

# **Data Science and Visualisation Techniques applied on Bus Search Requests and its Correlating Booking Data**

Subtitle

## **Bachelor Thesis**

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# Abstract

(E.g. “This thesis investigates...”)

# Kurzfassung

(Z.B. "Diese Arbeit untersucht...")

# List of Abbreviations

ARP	Address Resolution Protocol
GPRS	General Packet Radio Service
GSM	Global System for Mobile communication
WLAN	Wireless Local Area Network

# Key Terms

GSM

Mobilfunk

Zugriffsverfahren

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# 1 Introduction



## 2 Info

### 2.0.1 Research Question

What Neural Networks are suitable to predict future bus bookings and which Attributes of bus search requests can be utilized to create an analytical dashboard

Research Question BA1: How to create a theoretical framework that covers basic DS aspects and visualization techniques in order to develop an analytical web-based dashboard

### 2.0.2 General

Basic Idea/Content:

- Explain available dataset, data structure, how data is gathered
- Explain what techniques are used to clean the base dataset
- Interdisciplinary - explain why certain KPIs or models are chosen and are applied onto the dataset
- Prediction Model - explain the technologies, methods etc. used to create a ML based prediction model (To improve Yield Management). Maybe two models, Supervised Learning and unsupervised learning
- Data Clustering and other KPIs + applied statistical models (e.g. Clustering, LR), Heatmaps etc.
- Visualisation techniques used to display results of the applied statistical models
- Maybe? Short chapter about technical setup of the Dashboard

In general I would appreciate some general feedback what else could/should be described within this thesis. I think the Prediction Model will be the main aspect of this thesis (How it is created + which techniques are used, how is the performance when comparing prediction to actual booking data etc.)

### 2.0.3 Lit Research

[1] - provides also a lot of useful references to other papers that can be used

[2] - ML

[3], [4], [5], [6] - Tensorflow, ML etc.

[7], [8] - interdisciplinary to provide context which KPI's etc are chosen etc.

## 3 Available Dataset

This chapter focuses on explaining and analysing the available data. The data is analyzed for Business Intelligence (BI) purposes as well as on metrics that can be used to create predictions. Whereas BI [?] focuses on historical data and aims to support managers to make decisions traditional methods like predictive analytic asses potential future scenarios using advanced statistical methods [?].

### 3.1 Data Origin

The available dataset is gathered from a website that provides a service to find and book buses for individual journeys. This service is currently available in Austria, Germany, Switzerland and Lichtenstein. The buses itself are offered in real time by various different bus companies. Offers can vary in price which is based bus calculations which may vary from operator to operator. The data is stored in a relational database. Since the service also provides the possibility to directly book a bus, booking and corresponding user meta data is available as well.

### 3.2 Data Structure

The service launched in March 2017 therefore booking data is available back to this date. Tracking the search requests was introduced in October 2020. The request table itself keeps track of 40 attributes but not all of them host valuable information that could be analysed therefore only the ones which can be analysed are listed and explained below:

- `task_id` - PK (incremented value)
- `createdAt` - At which time the search request was made.
- `accountId` - Not empty when the user is currently logged in
- `amountSearchResults` - How many buses can be offered
- `containsTripCompany` - If the user wants to stop at a certain company during the trip
- `distanceInMeters` - Distance between departure and destination place
- `durationInSeconds` - Duration of the trip
- `pax` - Amount of passengers
- `taskFrom_address` - Departure address
- `taskFrom_lat` and `lng` - Latitude and Longitude of the departure
- `taskTo_address` - Destination address

### 3 Available Dataset

- taskTo\_lat and lng - Latitude and Longitude of the destination
- taskFrom\_Time - Desired departure time
- taskTo\_Time - Estimated arrival time
- cheapestPrice\_amount - The cheapest price for a bus
- bus\_id - The operator with the cheapest bus
- city - From which city the request was made
- country - From which country the request was made

Whenever a booking is made the correlating data is stored within a booking table. As the booking table contains sensitive data which is not scope of the analysis, so only three attributes are used:

- createdAt - At which time the booking was made.
- company\_id - FK used to identify who received the booking
- task\_id - FK used to link the booking to an search request

### 3.3 Data Cleansing

During this process the available data is investigated for irregularities that cause distortion when applying statistical models.

