

Hunting Effect on Individual Deer Stress Level

P15.2 Fortgeschrittenes Praxisprojekt

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Table of contents

Abstract	3
1 Introduction	3
1.1 Background	3
1.2 Data Generating Process	3
1.3 Research Question	3
2 Data Analysis	4
2.1 Hunting Events	4
2.2 Movement Data	4
2.3 Faecal Sample Data	5
2.4 Reproduction Data	5
3 Data Preprocessing	5
3.1 Filtering	6
3.2 Uncertainties	7
4 Model Selection	7
4.1 Statistical modeling approach	7
4.2 Machine learning approach	8
5 Model Evaluation	9
5.1 GAMMs	9
5.2 XGBoost	9
6 Conclusion & Outlook	10
Acknowledgements	10
References	11
7 Appendix	12
7.1 Reproduction data	12
7.2 GAMM	12
7.3 XGBoost	13

Abstract

Hunting activity has an impact on animal populations through removal of individuals. Moreover, it may have a non-lethal effect of inducing stress. In this project, we analyze the short-term stress response of red deer in the Bavarian Forest National Park to hunting events. The stress level of a deer was measured by the concentration of faecal cortisol metabolites (FCMs) in faecal samples. Combining spatiotemporal information about the faecal samples, the deer which produced them, and the hunting events occurred in the time period of sample collection, we aim to address how the FCM level in a deer's faecal matter is associated with the temporal and spatial distance to a hunting event that could have affected the deer.

1 Introduction

1.1 Background

Apart from the change in populations size, the effects of hunting on wildlife have so far been studied mainly on the basis of behavioral changes. This project aims to investigate the physiological stress response in red deer using a non-invasive method, the measurement of FCMs.

1.2 Data Generating Process

The data for the project origins in the *Bavarian Forest National Park*. Its location is highlighted in green in Figure 1. Within and on the borders of this area, red deer roam freely. Some of these deer have been collared with a GPS-device, which helps to track the movement. At some time, a *hunting event* happens and the deer experiences some amount of stress. Later, the deer defecates (*defecation event*). Subsequently, researchers visit the defecation location and collect a *faecal sample*.

Stress is expected to be higher in proximity¹ to hunting events. With higher stress, FCM values are expected to be higher. Huber et al. (2003) showed (Figure 2)

¹this includes temporal and spatial proximity



Figure 1: Location of Bavarian Forest National Park

that the FCM levels peak between 16 and 19 hours after a stress event (called “challenge”). Additionally we expect, that FCM levels are lower, the more time passes between defecation and sampling.

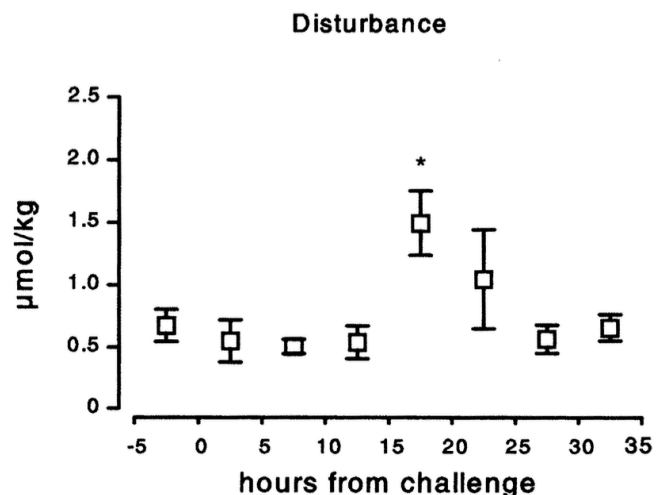


Figure 2: FCM levels over time

1.3 Research Question

Therefore our research question is two-fold:

- assess the effect of temporal and spatial distance on FCM level
- assess if the time between defecation event and sample collection affect the FCM levels

2 Data Analysis

We were provided with four distinct datasets. In the following subchapters we are going to describe the main features of each data set and address any anomalies.

2.1 Hunting Events

The dataset contains the location and time of 697 individual hunting events, spanning from 2020 to 2022. There are three main challenges:

- Just 519 of these 697 events have a complete timestamp, consisting of date and time of day. The remainder of 178 events only reported the date of the event.
- The events are not represented as a period of time, but as a single moment in time. Additionally, as shown in Figure 3, there appears to be seasonality in the occurrence of hunts.
- Similarly to ii), the events are only associated with a single spatial point. The locations of the events with complete timestamps are illustrated in Figure 4.

2.2 Movement Data

There are 40 collared deers which movements have been tracked completely or partially between February 2020 and February 2023. Some collars stopped working before the end-date, some deers got collared within the timespan of interest. The location of each individual deer is tracked on an hourly basis. The movement of four randomly selected deer is visualised in Figure 5. During the winter months, the deers roam in one of four enclosures within the national park.

