Value
SPC_TRIG_EXT1_PULSEWIDTH	44211	read/write	Sets the pulselength in samples.	2 up to [4G-1]
SPC_TRIG_EXT2_PULSEWIDTH	44212			
SPC_TRIG_EXT3_PULSEWIDTH	44213			
SPC_TRIG_EXT1_MODE	40511	read/write	(SPC_TM_POS   SPC_TM_PW_SMALLER)	2000001h
SPC_TRIG_EXT2_MODE	40512			
SPC_TRIG_EXT3_MODE	40513			

### **TTL pulselength trigger for long LOW pulses**

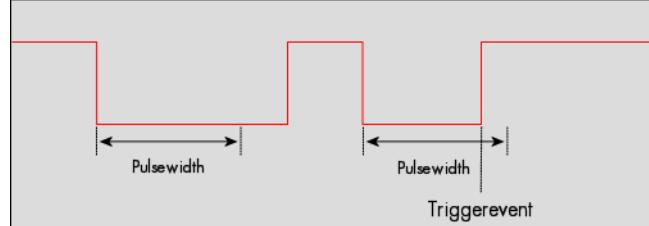
This mode is for detecting LOW pulses of an external TTL signal that are longer than a programmed pulselength. If the pulse is shorter than the programmed pulselength, no trigger will be detected. The board will trigger on the first pulse matching the trigger condition after starting the board. The next triggerevent will then be detected, if the actual recording/replay has finished and the board is armed and waiting for a trigger again.



Register	Value	Direction	set to	Value
SPC_TRIG_EXT1_PULSEWIDTH	44211	read/write	Sets the pulsewidth in samples.	2 up to [4G-1]
SPC_TRIG_EXT2_PULSEWIDTH	44212			
SPC_TRIG_EXT3_PULSEWIDTH	44213			
SPC_TRIG_EXT1_MODE	40511	read/write	(SPC_TM_NEG   SPC_TM_PW_GREATER)	4000002h
SPC_TRIG_EXT2_MODE	40512			
SPC_TRIG_EXT3_MODE	40513			

### TTL pulselength trigger for short LOW pulses

This mode is for detecting LOW pulses of an external TTL signal that are shorter than a programmed pulselength. If the pulse is longer than the programmed pulselength, no trigger will be detected. The board will trigger on the first pulse matching the trigger condition after starting the board. The next triggerevent will then be detected, if the actual recording/replay has finished and the board is armed and waiting for a trigger again.



Register	Value	Direction	set to	Value
SPC_TRIG_EXT1_PULSEWIDTH	44211	read/write	Sets the pulselength in samples.	2 up to [4G-1]
SPC_TRIG_EXT2_PULSEWIDTH	44212			
SPC_TRIG_EXT3_PULSEWIDTH	44213			
SPC_TRIG_EXT1_MODE	40511	read/write	(SPC_TM_NEG   SPC_TM_PW_SMALLER)	2000002h
SPC_TRIG_EXT2_MODE	40512			
SPC_TRIG_EXT3_MODE	40513			

The following example shows, how to setup the card for using external TTL pulse width trigger on EXT1 (X1) input:

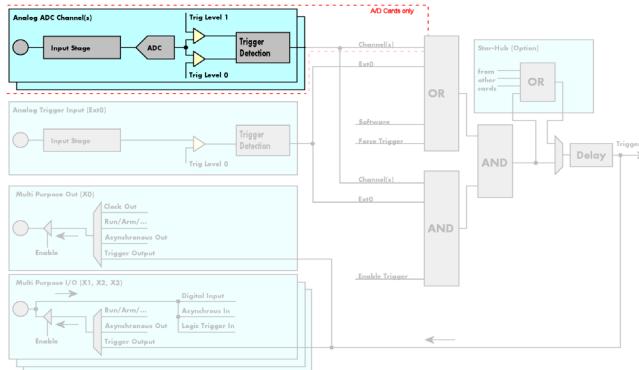
```
// Setting up external X1 TTL trigger to detect low pulses that are longer than 50 samples ...
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXT1_MODE, SPC_TM_NEG | SPC_TM_PW_GREATER);
spcm_dwSetParam_i64 (hDrv, SPC_TRIG_EXT1_PULSEWIDTH , 50);
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK,
                     SPC_TMASK_EXT1); // ... and enable it in OR mask
```

To find out what maximum pulselength (in samples) is available, please read out the register shown in the table below:

Register	Value	Direction	Description
SPC_TRIG_EXT_AVAILPULSEWIDTH	44201	read	Contains the maximum possible value for the external trigger pulselength counter. Valid for all of the external trigger sources.

## Channel Trigger

### Overview of the channel trigger registers



The channel trigger modes are the most common modes, compared to external equipment like oscilloscopes. The huge variety of different channel trigger modes enable you to observe nearly any part of the analog signal. This chapter is about to explain the different modes in detail. To enable the channel trigger, you have to set the channel triggermode register accordingly. Therefore you have to choose, if you either want only one channel to be the trigger source, or if you want to combine two or more channels to a logical OR or a logical AND trigger.

For all channel trigger modes, the OR mask must contain the corresponding input channels (channel 0 taken as example here):

Register	Value	Direction	Description
SPC_TRIG_CH_ORMASK0	40460	read/write	Defines the OR mask for the channel trigger sources.
SPC_TMASK0_CH0	1h		Enables channel0 input for the channel OR mask

The following table shows the according registers for the two general channel trigger modes. It lists the maximum of the available channel mode registers for your card's series. So it can be that you have less channels installed on your specific card and therefore have less valid channel mode registers. If you try to set a channel, that is not installed on your specific card, an error message will be returned.

Register	Value	Direction	Description
SPC_TRIG_CH_AVAILMODES	40600	read	Bitmask, in which all bits of the below mentioned modes for the channel trigger are set, if available.
SPC_TRIG_CH0_MODE	40610	read/write	Sets the trigger mode for channel 0. Channel 0 must be enabled in the channel OR/AND mask.
SPC_TRIG_CH1_MODE	40611	read/write	Sets the trigger mode for channel 1. Channel 1 must be enabled in the channel OR/AND mask.
SPC_TRIG_CH2_MODE	40612	read/write	Sets the trigger mode for channel 2. Channel 2 must be enabled in the channel OR/AND mask.
SPC_TRIG_CH3_MODE	40613	read/write	Sets the trigger mode for channel 3. Channel 3 must be enabled in the channel OR/AND mask.
SPC_TRIG_CH4_MODE	40614	read/write	Sets the trigger mode for channel 4. Channel 4 must be enabled in the channel OR/AND mask.
SPC_TRIG_CH4_MODE	40615	read/write	Sets the trigger mode for channel 5. Channel 5 must be enabled in the channel OR/AND mask.
SPC_TRIG_CH5_MODE	40616	read/write	Sets the trigger mode for channel 6. Channel 6 must be enabled in the channel OR/AND mask.
SPC_TRIG_CH6_MODE	40617	read/write	Sets the trigger mode for channel 7. Channel 7 must be enabled in the channel OR/AND mask.
SPC_TM_NONE	00000000h		Channel is not used for trigger detection. This is as with the trigger masks another possibility for disabling channels.
SPC_TM_POS	00000001h		Enables the trigger detection for positive edges
SPC_TM_NEG	00000002h		Enables the trigger detection for negative edges
SPC_TM_BOTH	00000004h		Enables the trigger detection for positive and negative edges
SPC_TM_LOW	00000010h		Enables the trigger detection for LOW levels
SPC_TM_HIGH	00000008h		Enables the trigger detection for HIGH levels
SPC_TM_POS   SPC_TM_REARM	01000001h		Trigger detection for positive edges on level 0. Trigger is armed when crossing level 1 to avoid false trigger on noise
SPC_TM_NEG   SPC_TM_REARM	01000002h		Trigger detection for negative edges on level 1. Trigger is armed when crossing level 0 to avoid false trigger on noise
SPC_TM_POS   SPC_TM_PW_GREATER	04000001h		Enables the pulsewidth trigger detection for long positive pulses
SPC_TM_NEG   SPC_TM_PW_GREATER	04000002h		Enables the pulsewidth trigger detection for long negative pulses
SPC_TM_POS   SPC_TM_PW_SMALLER	02000001h		Enables the pulsewidth trigger detection for short positive pulses
SPC_TM_NEG   SPC_TM_PW_SMALLER	02000002h		Enables the pulsewidth trigger detection for short negative pulses
SPC_TM_WINENTER	00000020h		Enables the window trigger for entering signals
SPC_TM_WINLEAVE	00000040h		Enables the window trigger for leaving signals
SPC_TM_INWIN	00000080h		Enables the window trigger for inner signals
SPC_TM_OUTSIDEWIN	00000100h		Enables the window trigger for outer signals
SPC_TM_POS   SPC_TM_HYSTERESIS	20000001h		Enables the trigger detection for positive edges with hysteresis
SPC_TM_NEG   SPC_TM_HYSTERESIS	20000002h		Enables the trigger detection for negative edges with hysteresis
SPC_TM_POS   SPC_TM_REARM   SPC_TM_HYSTERESIS	21000001h		Trigger detection for positive edges with hysteresis on level 0. Trigger is armed when crossing level 1 to avoid false trigger on noise
SPC_TM_NEG   SPC_TM_REARM   SPC_TM_HYSTERESIS	21000002h		Trigger detection for negative edges with hysteresis on level 1. Trigger is armed when crossing level 0 to avoid false trigger on noise
SPC_TM_LOW   SPC_TM_HYSTERESIS	20000010h		Enables the trigger detection for LOW levels with hysteresis
SPC_TM_HIGH   SPC_TM_HYSTERESIS	20000008h		Enables the trigger detection for HIGH levels with hysteresis
SPC_TM_SPIKE	00000200h		Enables the spike trigger mode.

SPC_TM_WINENTER   SPC_TM_PW_GREATER	04000020h	Enables the window trigger for long inner signals
SPC_TM_WINLEAVE   SPC_TM_PW_GREATER	04000040h	Enables the window trigger for long outer signals
SPC_TM_WINENTER   SPC_TM_PW_SMALLER	02000020h	Enables the window trigger for short inner signals
SPC_TM_WINLEAVE   SPC_TM_PW_SMALLER	02000040h	Enables the window trigger for short outer signals

If you want to set up a two channel board to detect only a positive edge on channel 0, you would have to setup the board like the following example. Both of the examples either for the single trigger source and the OR trigger mode do not include the necessary settings for the trigger levels. These settings are detailed described in the following paragraphs.

```
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK, SPC_TMASK_NONE); // disable software trigger
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_CH_ORMASK0, SPC_TMASK0_CH0); // Enable channel 0 in the OR mask
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_CH0_MODE, SPC_TM_POS ); // Set triggermode of channel 0 to positive edge
```

If you want to set up a two channel board to detect a trigger event on either a positive edge on channel 0 or a negative edge on channel 1 you would have to set up your board as the following example shows.

```
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK, SPC_TMASK_NONE); // disable software trigger
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_CH_ORMASK0, SPC_TMASK0_CH0 | SPC_TMASK0_CH1); // Enable channel 0 + 1
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_CH0_MODE, SPC_TM_POS ); // Set triggermode of channel 0 to positive edge
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_CH1_MODE, SPC_TM_NEG ); // Set triggermode of channel 1 to negative edge
```

## Channel trigger level

All of the channel trigger modes listed above require at least one trigger level to be set (except SPC\_TM\_NONE of course). Some modes like the window triggers require even two levels (upper and lower level) to be set.

After the data has been sampled, the upper N data bits are compared with the N bits of the trigger levels. The following table shows the level registers and the possible values they can be set to for your specific card.

As the trigger levels are compared to the digitized data, the trigger levels depend on the channels input range. For every input range available to your board there is a corresponding range of trigger levels. On the different input ranges the possible stepsize for the trigger levels differs as well as the maximum and minimum values. The table further below gives you the absolute trigger levels for your specific card series.

16 bit resolution for the trigger levels:

Register	Value	Direction	Description	Range
SPC_TRIG_CH0_LEVEL0	42200	read/write	Trigger level 0 channel 0: main trigger level / upper level if 2 levels used	-32767 to +32767
SPC_TRIG_CH1_LEVEL0	42201	read/write	Trigger level 0 channel 1: main trigger level / upper level if 2 levels used	-32767 to +32767
SPC_TRIG_CH2_LEVEL0	42202	read/write	Trigger level 0 channel 2: main trigger level / upper level if 2 levels used	-32767 to +32767
SPC_TRIG_CH3_LEVEL0	42203	read/write	Trigger level 0 channel 3: main trigger level / upper level if 2 levels used	-32767 to +32767
SPC_TRIG_CH4_LEVEL0	42204	read/write	Trigger level 0 channel 4: main trigger level / upper level if 2 levels used	-32767 to +32767
SPC_TRIG_CH5_LEVEL0	42205	read/write	Trigger level 0 channel 5: main trigger level / upper level if 2 levels used	-32767 to +32767
SPC_TRIG_CH6_LEVEL0	42206	read/write	Trigger level 0 channel 6: main trigger level / upper level if 2 levels used	-32767 to +32767
SPC_TRIG_CH7_LEVEL0	42207	read/write	Trigger level 0 channel 7: main trigger level / upper level if 2 levels used	-32767 to +32767
SPC_TRIG_CH0_LEVEL1	42300	read/write	Trigger level 1 channel 0: auxiliary trigger level / lower level if 2 levels used	-32767 to +32767
SPC_TRIG_CH1_LEVEL1	42301	read/write	Trigger level 1 channel 1: auxiliary trigger level / lower level if 2 levels used	-32767 to +32767
SPC_TRIG_CH2_LEVEL1	42302	read/write	Trigger level 1 channel 2: auxiliary trigger level / lower level if 2 levels used	-32767 to +32767
SPC_TRIG_CH3_LEVEL1	42303	read/write	Trigger level 1 channel 3: auxiliary trigger level / lower level if 2 levels used	-32767 to +32767
SPC_TRIG_CH4_LEVEL1	42304	read/write	Trigger level 1 channel 4: auxiliary trigger level / lower level if 2 levels used	-32767 to +32767
SPC_TRIG_CH5_LEVEL1	42305	read/write	Trigger level 1 channel 5: auxiliary trigger level / lower level if 2 levels used	-32767 to +32767
SPC_TRIG_CH6_LEVEL1	42306	read/write	Trigger level 1 channel 6: auxiliary trigger level / lower level if 2 levels used	-32767 to +32767
SPC_TRIG_CH7_LEVEL1	42307	read/write	Trigger level 1 channel 7: auxiliary trigger level / lower level if 2 levels used	-32767 to +32767

16bit trigger level representation depending on selected input range

Triggerlevel	Input ranges					
	±200 mV	±500 mV	±1 V	±2 V	±5 V	±10 V
32767	+199.994 mV	+499.985 mV	+999.969 mV	+1999.939 mV	+4999.847 mV	+9999.695 mV
32766	+199.988 mV	+499.969 mV	+999.939 mV	+1999.878 mV	+4998.695 mV	+9999.390 mV
...						
16384	+100.000 mV	+250.000 mV	+500.000 mV	+1000.000 mV	+2500.000 mV	+5000.000 mV
Step size	6.10 µV	15.26 µV	30.52 µV	61.04 µV	152.59 µV	305.18 µV

Triggerlevel	Input ranges					
	±200 mV	±500 mV	±1 V	±2 V	±5 V	±10 V
...						
2	+0.012 mV	+0.031 mV	+0.061 mV	+0.122 mV	+0.305 mV	+0.610 mV
1	+0.006 mV	+0.015 mV	+0.031 mV	+0.061 mV	+0.153 mV	+0.305 mV
0	0 V	0 V	0 V	0 V	0 V	0 V
-1	-0.006 mV	-0.015 mV	-0.031 mV	-0.061 mV	-0.153 mV	-0.305 mV
-2	-0.012 mV	-0.031 mV	-0.061 mV	-0.122 mV	-0.305 mV	-0.610 mV
...						
-16384	-100.000 mV	-250.000 mV	-500.000 mV	-1000.000 mV	-2500.000 mV	-5000.000 V
...						
-32766	-199.988 mV	-499.969 mV	-999.939 mV	-1999.878 mV	-4998.695 mV	-9999.390 mV
-32767	-199.994 mV	-499.985 mV	-999.969 mV	-1999.939 mV	-4999.847 mV	-9999.695 mV
<b>Step size</b>	<b>6.10 µV</b>	<b>15.26 µV</b>	<b>30.52 µV</b>	<b>61.04 µV</b>	<b>152.59 µV</b>	<b>305.18 µV</b>

The following example shows, how to set up a one channel board to trigger on channel 0 with rising edge. It is assumed, that the input range of channel 0 is set to the the ±200 mV range. The decimal value for SPC\_TRIG\_CHO\_LEVEL0 corresponds then with 5.004 mV, which is the resulting trigger level.

```
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK, SPC_TMASK_NONE);           // disable default software trigger
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_CHO_MODE, SPC_TM_POS);               // Setting up channel trig (rising edge)
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_CHO_LEVEL0, 819);                   // Sets 16bit triggerlevel to 5.004 mV
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_CH_ORMASK0, SPC_TMASK0_CHO); // and enable it within the OR mask
```

### **Reading out the number of possible trigger levels**

The Spectrum driver also contains a register that holds the value of the maximum possible different trigger levels considering the above mentioned exclusion of the most negative possible value. This is useful, as new drivers can also be used with older hardware versions, because you can check the trigger resolution during run time. The register is shown in the following table:

Register	Value	Direction	Description
SPC_READTRGLVLCOUNT	2500	r	Contains the number of different possible trigger levels meaning ± of the value.

In case of a board that uses 8 bits for trigger detection the returned value would be 127, as either the zero and 127 positive and negative values are possible. The resulting trigger step width in mV can easily be calculated from the returned value. It is assumed that you know the actually selected input range.

To give you an example on how to use this formula we assume, that the ±1.0 V input range is selected and the board uses 8 bits for trigger detection. The result would be 7.81 mV, which is the step width for your type of board within the actually chosen input range.

$$\text{Trigger step width} = \frac{\text{Input Range}_{\max}}{\text{Number of trigger levels} + 1}$$

$$\text{Trigger step width} = \frac{+1000 \text{ mV}}{127 + 1}$$

## Detailed description of the channel trigger modes

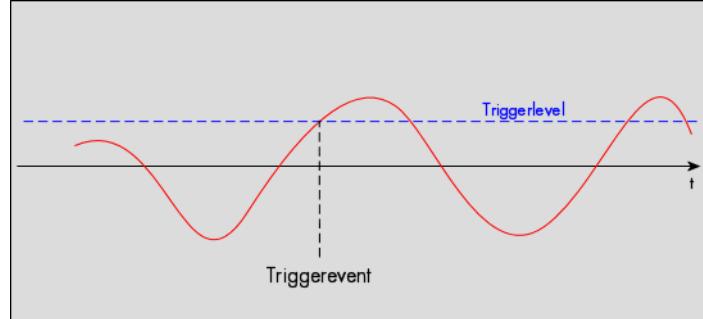
For all channel trigger modes, the OR mask must contain the corresponding input channels (channel 0 taken as example here):.

Register	Value	Direction	Description
SPC_TRIG_CH_ORMASK0	40460	read/write	Defines the OR mask for the channel trigger sources.
SPC_TMASK0_CH0	1h		Enables channel0 input for the channel OR mask

### Channel trigger on positive edge

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal from lower values to higher values (rising edge) then the trigger event will be detected.

These edge triggered channel trigger modes correspond to the trigger possibilities of usual oscilloscopes.

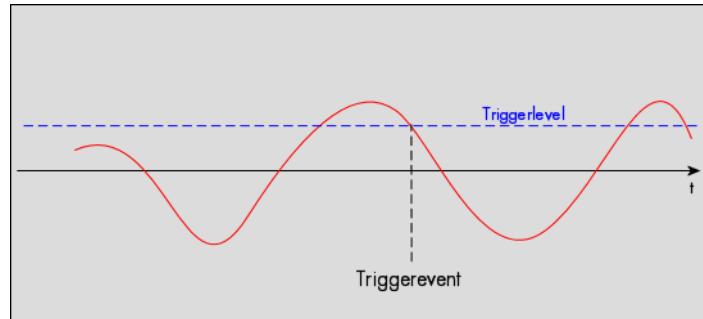


Register	Value	Direction	set to	Value
SPC_TRIG_CH0_MODE	40610	read/write	SPC_TM_POS	1h
SPC_TRIG_CH0_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant

### Channel trigger on negative edge

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal from higher values to lower values (falling edge) then the trigger event will be detected.

These edge triggered channel trigger modes correspond to the trigger possibilities of usual oscilloscopes.

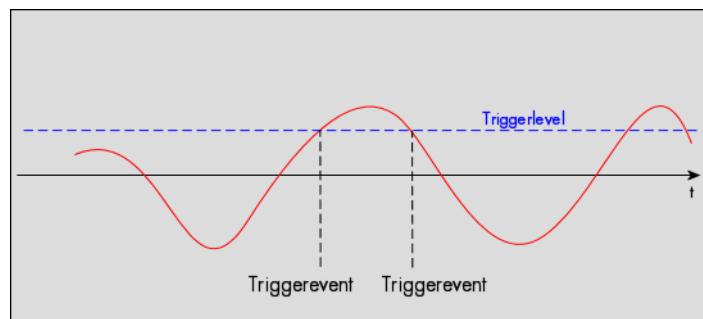


Register	Value	Direction	set to	Value
SPC_TRIG_CH0_MODE	40610	read/write	SPC_TM_NEG	2h
SPC_TRIG_CH0_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant

### Channel trigger on positive and negative edge

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal (either rising or falling edge) the trigger event will be detected.

These edge triggered channel trigger modes correspond to the trigger possibilities of usual oscilloscopes.

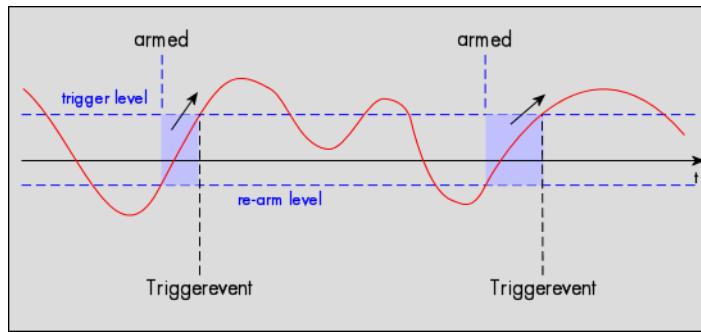


Register	Value	Direction	set to	Value
SPC_TRIG_CH0_MODE	40610	read/write	SPC_TM_BOTH	4h
SPC_TRIG_CH0_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant

### **Channel re-arm trigger on positive edge**

The analog input is continuously sampled with the selected sample rate. If the programmed re-arm level is crossed from lower to higher values, the trigger engine is armed and waiting for trigger. If the programmed trigger level is crossed by the channel's signal from lower values to higher values (rising edge) then the triggerevent will be detected and the trigger engine will be disarmed. A new trigger event is only detected if the trigger engine is armed again.

The re-arm trigger modes can be used to prevent the board from triggering on wrong edges in noisy signals.

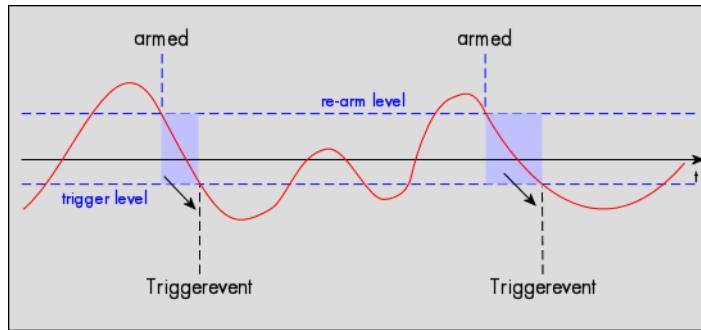


Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_POS   SPC_TM_REARM	01000001h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Defines the re-arm level relatively to the channel's input range	board dependant

### **Channel re-arm trigger on negative edge**

The analog input is continuously sampled with the selected sample rate. If the programmed re-arm level is crossed from higher to lower values, the trigger engine is armed and waiting for trigger. If the programmed trigger level is crossed by the channel's signal from higher values to lower values (falling edge) then the triggerevent will be detected and the trigger engine will be disarmed. A new trigger event is only detected, if the trigger engine is armed again.

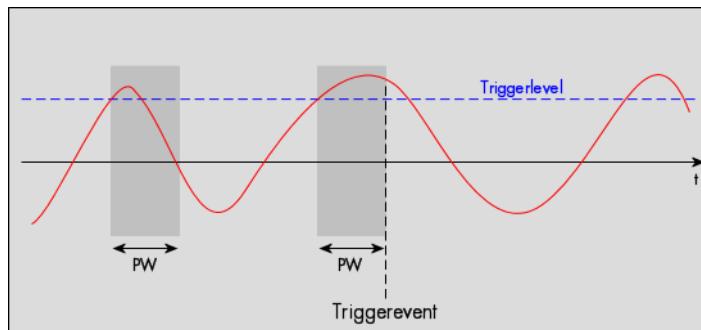
The re-arm trigger modes can be used to prevent the board from triggering on wrong edges in noisy signals.



Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_NEG   SPC_TM_REARM	01000002h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Defines the re-arm level relatively to the channel's input range	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant

### **Channel pulsewidth trigger for long positive pulses**

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal from lower to higher values (rising edge) the pulsewidth counter is started. If the signal crosses the trigger level again in the opposite direction within the programmed pulsewidth time, no trigger will be detected. If the pulsewidth counter reaches the programmed amount of samples, without the signal crossing the trigger level in the opposite direction, the triggerevent will be detected.



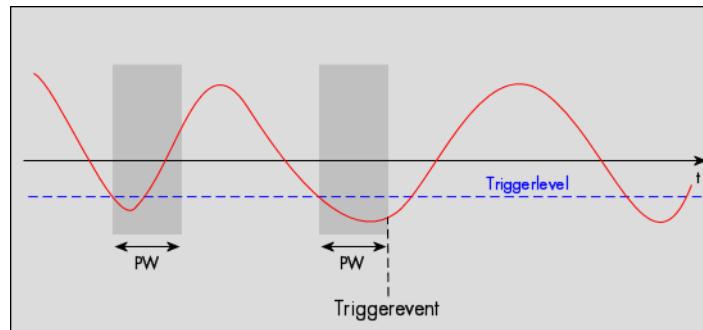
The pulsewidth trigger modes for long pulses can be used to prevent the board from triggering on wrong (short) edges in noisy signals.

Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_POS   SPC_TM_PW_GREATER	04000001h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_PULSEWIDTH	44101	read/write	Sets the pulsewidth in samples. Values from 2 to [4G -1] are allowed.	2 to [4G -1]

### **Channel pulselwidth trigger for long negative pulses**

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal from higher to lower values (falling edge) the pulselwidth counter is started. If the signal crosses the trigger level again in the opposite direction within the the programmed pulselwidth time, no trigger will be detected. If the pulselwidth counter reaches the programmed amount of samples, without the signal crossing the trigger level in the opposite direction, the triggerevent will be detected.

The pulselwidth trigger modes for long pulses can be used to prevent the board from triggering on wrong (short) edges in noisy signals.

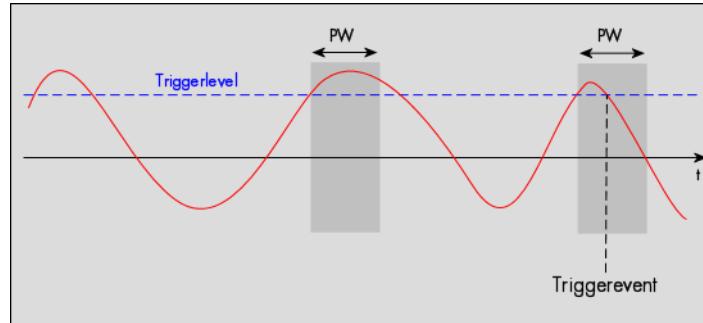


Register	Value	Direction	set to	Value
SPC_TRIG_CH0_MODE	40610	read/write	SPC_TM_NEG   SPC_TM_PW_GREATER	04000002h
SPC_TRIG_CH0_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CH0_PULSEWIDTH	44101	read/write	Sets the pulselwidth in samples. Values from 2 to [4G -1] are allowed.	2 to [4G -1]

### **Channel pulselwidth trigger for short positive pulses**

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal from lower to higher values (rising edge) the pulselwidth counter is started. If the pulselwidth counter reaches the programmed amount of samples, no trigger will be detected.

If the signal does cross the trigger level again within the the programmed pulselwidth time, a triggerevent will be detected.

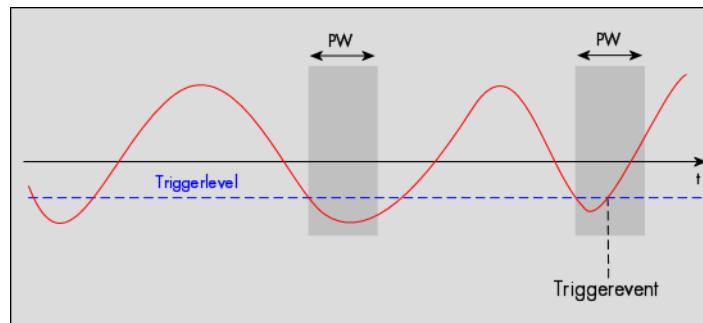


Register	Value	Direction	set to	Value
SPC_TRIG_CH0_MODE	40610	read/write	SPC_TM_POS   SPC_TM_PW_SMALLER	02000001h
SPC_TRIG_CH0_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CH0_PULSEWIDTH	44101	read/write	Sets the pulselwidth in samples. Values from 2 to [4G -1] are allowed.	2 to [4G -1]

### **Channel pulselwidth trigger for short negative pulses**

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal from higher to lower values (falling edge) the pulselwidth counter is started. If the pulselwidth counter reaches the programmed amount of samples, no trigger will be detected.

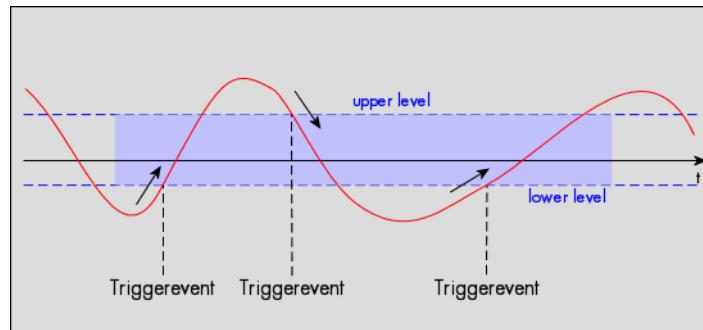
If the signal does cross the trigger level again within the the programmed pulselwidth time, a triggerevent will be detected.



Register	Value	Direction	set to	Value
SPC_TRIG_CH0_MODE	40610	read/write	SPC_TM_NEG   SPC_TM_PW_SMALLER	02000002h
SPC_TRIG_CH0_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CH0_PULSEWIDTH	44101	read/write	Sets the pulselwidth in samples. Values from 2 to [4G -1] are allowed.	2 to [4G -1]

### **Channel window trigger for entering signals**

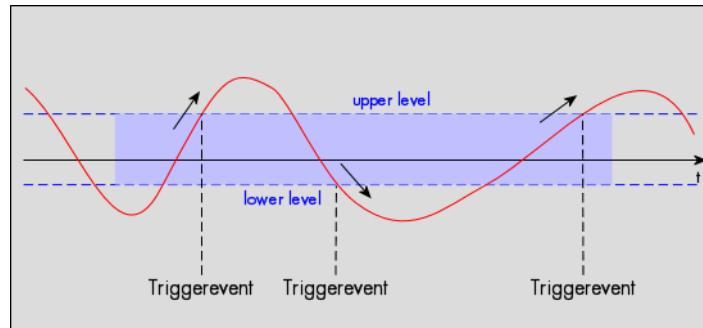
The analog input is continuously sampled with the selected sample rate. The upper and the lower level define a window. Every time the signal enters the window from the outside, a triggerevent will be detected.



Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_WINENTER	00000020h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the upper trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Set it to the lower trigger level relatively to the channel's input range.	board dependant

### **Channel window trigger for leaving signals**

The analog input is continuously sampled with the selected sample rate. The upper and the lower level define a window. Every time the signal leaves the window from the inside, a triggerevent will be detected.

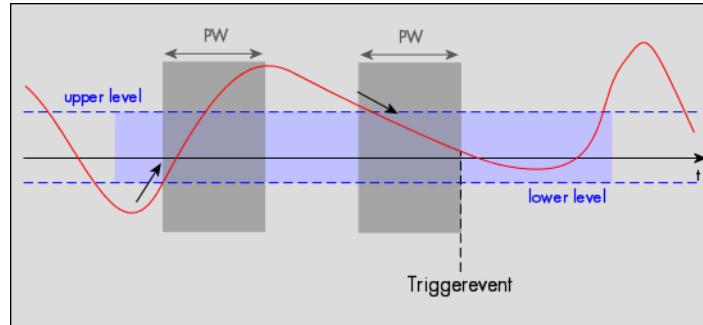


Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_WINLEAVE	00000040h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the upper trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Set it to the lower trigger level relatively to the channel's input range.	board dependant

### **Channel window trigger for long inner signals**

The analog input is continuously sampled with the selected sample rate. The upper and the lower levels define a window. Every time the signal enters the window from the outside, the pulsewidth counter is started. If the signal leaves the window before the pulsewidth counter has stopped, no trigger will be detected.