Search requests are tracked whenever a user opens the service and searches for a certain connection. Given that behaviour it may occur that a user searches for the same connection within a short time window. This behaviour results in the need of de-duplication to avoid bias. To filter out duplicates the attributes ipHash, createdAt, taskFrom\_address and taskTo\_address. A search request is considered as non duplicate whenever the timespan between equal entries is larger than one hour. To pre-process the data the following logic is applied once //todoChange:

```
query = '''
DELETE t1
FROM search_requests_clean t1
INNER JOIN search_requests_clean t2
    ON t1.taskFrom_address = t2.taskFrom_address
    AND t1.taskTo_address = t2.taskTo_address
    AND t1.ipHash = t2.ipHash
    AND t1.createdAt > t2.createdAt
    AND t1.createdAt - t2.createdAt <= %s
'''

timespan = 3600 # 3600 seconds - 1 hour
cursor = connection.cursor()
cursor.execute(query, (timespan,))
connection.commit()
```

### 3 Available Dataset

//todo more explanation The logic above compares all entries based on the attributes mentioned above removes equal entries that are within a timespan of 1 hour.

Regarding validation and norming the available data present in both tables no actions are required due to fact that attributes that do not meet their defined data types are not stored in first place.

## 3.4 Data Augmentation

Starting from March 2020 countries like Austria, Germany, Switzerland and Lichtenstein had to put travel restrictions into effect due to the ongoing Covid19 pandemic citeHere. This travel restrictions impacted the gathered booking data as those restrictions forbid travelling.

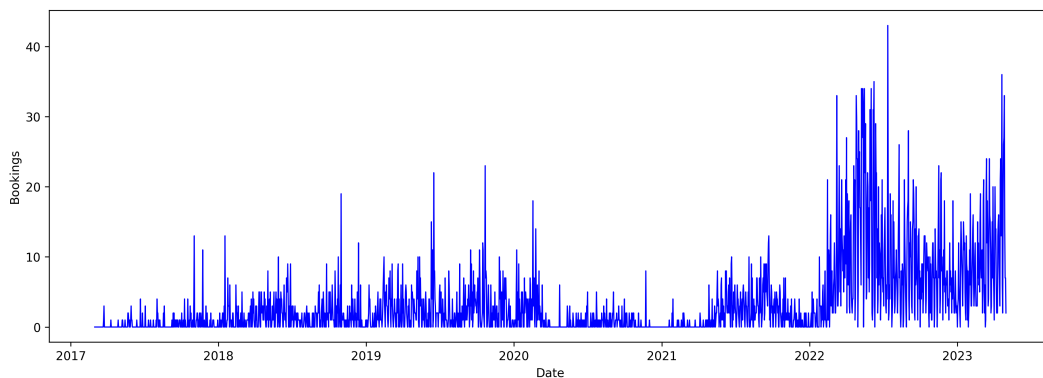


Figure 3.1: Bookings over time - [source:author]

Figure 3.2 highlights the drop of bookings starting from March 2020 until June 2022. To achieve reliable results when utilizing this data for a time series forecasting ML model this time period needs augmentation. When analysing the chart 3.2 an continuous growth of bookings is visible until 2021. One way to augment the data citehere is calculate the average growth during this time span. To substitute the distorted data the current data is replaced by the value of the previous year. This value is then multiplied by the average growth. Furthermore missing timestamps throughout the whole time series are added with a value of zero. The following logic is applied to the data frame:

```
df = db.get_booking_data()
average_growth = df['bookings'].pct_change().mean()
substitute_corona = pd.date_range(start='2020-03-01', end
    ='2022-05-01', freq='D')
df['date(createdAt)'] = pd.to_datetime(df['date(createdAt)'])
df = (df.set_index('date(createdAt)')
    .reindex(pd.date_range('2018-01-01', '2023-05-01', freq='D'))
    .rename_axis(['date(createdAt)'])
    .fillna(0)
    .reset_index())

df.set_index('date(createdAt)', inplace=True)

for date in substitute_corona:
```