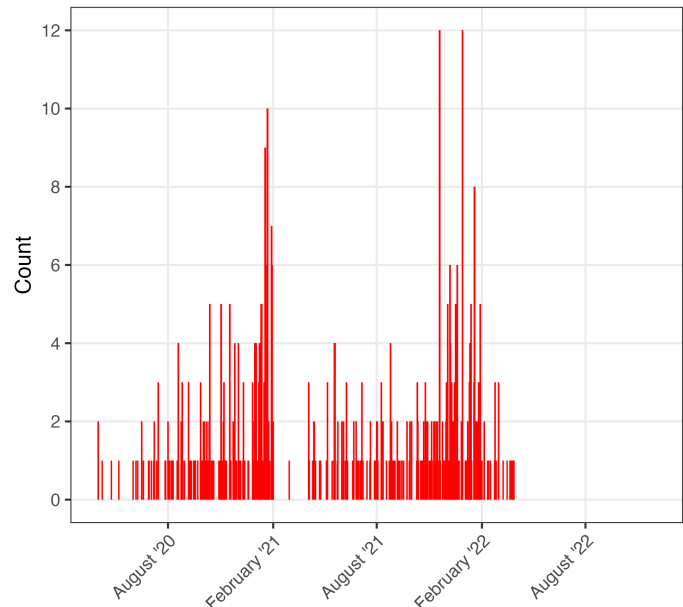


Figure 3: Hunts - Daily Count

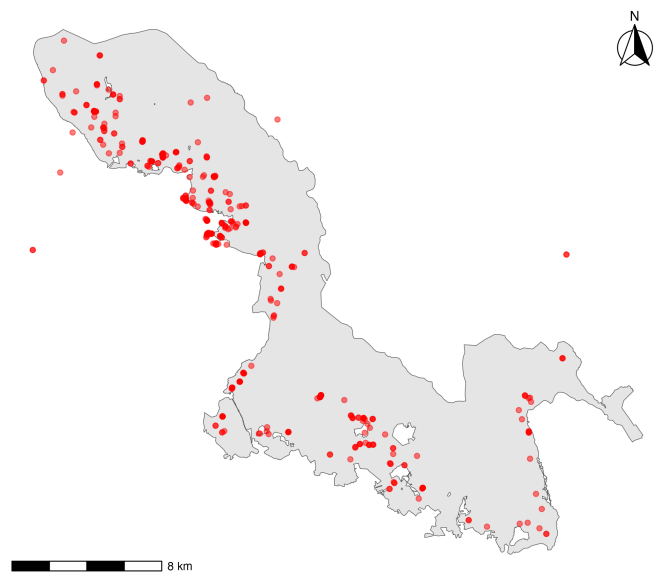


Figure 4: Hunts - Locations

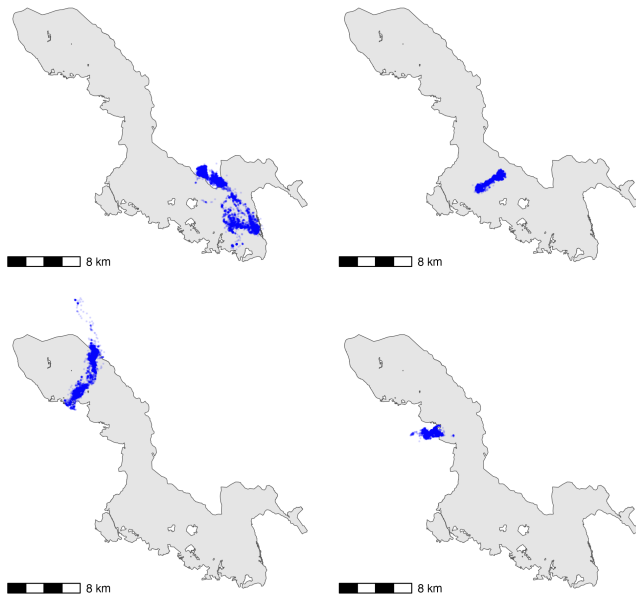


Figure 5: Deers - Locations of four Deer

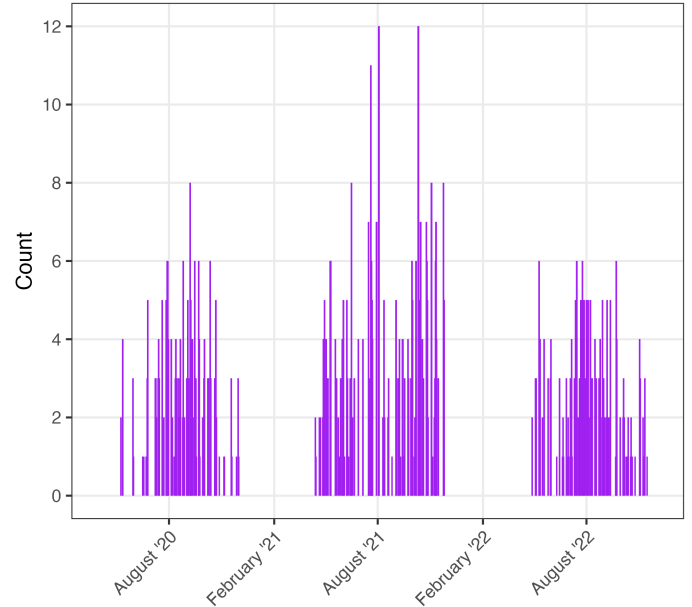


Figure 6: Samples - Daily Count

2.3 Faecal Sample Data

The faecal sample dataset contains information on 809 faecal samples. Most importantly, the FCM-level (in nanograms per gram [ng/g]), the location of the sample, as shown in Figure 7, the associated collared deer, the approximate time of defecation and the time of sampling. The samples were taken at irregular intervals, but with obvious seasonality (see Figure 6) from 2020 to 2022.

