

# Αριστοτέλειο Πανεπιστήμιο Θεσσαλονίκης Πολυτεχνική Σχολή

# Δίκτυα Υπολογιστών ΙΙ

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## 1 Δομή του προγράμματος

```
applications
   Copter.java
   Echo.java
   Media.java
   Obd.java
plots
   plot.py
stamps
   audio.txt
   auto.txt
   copter_tcp.txt
   copter.txt
   echo.txt
   https.txt
   image.txt
   obd_tcp.txt
   obd.txt
   temp.txt
   test.txt
   welcome.txt
UserApplication.java
```

- Το αρχείο που βρίσκεται η main είναι το UserApplication.java.
- Στον φάκελο applications, δημιουργήσαμε ξεχωριστά αρχεία για κάθε εφαρμογή.
- Στον φάκελο *stamps*, βρίσκονται οι έξοδοι του προγράμματος figlet για ascii art λόγους, όπως έχει αναφερθεί και στο report!
- Στον φάκελο plots, έχουμε τέλος ένα python αρχείο για να δημιουργήσουμε τα διαγράμματα μας.

## UserApplication.java

51

```
1 // it is considered in general a bad practise to use asterisks to import all the classes
import java.io.*;
3 import java.net.*;
import java.nio.charset.StandardCharsets;
5 import java.lang.System;
6 import java.awt.Desktop;
7 import javax.sound.sampled.*;
8 import java.lang.Math.*;
9 import java.util.Arrays;
import java.util.Scanner;
import java.time.LocalDateTime;
import applications.*;
15 class UserApplication {
      // TODO create a script that is scraping from ithaki website the request code and the
     ports.
      public static void main (String[] args) throws Exception {
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20
21
          // windows users may be not able to view colors on terminal
22
          final String ANSI_CYAN = "\u001B[36m";
          final String ANSI_RESET = "\u001B[0m";
          // print welcome text
          Scanner input = new Scanner(new File("stamps/welcome.txt"));
          while (input.hasNextLine())
28
29
              System.out.print(ANSI_CYAN); // add some color!
30
              System.out.print(input.nextLine());
              System.out.println(ANSI_RESET);
33
          System.out.println();
35
          System.out.print("Press ENTER to continue");
          System.in.read();// pause a little bit to enjoy the view
36
37
38
           // preamble
          byte[] clientIP = { (byte)192, (byte)168, (byte)1, (byte)20};
40
          byte[] hostIP = { (byte)155, (byte)207, (byte)18, (byte)208};
41
          InetAddress clientAddress = InetAddress.getByAddress(clientIP);
          InetAddress hostAddress = InetAddress.getByAddress(hostIP);
43
          int serverPort = 38022;
44
          int clientPort = 48022;
45
          String requestCodeEcho = "E0818 ";
          String requestCodeImage = "M2685UDP=1024";
          String requestCodeSound = "A7269";
48
          String requestCodeCopter = "Q2797";
          String requestCodeVehicle = "V4118";
          DatagramSocket socket = new DatagramSocket(clientPort);
52
          long timeBefore = 0;
          int flag =1; // control user input
          do {
```

```
System.out.println("\nPlease enter a number (1-11). Available options are:\n1) Echo
with delay\n2) Echo no delay\n3) Temperature\n4) Image\n5) Music\n6) Vehicle UDP\n7)
Ithakicopter UDP\n8) Autopilot\n9) HTTPS TCP\n10) Ithakicopter TCP\n11) Vehicle TCP");
    String choiceApp = (new Scanner(System.in)).nextLine();
    //checkArguements(args); // check the validity of command line arguement
    switch (choiceApp) {
    case "1":
                          ----- Echo -----
    input = new Scanner(new File("stamps/echo.txt"));
    while (input.hasNextLine())
        System.out.println(input.nextLine());
    Thread.sleep(1500); // pause a little bit to enjoy the view
    File info = new File("logs/echo_info_delay.txt");
    FileWriter writerInfo = new FileWriter(info);
    writerInfo.write("Info:\n" + "The request code is " + requestCodeEcho + "\n");
    writerInfo.write("Tic: " + LocalDateTime.now() + "\n");
    File fileSamples = new File("logs/echo_samples_delay.txt");
    FileWriter writerSamples = new FileWriter(fileSamples);
    File fileThroughput = new File("logs/echo_throughput_delay.txt");
    FileWriter writerThroughput = new FileWriter(fileThroughput);
    File fileRto = new File("logs/rto.txt");
    FileWriter writerRto = new FileWriter(fileRto);
    timeBefore = System.currentTimeMillis();
    long tic[] = new long[8];
    //long toc[] = new long[8];
    int cumsum[] = new int[8]; // cumulative sum
    float throughput[] = new float[8]; // worst case we need 8 elements to store data
    int count8sec[] = new int[8]; // keep track how many 8 seconds have passed
    for(int i = 0; i<8; i++) {</pre>
        tic[i] = timeBefore + i*1000; // move per second
    double rtts = 0;
    double rttd = 0;
    double rto = 0;
    int isFirst = 1;
    while ((System.currentTimeMillis() - timeBefore) < 60000 * 4){</pre>
        long rtt = Echo.execute(socket, hostAddress, serverPort, requestCodeEcho);
        writerSamples.write(rtt + "\n");
        // throughput moving average
         for(int i = 0; i<8; i++) {</pre>
              //System.out.println("The element " + i + " has tic: " + tic[i]);
              long toc = System.currentTimeMillis() - tic[i];
             System.out.println("The element " + i + " has toc: " + toc);
              if (toc < 8000 && toc > 0) {
                  cumsum[i] += 32*8; // assume no timeouts during the measurements
```