If the pulsewidth counter stops and the signal is still inside the window, the triggerevent will be detected.

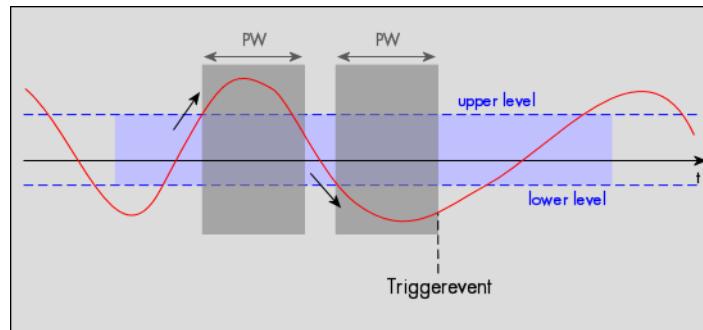


Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_WINENTER   SPC_TM_PW_GREATER	04000020h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the upper trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Set it to the lower trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_PULSEWIDTH	44101	read/write	Sets the pulsewidth in samples. Values from 2 to [4G -1] are allowed.	2 to [4G -1]

### Channel window trigger for long outer signals

The analog input is continuously sampled with the selected sample rate. The upper and the lower levels define a window. Every time the signal leaves the window from the inside, the pulselength counter is started. If the signal enters the window before the pulselength counter has stopped, no trigger will be detected.

If the pulselength counter stops and the signal is still outside the window, the trigger event will be detected.

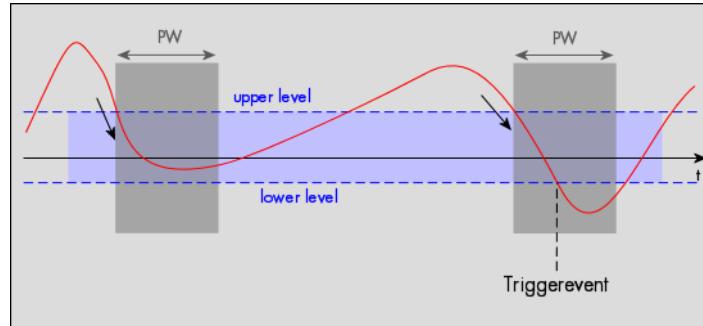


Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_WINLEAVE   SPC_TM_PW_GREATER	04000040h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the upper trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Set it to the lower trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_PULSEWIDTH	44101	read/write	Sets the pulselength in samples. Values from 2 to [4G -1] are allowed.	2 to [4G -1]

### Channel window trigger for short inner signals

The analog input is continuously sampled with the selected sample rate. The upper and the lower levels define a window. Every time the signal enters the window from the outside, the pulselength counter is started. If the pulselength counter stops and the signal is still inside the window, no trigger will be detected.

If the signal leaves the window before the pulselength counter has stopped, the trigger event will be detected.

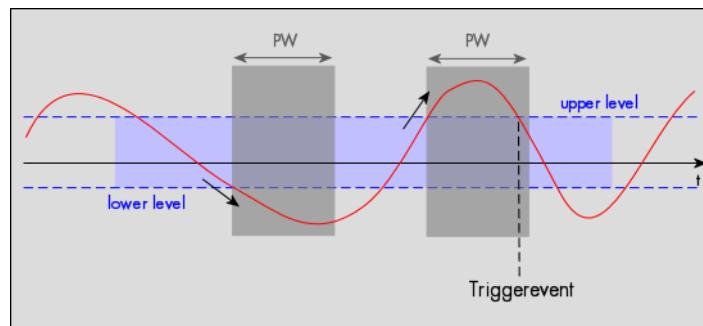


Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_WINENTER   SPC_TM_PW_SMALLER	02000020h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the upper trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Set it to the lower trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_PULSEWIDTH	44101	read/write	Sets the pulselength in samples. Values from 2 to [4G -1] are allowed.	2 to [4G -1]

### Channel window trigger for short outer signals

The analog input is continuously sampled with the selected sampling rate. The upper and the lower levels define a window. Every time the signal leaves the window from the inside, the pulselength counter is started. If the pulselength counter stops and the signal is still outside the window, no trigger will be detected.

If the signal enters the window before the pulselength counter has stopped, the trigger event will be detected.



Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_WINLEAVE   SPC_TM_PW_SMALLER	02000040h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the upper trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Set it to the lower trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_PULSEWIDTH	44101	read/write	Sets the pulselength in samples. Values from 2 to [4G -1] are allowed.	2 to [4G -1]

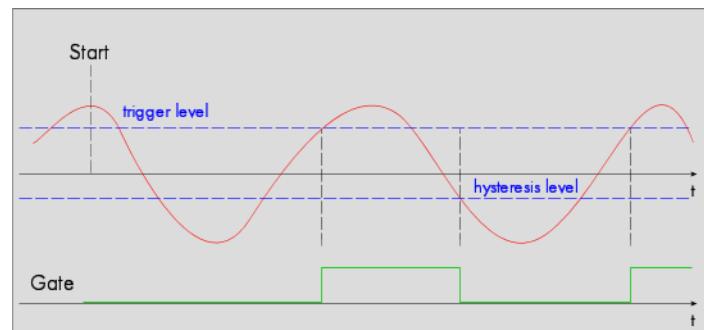
### **Channel hysteresis trigger on positive edge**

This trigger mode will generate an internal gate signal that can be useful for masking a second trigger event generated by a different mode. The analog input is continuously sampled with the selected sample rate.

If the programmed trigger level is crossed by the channel's signal from lower values to higher values (rising edge) the gate starts.

When the signal crosses the programmed hysteresis level from higher values to lower values (falling edge) then the gate will stop.

As this mode is purely edge-triggered, the high level at the cards start time does not trigger the board.



Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_POS   SPC_TM_HYSTERESIS	20000001h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Defines the hysteresis level relatively to the channel's input range	board dependant

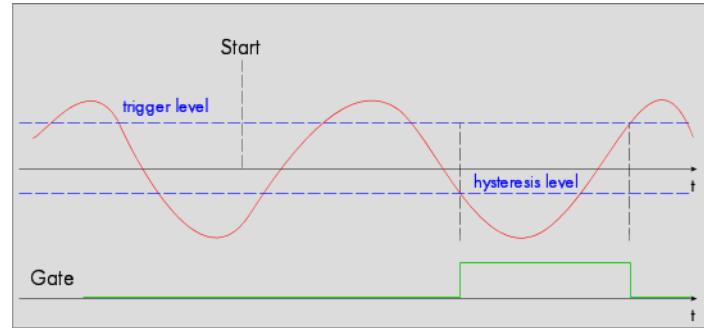
### **Channel hysteresis trigger on negative edge**

This trigger mode will generate an internal gate signal that can be useful for masking a second trigger event generated by a different mode. The analog input is continuously sampled with the selected sample rate.

If the programmed trigger level is crossed by the channel's signal higher values to lower values (falling edge) the gate starts.

When the signal crosses the programmed hysteresis level from lower values to higher values (rising edge) then the gate will stop.

As this mode is purely edge-triggered, the low level at the cards start time does not trigger the board.

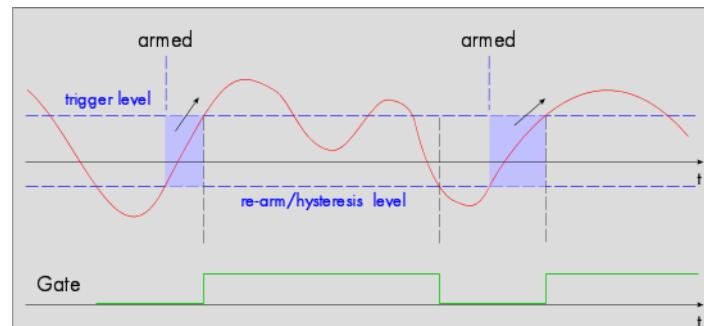


Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_NEG   SPC_TM_HYSTERESIS	20000002h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Defines the hysteresis level relatively to the channel's input range	board dependant

### **Channel re-arm hysteresis trigger on positive edge**

This trigger mode will generate an internal gate signal that can be useful for masking a second trigger event generated by a different mode. The analog input is continuously sampled with the selected sample rate.

If the programmed re-arm/hysteresis level is crossed from lower to higher values, the trigger engine is armed and waiting for trigger. If the programmed trigger level is crossed by the channel's signal from lower values to higher values (rising edge) then the gate starts and the trigger engine will be disarmed. If the programmed re-arm/hysteresis level is crossed by the channel's signal from higher values to lower values (falling edge) the gate stops.



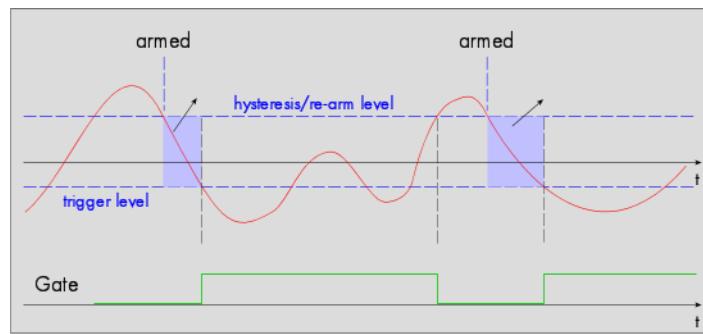
A new trigger event is only detected, if the trigger engine is armed again. The re-arm trigger modes can be used to prevent the board from triggering on wrong edges in noisy signals.

Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_POS   SPC_TM_REARM   SPC_TM_HYSTERESIS	21000001h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Defines the re-arm and hysteresis level relatively to the channel's input range	board dependant

### **Channel re-arm hysteresis trigger on negative edge**

This trigger mode will generate an internal gate signal that can be useful for masking a second trigger event generated by a different mode. The analog input is continuously sampled with the selected sample rate.

If the programmed re-arm/hysteresis level is crossed from higher to lower values, the trigger engine is armed and waiting for trigger. If the programmed trigger level is crossed by the channel's signal from higher values to lower values (falling edge) then the gate starts and the trigger engine will be disarmed. If the programmed re-arm/hysteresis level is crossed by the channel's signal from lower values to higher values (rising edge) the gate stops.



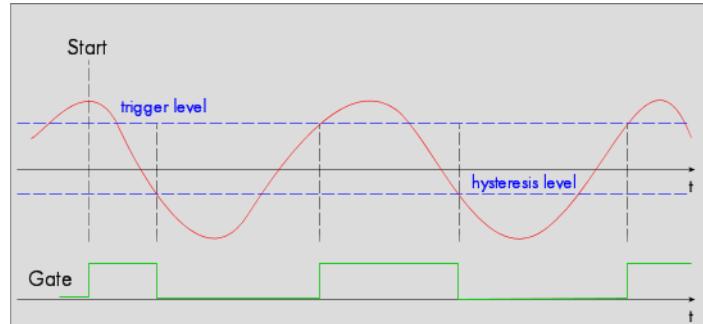
A new trigger event is only detected, if the trigger engine is armed again. The re-arm trigger modes can be used to prevent the board from triggering on wrong edges in noisy signals.

Register	Value	Direction	set to	Value
SPC_TRIG_CH0_MODE	40610	read/write	SPC_TM_NEG   SPC_TM_REARM   SPC_TM_HYSTERESIS	21000002h
SPC_TRIG_CH0_LEVEL0	42200	read/write	Defines the trigger level relatively to the channel's input range	board dependant
SPC_TRIG_CH0_LEVEL1	42300	read/write	Defines the re-arm and hysteresis level relatively to the channel's input range	board dependant

### **High level hysteresis trigger**

This trigger mode will generate an internal gate signal that can be useful for masking a second trigger event generated by a different mode. The analog input is continuously sampled with the selected sample rate.

If the signal is equal or higher than the programmed trigger level the gate starts.



When the signal is lower than the programmed hysteresis level the gate will stop.

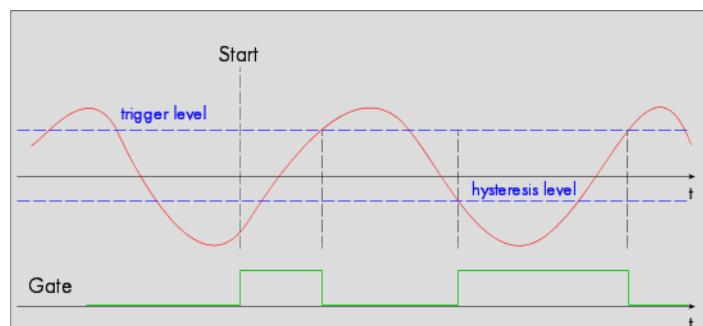
As this mode is level-triggered, the high level at the cards start time does trigger the board.

Register	Value	Direction	set to	Value
SPC_TRIG_CH0_MODE	40610	read/write	SPC_TM_HIGH   SPC_TM_HYSTERESIS	20000008h
SPC_TRIG_CH0_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CH0_LEVEL1	42300	read/write	Defines the hysteresis level relatively to the channel's input range	board dependant

### **Low level hysteresis trigger**

This trigger mode will generate an internal gate signal that can be useful for masking a second trigger event generated by a different mode. The analog input is continuously sampled with the selected sample rate.

If the signal is equal or lower than the programmed trigger level the gate starts.



When the signal is higher than the programmed hysteresis level the gate will stop.

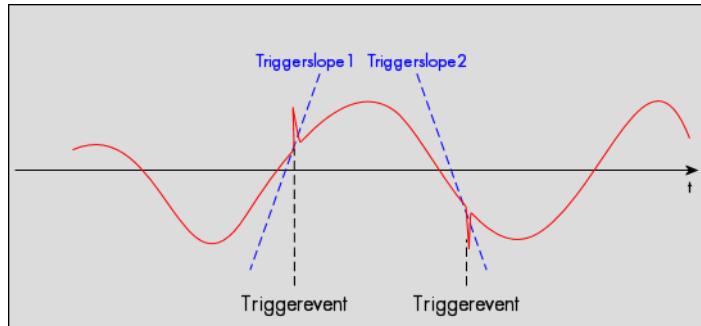
As this mode is level-triggered, the high level at the cards start time does trigger the board.

Register	Value	Direction	set to	Value
SPC_TRIG_CH0_MODE	40610	read/write	SPC_TM_LOW   SPC_TM_HYSTERESIS	20000010h
SPC_TRIG_CH0_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CH0_LEVEL1	42300	read/write	Defines the hysteresis level relatively to the channel's input range	board dependant

### **Channel spike trigger (slope trigger)**

The analog input is continuously sampled with the selected sampling rate. If the difference between two samples is higher than the programmed value (in either positive or negative direction) the trigger event will be detected.

This slope triggered channel trigger mode is ideally suited for monitoring of power supply lines and triggering on noise or spikes.



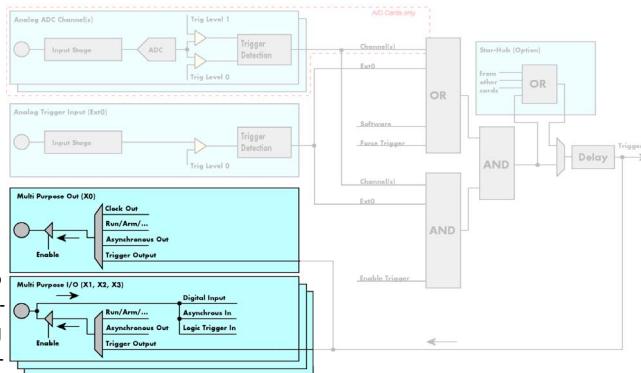
Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_SPIKE	200h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set the difference between two samples relatively to the channel's input range for positive slopes.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Set the difference between two samples relatively to the channel's input range for negative slopes.	board dependant

## Multi Purpose I/O Lines

### Standard I/O lines (X0, X1, X2, X3)

The cards of the M2p series and the related digitizerNETBOX and generatorNETBOX products have four multi purpose lines. Three of these are multi purpose I/O lines (X1, X2, X3) as well as one multi purpose output (X0). These lines can be used for a wide variety of functions to help the interconnection with external equipment. The functionality of these multi purpose lines can be software programmed and each of these lines can either be used for input (X1, X2, X3 only) or output.

The multi purpose I/O lines may be used as status outputs such as trigger output or internal arm/run as well as for asynchronous I/O to control external equipment as well as additional digital input or output lines that are sampled or replayed synchronously with the analog data. The three input lines can also be used as additional logic trigger inputs, as described in the external trigger chapter.



The multi purpose I/O lines are available on the front plate and labeled with X0 (line 0), X1 (line 1), X2 (line 2) and X3 (line 3). As default these lines are switched off.



**Please be careful when programming these lines as an output whilst maybe still being connected with an external signal source, as that may damage components either on the external equipment or on the card itself.**

### Programming the behavior

Each multi purpose I/O line can be individually programmed. Please check the available modes by reading the SPCM\_X0\_AVAILMODES, SPCM\_X1\_AVAILMODES, SPCM\_X2\_AVAILMODES and SPCM\_X3\_AVAILMODES register first. The available modes may differ from card to card and may be enhanced with new driver/firmware versions to come.

Register	Value	Direction	Description
SPCM_X0_AVAILMODES	600300	read	Bitmask with all bits of the below mentioned modes showing the available modes for (X0)
SPCM_X1_AVAILMODES	600301	read	Bitmask with all bits of the below mentioned modes showing the available modes for (X1)
SPCM_X2_AVAILMODES	600302	read	Bitmask with all bits of the below mentioned modes showing the available modes for (X2)
SPCM_X3_AVAILMODES	600303	read	Bitmask with all bits of the below mentioned modes showing the available modes for (X3)
SPCM_X0_MODE	600200	read/write	Defines the mode for (X0). Only one mode selection is possible to be set at a time
SPCM_X1_MODE	600201	read/write	Defines the mode for (X1). Only one mode selection is possible to be set at a time
SPCM_X2_MODE	600202	read/write	Defines the mode for (X2). Only one mode selection is possible to be set at a time
SPCM_X3_MODE	600203	read/write	Defines the mode for (X3). Only one mode selection is possible to be set at a time
SPCM_XMODE_DISABLE	00000000h	No mode selected. Output is tristate (default setup)	
SPCM_XMODE_ASYNCIN	00000001h	Connector is programmed for asynchronous input. Use SPCM_XX_ASYNCIO to read data asynchronous as shown in the passage below.	
SPCM_XMODE_ASYNCOUT	00000002h	Connector is programmed for asynchronous output. Use SPCM_XX_ASYNCIO to write data asynchronous as shown in the passage below.	
SPCM_XMODE_DIGIN	00000004h	A/D cards only: Connector is programmed for synchronous digital input. For each analog channel, one digital channel X1/X2/X3 is integrated into the ADC data stream. Depending on the ADC resolution of your card the resulting merged samples can have different formats. Please check the „Sample format“ chapter and the following passage on „Synchronous digital inputs“ for more details. Please note that automatic sign extension of analog data is ineffective as soon as one digital input line is activated and the software must properly mask out the digital bits.	
SPCM_XMODE_TRIGIN	00000010h	Connector is programmed as additional TTL trigger input. X1/X2/X3 are available as Ext1/Ext2/Ext3 trigger input. Please be sure to also set the corresponding trigger OR/AND masks to use this trigger input for trigger detection.	
SPCM_XMODE_DIGOUT	00000008h	D/A cards only: Connector is programmed for synchronous digital output. Digital channels can be „included“ within the analog samples and synchronously replayed along. Requires additional MODE bits to be set along with this flag, as explained later on.	
SPCM_XMODE_TRIGOUT	00000020h	Connector is programmed as trigger output and shows the trigger detection. The trigger output goes HIGH as soon as the trigger is recognized. After end of acquisition it is LOW again. In Multiple Recording/Gated Sampling/ABA mode it goes LOW after the acquisition of the current segment stops. In standard FIFO mode the trigger output is HIGH until FIFO mode is stopped.	
SPCM_XMODE_RUNSTATE	00000100h	Connector shows the current run state of the card. If acquisition/output is running the signal is HIGH. If card has stopped the signal is LOW.	
SPCM_XMODE_ARMSTATE	00000200h	Connector shows the current ARM state of the card. If the card is armed and ready to receive a trigger the signal is HIGH. If the card isn't running or the card is still acquiring pretrigger data or the trigger has already been detected, the signal is LOW.	
SPCM_XMODE_CONTOUTMARK	00002000h	D/A cards only: Outputs a HIGH pulse as continuous marker signal for continuous replay mode. The marker signal length is 1/2 of the programmed memory size.	
SPCM_XMODE_SYSCLKOUT	00004000h	Output of internal FPGA system clock. The system clock is always an even division of the current sampling clock.	

SPCM_XMODE_CLKOUT	00008000h	Connector reflects the internally generated sampling clock. In case that oversampling is active, the clock present here is by SPC_OVERSAMPLINGFACTOR higher than the programmed sample rate. See „Oversampling“ passage in clock chapter for further details.
SPCM_XMODE_SYNCARMSTATE	00010000h	Connector shows the current ARM state of all cards currently connected Star-Hub and enabled for synchronization. If all cards are armed and ready to receive a trigger the signal is HIGH. If all cards are ready or one running card is still acquiring pretrigger data or the trigger has been detected the signal is LOW. A card that has reached the end of its acquisition will remove itself from the equation and not contribute to this signal until all cards are finished.



**Please note that a change to the SPCM\_X0\_MODE, SPCM\_X1\_MODE, SPCM\_X2\_MODE or SPCM\_X3\_MODE will only be updated with the next call to either the M2CMD\_CARD\_START or M2CMD\_CARD\_WRITESETUP register. For further details please see the relating chapter on the M2CMD\_CARD registers.**

## Asynchronous I/O

To use asynchronous I/O on the multi purpose I/O lines it is first necessary to switch these lines to the desired asynchronous mode by programming the above explained mode registers. As a special feature asynchronous input can also be read if the mode is set to trigger input or digital input.

Register	Value	Direction	Description
SPCM_XX_ASYNCIO	47220	read/write	Connector X1 is linked to bit 1 of the register, connector X2 is linked to bit 2 while connector X3 is linked to bit 3 of this register. Data is written/read immediately without any relation to the currently used sampling rate or mode. If a line is programmed to output, reading this line asynchronously will return the current output level. Connector X0 is not available as an input, hence bit 0 of the register is only used as an output.

Example of asynchronous write and read. We write a high pulse on output X2 and wait for a high level answer on input X1:

```

spcm_dwSetParam_i32 (hDrv, SPCM_X0_MODE, SPCM_XMODE_CLKOUT); // X0 set to clock output
spcm_dwSetParam_i32 (hDrv, SPCM_X1_MODE, SPCM_XMODE_ASYNCIN); // X1 set to asynchronous input
spcm_dwSetParam_i32 (hDrv, SPCM_X2_MODE, SPCM_XMODE_ASYNCOUT); // X2 set to asynchronous output
spcm_dwSetParam_i32 (hDrv, SPCM_X3_MODE, SPCM_XMODE_TRIGOUT); // X3 set to trigger output

spcm_dwSetParam_i32 (hDrv, SPCM_XX_ASYNCIO, 0); // programming a high pulse on output X2
spcm_dwSetParam_i32 (hDrv, SPCM_XX_ASYNCIO, 4);
spcm_dwSetParam_i32 (hDrv, SPCM_XX_ASYNCIO, 0);

do {
    spcm_dwGetParam_i32 (hDrv, SPCM_XX_ASYNCIO, &lAsyncIn); // read input in a loop
} while ((lAsyncIn & 2) == 0); // until X1 is going to high level

```

## Special behavior of trigger output

As the driver of the M2p series is the same as the driver for the M2i series and some old software may rely on register structure of the M2i card series, there is a special compatible trigger output register that will work according to the M2i series style. It is not recommended to use this register unless you're converting M2i software to the M2p card series:

Register	Value	Direction	Description
SPC_TRIG_OUTPUT	40100	read/write	M2i style trigger output programming. Write a „1“ to enable: - X3 trigger output (SPCM_X3_MODE = SPCM_XMODE_TRIGOUT ) - X2 arm state (SPCM_X2_MODE = SPCM_XMODE_ARMSTATE) - X1 run state (SPCM_X1_MODE = SPCM_XMODE_RUNSTATE)  Write a „0“ to disable all three outputs: - SPCM_X1_MODE = SPCM_X2_MODE = SPCM_X3_MODE = SPCM_XMODE_DISABLE



**The SPC\_TRIG\_OUTPUT register overrides the multi purpose I/O settings done by SPCM\_X1\_MODE, SPCM\_X2\_MODE and SPCM\_X3\_MODE and vice versa. Do not use both methods together from within one program.**

## Synchronous digital inputs

The cards of the M2p series allow a very detailed setup on how to optionally record synchronous digital channels along with analog acquisition. The SPC\_DIGMODEx register allows the setup separately for every analog channel. The table below shows the related registers and the values that correspond with the different possibilities. The mask and mode and mode values have to properly be combined. This is shown in the example below the tables:

Register	Value	Direction	Description
SPC_DIGMODE0	47250	read/write	Set the digital input sources for channel 0.
SPC_DIGMODE1	47251	read/write	Set the digital input sources for channel 1.
SPC_DIGMODE2	47252	read/write	Set the digital input sources for channel 2.
SPC_DIGMODE3	47253	read/write	Set the digital input sources for channel 3.
SPC_DIGMODE4	47254	read/write	Set the digital input sources for channel 4.
SPC_DIGMODE5	47255	read/write	Set the digital input sources for channel 5.
SPC_DIGMODE6	47256	read/write	Set the digital input sources for channel 6.
SPC_DIGMODE7	47257	read/write	Set the digital input sources for channel 7.
SPCM_DIGMODE_OFF	0000000h		Disable acquisition of digital data for the masked analog bit (see masks below).

SPCM_DIGMODE_X1	294A5000h	Enable acquisition of multi-purpose input X1 for the masked analog bit (see masks below).
SPCM_DIGMODE_X2	318C6000h	Enable acquisition of multi-purpose input X2 for the masked analog bit (see masks below).
SPCM_DIGMODE_X3	39CE7000h	Enable acquisition of multi-purpose input X3 for the masked analog bit (see masks below).

DIGMODEMASK_BIT15	F8000000h	Enable acquisition of a digital source (sources see above) into bit15 of the analog sample.
DIGMODEMASK_BIT14	07C00000h	Enable acquisition of a digital source (sources see above) into bit14 of the analog sample.
DIGMODEMASK_BIT13	003E0000h	Enable acquisition of a digital source (sources see above) into bit13 of the analog sample.

Each mask constant has to be bitwise AND combined with a source/mode constant, to define which digital source will be inserted at which position of the analog sample. The SPC\_DIGMODEx register defines then, what analog channel this is applied to.

The driver will automatically scale the analog samples prior to inserting the digital channels to keep the channel at the maximum possible resolution.

## Sample Format

Any channels that will not store any digital inputs within their samples still provide the full 16 bit resolution. :

Data bit	Standard Mode			
	16 bit ADC resolution	1 digital input enabled 15 bit ADC resolution	2 digital inputs enabled 14 bit ADC resolution	3 digital inputs enabled 13 bit ADC resolution
D15	ADx Bit 15 (MSB)	Digital bit 0 (any X input)*	Digital bit 0 (any X input)*	Digital bit 0 (any X input)*
D14	ADx Bit 14	ADx Bit 15 (MSB)	Digital bit 1 (any X input)*	Digital bit 1 (any X input)*
D13	ADx Bit 13	ADx Bit 14	ADx Bit 15 (MSB)	Digital bit 2 (any X input)*
D12	ADx Bit 12	ADx Bit 13	ADx Bit 14	ADx Bit 15 (MSB)
D11	ADx Bit 11	ADx Bit 12	ADx Bit 13	ADx Bit 14
D10	ADx Bit 10	ADx Bit 11	ADx Bit 12	ADx Bit 13
D9	ADx Bit 9	ADx Bit 10	ADx Bit 11	ADx Bit 12
D8	ADx Bit 8	ADx Bit 9	ADx Bit 10	ADx Bit 11
D7	ADx Bit 7	ADx Bit 8	ADx Bit 9	ADx Bit 10
D6	ADx Bit 6	ADx Bit 7	ADx Bit 8	ADx Bit 9
D5	ADx Bit 5	ADx Bit 6	ADx Bit 7	ADx Bit 8
D4	ADx Bit 4	ADx Bit 5	ADx Bit 6	ADx Bit 7
D3	ADx Bit 3	ADx Bit 4	ADx Bit 5	ADx Bit 6
D2	ADx Bit 2	ADx Bit 3	ADx Bit 4	ADx Bit 5
D1	ADx Bit 1	ADx Bit 2	ADx Bit 3	ADx Bit 4
D0	ADx Bit 0 (LSB)	ADx Bit 1 (LSB)	ADx Bit 2 (LSB)	ADx Bit 3 (LSB)

\* Any X-input can be used as a source for that digital channel, except X0, which is output only.



**Please note that automatic sign extension of analog data is ineffective as soon as one digital input line is activated and the software must properly mask out all the digital bits from the samples.**



**The digital source has to be properly set to input direction to be a valid digital source. Also the analog channel into that the digital signals shall be routed to must be activated properly for acquisition as described in the „Channel Selection“ passage.**

The following example shows how to enable a different number of digital channels (one and two respectively) on two different analog channels:

```

spcm_dwSetParam_i32 (hDrv, SPCM_X1_MODE, SPCM_XMODE_DIGIN); // X1 set to synchronous input
spcm_dwSetParam_i32 (hDrv, SPCM_X2_MODE, SPCM_XMODE_DIGIN); // X2 set to synchronous input
spcm_dwSetParam_i32 (hDrv, SPCM_X3_MODE, SPCM_XMODE_DIGIN); // X3 set to synchronous input

// Enable acquisition of X1 input into bit15 of analog channel 0.
// Resulting Ch0 A/D samples will be 15bit.
uint32 dwValue = (DIGMODEMASK_BIT15 & SPCM_DIGMODE_X1);
spcm_dwSetParam_i32 (hDrv, SPCM_DIGMODE0, dwValue);

// Enable acquisition of X2 input into bit15 and X3 input into bit14 of analog channel 1.
// Resulting Ch1 A/D samples will be 14bit.
dwValue = (DIGMODEMASK_BIT15 & SPCM_DIGMODE_X2) | (DIGMODEMASK_BIT14 & SPCM_DIGMODE_X3);
spcm_dwSetParam_i32 (hDrv, SPCM_DIGMODE1, dwValue);

```

The following example shows how to enable all three digital channels provided via the multi-purpose lines X1, X2 and X3 to one channel and hence reduce the resolution of this channel to 13 bit:

```

spcm_dwSetParam_i32 (hDrv, SPCM_X1_MODE, SPCM_XMODE_DIGIN); // X1 set to synchronous input
spcm_dwSetParam_i32 (hDrv, SPCM_X2_MODE, SPCM_XMODE_DIGIN); // X2 set to synchronous input
spcm_dwSetParam_i32 (hDrv, SPCM_X3_MODE, SPCM_XMODE_DIGIN); // X3 set to synchronous input

// define and clear a temporary variable
uint32 dwValue = 0;

// add three sources (X1, X2 and X3) at three different positions (bit15, bit14 and bit13)
dwValue |= (DIGMODEMASK_BIT15 & SPCM_DIGMODE_X3);
dwValue |= (DIGMODEMASK_BIT14 & SPCM_DIGMODE_X2);
dwValue |= (DIGMODEMASK_BIT13 & SPCM_DIGMODE_X1);

// and write value to channel 0 digemode register. Resulting Ch0 A/D samples will be 13bit.
spcm_dwSetParam_i32 (hDrv, SPCM_DIGMODE0, dwValue);

```

## Additional I/O lines with Option -DigBNC

The options M2p.xxxx-DigBNC extend the multi purpose I/O lines of each digitizerNETBOX/generatorNETBOX by adding eight more I/O lines as an option. These additional lines X4, X5 ... X11 share the same capabilities as their standard I/O counter parts (X1 .. X3), except the trigger input functionality.



**Please be careful when programming these lines as an output whilst maybe still being connected with an external signal source, as that may damage components either on the external equipment or on the card itself.**

### Programming the behavior

Each multi purpose I/O line can be individually programmed. Please check the available modes by reading the SPCM\_X4\_AVAILMODE up to SPCM\_X19\_AVAILMODE register first. The available modes may differ from card to card and may be enhanced with new driver/firmware versions to come.

