

En Xu (Thomas) Li

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📍 Toronto, Canada

Education

Sep 2017 – Apr 2022 | **Bachelor of Applied Science in Engineering Science**, University of Toronto
Robotics Major, Artificial Intelligence Minor, Engineering Business Minor
3rd Year Annual GPA: 3.97
University of Toronto Scholar, NSERC Undergrad Student Research Award, Dean's Honour List

Experience

Sep 2021 - Ongoing | **University of Toronto Institute of Aerospace Studies** | Undergraduate Thesis Student
Supervised by Prof. Steven Waslander, Toronto Robotics and Artificial Intelligence Laboratory

- 4D Panoptic LiDAR Segmentation for Autonomous Vehicles

May 2020 - Aug 2021 | **Noah's Ark Lab, Huawei Canada** | 3D Perception Research Intern
Supervised by Dr. Bingbing Liu, Cognitive IoV Perception Team

- Built a custom PyTorch training pipeline for panoptic segmentation with LiDAR inputs
- Project lead for researching real-time deployable panoptic segmentation networks using LiDAR point cloud as inputs. First author of *CPSeg* and *SMAC-Seg*, state-of-the-art methods on SemanticKITTI panoptic segmentation benchmarks. Three Patents pending, two paper under review at *AAAI 2022* and *ICRA 2022*.
- Designed and supported the development of high-performance perception models. Co-author of *AF2-S3net* (accepted at *CVPR 2021*) and *GP-S3net* (accepted at *ICCV 2021*). The two models are top ranked on SemanticKITTI and nuScenes semantic segmentation and panoptic segmentation challenges upon publication.

May 2019 - Aug 2019 | **Department of ECE, University of Toronto** | Summer Student Researcher
Supervised by Prof. Roman Genov, Intelligent Sensory Microsystems Laboratory

- Designed FSMs and Programmed the FPGA board (Opal Kelly XEM7310) to control 3D imaging cameras with time-of-flight sensors using Verilog and Python
- Improved the PC-FPGA communication and memory interfacing to allow faster data process by replacing sequential read/write to all-freedom DDR3 memory address mapping

Honors

2020 | **Daisy Intelligence Scholarship**

- awarded to top ranked robotics major student based on course grades in 3rd year

2019 | **NSERC USRA**

- Undergraduate Student Research Award by Natural Sciences and Engineering Research Council of Canada

ESROP-U of T Fellowship [*declined*]

- awarded by Engineering Science Research Opportunities Program to pursue a paid summer research internship at University of Toronto

ESROP-Global Fellowship [*declined*]

- awarded by Engineering Science Research Opportunities Program to pursue a paid summer research internship at National University of Singapore

2017 | **University of Toronto Scholar**
The Murray Calder Hendry Scholarship

Projects

2021	Buddify <ul style="list-style-type: none">Created a smart platform to match individuals based on their personality and common interests, powered by Reactjs and Nodejs, built with machine learning clustering algorithms
2019	BallBallU <ul style="list-style-type: none">Designed, fabricated and programmed a robot prototype that autonomously detect and deploy objects to canisters.Winning 2nd place in the competition FoodDet <ul style="list-style-type: none">Designed and Trained a food detector with modified Faster R-CNN backbone on collected and processed data

Publications

2021	[1] E. Li , R. Razani, B. Liu, "CPSeg: Cluster-free Panoptic Segmentation Network of LiDAR Point Clouds," <i>under review</i> , 2021
	[2] E. Li , R. Razani, B. Liu, "LiDAR Panoptic Segmentation via Sparse Multi-directional Clustering," <i>under review</i> , 2021
	[3] R. Razani*, R. Cheng*, E. Li , E. Tagahvi, Y. Ren, B. Liu, "GP-S3Net: <u>G</u> raph-based <u>P</u> anoptic <u>S</u> parse <u>S</u> emantic <u>S</u> egmentation Network," ICCV 2021
	[4] R. Cheng, R. Razani, E. Tagahvi, E. Li , B. Liu, " $(AF)^2$ -S3Net: <u>A</u> ttentive <u>F</u> eature Fusion with <u>A</u> ddaptive <u>F</u> eature Selection for <u>S</u> parse <u>S</u> emantic <u>S</u> egmentation Network," CVPR 2021

Patents

2021	[1] E. Li , R. Razani, Y. Ren, B. Liu, "METHODS AND SYSTEMS FOR DETERMINISTIC CALCULATION OF SURFACE NORMAL VECTORS FOR SPARSE POINT CLOUDS," <i>patent filing</i> , 2021
	[2] E. Li , R. Razani, B. Liu, "SYSTEM AND METHOD FOR PANOTIC SEGMENTATION SYSTEM OF POINT CLOUDS," <i>patent filing</i> , 2021
	[3] E. Li , R. Razani, B. Liu, "SYSTEM AND METHOD FOR PROPOSAL-FREE AND CLUSTER-FREE PANOPTIC SEGMENTATION SYSTEM OF POINT CLOUDS," <i>patent filing</i> , 2021