smart.city.kempten - microcontrollers

The model contains three microcontrollers with different functionality, sensors and actors:

- Inner City One
 - 8 space parking area with display
 - smart waste at town hall (also shown on parking display)
 - MQTT upload of parking and smart waste data
 - wiring documented in wiring_inner_city_1.pdf
 - hardware used
 - * Raspberry Pico 2 W
 - * 3 multiplexers TCA9548A (two for parking spaces and one for waste containers)
 - * 8 ToF sensors VL53L0X for parking spaces (via two multiplexers)
 - \ast 3 light sensors GY302 / BH1750 for waste containers (via multiplexer)
 - * 3 5mm LEDs for light barrier of waste containers
 - * OLED display SH1106 for parking area and smart waste
- Inner City Two
 - 4 way traffic light at city hall, with traffic count and traffic count display for incoming street
 - MQTT upload of traffic count (6 sensors at main crossing)
 - 3 way traffic light
 - illuminated controller below street
 - wiring documented in wiring_inner_city_2.pdf
 - hardware used
 - * Raspberry Pico W
 - * 7 traffic light columns with 3 0805 SMD LEDs (red/yellow/green) each, mounted behind trans red/yellow/green 1*1 round LEGO plates
 - * 6 magnetic hall sensors KY-024 for traffic count at main crossing
 - * 3 5mm LEDs for illumination of controller (below street)
 - * OLED display SH1106 for traffic count of street entering the model at the left side
- Iller
 - 6 space parking area with display,
 - smart waste (also shown on parking display)
 - 4 way traffic crossing with traffic count and traffic count display for incoming street
 - environment sensor with display
 - MQTT upload of parking area, traffic count and environment data
 - wiring documented in wiring iller.pdf
 - hardware used
 - * Raspberry Pico 2 W
 - * 4 traffic light columns with 3 0805 SMD LEDs (red/yellow/green)

each, mounted behind trans red/yellow/green 1*1 round LEGO plates

- * 3 multiplexers TCA9548A (one for parking spaces, one for waste containers and one for displays)
- * 6 ToF sensors VL53L0X for parking spaces (via multiplexer)
- * 3 light sensors GY302 / BH1750 for waste containers (via multiplexer)
- * 3 5mm LED for light barrier of waste containers
- * 3 magnetic hall sensors KY-024 for traffic count at crossing
- * 1 BME280 for temperature, pressure and humidity and 1 GY302 / BH1750 for light level (via multiplexer)
- * 3 OLED displays SH1106 for traffic count, parking area/smart waste and environmental data (via multiplexer)

An USB connection of all controllers is available individually at the back side of the model via Micro-USB.

This connection mainly provides the power for the controllers via USB. Power consumption is currently below 1 W per controller, therefore all controllers may be powered by a standard 5V power adapter using y-cables.

However, the USB connections can be used to directly access the controllers individually without the necessity of removing them from the model, e.g. to update and configure them.