2.4 Reproduction Data

The reproduction data contains reproduction information on some of the deers. It has not been used in our analysis and modelling approach, for the reasons see Section 7.1.

3 Data Preprocessing

The datasets undergo preprocessing steps to facilitate analysis and modelling:

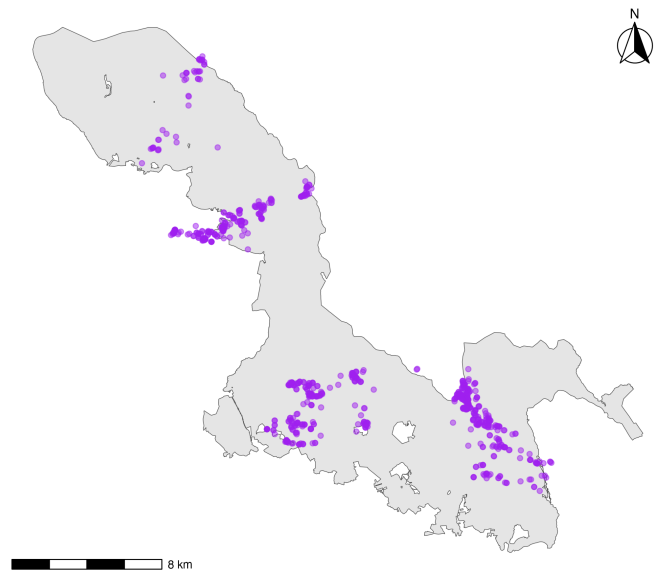


Figure 7: Samples - Locations

- Conversion of Timestamps and Coordinates to a uniform format
- Removal of entries with missing values (especially timestamps), zeros, or highly implausible data

Each FCM sample gets associated with all hunting events occurring before the sample was produced. The resulting dataset contains samples linked to all prior hunting events, creating multiple pairings per sample.

3.1 Filtering

A hunting event and a deer are separated by both space and time. Therefore we define the essential covariates to be:

- Time Difference* between the hunting event and the subsequent defecation
- Spatial Distance* between a deer and the hunting event at the exact time of the event

Additionally we identify other covariates:

- Time Difference between defecation and sampling (*Sample Delay*)
- day of year [1-365] (*Defecation Day*)
- Number of hunts a deer experiences before defecation (*Number of Other Hunts*)

As each sample is associated with one or more hunting event, the main challenge is to identify the most relevant hunting event. We propose three different criterions to identify which hunting event is the most relevant one:

- Closest in time*: Choosing the hunting event, which happened closest to 19 hours prior to the defecation event. This takes the findings of Huber et al. (2003) into account, that cortisol metabolite concentrations peak around 19 hours post-stress event (see Figure 2).
- Nearest*: Choosing the observation with the shortest spatial distance between the hunting event and the deer's interpolated position at the time of the hunting event.

- Highest score*: Introducing a scoring function to consider both spatial and temporal distance. We designed a score proportional to the inverse square of the distance and a “spike” function based on Time Difference (see Figure 8). The inverse square component is inspired by the inverse square law for sound intensity, spike function was inspired by the general dynamics of stress responses, incorporating insights from Huber et al. (2003), and Piñero et al. (2025). The observation with the highest score was selected.

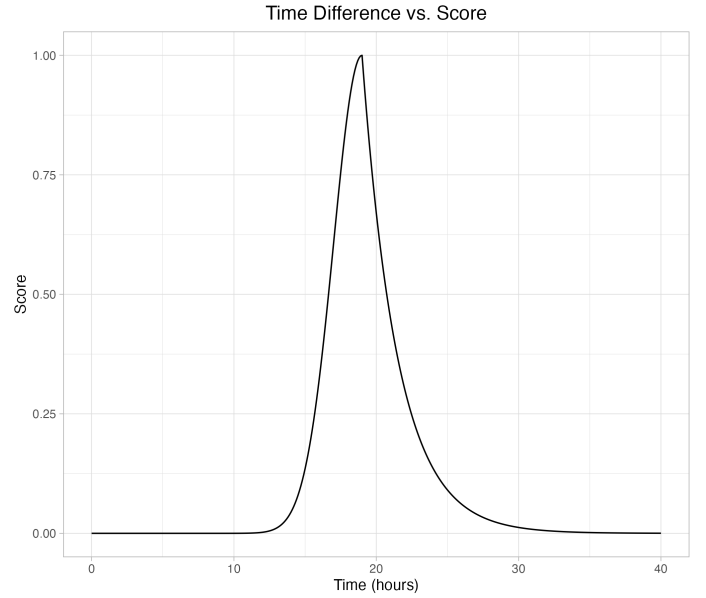


Figure 8: Score Function

$$S(d, t) \propto \frac{1}{d^2} \cdot \begin{cases} f_t(t), \mathbf{t} \sim \mathcal{N}(\mu, \sigma^2) & |t \leq \mu \\ f_t(t), \mathbf{t} \sim \mathcal{Laplace}(\mu, b) & |t > \mu \end{cases}$$

Where d is the spatial distance, t the Time Difference between hunting and defecation event, while $\mu = 19$, once again incorporates Huber et al. (2003) findings. $\sigma = 2$ and $b = 2.5$ are shape paramters.

