



T. Höllt^{♦♣}, M. Hadwiger[♣], O. Knio[♣], I. Hoteit[♣]

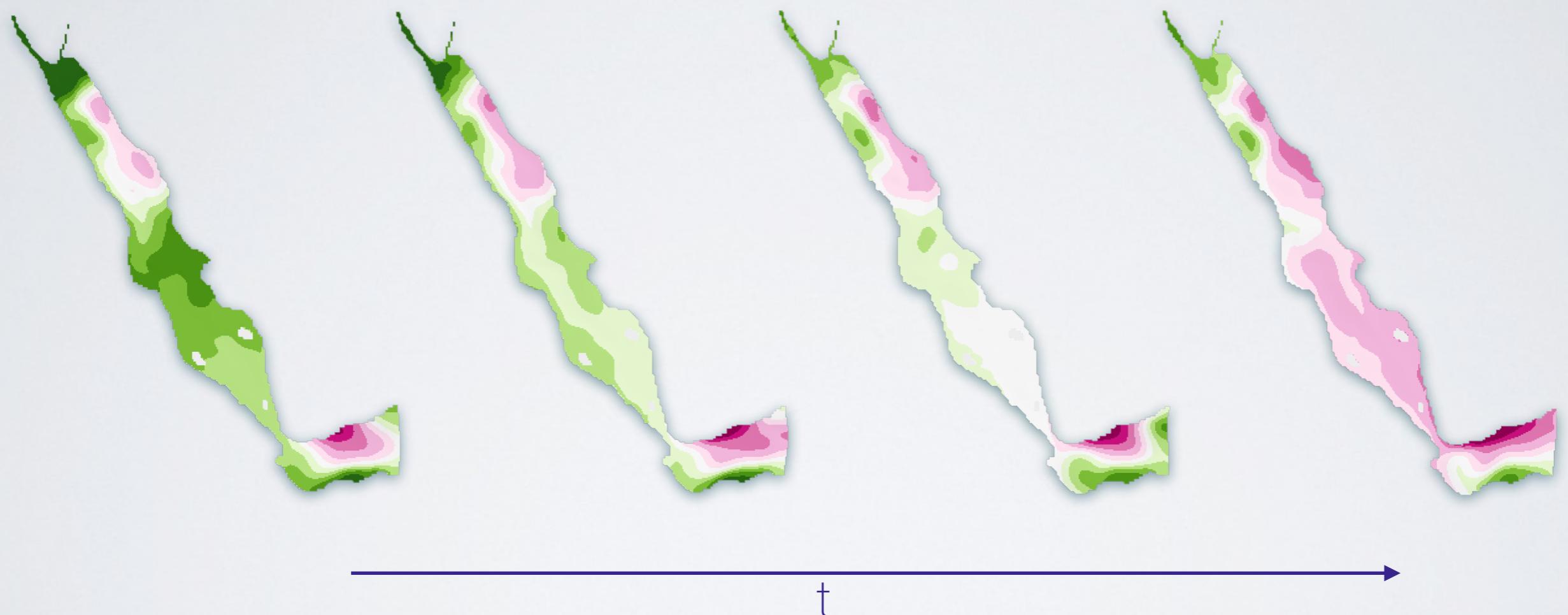
[♣] King Abdullah University of Science and Technology

[♦] Computer Graphics & Visualization, TU Delft

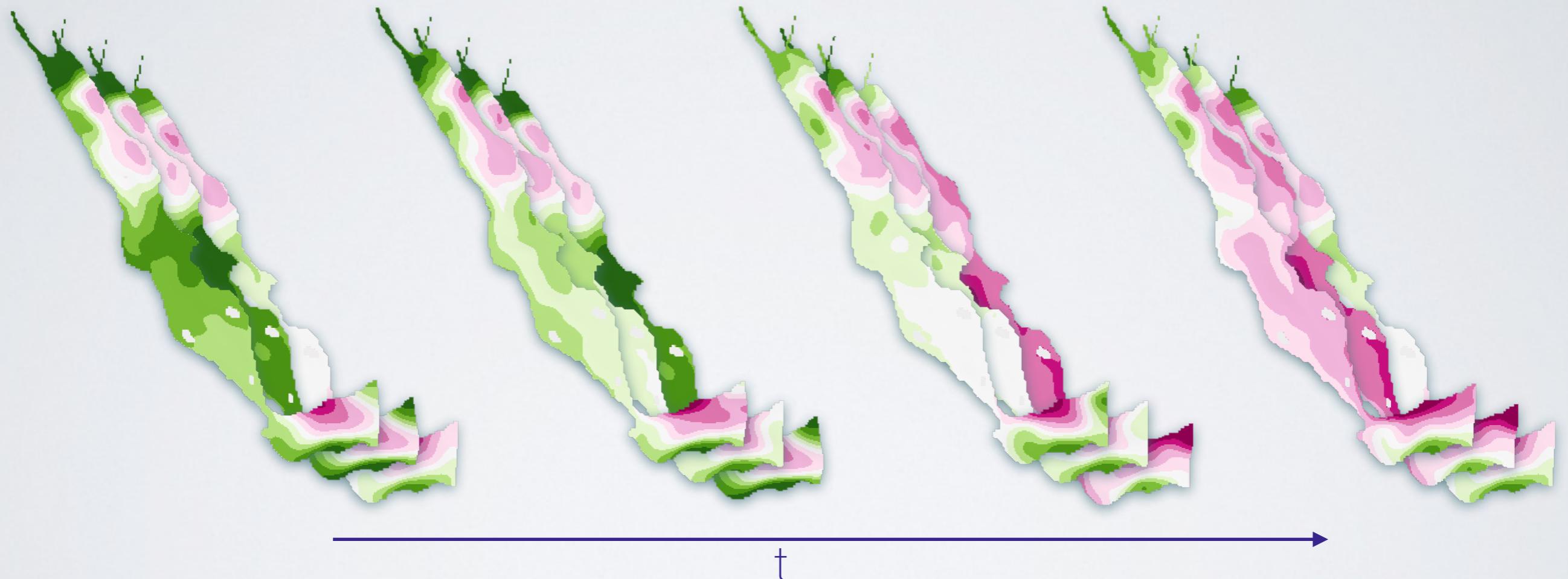
Probability Maps for the Visualization
of Assimilation Ensemble Flow Data



Motivation



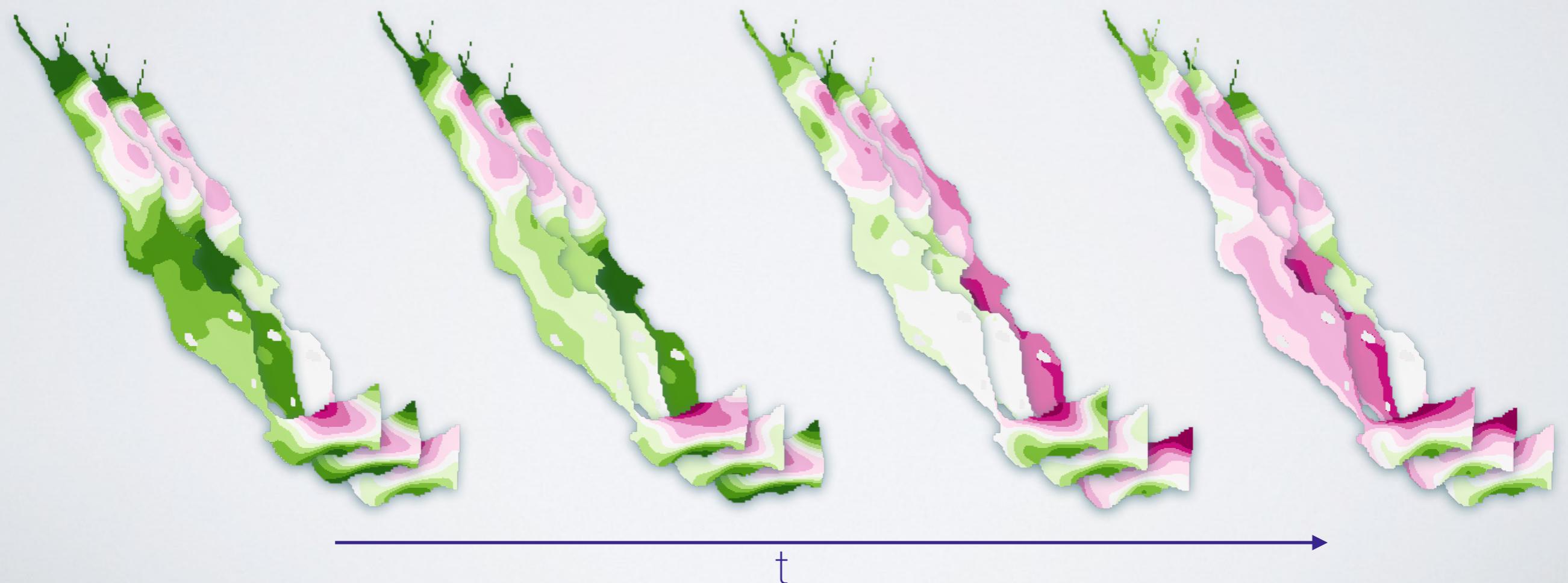
Motivation



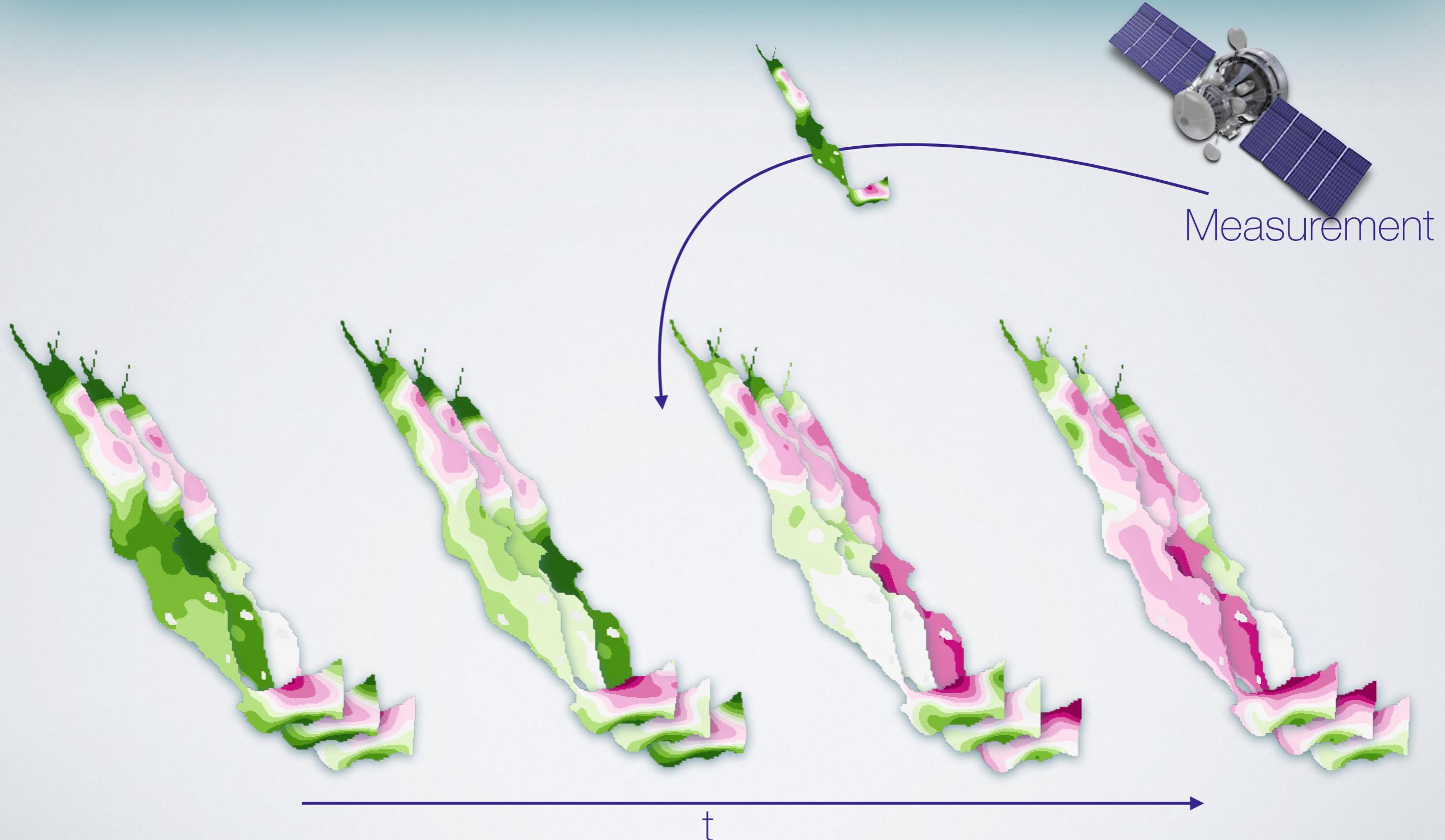
Ensemble Simulation

- Uncertainty in model + model parameters
- Uncertainty in boundary conditions
 - measurement errors, low resolution...
- Random sampling of uncertainty space
 - tens to hundreds of samples

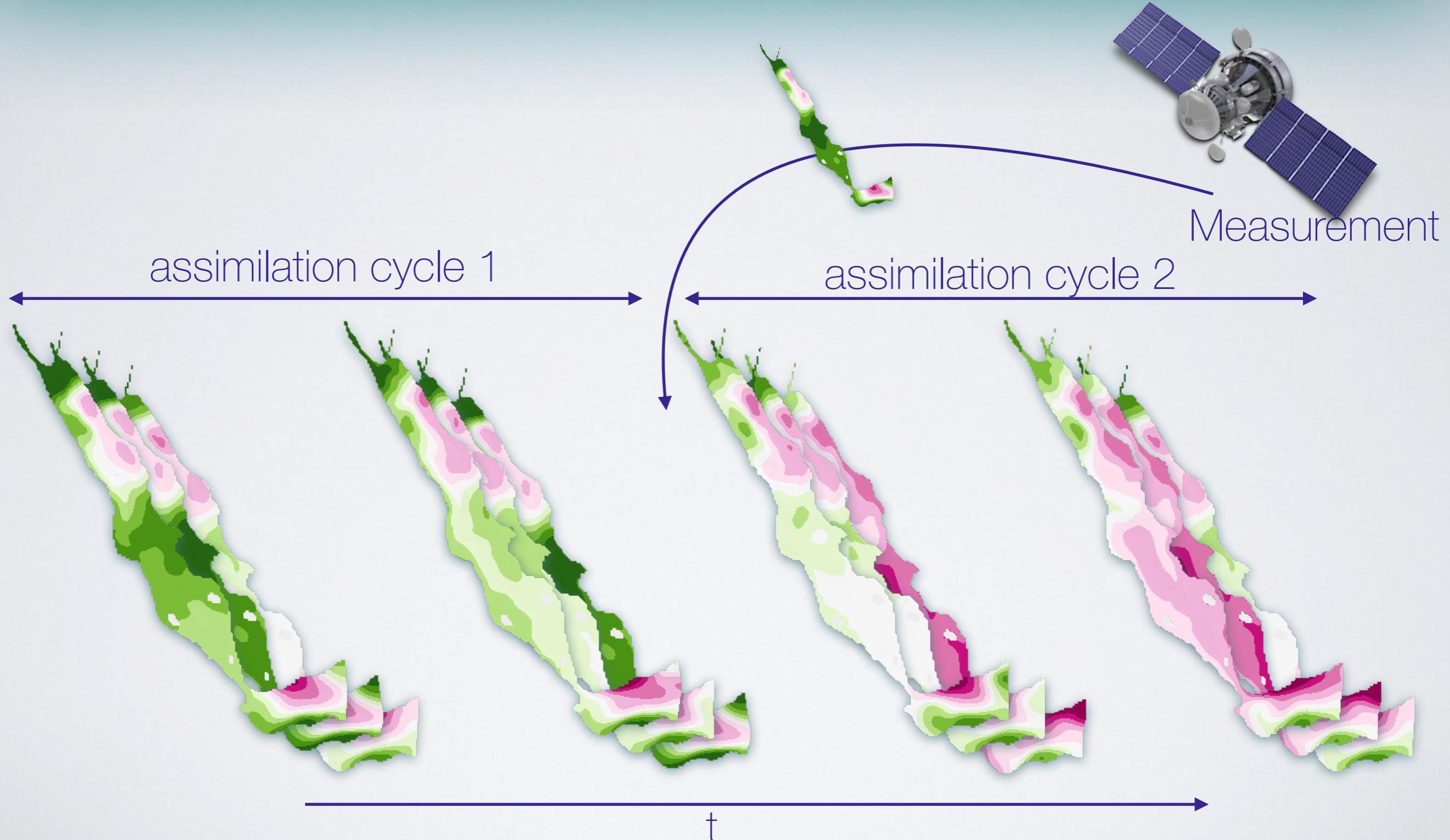
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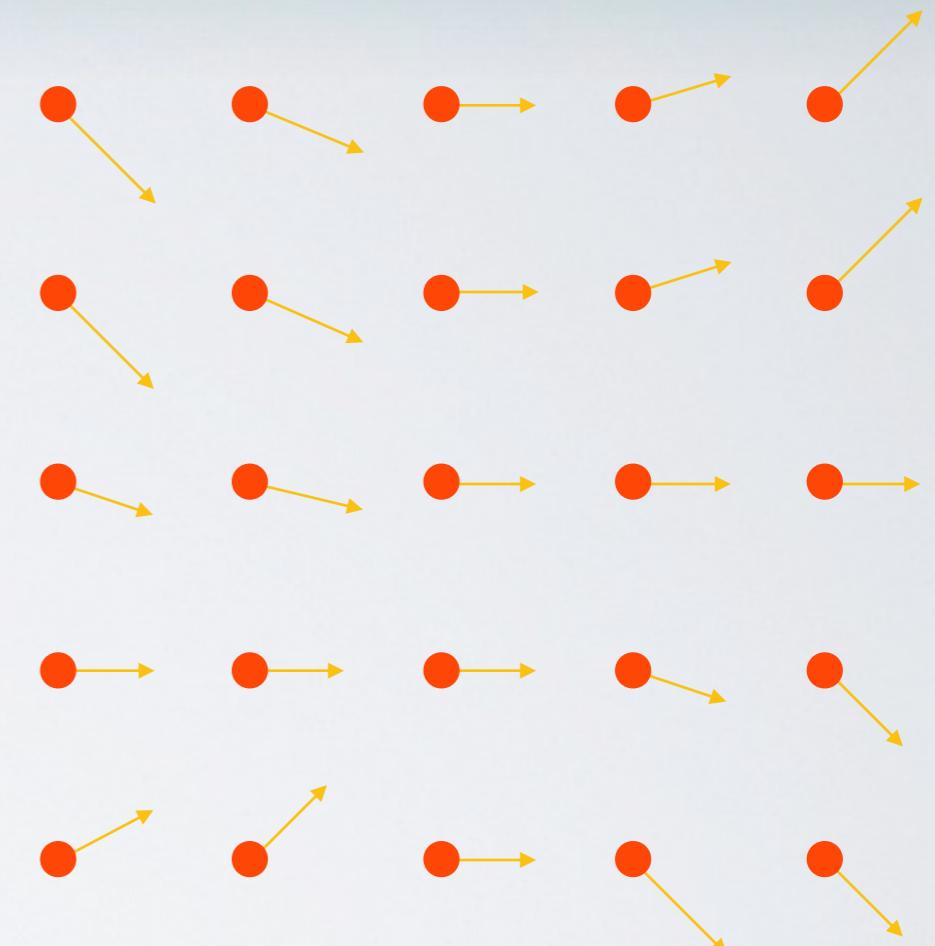


