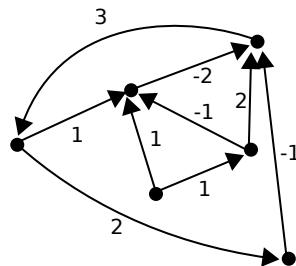
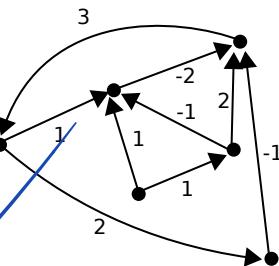


Exercise 1 All-pairs shortest paths

11 pts

- (a) (3 pts) Consider the edge-weighted directed graph shown on the figure (in two copies, to help with sketching). Find a valid vertex potential function, and use it to reweight the graph, as in Johnson's algorithm discussed in the lecture.



- (b) (4 pts) The Floyd-Warshall algorithm for a graph with vertex set $\{1, \dots, n\}$ and edge-weights $w(i, j)$, where a missing edge has weight ∞ , can be described as follows:

```
d(:, :) = w(:, :)
for k=1..n:
    for i=1..n:
        for j=1..n:
            d(i, j) = min{d(i, j), d(i, k)+d(k, j)}
```

Suppose that you forgot the correct nesting of the loops, and instead of the order k, i, j , you write them in the order (i) i, k, j , or (ii) i, j, k , leaving the last line unchanged.

Are any of these variants still correct? If yes, argue why, if not, give a small counterexample.

- (c) (4 pts) Describe the modification necessary to the Floyd-Warshall algorithm, that allows the efficient construction of the actual shortest paths. ($O(n^2)$ extra storage should be sufficient.)

Exercise 2 Approximate distances

7 pts

Consider the following, “simplified” version of the *APD* algorithm discussed in the lecture. (The original APD algorithm computes, given the adjacency matrix A of an unweighted, undirected, connected graph, the pairwise distance matrix D , in time $O(M(n) \log n)$, where $M(n)$ is the time necessary to multiply two $n \times n$ matrices.)

AAPD(A):

if $A_{i,j} = 1$ for all $i \neq j$ **then return** A

$Z = A^2 + A$

let B be an $n \times n$ matrix, where

$$B_{i,j} = \begin{cases} 1 & \text{if } Z_{i,j} \geq 1, \text{ and } i \neq j \\ 0 & \text{otherwise} \end{cases}$$

let $T = AAPD(B)$

return $n \times n$ matrix D , where:

$$D_{i,j} = \begin{cases} 1 & \text{if } A_{i,j} = 1 \\ 2 \cdot T_{i,j} & \text{otherwise.} \end{cases}$$

- (a) (4 pts) The distances returned by this simplified algorithm are clearly not always correct. Give a small example that makes this evident, and sketch the execution by hand.
- (b) (3 pts) Show that the distances returned by the algorithm (denoted D) are never smaller than the true distances (denoted Δ), meaning $\Delta_{i,j} \leq D_{i,j}$ for all i, j .
- (c) (bonus 3 pts) Show that the distances returned by the algorithm are never more than twice the true distances: $D_{i,j} \leq 2\Delta_{i,j}$ for all i, j .

Exercise 3 Set disjointness

4 pts

This problem is not directly related to graphs, its purpose is to illustrate the usefulness of matrix multiplication in solving problems.

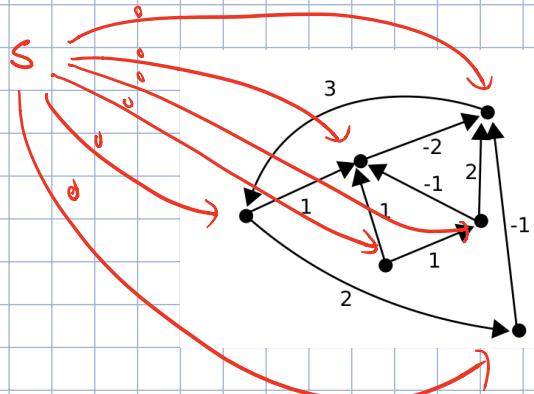
Suppose we are given n subsets of the set $\{1, 2, \dots, n\}$, denoted A_1, \dots, A_n . Describe an algorithm that runs in time $o(n^3)$ and finds a pair i, j of indices $1 \leq i, j \leq n$ such that A_i and A_j are disjoint (or reports that there are no such pairs).