Register	Value	Direction	Description
SPCM_X4_AVAILMODES	600304	read	Bitmask with all bits of the below mentioned modes showing the available modes for (X4)
SPCM_X5_AVAILMODES	600305	read	Bitmask with all bits of the below mentioned modes showing the available modes for (X5)
...	...	read	...
SPCM_X10_AVAILMODES	600310	read	Bitmask with all bits of the below mentioned modes showing the available modes for (X10)
SPCM_X11_AVAILMODES	600311	read	Bitmask with all bits of the below mentioned modes showing the available modes for (X11)
SPCM_X4_MODE	600204	read/write	Defines the mode for (X4). Only one mode selection is possible to be set at a time
SPCM_X5_MODE	600205	read/write	Defines the mode for (X5). Only one mode selection is possible to be set at a time
...	...	read/write	...
SPCM_X10_MODE	600210	read/write	Defines the mode for (X10). Only one mode selection is possible to be set at a time
SPCM_X11_MODE	600211	read/write	Defines the mode for (X11). Only one mode selection is possible to be set at a time
SPCM_XMODE_DISABLE	00000000h	No mode selected. Output is tristate (default setup)	
SPCM_XMODE_ASYNCIN	00000001h	Connector is programmed for asynchronous input. Use SPCM_XX_ASYNCIO to read data asynchronous as shown in the passage below.	
SPCM_XMODE_ASYNCOUT	00000002h	Connector is programmed for asynchronous output. Use SPCM_XX_ASYNCIO to write data asynchronous as shown in the passage below.	
SPCM_XMODE_DIGIN	00000004h	A/D cards only: Connector is programmed for synchronous digital input. For each analog channel, one digital channel X1/X2/X3 is integrated into the ADC data stream. Depending on the ADC resolution of your card the resulting merged samples can have different formats. Please check the „Sample format“ chapter and the following passage on „Synchronous digital inputs“ for more details. Please note that automatic sign extension of analog data is ineffective as soon as one digital input line is activated and the software must properly mask out the digital bits.	
SPCM_XMODE_DIGOUT	00000008h	D/A cards only: Connector is programmed for synchronous digital output. Digital channels can be „included“ within the analog samples and synchronously replayed along. Requires additional MODE bits to be set along with this flag, as explained later on.	
SPCM_XMODE_TRIGOUT	00000020h	Connector is programmed as trigger output and shows the trigger detection. The trigger output goes HIGH as soon as the trigger is recognized. After end of acquisition it is LOW again. In Multiple Recording/Gated Sampling/ABA mode it goes LOW after the acquisition of the current segment stops. In standard FIFO mode the trigger output is HIGH until FIFO mode is stopped.	
SPCM_XMODE_RUNSTATE	00000100h	Connector shows the current run state of the card. If acquisition/output is running the signal is HIGH. If card has stopped the signal is LOW.	
SPCM_XMODE_ARMSTATE	00000200h	Connector shows the current ARM state of the card. If the card is armed and ready to receive a trigger the signal is HIGH. If the card isn't running or the card is still acquiring pretrigger data or the trigger has already been detected, the signal is LOW.	
SPCM_XMODE_CONTOUTMARK	00002000h	D/A cards only: Outputs a HIGH pulse as continuous marker signal for continuous replay mode. The marker signal length is 1/2 of the programmed memory size.	
SPCM_XMODE_SYNCARMSTATE	00010000h	Connector shows the current ARM state of all cards currently connected Star-Hub and enabled for synchronization. If all cards are armed and ready to receive a trigger the signal is HIGH. If all cards are ready or one running card is still acquiring pretrigger data or the trigger has been detected the signal is LOW. A card that has reached the end of its acquisition will remove itself from the equation and not contribute to this signal until all cards are finished.	



**Please note that a change to the SPCM\_X4MODE up to SPCM\_X11\_MODE will only be updated with the next call to either the M2CMD\_CARD\_START or M2CMD\_CARD\_WRITESETUP register. For further details please see the relating chapter on the M2CMD\_CARD registers.**

### Asynchronous I/O

To use asynchronous I/O on the multi purpose I/O lines it is first necessary to switch these lines to the desired asynchronous mode by programming the above explained mode registers. As a special feature asynchronous input can also be read if the mode is set to trigger input or digital input.

Register	Value	Direction	Description
SPCM_XX_ASYNCIO	47220	read/write	Connector X4 is linked to bit 4 of the register, connector X5 is linked to bit 5 and so on until X11 on bit 11. Data is written/read immediately without any relation to the currently used sampling rate or mode. If a line is programmed to output, reading this line asynchronously will return the current output level.

Example of asynchronous write and read. We write a high pulse on output X4 and wait for a high level answer on input X11:

```

spcm_dwSetParam_i32 (hDrv, SPCM_X11_MODE, SPCM_XMODE_ASYNCIN); // X1 set to asynchronous input
spcm_dwSetParam_i32 (hDrv, SPCM_X4_MODE, SPCM_XMODE_ASYNCOUT); // X2 set to asynchronous output

spcm_dwSetParam_i32 (hDrv, SPCM_XX_ASYNCIO, 0x00);           // programming a high pulse on output X4
spcm_dwSetParam_i32 (hDrv, SPCM_XX_ASYNCIO, 0x10);
spcm_dwSetParam_i32 (hDrv, SPCM_XX_ASYNCIO, 0x00);

do {
    spcm_dwGetParam_i32 (hDrv, SPCM_XX_ASYNCIO, &lAsyncIn);      // read input in a loop
} while ((lAsyncIn & 0x00100) == 0);                           // until X11 is going to high level

```

## Synchronous digital inputs

The cards of the M2p series allow a very detailed setup on how to optionally record synchronous digital channels along with analog acquisition. The SPC\_DIGMODEx register allows the setup separately for every analog channel. The table below shows the related registers and the values that correspond with the different possibilities. The mask and mode and mode values have to properly be combined. This is shown in the example below the tables:

Register	Value	Direction	Description
SPC_DIGMODE0	47250	read/write	Set the digital input sources for channel 0.
SPC_DIGMODE1	47251	read/write	Set the digital input sources for channel 1.
SPC_DIGMODE2	47252	read/write	Set the digital input sources for channel 2.
SPC_DIGMODE3	47253	read/write	Set the digital input sources for channel 3.
SPC_DIGMODE4	47254	read/write	Set the digital input sources for channel 4.
SPC_DIGMODE5	47255	read/write	Set the digital input sources for channel 5.
SPC_DIGMODE6	47256	read/write	Set the digital input sources for channel 6.
SPC_DIGMODE7	47257	read/write	Set the digital input sources for channel 7.
SPCM_DIGMODE_OFF	0000000h		Disable acquisition of digital data for the masked analog bit (see masks below).

SPCM_DIGMODE_X4	84210001h	Enable acquisition of multi-purpose input X4 for the masked analog bit (see masks below).
SPCM_DIGMODE_X5	8C631002h	Enable acquisition of multi-purpose input X5 for the masked analog bit (see masks below).
SPCM_DIGMODE_X6	94A52004h	Enable acquisition of multi-purpose input X6 for the masked analog bit (see masks below).
SPCM_DIGMODE_X7	9CE73008h	Enable acquisition of multi-purpose input X7 for the masked analog bit (see masks below).
SPCM_DIGMODE_X8	A5294010h	Enable acquisition of multi-purpose input X8 for the masked analog bit (see masks below).
SPCM_DIGMODE_X9	AD6B5020h	Enable acquisition of multi-purpose input X9 for the masked analog bit (see masks below).
SPCM_DIGMODE_X10	B5AD6040h	Enable acquisition of multi-purpose input X10 for the masked analog bit (see masks below).
SPCM_DIGMODE_X11	BDEF7080h	Enable acquisition of multi-purpose input X11 for the masked analog bit (see masks below).

DIGMODEMASK_BIT15	F8000000h	Enable acquisition of a digital source (sources see above) into bit15 of the analog sample. Any X-Input allowed.
DIGMODEMASK_BIT14	07C00000h	Enable acquisition of a digital source (sources see above) into bit14 of the analog sample. Any X-Input allowed.
DIGMODEMASK_BIT13	003E0000h	Enable acquisition of a digital source (sources see above) into bit13 of the analog sample. Any X-Input allowed.
DIGMODEMASK_BIT12	0001F000h	Enable acquisition of a digital source (sources see above) into bit12 of the analog sample. Any X-Input allowed.

Each mask constant has to be bitwise AND combined with a source/mode constant, to define which digital source will be inserted at which position of the analog sample. The SPC\_DIGMODEx register defines then, what analog channel this is applied to.

The driver will automatically scale the analog samples prior to inserting the digital channels to keep the channel at the maximum possible resolution.

**Sample Format (with up to four digital channels)**

Any channels that will not store any digital inputs within their samples still provide the full 16 bit resolution. :

Data bit	Standard Mode	1 digital input enabled	2 digital inputs enabled	3 digital inputs enabled	4 digital inputs enabled
	16 bit ADC resolution	15 bit ADC resolution	14 bit ADC resolution	13 bit ADC resolution	12 bit ADC resolution
D15	ADx Bit 15 (MSB)	Digital bit 0 (any X input)*			
D14	ADx Bit 14	ADx Bit 15 (MSB)	Digital bit 1 (any X input)*	Digital bit 1 (any X input)*	Digital bit 1 (any X input)*
D13	ADx Bit 13	ADx Bit 14	ADx Bit 15 (MSB)	Digital bit 2 (any X input)*	Digital bit 2 (any X input)*
D12	ADx Bit 12	ADx Bit 13	ADx Bit 14	ADx Bit 15 (MSB)	Digital bit 3 (any X input)*
D11	ADx Bit 11	ADx Bit 12	ADx Bit 13	ADx Bit 14	ADx Bit 15 (MSB)
D10	ADx Bit 10	ADx Bit 11	ADx Bit 12	ADx Bit 13	ADx Bit 14
D9	ADx Bit 9	ADx Bit 10	ADx Bit 11	ADx Bit 12	ADx Bit 13
D8	ADx Bit 8	ADx Bit 9	ADx Bit 10	ADx Bit 11	ADx Bit 12
D7	ADx Bit 7	ADx Bit 8	ADx Bit 9	ADx Bit 10	ADx Bit 11
D6	ADx Bit 6	ADx Bit 7	ADx Bit 8	ADx Bit 9	ADx Bit 10
D5	ADx Bit 5	ADx Bit 6	ADx Bit 7	ADx Bit 8	ADx Bit 9
D4	ADx Bit 4	ADx Bit 5	ADx Bit 6	ADx Bit 7	ADx Bit 8
D3	ADx Bit 3	ADx Bit 4	ADx Bit 5	ADx Bit 6	ADx Bit 7
D2	ADx Bit 2	ADx Bit 3	ADx Bit 4	ADx Bit 5	ADx Bit 6
D1	ADx Bit 1	ADx Bit 2	ADx Bit 3	ADx Bit 4	ADx Bit 5
D0	ADx Bit 0 (LSB)	ADx Bit 1 (LSB)	ADx Bit 2 (LSB)	ADx Bit 3 (LSB)	ADx Bit 4 (LSB)

\* Any X-input can be used as a source for that digital channel, except X0, which is output only.

The following example shows how to enable four digital channels provided via the multi-purpose lines X2, X3, X8 and X11 to one channel and hence reduce the resolution of this channel to 12 bit:

```

spcm_dwSetParam_i32 (hDrv, SPCM_X2_MODE, SPCM_XMODE_DIGIN); // X2 set to synchronous input
spcm_dwSetParam_i32 (hDrv, SPCM_X3_MODE, SPCM_XMODE_DIGIN); // X3 set to synchronous input
spcm_dwSetParam_i32 (hDrv, SPCM_X8_MODE, SPCM_XMODE_DIGIN); // X8 set to synchronous input
spcm_dwSetParam_i32 (hDrv, SPCM_X11_MODE, SPCM_XMODE_DIGIN); // X11 set to synchronous input

// define and clear a temporary variable
uint32 dwValue = 0;

// add four sources (X2, X3, X8 and X11) at four different positions (bit15, bit14, bit13 and bit12)
dwValue |= (DIGMODEMASK_BIT15 & SPCM_DIGMODE_X2); // store X2 in Sample Bit15
dwValue |= (DIGMODEMASK_BIT14 & SPCM_DIGMODE_X3); // store X3 in Sample Bit14
dwValue |= (DIGMODEMASK_BIT13 & SPCM_DIGMODE_X8); // store X8 in Sample Bit13
dwValue |= (DIGMODEMASK_BIT12 & SPCM_DIGMODE_X11); // store X11 in Sample Bit12

// and write value to channel 0 digemode register. Resulting Ch0 A/D samples will be 12bit.
spcm_dwSetParam_i32 (hDrv, SPCM_DIGMODE0, dwValue);

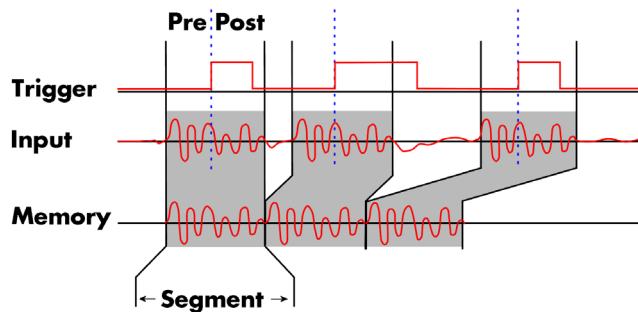
```

## Mode Multiple Recording

The Multiple Recording mode allows the acquisition of data blocks with multiple trigger events without restarting the hardware.

The on-board memory will be divided into several segments of the same size. Each segment will be filled with data when a trigger event occurs (acquisition mode).

As this mode is totally controlled in hardware there is a very small re-arm time from end of one segment until the trigger detection is enabled again. You'll find that re-arm time in the technical data section of this manual.



The following table shows the register for defining the structure of the segments to be recorded with each trigger event.

Register	Value	Direction	Description
SPC_POSTTRIGGER	10100	read/write	Acquisition only: defines the number of samples to be recorded per channel after the trigger event.
SPC_SEGMENTSIZE	10010	read/write	Size of one Multiple Recording segment: the total number of samples to be recorded per channel after detection of one trigger event including the time recorded before the trigger [pre trigger].

Each segment in acquisition mode can consist of pretrigger and/or posttrigger samples. The user always has to set the total segment size and the posttrigger, while the pretrigger is calculated within the driver with the formula: [pretrigger] = [segment size] - [posttrigger].

**⚠ When using Multiple Recording the maximum pretrigger is limited depending on the number of active channels. When the calculated value exceeds that limit, the driver will return the error ERR\_PRETRIGGERLEN. Please have a look at the table further below to see the maximum pretrigger length that is possible.**

## Recording modes

### Standard Mode

With every detected trigger event one data block is filled with data. The length of one multiple recording segment is set by the value of the segment size register SPC\_SEGMENTSIZE. The total amount of samples to be recorded is defined by the memsize register.

Memsize must be set to a multiple of the segment size. The table below shows the register for enabling Multiple Recording. For detailed information on how to setup and start the standard acquisition mode please refer to the according chapter earlier in this manual.

Register	Value	Direction	Description
SPC_CARDMODE	9500	read/write	Defines the used operating mode
SPC_REC_STD_MULTI	2		Enables Multiple Recording for standard acquisition.

The total number of samples to be recorded to the on-board memory in Standard Mode is defined by the SPC\_MEMSIZE register.

Register	Value	Direction	Description
SPC_MEMSIZE	10000	read/write	Defines the total number of samples to be recorded per channel.

### FIFO Mode

The Multiple Recording in FIFO Mode is similar to the Multiple Recording in Standard Mode. In contrast to the standard mode it is not necessary to program the number of samples to be recorded. The acquisition is running until the user stops it. The data is read block by block by the driver as described under FIFO single mode example earlier in this manual. These blocks are online available for further data processing by the user program. This mode significantly reduces the amount of data to be transferred on the PCI bus as gaps of no interest do not have to be transferred. This enables you to use faster sample rates than you would be able to in FIFO mode without Multiple Recording. The advantage of Multiple Recording in FIFO mode is that you can stream data online to the host system. You can make real-time data processing or store a huge amount of data to the hard disk. The table below shows the dedicated register for enabling Multiple Recording. For detailed information how to setup and start the board in FIFO mode please refer to the according chapter earlier in this manual.

Register	Value	Direction	Description
SPC_CARDMODE	9500	read/write	Defines the used operating mode
SPC_REC_FIFO_MULTI	32		Enables Multiple Recording for FIFO acquisition.

The number of segments to be recorded must be set separately with the register shown in the following table:

Register	Value	Direction	Description
SPC_LOOPS	10020	read/write	Defines the number of segments to be recorded
0			Recording will be infinite until the user stops it.
1 ... [4G - 1]			Defines the total segments to be recorded.

## Limits of pre trigger, post trigger, memory size

The maximum memory size parameter is only limited by the number of activated channels and by the amount of installed memory. Please keep in mind that each samples needs 2 bytes of memory to be stored. Minimum memory size as well as minimum and maximum post trigger limits are independent of the activated channels or the installed memory.

Due to the internal organization of the card memory there is a certain stepsize when setting these values that has to be taken into account. The following table gives you an overview of all limits concerning pre trigger, post trigger, memory size, segment size and loops. The table shows all values in relation to the installed memory size in samples. If more memory is installed the maximum memory size figures will increase according to the complete installed memory

Activated Channels	Used Mode	Memory size SPC_MEMSIZE			Pre trigger SPC_PRETRIGGER			Post trigger SPC_POSTTRIGGER			Segment size SPC_SEGMENTSIZE			Loops SPC_LOOPS		
		Min	Max	Step	Min	Max	Step	Min	Max	Step	Min	Max	Step	Min	Max	Step
1 Ch	Standard Single	16	Mem	8	8	Mem - 8	8	8	8G - 8	8	not used			not used		
	Standard Multi/ABA	16	Mem	8	8	32k	8	8	Mem - 8	8	16	Mem	8	not used		
	Standard Gate	16	Mem	8	8	32k	8	8	Mem - 8	8	not used			not used		
	FIFO Single	not used			8	32k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1
	FIFO Multi/ABA	not used			8	32k	8	8	8G - 8	8	16	pre+post	8	0 (∞)	4G - 1	1
	FIFO Gate	not used			8	32k	8	8	8G - 8	8	not used			0 (∞)	4G - 1	1
2 Ch	Standard Single	16	Mem/2	8	8	Mem/2 - 8	8	8	8G - 8	8	not used			not used		
	Standard Multi/ABA	16	Mem/2	8	8	16k	8	8	Mem/2 - 8	8	16	Mem/2	8	not used		
	Standard Gate	16	Mem/2	8	8	16k	8	8	Mem/2 - 8	8	not used			not used		
	FIFO Single	not used			8	16k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1
	FIFO Multi/ABA	not used			8	16k	8	8	8G - 8	8	16	pre+post	8	0 (∞)	4G - 1	1
	FIFO Gate	not used			8	16k	8	8	8G - 8	8	not used			0 (∞)	4G - 1	1
4 Ch	Standard Single	16	Mem/4	8	8	Mem/4 - 8	8	8	8G - 16	8	not used			not used		
	Standard Multi/ABA	16	Mem/4	8	8	8k	8	8	Mem/4 - 8	8	16	Mem/4	8	not used		
	Standard Gate	16	Mem/4	8	8	8k	8	8	Mem/4 - 8	8	not used			not used		
	FIFO Single	not used			8	8k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1
	FIFO Multi/ABA	not used			8	8k	8	8	8G - 16	8	16	pre+post	8	0 (∞)	4G - 1	1
	FIFO Gate	not used			8	8k	8	8	8G - 16	8	not used			0 (∞)	4G - 1	1
8 Ch	Standard Single	16	Mem/8	8	8	Mem/8 - 8	8	8	8G - 8	8	not used			not used		
	Standard Multi/ABA	16	Mem/8	8	8	4k	8	8	Mem/8 - 8	8	16	Mem/8	8	not used		
	Standard Gate	16	Mem/8	8	8	4k	8	8	Mem/8 - 8	8	not used			not used		
	FIFO Single	not used			8	4k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1
	FIFO Multi/ABA	not used			8	4k	8	8	8G - 16	8	16	pre+post	8	0 (∞)	4G - 1	1
	FIFO Gate	not used			8	4k	8	8	8G - 16	8	not used			0 (∞)	4G - 1	1

All figures listed here are given in samples. An entry of [8G - 16] means [8 GSamples - 16] = 8,589,934,576 samples.

The given memory and memory / divider figures depend on the installed on-board memory as listed below:

Installed Memory	
<b>512 MSample</b>	
Mem	512 MSample
Mem/2	256 MSample
Mem/4	128 MSample
Mem/8	64 MSample

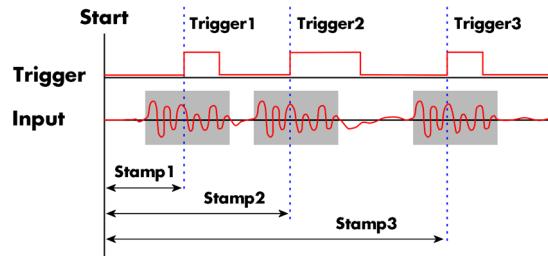
Please keep in mind that this table shows all values at once. Only the absolute maximum and minimum values are shown. There might be additional limitations. Which of these values are programmed depends on the used mode. Please read the detailed documentation of the mode.

## Multiple Recording and Timestamps

Multiple Recording is well matching with the timestamp option. If timestamp recording is activated each trigger event and therefore each Multiple Recording segment will get timestamped as shown in the drawing on the right.

Please keep in mind that the trigger events are timestamped, not the beginning of the acquisition. The first sample that is available is at the time position of [Timestamp - Pretrigger].

The programming details of the timestamp option is explained in an extra chapter.



## Trigger Modes

When using Multiple Recording all of the card's trigger modes can be used including the software trigger. For detailed information on the available trigger modes, please take a look at the relating chapter earlier in this manual.

### Trigger Counter

The number of acquired trigger events in Multiple Recording mode is counted in hardware and can be read out while the acquisition is running or after the acquisition has finished. The trigger events are counted both in standard mode as well as in FIFO mode.

Register	Value	Direction	Description
SPC_TRIGGERCOUNTER	200905	read	Returns the number of trigger events that has been acquired since the acquisition start. The internal trigger counter has 48 bits. It is therefore necessary to read out the trigger counter value with 64 bit access or 2 x 32 bit access if the number of trigger events exceed the 32 bit range.

**⚠ The trigger counter feature needs at least driver version V2.17 and firmware version V20 (M2i series), V10 (M3i series), V6 (M4i/M4x series) or V1 (M2p series). Please update the driver and the card firmware to these versions to use this feature. Trying to use this feature without the proper firmware version will issue a driver error.**

Using the trigger counter information one can determine how many Multiple Recording segments have been acquired and can perform a memory flush by issuing Force trigger commands to read out all data. This is helpful if the number of trigger events is not known at the start of the acquisition. In that case one will do the following steps:

- Program the maximum number of segments that one expects or use the FIFO mode with unlimited segments
- Set a timeout to be sure that there are no more trigger events acquired. Alternatively one can manually proceed as soon as it is clear from the application that all trigger events have been acquired
- Read out the number of acquired trigger segments
- Issue a number of Force Trigger commands to fill the complete memory (standard mode) or to transfer the last FIFO block that contains valid data segments
- Use the trigger counter value to split the acquired data into valid data with a real trigger event and invalid data with a force trigger event.

## Programming examples

The following example shows how to set up the card for Multiple Recording in standard mode.

```
spcm_dwSetParam_i32 (hDrv, SPC_CARDMODE, SPC_REC_STD_MULTI); // Enables Standard Multiple Recording  
spcm_dwSetParam_i64 (hDrv, SPC_SEGMENTSIZE,    1024);          // Set the segment size to 1024 samples  
spcm_dwSetParam_i64 (hDrv, SPC_POSTTRIGGER,    768);          // Set the posttrigger to 768 samples and therefore  
                                                               // the pretrigger will be 256 samples  
spcm_dwSetParam_i64 (hDrv, SPC_MEMSIZE,        4096);          // Set the total memsize for recording to 4096 samples  
                                                               // so that actually four segments will be recorded  
  
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXT0_MODE, SPC_TM_POS); // Set triggermode to ext. TTL mode (rising edge)  
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK,   SPC_TMASK_EXT0); // and enable it within the trigger OR-mask
```

The following example shows how to set up the card for Multiple Recording in FIFO mode.

```
spcm_dwSetParam_i32 (hDrv, SPC_CARDMODE, SPC_REC_FIFO_MULTI); // Enables FIFO Multiple Recording  
spcm_dwSetParam_i64 (hDrv, SPC_SEGMENTSIZE,    2048);          // Set the segment size to 2048 samples  
spcm_dwSetParam_i64 (hDrv, SPC_POSTTRIGGER,    1920);          // Set the posttrigger to 1920 samples and therefore  
                                                               // the pretrigger will be 128 samples  
spcm_dwSetParam_i64 (hDrv, SPC_LOOPS,         256);           // 256 segments will be recorded  
  
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXT0_MODE, SPC_TM_NEG); // Set triggermode to ext. TTL mode (falling edge)  
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK,   SPC_TMASK_EXT0); // and enable it within the trigger OR-mask
```

## Timestamps

### General information

The timestamp function is used to record trigger events relative to the beginning of the measurement, relative to a fixed time-zero point or synchronized to an external reset clock. The reset clock can come from a radio clock, a GPS signal or from any other external machine.

The timestamp is internally realized as a very wide counter that is running with the currently used sampling rate. The counter is reset either by explicit software command or depending on the mode by the start of the card. On receiving the trigger event the current counter value is stored in an extra FIFO memory.

This function is designed as an enhancement to the Multiple Recording mode and is also used together with the Gated Sampling and ABA mode, but can also be used with plain single acquisitions.

Each recorded timestamp consists of the number of samples that has been counted since the last counter reset has been done. The actual time in relation to the reset command can be easily calculated by the formula on the right. Please note that the timestamp recalculation depends on the currently used sampling rate. Please have a look at the clock chapter to see how to read out the sampling rate.

$$t = \frac{\text{Timestamp}}{\text{Sampling rate}}$$

If you want to know the time between two timestamps, you can simply calculate this by the formula on the right.

$$\Delta t = \frac{\text{Timestamp}_{n+1} - \text{Timestamp}_n}{\text{Sampling rate}}$$

The following registers can be used for the timestamp function:

Register	Value	Direction	Description
SPC_TIMESTAMP_STARTTIME	47030	read/write	Return the reset time when using reference clock mode. Hours are placed in bit 16 to 23, minutes are placed in bit 8 to 15, seconds are placed in bit 0 to 7
SPC_TIMESTAMP_STARTDATE	47031	read/write	Return the reset date when using reference clock mode. The year is placed in bit 16 to 31, the month is placed in bit 8 to 15 and the day of month is placed in bit 0 to 7
SPC_TIMESTAMP_TIMEOUT	47045	read/write	Set's a timeout in milli seconds for waiting of an reference clock edge
SPC_TIMESTAMP_AVAILMODES	47001	read	Returns all available modes as a bitmap. Modes are listed below
SPC_TIMESTAMP_CMD	47000	read/write	Programs a timestamp mode and performs commands as listed below
SPC_TS MODE_DISABLE	0		Timestamp is disabled.
SPC_TS_RESET	1h		The counters are reset and the local PC time is stored for read out by SPC_TIMESTAMP_STARTTIME and SPC_TIMESTAMP_STARTDATE registers. Only usable with mode TSMODE_STANDARD
SPC_TS MODE STANDARD	2h		Standard mode, counter is reset by explicit reset command SPC_TS_RESET or SPC_TS_RESET_WAITREFCLOCK.
SPC_TS MODE STARTRESET	4h		Counter is reset on every card start, all timestamps are in relation to card start.
SPC_TS_RESET_WAITREFCLK	8h		Similar as SPC_TS_RESET, but aimed at SPC_TSCNT_REFCLKxxx modes: The counters are reset then the driver waits for the reference edge as long as defined by the timestamp timeout time. After detecting the edge, the local PC time is stored for read out by SPC_TIMESTAMP_STARTTIME and SPC_TIMESTAMP_STARTDATE registers. Only usable with mode TSMODE_STANDARD
SPC_TSCNT_INTERNAL	100h		Counter is running with complete width on sampling clock
SPC_TSCNT_REFCLKPOS	200h		Counter is split, upper part is running with external reference clock positive edge, lower part is running with sampling clock
SPC_TSCNT_REFCLKNEG	400h		Counter is split, upper part is running with external reference clock negative edge, lower part is running with sampling clock
SPC_TSIOACQ_ENABLE	1000h		Enables the trigger synchronous acquisition of the multi-purpose inputs with every stored timestamp in the upper 64 bit. See Multi-purpose I/O chapter for details on these inputs.
SPC_TSFEAT_NONE	0		No additional timestamp is created. The total number of stamps is only trigger related.
SPC_TSFEAT_STORE1STABA	10000h		Enables the creation of one additional timestamp for the first A area sample when using the optional ABA (dual-time-base) mode.
SPC_TSFEAT_TRGSRC	80000h		Reading this flag from the SPC_TIMESTAMP_AVAILMODES indicates that the card is capable of encoding the trigger source into the timestamp. Writing this flag to the SPC_TIMESTAMP_CMD register enables the storage of the trigger source in the upper 64 bit of the timestamp value.

 **Writing of SPC\_TS\_RESET and SPC\_TS\_RESET\_WAITREFCLK to the command register can only have an effect on the counters, if the cards clock generation is already active. This is the case when the card either has already done an acquisition after the last reset or if the clock setup has already been actively transferred to the card by issuing the M2CMD\_CARD\_WRITESETUP command.**

## Example for setting timestamp mode:

The timestamp mode must consist of one of the mode constants, one of the counter and one of the feature constants:

```
// setting timestamp mode to standard using internal clocking
spcm_dwSetParam_i32 (hDrv, SPC_TIMESTAMP_CMD, SPC_TSMODE_STANDARD | SPC_TSCNT_INTERNAL | SPC_TSFEAT_NONE);

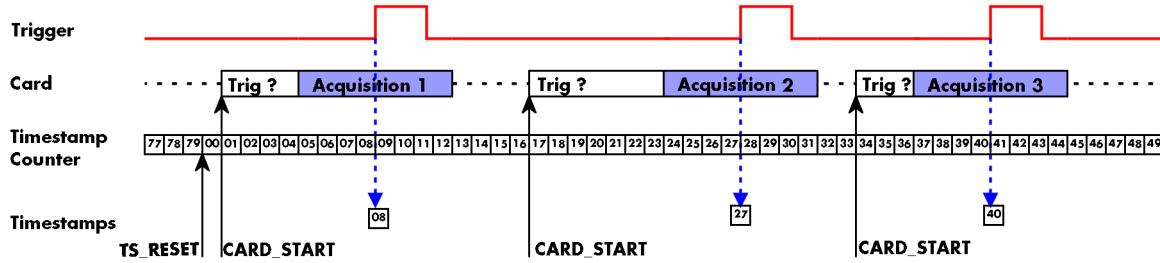
// setting timestamp mode to start reset mode using internal clocking
spcm_dwSetParam_i32 (hDrv, SPC_TIMESTAMP_CMD, SPC_TSMODE_STARTRESET | SPC_TSCNT_INTERNAL | SPC_TSFEAT_NONE);

// setting timestamp mode to standard using external reference clock with positive edge
spcm_dwSetParam_i32 (hDrv, SPC_TIMESTAMP_CMD, SPC_TSMODE_STANDARD | SPC_TSCNT_REFCLKPOS | SPC_TSFEAT_NONE);
```

## Timestamp modes

### Standard mode

In standard mode the timestamp counter is set to zero once by writing the TS\_RESET command to the command register. After that command the counter counts continuously independent of start and stop of acquisition. The timestamps of all recorded trigger events are referenced to this common zero time. With this mode you can calculate the exact time difference between different recordings and also within one acquisition (if using Multiple Recording or Gated Sampling).



The following table shows the valid values that can be written to the timestamp command register for this mode:

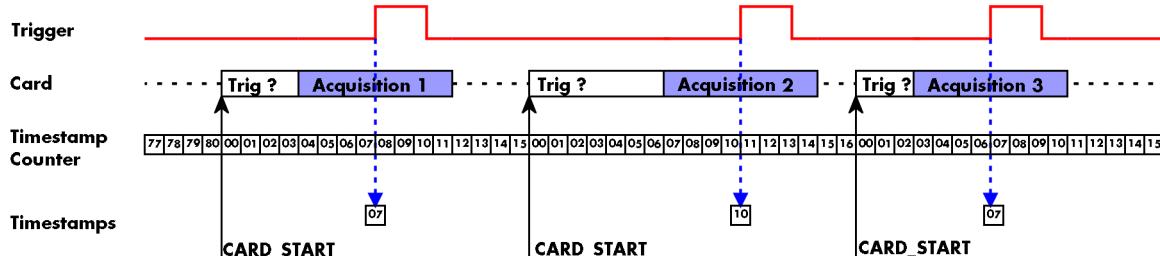
Register	Value	Direction	Description
SPC_TIMESTAMP_CMD	47000	read/write	Programs a timestamp mode and performs commands as listed below
SPC_TSMODE_DISABLE	0		Timestamp is disabled.
SPC_TS_RESET	1h		The timestamp counter is set to zero
SPC_TSMODE_STANDARD	2h		Standard mode, counter is reset by explicit reset command.
SPC_TSCNT_INTERNAL	100h		Counter is running with complete width on sampling clock

Please keep in mind that this mode only work sufficiently as long as you don't change the sampling rate between two acquisitions that you want to compare.



### StartReset mode

In StartReset mode the timestamp counter is set to zero on every start of the card. After starting the card the counter counts continuously. The timestamps of one recording are referenced to the start of the recording. This mode is very useful for Multiple Recording and Gated Sampling (see according chapters for detailed information on these two optional modes).



The following table shows the valid values that can be written to the timestamp command register.