### 3 Available Dataset

```
year_ago = str(date - relativedelta(years=1)).split(" ")[0]
val = int(math.ceil(df.loc[year_ago]['bookings'] * (1+
    average_growth)))
df.loc[str(date).split(" ")[0]] = val
```

The average growth per anno is around 30%. After applying the logic the data set looks the following:

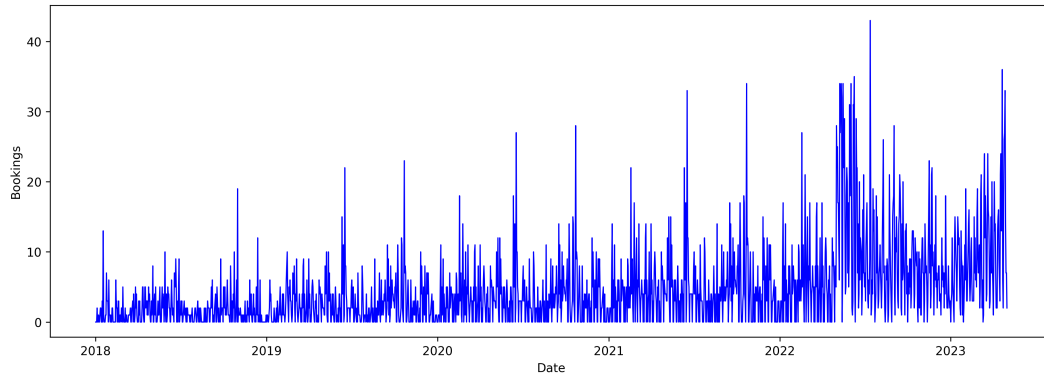


Figure 3.2: Augmented Data Set - [source:author]

The impact of this augmentation in terms of prediction accuracy is compared in chapter ??.

## 3.5 Possible Analytical Strategies that can be applied

Explain what can be applied to the dataset, what processes could be improved by analysing the data.

Improve Yield Managment (Prediction Model, ML)

## 4 Key Performance Indicators and Yield Management

### 4.0.1 Yield Management

What Neural Networks are suitable to predict future bus bookings and which Attributes of bus search requests can be utilized to create an analytical dashboard

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[3], [4], [5], [6] - Tensorflow, ML etc.

[7], [8] - interdisciplinary to provide context which KPI's etc are chosen etc.

## 5 Predicting Future Bookings

The knowledge of potential future bookings provide useful insights when it comes to yield management. Yield management in general describes controlling price and capacity control in a simultaneous ways [9]. Therefore those predictions can be used to support bus operators in their pricing strategy. This chapter focuses on creating two prediction models utilizing different techniques based on the data that is available. Both models are implemented using python and the following libraries.

- `matplotlib`<sup>1</sup> - used for plotting
- `pandas`<sup>2</sup> - used for data manipulation
- `tensorflow`<sup>3</sup> - provides ML models
- `keras`<sup>4</sup> - Neural Network library

As there are various models available a literature review was conducted to figure out which models fit the purpose of time series forecasting. It turns out that the most promising NN that can be utilized for time series prediction are either Convolutional Neural Networks (CNN) or Recurrent Neural Networks (RNN) especially Long Short-Term Memory (LSTM)[10][11][12][13].

### 5.1 Backpropagation

As both of the models LSTM and CNN use back propagation (BP) for its training the basic concepts of the algorithm are explained in this section. To understand the logic of backpropagation a few terms need a detailed explanation:

#### Gradient

The gradient also called gradient descent is an algorithm that is used to optimize the loss function within backpropagation. That means that the gradient descent indicates by how much the weights and biases need to be adjusted in order to reduce the actual error value which is the result of the applied loss function. [14]

#### Bias

The bias is an additional parameter used in each neuron of a NN. It is used to directly influence the activation function to offset the results either to the negative or positive direction. When looking at the sigmoid function without any bias in place where  $x$  correlates to the input value and  $w$  indicates the used weight:

$$\sigma(x) = \frac{1}{1 + e^{-(w*x)}} \quad (5.1)$$

---

<sup>1</sup><https://matplotlib.org/>

<sup>2</sup><https://pandas.pydata.org/>

<sup>3</sup><https://www.tensorflow.org/>

<sup>4</sup><https://keras.io/>

When looking at figure 5.1 the weights only influence the steepness of the function but won't shift it along the x axes.

