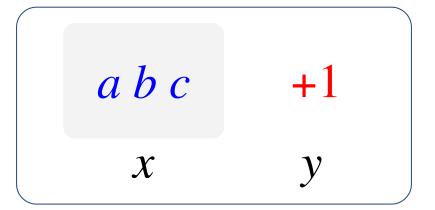
50.007 Machine Learning

Hidden Markov Model

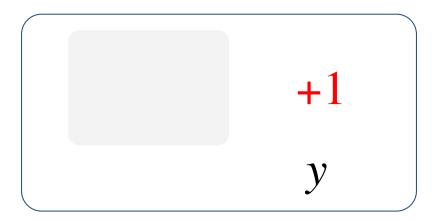
(Adapted from Prof. Lu Wei's slides)

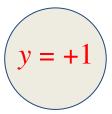
Roy Ka-Wei Lee Assistant Professor, DAI/ISTD, SUTD

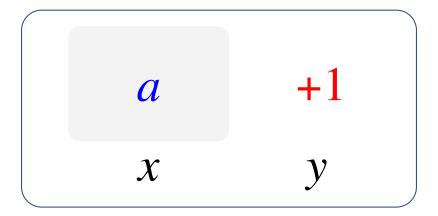


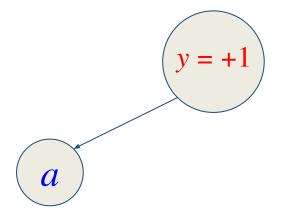


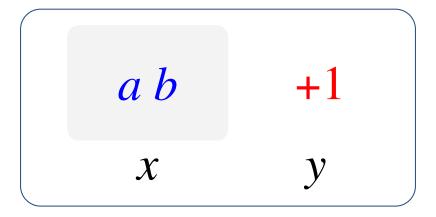


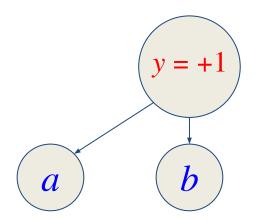


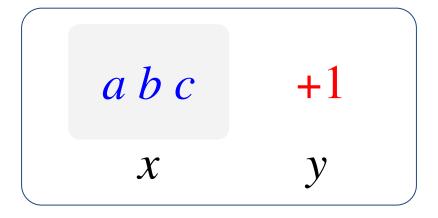


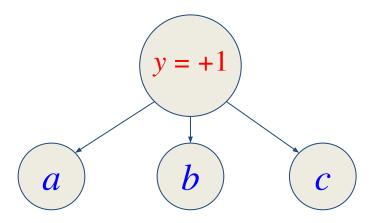




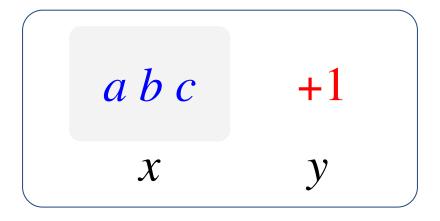


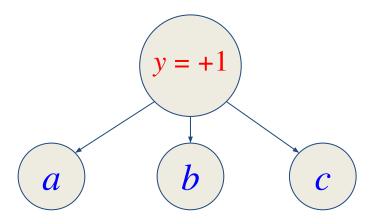






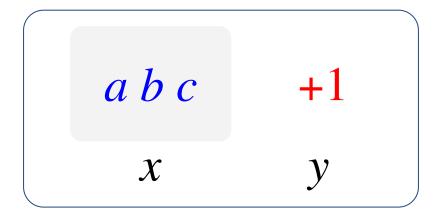


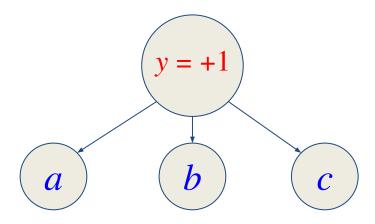




$$p(x="a, b, c", y = +1)$$







p(x="a, b, c", y = +1) = p(y = +1) p(a | y = +1) p(b | y = +1) p(c | y = +1)