Register	Value	Direction	Description
SPC_TIMESTAMP_CMD	47000	read/write	Programs a timestamp mode and performs commands as listed below
SPC_TS MODE_DISABLE	0		Timestamp is disabled.
SPC_TS MODE_STARTRESET	4h		Counter is reset on every card start, all timestamps are in relation to card start.
SPC_TSCNT_INTERNAL	100h		Counter is running with complete width on sampling clock

## Refclock mode

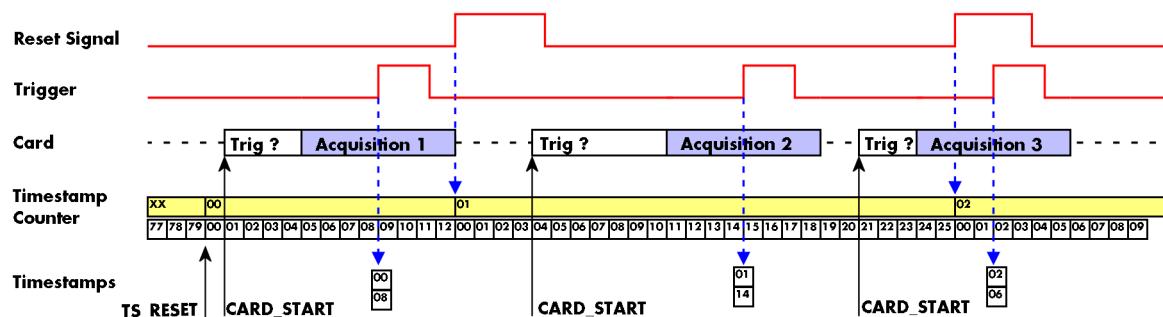
In addition to the counter counting the samples a second separate counter is utilized. An additional external signal is used, which affects both counters and needs to be fed in externally. This external reference clock signal will reset the sample counter and also increase the second counter. The second counter holds the number of the clock edges that have occurred on the external reference clock signal and the sample counter holds the position within the current reference clock period with the resolution of the sampling rate.

This mode can be used to obtain an absolute time reference when using an external radio clock or a GPS receiver. In that case the higher part is counting the seconds since the last reset and the lower part is counting the position inside the second using the current sampling rate.

**! Please keep in mind that as this mode uses an additional external signal and can therefore only be used when connecting an reference clock signal on the related connector on the card:**

- X0 on M4i/M4x and related digitizerNETBOX products
- X1 on M2p and related digitizerNETBOX products

The counting is initialized with the timestamp reset command. Both counters will then be set to zero.



The following table shows the valid values that can be written to the timestamp command register for this mode:

Register	Value	Direction	Description
SPC_TIMESTAMP_STARTTIME	47030	read/write	Return the reset time when using reference clock mode. Hours are placed in bit 16 to 23, minutes are placed in bit 8 to 15, seconds are placed in bit 0 to 7
SPC_TIMESTAMP_STARTDATE	47031	read/write	Return the reset date when using reference clock mode. The year is placed in bit 16 to 31, the month is placed in bit 8 to 15 and the day of month is placed in bit 0 to 7
SPC_TIMESTAMP_TIMEOUT	47045	read/write	Sets a timeout in milli seconds for waiting for a reference clock edge
SPC_TIMESTAMP_CMD	47000	read/write	Programs a timestamp mode and performs commands as listed below
SPC_TS MODE_DISABLE	0		Timestamp is disabled.
SPC_TS_RESET	1h		The counters are reset and the local PC time is stored for read out by SPC_TIMESTAMP_STARTTIME and SPC_TIMESTAMP_STARTDATE registers.
SPC_TS_RESET_WAITREFCLK	8h		Similar as SPC_TS_RESET, but aimed at SPC_TSCNT_REFCLKxxx modes: The counters are reset then the driver waits for the reference edge as long as defined by the timeout time. After detecting the edge, the local PC time is stored for read out by SPC_TIMESTAMP_STARTTIME and SPC_TIMESTAMP_STARTDATE registers.
SPC_TS MODE STANDARD	2h		Standard mode, counter is reset by explicit reset command.
SPC_TS MODE STARTRESET	4h		Counter is reset on every card start, all timestamps are in relation to card start.
SPC_TSCNT_REFCLKPOS	200h		Counter is split, upper part is running with external reference clock positive edge, lower part is running with sampling clock
SPC_TSCNT_REFCLKNEG	400h		Counter is split, upper part is running with external reference clock negative edge, lower part is running with sampling clock

To synchronize the external reference clock signal with the PC clock it is possible to perform a timestamp reset command which waits a specified time for the occurrence of the external clock edge. As soon as the clock edge is found the function stores the current PC time and date which can be used to get the absolute time. As the timestamp reference clock can also be used with other clocks that don't need to be synchronized with the PC clock the waiting time can be programmed using the SPC\_TIMESTAMP\_TIMEOUT register.

Example for initialization of timestamp reference clock and synchronization of a seconds signal with the PC clock:

```

spcm_dwSetParam_i32 (hDrv, SPC_TIMESTAMP_CMD, SPC_TS MODE STANDARD | SPC_TSCNT_REFCLKPOS);
spcm_dwSetParam_i32 (hDrv, SPC_TIMESTAMP_TIMEOUT, 1500);
if (ERR_TIMESTAMP_SYNC == spcm_dwSetParam_i32 (hDrv, SPC_TIMESTAMP_CMD, SPC_TS_RESET_WAITREFCLK))
    printf ("Synchronization with external clock signal failed\n");

// now we read out the stored synchronization clock and date
int32 lSyncDate, lSyncTime;
spcm_dwGetParam_i32 (hDrv, SPC_TIMESTAMP_STARTDATE, &lSyncDate);
spcm_dwGetParam_i32 (hDrv, SPC_TIMESTAMP_STARTTIME, &lSyncTime);

// and print the start date and time information (European format: day.month.year hour:minutes:seconds)
printf ("Start date: %02d.%02d.%04d\n", lSyncDate & 0xff, (lSyncDate >> 8) & 0xff, (lSyncDate >> 16) & 0xffff);
printf ("Start time: %02d:%02d:%02d\n", (lSyncTime >> 16) & 0xff, (lSyncTime >> 8) & 0xff, lSyncTime & 0xff);

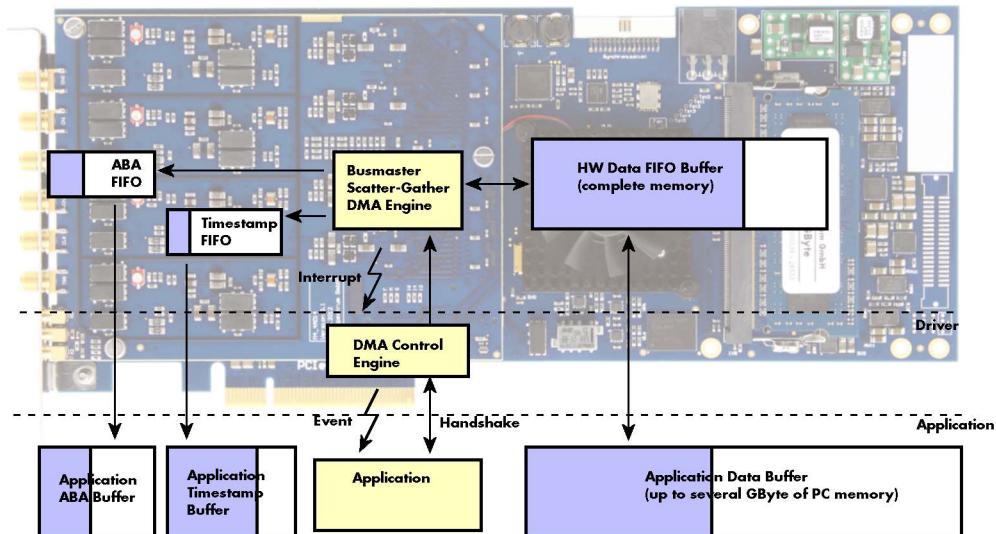
```

## Reading out the timestamps

### General

The timestamps are stored in an extra FIFO that is located in hardware on the card. This extra FIFO can read out timestamps using DMA transfer similar to the DMA transfer of the main sample data DMA transfer. The card has three completely independent busmaster DMA engines in hardware allowing the simultaneous transfer of both timestamp and sample data.

As seen in the picture there are separate FIFOs holding ABA and timestamp data.



Although an M4i is shown here, this applies to M4x and M2p cards as well. Each FIFO has its own DMA channel, the way data is handled by the DMA engine is similar for both kinds of extra FIFOs and is also very similar to the main sample data transfer engine. Therefore additional information can be found in the chapter explaining the main data transfer.

### Commands and Status information for extra transfer buffers.

As explained above the data transfer is performed with the same command and status registers like the card control and sample data transfer. It is possible to send commands for card control, data transfer and extra FIFO data transfer at the same time

Register	Value	Direction	Description
SPC_M2CMD	100	write only	Executes a command for the card or data transfer
M2CMD_EXTRA_STARTDMA	100000h		Starts the DMA transfer for an already defined buffer.
M2CMD_EXTRA_WAITDMA	200000h		Waits until the data transfer has ended or until at least the amount of bytes defined by notify size are available. This wait function also takes the timeout parameter into account.
M2CMD_EXTRA_STOPDMA	400000h		Stops a running DMA transfer. Data is invalid afterwards.
M2CMD_EXTRA_POLL	800000h		Polls data without using DMA. As DMA has some overhead and has been implemented for fast data transfer of large amounts of data it is in some cases more simple to poll for available data. Please see the detailed examples for this mode. It is not possible to mix DMA and polling mode.

The extra FIFO data transfer can generate one of the following status information::

Register	Value	Direction	Description
SPC_M2STATUS	110	read only	Reads out the current status information
M2STAT_EXTRA_BLOCKREADY	1000h		The next data block as defined in the notify size is available. It is at least the amount of data available but it also can be more data.
M2STAT_EXTRA_END	2000h		The data transfer has completed. This status information will only occur if the notify size is set to zero.

M2STAT_EXTRA_OVERRUN	4000h	The data transfer had an overrun (acquisition) or underrun (replay) while doing FIFO transfer.
M2STAT_EXTRA_ERROR	8000h	An internal error occurred while doing data transfer.

## Data Transfer using DMA

Data transfer consists of two parts: the buffer definition and the commands/status information that controls the transfer itself. Extra data transfer shares the command and status register with the card control, data transfer commands and status information.

The DMA based data transfer mode is activated as soon as the M2CMD\_EXTRA\_STARTDMA is given. Please see next chapter to see how the polling mode works.

### Definition of the transfer buffer

Before any data transfer can start it is necessary to define the transfer buffer with all its details. The definition of the buffer is done with the spcm\_dwDefTransfer function as explained in an earlier chapter. The following example will show the definition of a transfer buffer for timestamp data, definition for ABA data is similar:

```
spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_TIMESTAMP, SPCM_CARDTOPC, 0, pvBuffer, 0, lLenOfBufferInBytes);
```

In this example the notify size is set to zero, meaning that we don't want to be notified until all extra data has been transferred. Please have a look at the sample data transfer in an earlier chapter to see more details on the notify size.

Please note that extra data transfer is only possible from card to PC and there's no programmable offset available for this transfer.

### Buffer handling

A data buffer handshake is implemented in the driver which allows to run the card in different data transfer modes. The software transfer buffer is handled as one large buffer for each kind of data (timestamp and ABA) which is on the one side controlled by the driver and filled automatically by busmaster DMA from the hardware extra FIFO buffer and on the other hand it is handled by the user who set's parts of this software buffer available for the driver for further transfer. The handshake is fulfilled with the following 3 software registers:

Register	Value	Direction	Description
SPC_ABA_AVAIL_USER_LEN	210	read	This register contains the currently available number of bytes that are filled with newly transferred slow ABA data. The user can now use this ABA data for own purposes, copy it, write it to disk or start calculations with this data.
SPC_ABA_AVAIL_USER_POS	211	read	The register holds the current byte index position where the available ABA bytes start. The register is just intended to help you and to avoid own position calculation
SPC_ABA_AVAIL_CARD_LEN	212	write	After finishing the job with the new available ABA data the user needs to tell the driver that this amount of bytes is again free for new data to be transferred.
SPC_TS_AVAIL_USER_LEN	220	read	This register contains the currently available number of bytes that are filled with newly transferred timestamp data. The user can now use these timestamps for own purposes, copy it, write it to disk or start calculations with the timestamps.
SPC_TS_AVAIL_USER_POS	221	read	The register holds the current byte index position where the available timestamp bytes start. The register is just intended to help you and to avoid own position calculation
SPC_TS_AVAIL_CARD_LEN	222	write	After finishing the job with the new available timestamp data the user needs to tell the driver that this amount of bytes is again free for new data to be transferred.

Directly after start of transfer the SPC\_XXX\_AVAIL\_USER\_LEN is every time zero as no data is available for the user and the SPC\_XXX\_AVAIL\_CARD\_LEN is every time identical to the length of the defined buffer as the complete buffer is available for the card for transfer.

 **The counter that is holding the user buffer available bytes (SPC\_XXX\_AVAIL\_USER\_LEN) is sticking to the defined notify size at the DefTransfer call. Even when less bytes already have been transferred you won't get notice of it if the notify size is programmed to a higher value.**

### Remarks

- The transfer between hardware FIFO buffer and application buffer is done with scatter-gather DMA using a busmaster DMA controller located on the card. Even if the PC is busy with other jobs data is still transferred until the application buffer is completely used.
- As shown in the drawing above the DMA control will announce new data to the application by sending an event. Waiting for an event is done internally inside the driver if the application calls one of the wait functions. Waiting for an event does not consume any CPU time and is therefore highly requested if other threads do lot of calculation work. However it is not necessary to use the wait functions and one can simply request the current status whenever the program has time to do so. When using this polling mode the announced available bytes still stick to the defined notify size!
- If the on-board FIFO buffer has an overrun data transfer is stopped immediately.

### **Buffer handling example for DMA timestamp transfer (ABA transfer is similar, just using other registers)**

```

int8* pcData = (int8*) pvAllocMemPageAligned (lBufSizeInBytes);

// we now define the transfer buffer with the minimum notify size of one page = 4 kByte
spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_TIMESTAMP, SPCM_DIR_CARDTOPC, 4096, (void*) pcData, 0, lBufSizeInBytes);
do
{
    // we wait for the next data to be available. After this call we get at least 4k of data to proceed
    dwError = spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_EXTRA_STARTDMA | M2CMD_EXTRA_WAITDMA);

    if (!dwError)
    {

        // if there was no error we can proceed and read out the current amount of available data
        spcm_dwGetParam_i32 (hDrv, SPC_TS_AVAIL_USER_LEN, &lAvailBytes);
        spcm_dwGetParam_i32 (hDrv, SPC_TS_AVAIL_USER_POS, &lBytePos);

        printf ("We now have %d new bytes available\n", lAvailBytes);
        printf ("The available data starts at position %d\n", lBytePos);

        // we take care not to go across the end of the buffer
        if ((lBytePos + lAvailBytes) >= lBufSizeInBytes)
            lAvailBytes = lBufSizeInBytes - lBytePos;

        // our do function gets a pointer to the start of the available data section and the length
        vProcessTimestamps (&pcData[lBytePos], lAvailBytes);

        // the buffer section is now immediately set available for the card
        spcm_dwSetParam_i32 (hDrv, SPC_TS_AVAIL_CARD_LEN, lAvailBytes);
    }
}
while (!dwError); // we loop forever if no error occurs

```

**The extra FIFO has a quite small size compared to the main data buffer. As the transfer is done initiated by the hardware using busmaster DMA this is not critical as long as the application data buffers are large enough and as long as the extra transfer is started BEFORE starting the card.**



### **Data Transfer using Polling**

If the extra data is quite slow and the delay caused by the notify size on DMA transfers is unacceptable for your application it is possible to use the polling mode. Please be aware that the polling mode uses CPU processing power to get the data and that there might be an overrun if your CPU is otherwise busy. You should only use polling mode in special cases and if the amount of data to transfer is not too high.

Most of the functionality is similar to the DMA based transfer mode as explained above.

The polling data transfer mode is activated as soon as the M2CMD\_EXTRA\_POLL is executed.

#### **Definition of the transfer buffer**

This is similar to the above explained DMA buffer transfer. The value „notify size“ is ignored and should be set to 4k (4096).

#### **Buffer handling**

The buffer handling is also similar to the DMA transfer. As soon as one of the registers SPC\_TS\_AVAIL\_USER\_LEN or SPC\_ABA\_AVAIL\_USER\_LEN is read the driver will read out all available data from the hardware and will return the number of bytes that has been read. In minimum this will be one DWORD = 4 bytes.

### **Buffer handling example for polling timestamp transfer (ABA transfer is similar, just using other registers)**

```

int8* pcData = (int8*) pvAllocMemPageAligned (lBufSizeInBytes);

// we now define the transfer buffer with the minimum notify size of one page = 4 kByte
spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_TIMESTAMP, SPCM_DIR_CARDTOPC, 4096, (void*) pcData, 0, lBufSizeInBytes);

// we start the polling mode
dwError = spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_EXTRA_POLL);

// this is pure polling loop
do
{
    spcm_dwGetParam_i32 (hDrv, SPC_TS_AVAIL_USER_LEN, &lAvailBytes);
    spcm_dwGetParam_i32 (hDrv, SPC_TS_AVAIL_USER_POS, &lBytesPos);

    if (lAvailBytes > 0)
    {
        printf ("We now have %d new bytes available\n", lAvailBytes);
        printf ("The available data starts at position %d\n", lBytesPos);

        // we take care not to go across the end of the buffer
        if ((lBytesPos + lAvailBytes) >= lBufSizeInBytes)
            lAvailBytes = lBufSizeInBytes - lBytesPos;

        // our do function get's a pointer to the start of the available data section and the length
        vProcessTimestamps (&pcData[lBytesPos], lAvailBytes);

        // the buffer section is now immediately set available for the card
        spcm_dwSetParam_i32 (hDrv, SPC_TS_AVAIL_CARD_LEN, lAvailBytes);
    }
}
while (!dwError); // we loop forever if no error occurs

```

### **Comparison of DMA and polling commands**

This chapter shows you how small the difference in programming is between the DMA and the polling mode:

<b>DMA mode</b>	<b>Polling mode</b>
Define the buffer	spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_TIMESTAMP, SPCM_DIR...);
Start the transfer	spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_EXTRA_STARTDMA);
Wait for data	spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_EXTRA_WAITDMA);
Available bytes?	spcm_dwGetParam_i32 (hDrv, SPC_TS_AVAIL_USER_LEN, &lBytes);
Min available bytes	programmed notify size
Current position?	spcm_dwGetParam_i32 (hDrv, SPC_TS_AVAIL_USER_LEN, &lBytes);
Free buffer for card	spcm_dwSetParam_i32 (hDrv, SPC_TS_AVAIL_CARD_LEN, lBytes);

### **Data format**

Each timestamp is 128 bit long and internally mapped to two consecutive 64 bit (8 bytes) values. The lower 64 bit (counter value) contains the number of clocks that have been recorded with the currently used sampling rate since the last counter-reset has been done. The matching time can easily be calculated as described in the general information section at the beginning of this chapter.

The values the counter is counting and that are stored in the timestamp FIFO represent the moments the trigger event occurs internally. Compared to the real external trigger event, these values are delayed. This delay is fix and therefore can be ignored, as it will be identical for all recordings with the same setup.

### **Standard data format**

When internally mapping the timestamp from 128 bit to two 64 bit values, the unused upper 64 bits are filled up with zeros.

<b>Timestamp Mode</b>	<b>16<sup>th</sup> byte</b>	<b>...</b>	<b>11<sup>th</sup> byte</b>	<b>10<sup>th</sup> byte</b>	<b>9<sup>th</sup> byte</b>	<b>8<sup>th</sup> byte</b>	<b>7<sup>th</sup> byte</b>	<b>6<sup>th</sup> byte</b>	<b>5<sup>th</sup> byte</b>	<b>4<sup>th</sup> byte</b>	<b>3<sup>rd</sup> byte</b>	<b>2<sup>nd</sup> byte</b>	<b>1<sup>st</sup> byte</b>															
Standard/StartReset	0h																											
Refclock mode	0h																											
64 bit wide Timestamp																												
24 bit wide Refclock edge counter (seconds counter)																												
40 bit wide Timestamp																												

### **Extended timestamp data format**

Sometimes it is useful to store the level of additional external static signals together with a recording, such as e.g. control inputs of an external input multiplexer or settings of an external. When programming a special flag the upper 64 bit of every 128 bit timestamp value is not (as in standard data mode) filled up with leading zeros, but with the values of the digital inputs (X3, X2, X1) and optionally also (X19..X4). The following table shows the resulting 128 bit timestamps.

<b>Timestamp Mode</b>	<b>16<sup>th</sup> byte</b>	<b>...</b>	<b>15<sup>th</sup> byte</b>	<b>14<sup>th</sup> byte</b>	<b>...</b>	<b>9<sup>th</sup> byte</b>	<b>8<sup>th</sup> byte</b>	<b>7<sup>th</sup> byte</b>	<b>6<sup>th</sup> byte</b>	<b>5<sup>th</sup> byte</b>	<b>4<sup>th</sup> byte</b>	<b>3<sup>rd</sup> byte</b>	<b>2<sup>nd</sup> byte</b>	<b>1<sup>st</sup> byte</b>														
Standard/StartReset	0h																											
Refclock mode	0h																											
Extra Data Word																												
64 bit wide Timestamp																												
24 bit wide Refclock edge counter (seconds counter)																												
40 bit wide Timestamp																												

The above mentioned „Extra Data Word“ contains the following 48bit wide data, depending on the selected timestamp data format:

Timestamp Data Format	Bit 47	...	Bit 32	Bit 31	...	Bit 29	Bit 28	...	Bit 16	Bit 15	...	Bit 13	Bit 12	Bit 11	Bit 10	...	Bit 0
no special data format is set	0h																
SPC_TSXIOACQ_ENABLE	X19 .. X4 (option)		0h						X3 .. X1		0h						
SPC_TSFEAT_TRGSRC	0h		Trigger source bit-mask (X3, X2, X1) (see table below)		0h							Trigger source bit-mask (Ch0 .. Force) (see table below)					
SPC_TSXIOACQ_ENABLE   SPC_TSFEAT_TRGSRC	X19 .. X4 (option)		Trigger source bit-mask (X3, X2, X1) (see table below)		0h			X3 .. X1		0h		Trigger source bit-mask (Ch0 .. Force) (see table below)					

**The multi-purpose lines X19...X4 are only available when the additional digital I/O option (either DigSMB or DigFX2) is installed. For cards where this option is not installed, Bits 47 down to 32 are always zero.**



The trigger sources are encoded as follows:

SPC_TRGSRC_MASK_CH0	1h	Set when a trigger event occurring on channel 0 was leading to final trigger event.
SPC_TRGSRC_MASK_CH1	2h	Set when a trigger event occurring on channel 1 was leading to final trigger event.
SPC_TRGSRC_MASK_CH2	4h	Set when a trigger event occurring on channel 2 was leading to final trigger event.
SPC_TRGSRC_MASK_CH3	8h	Set when a trigger event occurring on channel 3 was leading to final trigger event.
SPC_TRGSRC_MASK_CH4	10h	Set when a trigger event occurring on channel 4 was leading to final trigger event.
SPC_TRGSRC_MASK_CH5	20h	Set when a trigger event occurring on channel 5 was leading to final trigger event.
SPC_TRGSRC_MASK_CH6	40h	Set when a trigger event occurring on channel 6 was leading to final trigger event.
SPC_TRGSRC_MASK_CH7	80h	Set when a trigger event occurring on channel 7 was leading to final trigger event.
SPC_TRGSRC_MASK_EXT0	100h	Set when a trigger event occurring on external trigger(Ext0) was leading to final trigger event.
SPC_TRGSRC_MASK_FORCE	400h	Set when a trigger event occurring by using the force trigger command is leading to final trigger event.
SPC_TRGSRC_MASK_X1	20000000h	Set when a trigger event occurring on TTL trigger(X1) is leading to final trigger event.
SPC_TRGSRC_MASK_X2	40000000h	Set when a trigger event occurring on TTL trigger(X2) is leading to final trigger event.
SPC_TRGSRC_MASK_X3	80000000h	Set when a trigger event occurring on TTL trigger(X3) is leading to final trigger event.

### Selecting the timestamp data format

Register	Value	Direction	Description
SPC_TIMESTAMP_CMD	47000	read/write	Programs a timestamp mode and performs commands as listed below
SPC_TSXIOACQ_ENABLE	1000h		Enables the trigger synchronous acquisition of the X1..X19 inputs with every stored timestamp in the upper 64 bit.
SPC_TSFEAT_TRGSRC	80000h		Enables the storage of the trigger source in the upper 64 bit of the timestamp value.

The selection between the different data format for the timestamps is done with a flag that is written to the timestamp command register. As this register is organized as a bitfield, the data format selection is available for all possible timestamp modes and different data modes can be combined.

## Combination of Memory Segmentation Options with Timestamps

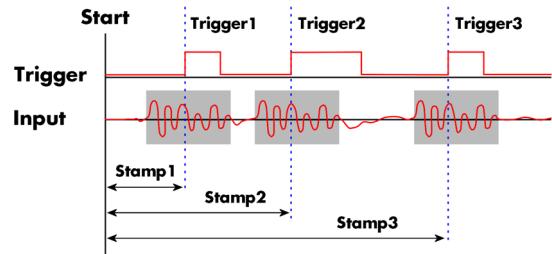
This topic should give you a brief overview how the timestamp option interacts with the options Multiple Recording and ABA mode for which the timestamps option has been made.

### Multiple Recording and Timestamps

Multiple Recording is well matching with the timestamp option. If timestamp recording is activated each trigger event and therefore each Multiple Recording segment will get timestamped as shown in the drawing on the right.

Please keep in mind that the trigger events are timestamped, not the beginning of the acquisition. The first sample that is available is at the time position of [Timestamp - Pretrigger].

The programming details of the timestamp option is explained in an extra chapter.



The following example shows the setup of the Multiple Recording mode together with activated timestamps recording and a short display of the acquired timestamps. The example doesn't care for the acquired data itself and doesn't check for error:

```
// setup of the Multiple Recording mode
spcm_dwSetParam_i32 (hDrv, SPC_CARDMODE, SPC_REC_STD_MULTI); // Enable Standard Multiple Recording
spcm_dwSetParam_i64 (hDrv, SPC_SEGMENTSIZE, 1024); // Segment size is 1 kSamples, Posttrigger is 768
spcm_dwSetParam_i64 (hDrv, SPC_POSTTRIGGER, 768); // samples and pretrigger therefore 256 samples.
spcm_dwSetParam_i64 (hDrv, SPC_MEMSIZE, 4096); // 4 kSamples in total acquired -> 4 segments

// setup the Timestamp mode and make a reset of the timestamp counter
spcm_dwSetParam_i32 (hDrv, SPC_TIMESTAMP_CMD, SPC_TSMODE_STANDARD | SPC_TSCNT_INTERNAL);
spcm_dwSetParam_i32 (hDrv, SPC_TIMESTAMP_CMD, SPC_TSMODE_RESET);

// now we define a buffer for timestamp data and start the acquisition. Each timestamp is 128 bit = 16 bytes.
int64* pllStamps = (int64*) pvAllocMemPageAligned (16 * 4);
spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_TIMESTAMP, SPCM_DIR_CARDTOPC, 0, (void*) pllStamps, 0, 4 * 16);
spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_CARD_START | M2CMD_CARD_ENABLETRIGGER | M2CMD_EXTRA_STARTDMA);

// we wait for the end timestamps transfer which will be received if all segments have been recorded
spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_EXTRA_WAITDMA);

// as we now have the timestamps we just print them and calculate the time in milli seconds
// for simplicity only the lower 64 bit part of the 128 bit stamp is used, hence only every
// second array element of pllStamps is used here.
int64 llSamplerate;
double dTime_ms;
spcm_dwGetParam_i64 (hDrv, SPC_SAMPLERATE, &llSamplerate);

for (int i = 0; i < 4; i++)
{
    dTime_ms = 1000.0 * pllStamps[2 * i] / llSamplerate;

    printf ("%d: %I64d samples = %.3f ms\n", i, pllStamps[2 * i], dTime_ms);
}
```

### Gate-End Alignment

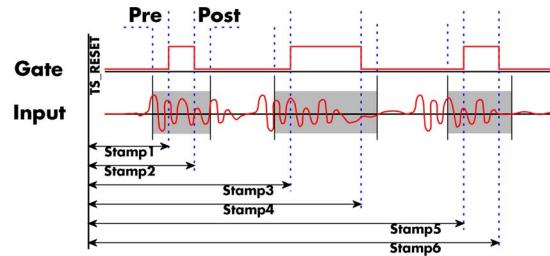
Due to the structure of the on-board memory, the length of a gate will be rounded up until the next card specific alignment:

Active Channels	M2i + M2i-exp		M4i + M4x		M2p 16bit
	8bit	12/14/16 bit	8bit	14/16 bit	
1 channel	4 Samples	2 Samples	32 Samples	16 Samples	8 Samples
2 channels	2 Samples	1 Samples	16 Samples	8 Samples	4 Samples
4 channels	1 Sample	1 Samples	8 Samples	4 Samples	2 Samples
8 channels	-	1 Samples	-	-	1 Samples
16 channels	-	1 Samples	-	-	-

So in case of a M4i.22xx card with 8bit samples and one active channel, the gate-end can only stop at 32Sample boundaries, so that up to 31 more samples can be recorded until the post-trigger starts. The timestamps themselves are not affected by this alignment.

## Gated Sampling and Timestamps

Gated Sampling and the timestamp mode fit very good together. If timestamp recording is activated each gate will get timestamped as shown in the drawing on the right. Both, beginning and end of the gate interval, are timestamped. Each gate segment will therefore produce two timestamps (Timestamp1 and Timestamp2) showing start of the gate interval and end of the gate interval. By taking both timestamps into account one can read out the time position of each gate as well as the length in samples. There is no other way to examine the length of each gate segment than reading out the timestamps.



Please keep in mind that the gate signals are timestamped, not the beginning and end of the acquisition. The first sample that is available is at the time position of [Timestamp1 - Pretrigger]. The length of the gate segment is [Timestamp2 - Timestamp1 + Alignment + Pretrigger + Posttrigger]. The last sample of the gate segment is at the position [Timestamp2 + Alignment + Posttrigger]. When using the standard gate mode the end of recording is defined by the expiring memsize counter. In standard gate mode there will be an additional timestamp for the last gate segment, when the maximum memsize is reached!

The programming details of the timestamp mode are explained in an extra chapter.

The following example shows the setup of the Gated Sampling mode together with activated timestamps recording and a short display of the acquired timestamps. The example doesn't care for the acquired data itself and doesn't check for error:

```
// setup of the Gated Sampling mode
spcm_dwSetParam_i32 (hDrv, SPC_CARDMODE, SPC_REC_STD_GATE); // Enables Standard Gated Sampling
spcm_dwSetParam_i64 (hDrv, SPC_PRETRIGGER, 32); // 32 samples to acquire before gate start
spcm_dwSetParam_i64 (hDrv, SPC_POSTTRIGGER, 32); // 32 samples to acquire before gate end
spcm_dwSetParam_i64 (hDrv, SPC_MEMSIZE, 4096); // 4 kSamples in total acquired

// setup the Timestamp mode and make a reset of the timestamp counter
spcm_dwSetParam_i32 (hDrv, SPC_TIMESTAMP_CMD, SPC_TSMODE_STANDARD | SPC_TSCNT_INTERNAL);
spcm_dwSetParam_i32 (hDrv, SPC_TIMESTAMP_CMD, SPC_TS_RESET);

// now we define a buffer for timestamp data and start acquisition, each timestamp is 128 bit = 16 bytes
// as we don't know the number of gate intervals we define the buffer quite large
int64* pllStamps = (int64*) pvAllocMemPageAligned (16 * 1000);
spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_TIMESTAMP, SPCM_DIR_CARDTOPC, 0, (void*) pllStamps, 0, 1000 * 16);
spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_CARD_START | M2CMD_CARD_ENABLEtrigger | M2CMD_EXTRA_STARTDMA);

// we wait for the end of timestamps transfer and read out the number of timestamps that have been acquired
int32 lAvailTimestampBytes;
spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_EXTRA_WAITDMA);
spcm_dwSetParam_i32 (hDrv, SPC_TS_AVAIL_USER_LEN, &lAvailTimestampBytes);

// as we now have the timestamps we just print them and calculate the time in milli seconds
// for simplicity only the lower 64 bit part of the 128 bit stamp is used, hence only every
// second array element of pllStamps is used here.
int64 llSamplerate, llLen, llAlign;
double dTime_ms;
spcm_dwGetParam_i64 (hDrv, SPC_SAMPLERATE, &llSamplerate);
spcm_dwGetParam_i64 (hDrv, SPC_GATE_LEN_ALIGNMENT, &llAlign);

// each even 128 bit timestamp is the start position of a gate segment each odd stamp is the end position
for (int i = 0; (i < (lAvailTimestampBytes / 16)) && (i < 1000); i++)
{
    dTime_ms = 1000.0 * pllStamps[4 * i] / llSamplerate;
    llLen = pllStamps[4 * i + 2] - pllStamps[4 * i] + 32 + 32; // (stop - start) + pre + post

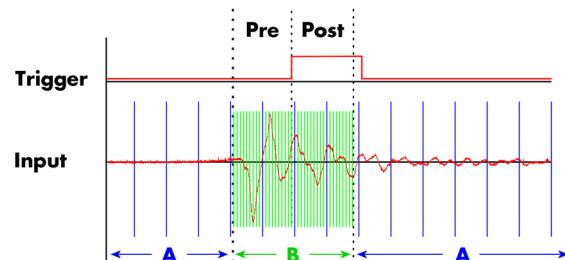
    if ((llLen % llAlign) != 0)
        llLen = (llLen + llAlign) - (llLen % llAlign); // correct for alignment

    printf ("%d: Start %I64d samples = %.3f ms", i, pllStamps[4 * i], dTime_ms);
    printf ("(Len = %I64d samples)\n", llLen);
}
```

## ABA Mode and Timestamps

The ABA mode is well matching with the timestamp option. If timestamp recording is activated, each trigger event and therefore each B time base segment will get time stamped as shown in the drawing on the right.