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```
System.out.println("Cumsum: " + cumsum[i]);
         }
         else if(toc > 8000){
             count8sec[i]++;
             tic[i] = count8sec[i] *8000 + timeBefore + i*1000;
             throughput[i] = cumsum[i]/(float)8;
             System.out.println("I will flush " + cumsum[i] + " cumsum");
             System.out.println("The throughput is: " + throughput[i]);
             writerThroughput.write(throughput[i]+ "\n");
             cumsum[i] = 0; // let's start again for the next 8 seconds
         }
     }
     // Retransmission timeout
     // init values
     if (isFirst == 1) {
         rtts = rtt;
         rttd = rtt/2;
         rto = 1; // according to rfc
         writerRto.write("RTT SRTT RTTd RTO\n");
     double temp = rtts;
     rtts = 0.875*temp + 0.125*rtt;
     temp = rttd;
     rttd = 0.75*temp + 0.25*Math.abs(rtt - rtts);
     rto = rtts + 1.8*rttd;
     writerRto.write(rtt + " " + rtts + " " + rttd + " " + rto + "\n");
     System.out.println();
     isFirst = 0;
}
writerInfo.write("Toc: " + LocalDateTime.now());
writerInfo.close();
writerSamples.close();
writerThroughput.close();
writerRto.close();
socket.close();
break;
input = new Scanner(new File("stamps/echo.txt"));
while (input.hasNextLine())
{
    System.out.println(input.nextLine());
}
Thread.sleep(1500); // pause a little bit to enjoy the view
info = new File("logs/echo_info_no_delay.txt");
writerInfo = new FileWriter(info);
writerInfo.write("Info:\n" + "The request code is " + requestCodeEcho + "\n");
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```
writerInfo.write("Tic: " + LocalDateTime.now() + "\n");
fileSamples = new File("logs/echo_samples_no_delay.txt");
writerSamples = new FileWriter(fileSamples);
fileThroughput = new File("logs/echo_throughput_no_delay.txt");
writerThroughput = new FileWriter(fileThroughput);
timeBefore = System.currentTimeMillis();
tic = new long[8];
//long toc[] = new long[8];
cumsum = new int[8]; // cumulative sum
throughput = new float[8]; // worst case we need 8 elements to store data
count8sec = new int[8];
for(int i = 0; i<8; i++) {</pre>
    tic[i] = timeBefore + i*1000; // move per second
while ((System.currentTimeMillis() - timeBefore) < 60000 * 4){</pre>
    long value = Echo.execute(socket, hostAddress, serverPort, "E0000");
    writerSamples.write(value + "\n");
     // throughput moving average
     for(int i = 0; i < 8; i++) {</pre>
         //System.out.println("The element " + i + " has tic: " + tic[i]);
         long toc = System.currentTimeMillis() - tic[i];
         System.out.println("The element " + i + " has toc: " + toc);
         if (toc < 8000 && toc > 0) {
             cumsum[i] += 32*8; // assume no timeouts during the measurements
             System.out.println("Cumsum: " + cumsum[i]);
         else if(toc > 8000){
             count8sec[i]++;
             tic[i] = count8sec[i] *8000 + timeBefore + i*1000;
             throughput[i] = cumsum[i]/(float)8;
             System.out.println("I will flush " + cumsum[i] + " cumsum");
             System.out.println("The throughput is: " + throughput[i]);
             writerThroughput.write(throughput[i]+ "\n");
             cumsum[i] = 0; // let's start again for the next 8 seconds
     System.out.println();
writerInfo.write("Toc: " + LocalDateTime.now());
writerInfo.close();
writerSamples.close();
writerThroughput.close();
socket.close();
break;
case "3":
/* ----- */
input = new Scanner(new File("stamps/temp.txt"));
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```
while (input.hasNextLine())
        System.out.println(input.nextLine());
    Thread.sleep(1500); // pause a little bit to enjoy the view
    FileWriter writerTemp = new FileWriter(new File("logs/temp_info.txt"));
    writerTemp.write("Info Temperature app:\n" + requestCodeEcho + "\n" + LocalDateTime.
now() + "\n");
    for (int i = 0; i < 1; i++) {
         Echo.execute(socket, hostAddress, serverPort, requestCodeEcho + "T00");
         System.out.println();
    writerTemp.write(LocalDateTime.now() + "\n");
    writerTemp.close();
    socket.close();
    break;
    case "4":
    input = new Scanner(new File("stamps/image.txt"));
    while (input.hasNextLine())
        System.out.println(input.nextLine());
    Thread.sleep(1500); // pause a little bit to enjoy the view
    //for (int i = 0; i<4; i++) Echo.execute(socket, hostAddress, serverPort,</pre>
requestCodeEcho);
    String encodingImage = "CAM=PTZDIR=R";
    FileWriter writerImage = new FileWriter(new File("logs/image_info_" + encodingImage));
    writerImage.write(encodingImage + "\n" + requestCodeImage + "\n" + LocalDateTime.now()
+ "\n");
    for (int i = 0; i < 1; i++) {</pre>
         Media.image(socket, hostAddress, serverPort, requestCodeImage + encodingImage);
         System.out.println();
    writerImage.write(LocalDateTime.now() + "\n");
    writerImage.close();
    socket.close();
    break;
    case "5":
               ------ */
    input = new Scanner(new File("stamps/audio.txt"));
    while (input.hasNextLine())
        System.out.println(input.nextLine());
    Thread.sleep(1500);
    //for (int i = 0; i<4; i++) Echo.execute(socket, hostAddress, serverPort,</pre>
requestCodeEcho);
    String numAudioPackets = "999";
    String[] type = {"F", "T"};
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```
String[] encoding = {"AQ", ""};
    String completeRequest = requestCodeSound + encoding[0] + type[0] + numAudioPackets;
    File infoMusic = new File("logs/music_info_" + encoding[1] + type[0] + ".txt");
    FileWriter writerInfoMusic = new FileWriter(infoMusic);
    writerInfoMusic.write(requestCodeSound + "\nEncoding: " + encoding[1] + "\nType: " +
type[0] + LocalDateTime.now() + "\n");
    Media.audio(socket, hostAddress, serverPort, completeRequest);
    System.out.println();
    writerInfoMusic.write(LocalDateTime.now() + "\n");
    writerInfoMusic.close();
    socket.close();
    break;
    case "6":
              ----- Vehicle OBD UDP----- */
    input = new Scanner(new File("stamps/obd.txt"));
    while (input.hasNextLine())
        System.out.println(input.nextLine());
    Thread.sleep(1500); // pause a little bit to enjoy the view
    Obd.udpTelemetry(socket, hostAddress, serverPort, requestCodeVehicle);
    socket.close();
    break;
    case "7":
                              ---- Ithakicopter UDP-----
    socket = new DatagramSocket(48078);
    input = new Scanner(new File("stamps/copter.txt"));
    while (input.hasNextLine())
        System.out.println(input.nextLine());
    Thread.sleep(1500);
    System.out.println("For Ithakicopter UDP telemetry you need to open ithakicopter.jar")
    System.out.print("Did you open it? If yes press ENTER to continue");
    System.in.read();
    Thread.sleep(1000); // pause a bit to catch up with the user
    System.out.println("Press ENTER to exit");
    Thread.sleep(1000);
    FileWriter writerCopter = new FileWriter(new File("logs/copter_info.txt"))
    writerCopter.write("Info Ithakicopter app:\n" + LocalDateTime.now() + "\n");
    writerCopter.write("MOTOR ALTITUDE TEMPERATURE PRESSURE");
    for (int i = 0; i<4; i++) Echo.execute(socket, hostAddress, serverPort,</pre>
requestCodeEcho);
    while (System.in.available() == 0) {
        Copter.udpTelemetry(socket, hostAddress, serverPort, writerCopter);
    }
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```
writerCopter.write(LocalDateTime.now() + "\n");
    writerCopter.close();
    socket.close();
    break;
    case "8":
    /* ----- */
    socket = new DatagramSocket(48078);
    Socket socketAuto = new Socket(hostAddress, 38048);
    input = new Scanner(new File("stamps/auto.txt"));
    while (input.hasNextLine())
        System.out.println(input.nextLine());
    }
    Thread.sleep(1500); // pause a little bit to enjoy the view
    int lowerBound = 160;
    int higherBound = 190;
    Copter.autopilot(socket, hostAddress, serverPort, socketAuto, Math.min(200, Math.max
(150, lowerBound)), Math.min(200, Math.max(150, higherBound)));
    socketAuto.close();
    break;
    case "9":
                    ----- HTTPS TCP----- */
    Socket httpsSocket = new Socket(hostAddress, 80);
    input = new Scanner(new File("stamps/https.txt"));
    while (input.hasNextLine())
    {
        System.out.println(input.nextLine());
    Thread.sleep(1500); // pause a little bit to enjoy the view
    https(httpsSocket);
    httpsSocket.close();
    break;
    case "10":
    // can we use 38098? If we open the website we see that this is the port opened
    //Socket socketCopter = new Socket(hostAddress, 38048);
    input = new Scanner(new File("stamps/copter_tcp.txt"));
    while (input.hasNextLine())
    {
        System.out.println(input.nextLine());
    Thread.sleep(1500); // pause a little bit to enjoy the view
    for (int i = 0; i<4; i++) Echo.execute(socket, hostAddress, serverPort,</pre>
requestCodeEcho);
    int target = 180;
    for (int i = 0; i<20; i++) {</pre>
    System.out.println(new String(Copter.tcpTelemetry(hostAddress, target)));
    //socketCopter.close();
    break;
```

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```
case "11":
                             ---- Vehicle OBD TCP----
    input = new Scanner(new File("stamps/obd_tcp.txt"));
    while (input.hasNextLine())
        System.out.println(input.nextLine());
    }
    Thread.sleep(1500); // pause a little bit to enjoy the view
    for (int i = 0; i<4; i++) Echo.execute(socket, hostAddress, serverPort,</pre>
requestCodeEcho);
    Socket socketVehicle = new Socket(hostAddress, 29078);
    FileWriter writerVehicleInfo = new FileWriter(new File("logs/car_info.txt"));
    writerVehicleInfo.write("Info Vehicle app:\n" + LocalDateTime.now() + "\n");
    FileWriter writerVehicleData = new FileWriter(new File("logs/car_telemetry.txt"));
    timeBefore = System.currentTimeMillis();
    float engineTime = 0;
    while (engineTime < 60 * 4){
        engineTime = Obd.tcpTelemetry(socketVehicle, writerVehicleData);
        System.out.println("The engine run time is " + engineTime + "\n");
    writerVehicleInfo.write(LocalDateTime.now() + "\n");
    writerVehicleInfo.close();
    writerVehicleData.close();
    socketVehicle.close();
    break;
     This is a playgorund!! Test whatever you like....
    case "12":
    Socket foo = new Socket(hostAddress, 38048);
    OutputStream out = foo.getOutputStream();
    InputStream in = foo.getInputStream();
    InputStreamReader isr = new InputStreamReader(in);
    BufferedReader bf = new BufferedReader(isr);
    ByteArrayOutputStream bis = new ByteArrayOutputStream();
    // if use readAllBytes the InputStream is closed
    // actually readNBytes is quite weird to be honest
    out.write("AUTO FLIGHTLEVEL=100 LMOTOR=100 RMOTOR=100 PILOT \r\n".getBytes());
    String data = new String();
    while ((data = bf.readLine()) != null) {
        bis.write((data + "\n").getBytes());
    data = new String(bis.toByteArray(), StandardCharsets.US_ASCII);
    System.out.println(data);
    break;
    case "13":
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```
// Major difference between this code snippet and the above is the reposnse time!
Actually it is all about null and ending stream!
    Socket foo1 = new Socket(hostAddress, 38048);
    OutputStream out1 = foo1.getOutputStream();
    InputStream in1 = foo1.getInputStream();
    InputStreamReader isr1 = new InputStreamReader(in1);
    BufferedReader bf1 = new BufferedReader(isr1);
    // if use readAllBytes the InputStream is closed
    // actually readNBytes is quite weird to be honest
    for (int i = 0; i < 4; i++) {</pre>
    out1.write("AUTO FLIGHTLEVEL=100 LMOTOR=100 RMOTOR=100 PILOT \r\n".getBytes());
    //String data1 = new String(in1.readNBytes(427), StandardCharsets.US_ASCII);
    //System.out.println(data1);
    //System.out.println(bf1.readLine());
    //System.out.println(bf1.readLine());
    //for (int i = 0; i < 40; i++) {
          System.out.println(bf1.readLine());
    //
    //}
    // In general we have a lag when reading if we are in the end of the stream
    //while(bf1.readLine() != null) {System.out.println(bf1.readLine());} // warning bf
read is called two times
    // waiting to encounter null isn't good. Too much lag. Waiting if the stream is closed
or not
    // why we do this? Ithaki when establishing this connection first send some
introductory info and then the actual telemetry. So you need to handle streams in a proper
way!
    if (i==0) {
        for (int l = 0; l < 14; l++) { // after some tinkering we have the data
            System.out.println(bf1.readLine());
    }
    else {
        System.out.println(bf1.readLine());
    }
    }
    break:
    /*
       *************************
                                 End of playground
     * ************************************
    default:
System.out.println("Please provide a valid input. If you want to exit then press Control-C
.\n");
flag = 0;
        } // end switch
    } while(flag == 0);
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```
----- Close UDP sockets -----*
    if (!socket.isClosed()) {
        socket.close();
        System.out.println("\nShuting down UDP sockets...");
    }
    System.out.println("\nx--------Hooray! Java application finished
successfully!----x");
}
private static void https(Socket socket) {
    try {
        InputStream in = socket.getInputStream(); // what I receive from the server
        OutputStream out = socket.getOutputStream(); // what i send to the server
        long timeBefore = System.currentTimeMillis();
        out.write("GET /netlab/hello.html HTTP/1.0\r\nHost: ithaki.eng.auth.gr:80\r\n\r\n"
.getBytes());
        byte[] inputBuffer = in.readAllBytes();
        String message = new String(inputBuffer, StandardCharsets.US_ASCII);
        System.out.println("Ithaki responded via TCP with: \n" + message);
        System.out.println("Time response: " + (System.currentTimeMillis() - timeBefore)/(
float)1000 + " seconds");
        socket.close();
    }
    catch (Exception x) {
        System.out.println(x + "TCP application failed");
    }
private static void checkArguements (String[] args) {
    if (args.length == 2) {
        System.out.println("Command line arguements: This is the first " + args[0] + " " +
 "and this is the second " + args[1]);
    String[] directionOptions = {"L", "D", "U", "R"};
    int flag = 0;
    for (String i : directionOptions) {
        if (i.equals(args[0])) {
            flag = 1;
            System.out.println("Direction: " + args[0]);
            break:
        }
    }
    if (flag == 0) {
        System.out.println("Try again, wrong direction. Available options are: L, R, U, D"
);
        return;
    if (Integer.parseInt(args[1])>=1 && Integer.parseInt(args[1])<=100) {</pre>
        System.out.println("How many times to repeat the movement of the camera on that
direction? " + Integer.parseInt(args[1]));
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### 3 applications

#### 3.1 Echo.java