Faith is a fine invention



Noun Verb Determiner Adjective Noun

N V D A N

Faith is a fine invention

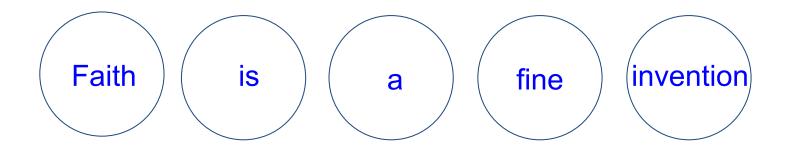




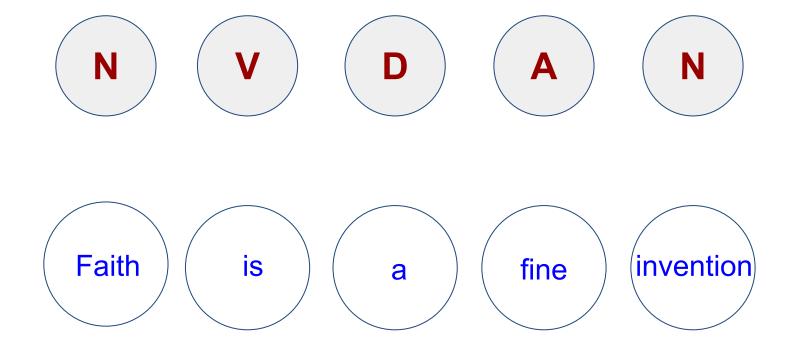






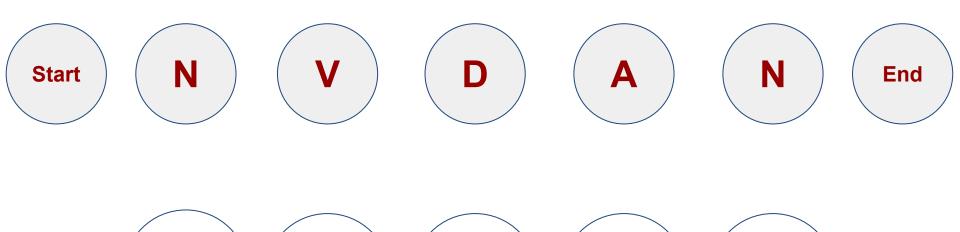








is



a



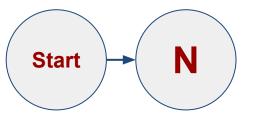
Faith

invention

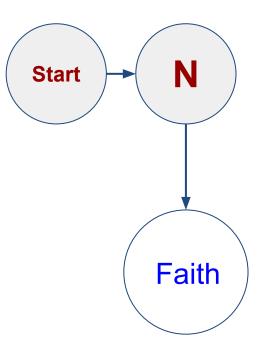
fine



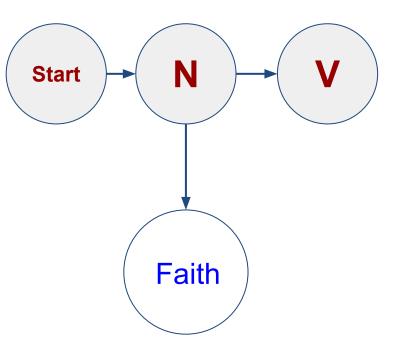




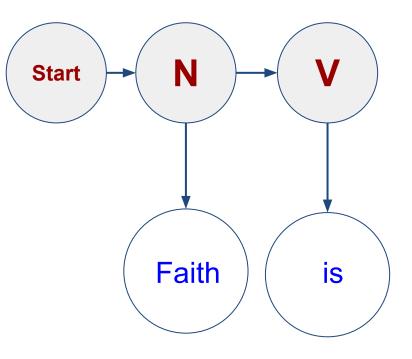




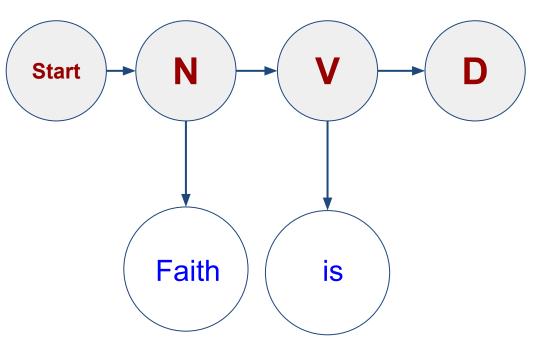




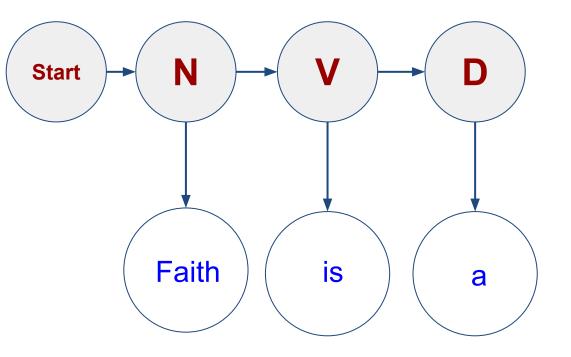




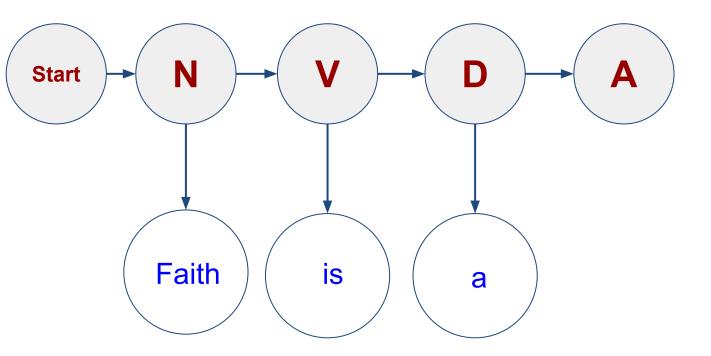




