

# Homework 7

Jaden Wang

**Problem** (do Carmo 3.8). Let  $M$  be a Riemannian manifold. Let  $X \in \mathfrak{X}(M)$  and  $f \in \mathcal{D}(M)$ . Define the divergence of  $X$  as a function  $\operatorname{div} X(p) = \text{trace of the linear map } Y(p) \rightarrow \nabla_Y X(p), p \in M$ , and the gradient of  $f$  as a vector field  $\operatorname{grad} f$  on  $M$  defined by

$$\langle \operatorname{grad} f(p), v \rangle = df_p(v), \quad p \in M, \quad v \in T_p M$$

(a) Let  $E_i$  be a geodesic frame at  $p \in M$ . Show that

$$\operatorname{grad} f(p) = \sum_{i=1}^n (E_i(f)) E_i(p),$$

and

$$\operatorname{div} X(p) = \sum_{i=1}^n E_i(f_i)(p),$$

where  $X = f^i E_i$ .

(b) Let  $M = \mathbb{R}^n$ , with coordinates  $(x_1, \dots, x_n)$  and  $\frac{\partial}{\partial x_i} = (0, \dots, 1, \dots, 0) = e_i$ . Show that

$$\operatorname{grad} f = \sum_{i=1}^n \frac{\partial f}{\partial x_i} e_i,$$

$\operatorname{div} X = \sum_{i=1}^n \frac{\partial f_i}{\partial x_i}$ , where  $X = f^i e_i$ .

*Proof.* (a) Recall that a geodesic frame Write  $v = v^i E_i(p)$ . Then

$$\begin{aligned} df_p(v) &= df_p(v^i E_i(p)) \\ &= v^i df_p(E_i(p)) && \text{linear map} \\ &= v^i \frac{\partial f}{\partial x_i}(p) \\ &= v^i E_i(f)(p) \\ &= \langle E_i(f) E_i(p), v^i E_i(p) \rangle \\ &= \langle \operatorname{grad} f, v \rangle. \end{aligned}$$

Thus  $\operatorname{grad} f = E^i(f) E_i(p)$ .

Recall that trace of a linear map  $L$  is defined as  $\text{tr } L := \sum_{i=1}^n \langle L(E_i), E_i \rangle$ .

$$\begin{aligned}
\text{div } X(p) &= \text{div} \left( f^i E_i \right) (p) \\
&= \sum_{j=1}^n \langle \nabla_{E_j} \left( f^i E_i \right) (p), E_j(p) \rangle \\
&= \sum_{j=1}^n \langle E_j(f^i) E_i(p) + f^i \nabla_{E_j} E_i(p), E_j(p) \rangle \\
&= \sum_{j=1}^n \langle E_j(f^i) E_i(p) + 0, E_j(p) \rangle && \text{geodesic frame} \\
&= E_i(f^i)(p).
\end{aligned}$$

(b) This is immediate.

$$\begin{aligned}
\text{grad } f(p) &= e^i(f) e_i(p) \\
&= \frac{\partial f}{\partial x_i} e_i.
\end{aligned}$$

$$\begin{aligned}
\text{div } X(p) &= E_i(f^i)(p) \\
&= \frac{\partial f^i}{\partial x_i}.
\end{aligned}$$

□

**Problem** (do Carmo 3.9). Let  $M$  be a Riemannian manifold. Define the Laplacian  $\Delta : \mathcal{D}(M) \rightarrow \mathcal{D}(M)$  of  $M$  by

$$\Delta f = \text{div grad } f, \quad f \in \mathcal{D}(M).$$

(a) Let  $E_i$  be a geodesic frame at  $p \in M$ . Prove that

$$\Delta f(p) = E_i(E^i(f))(p).$$

Conclude that if  $M = \mathbb{R}^n$ ,  $\Delta$  coincides with the usual Laplacian, namely  $\Delta f = \sum_i \frac{\partial^2 f}{\partial x_i^2}$ .

