

Homework 13

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Problem (4.4.3).

$$\begin{aligned}\int_a^b c^* \omega &= \int_a^b c^* df \\ &= \int_a^b d(c^* f) \\ &= \int_a^b d(f \circ c) \\ &= \int_a^b \frac{d(f \circ c)}{dx} dx \\ &= f \circ c(b) - f \circ c(a) && \text{FTC} \\ &= f(q) - f(p)\end{aligned}$$

Problem (4.4.5). Let $\gamma(t) = (\gamma_1(t), \gamma_2(t), \gamma_3(t))$ where we view $S^1 \cong I/\partial I$. Since ω is a 1-form, we have $\omega = \sum_{i=1}^k f_i dx_i$, where $f_i : X \rightarrow \mathbb{R}$. Therefore,

$$\begin{aligned}\gamma^* \omega &= \sum_{i=1}^k (f_i \circ \gamma) \gamma^* dx_i \\ &= \sum_{i=1}^k (f_i \circ \gamma) d(x_i \circ \gamma) \\ &= \sum_{i=1}^k (f_i \circ \gamma) d\gamma_i \\ &= \sum_{i=1}^k (f_i \circ \gamma) \frac{d\gamma_i}{dt} dt\end{aligned}$$

Therefore,

$$\begin{aligned}\oint_{\gamma} \omega &= \int_{S^1} \sum_{i=1}^k (f_i \circ \gamma(t)) \frac{d\gamma_i}{dt} dt \\ &= \sum_{i=1}^k \int_{S^1} (f_i \circ \gamma(t)) \frac{d\gamma_i}{dt} dt\end{aligned}$$

Problem (4.4.7). By Problem 3, since the endpoints p of a closed curve are the same, we immediately obtain

$$\oint_{\gamma} \omega = f(p) - f(p) = 0$$

Problem (4.4.8).

(a) First note that under the polar coordinates, $x = r \cos \theta$, $y = r \sin \theta$, and $r^2 = x^2 + y^2$.

Thus $dx = \frac{\partial x}{\partial r} dr + \frac{\partial x}{\partial \theta} d\theta = \cos \theta dr - r \sin \theta d\theta$ and $dy = \frac{\partial y}{\partial r} dr + \frac{\partial y}{\partial \theta} d\theta = \sin \theta dr + r \cos \theta d\theta$.

Thus we have

$$\begin{aligned}
 \int_{C_a} \omega &= \int_{C_a} \frac{-y}{x^2 + y^2} dx + \int_{C_a} \frac{x}{x^2 + y^2} dy \\
 &= \int_a^a \frac{-\sin \theta \cos \theta}{r} dr + \int_0^{2\pi} (\sin \theta)^2 d\theta + \int_a^a \frac{\cos \theta \sin \theta}{r} dr + \int_0^{2\pi} (\cos \theta)^2 d\theta \\
 &= 0 + \int_0^{2\pi} (\sin^2 \theta + \cos^2 \theta) d\theta + 0 \\
 &= \theta \Big|_0^{2\pi} \\
 &= 2\pi
 \end{aligned}$$

(b) Note that when $x > 0$, $\frac{y}{x}$ is well-defined. Thus we have

$$\begin{aligned}
 d \left(\arctan \frac{y}{x} \right) &= \frac{\partial \arctan \frac{y}{x}}{\partial x} dx + \frac{\partial \arctan \frac{y}{x}}{\partial y} dy \\
 &= \frac{1}{1 + \left(\frac{y}{x} \right)^2} \left(-\frac{y}{x^2} \right) dx + \frac{1}{1 + \left(\frac{y}{x} \right)^2} \frac{1}{x} dy \\
 &= \frac{-y}{x^2 + y^2} dx + \frac{x}{x^2 + y^2} dy
 \end{aligned}$$

(c) Suppose $w = \partial f$ for some $f : \mathbb{R}^2 - \{0\} \rightarrow \mathbb{R}$, then by 7 its contour integral would be 0, but that contradicts with part a.

