```
\begin{array}{l} \delta > \\ \bar{\rho} \\ \bar{\rho} = \\ \bar{\rho} (1 + \\ \delta) \\ \Omega_0 = \\ \Omega_{m,0} = \\ 1 \end{array}
               \frac{1}{r}
M

\begin{array}{l}
M \\
\pi r^3 \\
\overline{3\overline{\rho}(1+\delta)}. \\
M(r) \\
\xi = \\
\frac{1}{2}(rt)^2 - \\
\underline{GM} \\
\tau \\
0 < 0 \\
\xi < 0 \\
0 \\
\cos \theta)t = 
\end{array}

               \cos \theta t =
\begin{array}{l} B(\theta\overset{-}{-}\\ \sin\theta)A = \\ \frac{GM}{2\epsilon}B = \\ \frac{2\epsilon_M}{2\epsilon_M}\\ \frac{2\epsilon_M}{(2\epsilon)^{3/2}}\\ r(t)\\ r_{ta} = \\ 2A\\ t_{ta} = \\ \pi B\\ t_{coll} = \\ 2t_{ta}\\ t_{coll} = \\ 2t_{ta}\\ t_{coll}\\ t_{col
                     B(\theta -

\begin{array}{l}
t \in \mathcal{X} \\
\rho(t) \\
t_i = \\
y_i = \\
t_i
\end{array}

          t_{i}
                          (ax_i)t =
               \overset{\cdot }{\underset{ax}{axi}} \overset{\cdot }{\underset{nopeculiarvelocity}{andr}} = \overset{\cdot }{\underset{ax}{axi}} \overset{\cdot }{\underset{nopeculiarvelocity}{andr}} = \overset{\cdot }{\underset{ax}{axi}} \overset{\cdot }{\underset{nopeculiarvelocity}{andr}} = \overset{\cdot }{\underset{ax}{axi}} \overset{\cdot }{\underset{nopeculiarvelocity}{andr}} = \overset{\cdot }{\underset{ax}{axi}} \overset{\cdot }{\underset{nopeculiarvelocity}{andr}} = \overset{\cdot }{\underset{ax}{axi}} \overset{\cdot }{\underset{nopeculiarvelocity}{andr}} = \overset{\cdot }{\underset{ax}{axi}} \overset{\cdot }{\underset{nopeculiarvelocity}{andr}} = \overset{\cdot }{\underset{ax}{axi}} \overset{\cdot }{\underset{nopeculiarvelocity}{andr}} = \overset{\cdot }{\underset{nopec
          \overline{\overline{H}}r_i.H = \dot{a}/a
t = t_i

\overline{3\bar{\rho}(t_i)(1+\delta_i),\epsilon=\frac{v_i^2}{2}-\frac{GM}{r_i}}.

               \begin{array}{l} a \propto \\ \frac{a}{t^{2/3}} \times \\ H = \\ \frac{2}{(3t)} \times \\ \rho = \\ \frac{e}{\rho_{crit}} = \\ \frac{e}{6\pi G t^2} \times \\ \frac{B}{10^{r_i}} \times \\ \frac{e}{\rho_{crit}} \times \\ \frac{e}{\rho_{crit

\frac{B}{10\frac{r_i}{\delta_i}, B = \frac{9}{20}\frac{t_i}{\delta_i}}.

\rho \stackrel{M}{=} \frac{M}{\frac{4\pi}{4\pi}r^3} = \frac{\frac{3M}{4\pi A^3}(1 - \cos\theta)^{-3}becauser = \frac{4}{4}
                     A(1-
               \cos \theta),

\frac{\bar{\rho}}{\bar{\rho}} = \frac{1}{6\pi G t^2} = \frac{1}{6\pi G B^2} (\theta - \sin \theta)^{-2} becauset = B(\theta - \cos \theta)

               \sin \theta).
               \frac{\delta}{\frac{\rho}{\bar{\rho}}} =
\frac{\rho}{2} \frac{\theta - \sin \theta}{(1 - \cos \theta)^3}.
\rho(t)
```

 $\begin{array}{c}
\rho(\theta) \\
t < < \\
t_{ta}
\end{array}$