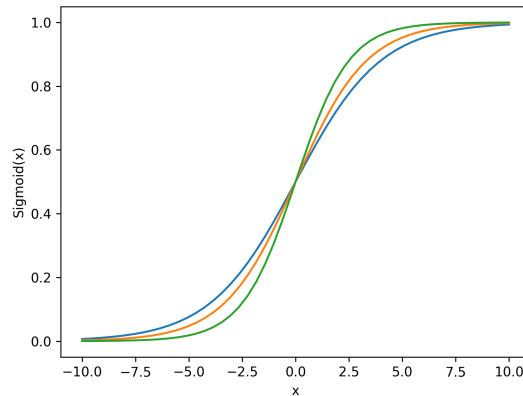


Figure 5.1: Sigmoid function with different weights and no bias - [source:[15]]

To shift the function along the x axes the sigmoid function is adapted with the bias  $b$  value:

$$\sigma(x) = \frac{1}{1 + e^{-(w*x+b)}} \quad (5.2)$$

By adding the bias value as constant to the sigmoid function can be shifted along the x axes as shown in 5.2.

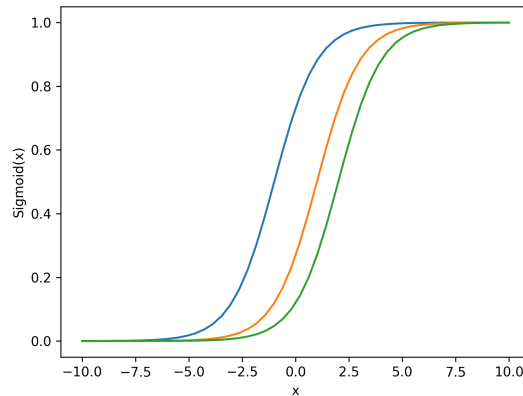


Figure 5.2: Sigmoid function with same weights but different bias - [source:author]

The bias therefore is utilized to directly influence the result of the activation function and whether or not a certain neuron is activated or not.

### Activation Function

Activation functions introduce non-linearity characteristics to NN. This function is applied to the output of a neuron and decides whether or not a neuron is activated or not.[16]. In combination with the descent gradient this function enables the NN to learn complex patterns within a training set. Originally the sigmoid function [14] was used as activation function for NN but as of today multiple other functions like softmax, Tanh, ReLu emerged [16].



### Phases

Backpropagation follows an iterative process. At the beginning there is the feed forward pass. During this phase the input data is passed through all layers. Each hidden layer applies a linear function to create certain weights those outputs then are fed to the activation function. Depending on how many hidden layers are used within the NN the output of the activation function is used as input for the next neuron. At the end the predicted outputs by the model are compared with the actual outputs of the training data. This comparison is evaluated through a loss function. At this step the actual learning process of the model starts by calculating the gradient of the loss function considering the output of the NN. After that the back pass is initiated. Along this phase the gradients of each previous layers are multiplied with a local gradient it's weights which results in a gradient in respect to the layer's inputs. After receiving all gradients based on the network's input data, all weights and biases are updated and optimized to reduce the result of the loss function. The steps forward pass, loss calculation, back pass, and the updates of weight and biases are repeated to improve the network in an iterative way. [14] Figure 5.3 demonstrates the logic of the backpropagation algorithm. Whereas  $w_u$  represents the updated weights after each iteration.

