

Homework 11

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Problem (Do Carmo 6.1). Let M_1 and M_2 be Riemannian manifolds, and consider the product $M_1 \times M_2$ with the product metric. Let ∇^1, ∇^2 be the Riemannian connection of M_1, M_2 , respectively.

- (a) Show that the Riemannian connection ∇ of $M_1 \times M_2$ is given by $\nabla_{Y_1+Y_2}(X_1 + X_2) = \nabla_{Y_1}^1 X_1 + \nabla_{Y_2}^2 X_2$, with $X_1, Y_1 \in \mathfrak{X}(M_1), X_2, Y_2 \in \mathfrak{X}(M_2)$.
- (b) For every $p \in M_1$, the set $(M_2)_p = \{(p, q) \in M_1 \times M_2 : q \in M_2\}$ is a submanifold of $M_1 \times M_2$, naturally diffeomorphic to M_2 . Prove that $(M_2)_p$ is totally geodesic submanifold of $M_1 \times M_2$.
- (c) Let $\sigma(x, y) \subset T_{(p,q)}(M_1 \times M_2)$ be a plane such that $x \in T_p M_1$ and $y \in T_q M_2$. Show that $K(\sigma) = 0$.

Proof. (a) The Riemannian connection is compatible with the tangent functor. Product structure of manifold is preserved through tangent functor in tangent spaces, and product and coproduct are isomorphic in the category of finite dimensional vector spaces, so product turns into direct sum.

- (b) Let $X_2, Y_2 \in \mathfrak{X}((M_2)_p)$ and $\bar{X} = X_1 + X_2$ and $\bar{Y} = Y_1 + Y_2$ be the extensions of X_2, Y_2 in $M_1 \times M_2$. That is, $\bar{X}_{(p,q)} = X_2(q)$ so $X_1(p) = 0$ and similarly $Y_1(p) = 0$. Now we compute

$$\begin{aligned}
 B_2(X_2, Y_2) &= \bar{\nabla}_{\bar{X}} \bar{Y} - \nabla_{X_2}^2 Y_2 \\
 &= \nabla_{X_1}^1 Y_1 + \nabla_{X_2}^2 Y_2 - \nabla_{X_2}^2 Y_2 \\
 &= \nabla_{X_1}^1 Y_1 \\
 &\equiv 0,
 \end{aligned}$$

where the last equality comes from the fact that $B_2(X, Y)$ is only defined on $(M_2)_p$, which forces $X_1, Y_1 = 0$ since the extensions must agree with X_2, Y_2 on $(M_2)_p$, which in turn forces $\nabla_{X_1}^1 Y_1$ at any point in $(M_2)_p$ to be zero. It follows that $H_\eta \equiv 0$ for any $\eta \in T_{(p,q)}(M_2)_p^T$ and thus $(M_2)_p$ is totally geodesic.

- (c) Consider the local vector field extension X, Y of x, y at (p, q) in M_1, M_2 respectively. Since they are in orthogonal complements, in the product manifold they become $(X, 0)$ and $(0, Y)$. It suffices to show that $R((X, 0), (0, Y))(X, 0) = 0$. In local coordinates $\left(\frac{\partial}{\partial x_j}, \frac{\partial}{\partial y_i}\right)$, $(X, 0), (0, Y)$ are $(x_j, 0)$ and $(0, y_i)$ where x_j only depends on $p \in M_1$, y_i only depends on $q \in M_2$. Therefore, we have $(X(p), 0)y_i(q) = 0$ and $(0, Y(q))x_j(p) = 0$, and we compute

$$\begin{aligned} [(X, 0), (0, Y)](f)(p, q) &= (X, 0)(0, Y)(f)(p, q) - (0, Y)(X, 0)(f)(p, q) \\ &= (X(p), 0) \left(y_i(q) \frac{\partial f}{\partial y_i}(p, q) \right) - (0, Y(q)) \left(x_j(p) \frac{\partial f}{\partial x_j}(p, q) \right) \\ &= x_j(p) y_i(q) \frac{\partial^2 f}{\partial x_j \partial y_i} - y_i(q) x_j(p) \frac{\partial^2 f}{\partial y_i \partial x_j}(p, q) \\ &= 0. \end{aligned}$$

Finally, we compute

$$\begin{aligned} R((X, 0), (0, Y))(X, 0) &= \nabla_{(0, Y)} \nabla_{(X, 0)}(X, 0) - \nabla_{(X, 0)} \nabla_{(0, Y)}(X, 0) - \nabla_{[(X, 0), (0, Y)]}(X, 0) \\ &= \nabla_{(0, Y)}(\nabla_X^1 X, 0) - \nabla_{(X, 0)}(\nabla_0^1 X + \nabla_Y^2 0) - 0 \\ &= 0. \end{aligned}$$

□

Problem (6.2). Show that $x : \mathbb{R}^2 \rightarrow \mathbb{R}^4$ given by

$$x(\theta, \phi) = \frac{1}{\sqrt{2}}(\cos \theta, \sin \theta, \cos \phi, \sin \phi), \quad (\theta, \phi) \in \mathbb{R}^2,$$

is an immersion of \mathbb{R}^2 into the unit sphere $S^3 \subset \mathbb{R}^4$, whose image $x(\mathbb{R}^2)$ is a torus T^2 with sectional curvature zero in the induced metric.