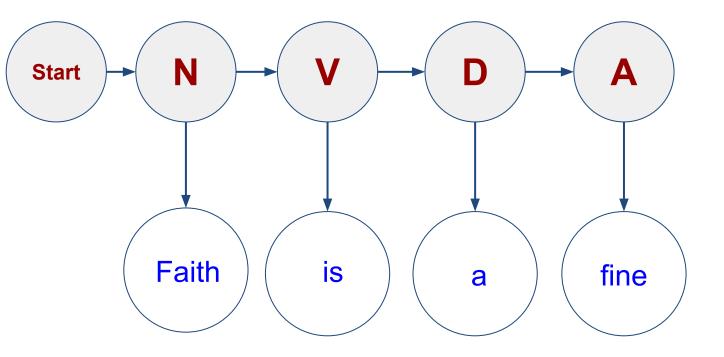




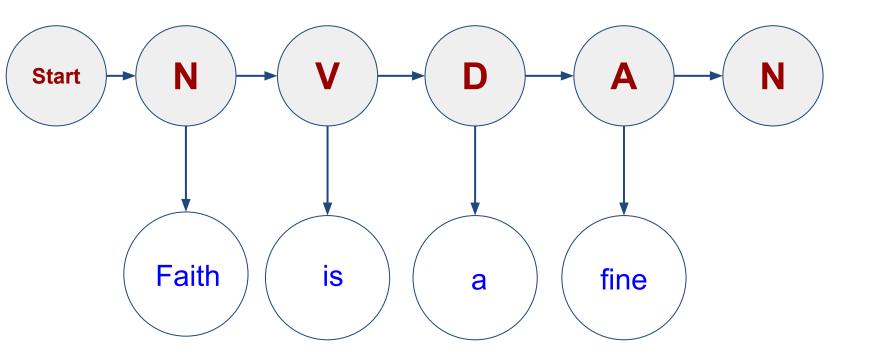




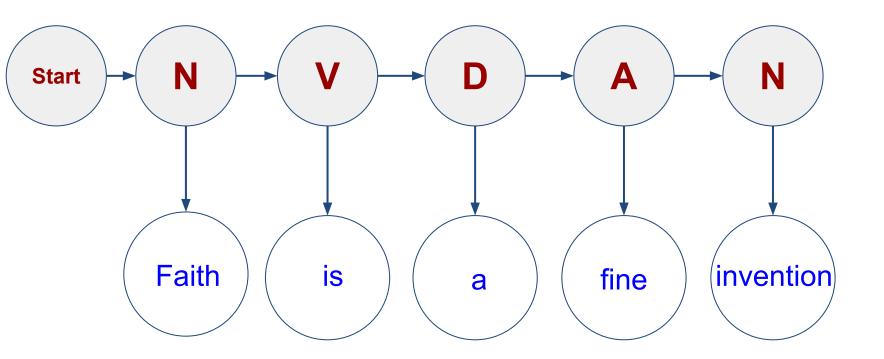




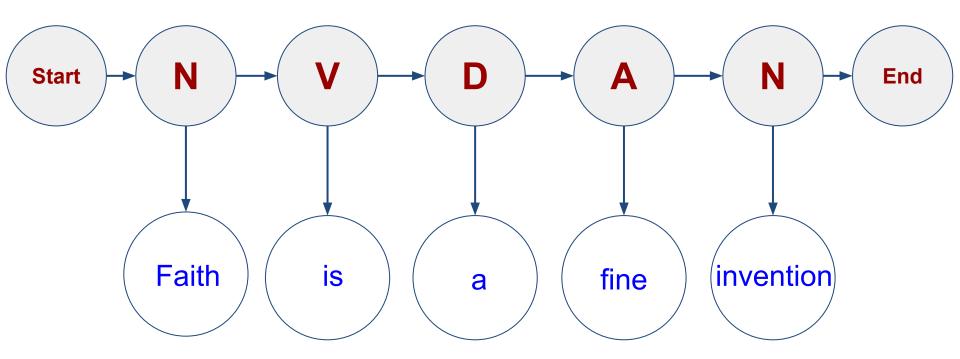




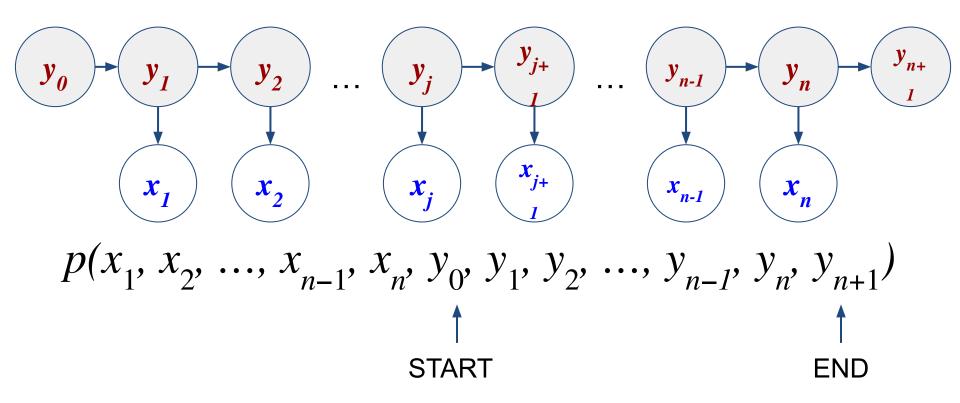




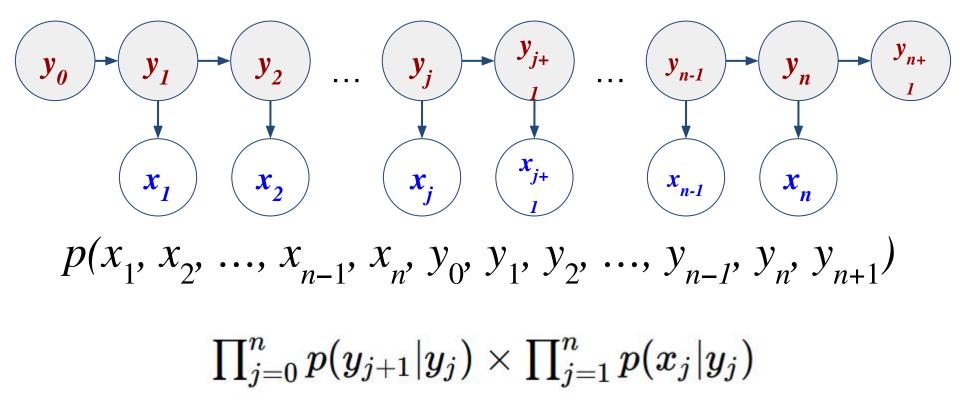




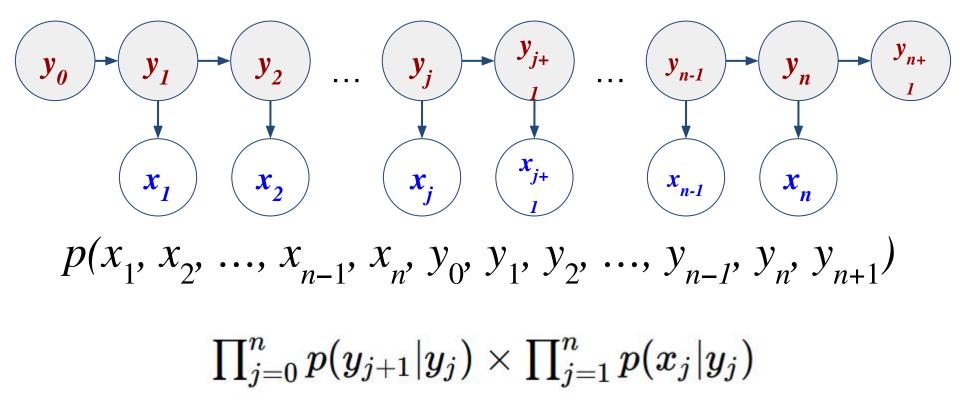




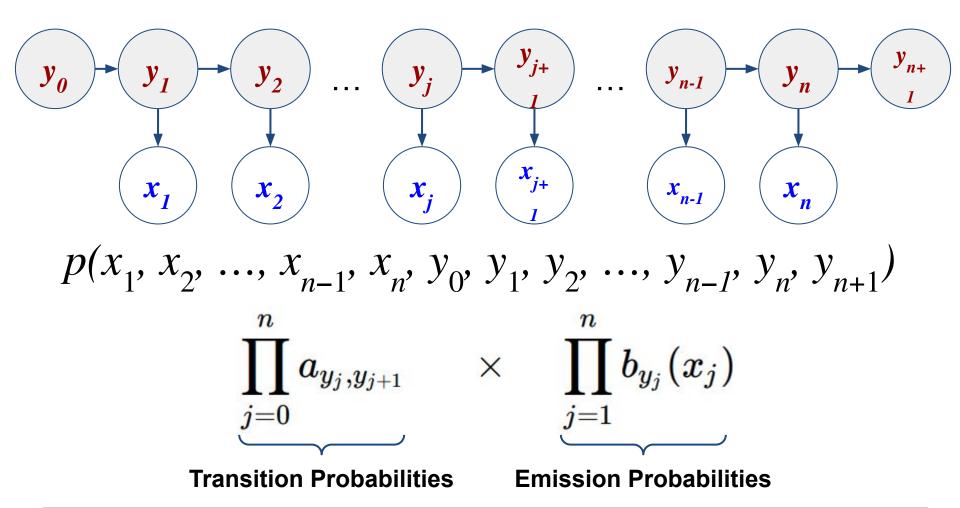














Hidden Markov Model

- An HMM is defined by a tuple $\langle \mathcal{T}, \mathcal{O}, \theta \rangle$, where
 - $-\mathcal{T}$: a set of states including START and END states