```
package applications;
import java.net.DatagramSocket;
4 import java.net.DatagramPacket;
5 import java.net.InetAddress;
6 import java.nio.charset.StandardCharsets;
8 public class Echo {
      * UDP TX/RX Echo application with delay
      * WARNING: It doesn't close the DatagramSocket. You should do it manually if it is
     desired after the call of the function.
       * @param requestCode If request code is set to E000 then the execute will have no delay
     for the RX
      public static long execute(DatagramSocket socket, InetAddress hostAddress, int serverPort,
      String requestCode) {
         System.out.println("\n------");
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         if (requestCode.equals("E0000")) System.out.println("Delay: OFF");
         else if (requestCode.length()>5) System.out.println("Mode: Temperature\nDelay: OFF");
21
         else System.out.println("Delay: OFF");
          byte[] txbuffer = requestCode.getBytes();
         byte[] rxbuffer = new byte[64];
         long diff = 0;
         try {
             socket.setSoTimeout(3000);
             DatagramPacket sendPacket = new DatagramPacket(txbuffer, txbuffer.length,
     hostAddress, serverPort);
             DatagramPacket receivePacket= new DatagramPacket(rxbuffer, rxbuffer.length);
31
              // ACTION
32
             socket.send(sendPacket);
33
             System.out.println("The request code is: "+ requestCode + "\nThe destination port
     is: " + serverPort + "\nMy listening port (clientPort): " + socket.getLocalPort());
             long timeBefore = System.currentTimeMillis();
             System.out.println("My system time, when the request is sent, is: " + timeBefore);
             // LISTEN
             socket.receive(receivePacket);
             long timeAfter = System.currentTimeMillis();
             diff = timeAfter - timeBefore;
```