Problem (4.4.13). Suppose S is the graph of $G : \mathbb{R}^2 \rightarrow \mathbb{R}$, then S can be parameterized by $h(x_1, x_2) = (x_1, x_2, G(x_1, x_2))$. Therefore,

$$dx_3 = dG = \frac{\partial G}{\partial x_1} dx_1 + \frac{\partial G}{\partial x_2} dx_2.$$

Then the 2-form becomes

$$\begin{aligned}
 dA &= -n_1 \frac{\partial G}{\partial x_1} dx_1 \wedge dx_2 - n_2 \frac{\partial G}{\partial x_2} dx_1 \wedge dx_2 + n_3 dx_1 \wedge dx_2 \\
 &= \left(-\frac{\partial G}{\partial x_1} n_1, -\frac{\partial G}{\partial x_2} n_2, n_3 \right) dx_1 \wedge dx_2 =: \mathbf{v} dx_1 \wedge dx_2 \quad n_i \text{ are linearly independent} \\
 &= \begin{pmatrix} -\frac{\partial G}{\partial x_1} & 0 & 0 \\ 0 & -\frac{\partial G}{\partial x_2} & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} n_1 \\ n_2 \\ n_3 \end{pmatrix} dx_1 \wedge dx_2 =: \mathbf{D} \mathbf{n} dx_1 \wedge dx_2
 \end{aligned}$$

$$\begin{aligned}
&= \|D\| \mathbf{n} dx_1 \wedge dx_2 && \mathbf{n} \text{ unit vec} \\
&= \sqrt{\left(\frac{\partial G}{\partial x_1}\right)^2 + \left(\frac{\partial G}{\partial x_2}\right)^2 + 1} \mathbf{n} dx_1 \wedge dx_2 \\
&= \|\mathbf{v}\| \mathbf{n} dx_1 \wedge dx_2
\end{aligned}$$

which coincides with the other definition of dA after dotting with \mathbf{n} .

Problem (4.5.1). Denote the given form ω .

(a)

$$\begin{aligned}
d(\omega) &= d(z^2 dx \wedge dy) + d(z^2 dx \wedge dz) + d(2y dx \wedge dz) \\
&= d(z^2) \wedge dx \wedge dy + d(z^2) dx \wedge dz + d(2y) \wedge dx \wedge dz \\
&= 2z dz \wedge dx \wedge dy + 2z dz \wedge dx \wedge dz + 2dy \wedge dx \wedge dz \\
&= (2z - 2) dx \wedge dy \wedge dz
\end{aligned}$$

(b)

$$\begin{aligned}
d\omega &= 13dx \wedge dx + 2ydy \wedge dy + d(xyz)dz \\
&= 0 + 0 + (yzdx + xzdy + xydz) \wedge dz \\
&= yzdx \wedge dz + xzdy \wedge dz
\end{aligned}$$

(c)

$$\begin{aligned}
d(fdg) &= df \wedge dg + 0 && \text{product rule} \\
&= \left(\frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz\right) \wedge \left(\frac{\partial g}{\partial x} dx + \frac{\partial g}{\partial y} dy + \frac{\partial g}{\partial z} dz\right) \\
&= \frac{\partial f}{\partial x} \frac{\partial g}{\partial y} dx \wedge dy + \frac{\partial f}{\partial x} \frac{\partial g}{\partial z} dx \wedge dz + \frac{\partial f}{\partial y} \frac{\partial g}{\partial x} dy \wedge dx \\
&\quad + \frac{\partial f}{\partial y} \frac{\partial g}{\partial z} dy \wedge dz + \frac{\partial f}{\partial z} \frac{\partial g}{\partial x} dz \wedge dx + \frac{\partial f}{\partial z} \frac{\partial g}{\partial y} dz \wedge dy \\
&= \left(\frac{\partial f}{\partial x} \frac{\partial g}{\partial y} - \frac{\partial f}{\partial y} \frac{\partial g}{\partial x}\right) dx \wedge dy + \left(\frac{\partial f}{\partial x} \frac{\partial g}{\partial z} - \frac{\partial f}{\partial z} \frac{\partial g}{\partial x}\right) dx \wedge dz + \left(\frac{\partial f}{\partial y} \frac{\partial g}{\partial z} - \frac{\partial f}{\partial z} \frac{\partial g}{\partial y}\right) dy \wedge dz
\end{aligned}$$

(d)

$$d\omega = 0 + 0 + 6y^2 dy \wedge dz \wedge dx + 0 = 6y^2 dy \wedge dz \wedge dx$$

Problem (4.5.2).

$$\begin{aligned}\nabla \times F &= \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \\ &= \frac{x^2 + y^2 - 2x^2}{(x^2 + y^2)^2} + \frac{x^2 + y^2 - 2y^2}{(x^2 + y^2)^2} \\ &= 0\end{aligned}$$

By Problem 4.4.8, we know that F is not the differential of any function, thus it cannot be written as the gradient of any function. Otherwise, the gradient expression immediately leads to the 1-form aka differential.