 - (*): a set of observation symbols
 - θ : Transition and emission parameters $a_{u,v}$, and $b_u(o)$



$$\mathcal{T} = \{\mathtt{START}, A, B, \mathtt{STOP}\}$$
 $\mathcal{O} = \{\texttt{``the"}, \texttt{``dog"}\}$

$u \backslash v$	\boldsymbol{A}	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
В	0.0	0.8	0.2

$u \backslash o$	"the"	"dog"
\boldsymbol{A}	0.9	0.1
B	0.1	0.9

$$a_{u,v}$$

$$b_u(o)$$



 $a_{u,v}$

$u \backslash v$	\boldsymbol{A}	B	STOP
START	1.0	0.0	0.0
\boldsymbol{A}	0.5	0.5	0.0
B	0.0	8.0	0.2

 $b_u(o)$

$u \setminus o$	"the"	"dog"
\boldsymbol{A}	0.9	0.1
B	0.1	0.9

$$(\mathbf{x},\mathbf{y}) = \mathrm{the}/A, \mathrm{dog}/B, \mathrm{the}/A$$



What is $p(\mathbf{x}, \mathbf{y})$?

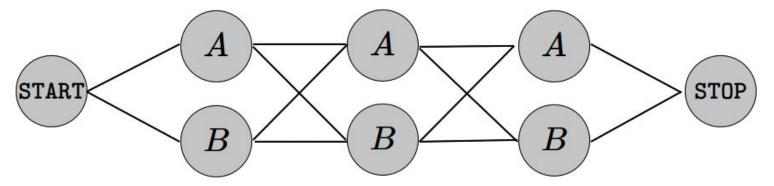
 $a_{u,v}$

$u \backslash v$	\boldsymbol{A}	B	STOP
START	1.0	0.0	0.0
\boldsymbol{A}	0.5	0.5	0.0
\boldsymbol{B}	0.0	0.8	0.2

 $b_u(o)$

$u \backslash o$	"the"	"dog"
\boldsymbol{A}	0.9	0.1
B	0.1	0.9

$$(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$$





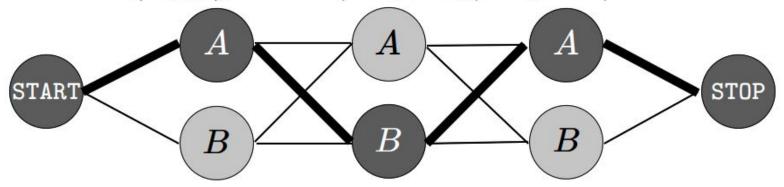
 $a_{u,v}$

$u \backslash v$	\boldsymbol{A}	В	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	0.8	0.2