Hint: Matrix multiplication.

Total: 22 points. Have fun with the solutions!

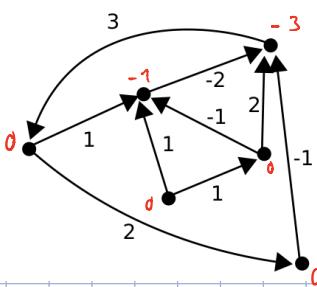
From: Yunmeng Li and Thore Brehmer

- (a) (3 pts) Consider the edge-weighted directed graph shown on the figure (in two copies, to help with sketching). Find a valid vertex potential function, and use it to reweight the graph, as in Johnson's algorithm discussed in the lecture.



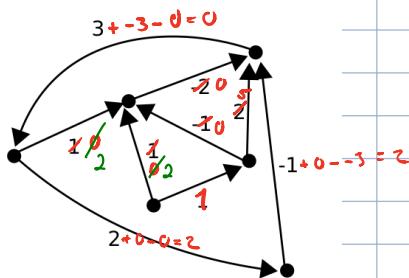
$s \dots$

$d(s, D)$



$s \dots$

new-edge-weights:



$$d(u, v) = d'(u, v) + p(u) - p(v)$$

3

- (b) (4 pts) The Floyd-Warshall algorithm for a graph with vertex set $\{1, \dots, n\}$ and edge-weights $w(i, j)$, where a missing edge has weight ∞ , can be described as follows:

```
d(:, :) = w(:, :)
for k=1..n:
    for i=1..n:
        for j=1..n:
            d(i, j) = min{d(i, j), d(i, k)+d(k, j)}
```

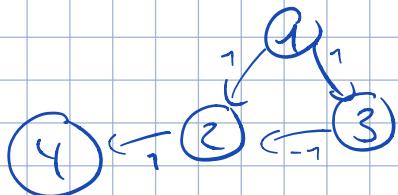


Suppose that you forgot the correct nesting of the loops, and instead of the order k, i, j , you write them in the order (i) i, k, j , or (ii) i, j, k , leaving the last line unchanged.

Are any of these variants still correct? If yes, argue why, if not, give a small counterexample.

(i) i, k, j Not working

For $i = 1$:



i	1	2	3	4
1	0	1	1	∞
2	∞	0	∞	1
3	∞	1	0	∞
4	∞	∞	∞	0

$i=1$:

$$d(1,1) = 0 \quad d(1,1) = 0$$

$$d(1,2) = 1 \quad d(1,2) = 1$$

$$d(1,3) = 1 \quad d(1,3) = 1$$

$$d(1,4) = \infty \quad d(1,4) = 2$$

$k=2$:

$$d(1,1) = 0 \quad d(1,1) = 0$$

$$d(1,2) = 1 \quad d(1,2) = 1$$

$$d(1,3) = 1 \quad d(1,3) = 1$$

$$d(1,4) = 2 \quad d(1,4) = 2$$

$k=3$:

$$d(1,1) = 0 \quad d(1,1) = 0$$

$$d(1,2) = 1 \quad d(1,2) = 1$$

$$d(1,3) = 1 \quad d(1,3) = 1$$

$$d(1,4) = 2 \quad d(1,4) = 2$$

$k=4$:

$$d(1,1) = 0 \quad d(1,1) = 0$$

$$d(1,2) = 1 \quad d(1,2) = 1$$

$$d(1,3) = 1 \quad d(1,3) = 1$$

$$d(1,4) = 2 \quad d(1,4) = 2$$

$i=1$:

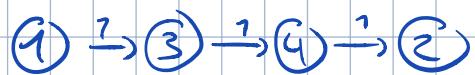
k	1	2	3	4
1	0	1	1	∞
2	0	1	1	2
3	0	0	1	2
4	0	0	∞	2

$$d(1,4) = 2 \text{ but should be } 1 \frac{1}{2}$$

distance from $i=1$ cannot be changed anymore, as the for loop is now on the second ($i=2$) iteration

\Rightarrow (i) i, k, j will not work

(ii) i, j, k Not working e.g.