Assimilation

- Simulation steered by measured data
 - not all simulated data is also measured
- Ensemble resampled after assimilation
 - unclear correspondences between cycles
 - hard to track behavior over time
 - follow all possible combinations?

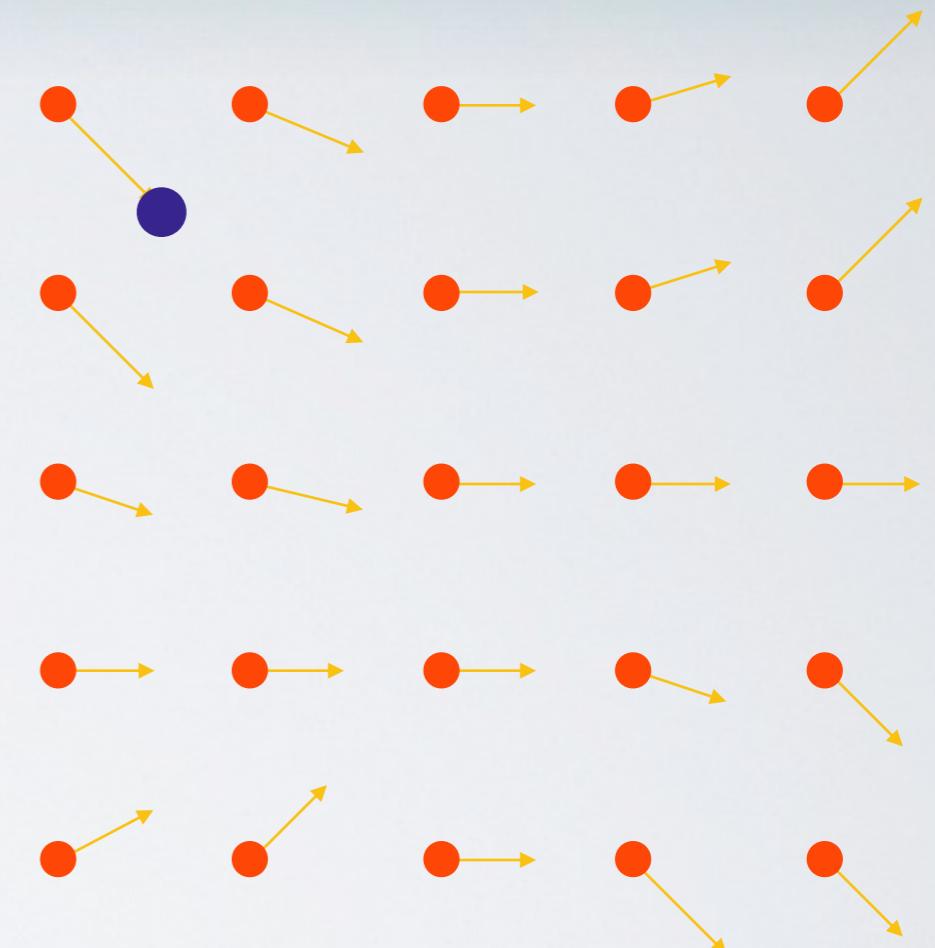
Pathline Tracing

- Input
 - regular sampled domain
 - flow direction + magnitude



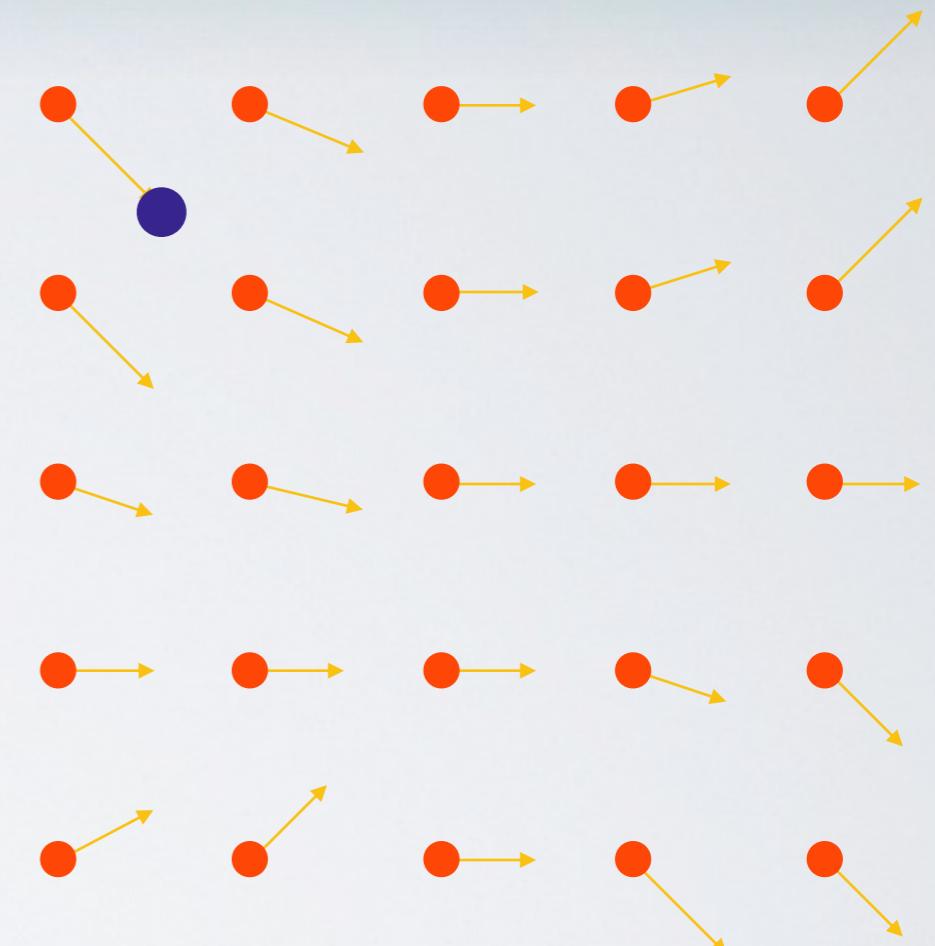
Pathline Tracing

- Input
 - regular sampled domain
 - flow direction + magnitude
 - inject particle



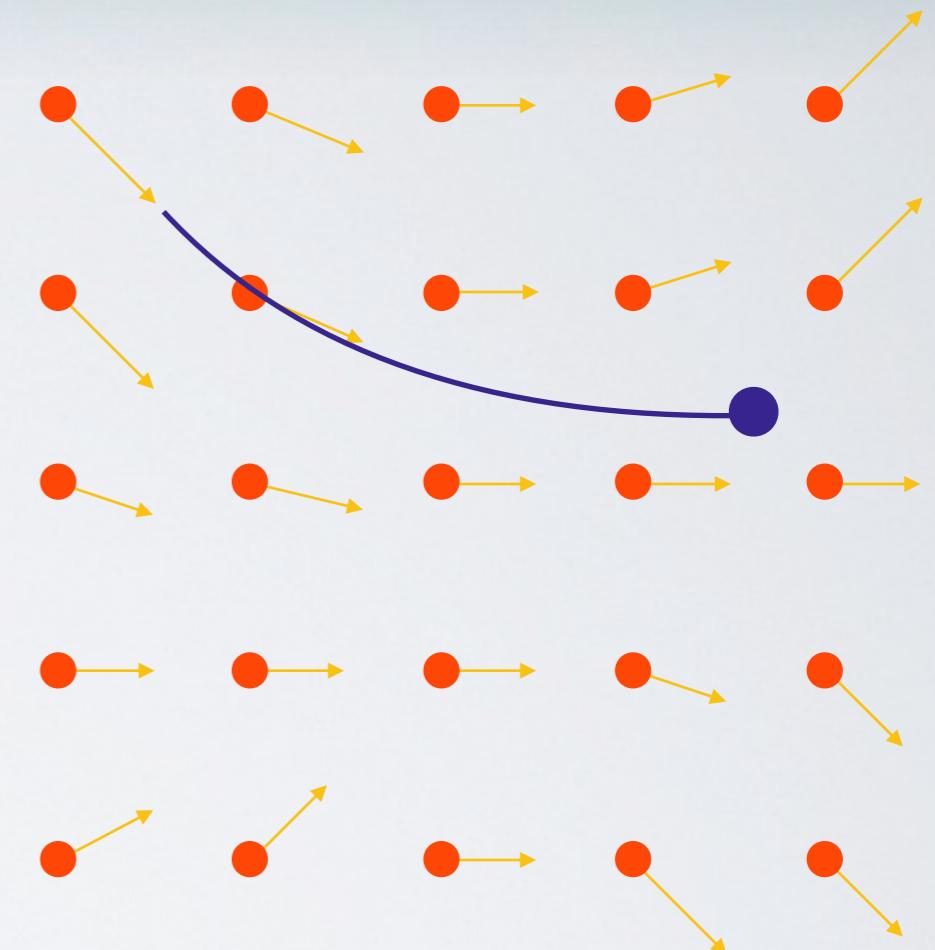
Pathline Tracing

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- Integrate path



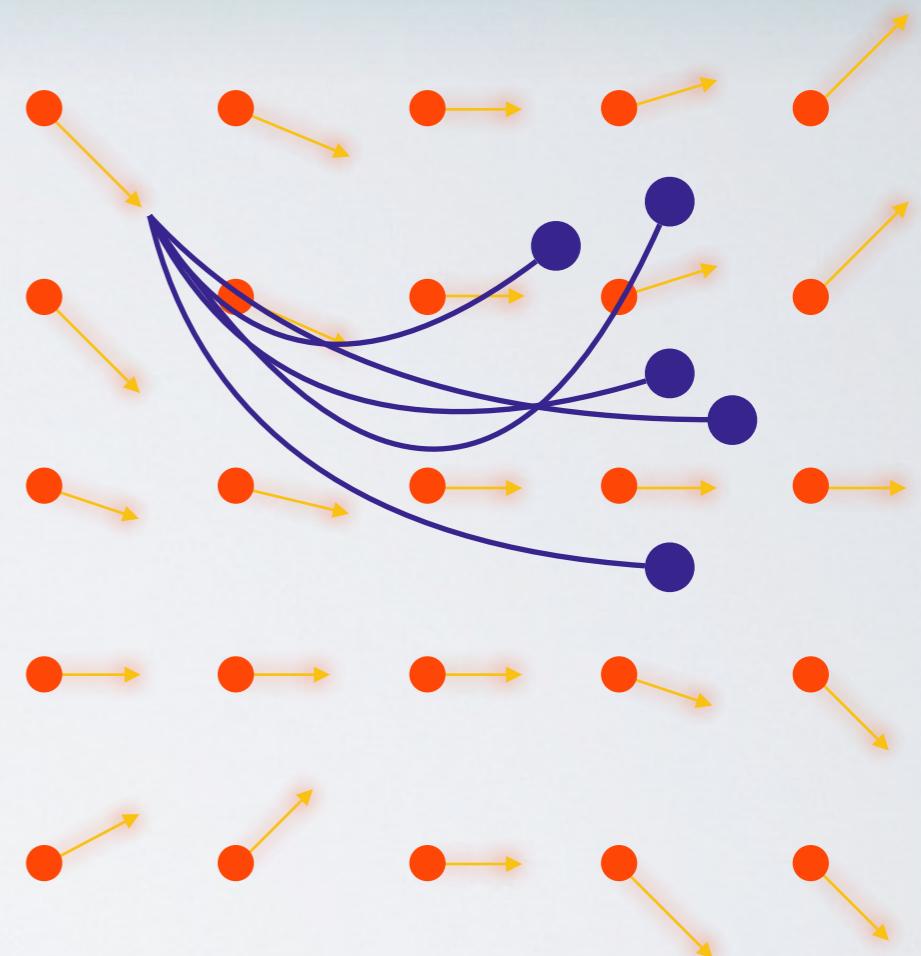
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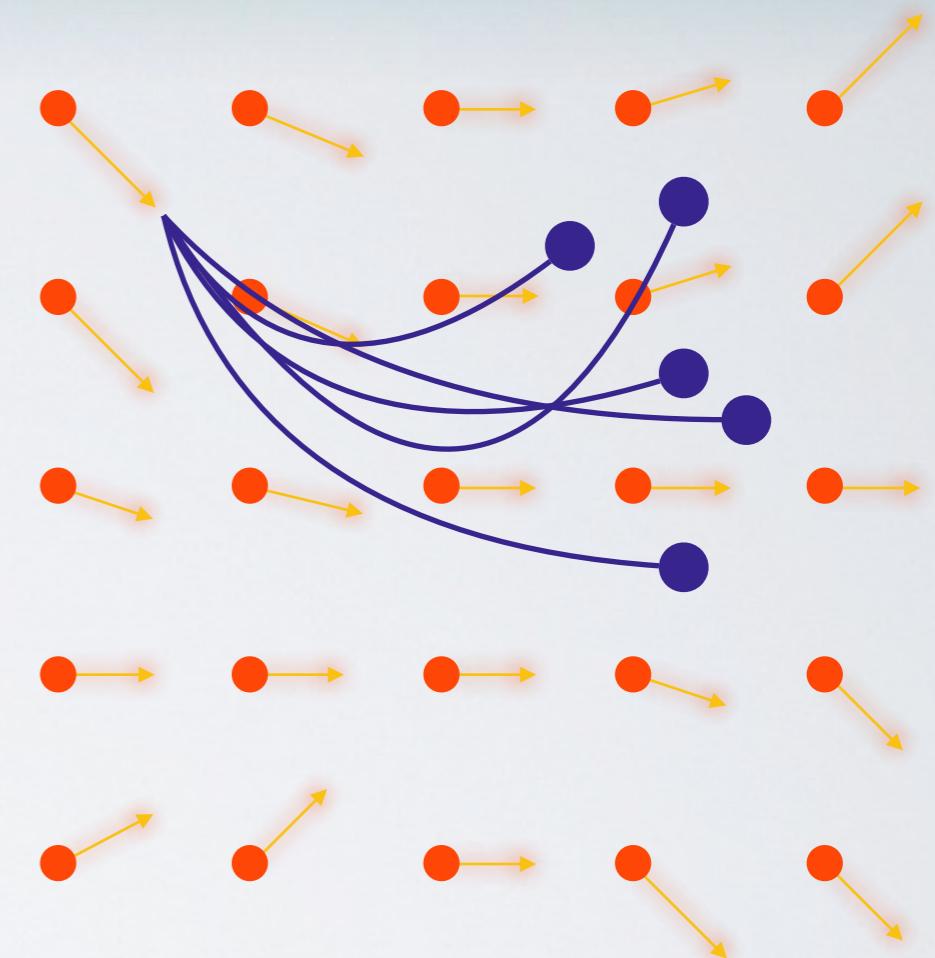
Ensemble Tracing