Having identified the most relevant hunting event, covariate i) can be calculated easily as the Time Difference of the hunting event and the defecation event. To obtain covariate ii) we have to take in account, that the movement data is recorded in 1-hour intervals, while the hunting events occur at arbitrary times. Therefore we need to approximate the exact deer positions at hunting event times. We interpolate deer positions at

Table 1: The three proposed DataSets. For each DataSet, *Temporal* refers to the upper limit of Time Difference between Hunting Event and Defecation Event, with the lower limit being zero. *Spatial* refers to the upper limit of the distance between deer and Hunting event, with the lower being zero as well.

DataSet	Temporal [h]	Spatial [km]
Closest in time	36	10
Nearest	36	10
Highest score	200	15

the timestamp of each hunting event, assuming constant velocity and linear movement. Features iii) and iv) are again easy to obtain. For covariate v), we need to define a cutoff point in time and space, to identify which other hunting events could have affected a deer as well (see Table 1).

3.2 Uncertainties

A major challenge in our analysis is the large uncertainty in data which propagates through the pre-processing steps into our models.

First, the uncertainty about spatial distances between deer and hunting events is large. While the movement of deer was tracked at hourly intervals, hunting events occurred irregularly. In our interpolation-based approximation of a deer’s location at the time of hunting event, the approximation error is unknown.

Second, we have very limited information for addressing the short-term stress response of the deer. On the one hand, the available data contain only 500 hunting events with complete time and location information scattered across a $30\text{km} \times 30\text{km}$ area in the span of two years. The observed hunting events only populate the space-time scarcely. On the other hand, we observe in Figure 5 that the deer tended to roam around within a small area. As a result, each deer is likely to have only encountered very few hunting events at small spatial and temporal distances.

Third, there could be a large number of confounders for which we possess no information. Based on GPS

Table 2: Count of individual deer and faecal sample for each of the proposed DataSets.

DataSet	Deer	Observations
Closest in time	35	149
Nearest	35	147
Highest score	36	223

coordinates, we can compute Euclidean distances between deer and hunting events. However, we cannot account for terrain and vegetation which could affect the propagation of sound and therefore contaminate the potential effect of hunting events. Furthermore, there could be unobserved stress stimuli, such as weather conditions, predators, and human activities other than hunting.

Fourth, we assumed that each hunting event was actually a sound event (i.e. a shot was fired). Therefore, we weighted the value of our score function by the inverse square distance.

4 Model Selection

To address how the FCM level depends on Time Difference and spatial distance, we follow a statistical approach for interpretability and a machine learning approach for exploration. In this section, we present details on model specification. Both approaches use all the datasets shown in Table 2.

4.1 Statistical modeling approach

For each dataset shown in Table 2, we consider the five covariates introduced in Section 3.1.

The *Time Difference* and *spatial distance* are of main interest for our first research question. The effect of *sample delay* is the subject of our second research question. We consider the *day of defecation* as a potential confounder, as the deer’s stress level exhibits seasonal patterns (Vilela et al. 2020). The *number of other relevant hunting events* reflects the intensity of recent hunting activity. In time periods of frequent hunting events, a deer might have a generally higher stress level, or adaptation might occur which dampens the stress response towards new hunting events.

We propose a generalized additive mixed model (GAMM) to account for potentially non-linear effects of covariates and potential individual differences between the observed deer. We use the R package `mgcv` (Wood 2011) to fit the models. The covariates Time Difference, Distance, Sample Delay, and Defecation Day are encoded by penalized cubic regression splines. We do not use a cyclical spline for Defecation Day, because faecal samples were not collected during winter and therefore Defecation Day is not a cyclical variable. The Number of Other Relevant Hunting Events is adopted as a linear effect. We further introduce a random intercept for each deer.

For the distributional assumption, we use the Gamma family with a log link. Since the FCM level is non-negative, we expect the Gamma assumption to be more appropriate than Gaussian. A full specification of our GAMM model is as follows. Let $i = 1, \dots, N$ be the indices of the deer and $j = 1, \dots, n_i$ be the indices of faecal samples for each deer

$$\begin{aligned} \text{FCM}_{ij} &\stackrel{\text{iid}}{\sim} \mathcal{Ga}\left(\nu, \frac{\nu}{\mu_{ij}}\right) \quad \text{for } j = 1, \dots, n_i, \\ \mu_{ij} &= \mathbb{E}(\text{FCM}_{ij}) = \exp(\eta_{ij}), \\ \eta_{ij} &= \beta_0 \\ &\quad + \beta_1 \text{Number of Other Relevant Hunting Events}_{ij} \\ &\quad + f_1(\text{Time Difference}_{ij}) + f_2(\text{Distance}_{ij}) \\ &\quad + f_3(\text{Sample Delay}_{ij}) + f_4(\text{Defecation Day}_{ij}) \\ &\quad + \gamma_i, \\ \gamma_i &\stackrel{\text{iid}}{\sim} \mathcal{N}(0, \sigma_\gamma^2), \end{aligned}$$

where f_1, f_2, f_3, f_4 are penalized cubic regression splines, $\sigma_\gamma^2 > 0$, and $\nu > 0$.

