

Homework 3

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Problem (LN12 0.1.1). Show that the antipodal reflection $a : S^n \rightarrow S^n$, $a(x) = -x$ is an isometry.

Proof. The antipodal reflection is clearly smooth and has itself as the smooth inverse, and therefore is a diffeomorphism. For any $p \in S^n$, $v \in T_p S^n$, and any smooth curve $\gamma : (-\varepsilon, \varepsilon) \rightarrow S^n$ s.t. $\gamma(0) = p$, $\gamma'(0) = v$, its derivative is

$$\begin{aligned} da_p(v) &= (a \circ \gamma)'(0) \\ &= (-\gamma)'(0) \\ &= -\gamma'(0) \\ &= -v. \end{aligned}$$

For any Riemannian metric g on S^n and any $p \in S^n$, we have

$$\begin{aligned} g_p(da_p(v), da_p(w)) &= g_p(-v, -w) \\ &= -g_p(v, -w) && \text{bilinearity} \\ &= g_p(v, w), \end{aligned}$$

which proves that it is an isometry. □

Problem (LN12 0.2.1). Show that inversion $i : \mathbb{R}^n \setminus \{0\} \rightarrow \mathbb{R}^n$ given by $i(x) = \frac{x}{\|x\|^2}$ is a conformal transformation.

Proof. Let $M = \mathbb{R}^n \setminus \{0\}$. Given $p \in M$, $v \in T_p M$, and $\gamma : (-\varepsilon, \varepsilon) \rightarrow M$ s.t. $\gamma(0) = p$ and $\gamma'(0) = v$, we compute the derivative at p :

$$\begin{aligned} di_p(v) &= (i \circ \gamma)'(0) \\ &= \left(\frac{\gamma}{\|\gamma\|^2} \right)'(0) \\ &= \left(\frac{\gamma' \|\gamma\|^2 - 2\gamma \langle \gamma, \gamma' \rangle}{\|\gamma\|^4} \right)(0) && \text{quotient rule} \end{aligned}$$

$$= \frac{\|p\|^2 v - 2p\langle p, v \rangle}{\|p\|^4}.$$

Given $v, w \in T_p M$, we have

$$\begin{aligned} g_p(di_p(v), di_p(w)) &= \left\langle \frac{\|p\|^2 v - 2p\langle p, v \rangle}{\|p\|^4}, \frac{\|p\|^2 w - 2p\langle p, w \rangle}{\|p\|^4} \right\rangle \\ &= \frac{\langle v, w \rangle}{\|p\|^4} - \frac{4v^T p p^T w}{\|p\|^6} + \frac{4v^T p (p^T p) p^T w}{\|p\|^8} \\ &= \frac{\langle v, w \rangle}{\|p\|^4} - \frac{4v^T p p^T w}{\|p\|^6} + \frac{4v^T p p^T w}{\|p\|^6} \\ &= \frac{\langle v, w \rangle}{\|p\|^4}. \end{aligned}$$

Then the angle $\theta(di_p(v), di_p(w))$ between $di_p(v), di_p(w)$ is

$$\begin{aligned} \theta(di_p(v), di_p(w)) &= \arccos \left(\frac{g_p(di_p(v), di_p(w))}{g_p(di_p(v), di_p(v))^{\frac{1}{2}} g_p(di_p(w), di_p(w))^{\frac{1}{2}}} \right) \\ &= \arccos \left(\frac{\frac{\langle v, w \rangle}{\|p\|^4}}{\frac{\|v\| \|w\|}{\|p\|^4}} \right) \\ &= \arccos \left(\frac{\langle v, w \rangle}{\|v\| \|w\|} \right) \\ &= \arccos \left(\frac{g_p(v, w)}{g_p(v, v)^{\frac{1}{2}} g_p(w, w)^{\frac{1}{2}}} \right) \\ &= \theta(v, w). \end{aligned}$$

That is, i is conformal. □

Problem (LN12 0.2.3). Show that the Poincaré half-plane and disk are isometric.

Proof. Translating the half-plane up by 1 to get $H = \{(x, y) \in \mathbb{R}^2 : y > 1\}$ is clearly an isometry. Let $D = \{(x, y) : x^2 + (y - 0.5)^2 < 0.25\}$ be the open disk centered at $(0, 0.5)$ with radius 0.5. Inversion is a composition of smooth maps and thus smooth. First we show that the inversion map is a diffeomorphism between H and D . Given $p = (x, y) \in H$, observe