Please keep in mind that the trigger events - located in the B area - are timestamped, not the beginning of the acquisition. The first B sample that is available is at the time position of [Timestamp - Pretrigger].



The first A area sample is related to the card start and therefore in a fixed but various settings dependent relation to the timestamped B sample. To bring exact relation between the first A area sample (and therefore all area A samples) and the B area samples it is possible to let the card stamp the first A area sample automatically after the card start. The following table shows the register to enable this mode:

Register	Value	Direction	Description
SPC_TIMESTAMP_CMD	47000	read/write	Programs a timestamp setup including mode and additional features
SPC_TSFEAT_MASK	F0000h		Mask for the feature relating bits of the SPC_TIMESTAMP_CMD bitmask.
SPC_TSFEAT_STORE1STABA	10000h		Enables storage of one additional timestamp for the first A area sample (B time base related) in addition to the trigger related timestamps.
SPC_TSFEAT_NONE	0h		No additional timestamp is created. The total number of stamps is only trigger related.

This mode is compatible with all existing timestamp modes. Please keep in mind that the timestamp counter is running with the B area time-base.

```
// normal timestamp setup (e.g. setting timestamp mode to standard using internal clocking)
uint32 dwTimestampMode = (SPC_TSMODE_STANDARD | SPC_TSMODE_DISABLE);

// additionally enable index of the first A area sample
dwTimestampMode |= SPC_TSFEAT_STORE1STABA;

spcm_dwSetParam_i32 (hDrv, SPC_TIMESTAMP_CMD, dwTimestampMode);
```

The programming details of the ABA mode and timestamp modes are each explained in an dedicated chapter in this manual.

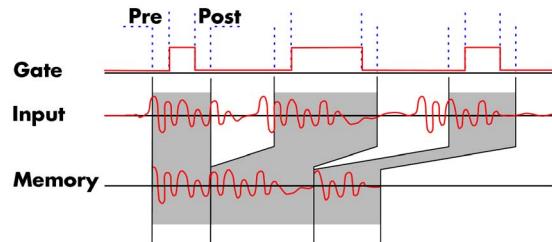
## Mode Gated Sampling

The Gated Sampling mode allows the data acquisition controlled by an external or an internal gate signal. Data will only be recorded if the programmed gate condition is true. When using the Gated Sampling acquisition mode it is in addition also possible to program a pre- and/or posttrigger for recording samples prior to and/or after the valid gate.

This chapter will explain all the necessary software register to set up the card for Gated Sampling properly.

The section on the allowed trigger modes deals with detailed description on the different trigger events and the resulting gates.

When using Gated Sampling the maximum pretrigger is limited as shown in the technical data section. When the programmed value exceeds that limit, the driver will return the error `ERR_PRETRIGGERLEN`.



Register	Value	Direction	Description
SPC_PRETRIGGER	10030	read/write	Defines the number of samples to be recorded per channel prior to the gate start.
SPC_POSTTRIGGER	10100	read/write	Defines the number of samples to be recorded per channel after the gate end.

## Acquisition modes

### Standard Mode

Data will be recorded as long as the gate signal fulfills the programmed gate condition. At the end of the gate interval the recording will be stopped and the card will pause until another gates signal appears. If the total amount of data to acquire has been reached, the card stops immediately. For that reason the last gate segment is ended by the expiring memory size counter and not by the gate end signal. The total amount of samples to be recorded can be defined by the memsize register. The table below shows the register for enabling Gated Sampling. For detailed information on how to setup and start the standard acquisition mode please refer to the according chapter earlier in this manual.

Register	Value	Direction	Description
SPC_CARDMODE	9500	read/write	Defines the used operating mode
SPC_REC_STD_GATE	4		Enables Gated Sampling for standard acquisition.

The total number of samples to be recorded to the on-board memory in Standard Mode is defined by the SPC\_MEMSIZE register.

Register	Value	Direction	Description
SPC_MEMSIZE	10000	read/write	Defines the total number of samples to be recorded per channel.

### FIFO Mode

The Gated Sampling in FIFO Mode is similar to the Gated Sampling in Standard Mode. In contrast to the Standard Mode you cannot program a certain total amount of samples to be recorded, but two other end conditions can be set instead. The acquisition can either run until the user stops it by software (infinite recording), or until a programmed number of gates has been recorded. The data is read continuously by the driver. This data is online available for further data processing by the user program. The advantage of Gated Sampling in FIFO mode is that you can stream data online to the host system with a lower average data rate than in conventional FIFO mode without Gated Sampling. You can make real-time data processing or store a huge amount of data to the hard disk. The table below shows the dedicated register for enabling Gated Sampling in FIFO mode. For detailed information how to setup and start the card in FIFO mode please refer to the according chapter earlier in this manual.

Register	Value	Direction	Description
SPC_CARDMODE	9500	read/write	Defines the used operating mode
SPC_REC_FIFO_GATE	64		Enables Gated Sampling for FIFO acquisition.

The number of gates to be recorded must be set separately with the register shown in the following table:

Register	Value	Direction	Description
SPC_LOOPS	10020	read/write	Defines the number of gates to be recorded
0			Recording will be infinite until the user stops it.
1 ... [4G - 1]			Defines the total number of gates to be recorded.

## Limits of pre trigger, post trigger, memory size

The maximum memory size parameter is only limited by the number of activated channels and by the amount of installed memory. Please keep in mind that each samples needs 2 bytes of memory to be stored. Minimum memory size as well as minimum and maximum post trigger limits are independent of the activated channels or the installed memory.

Due to the internal organization of the card memory there is a certain stepsize when setting these values that has to be taken into account. The following table gives you an overview of all limits concerning pre trigger, post trigger, memory size, segment size and loops. The table shows all values in relation to the installed memory size in samples. If more memory is installed the maximum memory size figures will increase according to the complete installed memory

Activated Channels	Used Mode	Memory size SPC_MEMSIZE			Pre trigger SPC_PRETRIGGER			Post trigger SPC_POSTTRIGGER			Segment size SPC_SEGMENTSIZE			Loops SPC_LOOPS		
		Min	Max	Step	Min	Max	Step	Min	Max	Step	Min	Max	Step	Min	Max	Step
1 Ch	Standard Single	16	Mem	8	8	Mem - 8	8	8	8G - 8	8	not used			not used		
	Standard Multi/ABA	16	Mem	8	8	32k	8	8	Mem - 8	8	16	Mem	8	not used		
	Standard Gate	16	Mem	8	8	32k	8	8	Mem - 8	8	not used			not used		
	FIFO Single	not used			8	32k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1
	FIFO Multi/ABA	not used			8	32k	8	8	8G - 8	8	16	pre+post	8	0 (∞)	4G - 1	1
	FIFO Gate	not used			8	32k	8	8	8G - 8	8	not used			0 (∞)	4G - 1	1
2 Ch	Standard Single	16	Mem/2	8	8	Mem/2 - 8	8	8	8G - 8	8	not used			not used		
	Standard Multi/ABA	16	Mem/2	8	8	16k	8	8	Mem/2 - 8	8	16	Mem/2	8	not used		
	Standard Gate	16	Mem/2	8	8	16k	8	8	Mem/2 - 8	8	not used			not used		
	FIFO Single	not used			8	16k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1
	FIFO Multi/ABA	not used			8	16k	8	8	8G - 8	8	16	pre+post	8	0 (∞)	4G - 1	1
	FIFO Gate	not used			8	16k	8	8	8G - 8	8	not used			0 (∞)	4G - 1	1
4 Ch	Standard Single	16	Mem/4	8	8	Mem/4 - 8	8	8	8G - 16	8	not used			not used		
	Standard Multi/ABA	16	Mem/4	8	8	8k	8	8	Mem/4 - 8	8	16	Mem/4	8	not used		
	Standard Gate	16	Mem/4	8	8	8k	8	8	Mem/4 - 8	8	not used			not used		
	FIFO Single	not used			8	8k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1
	FIFO Multi/ABA	not used			8	8k	8	8	8G - 16	8	16	pre+post	8	0 (∞)	4G - 1	1
	FIFO Gate	not used			8	8k	8	8	8G - 16	8	not used			0 (∞)	4G - 1	1
8 Ch	Standard Single	16	Mem/8	8	8	Mem/8 - 8	8	8	8G - 8	8	not used			not used		
	Standard Multi/ABA	16	Mem/8	8	8	4k	8	8	Mem/8 - 8	8	16	Mem/8	8	not used		
	Standard Gate	16	Mem/8	8	8	4k	8	8	Mem/8 - 8	8	not used			not used		
	FIFO Single	not used			8	4k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1
	FIFO Multi/ABA	not used			8	4k	8	8	8G - 16	8	16	pre+post	8	0 (∞)	4G - 1	1
	FIFO Gate	not used			8	4k	8	8	8G - 16	8	not used			0 (∞)	4G - 1	1

All figures listed here are given in samples. An entry of [8G - 16] means [8 GSamples - 16] = 8,589,934,576 samples.

The given memory and memory / divider figures depend on the installed on-board memory as listed below:

Installed Memory	
<b>512 MSample</b>	
Mem	512 MSample
Mem/2	256 MSample
Mem/4	128 MSample
Mem/8	64 MSample

Please keep in mind that this table shows all values at once. Only the absolute maximum and minimum values are shown. There might be additional limitations. Which of these values are programmed depends on the used mode. Please read the detailed documentation of the mode.

## Gate-End Alignment

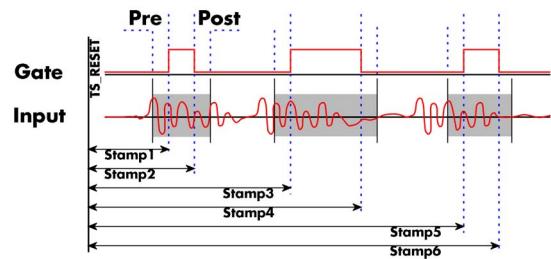
Due to the structure of the on-board memory, the length of a gate will be rounded up until the next card specific alignment:

Active Channels	M2i + M2i-exp		M4i + M4x		M2p 16bit
	8bit	12/14/16 bit	8bit	14/16 bit	
1 channel	4 Samples	2 Samples	32 Samples	16 Samples	8 Samples
2 channels	2 Samples	1 Samples	16 Samples	8 Samples	4 Samples
4 channels	1 Sample	1 Samples	8 Samples	4 Samples	2 Samples
8 channels	–	1 Samples	–	–	1 Samples
16 channels	–	1 Samples	–	–	–

So in case of a M4i.22xx card with 8bit samples and one active channel, the gate-end can only stop at 32Sample boundaries, so that up to 31 more samples can be recorded until the post-trigger starts. The timestamps themselves are not affected by this alignment.

## Gated Sampling and Timestamps

Gated Sampling and the timestamp mode fit very good together. If timestamp recording is activated each gate will get timestamped as shown in the drawing on the right. Both, beginning and end of the gate interval, are timestamped. Each gate segment will therefore produce two timestamps (Timestamp1 and Timestamp2) showing start of the gate interval and end of the gate interval. By taking both timestamps into account one can read out the time position of each gate as well as the length in samples. There is no other way to examine the length of each gate segment than reading out the timestamps.



Please keep in mind that the gate signals are timestamped, not the beginning and end of the acquisition. The first sample that is available is at the time position of [Timestamp1 - Pretrigger]. The length of the gate segment is [Timestamp2 - Timestamp1 + Alignment + Pretrigger + Posttrigger]. The last sample of the gate segment is at the position [Timestamp2 + Alignment + Posttrigger]. When using the standard gate mode the end of recording is defined by the expiring memsize counter. In standard gate mode there will be an additional timestamp for the last gate segment, when the maximum memsize is reached!

The programming details of the timestamp mode are explained in an extra chapter.

## Trigger

### Detailed description of the external analog trigger modes

For all external analog trigger modes shown below, either the OR mask or the AND must contain the external trigger to activate the external input as trigger source.:

Register	Value	Direction	Description
SPC_TRIG_ORMASK	40410	read/write	Defines the events included within the trigger OR mask of the card.
SPC_TRIG_ANDMASK	40430	read/write	Defines the events included within the trigger AND mask of the card.
SPC_TMASK_EXT0	2h		Enables the main external (analog) trigger 0 for the mask.

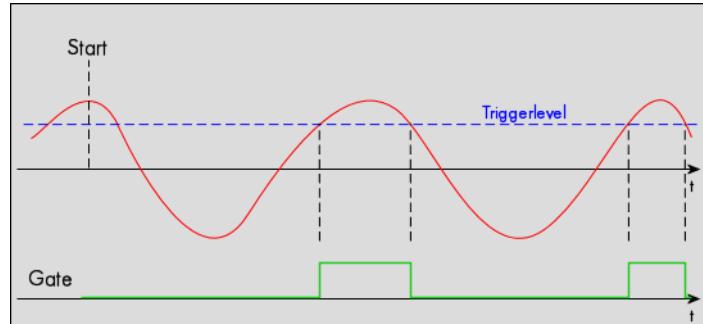
The following pages explain the available modes in detail. All modes that only require one single trigger level are available for both external trigger inputs. All modes that require two trigger levels are only available for the main external trigger input (Ext0).

#### Trigger on positive edge

The trigger input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the trigger signal from lower values to higher values (rising edge) then the gate starts.

When the signal crosses the programmed trigger level from higher values to lower values (falling edge) then the gate will stop.

As this mode is purely edge-triggered, the high level at the cards start time does not trigger the board.



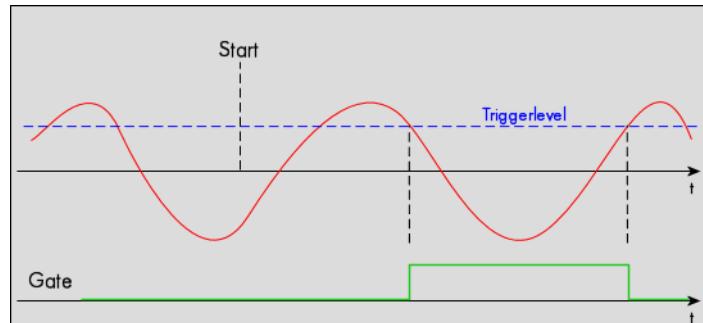
Register	Value	Direction	set to	Value
SPC_TRIG_EXT0_MODE	40510	read/write	SPC_TM_POS	1h
SPC_TRIG_EXT0_LEVEL0	42320	read/write	Set it to the desired trigger level in mV.	mV

#### Trigger on negative edge

The trigger input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the trigger signal from higher values to lower values (falling edge) then the gate starts.

When the signal crosses the programmed trigger from lower values to higher values (rising edge) then the gate will stop.

As this mode is purely edge-triggered, the low level at the cards start time does not trigger the board.



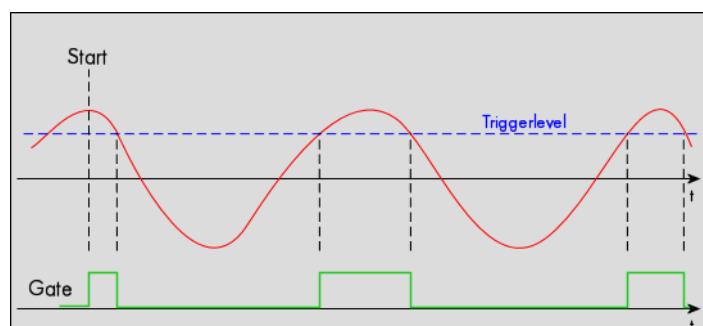
Register	Value	Direction	set to	Value
SPC_TRIG_EXT0_MODE	40510	read/write	SPC_TM_NEG	2h
SPC_TRIG_EXT0_LEVEL0	42320	read/write	Set it to the desired trigger level in mV.	mV

#### High level trigger

The external input is continuously sampled with the selected sample rate. If the signal is equal or higher than the programmed trigger level the gate starts.

When the signal is lower than the programmed trigger level the gate will stop.

As this mode is level-triggered, the high level at the cards start time does trigger the board.



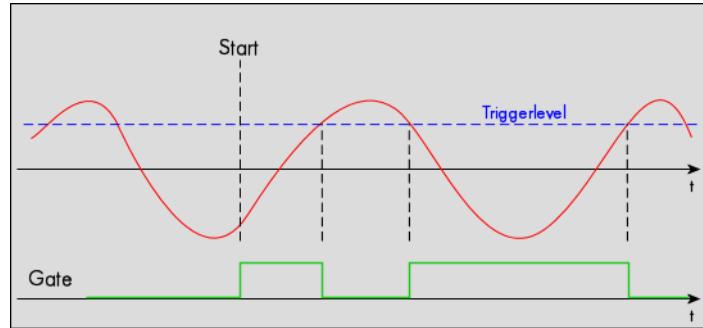
Register	Value	Direction	set to	Value
SPC_TRIG_EXT0_MODE	40510	read/write	SPC_TM_HIGH	00000008h
SPC_TRIG_EXT0_LEVEL0	42320	read/write	Set it to the desired trigger level in mV.	mV

**Low level trigger**

The external input is continuously sampled with the selected sample rate. If the signal is equal or lower than the programmed trigger level the gate starts.

When the signal is higher than the programmed trigger level the gate will stop.

As this mode is level-triggered, the high level at the cards start time does trigger the board.

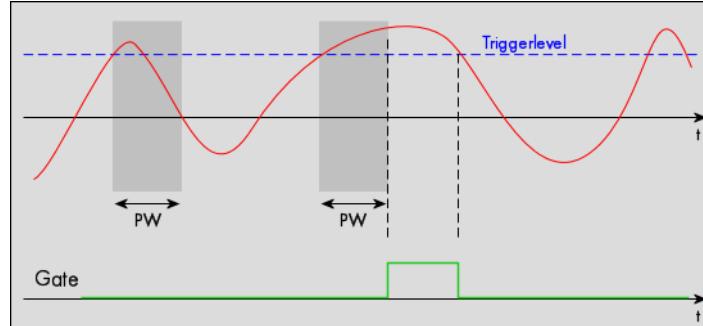


Register	Value	Direction	set to	Value
SPC_TRIG_EXTO_MODE	40510	read/write	SPC_TM_LOW	00000010h
SPC_TRIG_EXTO_LEVEL0	42320	read/write	Set it to the desired trigger level in mV.	mV

**Pulsewidth trigger for long positive pulses**

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal from lower to higher values (rising edge) the pulsewidth counter is started. If the signal crosses the trigger level again in the opposite direction within the programmed pulsewidth time, no trigger will be detected. If the pulsewidth counter reaches the programmed amount of samples, without the signal crossing the trigger level in the opposite direction, the gate will start.

If the programmed trigger level is crossed by the channel's signal from higher to lower values (falling edge) the gate will stop.



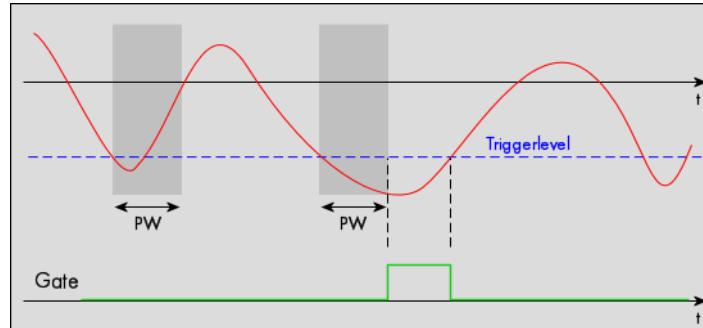
The pulsewidth trigger modes for long pulses can be used to prevent the board from triggering on wrong (short) edges in noisy signals.

Register	Value	Direction	set to	Value
SPC_TRIG_EXTO_MODE	40510	read/write	SPC_TM_POS   SPC_TM_PW_GREATER	04000001h
SPC_TRIG_EXTO_LEVEL0	42320	read/write	Set it to the desired trigger level in mV.	mV
SPC_TRIG_CHO_PULSEWIDTH	44101	read/write	Sets the pulsewidth in samples. Values from 2 to [4G - 1] are allowed.	2 to [4G - 1]

**Pulsewidth trigger for long negative pulses**

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal from higher to lower values (falling edge) the pulsewidth counter is started. If the signal crosses the trigger level again in the opposite direction within the programmed pulsewidth time, no trigger will be detected. If the pulsewidth counter reaches the programmed amount of samples, without the signal crossing the trigger level in the opposite direction, the gate will start.

If the programmed trigger level is crossed by the channel's signal from lower to higher values (rising edge) the gate will stop.



The pulsewidth trigger modes for long pulses can be used to prevent the board from triggering on wrong (short) edges in noisy signals.

Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_NEG   SPC_TM_PW_GREATER	04000002h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level in mV	mV
SPC_TRIG_CHO_PULSEWIDTH	44101	read/write	Sets the pulsewidth in samples. Values from 2 to [4G - 1] are allowed.	2 to [4G - 1]

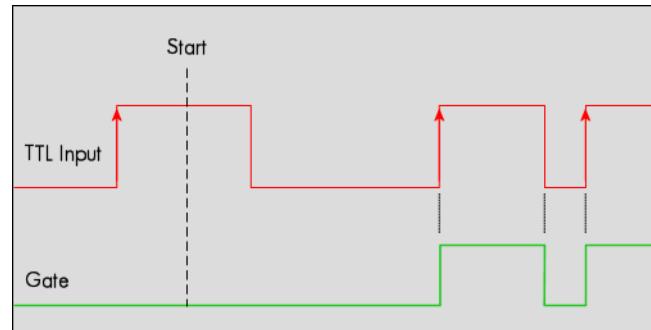
## **Detailed description of the logic gate trigger modes**

### **Positive TTL edge trigger**

This mode is for detecting the rising edges of an external TTL signal. The gate will start on rising edges that are detected after starting the board.

As this mode is purely edge-triggered, the high level at the cards start time, does not trigger the board.

With the next falling edge the gate will be stopped.



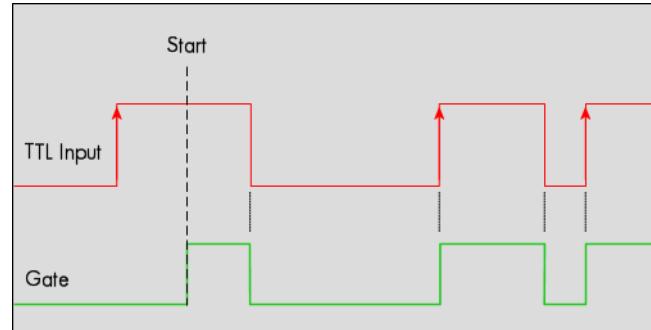
Register	Value	Direction	set to	Value
SPC_TRIG_EXT1_MODE	40511	read/write	SPC_TM_POS	
SPC_TRIG_EXT2_MODE	40512			
SPC_TRIG_EXT3_MODE	40513			1h

### **HIGH TTL level trigger**

This mode is for detecting the high levels of an external TTL signal. The gate will start on high levels that are detected after starting the board acquisition/generation.

As this mode is purely level-triggered, the high level at the cards start time, does trigger the board.

With the next low level the gate will be stopped.



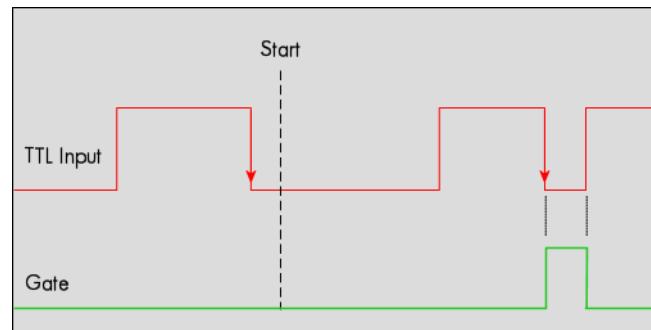
Register	Value	Direction	set to	Value
SPC_TRIG_EXT1_MODE	40511	read/write	SPC_TM_HIGH	
SPC_TRIG_EXT2_MODE	40512			
SPC_TRIG_EXT3_MODE	40513			8h

### **Negative TTL edge trigger**

This mode is for detecting the falling edges of an external TTL signal. The gate will start on falling edges that are detected after starting the board.

As this mode is purely edge-triggered, the low level at the cards start time, does not trigger the board.

With the next rising edge the gate will be stopped.



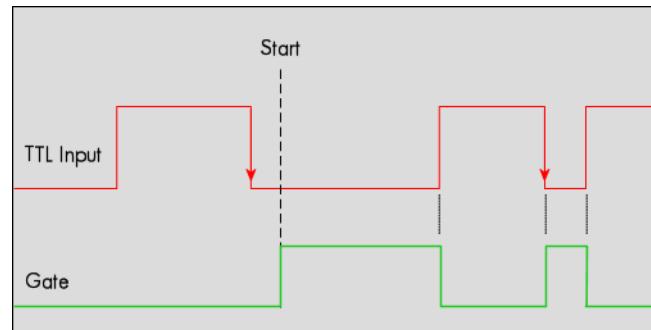
Register	Value	Direction	set to	Value
SPC_TRIG_EXT1_MODE	40511	read/write	SPC_TM_NEG	
SPC_TRIG_EXT2_MODE	40512			
SPC_TRIG_EXT3_MODE	40513			2h

### **LOW TTL level trigger**

This mode is for detecting the low levels of an external TTL signal. The gate will start on low levels that are detected after starting the board.

As this mode is purely level-triggered, the low level at the cards start time, does trigger the board.

With the next high level the gate will be stopped.



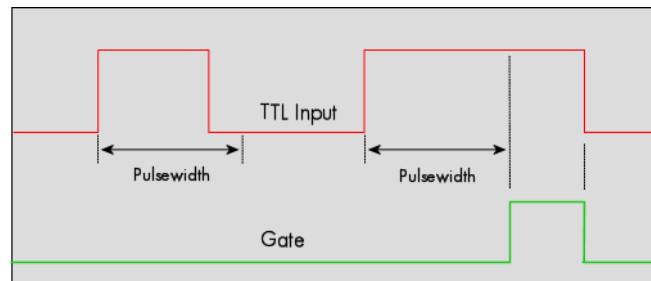
Register	Value	Direction	set to	Value
SPC_TRIG_EXT1_MODE	40511	read/write	SPC_TM_LOW	
SPC_TRIG_EXT2_MODE	40512			
SPC_TRIG_EXT3_MODE	40513			10h

### **TTL pulselength trigger for long HIGH pulses**

This mode is for detecting a rising edge of an external TTL signal followed by a HIGH pulse that are longer than a programmed pulselength. If the pulse is shorter than the programmed pulselength, no trigger will be detected.

The gate will start on the first pulse matching the trigger condition after starting the board.

The gate will stop with the next falling edge.



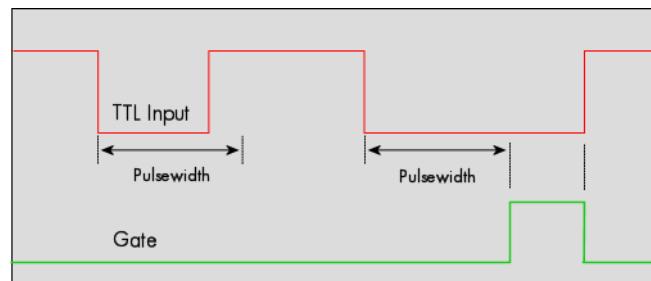
Register	Value	Direction	set to	Value
SPC_TRIG_EXT1_PULSEWIDTH	44211	read/write	Sets the pulselength in samples.	2 up to [4G-1]
SPC_TRIG_EXT2_PULSEWIDTH	44212			
SPC_TRIG_EXT3_PULSEWIDTH	44213			
SPC_TRIG_EXT1_MODE	40511	read/write	(SPC_TM_POS   SPC_TM_PW_GREATER)	4000001h
SPC_TRIG_EXT2_MODE	40512			
SPC_TRIG_EXT3_MODE	40513			

### **TTL pulselength trigger for long LOW pulses**

This mode is for detecting a falling edge of an external TTL signal followed by a LOW pulse that are longer than a programmed pulselength. If the pulse is shorter than the programmed pulselength, no trigger will be detected.

The gate will start on the first pulse matching the trigger condition after starting the board.

The gate will stop with the next rising edge.



Register	Value	Direction	set to	Value
SPC_TRIG_EXT1_PULSEWIDTH	44211	read/write	Sets the pulselength in samples.	2 up to [4G-1]
SPC_TRIG_EXT2_PULSEWIDTH	44212			
SPC_TRIG_EXT3_PULSEWIDTH	44213			
SPC_TRIG_EXT1_MODE	40511	read/write	(SPC_TM_NEG   SPC_TM_PW_GREATER)	4000002h
SPC_TRIG_EXT2_MODE	40512			
SPC_TRIG_EXT3_MODE	40513			

The following example shows, how to setup the card for using external TTL pulse width trigger on EXT1 (X1) input:

```
// Setting up external X1 TTL trigger to detect low pulses that are longer than 50 samples ...
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXT1_MODE, SPC_TM_NEG | SPC_TM_PW_GREATER);
spcm_dwSetParam_i64 (hDrv, SPC_TRIG_EXT1_PULSEWIDTH,
                     50);
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK,
                     SPC_TMASK_EXT1); // ... and enable it in OR mask
```

## Channel triggers modes

For all channel trigger modes, the OR mask must contain the corresponding input channels (channel 0 taken as example here):.

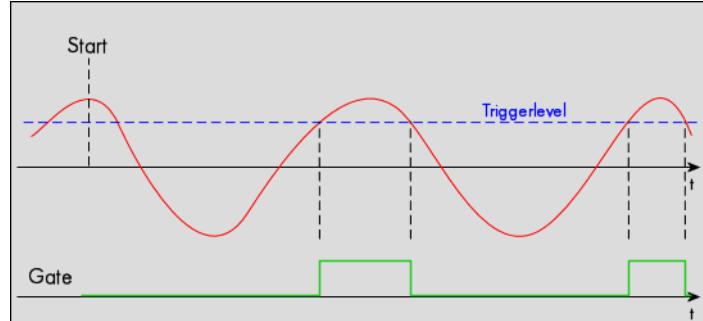
Register	Value	Direction	Description
SPC_TRIG_CH_ORMASK0	40460	read/write	Defines the OR mask for the channel trigger sources.
SPC_TMASKO_CHO	1h		Enables channel0 input for the channel OR mask

### Channel trigger on positive edge

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal from lower values to higher values (rising edge) the gate starts.

When the signal crosses the programmed trigger level from higher values to lower values (falling edge) then the gate will stop.

As this mode is purely edge-triggered, the high level at the cards start time does not trigger the board.



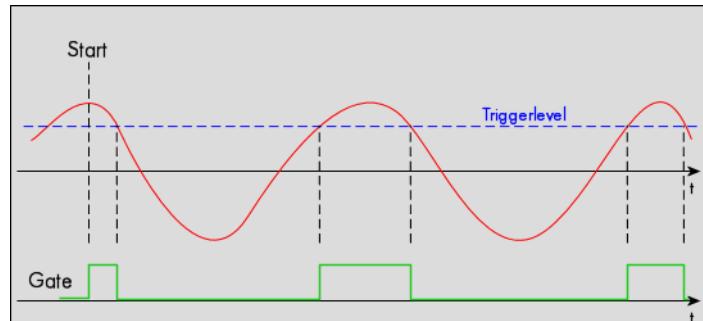
Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_POS	1h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant

### Channel trigger HIGH level

The analog input is continuously sampled with the selected sample rate. If the signal is equal or higher than the programmed trigger level the gate starts.

When the signal is lower than the programmed trigger level the gate will stop.

As this mode is level-triggered, the high level at the cards start time does trigger the board.



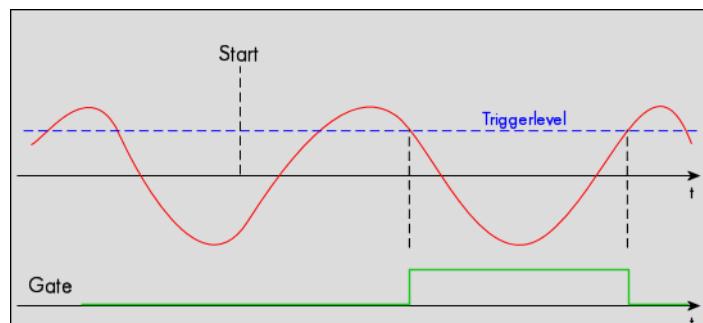
Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_HIGH	8h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant

### Channel trigger on negative edge

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal higher values to lower values (falling edge) the gate starts.

When the signal crosses the programmed trigger from lower values to higher values (rising edge) then the gate will stop.

As this mode is purely edge-triggered, the low level at the cards start time does not trigger the board.