 $b_u(o)$

$u \backslash o$	"the"	"dog"
\boldsymbol{A}	0.9	0.1
B	0.1	0.9

 $(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$



 $a_{\mathtt{START},A}$



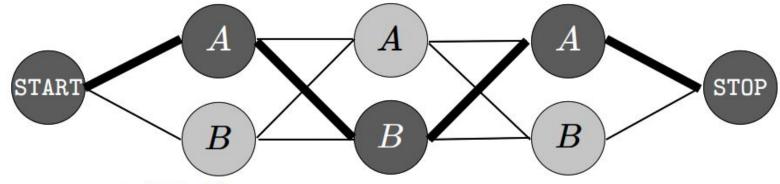
 $a_{u,v}$

$u \backslash v$	\boldsymbol{A}	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	0.8	0.2

 $b_u(o)$

$u \backslash o$	"the"	"dog"
\boldsymbol{A}	0.9	0.1
B	0.1	0.9

 $(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$



 $a_{\mathtt{START},A} \times b_A (\text{"the"})$



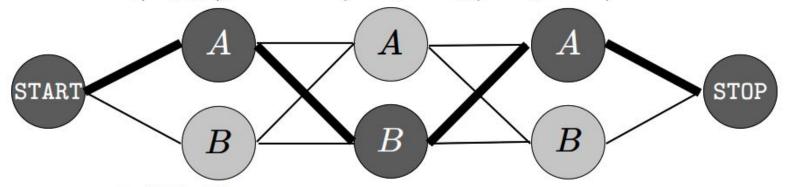
 $a_{u,v}$

$u \backslash v$	\boldsymbol{A}	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	0.8	0.2

 $b_u(o)$

$u \backslash o$	"the"	"dog"
\boldsymbol{A}	0.9	0.1
B	0.1	0.9

 $(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$



 $a_{\mathtt{START},A} \times b_A (\text{"the"}) \times a_{A,B}$



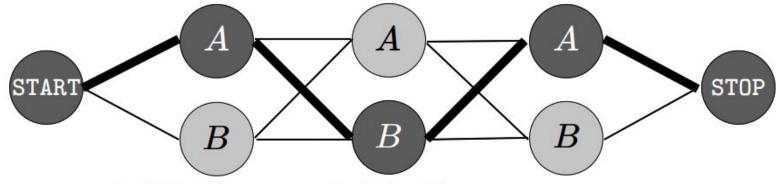
 $a_{u,v}$

$u \backslash v$	\boldsymbol{A}	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	0.8	0.2

 $b_u(o)$

$u \setminus o$	"the"	"dog"
\boldsymbol{A}	0.9	0.1
В	0.1	0.9

 $(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$



 $a_{\mathtt{START},A} \times b_A(\text{"the"}) \times a_{A,B} \times b_B(\text{"dog"})$



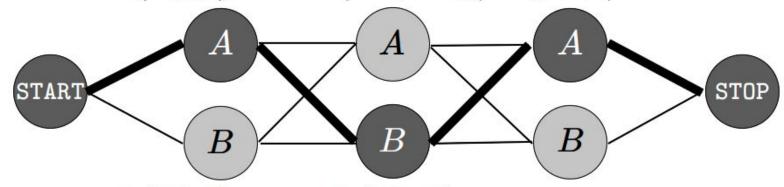
 $a_{u,v}$

$u \backslash v$	\boldsymbol{A}	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	0.8	0.2

 $b_u(o)$

$u \backslash o$	"the"	"dog"
\boldsymbol{A}	0.9	0.1
B	0.1	0.9

 $(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$



 $a_{\mathtt{START},A} \times b_A (\text{``the''}) \times a_{A,B} \times b_B (\text{``dog''}) \times a_{B,A}$



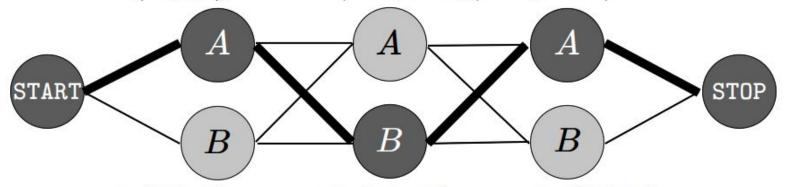
 $a_{u,v}$

$u \backslash v$	A	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
В	0.0	0.8	0.2