(b) Show that

$$\Delta(f \cdot g) = f \Delta g + g \Delta f + 2 \langle \text{grad } f, \text{grad } g \rangle.$$

*Proof.* (a) This is immediate from previous problem. Since  $\text{grad } f = E^i(f)E_i$ ,

$$\begin{aligned}\Delta f(p) &= \text{div}(E^i(f)E_i)(p) \\ &= E_i(E^i(f))(p).\end{aligned}$$

If  $M = \mathbb{R}^n$ , then

$$\Delta f = E_i(E^i(f)) = E_i\left(\frac{\partial f}{\partial x^i}\right) = \sum_i \frac{\partial^2 f}{\partial x_i^2}.$$

(b) First we compute

$$\langle \text{grad } f, \text{grad } g \rangle = \langle E^i(f)E_i, E^i(g)E_i \rangle = E^i(f)E_i(g).$$

It follows that

$$\begin{aligned}\Delta(f \cdot g) &= E_i(E^i(f \cdot g)) \\ &= E_i(E^i(f)g + fE^i(g)) && \text{Leibniz rule of derivation} \\ &= E_i(E^i(f))g + E^i(f)E_i(g) + E_i(f)E^i(g) + fE_i(E^i(g)) \\ &= g\Delta f + 2\langle \text{grad } f, \text{grad } g \rangle + f\Delta g.\end{aligned}$$

□

**Problem** (do Carmo 3.10). Let  $f : I \times [0, a] \rightarrow M$  be a parametrized surface such that for all  $t_0 \in [0, a]$ , the curve  $s \rightarrow f(s, t_0), s \in [0, 1]$  is a geodesic parametrized by arc length, which is orthogonal to the curve  $t \rightarrow f(0, t), t \in [0, a]$ , at the point  $f(0, t_0)$ . Prove that, for all  $(s_0, t_0) \in I \times [0, a]$ , the curves  $s \rightarrow f(s, t_0), t \rightarrow f(s_0, t)$  are orthogonal.

*Proof.* We want to show that  $\langle \frac{\partial f}{\partial s}, \frac{\partial f}{\partial t} \rangle \equiv 0$ . Since we already know that  $\langle \frac{\partial f}{\partial s} \Big|_{(0, t_0)}, \frac{\partial f}{\partial t} \Big|_{(0, t_0)} \rangle = 0$  for any  $t_0 \in [0, a]$ , it suffices to show that the inner product is constant as we vary  $s$ , *i.e.* it has 0 derivative wrt  $s$ . We compute

$$\begin{aligned}\frac{\partial}{\partial s} \left\langle \frac{\partial f}{\partial s}, \frac{\partial f}{\partial t} \right\rangle &= \left\langle \frac{D}{\partial s} \frac{\partial f}{\partial s}, \frac{\partial f}{\partial t} \right\rangle + \left\langle \frac{\partial f}{\partial s}, \frac{D}{\partial s} \frac{\partial f}{\partial t} \right\rangle && \text{Leibniz rule} \\ &= \left\langle \frac{D}{\partial s} \frac{\partial f}{\partial s}, \frac{\partial f}{\partial t} \right\rangle + \left\langle \frac{\partial f}{\partial s}, \frac{D}{\partial t} \frac{\partial f}{\partial s} \right\rangle && \text{symmetry lemma} \\ &= \left\langle 0, \frac{\partial f}{\partial t} \right\rangle + \left\langle \frac{\partial f}{\partial s}, \frac{D}{\partial t} \frac{\partial f}{\partial s} \right\rangle && \text{geodesic along } s\end{aligned}$$

$$\begin{aligned}
&= \frac{1}{2} \frac{\partial}{\partial t} \left\langle \frac{\partial f}{\partial s}, \frac{\partial f}{\partial s} \right\rangle \\
&= 0.
\end{aligned}$$

□