480: Activities 12

Online handouts: gaussian_random.cpp, random_walk.cpp, and other

listings. Today we'll play some games with the GSL random number

generators.

Your goals for today:

- Generate some random walks and verify their
- properties. Try out primitive Monte Carlo integration.
- Take a look at an alternative version of the random walk code using classes.

Please work in pairs (more or less). The instructors will bounce around and answer questions.

Random Number Generation

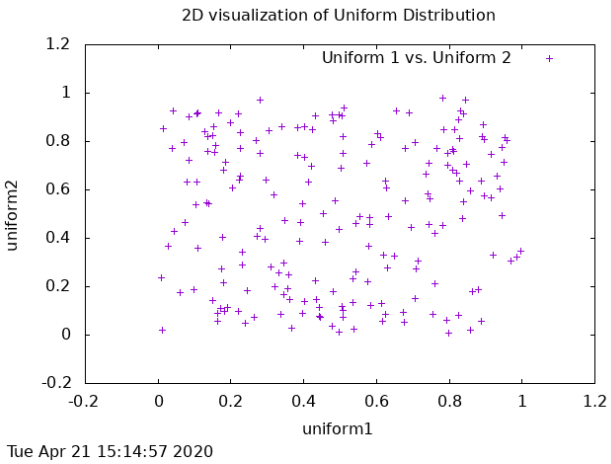
The program gaussian_random.cpp calls GSL routines to generate both uniformly distributed and gaussian distributed numbers.

1. Look at the gaussian_random.cpp code (there is a printout) and identify where the random number generators are allocated, seeded, and called. *If you were creating a RandomNumber class, what statement(s) would you put in the constructor and destructor? What private variables would you define?*

I would add statements for creating and removing a uniform or gaussian distribution with N points and other parameters (standard deviation or upper/lower bounds). The only private variable I can think of would be the seed.

Compile and link the code (use make_gaussian_random) then generate pairs of uniformly and gaussian distributed numbers in random_numbers.dat.

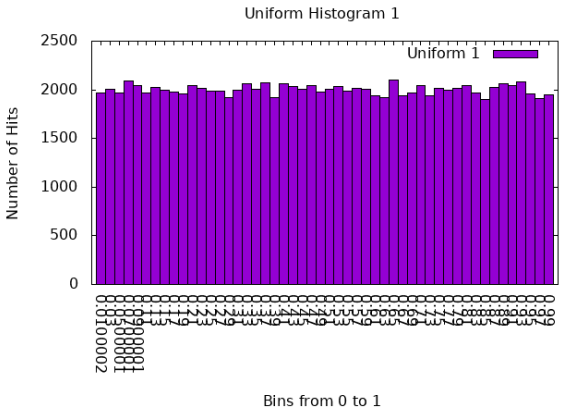
2. Devise and carry out a way to use gnuplot to roughly check that the random numbers are uniformly distributed. [Hint: Read the notes. Your eye is a good judge of nonuniformity in two dimensions.] *What did you do?*