```
System.out.println("The time required to reveive a packet is: " + diff + "
     milliseconds");
              //System.out.println("The port that opened ithaki to send the request is : " +
43
     receivePacket.getPort() + " and the address of ithaki is: " + receivePacket.getAddress());
              String message = new String(receivePacket.getData(), StandardCharsets.US_ASCII);
     // convert binary to ASCI
              System.out.println("Ithaki responded with: " + message);
45
46
          catch (Exception x) {
              // x.printStackTrace(); // a more detailed diagnostic call
              System.out.println(x);
              System.out.println("Something went wrong about Echo application mode");
          return diff;
     }
53
```

#### 3.2 Media.java

```
package applications;
import java.net.DatagramSocket;
4 import java.net.DatagramPacket;
5 import java.net.InetAddress;
6 import java.io.ByteArrayOutputStream;
7 import java.io.ByteArrayInputStream;
8 import java.io.File;
9 import java.io.FileWriter;
import java.io.FileOutputStream;
import java.io.IOException;
import java.awt.Desktop;
import java.util.Arrays;
import javax.sound.sampled.*;
public class Media {
      private static String pathFileImage = "/home/tkatz/repos/ece-networks2/media/image/sandbox
18
     /ithaki_image.jpg";
      private static String pathFileSound = "/home/tkatz/repos/ece-networks2/media/music/sandbox
19
     /track.wav";
      public static void image(DatagramSocket socket, InetAddress hostAddress, int serverPort,
     String requestCode) throws IOException {
          //if (numImage != (Integer.parseInt(args[1])-1)){
23
               continue; // readjust the camera as many time is requested via the command line
     arguement. Print only the result, the last request
          //}
          byte[] txbufferImage = requestCode.getBytes();
27
          byte[] rxbufferImage = new byte[1024];
28
          int countPackets = 0;
          long timeBefore = System.currentTimeMillis();
          long timeBeforePerPacket = System.currentTimeMillis();
          //System.out.println("My system time, when the request is sent, is: " + timeBefore);
          System.out.println("The request code is " + requestCode);
34
          DatagramPacket sendPacket = new DatagramPacket(txbufferImage, txbufferImage.length,
35
     hostAddress, serverPort);
          DatagramPacket receivePacket= new DatagramPacket(rxbufferImage, rxbufferImage.length);
```

```
// TX
          System.out.println("I am sleeping... Camera needs time to readjust");
          try {
40
              socket.send(sendPacket);
41
              Thread.sleep(5000); // sleep in order for the camera to readjust
          catch (Exception x) {
              // x.printStackTrace(); // a more detailed diagnostic call
              System.out.println(x);
              System.out.println("Image application TX failed");
48
          // RX
          ByteArrayOutputStream bufferImage = new ByteArrayOutputStream();
51
52 outerloop:
          try {
53
              socket.setSoTimeout(3000);
              for (;;) {
55
                  socket.receive(receivePacket); // blocking command
56
                  countPackets++;
                  long timeAfterPerPacket = System.currentTimeMillis();
59
                  System.out.println("The time required to reveive a packet is: " + (
60
     timeAfterPerPacket - timeBeforePerPacket)/(float)1000 + " seconds");
                  timeBeforePerPacket = System.currentTimeMillis();
61
62
                  System.out.println("Packet No" + countPackets + ". Length of data: " +
63
     rxbufferImage.length + ". The received bytes in hexadecimal format are:");
                  for (int i = 0; i<rxbufferImage.length; i++) {</pre>
                      System.out.print(String.format("%02X", rxbufferImage[i])); // convert
65
     bytes to hexa string
                      bufferImage.write(rxbufferImage[i]); // dynamic byte allocation
                      if ((String.format("%02X", rxbufferImage[i]).equals("D9")) && (i!=0)) {
68
                           if ((String.format("%02X", rxbufferImage[i-1]).equals("FF"))) {
                               break outerloop; // stop writing when EOF (OxFFD9 delimiter)
                           }
                      }
                  System.out.println();
              }
75
76
          catch (Exception x) {
              // x.printStackTrace(); // a more detailed diagnostic call
              System.out.println(x);
              System.out.println("Image application RX failed");
80
81
          long timeAfter = System.currentTimeMillis(); // get the time when the image is
     received in bytes
83
          // logs for the received byte content
84
          System.out.println("\nComplete byte content of the image file in hexadecimal format:")
          byte[] completeDataImage = bufferImage.toByteArray();
86
          for (byte i : completeDataImage) {
87
              System.out.print(String.format("%02X", i)); // print hexadecimal the content of
88
     the byte array
          }
          System.out.println("\n\nTotal number of packages: " + (countPackets));
          System.out.println("How many Kbytes is the image? " + completeDataImage.length/(float)
```