Proof. Using the Euclidean metric of \mathbb{R}^4 , clearly for any $(\theta, \phi) \in \mathbb{R}^2$,

$$\|x(\theta, \phi)\|^2 = \frac{1}{2}(1 + 1) = 1.$$

Hence x maps into S^3 . The Jacobian is

$$dx_{(\theta, \phi)} = \left(\frac{\partial x}{\partial \theta} \quad \frac{\partial x}{\partial \phi} \right) = \frac{1}{\sqrt{2}} \begin{pmatrix} -\sin \theta & 0 \\ \cos \theta & 0 \\ 0 & -\sin \phi \\ 0 & \cos \phi \end{pmatrix}.$$

Since \sin, \cos cannot be simultaneously zero, the rank of the Jacobian is always 2, showing that x is an immersion.

The metric tensor is

$$G = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

Since curvature $R_{kij\ell}$ is just the second derivative of g_{ij} per Riemann's habilitation, since g_{ij} is constant, curvature must be zero. So is the sectional curvature. Alternatively, since $T^2 = S^1 \times S^1$ is a 2-dimensional product manifold, any 2-dimensional plane of the tangent space is the whole tangent space, and one vector from each TS^1 would give zero sectional curvature by Problem 1 (c). \square

Problem (6.3). Let M be a Riemannian manifold and let $N \subset K \subset M$ be submanifolds of M . Suppose that N is totally geodesic in K and that K is totally geodesic in M . Prove that N is totally geodesic in M .

Proof. Given $p \in N$ and a geodesic γ of N emanating from p , since N is totally geodesic in K , then γ is also a geodesic of K emanating from p . But since K is totally geodesic in M , γ is then a geodesic of M emanating from p . Thus N is totally geodesic in M . \square

Problem (6.7). Show that if M is a totally geodesic submanifold of \overline{M} , then for any tangent fields to M , ∇ and $\overline{\nabla}$ coincide.

Proof. Since M is totally geodesic in \overline{M} , by definition $H_\eta(X, Y) = \langle B(X, Y), \eta \rangle = 0$ for any tangent fields X, Y and normal field η . This implies that $B(X, Y) \in TM$ by definition of orthogonality. However, by definition $B(X, Y) \in TM^\perp$. This forces $B(X, Y) \equiv 0$ since the only common vector field of orthogonal bundles are the zero vector field. This implies $\nabla_X Y = \overline{\nabla}_X Y$. \square

Problem (6.8). (The Clifford torus). Consider the immersion x given in Problem 2.

- (a) Show that the vectors $e_1 = (-\sin \theta, \cos \theta, 0, 0)$, $e_2 = (0, 0, -\sin \phi, \cos \phi)$ form an orthonormal basis of the tangent space, and that the vectors $n_1 = \frac{1}{\sqrt{2}}(\cos \theta, \sin \theta, \cos \phi, \sin \phi)$, $n_2 = \frac{1}{\sqrt{2}}(-\cos \theta, -\sin \theta, \cos \phi, \sin \phi)$ for an orthonormal basis of the normal space.

(b) Use the fact that

$$\langle S_{n_k}(e_i), e_j \rangle = - \langle \bar{\nabla}_{e_i} n_k, e_j \rangle = \langle \bar{\nabla}_{e_i} e_j, n_k \rangle,$$

where $\bar{\nabla}$ is the covariant derivative (the usual derivative) of \mathbb{R}^4 , and $i, j, k = 1, 2$, to establish that the matrices of S_{n_1} and S_{n_2} with respect to the basis $\{e_1, e_2\}$ are

$$S_{n_1} = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$S_{n_2} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

(c) From Problem 2, x is an immersion of the torus T^2

into S^3 . Show that x is a minimal immersion.

Proof. (a) Since metric is the Euclidean metric in \mathbb{R}^4 , orthogonality and unit length are trivial to check. We know e_1, e_2 form a basis of tangent space because they are scalar multiples of basis $\frac{\partial x}{\partial \theta}$ and $\frac{\partial x}{\partial \phi}$.

(b) We compute

$$\bar{\nabla}_{e_1} e_1 = 2 \frac{\partial x}{\partial \theta} \frac{\partial x}{\partial \theta} = 2 \frac{\partial^2 x}{\partial \theta^2} = \sqrt{2}(-\cos \theta, -\sin \theta, 0, 0),$$

$$\bar{\nabla}_{e_1} e_2 = 2 \frac{\partial^2 x}{\partial \theta \partial \phi} = 0$$

$$\bar{\nabla}_{e_2} e_2 = 2 \frac{\partial^2 x}{\partial \phi^2} = \sqrt{2}(0, 0, -\cos \phi, -\sin \phi).$$

Therefore, we obtain

$$S_{n_1} = \begin{pmatrix} \langle \bar{\nabla}_{e_1} e_1, n_1 \rangle & 0 \\ 0 & \langle \bar{\nabla}_{e_2} e_2, n_1 \rangle \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$S_{n_2} = \begin{pmatrix} \langle \bar{\nabla}_{e_1} e_1, n_2 \rangle & 0 \\ 0 & \langle \bar{\nabla}_{e_2} e_2, n_2 \rangle \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

(c) We claim that the normal space of T_2 in S^3 is spanned by n_2 . Since $x(\theta, \phi) \in S^3$, any tangent vector on S^3 needs to be orthogonal to $x(\theta, \phi)$. We see that $\langle n_2, x(\theta, \phi) \rangle = 0$, showing that n_2 is a tangent vector on S^3 . Since n_2 is orthogonal to e_1, e_2 , and the

three of them form a basis for the tangent space on S^3 , we conclude that n_2 spans the normal space.

Therefore, since $\text{tr } S_{n_2} = 0$, we have $\text{tr } S_\eta = 0$ for all η in the normal space of T_2 in S^3 . Hence, x is a minimal immersion.

□