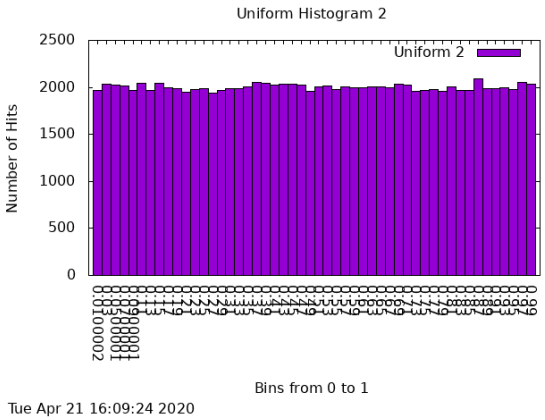


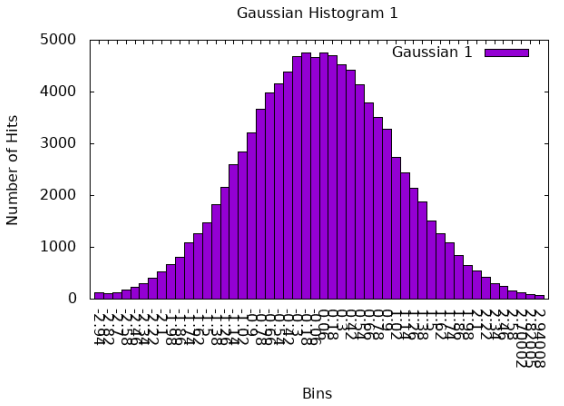
I plotted each column against each other to see if any clumps emerged. For N=200, there does not seem to be any region with an outsized representation, implying they are uniformly distributed.

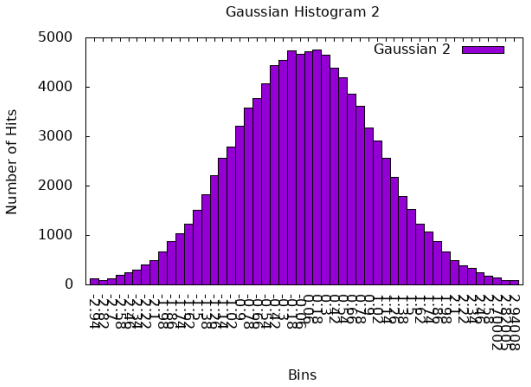
3. You can check the distributions more quantitatively by making histograms of the random numbers. Think about how you would do that. Then take a look at gaussian_random_new.cpp, which has added crude histogramming (as well as automatic seeding). Use the makefile to compile and run with about 100,000 points. Look at random_histogram.dat. *Use gnuplot to plot appropriate columns (with*

appropriate ranges of y) to check the uniform and gaussian distributions. Do they look random? In what way?