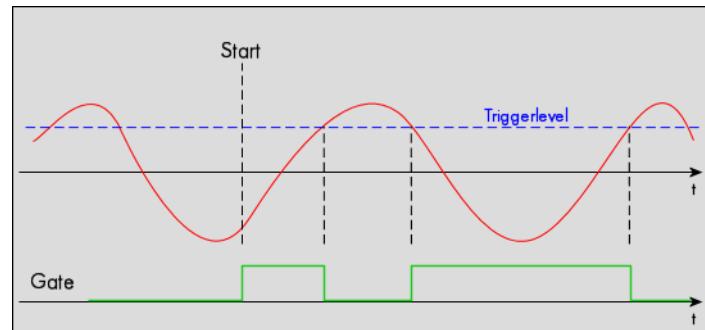
Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_NEG	2h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant

### **Channel trigger LOW level**

The analog input is continuously sampled with the selected sample rate. If the signal is equal or lower than the programmed trigger level the gate starts.

When the signal is higher than the programmed trigger level the gate will stop.

As this mode is level-triggered, the high level at the cards start time does trigger the board.



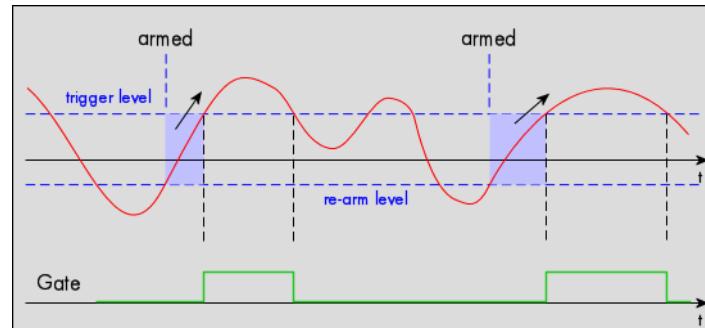
Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_LOW	10h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant

### **Channel re-arm trigger on positive edge**

The analog input is continuously sampled with the selected sample rate. If the programmed re-arm level is crossed from lower to higher values, the trigger engine is armed and waiting for trigger.

If the programmed trigger level is crossed by the channel's signal from lower values to higher values (rising edge) then the gate starts and the trigger engine will be disarmed.

If the programmed trigger level is crossed by the channel's signal from higher values to lower values (falling edge) the gate stops.



A new trigger event is only detected, if the trigger engine is armed again. The re-arm trigger modes can be used to prevent the board from triggering on wrong edges in noisy signals.

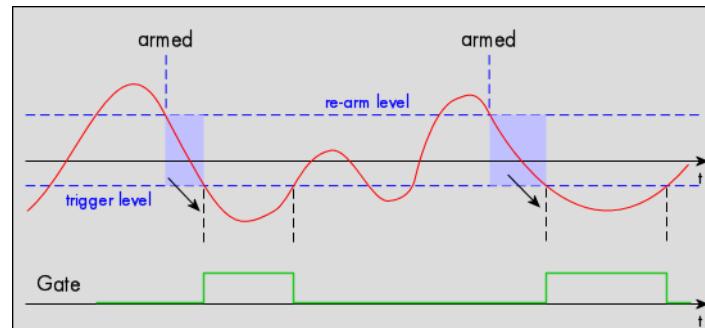
Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_POS   SPC_TM_REARM	01000001h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Defines the re-arm level relatively to the channels's input range	board dependant

### **Channel re-arm trigger on negative edge**

The analog input is continuously sampled with the selected sample rate. If the programmed re-arm level is crossed from higher to lower values, the trigger engine is armed and waiting for trigger.

If the programmed trigger level is crossed by the channel's signal from higher values to lower values (falling edge) then the gate starts and the trigger engine will be disarmed.

If the programmed trigger level is crossed by the channel's signal from lower values to higher values (rising edge) the gate stops.



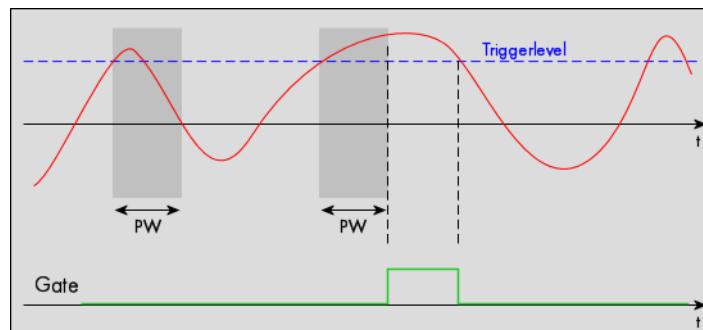
A new trigger event is only detected, if the trigger engine is armed again. The re-arm trigger modes can be used to prevent the board from triggering on wrong edges in noisy signals.

Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_NEG   SPC_TM_REARM	01000002h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Defines the re-arm level relatively to the channels's input range	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Defines the re-arm level relatively to the channels's input range	board dependant

### **Channel pulsewidth trigger for long positive pulses**

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal from lower to higher values (rising edge) the pulsewidth counter is started. If the signal crosses the trigger level again in the opposite direction within the the programmed pulselwidth time, no trigger will be detected. If the pulselwidth counter reaches the programmed amount of samples, without the signal crossing the trigger level in the opposite direction, the gate will start.

If the programmed trigger level is crossed by the channel's signal from higher to lower values (falling edge) the gate will stop.



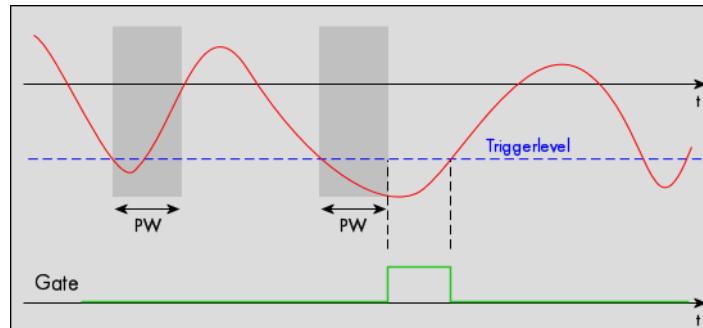
The pulselwidth trigger modes for long pulses can be used to prevent the board from triggering on wrong (short) edges in noisy signals.

Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_POS   SPC_TM_PW_GREATER	04000001h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_PULSEWIDTH	44101	read/write	Sets the pulselwidth in samples. Values from 2 to [4G - 1] are allowed.	2 to [4G - 1]

### **Channel pulsewidth trigger for long negative pulses**

The analog input is continuously sampled with the selected sample rate. If the programmed trigger level is crossed by the channel's signal from higher to lower values (falling edge) the pulselwidth counter is started. If the signal crosses the trigger level again in the opposite direction within the the programmed pulselwidth time, no trigger will be detected. If the pulselwidth counter reaches the programmed amount of samples, without the signal crossing the trigger level in the opposite direction, the gate will start.

If the programmed trigger level is crossed by the channel's signal from lower to higher values (rising edge) the gate will stop.



The pulselwidth trigger modes for long pulses can be used to prevent the board from triggering on wrong (short) edges in noisy signals.

Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_NEG   SPC_TM_PW_GREATER	04000002h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_PULSEWIDTH	44101	read/write	Sets the pulselwidth in samples. Values from 2 to [4G - 1] are allowed.	2 to [4G - 1]

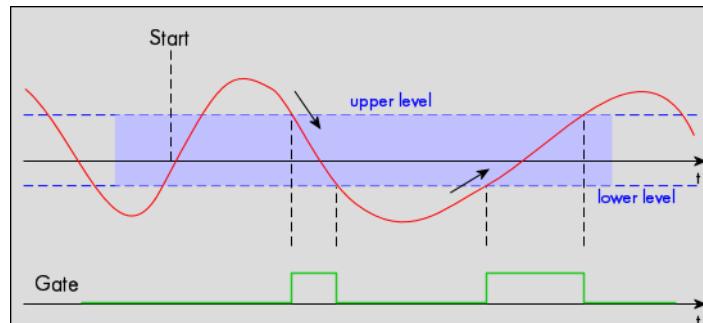
### **Channel window trigger for entering signals**

The analog input is continuously sampled with the selected sample rate. The upper and the lower level define a window.

When the signal enters the window from the outside to the inside, the gate will start.

When the signal leaves the window from the inside to the outside, the gate will stop.

As this mode is purely edge-triggered, the signal outside the window at the cards start time does not trigger the board.



Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_WINENTER	00000020h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the upper trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Set it to the lower trigger level relatively to the channel's input range.	board dependant

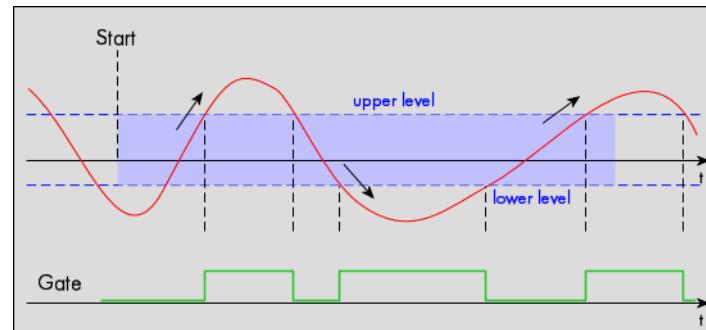
### Channel window trigger for leaving signals

The analog input is continuously sampled with the selected sample rate. The upper and the lower level define a window.

When the signal leaves the window from the inside to the outside, the gate will start.

When the signal enters the window from the outside to the inside, the gate will stop.

As this mode is purely edge-triggered, the signal within the window at the cards start time does not trigger the board.



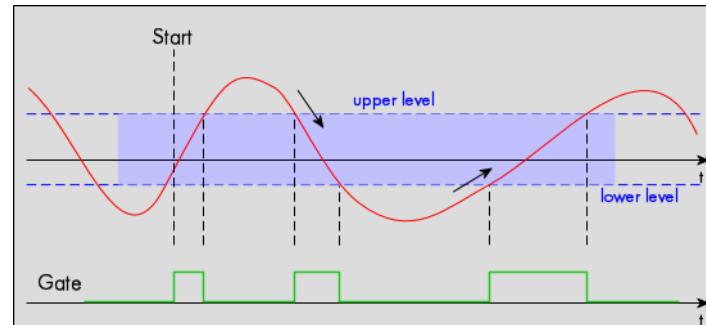
### Channel window trigger for inner signals

The analog input is continuously sampled with the selected sample rate. The upper and the lower level define a window.

When the signal enters the window from the outside to the inside, the gate will start.

When the signal leaves the window from the inside to the outside, the gate will stop.

As this mode is level-triggered, the signal inside the window at the cards start time does trigger the board.



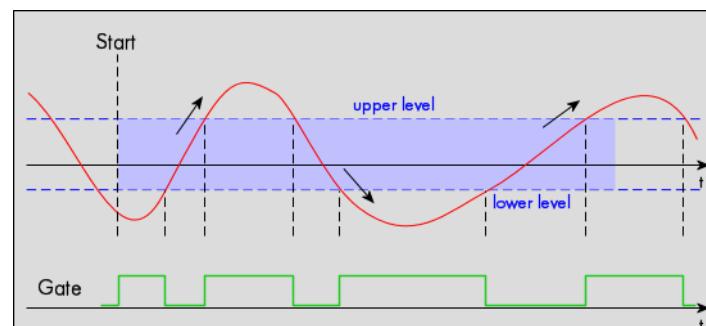
### Channel window trigger for outer signals

The analog input is continuously sampled with the selected sample rate. The upper and the lower level define a window.

When the signal leaves the window from the inside to the outside, the gate will start.

When the signal enters the window from the outside to the inside, the gate will stop.

As this mode is level-triggered, the signal outside the window at the cards start time does trigger the board.



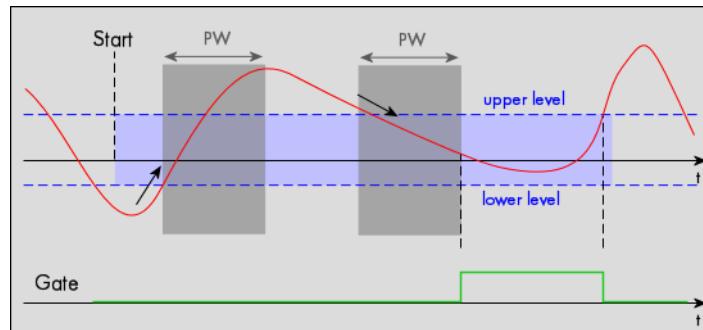
Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_WINLEAVE	00000040h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the upper trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Set it to the lower trigger level relatively to the channel's input range.	board dependant

### Channel window trigger for long inner signals

The analog input is continuously sampled with the selected sample rate. The upper and the lower levels define a window. Every time the signal enters the window from the outside, the pulselength counter is started. If the signal leaves the window before the pulselength counter has stopped, no trigger will be detected.

When the pulselength counter stops and the signal is still inside the window, the gate will start.

When the signal leaves the window from the inside to the outside, the gate will stop.



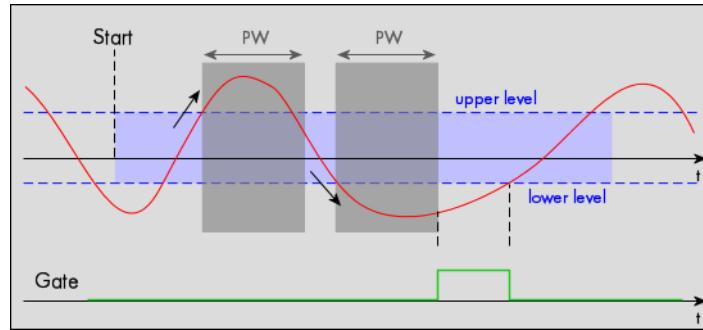
Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_WINENTER   SPC_TM_PW_GREATER	04000020h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the upper trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Set it to the lower trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_PULSEWIDTH	44101	read/write	Sets the pulselength in samples. Values from 2 to [4G - 1] are allowed.	2 to [4G - 1]

### Channel window trigger for long outer signals

The analog input is continuously sampled with the selected sample rate. The upper and the lower levels define a window. Every time the signal leaves the window from the inside, the pulselength counter is started. If the signal enters the window before the pulselength counter has stopped, no trigger will be detected.

When the pulselength counter stops and the signal is still outside the window, the gate will start.

When the signal enters the window from the outside to the inside, the gate will stop.



Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_WINLEAVE   SPC_TM_PW_GREATER	04000040h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the upper trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Set it to the lower trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_PULSEWIDTH	44101	read/write	Sets the pulselength in samples. Values from 2 to [4G - 1] are allowed.	2 to [4G - 1]

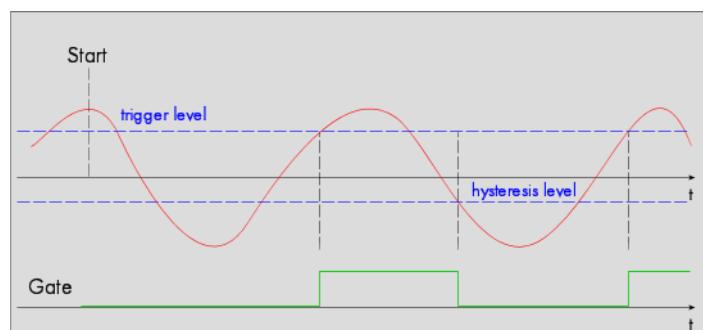
### Channel hysteresis trigger on positive edge

This trigger mode will generate an internal gate signal that can be useful for masking a second trigger event generated by a different mode. The analog input is continuously sampled with the selected sample rate.

If the programmed trigger level is crossed by the channel's signal from lower values to higher values (rising edge) the gate starts.

When the signal crosses the programmed hysteresis level from higher values to lower values (falling edge) then the gate will stop.

As this mode is purely edge-triggered, the high level at the cards start time does not trigger the board.



Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_POS   SPC_TM_HYSTERESIS	20000001h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Defines the hysteresis level relatively to the channel's input range	board dependant

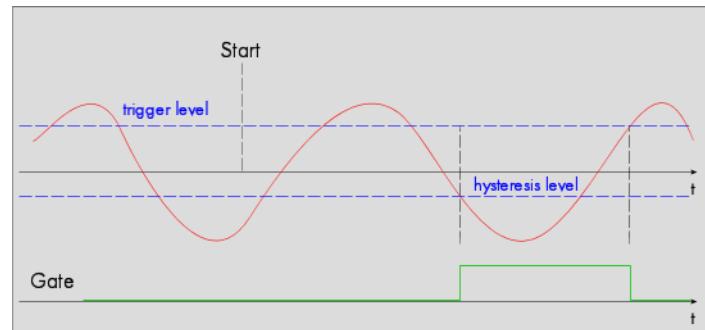
### **Channel hysteresis trigger on negative edge**

.This trigger mode will generate an internal gate signal that can be useful for masking a second trigger event generated by a different mode. The analog input is continuously sampled with the selected sample rate.

If the programmed trigger level is crossed by the channel's signal higher values to lower values (falling edge) the gate starts.

When the signal crosses the programmed hysteresis level from lower values to higher values (rising edge) then the gate will stop.

As this mode is purely edge-triggered, the low level at the cards start time does not trigger the board.

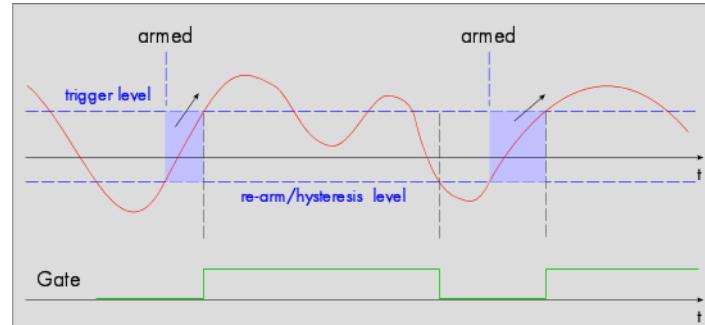


Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_NEG   SPC_TM_HYSTERESIS	20000002h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Defines the hysteresis level relatively to the channel's input range	board dependant

### **Channel re-arm hysteresis trigger on positive edge**

.This trigger mode will generate an internal gate signal that can be useful for masking a second trigger event generated by a different mode. The analog input is continuously sampled with the selected sample rate.

If the programmed re-arm/hysteresis level is crossed from lower to higher values, the trigger engine is armed and waiting for trigger. If the programmed trigger level is crossed by the channel's signal from lower values to higher values (rising edge) then the gate starts and the trigger engine will be disarmed. If the programmed re-arm/hysteresis level is crossed by the channel's signal from higher values to lower values (falling edge) the gate stops.



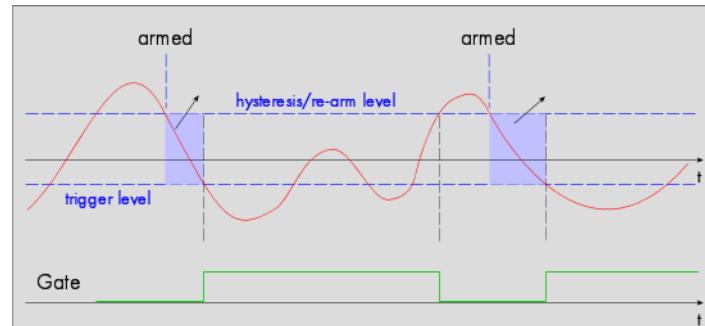
A new trigger event is only detected, if the trigger engine is armed again. The re-arm trigger modes can be used to prevent the board from triggering on wrong edges in noisy signals.

Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_POS   SPC_TM_REARM   SPC_TM_HYSTERESIS	21000001h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Defines the re-arm and hysteresis level relatively to the channel's input range	board dependant

### **Channel re-arm hysteresis trigger on negative edge**

.This trigger mode will generate an internal gate signal that can be useful for masking a second trigger event generated by a different mode. The analog input is continuously sampled with the selected sample rate.

If the programmed re-arm/hysteresis level is crossed from higher to lower values, the trigger engine is armed and waiting for trigger. If the programmed trigger level is crossed by the channel's signal from higher values to lower values (falling edge) then the gate starts and the trigger engine will be disarmed. If the programmed re-arm/hysteresis level is crossed by the channel's signal from lower values to higher values (rising edge) the gate stops.



A new trigger event is only detected, if the trigger engine is armed again. The re-arm trigger modes can be used to prevent the board from triggering on wrong edges in noisy signals.

Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_NEG   SPC_TM_REARM   SPC_TM_HYSTERESIS	21000002h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Defines the re-arm level relatively to the channel's input range	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Defines the re-arm and hysteresis level relatively to the channel's input range	board dependant

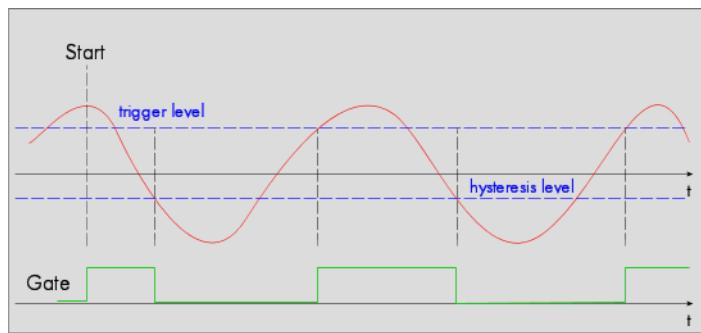
### High level hysteresis trigger

This trigger mode will generate an internal gate signal that can be useful for masking a second trigger event generated by a different mode. The analog input is continuously sampled with the selected sample rate.

If the signal is equal or higher than the programmed trigger level the gate starts.

When the signal is lower than the programmed hysteresis level the gate will stop.

As this mode is level-triggered, the high level at the cards start time does trigger the board.



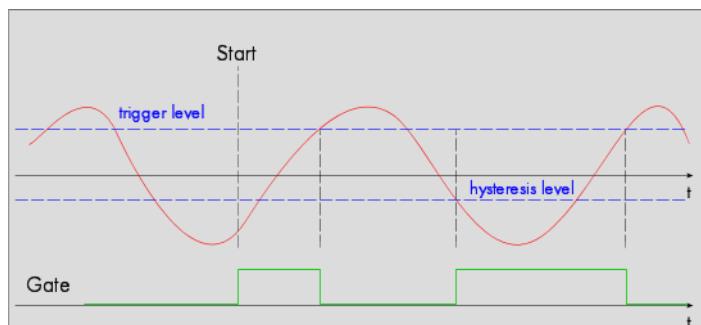
### Low level hysteresis trigger

This trigger mode will generate an internal gate signal that can be useful for masking a second trigger event generated by a different mode. The analog input is continuously sampled with the selected sample rate.

If the signal is equal or lower than the programmed trigger level the gate starts.

When the signal is higher than the programmed hysteresis level the gate will stop.

As this mode is level-triggered, the high level at the cards start time does trigger the board.



Register	Value	Direction	set to	Value
SPC_TRIG_CHO_MODE	40610	read/write	SPC_TM_HIGH   SPC_TM_HYSTERESIS	20000008h
SPC_TRIG_CHO_LEVEL0	42200	read/write	Set it to the desired trigger level relatively to the channel's input range.	board dependant
SPC_TRIG_CHO_LEVEL1	42300	read/write	Defines the hysteresis level relatively to the channel's input range	board dependant

## Programming examples

The following examples shows how to set up the card for Gated Sampling in standard mode and for Gated Sampling in FIFO mode.

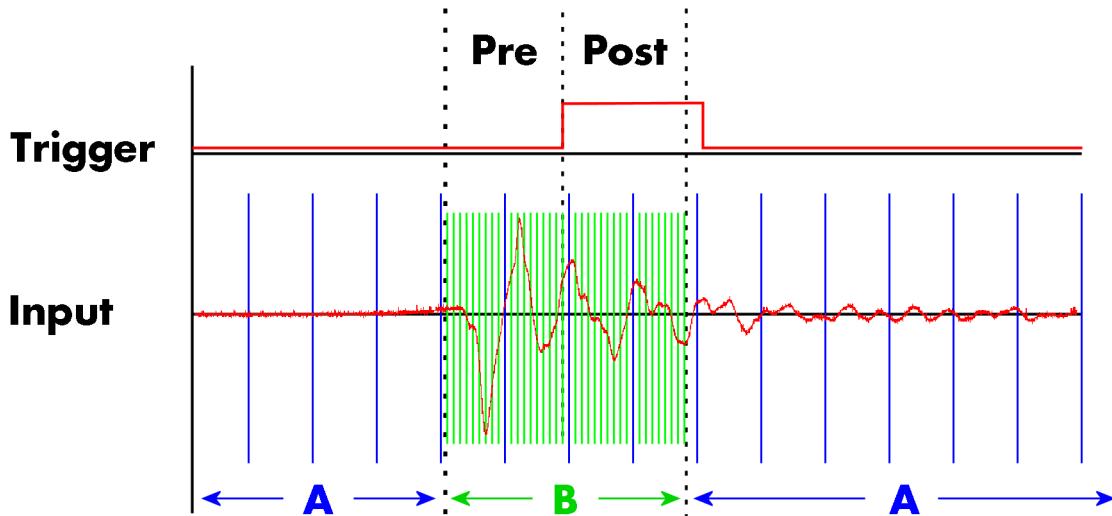
```
spcm_dwSetParam_i32 (hDrv, SPC_CARDMODE, SPC_REC_STD_GATE); // Enables Standard Gated Sampling
spcm_dwSetParam_i32 (hDrv, PRETRIGGER, 256); // Set the pretrigger to 256 samples
spcm_dwSetParam_i32 (hDrv, POSTTRIGGER, 2048); // Set the posttrigger to 2048 samples
spcm_dwSetParam_i32 (hDrv, SPC_MEMSIZE, 8192); // Set the total memsize for recording to 8192 samples
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXTO_MODE, SPC_TM_POS); // Set triggermode to ext. TTL mode (rising edge)
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXTO_LEVEL0, 1500); // Set trigger level to +1500 mV
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK, SPC_TMASK_EXTO); // and enable it within the trigger OR-mask
```

```
spcm_dwSetParam_i32 (hDrv, SPC_CARDMODE, SPC_REC_FIFO_GATE); // Enables FIFO Gated Sampling
spcm_dwSetParam_i32 (hDrv, PRETRIGGER, 128); // Set the pretrigger to 128 samples
spcm_dwSetParam_i32 (hDrv, POSTTRIGGER, 512); // Set the posttrigger to 512 samples
spcm_dwSetParam_i32 (hDrv, SPC_LOOP, 1024); // 1024 gates will be recorded
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXTO_MODE, SPC_TM_NEG); // Set triggermode to ext. TTL mode (falling edge)
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXTO_LEVEL0, -1500); // Set trigger level to -1500 mV
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK, SPC_TMASK_EXTO); // and enable it within the trigger OR-mask
```

## ABA mode (dual timebase)

### General information

The ABA mode allows the acquisition of data with a dual timebase. In case of trigger event the inputs are sampled very fast with the programmed sampling rate. This part is similar to the Multiple Recording option. But instead of having no data in between the segments one has the opportunity to continuously sample the inputs with a slower sampling rate the whole time. Combining this with the recording of the timestamps gives you a complete acquisition with a dual timebase as shown in the drawing.



As seen in the drawing the area around the trigger event is sampled between pretrigger and posttrigger with full sampling speed (area B of the acquisition). Outside of this area B the input is sampled with the slower ABA clock (area A of the acquisition). As changing sampling clock on the fly is not possible there is no real change in the sampling speed but area A runs continuously with a slow sampling speed without stopping when the fast sampling takes place. As a result one gets a continuous slow sampled acquisition (area A) with some fast sampled parts (area B).

The ABA mode is available for standard recording as well as for FIFO recording. In case of FIFO recording ABA and the acquisition of the fast sampled segments will run continuously until it is stopped by the user.

A second possible application for the ABA mode is the use of the ABA data for slow monitoring of the inputs while waiting for an acquisition. In that case one wouldn't record the timestamps but simply monitor the current values by acquiring ABA data.

The ABA mode needs a second clock base. As explained above the acquisition is not changing the sampling clock but runs the slower acquisition with a divided clock. The ABA memory setup including the divider value can be programmed with the following registers

Register	Value	Direction	Description
SPC_SEGMENTSIZE	10010	read/write	Size of one Multiple Recording segment: the number of samples to be record after each trigger event.
SPC_POSTTRIGGER	10030	read/write	Defines the number of samples to be recorded after each trigger event.
SPC_ABADIVIDER	10040	read/write	Programs the divider which is used to sample slow ABA data: For 16 bit cards : between 8 and [64k - 8] in steps of 8

The resulting ABA clock is then calculated by sampling rate / ABA divider.

Each segment can consist of pretrigger and/or posttrigger samples. The user always has to set the total segment size and the posttrigger, while the pretrigger is calculated within the driver with the formula: [pretrigger] = [segment size] - [posttrigger].

**When using ABA mode or Multiple Recording the maximum pretrigger is limited depending on the number of active channels. When the calculated value exceeds that limit, the driver will return the error !**



### Standard Mode

With every detected trigger event one data block is filled with data. The length of one ABA segment is set by the value of the segmentsize register. The total amount of samples to be recorded is defined by the memsize register.

Memsize must be set to a multiple of the segment size. The table below shows the register for enabling standard ABA mode. For detailed information on how to setup and start the standard acquisition mode please refer to the according chapter earlier in this manual.

Register	Value	Direction	Description
SPC_CARDMODE	9500	read/write	Defines the used operating mode
SPC_REC_STD_ABA	8h		Data acquisition to on-board memory for multiple trigger events. While the multiple trigger events are stored with programmed sampling rate the inputs are sampled continuously with a slower sampling speed.

The total number of samples to be recorded to the on-board memory in standard mode is defined by the SPC\_MEMSIZE register.

Register	Value	Direction	Description
SPC_MEMSIZE	10000	read/write	Defines the total number of samples to be recorded.

## FIFO Mode

The ABA FIFO Mode is similar to the Multiple Recording FIFO mode. In contrast to the standard mode it is not necessary to program the number of samples to be recorded. The acquisition is running until the user stops it. The data is read block by block by the driver as described under Single FIFO mode example earlier in this manual. These blocks are online available for further data processing by the user program. This mode significantly reduces the average data transfer rate on the PCI bus. This enables you to use faster sample rates than you would be able to in FIFO mode without ABA.

Register	Value	Direction	Description
SPC_CARDMODE	9500	read/write	Defines the used operating mode
SPC_REC_FIFO_ABA	80h		Continuous data acquisition for multiple trigger events together with continuous data acquisition with a slower sampling clock.

The number of segments to be recorded must be set separately with the register shown in the following table:

Register	Value	Direction	Description
SPC_LOOPS	10020	read/write	Defines the number of segments to be recorded
0			Recording will be infinite until the user stops it.
1 ... [4G - 1]			Defines the total segments to be recorded.

## Limits of pre trigger, post trigger, memory size

The maximum memory size parameter is only limited by the number of activated channels and by the amount of installed memory. Please keep in mind that each samples needs 2 bytes of memory to be stored. Minimum memory size as well as minimum and maximum post trigger limits are independent of the activated channels or the installed memory.

Due to the internal organization of the card memory there is a certain stepsize when setting these values that has to be taken into account. The following table gives you an overview of all limits concerning pre trigger, post trigger, memory size, segment size and loops. The table shows all values in relation to the installed memory size in samples. If more memory is installed the maximum memory size figures will increase according to the complete installed memory

Activated Channels	Used Mode	Memory size SPC_MEMSIZE			Pre trigger SPC_PRETRIGGER			Post trigger SPC_POSTTRIGGER			Segment size SPC_SEGMENTSIZE			Loops SPC_LOOPS		
		Min	Max	Step	Min	Max	Step	Min	Max	Step	Min	Max	Step	Min	Max	Step
1 Ch	Standard Single	16	Mem	8	8	Mem - 8	8	8	8G - 8	8	not used			not used		
	Standard Multi/ABA	16	Mem	8	8	32k	8	8	Mem - 8	8	16	Mem	8	not used		
	Standard Gate	16	Mem	8	8	32k	8	8	Mem - 8	8	not used			not used		
	FIFO Single	not used			8	32k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1
	FIFO Multi/ABA	not used			8	32k	8	8	8G - 8	8	16	pre+post	8	0 (∞)	4G - 1	1
	FIFO Gate	not used			8	32k	8	8	8G - 8	8	not used			0 (∞)	4G - 1	1
2 Ch	Standard Single	16	Mem/2	8	8	Mem/2 - 8	8	8	8G - 8	8	not used			not used		
	Standard Multi/ABA	16	Mem/2	8	8	16k	8	8	Mem/2 - 8	8	16	Mem/2	8	not used		
	Standard Gate	16	Mem/2	8	8	16k	8	8	Mem/2 - 8	8	not used			not used		
	FIFO Single	not used			8	16k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1
	FIFO Multi/ABA	not used			8	16k	8	8	8G - 8	8	16	pre+post	8	0 (∞)	4G - 1	1
	FIFO Gate	not used			8	16k	8	8	8G - 8	8	not used			0 (∞)	4G - 1	1
4 Ch	Standard Single	16	Mem/4	8	8	Mem/4 - 8	8	8	8G - 16	8	not used			not used		
	Standard Multi/ABA	16	Mem/4	8	8	8k	8	8	Mem/4 - 8	8	16	Mem/4	8	not used		
	Standard Gate	16	Mem/4	8	8	8k	8	8	Mem/4 - 8	8	not used			not used		
	FIFO Single	not used			8	8k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1
	FIFO Multi/ABA	not used			8	8k	8	8	8G - 16	8	16	pre+post	8	0 (∞)	4G - 1	1
	FIFO Gate	not used			8	8k	8	8	8G - 16	8	not used			0 (∞)	4G - 1	1
8 Ch	Standard Single	16	Mem/8	8	8	Mem/8 - 8	8	8	8G - 8	8	not used			not used		
	Standard Multi/ABA	16	Mem/8	8	8	4k	8	8	Mem/8 - 8	8	16	Mem/8	8	not used		
	Standard Gate	16	Mem/8	8	8	4k	8	8	Mem/8 - 8	8	not used			not used		
	FIFO Single	not used			8	4k	8	not used			16	8G - 16	8	0 (∞)	4G - 1	1

Activated Channels	Used Mode	Memory size SPC_MEMSIZE			Pre trigger SPC_PRETRIGGER			Post trigger SPC_POSTTRIGGER			Segment size SPC_SEGMENTSIZE			Loops SPC_LOOPS		
		Min	Max	Step	Min	Max	Step	Min	Max	Step	Min	Max	Step	Min	Max	Step
FIFO Multi/ABA	not used	8	4k	8	8	8G - 16	8	16	pre+post	8	0 ( $\infty$ )	4G - 1	1	(Defined by segment and post) <span style="color:red;">(Limited by max pretrigger)</span>		
	FIFO Gate	8	4k	8	8	8G - 16	8	not used			0 ( $\infty$ )	4G - 1	1			

All figures listed here are given in samples. An entry of [8G - 16] means [8 GSamples - 16] = 8,589,934,576 samples.