 $b_u(o)$

$u \backslash o$	"the"	"dog"
\boldsymbol{A}	0.9	0.1
В	0.1	0.9

 $(\mathbf{x}, \mathbf{y}) = \text{the}/A, \text{dog}/B, \text{the}/A$



 $a_{\mathtt{START},A} \times b_A(\text{"the"}) \times a_{A,B} \times b_B(\text{"dog"}) \times a_{B,A} \times b_A(\text{"the"})$



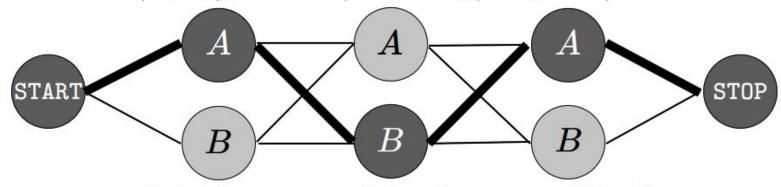
 $a_{u,v}$

$u \backslash v$	\boldsymbol{A}	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	0.8	0.2

 $b_u(o)$

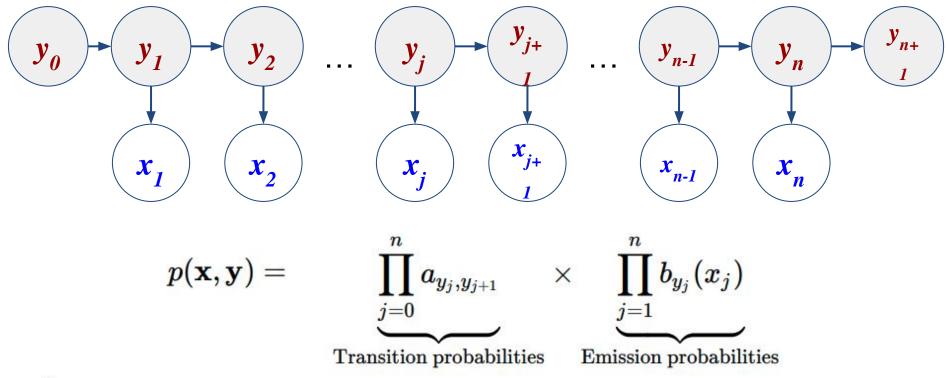
$u \setminus o$	"the"	"dog"
\boldsymbol{A}	0.9	0.1
В	0.1	0.9

 $(\mathbf{x}, \mathbf{y}) = \mathrm{the}/A, \mathrm{dog}/B, \mathrm{the}/A$



 $a_{\mathtt{START},A} \times b_A (\text{"the"}) \times a_{A,B} \times b_B (\text{"dog"}) \times a_{B,A} \times b_A (\text{"the"}) \times a_{A,\mathtt{STOP}}$

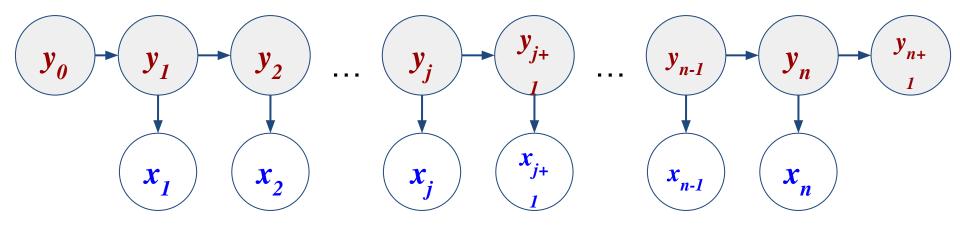






Now that we know what are the model parameters, how do we estimate them? In other words, how to do learning?

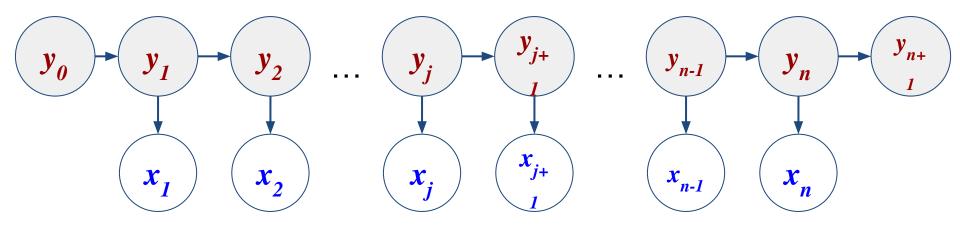




$$a_{u,v} = rac{\mathrm{count}(u,v)}{\mathrm{count}(u)}$$

$$b_u(o) = rac{\mathrm{count}(u
ightarrow o)}{\mathrm{count}(u)}$$





Number of times we see a transition from u to v

$$a_{u,v} = rac{ ext{count}(u,v)}{ ext{count}(u)}$$

Number of times we see the state u in the training set

Number of times we see observation o generated from u

$$b_u(o) = rac{\mathrm{count}(u
ightarrow o)}{\mathrm{count}(u)}$$

Number of times we see the state u in the training set



$$a_{\mathtt{START},A}{ imes}b_A(e){ imes}a_{A,B}{ imes}b_B(g){ imes}a_{B,\mathtt{STOP}}$$