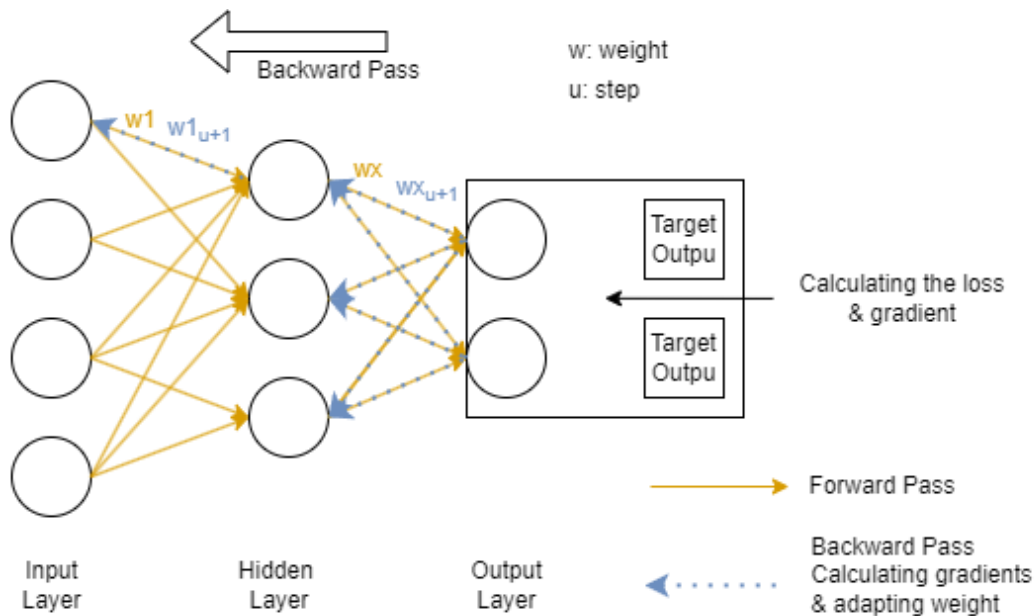


Figure 5.3: Simplified logic of the backpropagation algorithmus - [source:[14]]

## 5.2 The Models

Both models CNN and RNN/LSTM can be used for time series forecasting. To create accurate prediction models a basic knowledge about models functionality is required. Therefore this section explains the components of each NN as well as the approaches those models follow.

### 5.2.1 LSTM

LSTM is an RNN and was invented by [17] in 1997. Until today this NN is widley used for time series forecasting and provides reliable results for short as well as long term predictions [18]. LSTM have so called memory cells which are responsible to store the state of data.

Whenever information arrives at a memory cell its outcome is defined by refreshing the cell state with the newly arrived information. LSTM utilizes gates to control a cells state by either including or excluding information [19]. The gates are called:

- input gate - data selection and storage for upcoming state
- forget gate - data selection and storage which will not be used for the upcoming state
- output gate - sets information within the state that is send to the output

Those gates are created by combining sigmoid functions. The results of this gates are values ranging from zero to one. A result of zero indicates the cell to not pass any infomration whereas values close to one indicates the cell to pass all information. The LSTM Module or Repeating module consists of four NN layers which interact together as shown in Figure 5.4:

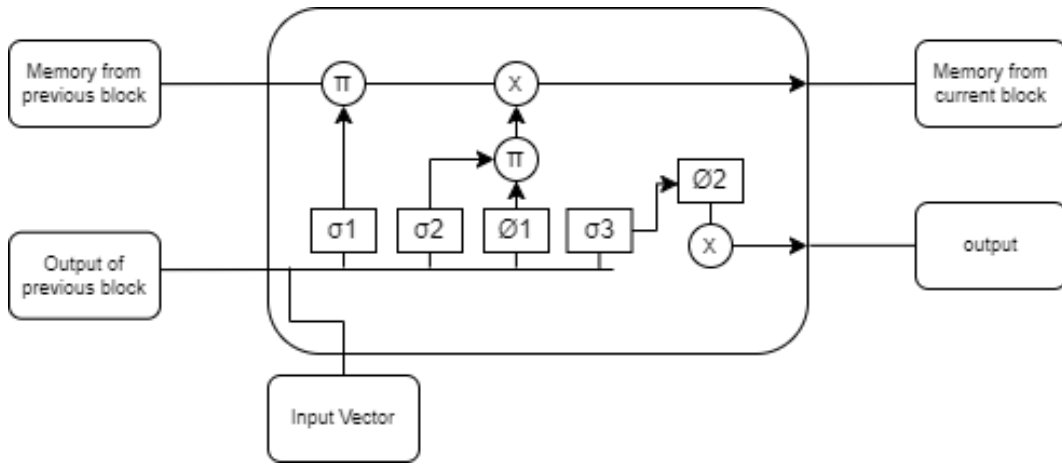


Figure 5.4: Repeating LSTM Module - [source:[15]]

In total the repeating model has 3 gate activation functions which are named  $\sigma_1$ ,  $\sigma_2$ ,  $\sigma_3$  and shown in figure 5.4. Furthermore  $\sigma_1$  and  $\sigma_2$  act as output activation functions too. The cell state is illustrated using a blue line which starts at  $S_{t-1}$  which indicates the previous memory block to  $S_t$  representing the current memory block. The amount of information that is passed is regulated by layer  $\sigma_1$  using the following function:

$$cf_t = \sigma_1(W_{cf} * [O_t - 1, x_t] + b_{cf})[15] \quad (5.3)$$

Furthermore two network layers are used to store new information to the cell state. Therefore sigmoid layer  $\sigma_2$  chooses the values which are updated by utilizing the following formula:

$$l_t = \sigma_2(W_l * [O_t - 1, x_t] + b_l)[15] \quad (5.4)$$

Layer  $\phi_1$  or  $\tanh$  is created by using new candidate values. This layer outputs a vector by utilizing the following formular:

$$\tilde{S}_t = \tanh(W_s * [O_t - 1, X_t] + b_s)[15] \quad (5.5)$$

The last step includes combination of both states 5.4 and 5.5 which is added to the state. Also the state is reconditioned by applying: [15]

$$S_t = cf_t * S_{t-1} + l_t * \tilde{S}_t - 1[15] \quad (5.6)$$

The reason why a LSTM model is used for this purpose is that a standalone RNN is challenging to train due its characteristics. As Back propagation is used for RNN's problems like vanishing-gradient occur. The gradient in general can be understand as a computed value through all time setps which in the end used to update parameters of the RNN. The vanasihing-gratdient over time results in information decay. By implementing an LSTM module this problem can be solved. [20]

### 5.2.2 CNN

CNN's follow the concept of NN consisting of multiple layers. The scope of application for this kind of network reaches from computer vision problems to time-series forecast modelling. Whereas data provided for image classification is structured in multi dimensional arrays (matrices), data used for time-series forecasting is provided via one dimensional arrays.[21] A CNN provides different types of layers . Those layer types are called pooling layer (PL), fully connected (FC), Convolution layer (CL) and flatten layer (FL). The connection of those layers are demonstrated in figure 5.5.

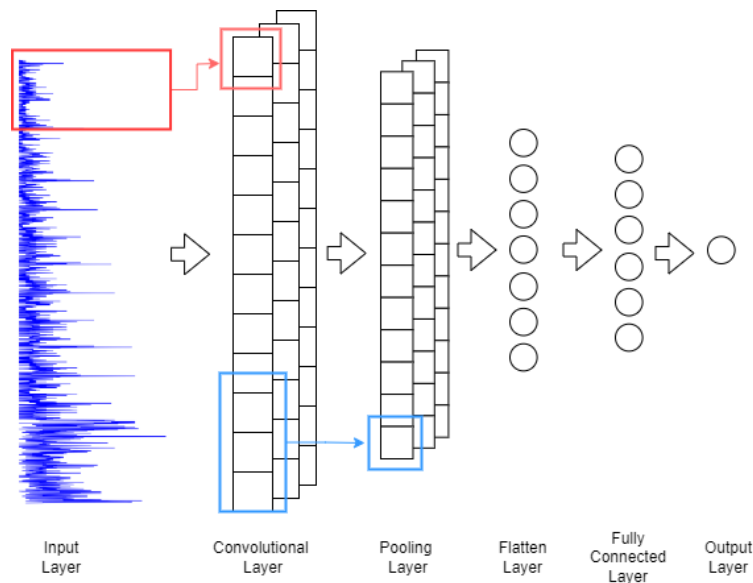


Figure 5.5: One Dimensional CNN Structure - [source:[22]]