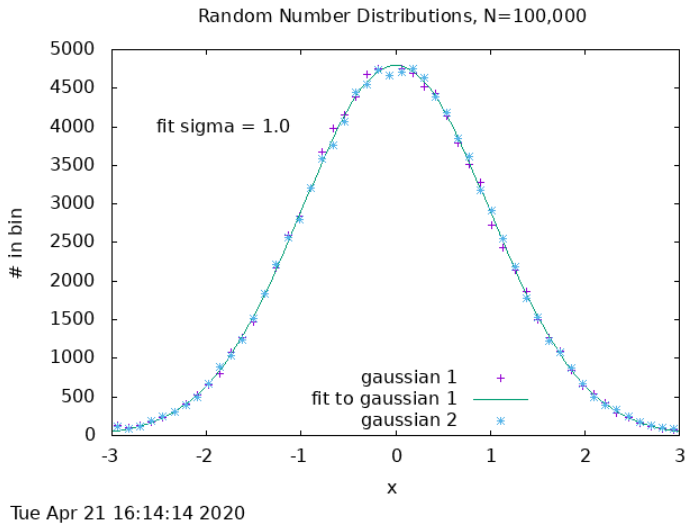


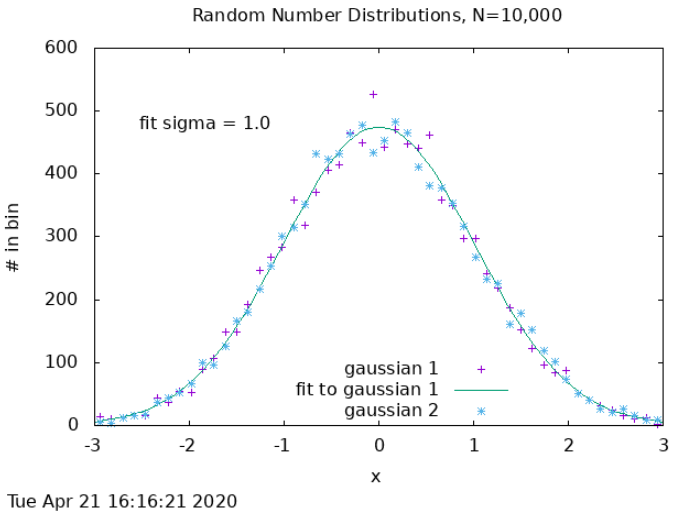


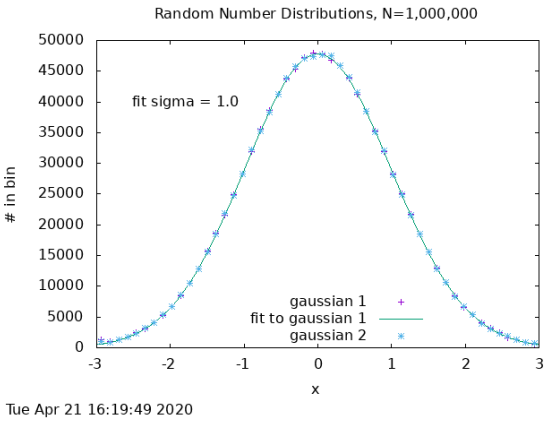


I couldn't get the xticks to work like I wanted, but the uniform distributions look flat as expected, and the gaussians take on the nice bell-curve shapes we want. These look like good random distributions.

4. Run gaussian_random_new.plt to plot and fit the gaussian distributions with gnuplot. Try 1,000,000 points and 10,000 points. *Do you reproduce the parameters of the gaussian distribution?* (You may need to set b to a reasonable starting point such as the approximate peak height to get a useful fit.)







I needed to seed the N = 1,000,000 fit with the amplitude in order to reproduce the parameters, but we were able to reproduce the parameters of the gaussian each time.

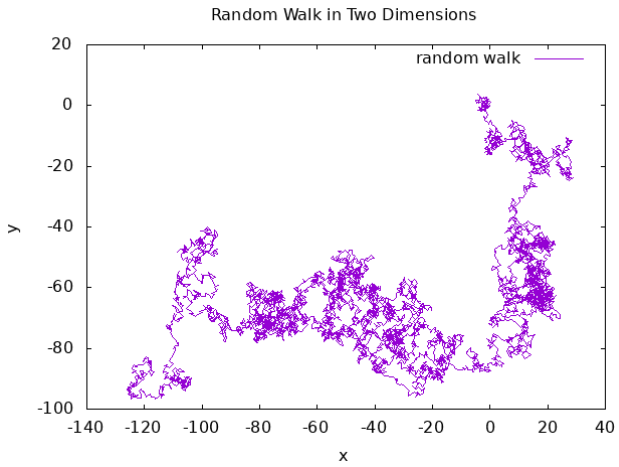
Random Walking

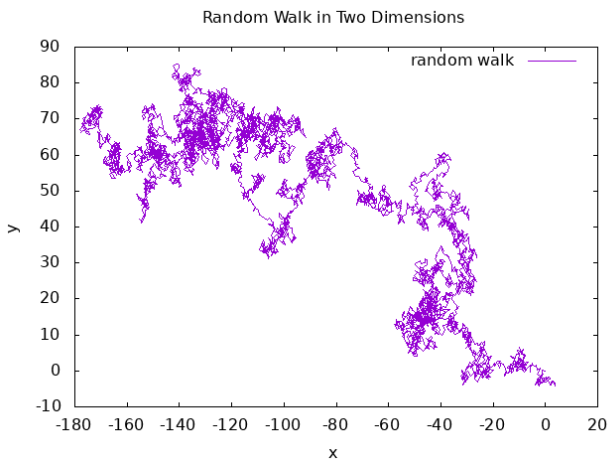
We'll generate random walks in two dimensions using method 2 from the list in Section b of the Activities 12 notes. In particular we'll start at the origin: (x,y) = (0,0) and for each step select Delta_x at random in the range [-sqrt(2), sqrt(2)] and Delta_y in the same range. So positive and negative steps in each direction are equally likely. The code random_walk.cpp implements this plan.

1. *What is the rms step length?* (Note: this is tricky!)

I think since <delta_x^2 + delta_y^2> = sqrt(2)/2 + sqrt(2)/2 = sqrt(2), rms step length is the square root of that → rms step length is 2^(1/4).