```
1000);
    // save image to a file
    File imageFile = new File(pathFileImage);
    FileOutputStream fos = null;
    try {
        fos = new FileOutputStream(imageFile);
        fos.write(completeDataImage);
        System.out.println("File has been written successfully");
    catch (Exception x) {
        // x.printStackTrace(); //
        System.out.println("Image application error when writing the file:");
    }
    fos.close(); // close the OutputStream
    // what time is o'clock?
    System.out.println("Total amount of time to receive a frame: " + (timeAfter -
timeBefore)/(float)1000 + " seconds");
    timeAfter = System.currentTimeMillis(); // get the time when the file is ready
    System.out.println("Total amount of time to receive and write a frame in a .jpg file:
" + (timeAfter - timeBefore)/(float)1000 + " seconds");
     // open file image
    Desktop desktop = Desktop.getDesktop();
    if (imageFile.exists()) {
         //desktop.open(imageFile);
    }
}
public static void audio(DatagramSocket socket, InetAddress hostAddress, int serverPort,
String requestCode) {
    // parsing the requestCode
    // expecting requestCode: AXXXX + ("AQ"" or "") + ("T" or "F") + numAudioPackets
    String encoding = "";
    String type = "F";
    String numAudioPackets = "";
    if (requestCode.length() == 11) {
         encoding = "AQ";
        type = requestCode.substring(7, 8);
        numAudioPackets = requestCode.substring(8, 11);
    }
    else {
        type = requestCode.substring(5, 6);
        numAudioPackets = requestCode.substring(6, 9);
    System.out.println("Requested: Encoding: " + encoding + ". Type: " + type + ". Number
of packets: " + numAudioPackets);
    // TX
    byte[] txbufferSound = ("L02" + requestCode).getBytes();
    DatagramPacket sendPacket = new DatagramPacket(txbufferSound, txbufferSound.length,
hostAddress, serverPort);
    try {
        socket.send(sendPacket);
    }
    catch (Exception x) {
        // x.printStackTrace(); // a more detailed diagnostic call
```

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```
System.out.println(x);
        System.out.println("Audio application TX failed");
    }
    // RX
    byte[] dataSound = new byte[128];
    DatagramPacket receivePacket= new DatagramPacket(dataSound, dataSound.length);
    ByteArrayOutputStream bufferSound = new ByteArrayOutputStream();
    int countPackets = 0;
    int packetsSize = 0;
    long timeBefore = System.currentTimeMillis();
    long timeBeforePerPacket = System.currentTimeMillis();
    // create files
    File diffSamples = new File("logs/" + encoding + type + "diff_samples.txt") ;
    File fileSamples = new File("logs/" + encoding + type + "samples.txt");
    File fileMean = new File("logs/aqdpcm_mean.txt");
    File fileStep = new File("logs/aqdpcm_step.txt");
    FileWriter writerDiffSamples = null;
    FileWriter writerSamples = null;
    FileWriter writerMean = null;
    FileWriter writerStep = null;
    try {
         writerDiffSamples = new FileWriter(diffSamples);
        writerSamples = new FileWriter(fileSamples);
        writerMean = new FileWriter(fileMean);
        writerStep = new FileWriter(fileStep);
    catch (Exception x) {
        System.out.println(x);
        System.out.println("Failed to create a file writer for the DPCM");
    }
    try {
        socket.setSoTimeout(3000);
        for (int 1 = 0; 1 < Integer.parseInt(numAudioPackets); 1++) {</pre>
             timeBeforePerPacket = System.currentTimeMillis();
             socket.receive(receivePacket);
             countPackets++;
             long timeAfterPerPacket = System.currentTimeMillis();
             System.out.println("The time required to reveive a packet is: " + (
timeAfterPerPacket - timeBeforePerPacket)/(float)1000 + " seconds");
             packetsSize += dataSound.length;
            System.out.println("Packet No" + countPackets + ". Length of data: " +
dataSound.length);
             if (encoding.equals("")) {
                 // DPCM
                 bufferSound.write(dpcm(dataSound, writerDiffSamples, writerSamples));
             else if (encoding.equals("AQ")) {
                 // AQ-DPCM
                 bufferSound.write(adpcm(dataSound, writerDiffSamples, writerSamples,
writerMean,
                                   writerStep));
            }
```

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```
else {
                 System.out.println("This is not a valid request code");
            System.out.println();
        }
    }
    catch (Exception x) {
        System.out.println(x);
        System.out.println("Receiving/writing the audio data failed");
    // close files
    try {
        writerSamples.close();
        writerDiffSamples.close();
        writerMean.close();
        writerStep.close();
    catch (Exception x) {
        System.out.println(x);
        System.out.println("Failed to close audio files");
    long timeAfter = System.currentTimeMillis();
    System.out.println("\nComplete byte content of the sound file in hexadecimal format:")
    byte[] completeDataSound = bufferSound.toByteArray();
    for (byte i : completeDataSound) {
        String hexa = String.format("%02X", i); // print hexadecimal the content of the
byte array
        System.out.print(hexa);
    System.out.println("\n\nTotal number of packages: " + (countPackets));
    System.out.println("How many Kbytes is the sound? " + completeDataSound.length/(float)
1000 + "\nHow many Kbytes is the data that was actually sent? " + packetsSize/(float)1000);
    System.out.println("Total amount of time to receive sound data: " + (timeAfter -
timeBefore)/(float)1000 + " seconds");
    boolean isBigEndian = false; // only in 16 bit samples does matter. In AQ-DPCM we use
16 bit encoding
    int encodingBits = 8;
    if (encoding.equals("AQ")) {
        isBigEndian = true;
        encodingBits = 16;
    AudioFormat modulationPCM = new AudioFormat(8000, encodingBits, 1, true, isBigEndian);
    // play sound
    try {
        SourceDataLine outputAudio = AudioSystem.getSourceDataLine(modulationPCM);
        //outputAudio.open(modulationPCM, 3200);
        outputAudio.open(modulationPCM);
        outputAudio.start();
        System.out.println("Getting ready to hear some music?");
        Thread.sleep(2000);
        System.out.print("In 3");
        Thread.sleep(1000);
        System.out.print(", 2");
```

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```
Thread.sleep(1000);
        System.out.println(", 1...");
        Thread.sleep(500);
        System.out.println("Listening...");
        Thread.sleep(500);
        outputAudio.write(completeDataSound, 0, completeDataSound.length);
        outputAudio.stop();
        outputAudio.close();
        System.out.println("\nSound application success!");
    catch (Exception x) {
        System.out.println(x);
        System.out.println("Sound playing failed");
    }
    // save music to file
    try{
        ByteArrayInputStream bufferSoundInput = new ByteArrayInputStream(completeDataSound
);
        AudioInputStream streamSoundInput = new AudioInputStream(bufferSoundInput,
modulationPCM, completeDataSound.length / modulationPCM.getFrameSize());
        AudioSystem.write(streamSoundInput, AudioFileFormat.Type.WAVE, new File(
pathFileSound));
        System.out.println("Sound file creation success");
    catch (Exception x) {
        System.out.println(x);
        System.out.println("Sound file creation failed");
    }
}
private static byte[] dpcm(byte[] dataSound, FileWriter writerDiffSamples,
                            FileWriter writerSamples) {
    ByteArrayOutputStream bufferSound = new ByteArrayOutputStream();
    int init = 0;
    int step = 1; // Trials: for 100 is pure noise, 4 good, 10 bad. I think below 4 you
are good. In general it shouldn't
    for (int i = 0; i < dataSound.length; i++) {</pre>
        String hexa = String.format("%02X", dataSound[i]); // print hexadecimal the
content of the byte array
        System.out.print("Input: decimal: " + dataSound[i] + ", unsigned: " + Byte.
toUnsignedInt(dataSound[i]) + " and the hexa: " + hexa + ", ");
        // get nibbles
        int maskLow = 0x0F;
        int maskHigh = 0xF0;
        int nibbleLow = dataSound[i] & maskLow; // D[i] = x[i] - x[i-1]
        int nibbleHigh = (dataSound[i] \& maskHigh) >> 4; // D[i-1] = x[i-1] - x[i-2]
        // differences
        int diffHigh = (nibbleHigh - 8)*step;
        int diffLow = (nibbleLow - 8)*step;
        // get samples
        int sampleFirst = init + diffHigh;
        int sampleSecond = sampleFirst + diffLow;
```

