```
\hat{x}(\mathbf{t})
               x_3(\tau_1,\tau_2)
             S' = \begin{bmatrix} (7_1, 7_2) \\ (7_1, 7_2) \end{bmatrix}
S' = \begin{bmatrix} -(N - 1), \dots, N - 1 \end{bmatrix} \times
               \begin{bmatrix} -(N-1), \cdots, N-1 \end{bmatrix}
               1
               x(\mathbf{t})
               \begin{array}{c} x_3(\tau_1, \tau_2) \\ W(\tau_1, \tau_2) \end{array}
               (\tau_1, \tau_2) \atop K(\tau_1, \tau_2)
             W(\tau_1, \tau_2)
K(\tau_1, \tau_2)
C(\tau_1, \tau_2)
C(\tau_1, \tau_2)
C(\tau_1, \tau_2)
               (\tau_1, \tau_2)

(\tau_1', \tau_2')

C(\tau_1, \tau_2)

C(\tau_1', \tau_2')
             C(\tau_{1}', \tau_{2}')
(\tau_{1}, \tau_{2})
(\tau_{1}', \tau_{2}')
??
C(\tau_{1}, \tau_{2})
\tau_{1}^{1} = [1, 0]
\tau_{2}^{0} [1, 0] \times [0, \infty]
C(\tau_{1}, \tau_{2})
x(\mathbf{t})
               x(\mathbf{t})
               C(	au_1,	au_2)
               \tilde{x_3}(\rho,\phi;\tau_1,\tau_2)x_3(\mathbf{T}_{\beta,\phi}\tau_1,\mathbf{T}_{\beta,\phi}\tau_2)
(1) \mathbf{T}_{\beta,\phi} = \beta \cos \phi - \sin \phi \sin \phi \cos \phi \rho = \log \beta
              C(	au_1,	au_2)
               \phi
               \overset{'}{y}(\mathbf{t}) =
               x(\mathbf{T}_{\alpha,\theta}\mathbf{t} +
             C(\tau_1, \tau_2)
               \tilde{y_3}(\rho,\phi;\tau_1,\tau_2) = \tilde{x_3}(\rho + \log \alpha, \phi + \theta;\tau_1,\tau_2)
             \tilde{x_3}
\begin{array}{c} \tilde{x_3} \\ \rho \phi \\ \tilde{X_3}(P, \Phi; \tau_1, \tau_2) \end{array}
               \tilde{X}_3(P,\Phi;\tau_1,\tau_2)
               \tilde{X}_3(0,0;\tau_1,\tau_2)
               \begin{array}{l} \tau_3(0,0,1) \\ (\tau_1,\tau_2) \\ \tau_1 = \\ [\tau_{1x},\tau_{1y}] \\ \tau_2 = \end{array}
               \begin{array}{l} \tau_{2} - \\ [\tau_{2x}, \tau_{2y}] \\ (\tau_{1}, \tau_{2}) = \\ (\tau_{0}, [k, l]), k \in \\ [0, 1], l \in \end{array}
                 [0,\infty]
                 (	au_1, 	au_2) =
                \begin{aligned} & (\tau_1, \tau_2) = \\ & (\tau_0, \tau_2) \to \\ & (\theta_1, \theta_2), \theta_1, \theta_2 \in \\ & [0, \pi 2] \\ & (\tau_1, \tau_2) = \\ & (\tau_0, \tau_2) \to \\ & (\theta_1, \lambda), \theta_1 \in \\ & [0, \pi 2], \lambda \in \\ & [0, \infty] \end{aligned} 
               \begin{bmatrix} 0, \infty \\ \tau_0 = \\ (1, 0) \\ \theta_1, \theta_2 \end{bmatrix}
```