- Multivalued vectors
- Trace multiple “sub-particles”
(1 per member)



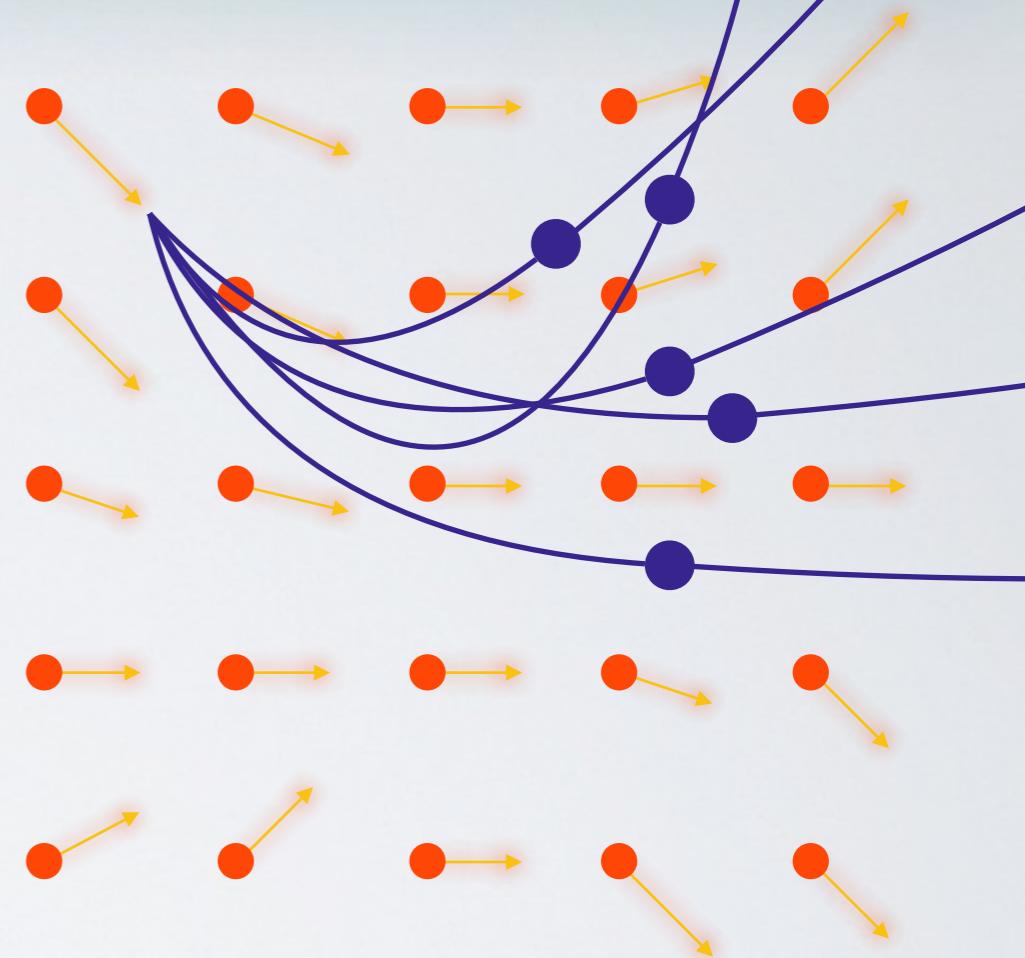
Ensemble Tracing

- Multivalued vectors
- Trace multiple “sub-particles”
(1 per member)
- Well defined temporal
correspondences
 - ⇒ 1 trace/member for
complete time series



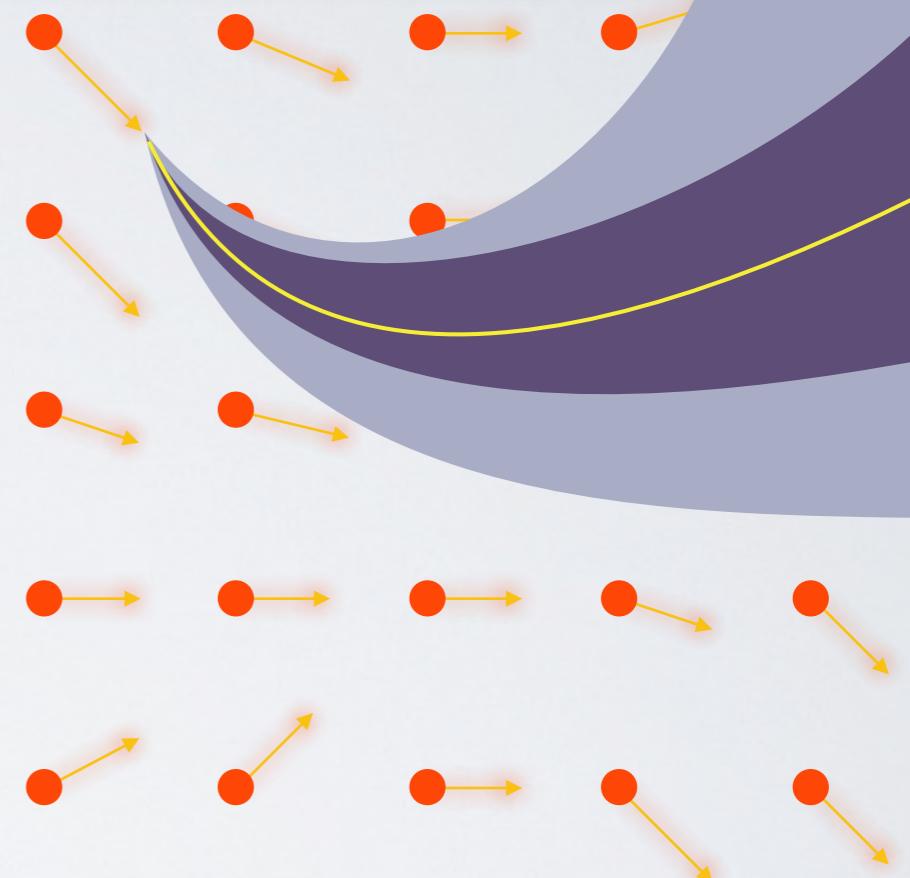
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Ensemble Tracing

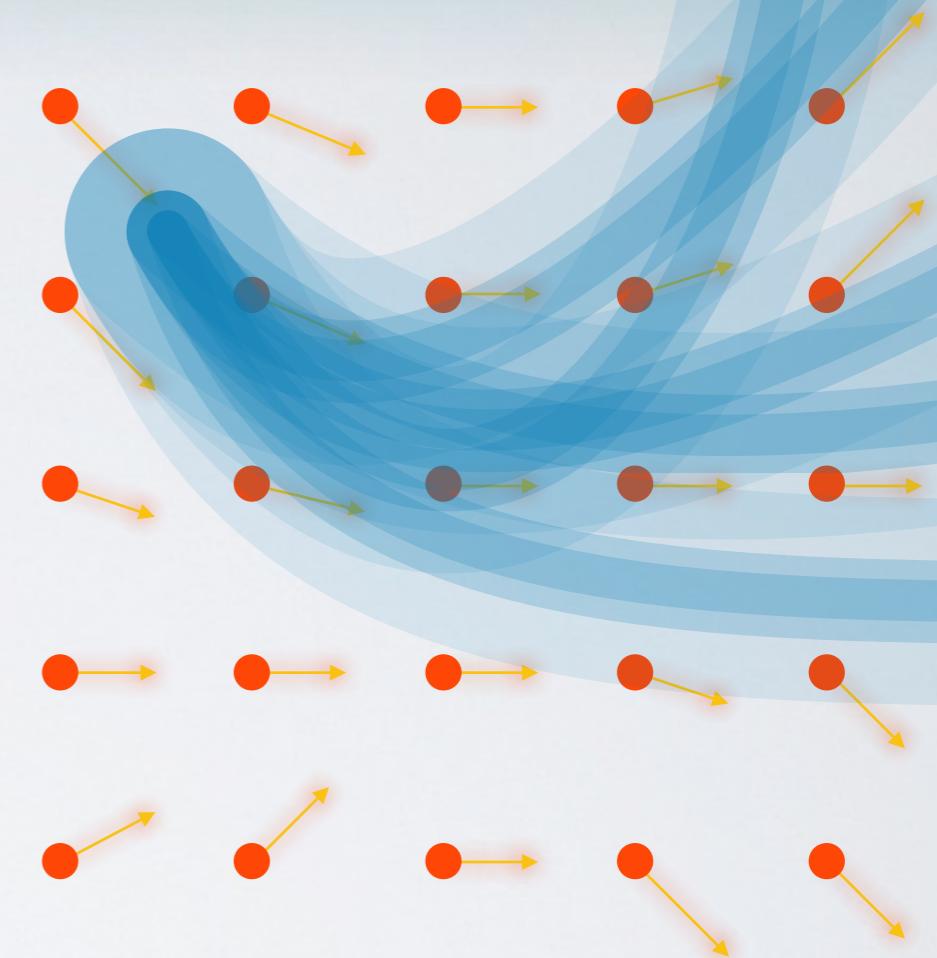
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 - one “sub-particle”/ member
- Mirzargar et al: Curve Boxplot^[1]



[1] Mirzargar et al, *Curve Boxplot: Generalization of Boxplot for Ensembles of Curves*, IEEE TVCG 20(12), 2014

Ensemble Tracing

- Trace multiple “sub-particles”
- Well defined correspondences
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- Mirzargar et al: Curve Boxplot^[1]
- Lampe & Hauser: Curve Density Estimate^[2]

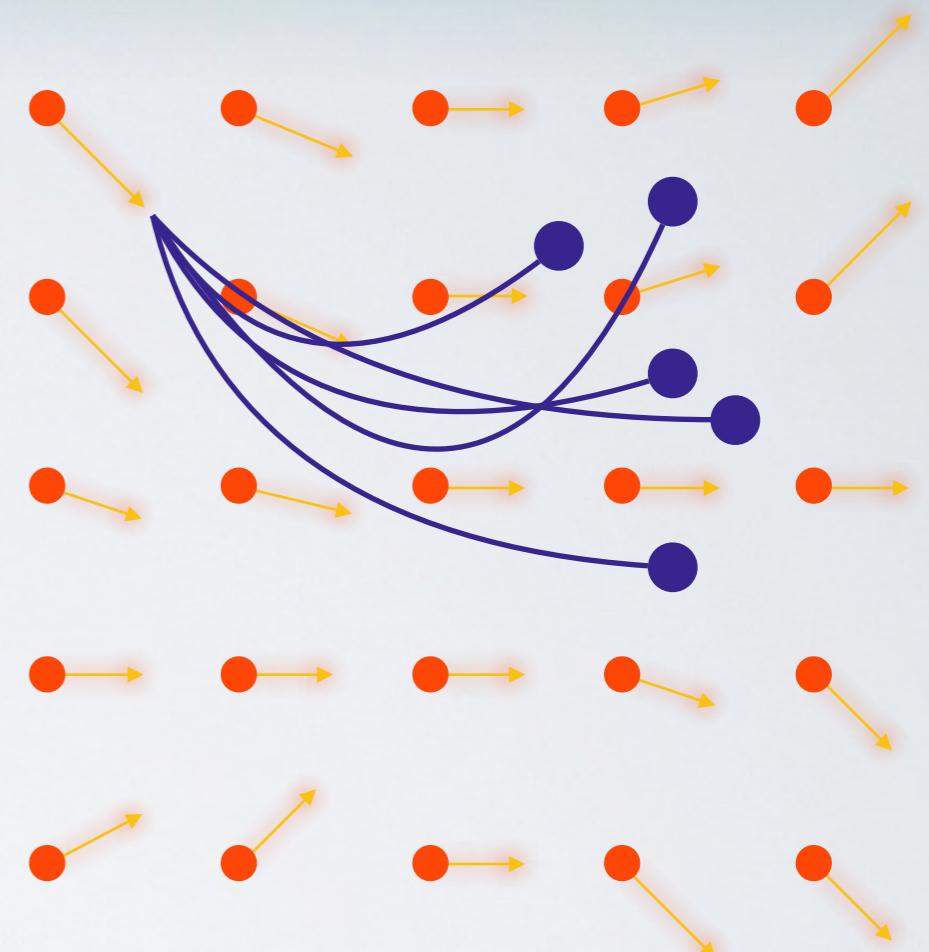


[1] Mirzargar et al, *Curve Boxplot: Generalization of Boxplot for Ensembles of Curves*, IEEE TVCG 20(12), 2014

[2] Lampe & Hauser, *Curve Density Estimate*, CGF 30(3), 2011

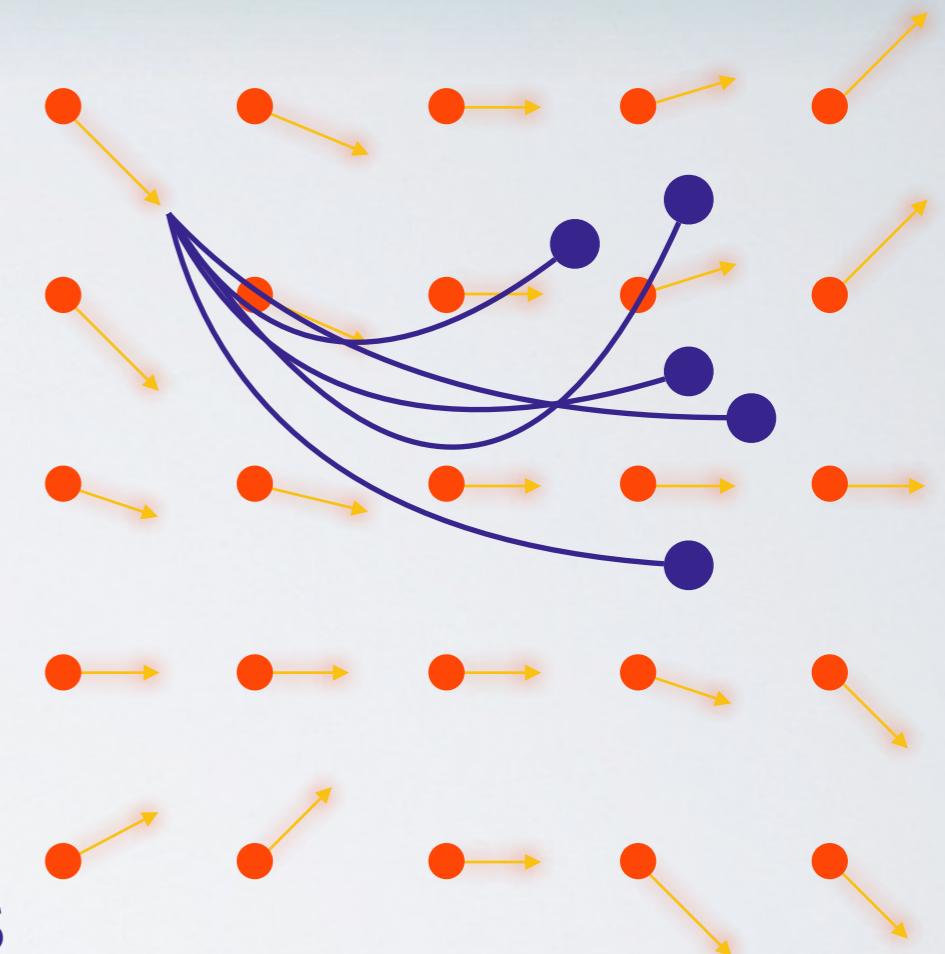
Assimilation Tracing

- Trace multiple “sub-particles”