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```
System.out.print("Masks high and low: " + maskHigh + ", " + maskLow + ". Masks in
312
     hex: " + String.format("%02X", maskHigh) +", " + String.format("%02X", maskLow) + ". Result
      of mask: " + String.format("%02X", nibbleHigh) + ", " + String.format("%02X", nibbleLow) +
      ". Nibbles high and low: " + nibbleHigh + ", " + nibbleLow + ", so the actual differences
     are: " + (nibbleHigh-8) +", " + (nibbleLow-8) + " and samples: " + sampleFirst + ", " +
     sampleSecond);
              init = sampleSecond;
              // check range
              int max8 = (int)(Math.pow(2,7)) - 1;
316
              int min8 = -(int)(Math.pow(2,7));
              int[] samples = {sampleFirst, sampleSecond};
              for (int j=0; j < samples.length; j++) {</pre>
                   if (samples[j]>max8) samples[j] = max8;
                  else if (samples[j] < min8) samples[j] = min8;</pre>
              // write data to files
              try {
                  writerDiffSamples.write(diffHigh + "n" + diffLow + "n");
                  writerSamples.write(samples[0] + "\n" + samples[1] + "\n");
              catch (Exception x) {
                  System.out.println(x);
330
                   System.out.println("Failed to write data to DPCM file");
              // write to buffer
334
              byte[] decodedSound = new byte[2];
              decodedSound[0] = (byte)sampleFirst;
              decodedSound[1] = (byte)sampleSecond;
              System.out.println(". Output: " + String.format("%02X", decodedSound[0]) + String.
338
     format("%02X", decodedSound[1]));
              try {
                  bufferSound.write(decodedSound);
              catch (Exception x) {
343
                  System.out.println(x);
                  System.out.println("Decoding DPCM failed");
              }
          }
          return bufferSound.toByteArray();
      private static byte[] adpcm(byte[] dataSound, FileWriter writerDiffSamples,
                                   FileWriter writerSamples, FileWriter writerMean, FileWriter
     writerStep) {
          // get the header first
          int mean = (Byte.toUnsignedInt(dataSound[1]) << 8 | Byte.toUnsignedInt(dataSound[0]));</pre>
     // be sure to not preserve the byte sign
          int meanSigned = (dataSound[1] << 8 | dataSound[0]); // this is wrong. Not sure though?</pre>
          System.out.println("dataSound[1]: " + String.format("%02X", dataSound[1]) + ",
     dataSound[1] <<8: " + String.format("%02X", (Byte.toUnsignedInt(dataSound[1])) <<8));
          System.out.println("The MSB of mean is " + String.format("%02X", dataSound[1]) + " and
      the LSB of the mean is "+ String.format("%02X", dataSound[0]) + ". The mean is " + mean +
```

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```
" and signed " + meanSigned + " and in hex unsigned: " + String.format("%02X", mean) + "
and signed " + String.format("%02X", meanSigned));
    int step = (Byte.toUnsignedInt(dataSound[3]) << 8 | Byte.toUnsignedInt(dataSound[2]));</pre>
    System.out.println("The MSB of step is " + String.format("%02X", dataSound[3]) + " and
 the LSB of the step is " + String.format("%02X", dataSound[2]) + ". The step is " + step +
 " and in hex: " + String.format("%02X", step));
    try {
        writerMean.write(meanSigned + "\n");
        writerStep.write(step + "\n");
    catch (Exception x) {
        System.out.println(x);
        System.out.println("Failed to write mean and step files for AQ-DPCM");
    ByteArrayOutputStream bufferSound = new ByteArrayOutputStream();
    int init = meanSigned; // in DPCM we don't know the init value, we assume zero. But
here we have data in the header.
    for (int i = 3; i < dataSound.length; i++) {</pre>
        // the sample may be bigger than byte. So you will need 16 bit encoding and store
each int to 2 bytes.
        System.out.print("Input: " + String.format("%02X", dataSound[i]) + ", "); // print
 hexadecimal the content of the byte array
        // get nibbles
        int maskLow = 0x0F;
        int maskHigh = 0xF0;
         int nibbleLow = (dataSound[i] & maskLow); // D[i] = x[i] - x[i-1], should be
unsigned
        int nibbleHigh = (dataSound[i] & maskHigh)>>4; // D[i-1] = x[i-1] - x[i-2], should
 be unsigned
        // differences
        int diffHigh = (nibbleHigh - 8)*step;
        int diffLow = (nibbleLow - 8)*step;
        // get samples (implement recursive formula)
        int sampleFirst = init + diffHigh;
         int sampleSecond = sampleFirst + diffLow;
        System.out.print("Masks high and low: " + maskHigh + ", " + maskLow + ". Masks in
hex: " + String.format("%02X", maskHigh) +", " + String.format("%02X", maskLow) + ". Result
 of mask: " + String.format("%02X", nibbleHigh) + ", " + String.format("%02X", nibbleLow) +
 ". Nibbles high and low: " + nibbleHigh + ", " + nibbleLow + ", so the actual differences
are: " + (nibbleHigh-8)*step +", " + (nibbleLow-8)*step + " and samples: " + sampleFirst +
", " + sampleSecond);
        init = sampleSecond;
        // check range
        int max16 = (int)(Math.pow(2,15)) - 1;
        int min16 = -(int)(Math.pow(2,15));
        int[] samples = {sampleFirst, sampleSecond};
        for (int j=0; j<samples.length; j++) {</pre>
             if (samples[j]>max16) samples[j] = max16;
             else if (samples[j] < min16) samples[j] = min16;</pre>
        System.out.print(". The actual samples due to 16-bit restriction are: " + samples
[0] + " and " + samples[1] + " and in hex format: " + String.format("%02X", samples[0]) + "
 " + String.format("%02X", samples[1]) + ". In short " + (short)samples[0] + ", " + (short
)samples[1] + " and in hex format as a short: " + String.format("%02X", (short)samples[0])
```

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```
+ ", " + String.format("%02X", (short)samples[1]));
405
               // write data to files
406
               try {
407
                   writerDiffSamples.write(diffHigh + "n" + diffLow + "n");
                   writerSamples.write(samples[0] + "\n" + samples[1] + "\n");
409
410
               catch (Exception x) {
411
                   System.out.println(x);
412
                   System.out.println("Failed to write data to AQ-DPCM file");
413
414
415
               // write to buffer
               byte[] decodedSound = new byte[4];
417
               decodedSound[0] = (byte)(samples[0]>>8); // MSB of sample 15-8
418
               decodedSound[1] = (byte)samples[0]; // LSB of sample 7-0
419
               decodedSound[2] = (byte)(samples[1]>>8);
420
421
               decodedSound[3] = (byte)samples[1];
               System.out.println(". Output: First sample " + String.format("%02X", decodedSound
422
      [0]) + String.format("%02X", decodedSound[1]) + " second sample: " + String.format("%02X",
     decodedSound[2]) + String.format("%02X", decodedSound[3]));
               try {
423
                   bufferSound.write(decodedSound);
424
               }
425
426
               catch (Exception x) {
427
                   System.out.println(x);
                   System.out.println("Decoding DPCM failed");
428
               }
          }
431
432
433
          return bufferSound.toByteArray();
434
435 }
```

### 3.3 Obd.java