Our model has two major limitations. First, it does not account for potential interactions between the covariates. Second, the random intercept term can only capture different base stress levels, but not differences in stress response. However, given the limited data, one must trade off between model complexity and stability in estimation. In fact, our current model already exhibits instability with respect to estimation procedures, which we discuss in Chapter 5.

4.2 Machine learning approach

Chen and Guestrin (2016) introduced XGBoost as a machine learning algorithm that improves prediction accuracy by building an ensemble of decision trees sequentially. Each new tree corrects the errors made by previous trees. XGBoost minimizes a loss function using gradient boosting (hence the name) by iteratively adding trees that best reduce the residual errors. Simultaneously, complexity gets penalized through regularization to prevent overfitting. A major feature of XGBoost is that it doesn't require specifying a parametric relationship between target and explanatory variables.

We propose a xgboost model using the R package `xgboost`, choosing *spatial distance* and *Time Difference* as covariates. To find the best fitting model for each dataset (see Table 2), we tune hyperparameters of the proposed xgboost model. We choose to tune the following parameters, using randomized grid search (Bergstra and Bengio 2012):

- *maximum depth*: Controls the maximum depth of each decision tree, determining how complex each tree can become.
- η : The learning rate, controls how much each new tree contributes to the ensemble, affecting how quickly or cautiously the model learns.
- γ : The minimum loss reduction required to make a split, acting as a regularization parameter that prevents creating splits that don't significantly improve the model.
- *subsample*: Specifies the fraction of training data used to build each tree, introducing randomness to prevent overfitting.
- *features by tree*: Determines the fraction of features (columns) randomly sampled for each tree, increasing diversity among trees.
- *minimum weight of child*: Minimum sum of instance weight needed in a child node, helping control the complexity of the model by preventing overly specific partitions.

5 Model Evaluation

5.1 GAMMs

We fitted and evaluated GAMM models across the three datasets, using REML and GCV as parameter estimation methods. We observed high instability with respect to the choice of dataset and estimation method.

In models estimated with the REML method, the smooth effects are penalized to almost linear, as shown in Figure 9. While the fitted curves have a similar tendency across the datasets, the standard error in estimation is generally high. Given such high uncertainty, no interpretation of the estimates is reliable. The GCV method yields more wiggly smooth effect estimates, which are visualized in Figure 11, but high uncertainty persists. For the other covariates, we also observe high uncertainty and therefore avoid making any unreliable statement.

On the “highest score” dataset which contains more observations than the other two datasets, both estimation methods agree on a negative non-linear effect of Sample Delay. This is in accordance with our prior knowledge that the FCM level in the faecal sample decays after defecation (Huber et al. 2003).

Similar to the smooth and linear effects, estimation of the deer-specific random intercepts exhibits high instability. In particular, the estimated random intercepts differ in order of magnitude across different dataset (see Figure 12).

5.2 XGBoost

The XGBoost model outperforms GAMM on the “highest score” and “nearest” dataset in terms of model fit measured by root mean squared error (RMSE), but performs worse on the “closest in time” dataset (see Table 3). After reviewing the hyperparameters (see Table 4) and comparisons between models trained on the actual data and the data with randomized labels we concluded that the XGBoost models likely did not learn noise and therefore are not overfitting.

We visualize the predictions of XGBoost models in Figure 10. One would expect a decrease in the FCM level