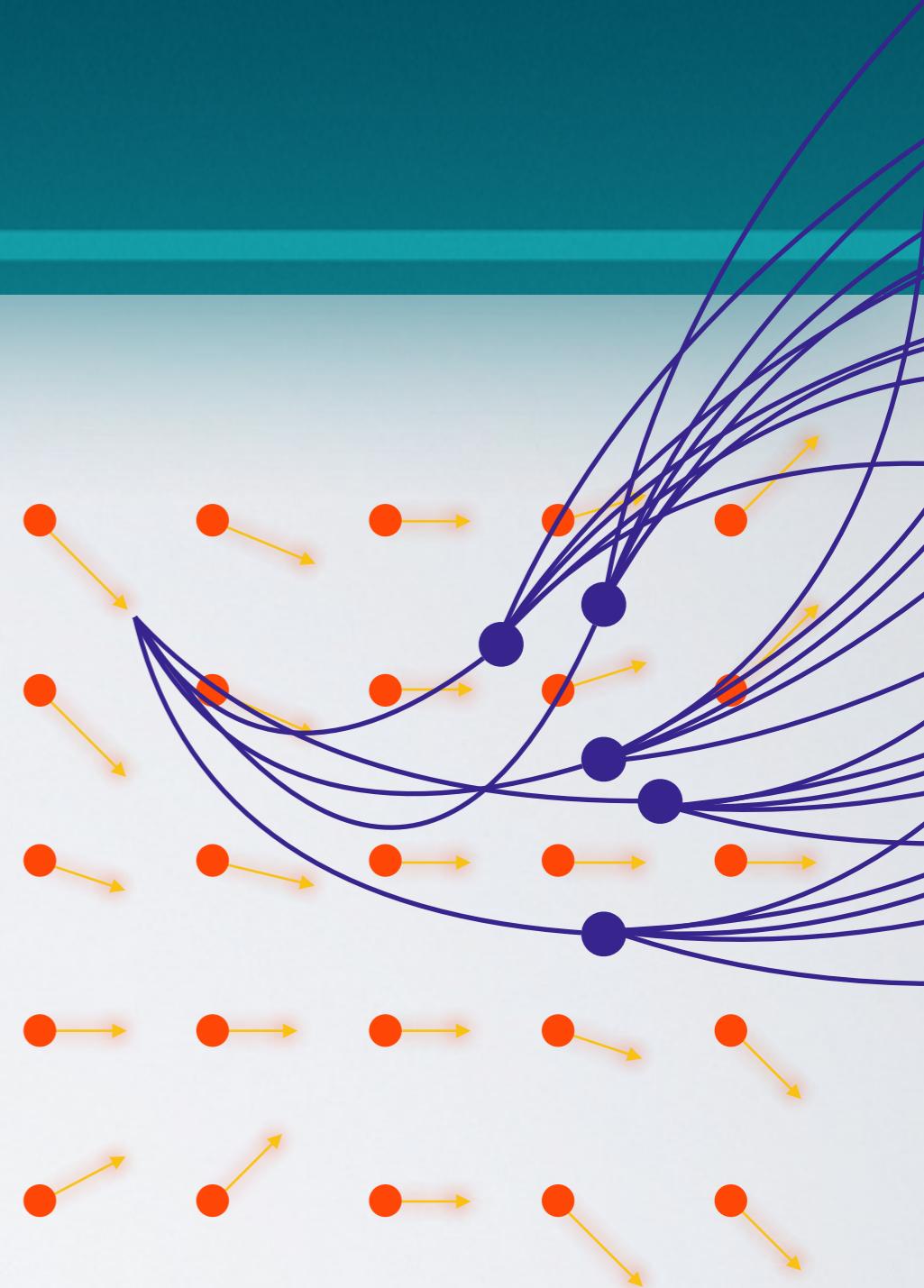
Assimilation Tracing

- Trace multiple “sub-particles”
- Brute force all combinations
- After assimilation cycle
 - new sub-particles per trace
 - eg. 5 members \Rightarrow 5*5 traces



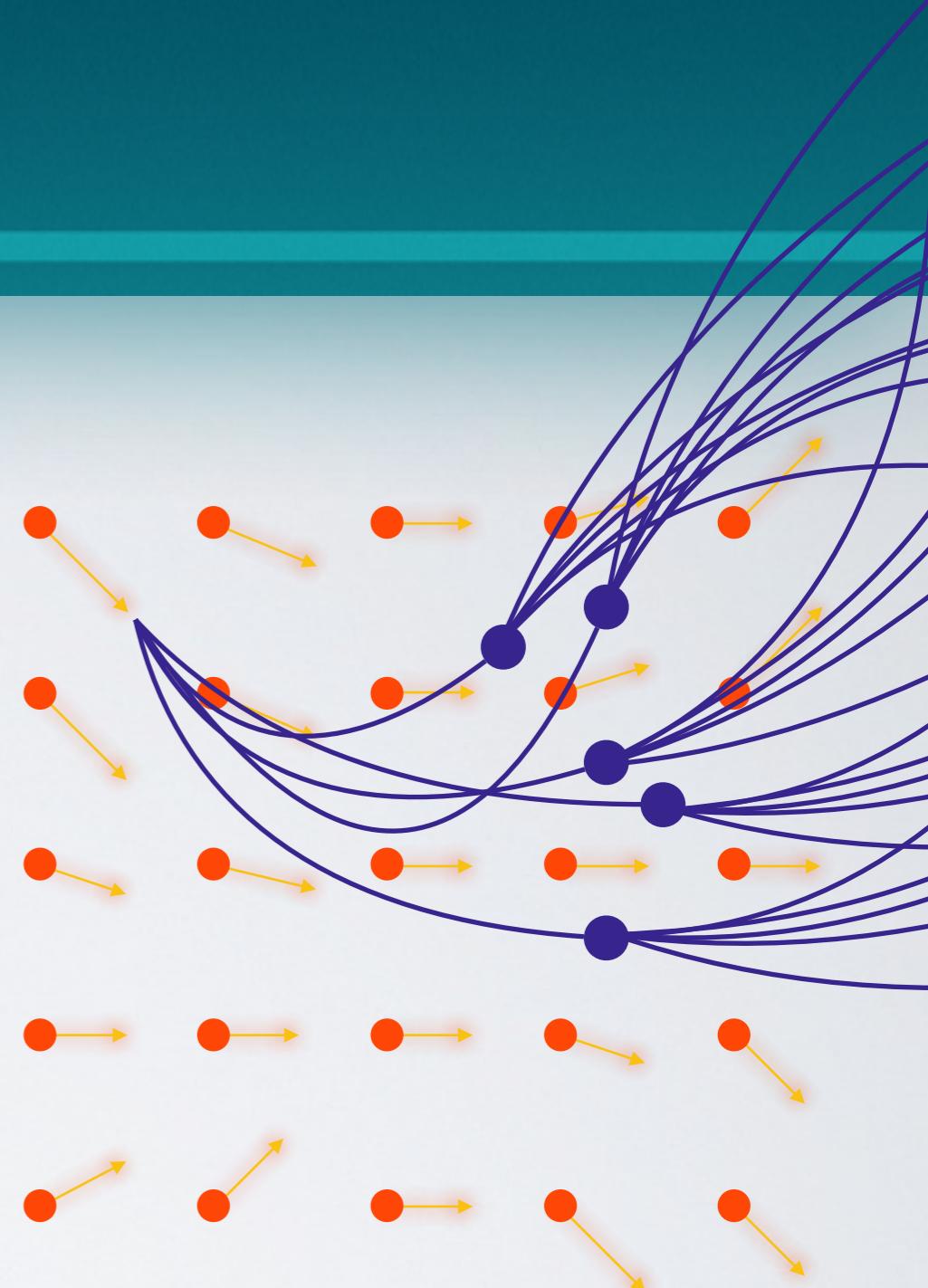
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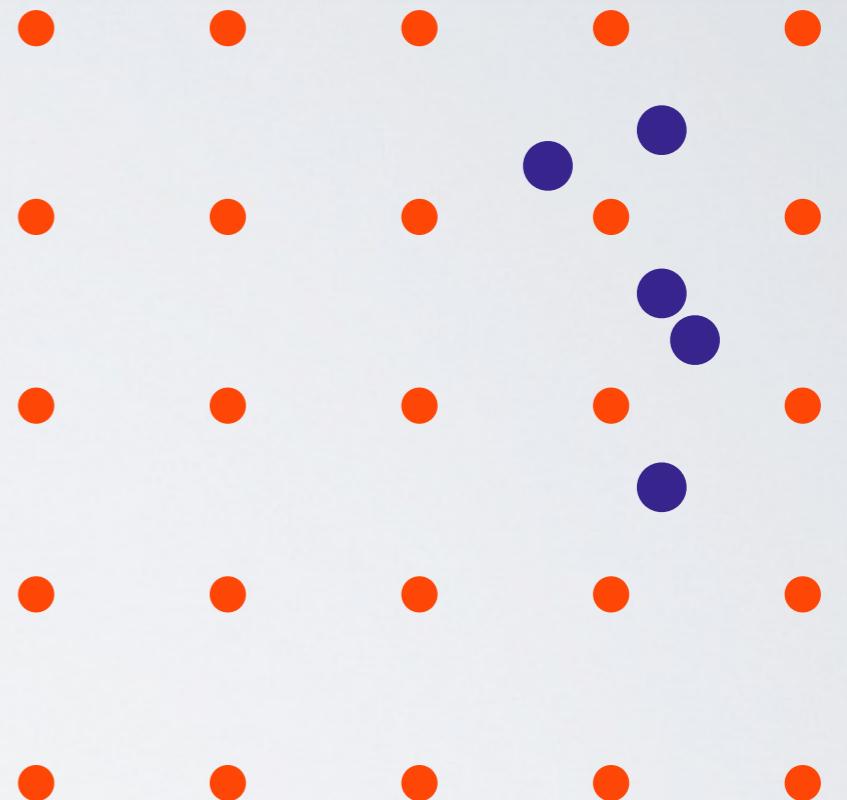
Assimilation Tracing

- Brute force all combinations
 - m members, c cycles
 - m^c combinations
 - Red Sea dataset: $\sim 1E17(!)$



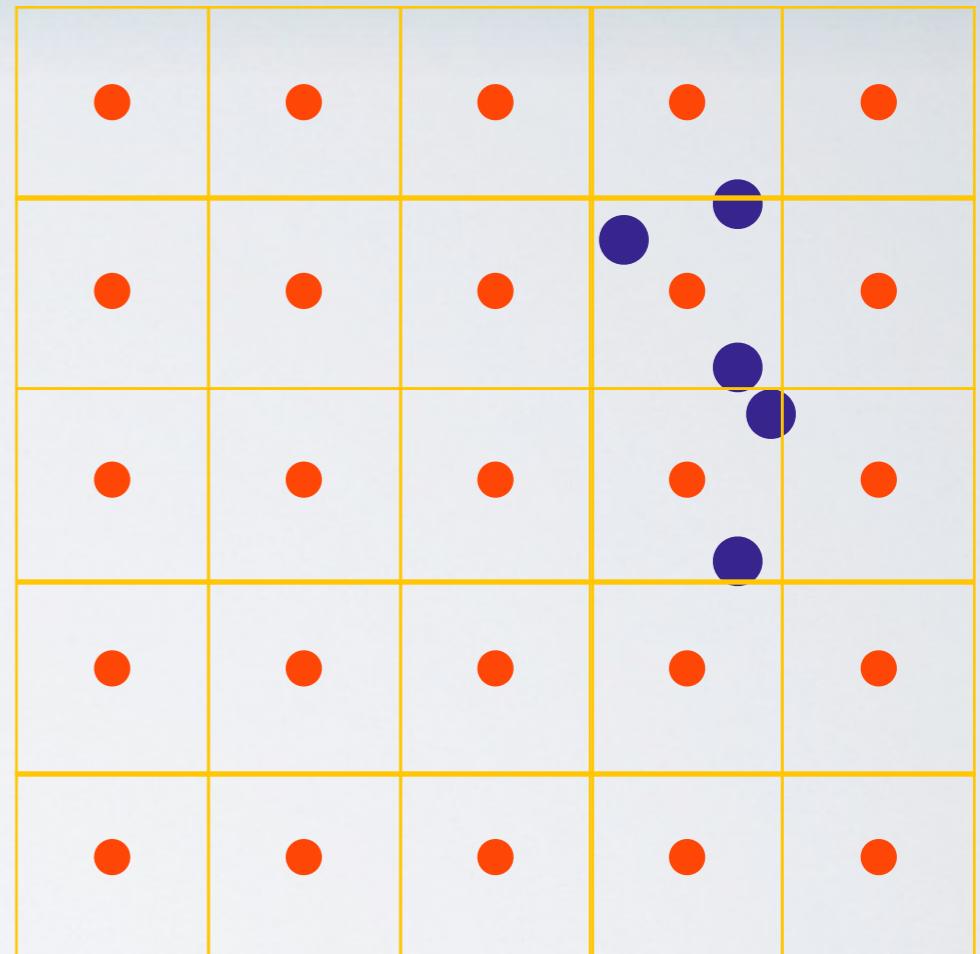
Binned Tracing

- Idea: discretize/bin domain
- Count particles per bin after each cycle
 - ☞ Probability-weight