2. Look at the random_walk.cpp code and identify where the random number generator is allocated, seeded, and called. Compile and link the code (use make_random_walk) and generate a random walk of 6400 steps.
3. *Plot the random walk (stored in "random_walk.dat") using gnuplot (use "with lines" to connect the points).* Repeat a couple of times to get some intuition for what the walks look like.





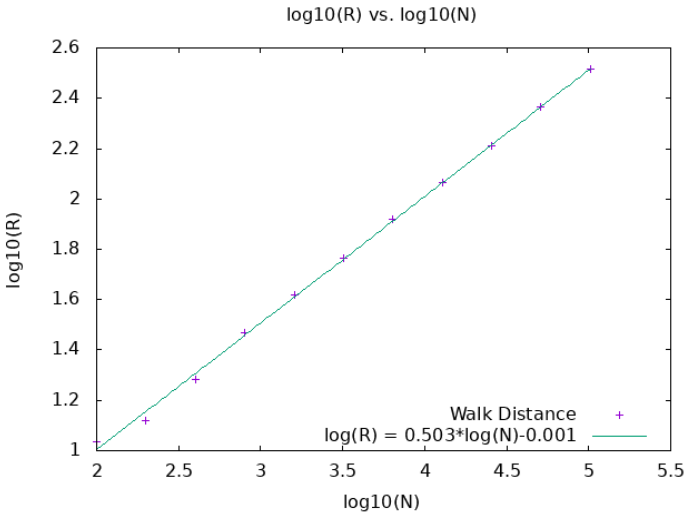
4. Check (using an editor) for the endpoints of a few walks. *Roughly how does a typical distance R from the origin scale with N? (Can you reproduce the derivation from the notes of how the average of R scales with N?)*

The theory predicts that R should scale with the square root of N, and that seems to roughly be the case from the few walks I've run. I understand why the cross-terms (xy terms) drop in the derivation and understand why we end up with a square root of N.

5. Now we'll study more systematically how the final distance from the origin R = sqrt(x_final^2 + y_final^2) scales with the number of steps N. Note that now we don't need to save anything from a run except the value of R. The value of R will fluctuate from run to run, so for each N we want to average over a number of trials. *How many trials should you use?*

I ended up running N/2 trials which was probably too many.

Edit the code to make multiple runs for each value of N and takes the average of R. *Make (and sketch) an appropriate plot that reveals the dependence of R on N.* [The code random_walk_length.cpp and plot file random_walk_length.plt implement this task. Try it yourself before looking at those.] *Does it agree with expectations?*



This is a log-log plot of R vs. N with a linear fit. Note that the slope of the fit is ½, meaning R increases with the square root of N.

This agrees with our expectations.

Monte Carlo Integration: Uniform and Gaussian Sampling

Your goal is to estimate the D-dimensional integral of

$$(x1 + x2 + \ldots + xD)^2 \; 1/(2\pi \; \sigma^2)^{D/2} \; \exp(-(x1^2+x2^2+\ldots+xD^2)/(2 \; \sigma^2))$$

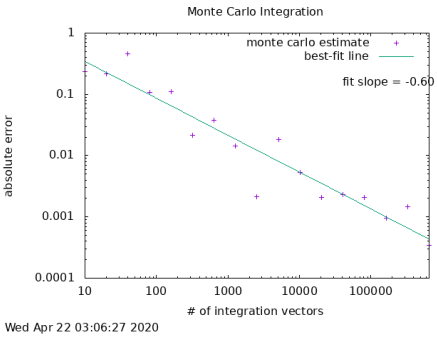
where each of the variables ranges from -infinity to +infinity. The exact answer is $D*\sigma^2$. [Note that the integral without the squared sum in front is normalized to be one.]