$i \setminus j$	1	2	3	4
1	0	∞	1	∞
2	∞	0	∞	∞
3	0	∞	0	1
4	∞	1	∞	0

$$d(1,2) = \min_{k=0}^4 \{ d(1,2), d(1,k) + d(k,2) \}$$

$$= \min \{ d(1,2), d(1,1) + d(1,2), \\ d(1,2) + d(2,2), \\ d(1,3) + d(3,2), \\ d(1,4) + d(4,2) \}$$

$$= \min \{ \infty, \infty + \infty, \\ \infty + 0, \\ 1 + \infty, \\ \infty + 1 \} = \infty$$

$$\Rightarrow d(1,2) = \infty \text{ even tho it should be 3}$$

distance from $i=1$ cannot be changed anymore, as the for loop is now on the second ($i=2$) iteration

\Rightarrow (i) i, k, j will not work 4

- (c) (4 pts) Describe the modification necessary to the Floyd-Warshall algorithm, that allows the efficient construction of the actual shortest paths. ($O(n^2)$ extra storage should be sufficient.)

```

d(:,:) = w(:,:)
for k=1..n:
    for i=1..n:
        for j=1..n:  $\leftarrow d_{old} = d(i,j)$ 
             $d(i,j) = \min\{d(i,j), d(i,k)+d(k,j)\}$ 

```

if a new min distance was found the path needs to be updated
if $d_{old} \neq d(i,j)$:

$\text{path_matrix}[i][j] = \text{path_matrix}[i][k]$

path_matrix is initialized similar to the matrix for the Floyd-Warshall algorithm. But every entry $\neq \infty$ is $= j$

- Modification should work as it only updates the path_matrix when a new shorter path has been found.

- Also the path always updates to $\text{path_matrix}[i][k]$
 \Leftrightarrow as the shortest path from i to j has k as middle edge

to print the path (s, t) :

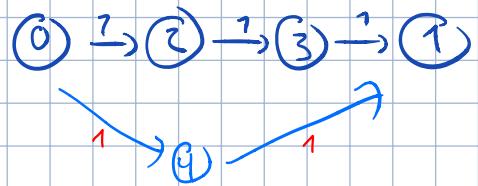
$\text{path} = [s]$

while $s \neq t$:

$s = \text{path_matrix}[s][t]$

$\text{path.append}(s)$

e.g.



	0	1	2	3	4
0	0	∞	1	1	
1	∞	0	∞	∞	
2	∞	∞	0	1	∞
3	∞	1	∞	0	∞
4	∞	1	∞	∞	0

$$\text{init_A} = \begin{array}{|c|cccc|} \hline & 0 & 1 & 2 & 3 & 4 \\ \hline 0 & 0 & \infty & 1 & 1 & \\ 1 & \infty & 0 & \infty & \infty & \\ 2 & \infty & \infty & 0 & 1 & \infty \\ 3 & \infty & 1 & \infty & 0 & \infty \\ 4 & \infty & 1 & \infty & \infty & 0 \\ \hline \end{array} \Rightarrow$$

	0	1	2	3	4
0	0	2	1	2	1
1	∞	0	∞	∞	∞
2	∞	2	0	1	∞
3	∞	1	∞	0	∞
4	∞	1	∞	∞	0

$$D =$$

	0	1	2	3	4
0	0	∞	² 0	⁴ 0	
1	∞	1	∞	∞	
2	∞	∞	2	³ 1	∞
3	∞	¹ 3	∞	3	∞
4	∞	⁴ 1	∞	∞	4

$$\text{init path-matrix} = \begin{array}{|c|cccc|} \hline & 0 & 1 & 2 & 3 & 4 \\ \hline 0 & 0 & \infty & 2 & 0 & 4 \\ 1 & \infty & 1 & \infty & \infty & \infty \\ 2 & \infty & \infty & 2 & 1 & \infty \\ 3 & \infty & 1 & \infty & 3 & \infty \\ 4 & \infty & 4 & 1 & \infty & 4 \\ \hline \end{array} \Rightarrow \text{path-matrix} =$$

	0	1	2	3	4
0	0	4	2	2	4
1	∞	1	∞	∞	∞
2	∞	3	2	3	∞
3	∞	1	∞	3	∞
4	∞	1	∞	∞	4

path(0, 1) ?