The given memory and memory / divider figures depend on the installed on-board memory as listed below:

	Installed Memory
<b>512 Msample</b>	
Mem	512 Msample
Mem/2	256 Msample
Mem/4	128 Msample
Mem/8	64 Msample

Please keep in mind that this table shows all values at once. Only the absolute maximum and minimum values are shown. There might be additional limitations. Which of these values are programmed depends on the used mode. Please read the detailed documentation of the mode.

### Example for setting ABA mode:

The following example will program the standard ABA mode, will set the fast sampling rate to 100 MHz and acquire 2k segments with 1k pretrigger and 1k posttrigger on every rising edge of the trigger input. Meanwhile the inputs are sampled continuously with the ABA mode with a ABA divider set to 5000 resulting in a slow sampling clock for the A area of 100 MHz / 5000 = 20 kHz:

```
// setting the fast sampling clock as internal 100 MHz
spcm_dwSetParam_i32 (hDrv, SPC_CLOCKMODE, SPC_CM_INTPLL);
spcm_dwSetParam_i64 (hDrv, SPC_SAMPLERATE, 100000000);

// enable the ABA mode and set the ABA divider to 5000 -> 100 MHz / 5000 = 20 kHz
spcm_dwSetParam_i32 (hDrv, SPC_CARDMODE, SPC_REC_STD_ABA);
spcm_dwSetParam_i32 (hDrv, SPC_ABADIVIDER, 5000);

// define the segmentsize, pre and posttrigger and the total amount of data to acquire
spcm_dwSetParam_i64 (hDrv, SPC_MEMSIZE, 16384);
spcm_dwSetParam_i64 (hDrv, SPC_SEGMENTSIZE, 2048);
spcm_dwSetParam_i64 (hDrv, SPC_POSTTRIGGER, 1024);

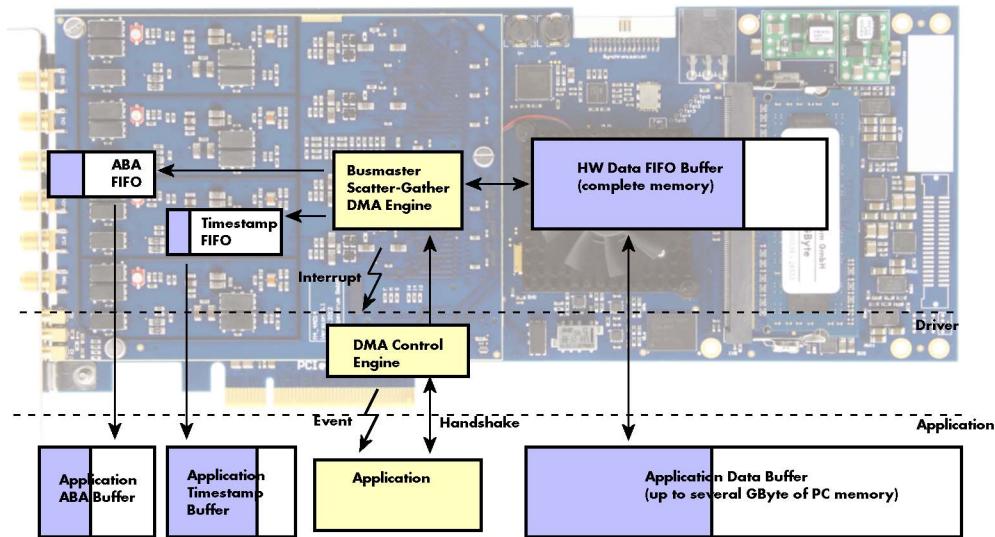
// set the trigger mode to external with positive edge
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_ORMASK, SPC_TMASK_EXT0);
spcm_dwSetParam_i32 (hDrv, SPC_TRIG_EXT0_MODE, SPC_TM_POS);
```

## Reading out ABA data

### General

The slow „A“ data is stored in an additional FIFO that is located in hardware on the card. This additional FIFO can read out slow „A“ data using DMA transfer similar to the DMA transfer of the main sample data DMA transfer. The card has three completely independent busmaster DMA engines in hardware allowing the simultaneous transfer of both „A“ and sample data, as well as optionally timestamp data. The sample data itself is read out as explained before using the standard DMA routine.

As seen in the picture there are separate FIFOs holding ABA and timestamp data.



Although an M4i is shown here, this applies to M4x and M2p cards as well. Each FIFO has its own DMA channel, the way data is handled by the DMA engine is similar for both kinds of extra FIFOs and is also very similar to the main sample data transfer engine. Therefore additional information can be found in the chapter explaining the main data transfer.

### **Commands and Status information for extra transfer buffers.**

As explained above the data transfer is performed with the same command and status registers like the card control and sample data transfer. It is possible to send commands for card control, data transfer and extra FIFO data transfer at the same time

Register	Value	Direction	Description
SPC_M2CMD	100	write only	Executes a command for the card or data transfer
M2CMD_EXTRA_STARTDMA	100000h		Starts the DMA transfer for an already defined buffer.
M2CMD_EXTRA_WAITDMA	200000h		Waits until the data transfer has ended or until at least the amount of bytes defined by notify size are available. This wait function also takes the timeout parameter into account.
M2CMD_EXTRA_STOPDMA	400000h		Stops a running DMA transfer. Data is invalid afterwards.
M2CMD_EXTRA_POLL	800000h		Polls data without using DMA. As DMA has some overhead and has been implemented for fast data transfer of large amounts of data it is in some cases more simple to poll for available data. Please see the detailed examples for this mode. It is not possible to mix DMA and polling mode.

The extra FIFO data transfer can generate one of the following status information::

Register	Value	Direction	Description
SPC_M2STATUS	110	read only	Reads out the current status information
M2STAT_EXTRA_BLOCKREADY	1000h		The next data block as defined in the notify size is available. It is at least the amount of data available but it also can be more data.
M2STAT_EXTRA_END	2000h		The data transfer has completed. This status information will only occur if the notify size is set to zero.
M2STAT_EXTRA_OVERRUN	4000h		The data transfer had an overrun (acquisition) or underrun (replay) while doing FIFO transfer.
M2STAT_EXTRA_ERROR	8000h		An internal error occurred while doing data transfer.

### **Data Transfer using DMA**

Data transfer consists of two parts: the buffer definition and the commands/status information that controls the transfer itself. Extra data transfer shares the command and status register with the card control, data transfer commands and status information.

The DMA based data transfer mode is activated as soon as the M2CMD\_EXTRA\_STARTDMA is given. Please see next chapter to see how the polling mode works.

#### **Definition of the transfer buffer**

Before any data transfer can start it is necessary to define the transfer buffer with all its details. The definition of the buffer is done with the spcm\_dwDefTransfer function as explained in an earlier chapter. The following example will show the definition of a transfer buffer for timestamp data, definition for ABA data is similar:

```
spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_TIMESTAMP, SPCM_CARDTOPC, 0, pvBuffer, 0, lLenOfBufferInBytes);
```

In this example the notify size is set to zero, meaning that we don't want to be notified until all extra data has been transferred. Please have a look at the sample data transfer in an earlier chapter to see more details on the notify size.

Please note that extra data transfer is only possible from card to PC and there's no programmable offset available for this transfer.

### **Buffer handling**

A data buffer handshake is implemented in the driver which allows to run the card in different data transfer modes. The software transfer buffer is handled as one large buffer for each kind of data (timestamp and ABA) which is on the one side controlled by the driver and filled automatically by busmaster DMA from the hardware extra FIFO buffer and on the other hand it is handled by the user who set's parts of this software buffer available for the driver for further transfer. The handshake is fulfilled with the following 3 software registers:

Register	Value	Direction	Description
SPC_ABA_AVAIL_USER_LEN	210	read	This register contains the currently available number of bytes that are filled with newly transferred slow ABA data. The user can now use this ABA data for own purposes, copy it, write it to disk or start calculations with this data.
SPC_ABA_AVAIL_USER_POS	211	read	The register holds the current byte index position where the available ABA bytes start. The register is just intended to help you and to avoid own position calculation
SPC_ABA_AVAIL_CARD_LEN	212	write	After finishing the job with the new available ABA data the user needs to tell the driver that this amount of bytes is again free for new data to be transferred.
SPC_TS_AVAIL_USER_LEN	220	read	This register contains the currently available number of bytes that are filled with newly transferred timestamp data. The user can now use these timestamps for own purposes, copy it, write it to disk or start calculations with the timestamps.
SPC_TS_AVAIL_USER_POS	221	read	The register holds the current byte index position where the available timestamp bytes start. The register is just intended to help you and to avoid own position calculation
SPC_TS_AVAIL_CARD_LEN	222	write	After finishing the job with the new available timestamp data the user needs to tell the driver that this amount of bytes is again free for new data to be transferred.

Directly after start of transfer the SPC\_XXX\_AVAIL\_USER\_LEN is every time zero as no data is available for the user and the SPC\_XXX\_AVAIL\_CARD\_LEN is every time identical to the length of the defined buffer as the complete buffer is available for the card for transfer.

**The counter that is holding the user buffer available bytes (SPC\_XXX\_AVAIL\_USER\_LEN) is sticking to the defined notify size at the DefTransfer call. Even when less bytes already have been transferred you won't get notice of it if the notify size is programmed to a higher value.**



### **Remarks**

- The transfer between hardware FIFO buffer and application buffer is done with scatter-gather DMA using a busmaster DMA controller located on the card. Even if the PC is busy with other jobs data is still transferred until the application buffer is completely used.
- As shown in the drawing above the DMA control will announce new data to the application by sending an event. Waiting for an event is done internally inside the driver if the application calls one of the wait functions. Waiting for an event does not consume any CPU time and is therefore highly requested if other threads do lot of calculation work. However it is not necessary to use the wait functions and one can simply request the current status whenever the program has time to do so. When using this polling mode the announced available bytes still stick to the defined notify size!
- If the on-board FIFO buffer has an overrun data transfer is stopped immediately.

**Buffer handling example for DMA timestamp transfer (ABA transfer is similar, just using other registers)**

```

int8* pcData = (int8*) pvAllocMemPageAligned (lBufSizeInBytes);

// we now define the transfer buffer with the minimum notify size of one page = 4 kByte
spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_TIMESTAMP, SPCM_DIR_CARDTOPC, 4096, (void*) pcData, 0, lBufSizeInBytes);

do
{
    // we wait for the next data to be available. After this call we get at least 4k of data to proceed
    dwError = spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_EXTRA_STARTDMA | M2CMD_EXTRA_WAITDMA);

    if (!dwError)
    {

        // if there was no error we can proceed and read out the current amount of available data
        spcm_dwGetParam_i32 (hDrv, SPC_TS_AVAIL_USER_LEN, &lAvailBytes);
        spcm_dwGetParam_i32 (hDrv, SPC_TS_AVAIL_USER_POS, &lBytePos);

        printf ("We now have %d new bytes available\n", lAvailBytes);
        printf ("The available data starts at position %d\n", lBytePos);

        // we take care not to go across the end of the buffer
        if ((lBytePos + lAvailBytes) >= lBufSizeInBytes)
            lAvailBytes = lBufSizeInBytes - lBytePos;

        // our do function gets a pointer to the start of the available data section and the length
        vProcessTimestamps (&pcData[lBytePos], lAvailBytes);

        // the buffer section is now immediately set available for the card
        spcm_dwSetParam_i32 (hDrv, SPC_TS_AVAIL_CARD_LEN, lAvailBytes);
    }
}
while (!dwError); // we loop forever if no error occurs

```

 **The extra FIFO has a quite small size compared to the main data buffer. As the transfer is done initiated by the hardware using busmaster DMA this is not critical as long as the application data buffers are large enough and as long as the extra transfer is started BEFORE starting the card.**

**Data Transfer using Polling**

If the extra data is quite slow and the delay caused by the notify size on DMA transfers is unacceptable for your application it is possible to use the polling mode. Please be aware that the polling mode uses CPU processing power to get the data and that there might be an overrun if your CPU is otherwise busy. You should only use polling mode in special cases and if the amount of data to transfer is not too high.

Most of the functionality is similar to the DMA based transfer mode as explained above.

The polling data transfer mode is activated as soon as the M2CMD\_EXTRA\_POLL is executed.

**Definition of the transfer buffer**

This is similar to the above explained DMA buffer transfer. The value „notify size“ is ignored and should be set to 4k (4096).

**Buffer handling**

The buffer handling is also similar to the DMA transfer. As soon as one of the registers SPC\_TS\_AVAIL\_USER\_LEN or SPC\_ABA\_AVAIL\_USER\_LEN is read the driver will read out all available data from the hardware and will return the number of bytes that has been read. In minimum this will be one DWORD = 4 bytes.

**Buffer handling example for polling timestamp transfer (ABA transfer is similar, just using other registers)**

```

int8* pcData = (int8*) pvAllocMemPageAligned (lBufSizeInBytes);

// we now define the transfer buffer with the minimum notify size of one page = 4 kByte
spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_TIMESTAMP, SPCM_DIR_CARDTOPC, 4096, (void*) pcData, 0, lBufSizeInBytes);

// we start the polling mode
dwError = spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_EXTRA_POLL);

// this is pure polling loop
do
{
    spcm_dwGetParam_i32 (hDrv, SPC_TS_AVAIL_USER_LEN, &lAvailBytes);
    spcm_dwGetParam_i32 (hDrv, SPC_TS_AVAIL_USER_POS, &lBytePos);

    if (lAvailBytes > 0)
    {
        printf ("We now have %d new bytes available\n", lAvailBytes);
        printf ("The available data starts at position %d\n", lBytePos);

        // we take care not to go across the end of the buffer
        if ((lBytePos + lAvailBytes) >= lBufSizeInBytes)
            lAvailBytes = lBufSizeInBytes - lBytePos;

        // our do function get's a pointer to the start of the available data section and the length
        vProcessTimestamps (&pcData[lBytePos], lAvailBytes);

        // the buffer section is now immediately set available for the card
        spcm_dwSetParam_i32 (hDrv, SPC_TS_AVAIL_CARD_LEN, lAvailBytes);
    }
}
while (!dwError); // we loop forever if no error occurs

```

**Comparison of DMA and polling commands**

This chapter shows you how small the difference in programming is between the DMA and the polling mode:

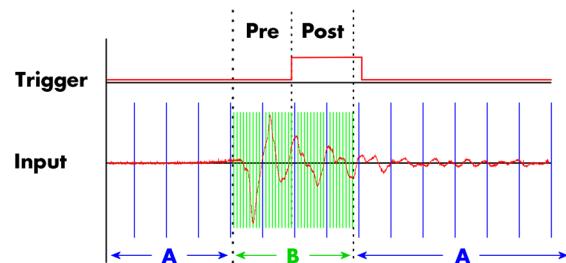
	<b>DMA mode</b>	<b>Polling mode</b>
Define the buffer	spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_TIMESTAMP, SPCM_DIR...);	spcm_dwDefTransfer_i64 (hDrv, SPCM_BUF_TIMESTAMP, SPCM_DIR...);
Start the transfer	spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_EXTRA_STARTDMA);	spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_EXTRA_POLL)
Wait for data	spcm_dwSetParam_i32 (hDrv, SPC_M2CMD, M2CMD_EXTRA_WAITDMA);	not in polling mode
Available bytes?	spcm_dwGetParam_i32 (hDrv, SPC_TS_AVAIL_USER_LEN, &lBytes);	spcm_dwGetParam_i32 (hDrv, SPC_TS_AVAIL_USER_LEN, &lBytes);
Min available bytes	programmed notify size	4 bytes
Current position?	spcm_dwGetParam_i32 (hDrv, SPC_TS_AVAIL_USER_LEN, &lBytes);	spcm_dwGetParam_i32 (hDrv, SPC_TS_AVAIL_USER_LEN, &lBytes);
Free buffer for card	spcm_dwSetParam_i32 (hDrv, SPC_TS_AVAIL_CARD_LEN, lBytes);	spcm_dwSetParam_i32 (hDrv, SPC_TS_AVAIL_CARD_LEN, lBytes);

**ABA Mode and Timestamps**

The ABA mode is well matching with the timestamp option. If timestamp recording is activated, each trigger event and therefore each B time base segment will get time stamped as shown in the drawing on the right.

Please keep in mind that the trigger events - located in the B area - are time stamped, not the beginning of the acquisition. The first B sample that is available is at the time position of [Timestamp - Pretrigger].

The first A area sample is related to the card start and therefore in a fixed but various settings dependent relation to the timestamped B sample. To bring exact relation between the first A area sample (and therefore all area A samples) and the B area samples it is possible to let the card stamp the first A area sample automatically after the card start. The following table shows the register to enable this mode:



Register	Value	Direction	Description
SPC_TIMESTAMP_CMD	47000	read/write	Programs a timestamp setup including mode and additional features
SPC_TSFEAT_MASK	F0000h		Mask for the feature relating bits of the SPC_TIMESTAMP_CMD bitmask.
SPC_TSFEAT_STORE1STABA	10000h		Enables storage of one additional timestamp for the first A area sample (B time base related) in addition to the trigger related timestamps.
SPC_TSFEAT_NONE	0h		No additional timestamp is created. The total number of stamps is only trigger related.

This mode is compatible with all existing timestamp modes. Please keep in mind that the timestamp counter is running with the B area timebase.

```
// normal timestamp setup (e.g. setting timestamp mode to standard using internal clocking)
uint32 dwTimestampMode = (SPC_TSMODE_STANDARD | SPC_TSMODE_DISABLE);

// additionally enable index of the first A area sample
dwTimestampMode |= SPC_TSFEAT_STORE1STABA;

spcm_dwSetParam_i32 (hDrv, SPC_TIMESTAMP_CMD, dwTimestampMode);
```

The programming details of the ABA mode and timestamp modes are each explained in a dedicated chapter in this manual.

## Option Star-Hub

### Star-Hub introduction

The purpose of the Star-Hub is to extend the number of channels available for acquisition or generation by interconnecting multiple cards and running them simultaneously.

The Star-Hub option allows to synchronize several M2p cards that are mounted within one host system (PC) and is part of the digitizerNETBOX and generatorNETBOX products, that include more than one digitizer/generator module.

Two different sized Star-Hub versions are available: a small version with 6 connectors (options SH6ex or SH6tm) for synchronizing up to six cards and a bigger version with 16 connectors (options SH16ex or SH16tm) for synchronizing up to sixteen cards.



**The M2p Star-Hub allows synchronizing cards of the same family as well as different families of the M2p series with each other**

Both sizes versions are implemented as either a piggy-back module that is mounted on top of one of the cards (options SH6tm or SH16tm), or as an extension (SH6ex or SH16ex). For details on how to install several cards including the one carrying the Star-Hub module, please refer to the section on hardware installation.

Either which of the available Star-Hub options is used, there will be no phase delay between the sampling clocks of the synchronized cards and either no delay between the trigger events. The card holding the Star-Hub is automatically also the clock master. Any one of the synchronized cards can be part of the trigger generation.

### Star-Hub trigger engine

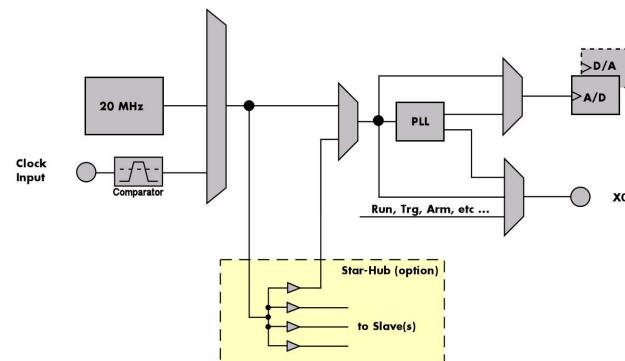
The trigger bus between an M2p card and the Star-Hub option consists of several lines. Some of them send the trigger information from the card's trigger engine to the Star-Hub and some receive the resulting trigger from the Star-Hub. All trigger events from the different cards connected can be combined logically by either OR or a logical AND within the Star-Hub.

While the returned trigger is identical for all synchronized cards, the sent out trigger of every single card depends on their respective trigger settings.

### Star-Hub clock engine

The card holding the Star-Hub is the clock master for the complete system. If you need to feed in an external clock to a synchronized system the clock has to be connected to the master card. Slave cards cannot generate a Star-Hub system clock. As shown in the drawing on the right, the clock master can use either its on-board reference, an external reference or directly distribute the external fed in clock input to be broadcast to all other cards.

All cards including the clock master itself receive the distributed clock with equal phase information. This makes sure that there is no phase delay between the cards.



### Software Interface

The software interface is similar to the card software interface that is explained earlier in this manual. The same functions and some of the registers are used with the Star-Hub. The Star-Hub is accessed using its own handle which has some extra commands for synchronization setup. All card functions are programmed directly on card as before. There are only a few commands that need to be programmed directly to the Star-Hub for synchronization.

The software interface as well as the hardware supports multiple Star-Hubs in one system. Each set of cards connected by a Star-Hub then runs totally independent. It is also possible to mix cards that are connected with the Star-Hub with other cards that run independent in one system.

### Star-Hub Initialization

The interconnection between the Star-Hubs is probed at driver load time and does not need to be programmed separately. Instead the cards can be accessed using a logical index. This card index is only based on the ordering of the cards in the system and is not influenced by the current cabling. It is even possible to change the cable connections between two system starts without changing the logical card order that is used for Star-Hub programming.



**The Star-Hub initialization must be done AFTER initialization of all cards in the system. Otherwise the interconnection won't be received properly.**

The Star-Hubs are accessed using a special device name „sync“ followed by the index of the star-hub to access. The Star-Hub is handled completely like a physical card allowing all functions based on the handle like the card itself.

Example with 4 cards and one Star-Hub (no error checking to keep example simple)

```
drv_handle hSync;
drv_handle hCard[4];

for (i = 0; i < 4; i++)
{
    sprintf (s, "/dev/spcm%d", i);
    hCard[i] = spcm_hOpen (s);
}
hSync = spcm_hOpen ("sync0");

...
spcm_vClose (hSync);
for (i = 0; i < 4; i++)
    spcm_vClose (hCard[i]);
```

Example for a digitizerNETBOX with two internal digitizer/generator modules. This example is also suitable for accessing a remote server with two cards installed:

```
drv_handle hSync;
drv_handle hCard[2];

for (i = 0; i < 2; i++)
{
    sprintf (s, "TCPIP::192.168.169.14::INST%d::INSTR", i);
    hCard[i] = spcm_hOpen (s);
}
hSync = spcm_hOpen ("sync0");

...
spcm_vClose (hSync);
for (i = 0; i < 2; i++)
    spcm_vClose (hCard[i]);
```

When opening the Star-Hub the cable interconnection is checked. The Star-Hub may return an error if it sees internal cabling problems or if the connection between Star-Hub and the card that holds the Star-Hub is broken. It can't identify broken connections between Star-Hub and other cards as it doesn't know that there has to be a connection.

The synchronization setup is done using bit masks where one bit stands for one recognized card. All cards that are connected with a Star-Hub are internally numbered beginning with 0. The number of connected cards as well as the connections of the star-hub can be read out after initialization. For each card that is connected to the star-hub one can read the index of that card:

Register	Value	Direction	Description
SPC_SYNC_READ_NUMCONNECTORS	48991	read	Number of connectors that the Star-Hub offers at max. (available with driver V5.6 or newer)
SPC_SYNC_READ_SYNCCOUNT	48990	read	Number of cards that are connected to this Star-Hub
SPC_SYNC_READ_CARDIDX0	49000	read	Index of card that is connected to star-hub logical index 0 (mask 0x0001)
SPC_SYNC_READ_CARDIDX1	49001	read	Index of card that is connected to star-hub logical index 1 (mask 0x0002)
...		read	...
SPC_SYNC_READ_CARDIDX7	49007	read	Index of card that is connected to star-hub logical index 7 (mask 0x0080)
SPC_SYNC_READ_CARDIDX8	49008	read	M2i only: Index of card that is connected to star-hub logical index 8 (mask 0x0100)
...		read	...
SPC_SYNC_READ_CARDIDX15	49015	read	M2i only: Index of card that is connected to star-hub logical index 15 (mask 0x8000)
SPC_SYNC_READ_CABLECON0		read	Returns the index of the cable connection that is used for the logical connection 0. The cable connections can be seen printed on the PCB of the star-hub. Use these cable connection information in case that there are hardware failures with the star-hub cabling.
...	49100	read	...
SPC_SYNC_READ_CABLECON15	49115	read	Returns the index of the cable connection that is used for the logical connection 15.

In standard systems where all cards are connected to one star-hub reading the star-hub logical index will simply return the index of the card again. This results in bit 0 of star-hub mask being 1 when doing the setup for card 0, bit 1 in star-hub mask being 1 when setting up card 1

and so on. On such systems it is sufficient to read out the SPC\_SYNC\_READ\_SYNCCOUNT register to check whether the star-hub has found the expected number of cards to be connected.

```
spcm_dwGetParam_i32 (hSync, SPC_SYNC_READ_SYNCCOUNT, &lSyncCount);
for (i = 0; i < lSyncCount; i++)
{
    spcm_dwGetParam_i32 (hSync, SPC_SYNC_READ_CARDIDX0 + i, &lCardIdx);
    printf ("star-hub logical index %d is connected with card %d\n", i, lCardIdx);
}
```

In case of 4 cards in one system and all are connected with the star-hub this program excerpt will return:

```
star-hub logical index 0 is connected with card 0
star-hub logical index 1 is connected with card 1
star-hub logical index 2 is connected with card 2
star-hub logical index 3 is connected with card 3
```

Let's see a more complex example with two Star-Hubs and one independent card in one system. Star-Hub A connects card 2, card 4 and card 5. Star-Hub B connects card 0 and card 3. Card 1 is running completely independent and is not synchronized at all:

card	Star-Hub connection	card handle	star-hub handle	card index in star-hub	mask for this card in star-hub
card 0	-	/dev/spcm0		0 (of star-hub B)	0x0001
card 1	-	/dev/spcm1			-
card 2	star-hub A	/dev/spcm2	sync0	0 (of star-hub A)	0x0001
card 3	star-hub B	/dev/spcm3	sync1	1 (of star-hub B)	0x0002
card 4	-	/dev/spcm4		1 (of star-hub A)	0x0002
card 5	-	/dev/spcm5		2 (of star-hub A)	0x0004

Now the program has to check both star-hubs:

```
for (j = 0; j < lStarhubCount; j++)
{
    spcm_dwGetParam_i32 (hSync[j], SPC_SYNC_READ_SYNCCOUNT,
        for (i = 0; i < lSyncCount; i++)
        {
            spcm_dwGetParam_i32 (hSync[j], SPC_SYNC_READ_CARDIDX0 + i, &lCardIdx);
            printf ("star-hub %c logical index %d is connected with card %d\n", (!j ? 'A' : 'B'), i, lCardIdx);
        }
    printf ("\n");
}
```

In case of the above mentioned cabling this program excerpt will return:

```
star-hub A logical index 0 is connected with card 2
star-hub A logical index 1 is connected with card 4
star-hub A logical index 2 is connected with card 5

star-hub B logical index 0 is connected with card 0
star-hub B logical index 1 is connected with card 3
```

For the following examples we will assume that 4 cards in one system are all connected to one star-hub to keep things easier.

## Setup of Synchronization

The synchronization setup only requires one additional register to enable the cards that are synchronized in the next run

Register	Value	Direction	Description
SPC_SYNC_ENABLEMASK	49200	read/write	Mask of all cards that are enabled for the synchronization

The enable mask is based on the logical index explained above. It is possible to just select a couple of cards for the synchronization. All other cards then will run independently. Please be sure to always enable the card on which the star-hub is located as this one is a must for the synchronization.

In our example we synchronize all four cards. The star-hub is located on card #2 and is therefor the clock master

```
spcm_dwSetParam_i32 (hSync, SPC_SYNC_ENABLEMASK, 0x000F); // all 4 cards are masked
// set the clock master to 100 MS/s internal clock
spcm_dwSetParam_i32 (hCard[2], SPC_CLOCKMODE, SPC_CM_INTPLL);
spcm_dwSetParam_i32 (hCard[2], SPC_SAMPLEATE, MEGA(100));

// set all the slaves to run synchronously with 100 MS/s
spcm_dwSetParam_i32 (hCard[0], SPC_SAMPLEATE, MEGA(100));
spcm_dwSetParam_i32 (hCard[1], SPC_SAMPLEATE, MEGA(100));
spcm_dwSetParam_i32 (hCard[3], SPC_SAMPLEATE, MEGA(100));
```

## Limits of Clock for synchronized cards

Using the M2p Star-Hub, it is possible to have synchronized cards run with different sample rates, as long as **both** of the following conditions are met for all cards connected to the Star-Hub and enabled for synchronization:

- 1) The sample rate of each card can be derived by integer division ( $1/N_i$ ) from the card with the fastest programmed sample rate.
- 2) The sample rate of each card can be derived by integer multiplication ( $* M_i$ ) of the card with the slowest programmed sample rate.

Both N and M must be an integer of 1 or greater, keeping the resulting sample rates within their allowed limits.

Example 1: Valid setup

- Samplerate(card0) = 100 MSps
- Samplerate(card1) = 25 MSps
- Samplerate(card2) = 5 MSps

This setup is perfectly valid, as  $100 \text{ MSps} / 25 \text{ MSps} = 4$  and  $100 \text{ MSps} / 5 \text{ MSps} = 20$  and also  $5 * 5 \text{ MSps} = 25 \text{ MSps}$

Example 2: Invalid setup:

- Samplerate(card0) = 100 MSps
- Samplerate(card1) = 25 MSps
- Samplerate(card2) = 10 MSps

This setup is not valid, although the first condition of  $100 \text{ MSps} / 25 \text{ MSps} = 4$  and  $100 \text{ MSps} / 10 \text{ MSps} = 20$  is met. But the second condition is violated, as a non-integer would be required:  $2.5 * 10 \text{ MSps} = 25 \text{ MSps}$ .

Example 3: Invalid setup:

- Samplerate(card0) = 100 MSps
- Samplerate(card1) = 30 MSps
- Samplerate(card2) = 10 MSps

This setup is not valid, although now the second condition is met, since a integer works:  $3 * 10 \text{ MSps} = 30 \text{ MSps}$  but the first requirement is now violated, since  $100 \text{ MSps} / 30 \text{ MSps} = 3.33$ , which is not an integer.

Example 4: Valid setup

- Samplerate(card0) = 100 MSps
- Samplerate(card1) = 20 MSps
- Samplerate(card2) = 10 MSps

This setup is perfectly valid again, as  $100 \text{ MSps} / 20 \text{ MSps} = 5$  and  $100 \text{ MSps} / 10 \text{ MSps} = 10$  and also  $2 * 10 \text{ MSps} = 20 \text{ MSps}$

## Setup of Trigger

Setting up the trigger does not need any further steps of synchronization setup. Simply all trigger settings of all cards that have been enabled for synchronization are connected together. All trigger sources and all trigger modes can be used on synchronization as well.