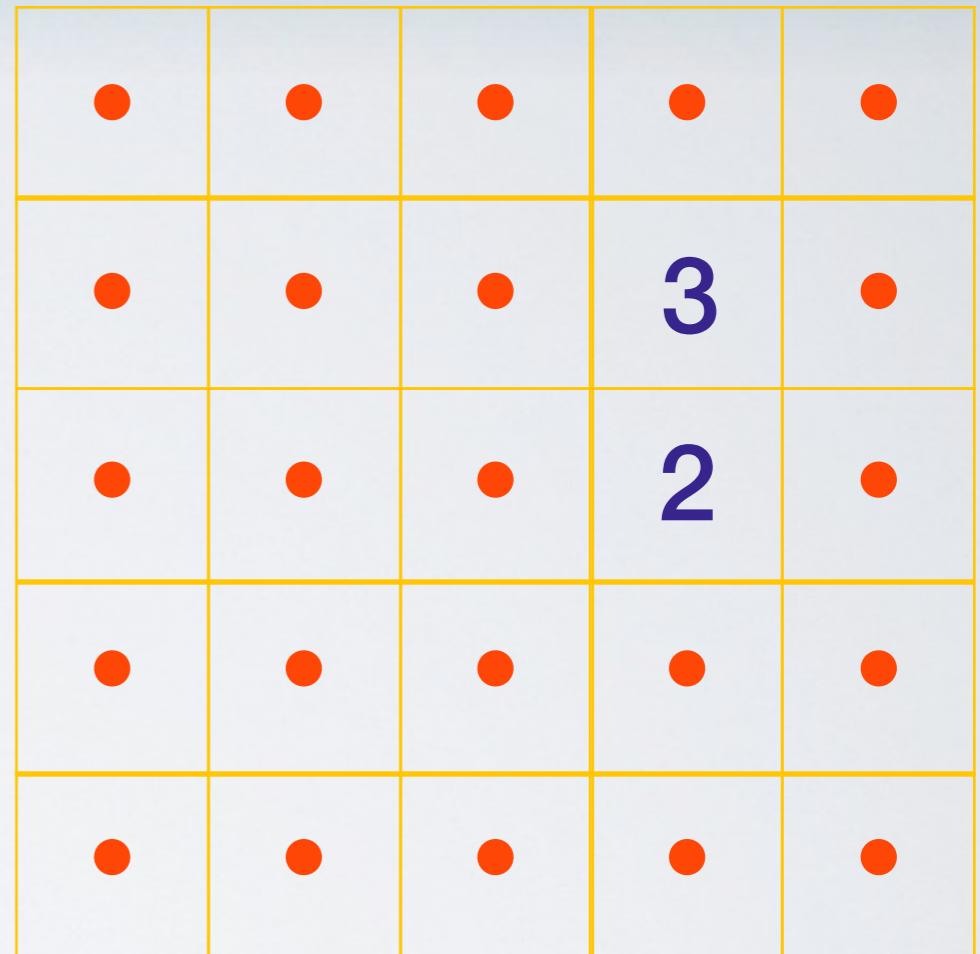
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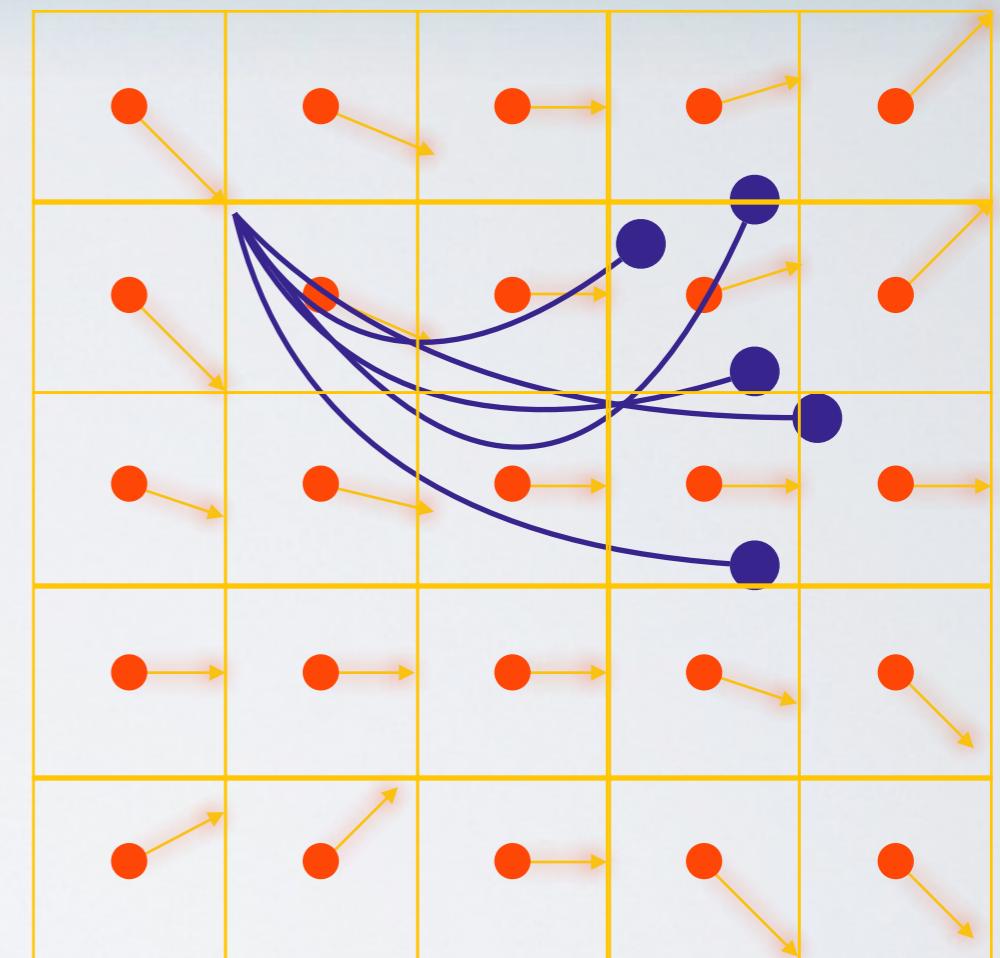
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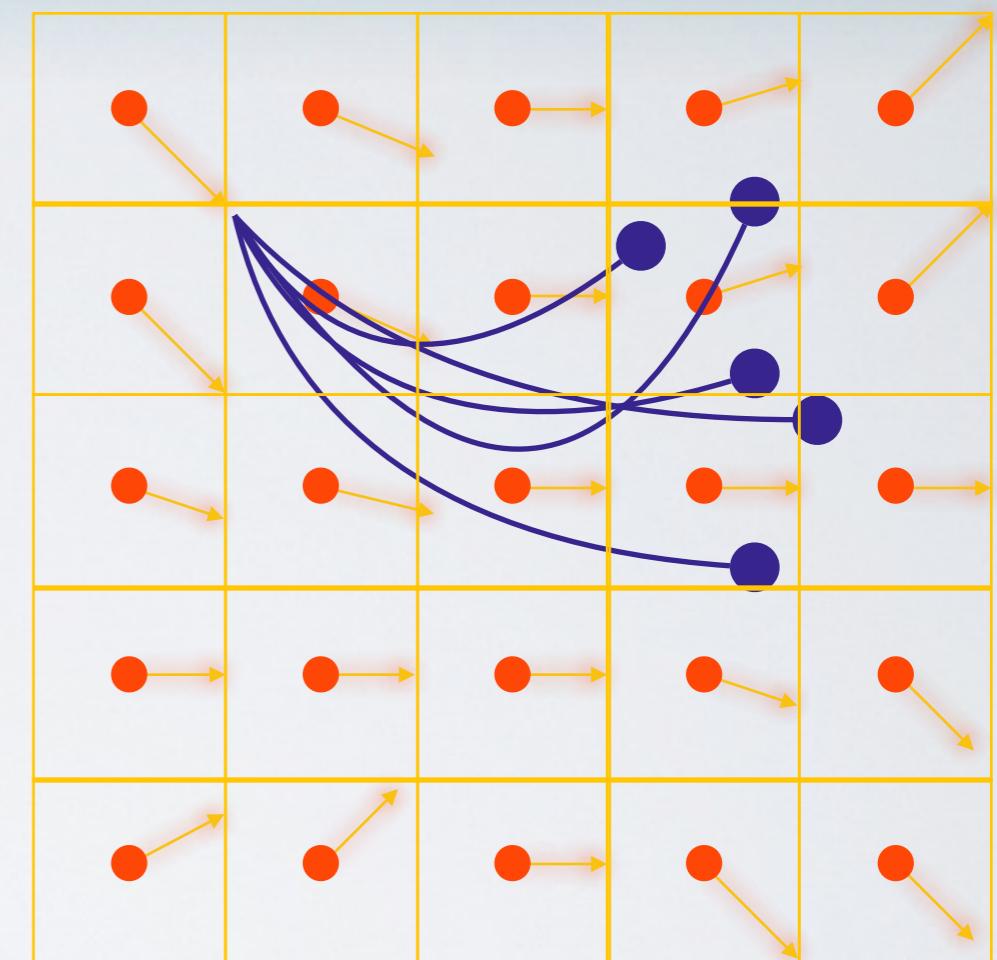
Binned Tracing

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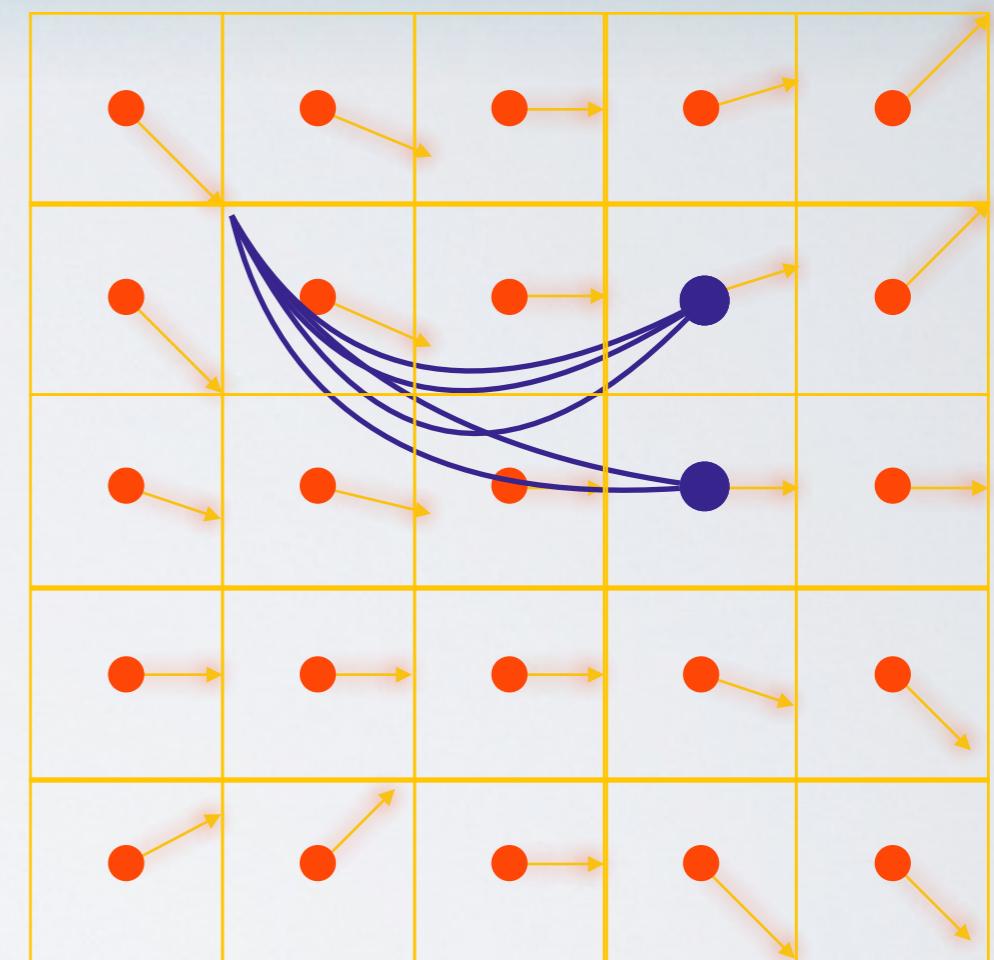
Binned Tracing

- Trace multiple “sub-particles”
- Adjust end to bin center



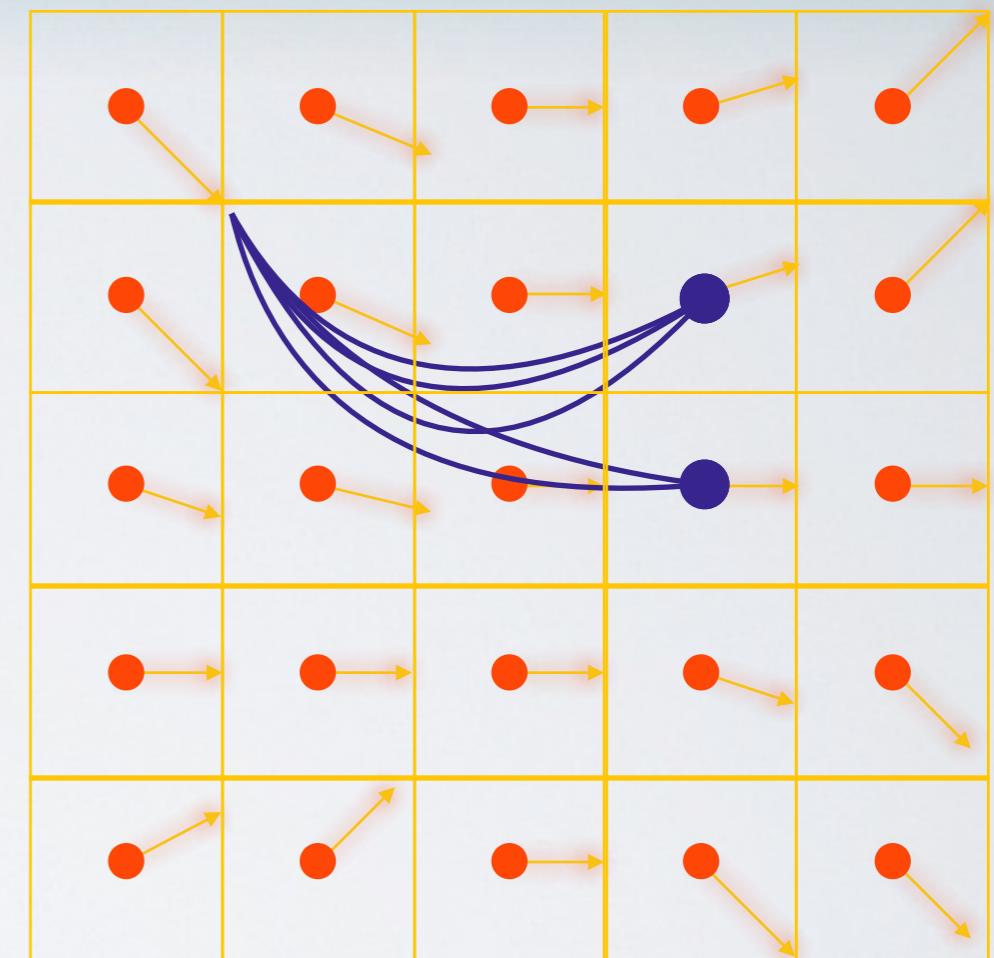
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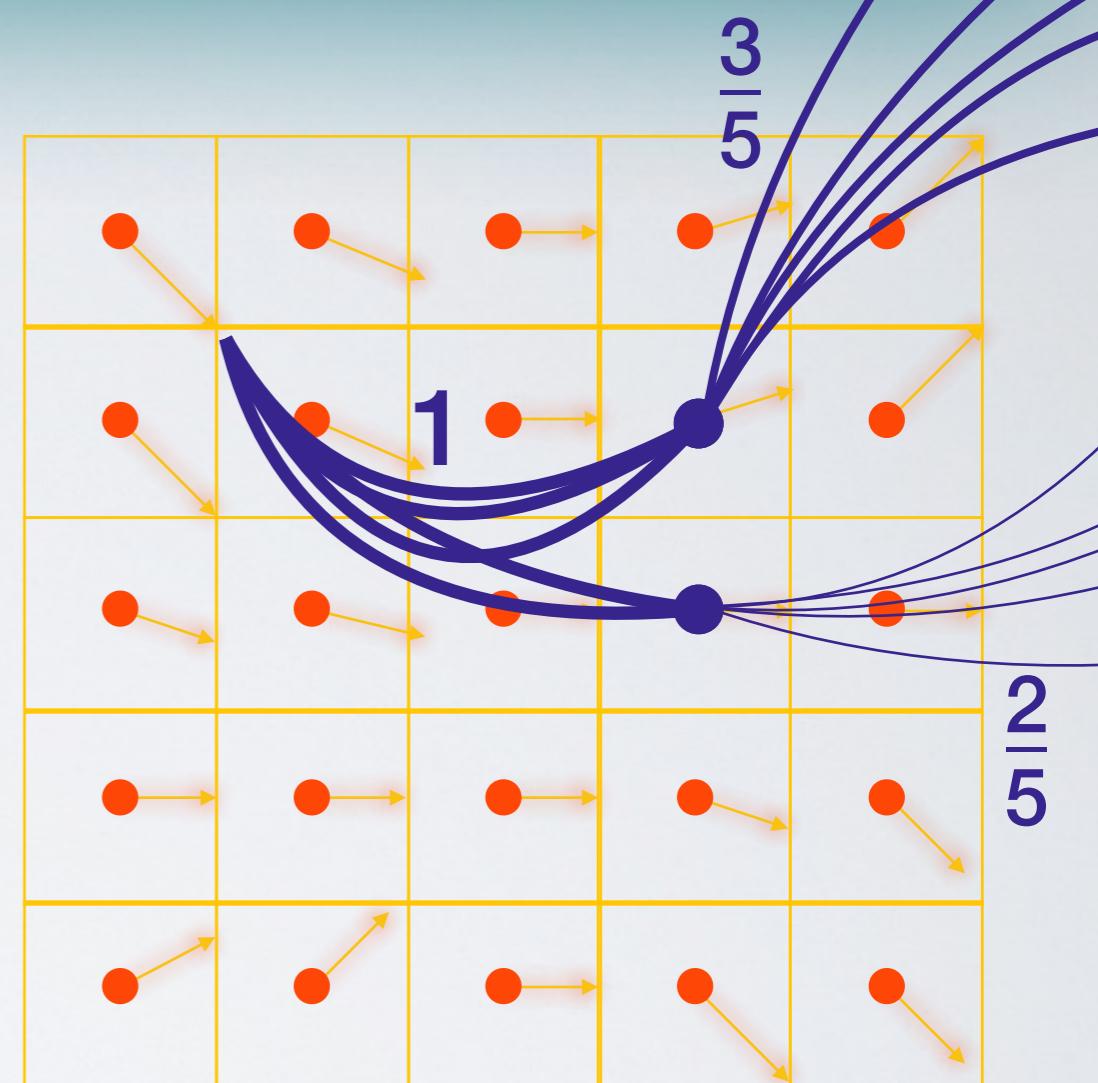
Binned Tracing

- Trace multiple “sub-particles”
- Adjust end to bin center
- Continue tracing from bins
- Attach probability-weights