$$\begin{aligned} \left\| \frac{p}{\|p\|^2} - \begin{pmatrix} 0 \\ \frac{1}{2} \end{pmatrix} \right\|^2 &= \left\| \begin{pmatrix} \frac{x}{x^2 + y^2} \\ \frac{2y - (x^2 + y^2)}{2(x^2 + y^2)} \end{pmatrix} \right\|^2 \\ &= \frac{4x^2 + 4y^2 - 4(x^2 + y^2)y + (x^2 + y^2)^2}{4(x^2 + y^2)^2} \end{aligned}$$

$$\begin{aligned}
&= \frac{1}{4} + 4(x^2 + y^2)(1 - y) \\
&< \frac{1}{4}
\end{aligned}$$

since $y > 1$. Thus the restricted inversion $i : H \rightarrow D$ is well-defined and remains smooth. I claim that its inverse is itself, which we name $j : D \rightarrow H$ due to differences in domain and codomain. We check j is well-defined: if we have $p = (x, y) \in D$, then

$$\begin{aligned}
x^2 + (y - 0.5)^2 &= x^2 + y^2 - y + \frac{1}{4} < \frac{1}{4} \\
y &> x^2 + y^2 \\
\frac{y}{x^2 + y^2} &> 1 & p \neq 0 \\
y_{j(p)} &> 1.
\end{aligned}$$

Since it is clear that $i \circ j(p) = j \circ i(p) = p$, inversion is a diffeomorphism. Now endow H and D with the modified metrics g and h respectively, where $g_p(v, w) = \frac{\langle v, w \rangle}{(y-1)^2}$ and $h_p(v, w) = \frac{\langle v, w \rangle}{(0.25 - \|p - (0, 0.5)\|^2)^2}$ due to the translation and scaling of the plane and disk. We observe

$$\begin{aligned}
h_{i(p)}(di_p(v), di_p(w)) &= \frac{\langle di_p(v), di_p(w) \rangle}{(0.25 - \|i(p) - (0, 0.5)\|^2)^2} \\
&= \frac{\langle v, w \rangle}{\|p\|^4 (0.25 - \|\frac{p}{\|p\|^2} - (0, 0.5)\|^2)^2} \\
&= \frac{\langle v, w \rangle}{\|p\|^4 \left(0.25 - \frac{1-y}{\|p\|^2} - 0.25\right)^2} \\
&= \frac{\langle v, w \rangle}{(y-1)^2} \\
&= g_p(v, w).
\end{aligned}$$

Hence (H, g) and (D, h) are isometric. □

Problem (LN12 0.3.1). Compute the metric of S^2 in terms of spherical coordinates θ and ϕ .

The parametric equation is $f(\theta, \phi) = (\cos \theta \sin \phi, \sin \theta \sin \phi, \cos \phi)$. Then

$$\frac{\partial f}{\partial \theta} = (-\sin \theta \sin \phi, \cos \theta \sin \phi, 0)$$

$$\frac{\partial f}{\partial \phi} = (\cos \theta \cos \phi, \sin \theta \cos \phi, -\sin \phi).$$

Since S^2 is endowed with the ambience Euclidean metric $\langle \cdot, \cdot \rangle$, the pullback metric on the parameter space is $g_{ij} = \langle \frac{\partial f}{\partial x_i}, \frac{\partial f}{\partial x_j} \rangle$, which is

$$\begin{aligned} G(\theta, \phi) &= \begin{pmatrix} \sin^2 \theta \sin^2 \phi + \cos^2 \theta \sin^2 \phi & 0 \\ 0 & \cos^2 \theta \cos^2 \theta + \sin^2 \theta \cos^2 \phi + \sin^2 \phi \end{pmatrix} \\ &= \begin{pmatrix} \sin^2 \phi & 0 \\ 0 & 1 \end{pmatrix}. \end{aligned}$$

Problem (LN12 0.4.1). Compute the length of the radius of the Poincaré disk (with respect to the Poincaré metric).

Consider the unit open disk D with the metric $g_p(v, w) = \frac{\langle v, w \rangle}{(1 - \|p\|^2)^2}$ and the curve $\gamma : [0, 1) \rightarrow D, t \mapsto (0, t)$ which traces out the radius. Then

$$\begin{aligned} L[\gamma] &= \int_0^1 g_{\gamma(t)}(\gamma'(t), \gamma'(t))^{\frac{1}{2}} dt \\ &= \int_0^1 g_{\gamma(t)}((0, 1), (0, 1))^{\frac{1}{2}} dt \\ &= \int_0^1 \frac{1}{1 - \|(0, t)\|^2} dt \\ &= \int_0^1 \frac{1}{1 - t^2} dt \\ &= \int_0^1 \frac{dt}{1 - t} + \int_0^1 \frac{dt}{1 + t} \\ &= (\ln |1 - t| + \ln |1 + t|) \Big|_0^1, \end{aligned}$$

which diverges. Thus loosely speaking, the radius is infinite.