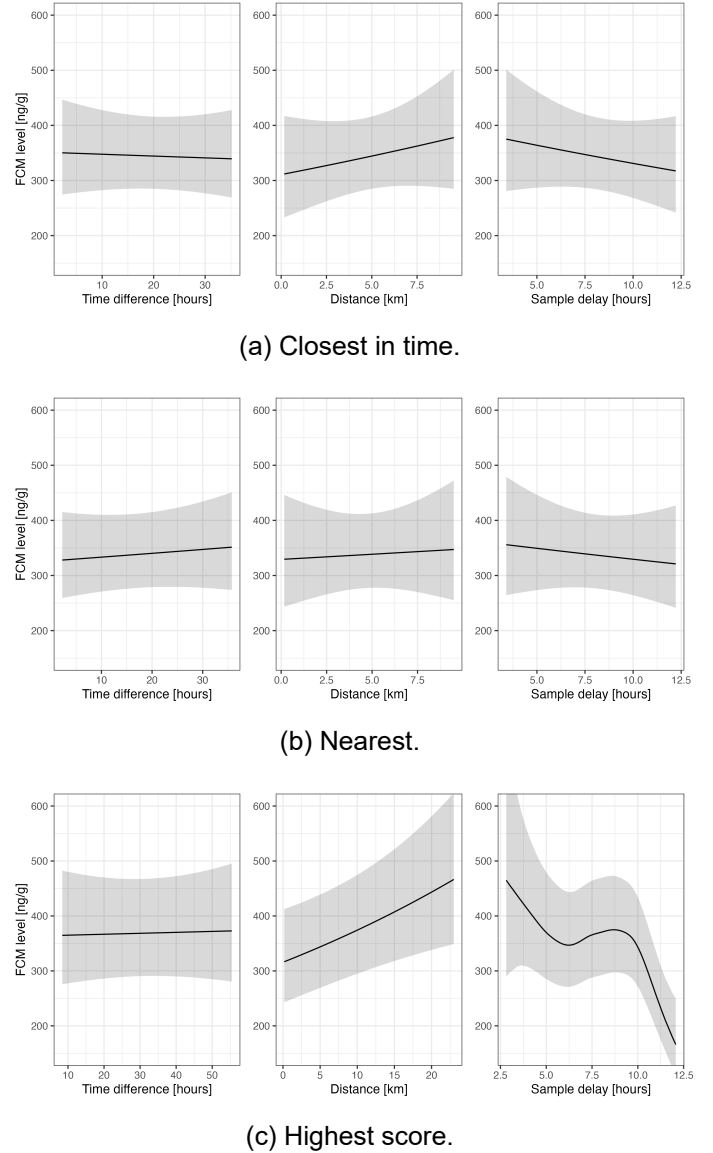


Figure 9: Adjusted predictions for the FCM level on the three datasets. The GAMM is fitted with the REML method. Each plot shows the predicted values of the FCM level in dependence of one covariate. The other covariates are held constant at the mean. The grey area shows the approximate confidence band (mean \pm 1.96 standard error).

Table 3: Comparison of RMSE between GAMMs and XGBoost models. The RMSE score is computed on all observations in each dataset.

DataSet	Model	RMSE
Closest in time	GAMM-GCV.Cp	166.77
Closest in time	GAMM-REML	178.64
Closest in time	XGBoost	167.53
Highest score	GAMM-GCV.Cp	163.69
Highest score	GAMM-REML	169.76
Highest score	XGBoost	150.80
Nearest	GAMM-GCV.Cp	169.50
Nearest	GAMM-REML	180.20
Nearest	XGBoost	152.24

closer to the zero point, however we did not observe this for models trained on the first two datasets. On the “highest score” dataset we observe a slight increase close to zero, but the same model also predicts a high plateau for time differences above 33 hours and spatial distances between 11.5 and 16 km. The XGBoost models show a relatively weak and very unclear effect.

6 Conclusion & Outlook

Due to the high level of uncertainty in the data, we were not able to show a consistent effect of spatial and temporal proximity to a hunting event on the FCM levels. However, we were able to show to a certain extent that the FCM level decreases with increasing sample delay.

We believe that a more rigorous approach to recording hunting events (e.g., tracking timespans rather than single moments and enforcing complete timestamps), coupled with a larger dataset and a more directed strategy (e.g., intentionally creating greater overlap of hunting events, movement data, and fecal samples in time and space), could reduce uncertainty and yield clearer results.

Acknowledgements

We would like to express our deepest gratitude to *Dr. Nicolas Ferry* for providing us with the opportunity to work on this project.

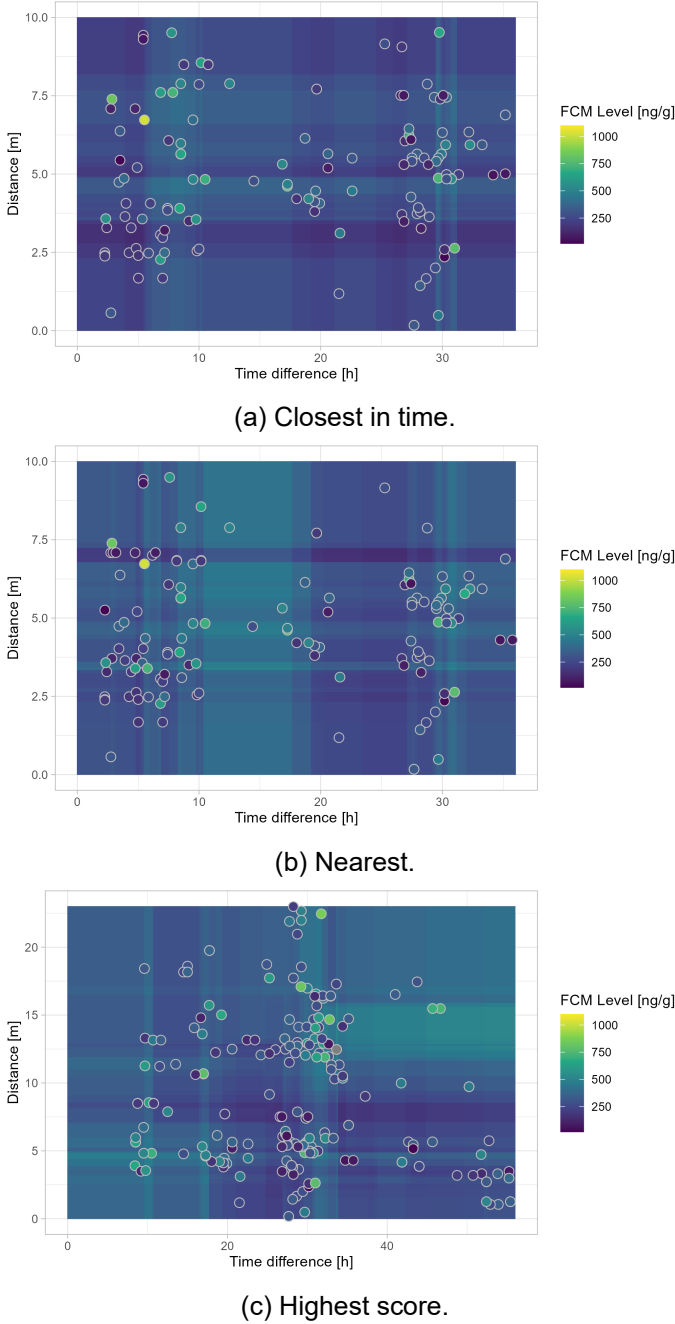


Figure 10: Predictions of XGBoost models on the three datasets. The points are all observations within each dataset.