```
package applications;
import java.io.File;
import java.io.FileWriter;
4 import java.io.BufferedReader;
5 import java.io.InputStream;
6 import java.io.InputStreamReader;
7 import java.io.OutputStream;
8 import java.net.DatagramSocket;
9 import java.net.DatagramPacket;
import java.net.Socket;
import java.net.InetAddress;
import java.nio.charset.StandardCharsets;
14 public class Obd {
      private static String[] header = {"01 1F", "01 0F", "01 11", "01 0C", "01 0D", "01 05"};
18
      public static void udpTelemetry(DatagramSocket socket, InetAddress hostAddress, int
     serverPort, String requestCode) {
20
          byte[] rxbuffer = new byte[16];
21
          DatagramPacket receivePacket = new DatagramPacket(rxbuffer, rxbuffer.length);
```

```
for (int i = 0; i < header.length; i++) {</pre>
        String completeCode = (requestCode + "OBD=" + header[i]);
        byte[] txbuffer = completeCode.getBytes();
        DatagramPacket sendPacket = new DatagramPacket(txbuffer, txbuffer.length,
hostAddress, serverPort);
        System.out.println("Complete request: " + completeCode);
        try {
             socket.send(sendPacket);
        catch (Exception x) {
             // x.printStackTrace(); // a more detailed diagnostic call
            System.out.println(x);
             System.out.println("OBD vehicle application TX failed");
        long timeBefore = System.currentTimeMillis();
        // RX
        try{
             socket.setSoTimeout(3000);
             socket.receive(receivePacket);
             String message = new String(rxbuffer, StandardCharsets.US_ASCII);
             System.out.println("Ithaki responded via UDP with: " + message);
             System.out.println("Ithaki UDP time response: " + (System.currentTimeMillis()-
timeBefore)/(float)1000 + " seconds");
             int[] values = parser(message);
             formula(values[0], values[1], header[i]);
        }
        catch (Exception x) {
            System.out.println(x);
             System.out.println("RX UDP vehicle failed");
        }
    }
}
public static float tcpTelemetry(Socket socket, FileWriter writerVehicle) {
    float engineTime = 0;
    try {
        InputStream in = socket.getInputStream();
        OutputStream out = socket.getOutputStream();
        BufferedReader bf = new BufferedReader(new InputStreamReader(in)); // wrapper on
top of the wrapper as java docs recommends
        for (int i = 0; i < header.length; i++) {</pre>
            out.write((header[i] + "\r").getBytes());
             //out.flush();
             long timeBefore = System.currentTimeMillis();
             System.out.println("Created TCP socket and set output stream... Waiting for
response");
             System.out.println("Header: " + header[i]);
             String data = bf.readLine();
             System.out.println("Ithaki responded via TCP with: " + data);
             System.out.println("Ithaki TCP time response: " + (System.currentTimeMillis()-
timeBefore)/(float)1000 + " seconds");
```

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```
int[] values = parser(data);
             float value = formula(values[0], values[1], header[i]);
             writerVehicle.write(value + " ");
             if (header[i] == "01 1F") engineTime = value;
         writerVehicle.write("\n");
    }
    catch (Exception x) {
         System.out.println(x);
         System.out.println("Oops... Vehicle OBD TCP failed");
    return engineTime;
private static float formula(int first, int second, String header) {
    float value = 0;
    switch (header) {
         case "01 1F":
             int engineRunTime = first*256 + second;
             System.out.println("Engine run time: " + engineRunTime);
             value = engineRunTime;
             break;
        case "01 OF":
             int intakeAirTemp = first - 40;
             System.out.println("Intake Air Temperature: " + intakeAirTemp);
             value = intakeAirTemp;
             break;
        case "01 11":
             float throttlePos = (first*100)/(float)255;
             System.out.println("Throttle position: " + throttlePos);
             value = throttlePos;
             break;
         case "01 0C":
             float engineRpm = ((first*256) + second)/(float)4;
             System.out.println("Engine RPM: " + engineRpm);
             value = engineRpm;
             break;
         case "01 0D":
             int speed = first;
             System.out.println("Vehicle speed: " + speed);
             value = speed;
             break;
         case "01 05":
             int coolantTemp = first -40;
             System.out.println("Coolant Temperature: " + coolantTemp);
             value = coolantTemp;
             break;
         default:
             System.out.println("Something went wrong calculating formual for vehicle stats
");
```

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```
138
           }
           System.out.println();
140
           return value;
141
142
143
144
      private static int[] parser(String data) {
           String byte1 = data.substring(6,8);
145
           // how to convert hexadecimal string to int?
146
           int first = Integer.parseInt(byte1, 16);
147
           System.out.print("Parsing the data: 1st byte: " + byte1 + " and as an integer: " +
148
      first);
           String byte2 = "";
           int second = 0;
150
           if (data.length()>8) {
               byte2 = data.substring(9,11);
               second = Integer.parseInt(byte2, 16);
153
               System.out.print(", 2nd byte: " + byte2 + " and as an integer: " + second);
154
           }
           System.out.println();
156
           int[] temp = {first, second};
158
159
           return temp;
160
161 }
```

#### 3.4 Copter.java

```
package applications;
import java.io.FileWriter;
4 import java.io.BufferedReader;
5 import java.io.ByteArrayOutputStream;
6 import java.io.InputStream;
7 import java.io.InputStreamReader;
8 import java.io.OutputStream;
9 import java.net.DatagramSocket;
import java.net.DatagramPacket;
import java.net.Socket;
import java.net.InetAddress;
import java.nio.charset.StandardCharsets;
import java.io.ByteArrayOutputStream;
public class Copter {
      public static String udpTelemetry(DatagramSocket socket, InetAddress hostAddress, int
     serverPort, FileWriter writerCopter) {
          // TX
18
          // open ithakicopter.jar
19
21
          //RX only
22
          byte[] rxbuffer = new byte[128];
          DatagramPacket receivePacket = new DatagramPacket(rxbuffer, rxbuffer.length);
25
          long timeBefore = System.currentTimeMillis();
26
          String telemetry = new String();
27
          try{
              socket.setSoTimeout(3000);
              socket.receive(receivePacket);
30
              telemetry = new String(rxbuffer, StandardCharsets.US_ASCII);
31
```