$$[0] + \text{path}(\text{path-matrix}[0][1], 1)$$

$$= [0] + [4] + \text{path}(\text{path-matrix}[4][1], 1)$$

$$= [0] + [4] + [1] \quad s == t \quad (1 == 1)$$

$$= [0, 4, 1]$$

4

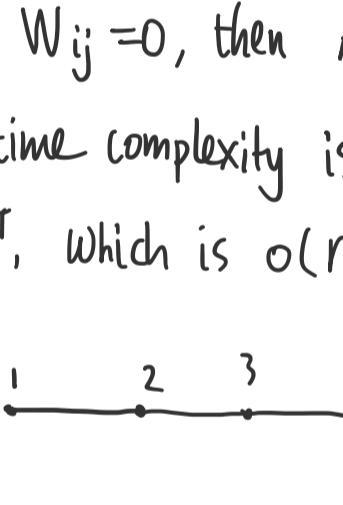
3. for each set A_i , we define a n -dim row vector V_i .
where $V_{i,j} = \begin{cases} 1 & \text{if } j \in A_i \\ 0 & \text{otherwise} \end{cases}$

then $A_i \cap A_j = \emptyset$ iff $V_i V_j^T = 0$, i.e. the inner product of V_i & V_j is 0. We can build a $n \times n$ matrix V ,

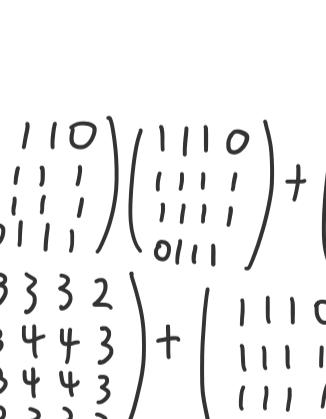
$$V = \begin{bmatrix} V_1 \\ V_2 \\ \vdots \\ V_n \end{bmatrix} \text{ then we compute } W = V V^T,$$

if $W_{ij} = 0$, then A_i & A_j are disjoint.

The time complexity is the same as the matrix multiplication $V V^T$, which is $O(n^3)$.

2. (a)  $A = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix}$

$$Z = \tilde{A}^T + A = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 & 0 \\ 1 & 2 & 1 & 1 \\ 1 & 1 & 2 & 1 \\ 0 & 1 & 1 & 1 \end{pmatrix}$$

$B = \begin{pmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 \end{pmatrix}$ 

$T = AAPD(B) :$

$$\begin{aligned} A &= B, \\ Z' &= \tilde{A}^T + A' = \begin{pmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \end{pmatrix} + \begin{pmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \end{pmatrix} \\ &= \begin{pmatrix} 3 & 3 & 3 & 2 \\ 3 & 4 & 4 & 3 \\ 3 & 4 & 4 & 3 \\ 2 & 3 & 3 & 3 \end{pmatrix} + \begin{pmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 4 & 4 & 4 & 2 \\ 4 & 5 & 5 & 4 \\ 4 & 5 & 5 & 4 \\ 2 & 4 & 4 & 4 \end{pmatrix} \end{aligned}$$

$T' = AAPD(B')$,

$T' = B'$ since $B'[i,j] = 1 \forall i,j$.

$$D' = \begin{pmatrix} 1 & 1 & 1 & 2 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 2 & 1 & 1 & 1 \end{pmatrix} = \begin{cases} 1 & \text{if } B'[i,j] = 1 \\ 2 \cdot B'[i,j] & \text{otherwise.} \end{cases}$$

$T = D'$

$$D = \begin{pmatrix} 2 & 1 & 2 & 4 \\ 1 & 2 & 1 & 2 \\ 2 & 1 & 2 & 1 \\ 4 & 2 & 1 & 2 \end{pmatrix}$$

So $d[1,4] = D[0,3] = 4$, however, the correct distance between vertex 1 & 4 is 3.

(b). In the APD algorithm, the update of D is

APD:

$$D_{ij} = \begin{cases} 2T_{ij} & \text{if } D_{ij} \text{ even} \\ 2T_{ij}-1 & \text{if } D_{ij} \text{ odd} \end{cases}$$

However, in AAPD algorithm, the update of D is

AAPD

$$D_{ij} = \begin{cases} 1 & \text{if } A_{ij} = 1 \\ 2T_{ij} & \text{otherwise.} \end{cases}$$

if $A_{ij} = 1$, both algorithms get $D_{ij} = 1$,

if $A_{ij} \neq 1$, then by above formulas, the D_{ij} in AAPD is

never smaller than D_{ij} in APD, therefore the true

distance $\Delta_{ij} \leq D_{ij}$. correct intuition, but would need to be done more formally