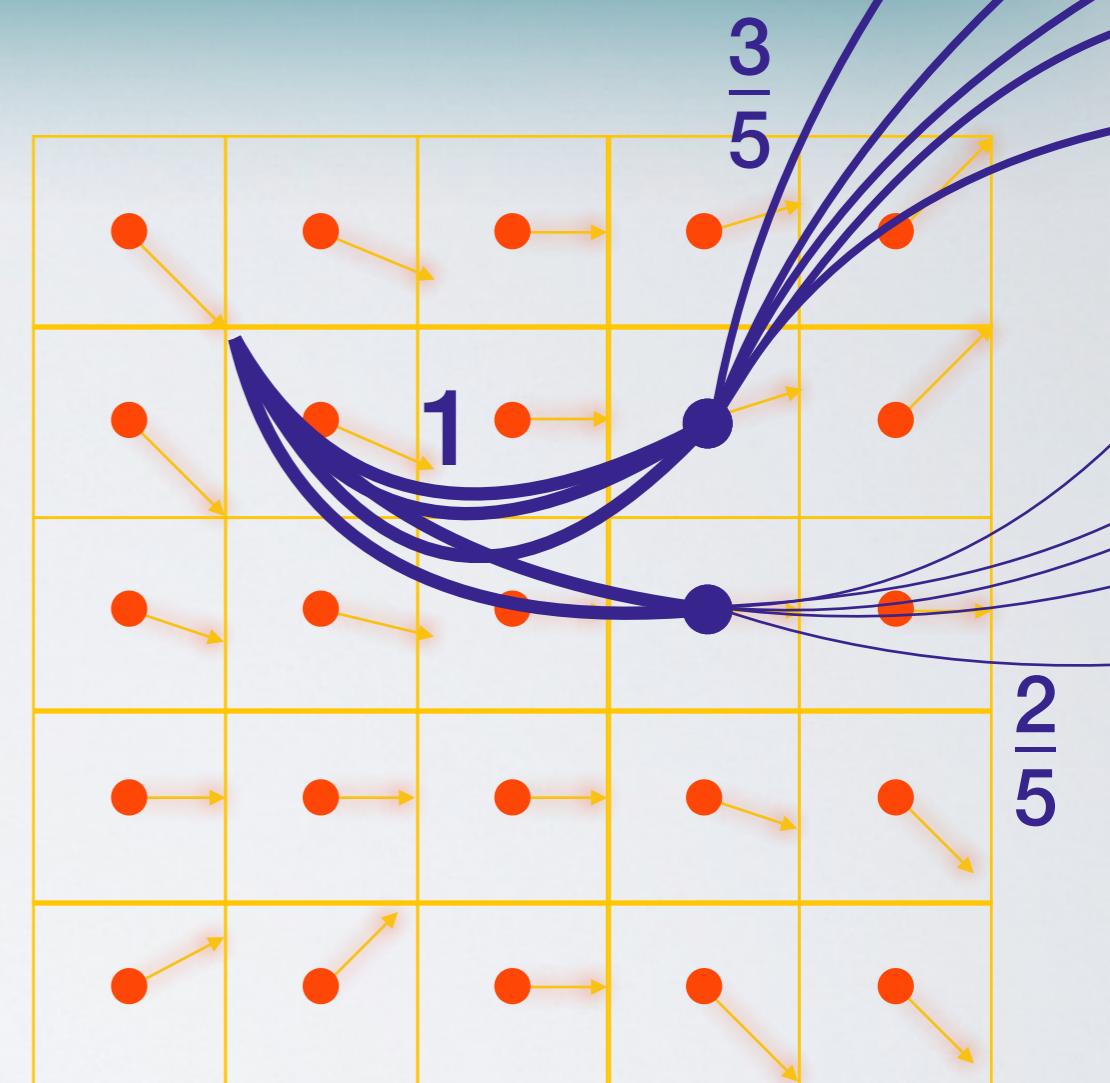
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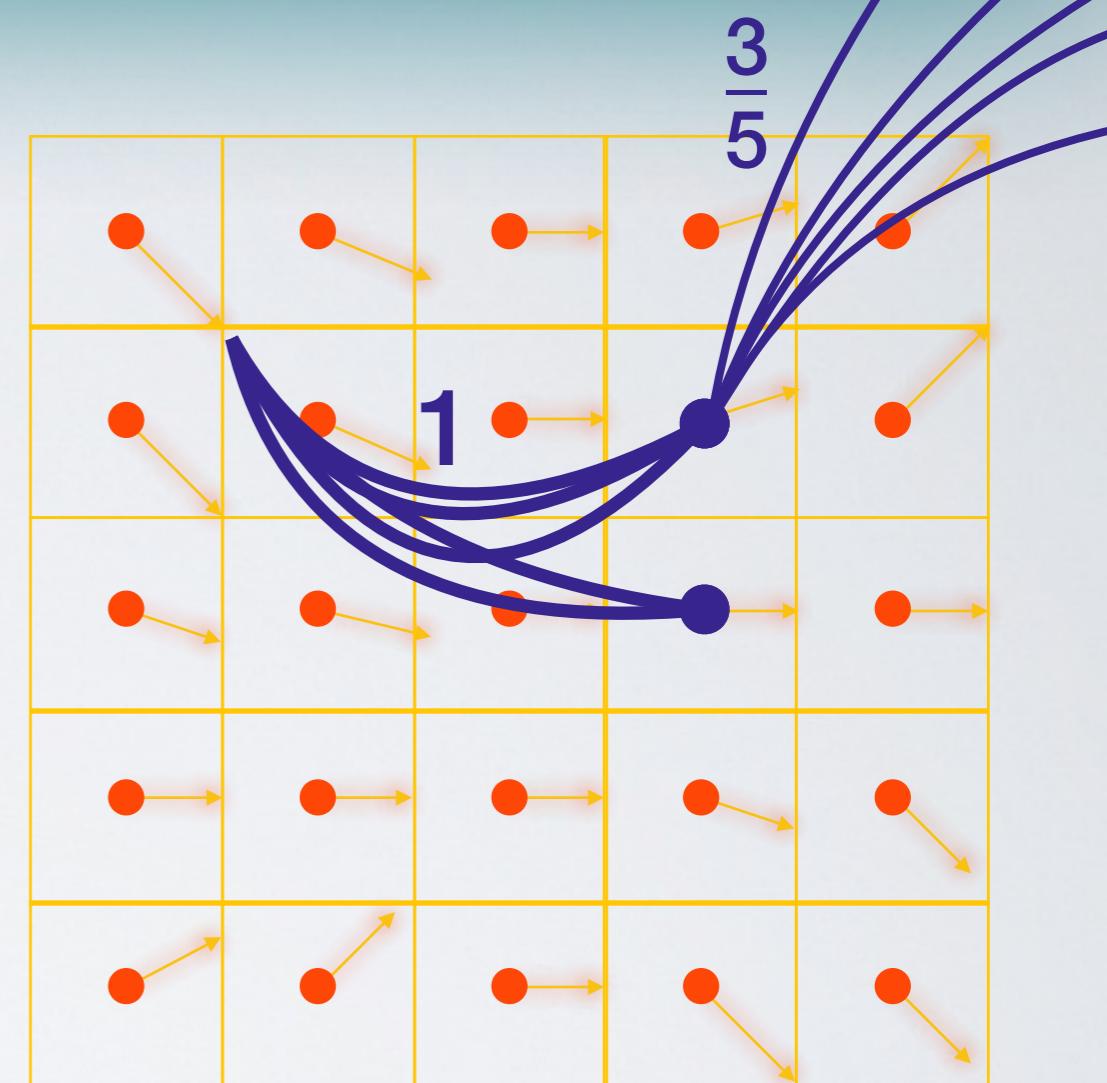
Early Termination

- Terminate early if probability below threshold
 - user defined
 - conservative default

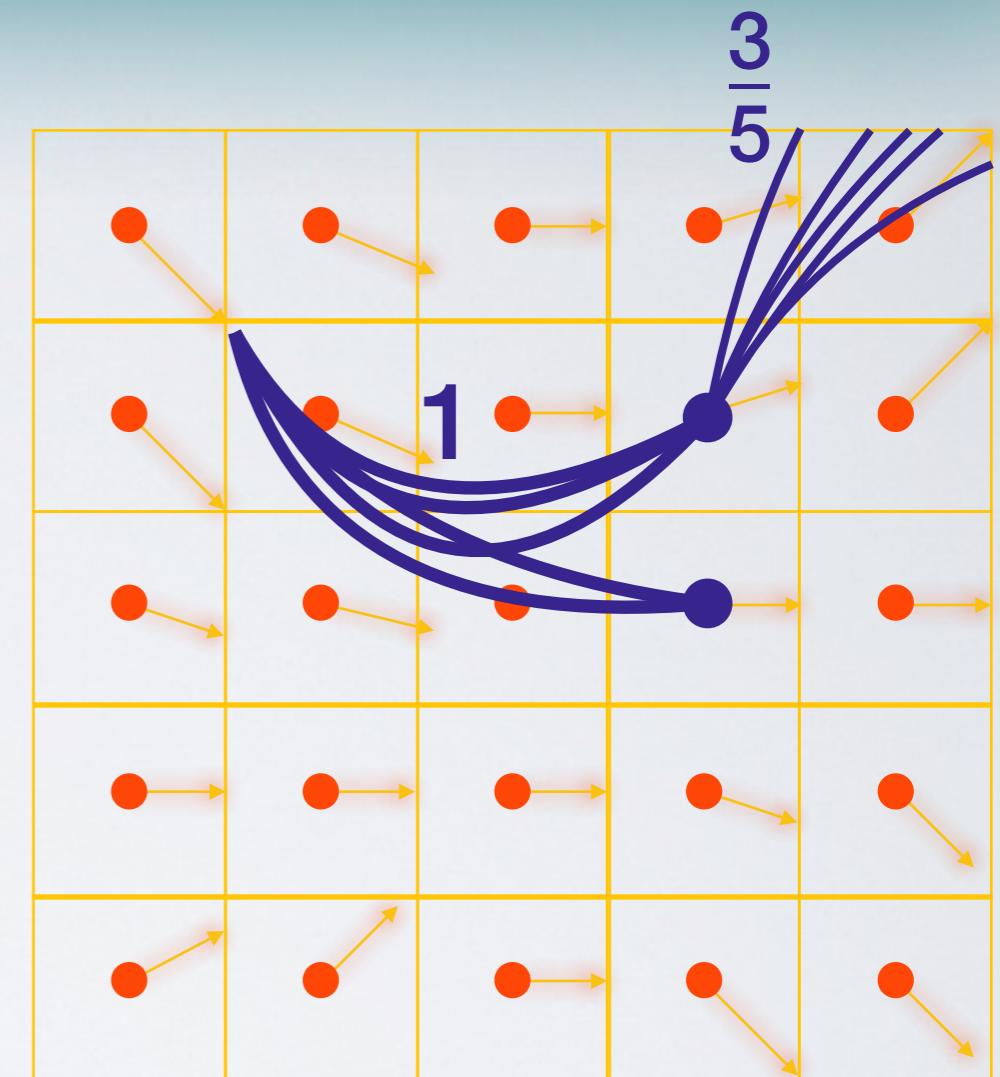


Early Termination

- Terminate early if probability below threshold
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Probability Map Creation