CNN is based on convolution which is a linear operation that multiplies input data with convolution filters. Those filters which are also called kernels correlate to a set of weights [22]. The kernel values are created during the learning process and are optimized from the NN utilizing back propagation. Furthermore this layer is utilized to detect features within the given one dimensional array. Those features are stored within a feature map and are calculated by applying convolutions on the input data. One crucial parameter to detect proper features is the size of the kernel. The kernel size can be understand as a number of weights that are multiplied with the input data. After each multiplication the sequence is shifted along the input data. Each shift during this process produces one output which is stored in the feature map. The following example demonstrates how this process is done.[23]

Input Data: [4,7,10,43,20,10] e.g. number of bookings per day.

Kernel: [0.5,0.25,0.2] Kernel size = 3

1st Multiplication:  $4 \times 0.5 + 7 \times 0.25 + 10 \times 0.2 = 5.75$

2nd Multiplication:  $7 \times 0.5 + 10 \times 0.25 + 43 \times 0.2 = 14.6$

...

Output sequence [5.75, 14.6, ...]

The second operation that is used within the CNN is called activation function. This non-linear function is utilized to detect complex relationships between variables and are applied onto the feature map. As of today multiple functions like ReLU, Sigmoid and softmax can be used as activation functions [24].

The pooling layer as shown in figure 5.5 is deployed within a NN to diminish the size of feature maps. To reduce the size pooling operations like average pooling, max pooling or sum pooling can be applied. Applying one of those operations results in less computational effort.[25]

The activation function is used within the fully connected layer. This layer applies the activation function onto the feature map and enables the model in combination with back-propagation to learn complex connections between features.[23]

The flatten layer transforms two dimensional input data into one dimensional input vectors. It's output is used to provide outputs to the fully connected layer. Over-fitting can be caused whenever all features are used in the flatten layer therefore a dropout layer can be set in place. This layer cancels out neurons during the training process of a NN which reduces the model's size.

### 5.3 Overfitting and Underfitting

One problem that can occur when utilizing NN for predictions is over-fitting or under-fitting of the training data. Both scenarios result in a poor performance of the trained model.

#### 5.3.1 Overfitting

Overfitting describes the phenomenon that the model is not able to improve its problem solving capabilities after a certain period of training. There are multiple reasons for the occurrence of overfitting. One reason for example is a inaccurate or unbalanced training set. This leads to the fact that the NN produces wrong connections during its training. Whereas the results for the training set are accurate the problems occur during the validation phase because the model learned wrong characteristics. [26]

#### 5.3.2 Underfitting

On the other hand underfitting arises when the model is not capable of identifying the traits of the training set and therefore struggles to achieve matching its target values. This results in a high loss values. Reasons for underfitting are caused by a lack of trainable parameters as well as a NN model with a simple architecture in terms of hidden layers.

In section 3.3 and 3.4 actions were taken to avoid both overfitting and underfitting.

## 5.4 Implementation

## 5.5 Reliability Comparison - LSTM, CNN

## 5.6 Model accuracy

Having a look at the model performance accuracy (comparing predictions of the model with already available data) , explain potential tweaks that have been applied to the model itself to achieve a higher level of accuracy.

## **6 Analytical Dashboard**

### **6.1 Technical Setup**

Explain the basic setup and used technologies for used for the analytical web based dashbaord

### **6.2 Applied Statistical Models**

explain which attributes also provide additional information that can be gathered from the dataset, which models were applied (algorithms)

### **6.3 Visualisation techniques**

which plots etc (and why) are used to display the gathered information

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# Appendix

(Hier können Schaltpläne, Programme usw. eingefügt werden.)