Daniel Schlichting's mentorship throughout the project was invaluable. We thank him for his guidance and patience.

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7 Appendix

7.1 Reproduction data

As the reproductive data only contain information on a subset of the deer, we were faced with the decision of how to label the rest of the deer (“pregnant”/“not pregnant”/NA). We are convinced that imputing this information would introduce a huge bias. For this reason, we deliberately chose not to include pregnancy data in our model. However, we are strongly in favour of including additional characteristics that could explain a shift in baseline stress levels.

7.2 GAMM

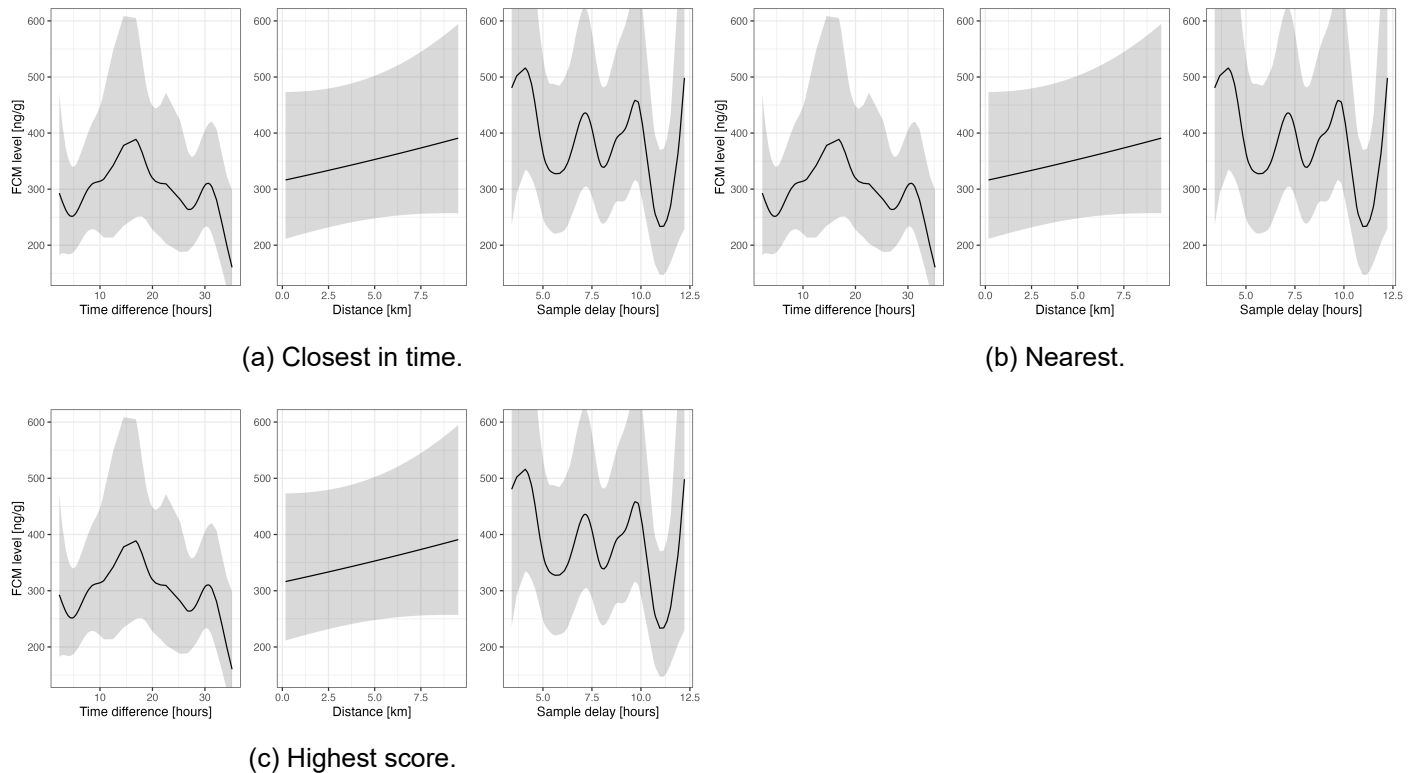


Figure 11: Adjusted predictions for the FCM level on the three datasets. Here the GAMM is fitted using the GCV method.