Probability Map Creation

cycle 1



cycle 2

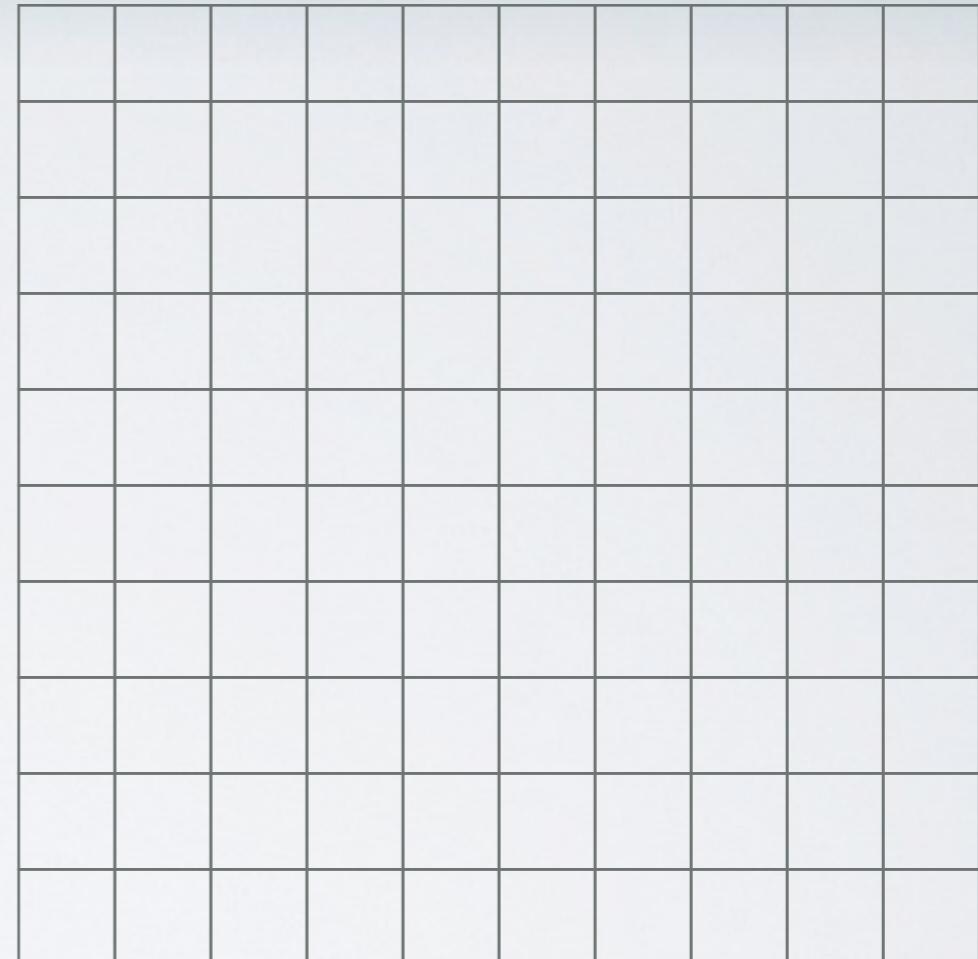


Probability Map Creation

cycle 1

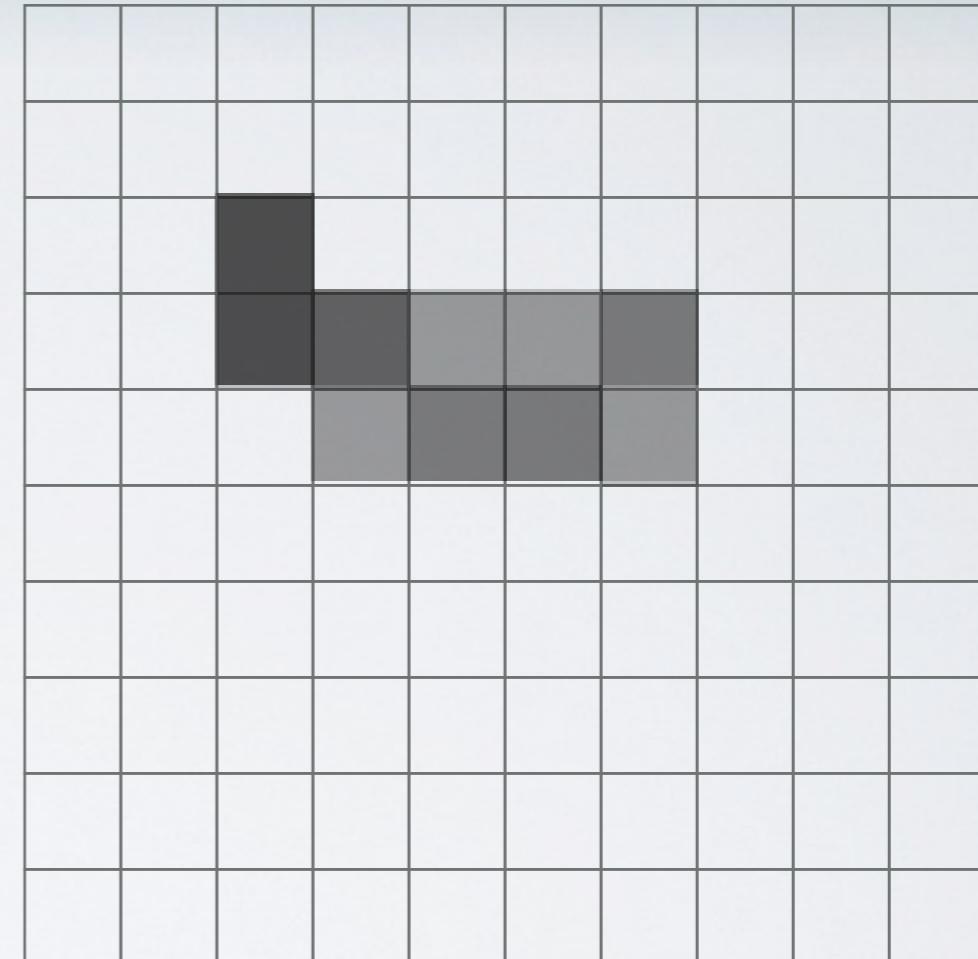


cycle 2



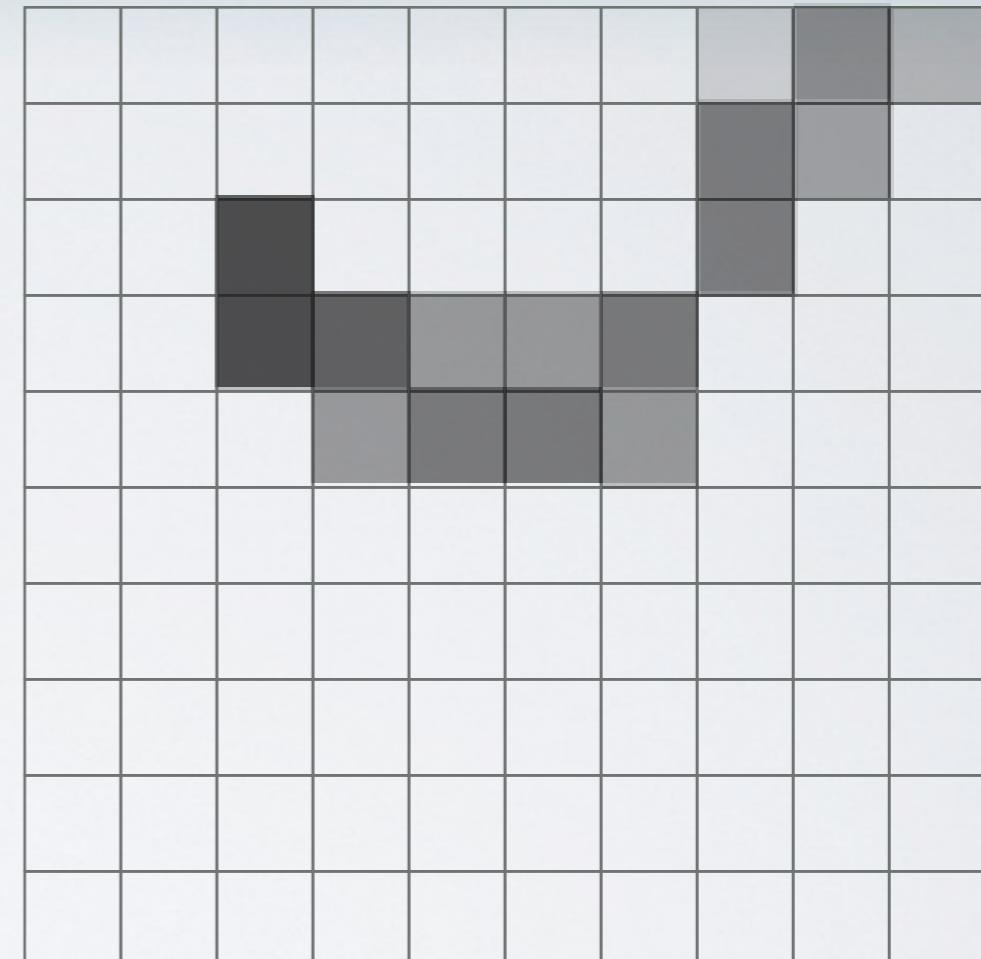
Probability Map Creation

cycle 2



- Rasterize pathlines, probability as alpha

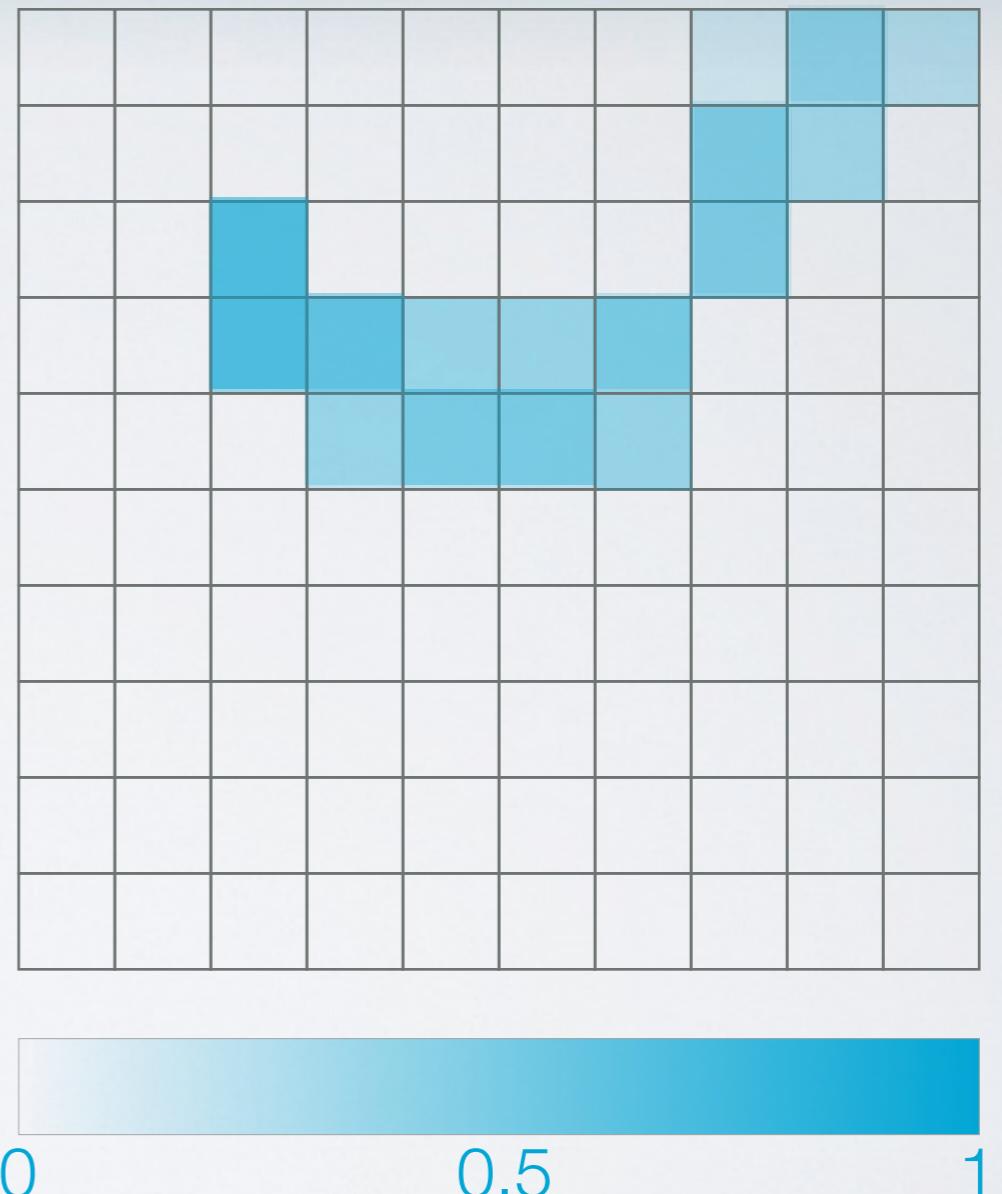
Probability Map Creation



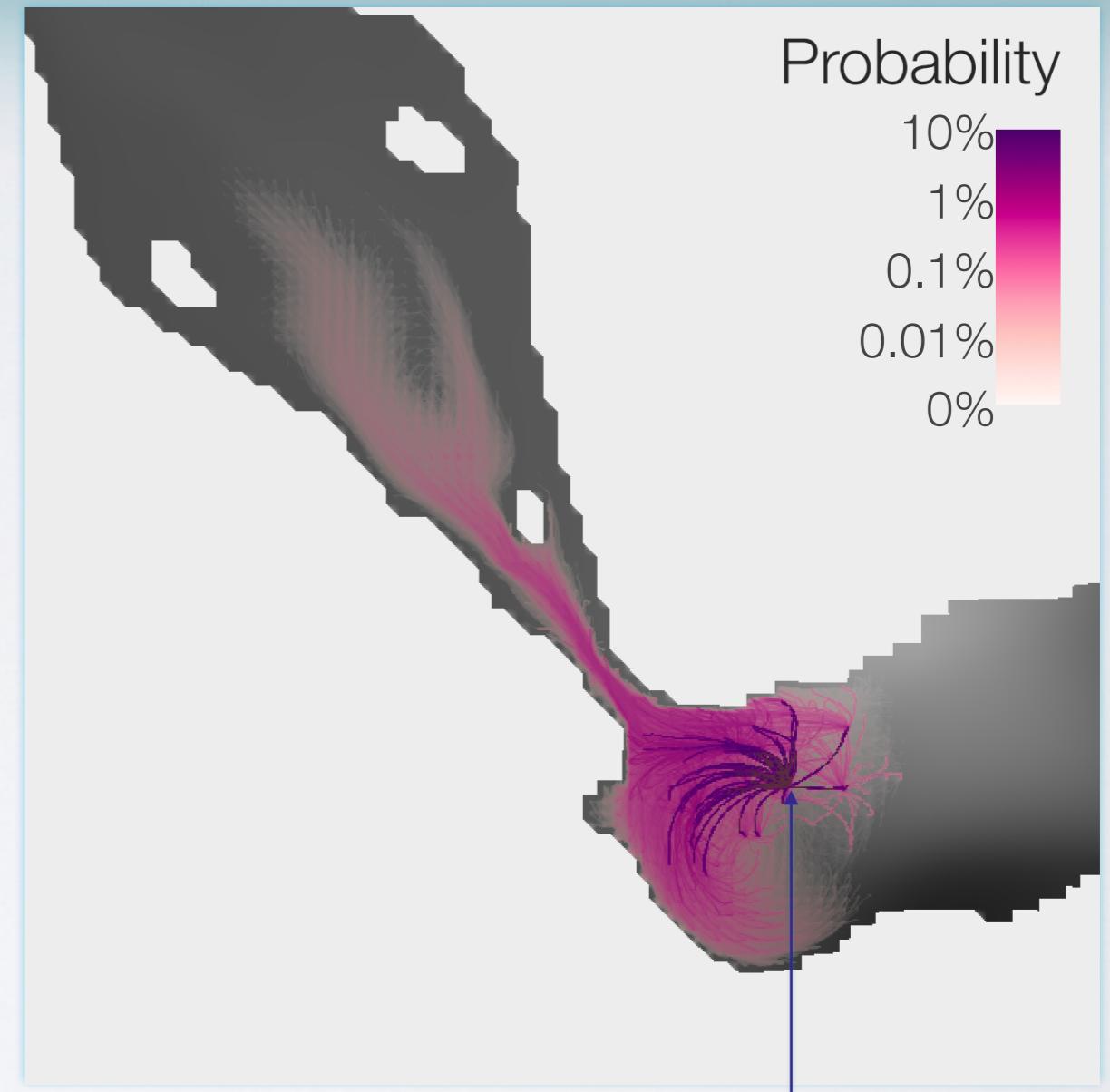
- Rasterize pathlines, probability as alpha

Probability Map Creation

- Simple alpha lookup in texture
- Per pixel probability
- Apply colormap in fragment shader

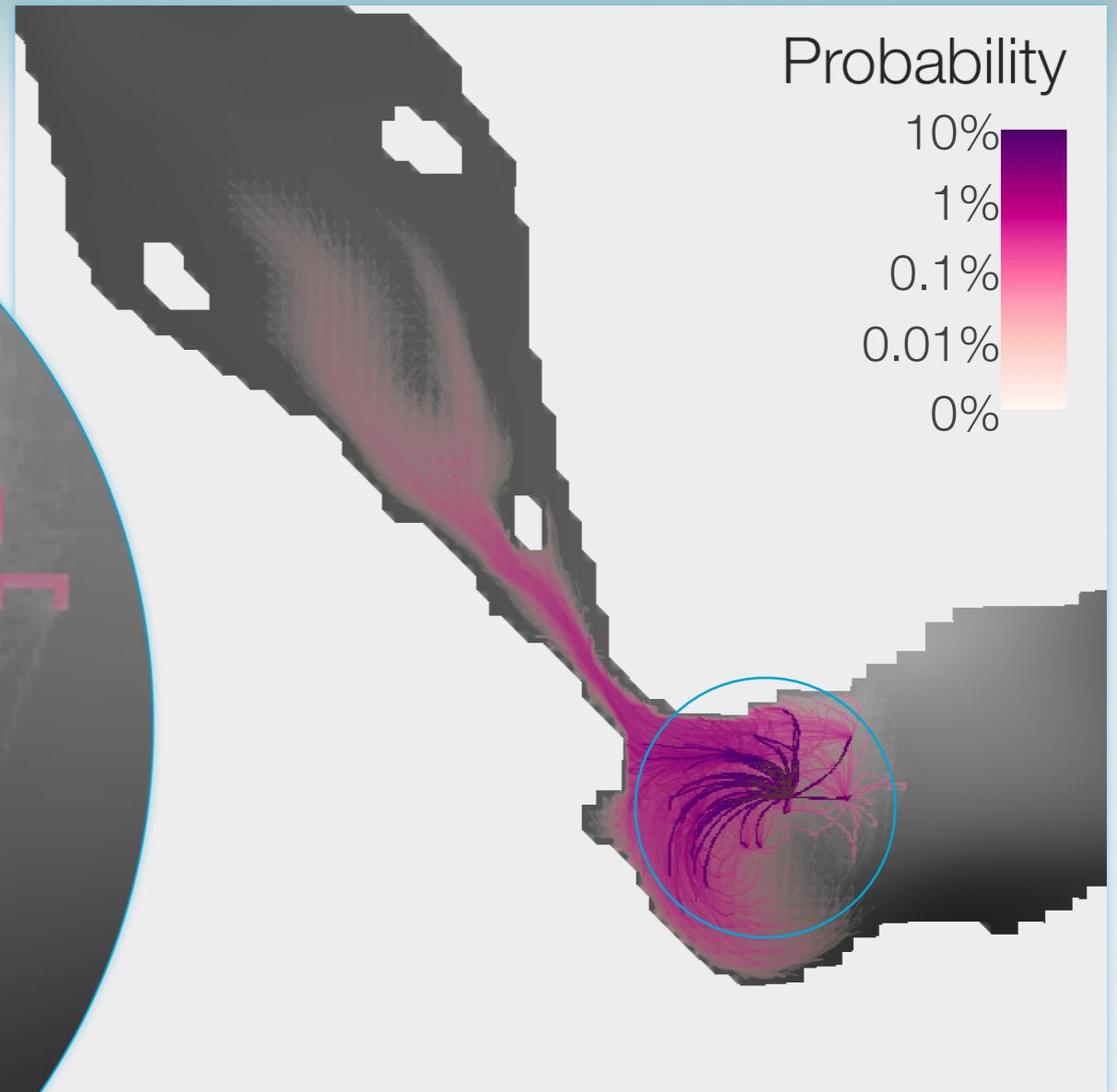
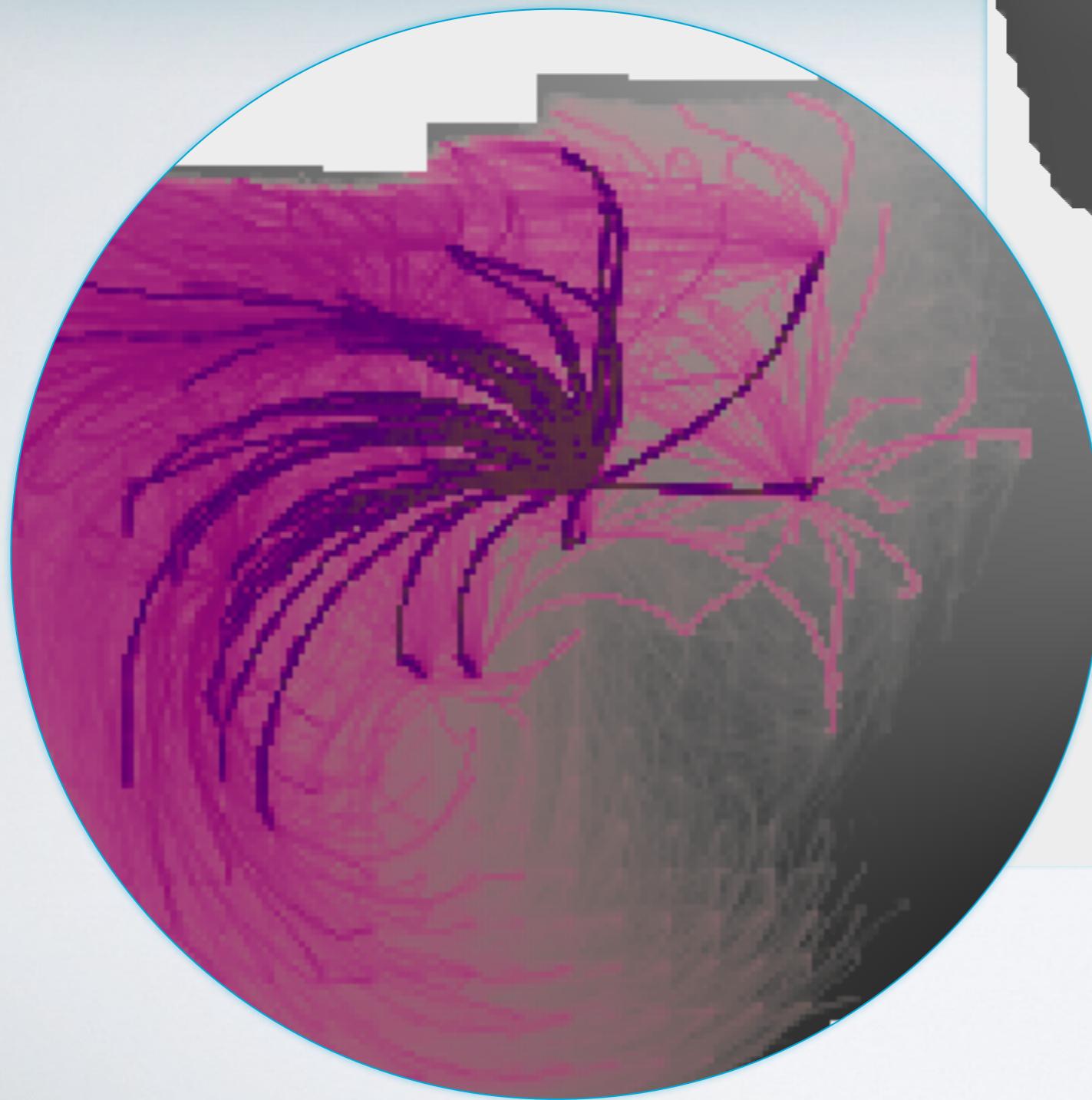