```
//System.out.print("Time repsonse: " + (System.currentTimeMillis() - timeBefore)/(
float)1000);
        System.out.println("Received data via UDP: " + telemetry);
        String[] tokensMotor = telemetry.split("LMOTOR=");
        String[] tokensAltitude = telemetry.split("ALTITUDE=");
        String[] tokensTemp = telemetry.split("TEMPERATURE=");
        String[] tokensPress = telemetry.split("PRESSURE=");
        writerCopter.write(tokensMotor[1].substring(0, 3) + " ");
        writerCopter.write(tokensAltitude[1].substring(0, 3) + " ");
        writerCopter.write(tokensTemp[1].substring(1, 6) + " ");
        writerCopter.write(tokensPress[1].substring(0, 7) + "\n");
    catch (Exception x) {
        System.out.println(x);
        System.out.println("RX UDP ithakicopter failed");
    return telemetry;
}
public static String tcpTelemetry(InetAddress hostAddress, int target) {
    String telemetry = "";
    Socket socket = new Socket();
         socket = new Socket(hostAddress, 38048);
        InputStream in = socket.getInputStream();
        OutputStream out= socket.getOutputStream();
        BufferedReader bf = new BufferedReader(new InputStreamReader(in)); // wrapper on
top of the wrapper as java docs recommends
        ByteArrayOutputStream bos = new ByteArrayOutputStream();
        String command = "AUTO FLIGHTLEVEL=" + target + " LMOTOR=" + target + " RMOTOR=" +
 target + " PILOT \r\n";
        //System.out.print("Request: " + command);
        out.write(command.getBytes());
        out.flush();
        //in.skipNBytes(427);
        for (int i = 0; i < 14; i++) {</pre>
             bos.write((bf.readLine() + "\n").getBytes());
        String data = new String(bos.toByteArray(), StandardCharsets.US_ASCII);
        //System.out.println("Received data via TCP: " + data);
        String[] tokens = data.split("\n");
        // take only the useful data and skip the info ithaki sent
        telemetry = tokens[13];
    }
    catch (Exception x) {
        System.out.println(x);
        System.out.println("Oops... Ithakicopter TCP failed");
    try {
    socket.close();
    }
    catch (Exception x) {
        System.out.println(x);
        System.out.println("Failed to close socket for ithakicopter TCP");
```

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```
}
90
91
92
93
       * tcpTelemetry function for the TX and udpTelemetry for RX. The way that these two
     functions are implemented force the autopilot
       * to be used with a combination of these two. We want to send a command only if it is
95
     needed and we want to listen all the time
       * to get feedback.
96
97
98
      public static void autopilot(DatagramSocket listen, InetAddress hostAddress, int
     serverPort, Socket send, int lowerBound, int higherBound) {
100
          lowerBound = Math.min(lowerBound, higherBound);
101
102
          higherBound = Math.max(lowerBound, higherBound);
103
           int target = (lowerBound + higherBound)/2;
104
          int motor = -1;
105
107
          try {
          System.out.println("AUTOPILOT: ON");
108
          System.out.println("You need to open ithakicopter.jar. Press ENTER to continue...");
109
          System.in.read();
110
          System.out.println("Press Control-C to exit...");
          Thread.sleep(1000);
          for (;;) {
114
               if ((motor<(lowerBound)) || (motor>(higherBound))) {
                   System.out.println("Send packet. Readjust...");
115
                   tcpTelemetry(hostAddress, target);
116
118
                   String telemetry = Copter.udpTelemetry(listen, hostAddress, serverPort, null);
119
                   String[] tokens = telemetry.split("LMOTOR=");
120
121
                   motor = Integer.parseInt(tokens[1].substring(0,3)); // get motor values
122
                   System.out.println("Parsed motor values: " + motor);
          }
124
          }
           catch (Exception x) {
126
               System.out.println(x);
               System.out.println("AUTOPILOT failed");
128
          }
      }
130
132 }
```

### 4 Plots

return telemetry;

```
from scipy.stats import norm
import matplotlib.pyplot as plt
import matplotlib.mlab as mlab
import pandas as pd
from numpy import genfromtxt
import numpy as np

# data = pd.read_csv('../logs/echo_samples_delay.csv', sep=',', header=None)
# data.plot(kind='bar')
```

```
# plt.ylable('frequency')
# plt.xlabel('Number of packets')
# plt.title('Histogram response time')
# plt.show()
#plt.hist(rtt,histtype = 'bar', bins='auto', density=1, alpha=0.7)
# print("Length of the array is: " + str(len(rtt)))
20 # Response time diagram
21 x = genfromtxt('../logs/session2/echo_samples_delay.txt', delimiter=',')
x = genfromtxt('../logs/session2/echo_samples_no_delay.txt', delimiter=',')
23 x = genfromtxt('../logs/session2/echo_throughput_delay.txt', delimiter=',')
24 x = genfromtxt('../logs/session2/echo_throughput_no_delay.txt', delimiter=',')
zs x = genfromtxt('../logs/session1/AQFsamples.txt')
x = genfromtxt('../logs/session2/Fsamples.txt')
27 x = genfromtxt('../logs/session2/Tsamples.txt')
28 x = genfromtxt('../logs/session2/second_clip/aqdpcm_mean.txt')
29 x = genfromtxt('../logs/session2/second_clip/aqdpcm_step.txt')
x = genfromtxt('../logs/second_clip/aqdpcm_step.txt')
plt.subplot(2,1,1)
plt.plot(x, 'm')
plt.xlabel('Number of samples', fontsize=12)
  plt.ylabel('Amplitude', fontsize=12)
  plt.grid(True)
plt.subplot(2,1,2)
plt.xlabel('Number of samples', fontsize=12)
plt.ylabel('Amplitude', fontsize=12)
40 plt.grid(True)
plt.plot(x, 'm')
42 plt.xlim(100, 200)
  plt.show()
46 #Retransmission timeout plot
47 data = genfromtxt('../logs/session2/rto.txt', delimiter=' ')
48 rtt = data[1:,0]
49 srtt = data[1:,1]
50 rttd = data[1:,2]
rto = data[1:,3]
plt.plot(rtt, label = "RTT")
plt.plot(srtt, label = "SRTT")
plt.plot(rttd, label = "RTTd")
55 plt.plot(rto, label = "RTO")
56 plt.xlabel('Number of packets', fontsize=12)
57 plt.ylabel("Time response", fontsize=12)
58 plt.legend()
59 plt.show()
61 # Copter
62 data = genfromtxt('../logs/session2/copter_2nd_run/copter_info.txt', delimiter=' ')
63 rtt = data[1:,0]
64 srtt = data[1:,1]
65 rttd = data[1:,2]
66 rto = data[1:,3]
plt.plot(rtt, label = "MOTOR")
68 plt.plot(srtt, label = "ALTITUDE")
69 plt.plot(rttd, label = "TEMPERATURE")
70 plt.plot(rto, label = "PRESSURE")
```

```
71 plt.xlabel('Number of packets', fontsize=12, labelpad=10)
72 plt.ylabel("Data", fontsize=12, labelpad=10)
73 plt.legend()
74 plt.grid(True);
75 plt.yticks(np.arange(0, 1200, 50))
76 plt.show()
78 #Vehicle
79 data = genfromtxt('../logs/car_telemetry.txt', delimiter=' ')
80 rtt = data[0:,0]
81 srtt = data[0:,1]
82 rttd = data[0:,2]
83 rto = data[0:,3]
s = data[0:, 4]
85 t = data[0:, 5]
86 plt.subplot(211)
87 plt.plot(rtt, label = "Engine run time")
88 plt.plot(rto, label = "Engine RPM")
89 plt.xlabel('Number of packets', fontsize=12, labelpad=10)
90 plt.ylabel("Data", fontsize=12, labelpad=10)
plt.legend()
92 plt.grid(True);
93 plt.subplot(212)
94 plt.plot(srtt, label = "Intake air temperature")
95 plt.plot(rttd, label = "Throttle position")
96 plt.plot(s, label = "Vehicle speed")
97 plt.plot(t, label = "Coolant temperature")
98 plt.xlabel('Number of packets', fontsize=12, labelpad=10)
99 plt.ylabel("Data", fontsize=12, labelpad=10)
plt.legend()
plt.grid(True);
#plt.yticks(np.arange(0, 2500, 25))
plt.show()
```