$$imes a_{\mathtt{START},A} { imes} b_A(e) { imes} a_{A,B} { imes} b_B(h) { imes} a_{B,\mathtt{STOP}}$$

$$imes a_{\mathtt{START},A} imes b_A(f) \!\! imes a_{A,B} \!\! imes b_B(h) \!\! imes a_{B,\mathtt{STOP}}$$

(1) Write down the likelihood



$$egin{aligned} &a_{ exttt{START},A} imes b_A(e) imes a_{A,B} imes b_B(g) imes a_{B, exttt{STOP}}\ & imes a_{ exttt{START},A} imes b_A(e) imes a_{A,B} imes b_B(h) imes a_{B, exttt{STOP}}\ & imes a_{ exttt{START},A} imes b_A(f) imes a_{A,B} imes b_B(h) imes a_{B, exttt{STOP}} \end{aligned}$$



$$egin{aligned} ig(a_{ exttt{START},A}ig)^3 imes ig(a_{A,B}ig)^3 imes ig(a_{B, exttt{STOP}}ig)^3 \ & imes ig(b_A(f)ig)^1 imes ig(b_A(e)ig)^2 \ & imes ig(b_B(h)ig)^2 imes ig(b_B(g)ig)^1 \end{aligned}$$



$$egin{aligned} (a_{ exttt{START},A})^3 imes (a_{A,B})^3 imes (a_{B, exttt{STOP}})^3 \ & imes (b_A(f))^1 imes (b_A(e))^2 \ & imes (b_B(h))^2 imes (b_B(g))^1 \end{aligned}$$



$$egin{aligned} &(a_{ exttt{START},A})^{\operatorname{Count}(exttt{START},A)} \ & imes (a_{A,B})^{\operatorname{Count}(A,B)} \ & imes (a_{B, exttt{STOP}})^{\operatorname{Count}(B, exttt{STOP})} \end{aligned}$$



$$rac{y^{(1)}}{x^{(1)}} \; = \; rac{(A,B)}{(e,g)} \qquad rac{y^{(2)}}{x^{(2)}} \; = \; rac{(A,B)}{(e,h)} \qquad rac{y^{(3)}}{x^{(3)}} \; = \; rac{(A,B)}{(f,h)}$$

$$\prod_{u,v} (a_{u,v})^{\operatorname{Count}(u,v)}$$



$$\prod_{u,v} (a_{u,v})^{\operatorname{Count}(u,v)}$$

$$imes \prod_{u,o} (b_u(o))^{\operatorname{Count}(u o o)}$$

(2) This is the likelihood. We can consider the log-likelihood.



$$\sum_{u,v} \operatorname{Count}(u,v) \log(a_{u,v})$$

$$+\sum_{u,o} \operatorname{Count}(u o o) \log(b_u(o))$$

(3) Next, take the partial derivative with respect to each individual parameter, and set it to zero. Solve the equation.



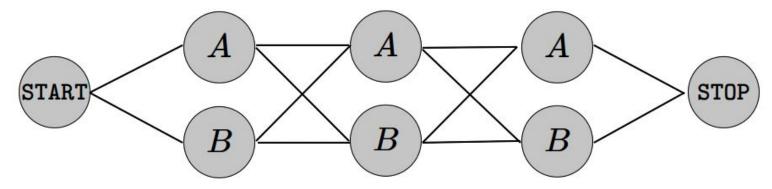
 $a_{u,v}$

$u \backslash v$	\boldsymbol{A}	B	STOP
START	1.0	0.0	0.0
A	0.5	0.5	0.0
B	0.0	8.0	0.2

 $b_u(o)$

$u \backslash o$	"the"	"dog"
\boldsymbol{A}	0.9	0.1
B	0.1	0.9

$$(\mathbf{x}, \mathbf{y}) = \mathrm{the}/A, \mathrm{dog}/B, \mathrm{the}/A$$



Which label sequence y is the most probable given the word sequence x?