Results



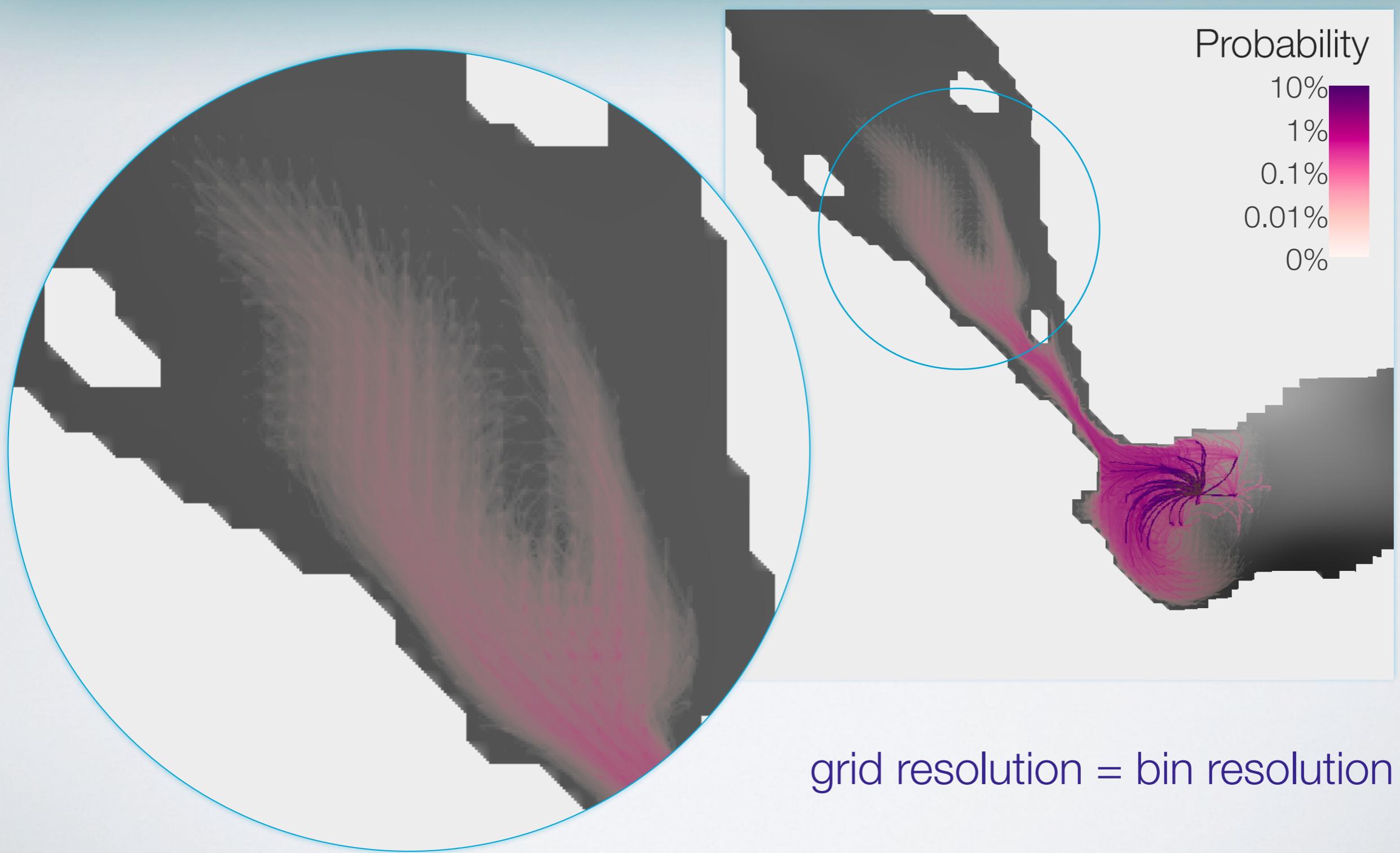
— Seed close to Bab-el-Mandeb

Results

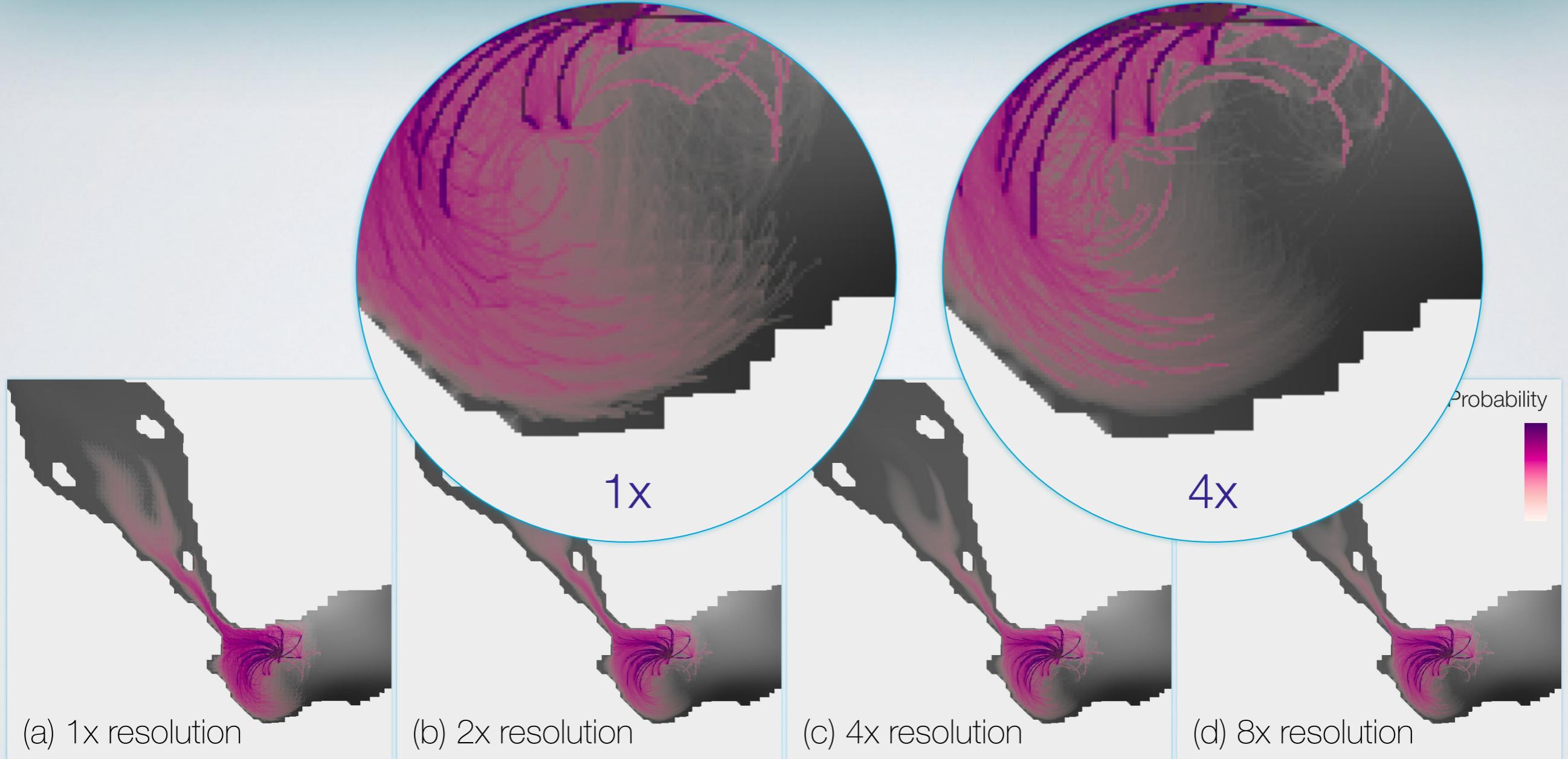


large variation in Gulf of Aden

Results

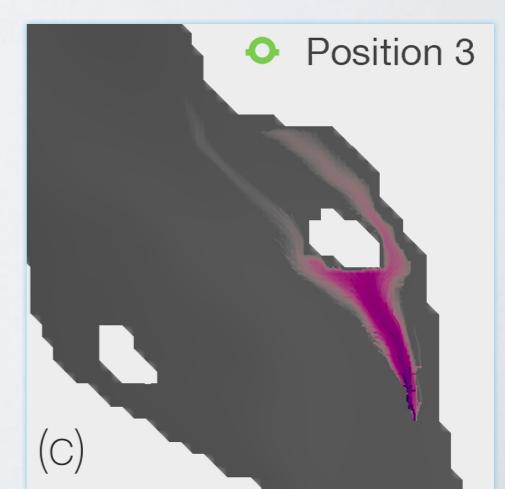
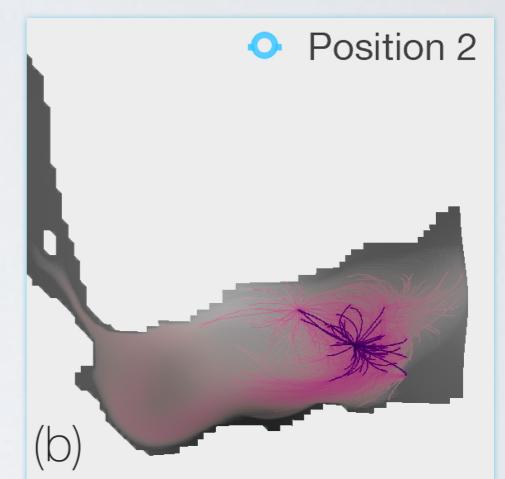
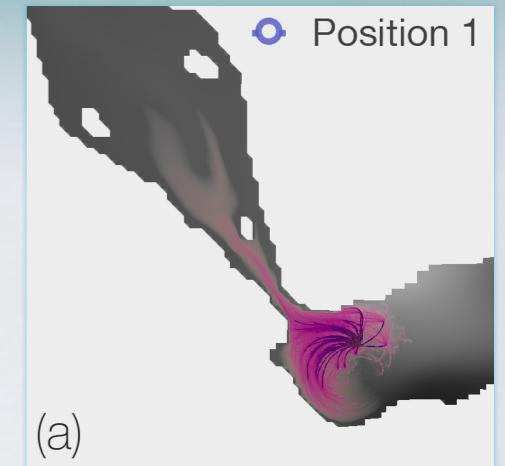


Results



Higher bin resolution gives better precision, larger computational cost

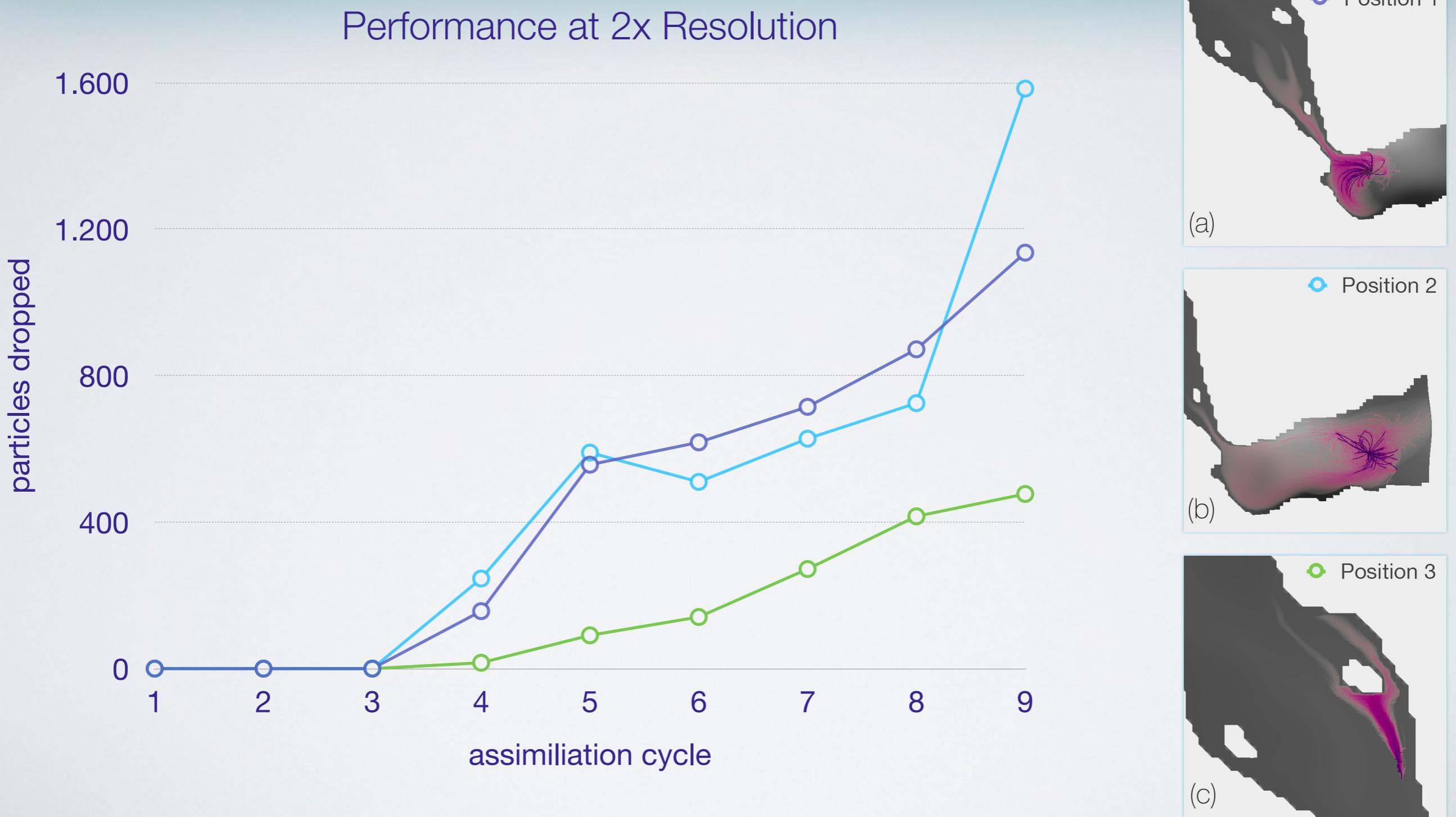
Results



Results



Results



Results



Results



Results



Questions?