Having positive edge of external trigger on card 0 to be the trigger source for the complete system needs the following setup:

```
spcm_dwSetParam_i32 (hCard[0], SPC_TRIG_ORMASK, SPC_TM_MASK_EXT0);
spcm_dwSetParam_i32 (hCard[0], SPC_TRIG_EXT0_MODE, SPC_TM_POS);

spcm_dwSetParam_i32 (hCard[1], SPC_TRIG_ORMASK, SPC_TM_NONE);
spcm_dwSetParam_i32 (hCard[2], SPC_TRIG_ORMASK, SPC_TM_NONE);
spcm_dwSetParam_i32 (hCard[3], SPC_TRIG_ORMASK, SPC_TM_NONE);
```

Assuming that the 4 cards are analog data acquisition cards with 4 channels each we can simply setup a synchronous system with all channels of all cards being trigger source. The following setup will show how to set up all trigger events of all channels to be OR connected. If any of the channels will now have a signal above the programmed trigger level the complete system will do an acquisition:

```

for (i = 0; i < lSyncCount; i++)
{
    int32 lAllChannels = (SPC_TMASK0_CH0 | SPC_TMASK0_CH1 | SPC_TMASK_CH2 | SPC_TMASK_CH3);
    spcm_dwSetParam_i32 (hCard[i], SPC_TRIG_CH_ORMASK0, lAllChannels);
    for (j = 0; j < 2; j++)
    {

        // set all channels to trigger on positive edge crossing trigger level 100
        spcm_dwSetParam_i32 (hCard[i], SPC_TRIG_CH0_MODE + j, SPC_TM_POS);
        spcm_dwSetParam_i32 (hCard[i], SPC_TRIG_CH0_LEVEL0 + j, 100);
    }
}

```

## Run the synchronized cards

Running of the cards is very simple. The star-hub acts as one big card containing all synchronized cards. All card commands have to be omitted directly to the star-hub which will check the setup, do the synchronization and distribute the commands in the correct order to all synchronized cards. The same card commands can be used that are also possible for single cards:

Register	Value	Direction	Description
SPC_M2CMD	100	write only	Executes a command for the card or data transfer
M2CMD_CARD_RESET	1h		Performs a hard and software reset of the card as explained further above
M2CMD_CARD_WRITESETUP	2h		Writes the current setup to the card without starting the hardware. This command may be useful if changing some internal settings like clock frequency and enabling outputs.
M2CMD_CARD_START	4h		Starts the card with all selected settings. This command automatically writes all settings to the card if any of the settings has been changed since the last one was written. After card has been started none of the settings can be changed while the card is running.
M2CMD_CARD_ENABLETRIGGER	8h		The trigger detection is enabled. This command can be either send together with the start command to enable trigger immediately or in a second call after some external hardware has been started.
M2CMD_CARD_FORCE_TRIGGER	10h		This command forces a trigger even if none has been detected so far. Sending this command together with the start command is similar to using the software trigger.
M2CMD_CARD_DISABLETRIGGER	20h		The trigger detection is disabled. All further trigger events are ignored until the trigger detection is again enabled. When starting the card the trigger detection is started disabled.
M2CMD_CARD_STOP	40h		Stops the current run of the card. If the card is not running this command has no effect.

All other commands and settings need to be send directly to the card that it refers to.

This example shows the complete setup and synchronization start for our four cards:

```

spcm_dwSetParam_i32 (hSync, SPC_SYNC_ENABLEMASK, 0x000F); // all 4 cards are masked

// to keep it easy we set all card to the same clock and disable trigger
for (i = 0; i < 4; i++)
{
    spcm_dwSetParam_i32 (hCard[i], SPC_CLOCKMODE, SPC_CM_INTPLL);
    spcm_dwSetParam_i32 (hCard[i], SPC_SAMPLERATE, MEGA(100));
    spcm_dwSetParam_i32 (hCard[i], SPC_TRIG_ORMASK, SPC_TM_NONE);
}

// card 0 is trigger master and waits for external positive edge
spcm_dwSetParam_i32 (hCard[0], SPC_TRIG_ORMASK, SPC_TMASK_EXT0);
spcm_dwSetParam_i32 (hCard[0], SPC_TRIG_EXT0_MODE, SPC_TM_POS);

// start the cards and wait for them a maximum of 1 second to be ready
spcm_dwSetParam_i32 (hSync, SPC_TIMEOUT, 1000);
spcm_dwSetParam_i32 (hSync, SPC_M2CMD, M2CMD_CARD_START | M2CMD_CARD_ENABLETRIGGER);
if (spcm_dwSetParam_i32 (hSync, SPC_M2CMD, M2CMD_CARD_WAITREADY) == ERR_TIMEOUT)
    printf ("Timeout occurred - no trigger received within time\n")

```

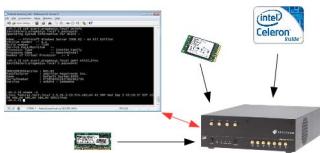
**Using one of the wait commands for the Star-Hub will return as soon as the card holding the Star-Hub has reached this state. However when synchronizing cards with different memory sizes there may be other cards that still haven't reached this level.**



## Error Handling

The Star-Hub error handling is similar to the card error handling and uses the function spcm\_dwGetErrorInfo\_i32. Please see the example in the card error handling chapter to see how the error handling is done.

## Option Embedded Server



The option turns the digitizerNETBOX/generatorNETBOX in a powerful PC that allows to run own programs on a small and remote data acquisition system. The digitizerNETBOX/generatorNETBOX is enhanced by more memory, a powerful CPU, a freely accessible internal SSD and a remote software development access method.

The digitizerNETBOX/generatorNETBOX can either run connected to LAN or it can run totally independent, storing/replaying data to/from the internal SSD. The original digitizerNETBOX/generatorNETBOX remote instrument functionality is still 100% available. Running the embedded server option it is possible to pre-calculate results based on the acquired data, pre-calculate generator data, store acquisitions locally and to transfer just the required data or results parts in a client-server based software structure. A different example for the digitizerNETBOX embedded server is surveillance/logger application which can run totally independent for days and send notification emails only over LAN or offloads stored data as soon as it's connected again.

Access to the embedded server is done through a standard text based Linux shell based on the ssh secure shell.

## Acessing the Embedded Server

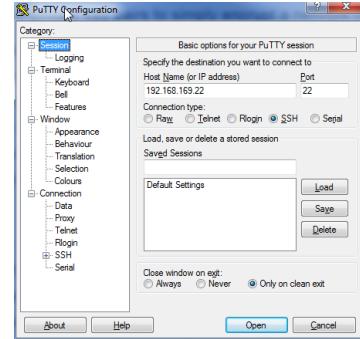
Access to the Embedded Server is only available if that particular option is installed. As this option is a combination of hardware features and software access a later update with that options needs some factory work. As long as no one uses the embedded server connection and no programs are placed in the autostart folder, the digitizerNETBOX/generatorNETBOX will behave just like a standard digitizerNETBOX or generatorNETBOX and can be used as a remote LXI device.

### SSH Connection

The embedded server is accessed using a standard SSH (secure shell) connection. Please install a SSH client on your working system and connect to the digitizerNETBOX/generatorNETBOX IP address (found in the control center) using port 22. Any SSH compatible client will do the job.

An example for a Windows based SSH client is PuTTY which shown on the right.

You may enter the login parameters here also and save a session for faster access.



Username      embedded  
Password      embedded

After first login you should immediately change the password to a personal one using the command „passwd“. Please keep in mind that it is possible to reset the password using the web interface of the digitizerNETBOX/generatorNETBOX. To fully secure access to the digitizerNETBOX/generatorNETBOX it is necessary to give a password to the web interface setup.

### Mounting network folders

Network folders can be mounted and unmounted using the standard Linux mount/unmount command. Please note that you need root rights to do a mounting/unmounting of a network folder. You get root rights for this command by using the „sudo“ command which gives you root rights for some dedicated commands.

Mounting a test folder from a Windows server with active directory may look like this:

```
cd  
mkdir tmp  
sudo mount -t cifs //192.168.169.123/tmp tmp -o user=YourUsername,domain=YourDomain,password=YourPassword
```

You may unmount the folder again with:

```
sudo umount tmp
```

Access to the /etc/fstab table is not available.

### Access to NTP (Network Time Protocol)

You access NTP with (requires firmware version V34 or newer):

```
sudo /usr/sbin/sntp -s de.pool.ntp.org
```

## **Editors**

As a default there are two standard editors installed on the system:

- GNU nano
- vim

## **Installing packages**

Any matching RPM modules can be installed to the system using root rights and the rpm packet manager:

```
sudo rpm -ihv mypackage.rpm
```

# **Programming**

For general information on programming of the internal Spectrum cards please have a look through the complete manual. Programming the cards inside the Embedded Server is 100% similar to programming of the cards of any other host system.

## **Accessing the cards**

Depending on the type of digitizerNETBOX/generatorNETBOX that you have there might be one or two cards installed in the system. If two cards are installed then there is also a Star-Hub installed. Please refer to the chapter „Introduction - Internal Digitizer Modules“ or „Introduction - Internal Generator Modules“ respectively to see how many digitizers are installed in your digitizerNETBOX/generatorNETBOX and whether a starhub is present or not.

As an example, for a DN2.491-16 you will find the information that you have 2 cards M2i.4912-exp and one Star-Hub installed. Accessing these components is done with the following handles:

```
1st card: "/dev/spcm0"  
2nd card: "/dev/spcm1"  
Star-Hub: "sync0"
```

## **Examples**

The home folder „examples-cpp“ contains all Linux based examples that are currently available. Please use and modify these examples for your own programs as you like.

The sub-folder „netbox\_embedded\_server“ contains some additional examples for using the embedded server features. The following examples are available:

### **Client/Server**

A simple example showing the communication over TCP/IP between the digitizerNETBOX/generatorNETBOX (server) and the host PC (client). The server is running an acquisition in FIFO Multiple Recording mode and calculates minimum and maximum value from every block. These results are then sent to the client program for further processing. In our example the results are simply printed to console.

Please change the TCP/IP settings inside the client program to your local settings to get it running.

### **simple\_rec\_fifo\_mail**

This example will run a FIFO multi acquisition and send a mail for each acquired segment as a SBench6 - compatible binary file and text header for that file. The example can easily be modified and used as a base for a monitoring application.

Please be sure to change the email settings to a server and port settings that is available on your system.

Please keep in mind that a high trigger frequency will flood your mailserver with emails which might trigger some spam detection mechanisms. You should therefore use this example only with single trigger events.

### **dbus**

This is an example on how to connect to the digitizerNETBOX/generatorNETBOX internal signals (currently only LAN state).

## **Autostart**

All executable files in the autostart folder will automatically be executed on system start-up. Please place any program in here that should run automatically after powering the system. It is requested to use the „fork()“ command to continue a program or a service in the background if multiple commands should be running.

The autostart feature can be turned off using the web interface in case that some failing program prevents the machine from starting.

## LEDs

The digitizerNETBOX/generatorNETBOX LEDs can be accessed using the special system command „netbox\_led\_client“. Calling this system command from inside a C++ program is shown in the client-server example.

The following commands will manipulate the Arm/Trig and Connected LEDs on the frontplate:

```
system ("netbox_led_client armgreen=1");
system ("netbox_led_client armgreen=0");
system ("netbox_led_client conngreen=1");
system ("netbox_led_client conngreen=0");
```

# Appendix

## Error Codes

The following error codes could occur when a driver function has been called. Please check carefully the allowed setup for the register and change the settings to run the program.

error name	value (hex)	value (dec.)	error description
ERR_OK	0h	0	Execution OK, no error.
ERR_INIT	1h	1	An error occurred when initializing the given card. Either the card has already been opened by another process or an hardware error occurred.
ERR_TYP	3h	3	Initialization only: The type of board is unknown. This is a critical error. Please check whether the board is correctly plugged in the slot and whether you have the latest driver version.
ERR_FNCNOTSUPPORTED	4h	4	This function is not supported by the hardware version.
ERR_BRDREMAP	5h	5	The board index re map table in the registry is wrong. Either delete this table or check it carefully for double values.
ERR_KERNELVERSION	6h	6	The version of the kernel driver is not matching the version of the DLL. Please do a complete re-installation of the hardware driver. This error normally only occurs if someone copies the driver library and the kernel driver manually.
ERR_HWDRVVERSION	7h	7	The hardware needs a newer driver version to run properly. Please install the driver that was delivered together with the card.
ERRADRANGE	8h	8	One of the address ranges is disabled (fatal error), can only occur under Linux.
ERR_INVALIDHANDLE	9h	9	The used handle is not valid.
ERR_BOARDNOTFOUND	Ah	10	A card with the given name has not been found.
ERR_BOARDINUSE	Bh	11	A card with given name is already in use by another application.
ERR_EXPHW64BITADR	Ch	12	Express hardware version not able to handle 64 bit addressing -> update needed.
ERR_FWVERSION	Dh	13	Firmware versions of synchronized cards or for this driver do not match -> update needed.
ERR_SYNCPROTOCOL	Eh	14	Synchronization protocol versions of synchronized cards do not match -> update needed
ERR_LASTERR	10h	16	Old error waiting to be read. Please read the full error information before proceeding. The driver is locked until the error information has been read.
ERR_BOARDINUSE	11h	17	Board is already used by another application. It is not possible to use one hardware from two different programs at the same time.
ERR_ABORT	20h	32	Abort of wait function. This return value just tells that the function has been aborted from another thread. The driver library is not locked if this error occurs.
ERR_BOARDLOCKED	30h	48	The card is already in access and therefore locked by another process. It is not possible to access one card through multiple processes. Only one process can access a specific card at the time.
ERR_DEVICE_MAPPING	32h	50	The device is mapped to an invalid device. The device mapping can be accessed via the Control Center.
ERR_NETWORKSETUP	40h	64	The network setup of a digitizerNETBOX has failed.
ERR_NETWORKTRANSFER	41h	65	The network data transfer from/to a digitizerNETBOX has failed.
ERR_FWPOWERCYCLE	42h	66	Power cycle (PC off/on) is needed to update the card's firmware (a simple OS reboot is not sufficient !)
ERR_NETWORKTIMEOUT	43h	67	A network timeout has occurred.
ERR_BUFFERSIZE	44h	68	The buffer size is not sufficient (too small).
ERR_RESTRICTEDACCESS	45h	69	The access to the card has been intentionally restricted.
ERR_INVALIDPARAM	46h	70	An invalid parameter has been used for a certain function.
ERR_TEMPERATURE	47h	71	The temperature of at least one of the card's sensors measures a temperature, that is too high for the hardware.
ERR_REG	100h	256	The register is not valid for this type of board.
ERR_VALUE	101h	257	The value for this register is not in a valid range. The allowed values and ranges are listed in the board specific documentation.
ERR_FEATURE	102h	258	Feature (option) is not installed on this board. It's not possible to access this feature if it's not installed.
ERR_SEQUENCE	103h	259	Command sequence is not allowed. Please check the manual carefully to see which command sequences are possible.
ERR_READABORT	104h	260	Data read is not allowed after aborting the data acquisition.
ERR_NOACCESS	105h	261	Access to this register is denied. This register is not accessible for users.
ERR_TIMEOUT	107h	263	A timeout occurred while waiting for an interrupt. This error does not lock the driver.
ERR_CALTYPE	108h	264	The access to the register is only allowed with one 64 bit access but not with the multiplexed 32 bit (high and low double word) version.
ERR_EXCEEDSINT32	109h	265	The return value is int32 but the software register exceeds the 32 bit integer range. Use double int32 or int64 accesses instead, to get correct return values.
ERR_NOWRITEALLOWED	10Ah	266	The register that should be written is a read-only register. No write accesses are allowed.
ERR_SETUP	10Bh	267	The programmed setup for the card is not valid. The error register will show you which setting generates the error message. This error is returned if the card is started or the setup is written.
ERR_CLOCKNOTLOCKED	10Ch	268	Synchronization to external clock failed: no signal connected or signal not stable. Please check external clock or try to use a different sampling clock to make the PLL locking easier.
ERR_MEMINIT	10Dh	269	On-board memory initialization error. Power cycle the PC and try another PCIe slot (if possible). In case that the error persists, please contact Spectrum support for further assistance.
ERR_POWERSUPPLY	10Eh	270	On-board power supply error. Power cycle the PC and try another PCIe slot (if possible). In case that the error persists, please contact Spectrum support for further assistance.
ERR_ADCCOMMUNICATION	10Fh	271	Communication with ADC failed. Power cycle the PC and try another PCIe slot (if possible). In case that the error persists, please contact Spectrum support for further assistance.
ERR_CHANNEL	110h	272	The channel number may not be accessed on the board: Either it is not a valid channel number or the channel is not accessible due to the current setup (e.g. Only channel 0 is accessible in interlace mode)
ERR_NOTIFYSIZE	111h	273	The notify size of the last spcm_dwDefTransfer call is not valid. The notify size must be a multiple of the page size of 4096. For data transfer it may also be a fraction of 4k in the range of 16, 32, 64, 128, 256, 512, 1k or 2k. For ABA and timestamp the notify size can be 2k as a minimum.
ERR_RUNNING	120h	288	The board is still running, this function is not available now or this register is not accessible now.
ERR_ADJUST	130h	304	Automatic card calibration has reported an error. Please check the card inputs.
ERR_PRETRIGGERLEN	140h	320	The calculated pretrigger size (resulting from the user defined posttrigger values) exceeds the allowed limit.
ERR_DIRMISMATCH	141h	321	The direction of card and memory transfer mismatch. In normal operation mode it is not possible to transfer data from PC memory to card if the card is an acquisition card nor it is possible to transfer data from card to PC memory if the card is a generation card.
ERR_POSTEXCDSEGMENT	142h	322	The posttrigger value exceeds the programmed segment size in multiple recording/ABA mode. A delay of the multiple recording segments is only possible by using the delay trigger!
ERR_SEGMENTINMEM	143h	323	Memszie is not a multiple of segment size when using Multiple Recording/Replay or ABA mode. The programmed segment size must match the programmed memory size.
ERR_MULTIPLEPW	144h	324	Multiple pulsewidth counters used but card only supports one at the time.

<b>error name</b>	<b>value (hex)</b>	<b>value (dec.)</b>	<b>error description</b>
ERR_NOCHANNELPWOR	145h	325	The channel pulselwidth on this card can't be used together with the OR conjunction. Please use the AND conjunction of the channel trigger sources.
ERR_ANDORMASKOVRLAP	146h	326	Trigger AND mask and OR mask overlap in at least one channel. Each trigger source can only be used either in the AND mask or in the OR mask, no source can be used for both.
ERR_ANDMASKEDGE	147h	327	One channel is activated for trigger detection in the AND mask but has been programmed to a trigger mode using an edge trigger. The AND mask can only work with level trigger modes.
ERR_ORMASKLEVEL	148h	328	One channel is activated for trigger detection in the OR mask but has been programmed to a trigger mode using a level trigger. The OR mask can only work together with edge trigger modes.
ERR_EDGEPEPERMOD	149h	329	This card is only capable to have one programmed trigger edge for each module that is installed. It is not possible to mix different trigger edges on one module.
ERR_DOLEVELMINDIFF	14Ah	330	The minimum difference between low output level and high output level is not reached.
ERR_STARHUBENABLE	14Bh	331	The card holding the star-hub must be enabled when doing synchronization.
ERR_PATPWMSMALLEDGE	14Ch	332	Combination of pattern with pulselwidth smaller and edge is not allowed.
ERR_XMODESETUP	14Dh	333	The chosen setup for (SPCM_X0_MODE .. SPCM_X19_MODE) is not valid. See hardware manual for details.
ERR_PCICHECKSUM	203h	515	The check sum of the card information has failed. This could be a critical hardware failure. Restart the system and check the connection of the card in the slot.
ERR_MEMALLOC	205h	517	Internal memory allocation failed. Please restart the system and be sure that there is enough free memory.
ERR_EEPROMLOAD	206h	518	Timeout occurred while loading information from the on-board EEPROM. This could be a critical hardware failure. Please restart the system and check the PCI connector.
ERR_CARDNOSUPPORT	207h	519	The card that has been found in the system seems to be a valid Spectrum card of a type that is supported by the driver but the driver did not find this special type internally. Please get the latest driver from <a href="http://www.spectrum-instrumentation.com">www.spectrum-instrumentation.com</a> and install this one.
ERR_CONFIGACCESS	208h	520	Internal error occurred during config writes or reads. Please contact Spectrum support for further assistance.
ERR_FIFOHWVERRUN	301h	769	Hardware buffer overrun in FIFO mode. The complete on-board memory has been filled with data and data wasn't transferred fast enough to PC memory. If acquisition speed is smaller than the theoretical bus transfer speed please check the application buffer and try to improve the handling of this one.
ERR_FIFOFINISHED	302h	770	FIFO transfer has been finished, programmed data length has been transferred completely.
ERR_TIMESTAMP_SYNC	310h	784	Synchronization to timestamp reference clock failed. Please check the connection and the signal levels of the reference clock input.
ERR_STARHUB	320h	800	The auto routing function of the Star-Hub initialization has failed. Please check whether all cables are mounted correctly.
ERR_INTERNAL_ERROR	FFFFh	65535	Internal hardware error detected. Please check for driver and firmware update of the card.

## **Spectrum Knowledge Base**

You will also find additional help and information in our knowledge base available on our website:

<https://spectrum-instrumentation.com/en/knowledge-base-overview>

## **Temperature sensors**

The M2p card series has integrated temperature sensors that allow to read out different internal temperatures. These functions are also available for the M2p cards mounted inside of the digitizerNETBOX and generatorNETBOX series. In here the temperature can be read out for every internal card separately.

**The Spectrum driver (starting with version 5.09) checks for overtemperature at every opening of the driver and also uses a background temperature watchdog to ensure that the card's operating temperature stays within the recommended operating range and an ERR\_TEMPERATURE error will be issued if exceeded.**



**In case of a detected temperature error, please carefully check the cooling requirements of the card as explained in the „Cooling Precautions“ chapter earlier in the manual.**



### **Temperature read-out registers**

Up to three different temperature sensors can be read-out for each M2p card. The temperature can be read in different temperature scales at any time:

Register	Value	Direction	Description
SPC_MON_TK_BASE_CTRL	500022	read	Base card temperature in Kelvin
SPC_MON_TK_MODA_0	500023	read	Temperature in Kelvin of front-end module A.
SPC_MON_TK_MODB_0	500024	read	Temperature in Kelvin of front-end module B.
SPC_MON_TC_BASE_CTRL	500025	read	Base card temperature in degrees Celsius
SPC_MON_TC_MODA_0	500026	read	Temperature in degrees Celsius of front-end module A.
SPC_MON_TC_MODB_0	500027	read	Temperature in degrees Celsius of front-end module B.
SPC_MON_TF_BASE_CTRL	500028	read	Base card temperature in degrees Fahrenheit
SPC_MON_TF_MODA_0	500029	read	Temperature in degrees Fahrenheit of front-end module A.
SPC_MON_TF_MODB_0	500030	read	Temperature in degrees Fahrenheit of front-end module B.

### **Temperature hints**

- Manual monitoring of the temperature figures might be used for application specific limits or for logging purposes.
- The temperature sensors can be used to optimize the system cooling.

### **59xx temperatures and limits**

The following description shows the meaning of each temperature figure on the M2p.59xx series and also gives maximum ratings that should not be exceeded. All figures given in degrees Celsius:

Sensor Name	Sensor Location	Typical figure at 25°C environment temperature	Maximum temperature
BASE_CTRL	Inside FPGA	50°C ±5°C	80°C
MODULE_0	Amplifier Front-End of Module A	40°C ±5°C	80°C
MODULE_1	Amplifier Front-End of Module B (if installed)	40°C ±5°C	80°C

## Details on M2p cards I/O lines

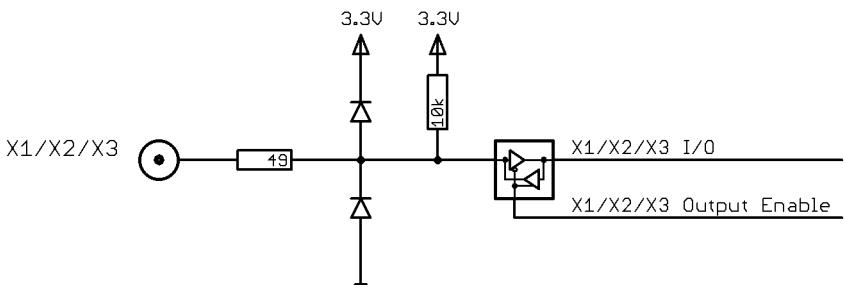
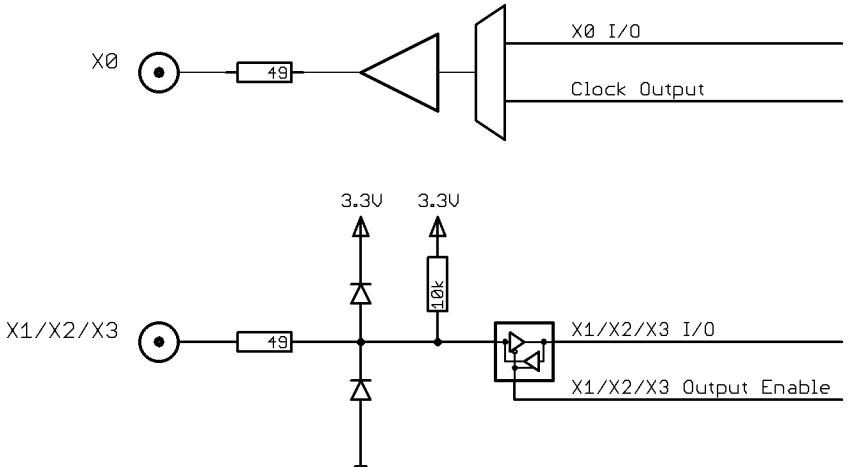
### Multi Purpose I/O Lines

The MMCX Multi Purpose I/O connectors of the M2p cards from Spectrum which do provide input capabilities (**X1, X2 and X3**) are protected against input over voltage conditions.

For this purpose clamping diodes of the types BAS516 are used in conjunction with a series resistor. All three I/O lines are internally clamped to signal ground and to 3.3V clamping voltage. So when connecting sources with a higher level than the clamping voltage plus the forward voltage of typically 0.6..0.7 V will be the resulting maximum high-level level.

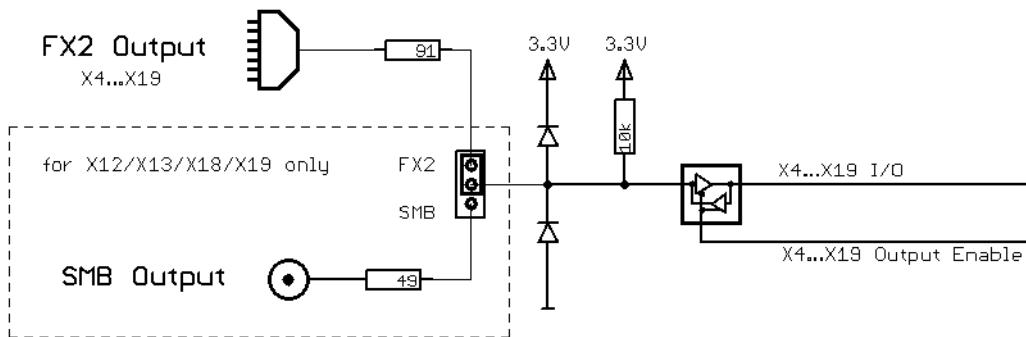
The maximum forward current limit for the used BAS516 diodes is 100 mA, which is effectively limited by the used series resistor for logic levels up to 5.0V. To avoid floating levels with unconnected inputs, a pull up resistor of 10 kOhm to 3.3V is used on each line.

**! The X0 output is always actively driven, hence connecting external sources might either damage the source or the output buffer of your M2p card.**



### Additional I/O Lines (Option -DigFX2)

The additional Multi Purpose I/O connectors of the M2p cards -DigFX2 option from Spectrum does provide sixteen additional Multi-Purpose I/O lines (**X4 to X19**), which are protected against input over voltage conditions. Four of these lines can be jumper selected to be routed to either the main multi-pin FX2 connector or to a SMB connector:



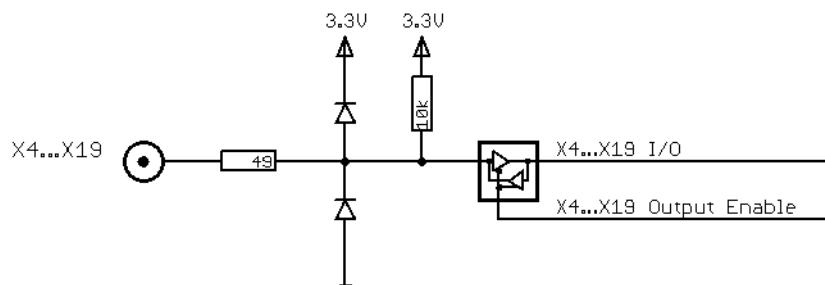
For this purpose clamping diodes of the types BAS516 are used in conjunction with a series resistor. All I/O lines are internally clamped to signal ground and to 3.3V clamping voltage. So when connecting sources with a higher level than the clamping voltage plus the forward voltage of typically 0.6..0.7 V will be the resulting maximum high-level level.

The maximum forward current limit for the used BAS516 diodes is 100 mA, which is effectively limited by the used series resistor for logic levels up to 5.0V. To avoid floating levels with unconnected inputs, a pull up resistor of 10 kOhm to 3.3V is used on each line.

## **Additional I/O Lines (Option -DigSMB)**

The additional Multi Purpose I/O connectors of the M2p card's -DigSMB option from Spectrum does provide sixteen additional Multi-Purpose I/O lines (**X4 to X19**), which are protected against input over voltage conditions:

For this purpose clamping diodes of the types BAS516 are used in conjunction with a series resistor. All I/O lines are internally clamped to signal ground and to 3.3V clamping voltage. So when connecting sources with a higher level than the clamping voltage plus the forward voltage of typically 0.6..0.7 V will be the resulting maximum high-level level.

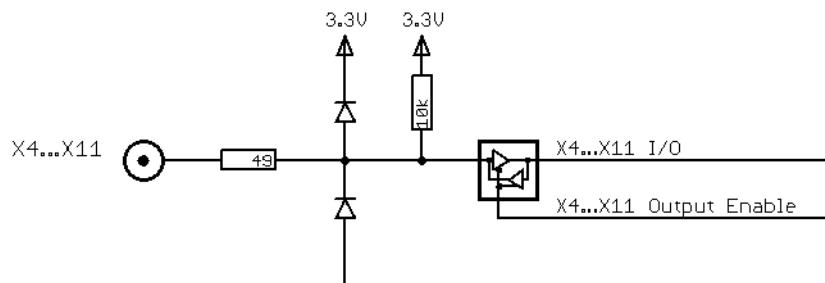


The maximum forward current limit for the used BAS516 diodes is 100 mA, which is effectively limited by the used series resistor for logic levels up to 5.0V. To avoid floating levels with unconnected inputs, a pull up resistor of 10 kOhm to 3.3V is used on each line.

## **Additional I/O Lines (Option -DigBNC)**

The additional Multi Purpose I/O connectors of the digitizerNETBOX's or generatorNETBOX's -DigBNC option from Spectrum does provide eight additional Multi-Purpose I/O lines (**X4 to X11**), which are protected against input over voltage conditions:

For this purpose clamping diodes of the types BAS516 are used in conjunction with a series resistor. All I/O lines are internally clamped to signal ground and to 3.3V clamping voltage. So when connecting sources with a higher level than the clamping voltage plus the forward voltage of typically 0.6..0.7 V will be the resulting maximum high-level level.



The maximum forward current limit for the used BAS516 diodes is 100 mA, which is effectively limited by the used series resistor for logic levels up to 5.0V. To avoid floating levels with unconnected inputs, a pull up resistor of 10 kOhm to 3.3V is used on each line.

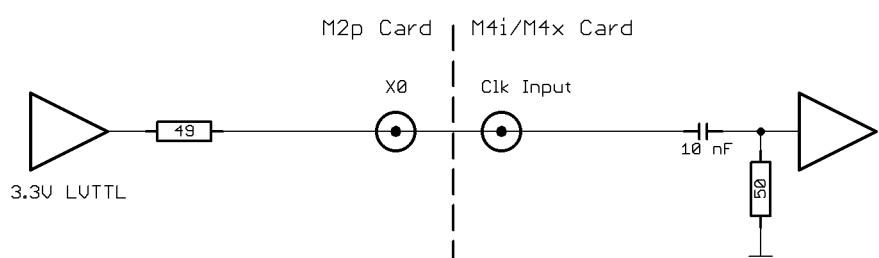
## **Interfacing M2p clock in/out with M4i/M4x**

### **M2p output to M4i/M4x input**

The clock output of the M2p card is a 3.3V LVTTL signal with a 50 Ohm series output impedance, capable of driving 50 Ohm terminated loads.

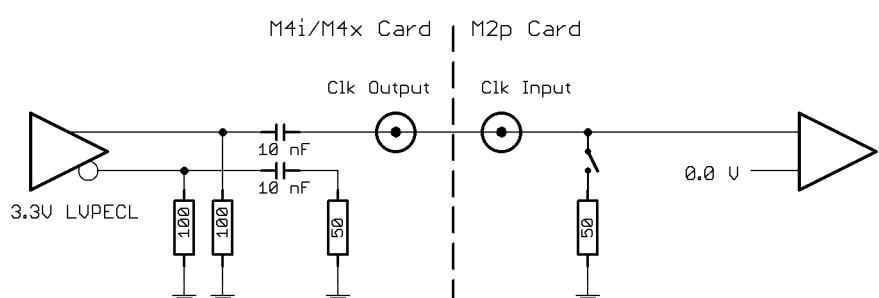
This allows to directly connect the M2p X0 output with the AC-coupled and 50 Ohm terminated LVPECL clock input of an M4i or M4x card.

The resulting voltage divider of the series resistor and the back termination reduce the 3.3V Vpp LVTTL output voltage to half and hence limit the maximum input swing to meet the M4i/M4x clock input specification.



### **M2p input to M4i/M4x output**

The clock output of the M4i/M4x cards is AC-coupled, single-ended LVPECL type with an output swing of approximately 800 mVpp.



Due to the programmable threshold level of the M2p card, the M4i/M4x clock output can be directly connected to the M2p DC-coupled clock input, when setting the threshold to zero Volt.

For best signal integrity and minimizing reflections due to the very fast edge rates of the M4i/M4x LVPECL output, activating the 50 Ohm termination on the M2p card is highly recommended.