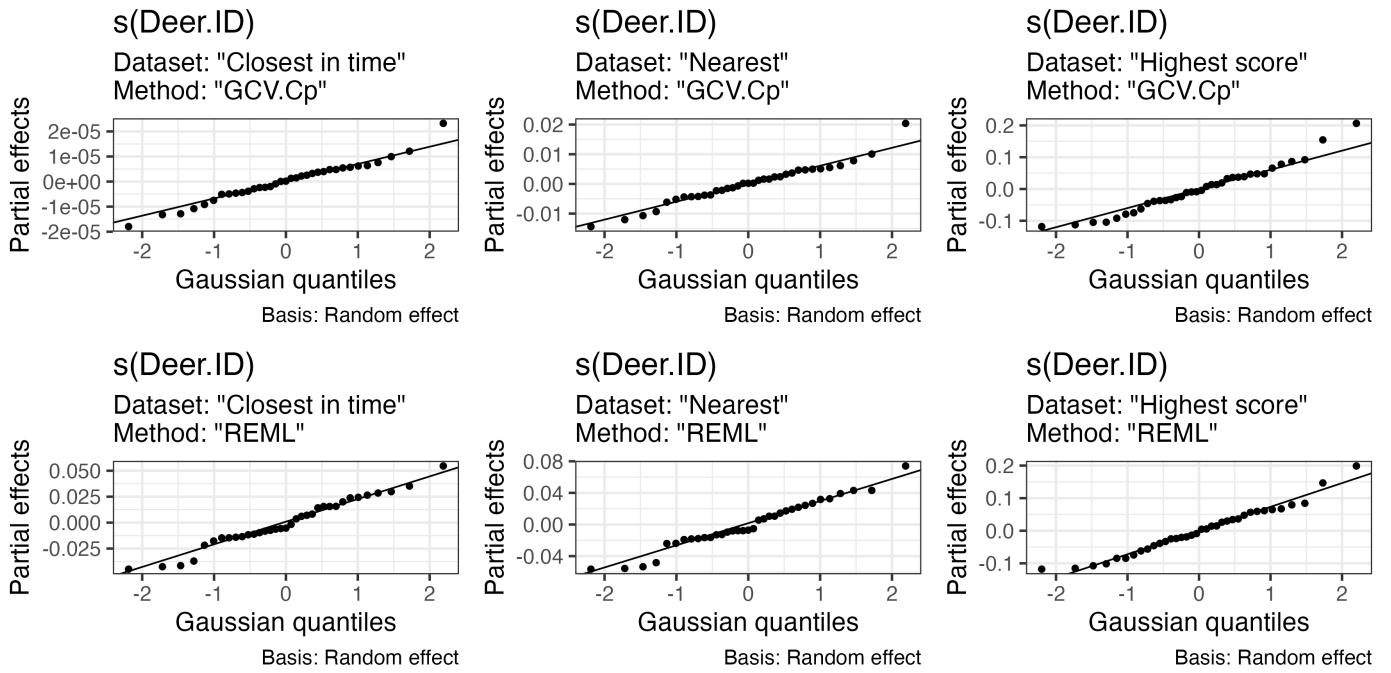


Figure 12: Random intercept estimates on the three datasets using REML and GCV.

7.3 XGBoost

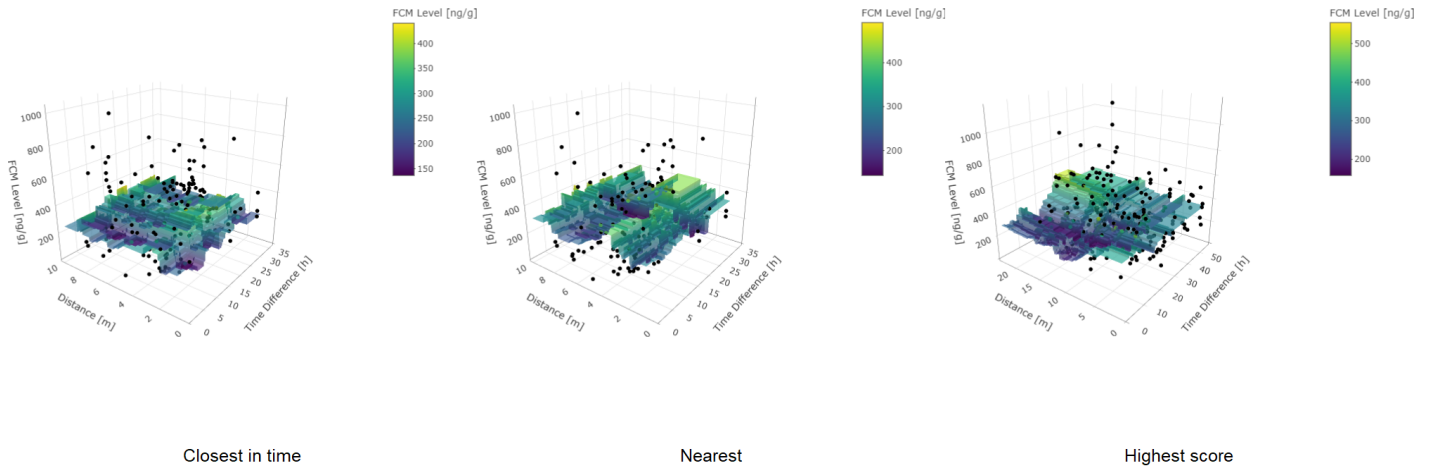


Figure 13: 3D Visualization of predictions for the FCM level on the three datasets by the XGBoost models. The observed data are shown as black points.

Table 4: Tuned hyperparameters for the XGBoost models.

DataSet	Max. depth	η	γ	Subsample	Features by tree	Min. weight of child
Closest in time	4	0.16	5.85	0.59	0.99	4.64
Nearest	4	0.17	5.89	0.60	0.98	4.75
Score	5	0.17	5.83	0.61	1.00	4.77