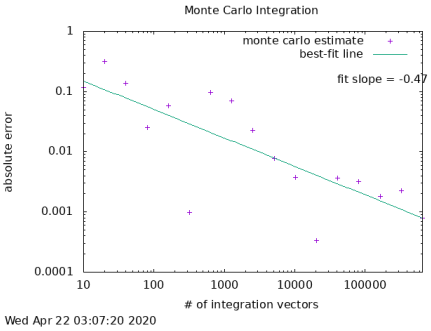
The basic Monte Carlo integration method is described in Section d of the Activities 12 notes. In particular, equations (12.15) and (12.16) show that the integral is given approximately by the range(s) times the average of the function evaluated at N random vectors. (So for a 5-dimensional integral, each vector is a set of 5 random numbers {x1,x2,x3,x4,x5}.)

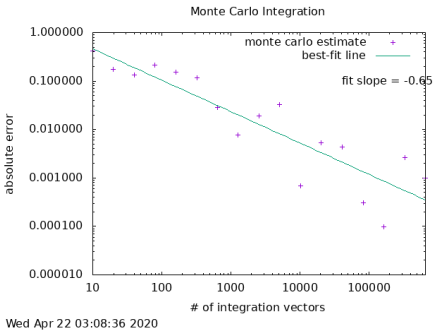
1. Look at mc_integration.cpp to see how this is implemented for our test integral. Because the integral has infinite limits, we approximate it with finite lower and upper limits. *How would you choose these?*

I would set some acceptable error tolerance, and find where our function drops below that.

2. The dimension is initially set to D=1 (called dim in the code). Compile it with make_mc_integration and run it several times. After each run, use mc_integration.plt to make a fitted plot of the error. *What do you observe?*







3. Next try changing the dimension to 3 and then to 10, repeating the last part. *What do you observe? Is it consistent with the notes?*

The slope doesn't change as we increase the dimension.
This agrees with the discussion in the notes that the error in monte-carlo integration doesn't scale with the dimension.

4. If you have time, modify the code to apply equations (12.34) and (12.35), where we identify w(x) as the normalized gaussian part of the integral and use the GSL routine for generating gaussian-distributed random numbers (from gaussian_random.cpp). [If you are short of time, use mc_integration_new.cpp.] *What should the integrand function return in this case?*

Repeat the analysis in different dimensions. *Why are the results better than for uniform sampling? Can you do D=100?*

Monte Carlo Integration: GSL Routines

Run a test program to do a simple D-dimensional integral as in the last section but with the Vegas and Miser programs.

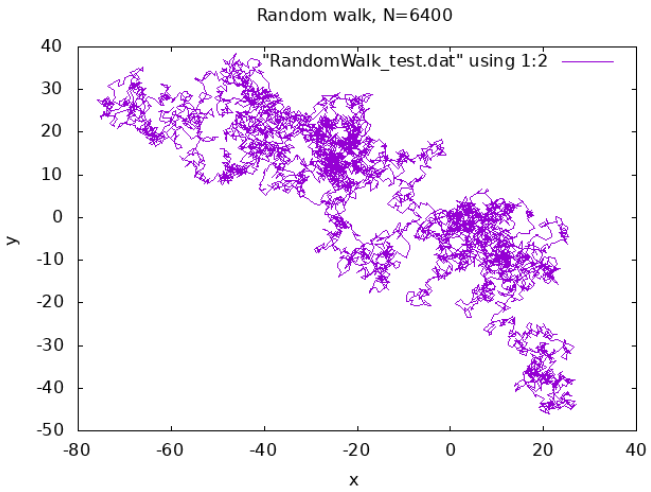
1. Take a look at the program gsl_monte_carlo_test.cpp while also looking at Monte Carlo integration in the online GSL library.
2. The initial integral is not a great test. After compiling and running the program, change the integrand to something more interesting (use your imagination!). Don't worry about knowing the exact answer; compare the results from the different routines. *What do you find?*

I tried running on an integrand of exponential and trigonometric functions. All three routines agreed on a result, although I have no idea if it's right.
I tried adding a cross-terms as well, so that the different x_i's would mix. Still the routines agreed on a result.
The error reported is also very good as well, with a sigma of in the 10^-3 region for all three routines.
I tried adding a rational function to the integral as well → 1/(1+x_i * x_(i-1)). The subroutines still agreed.
A common thread across all of these is that the sigma for the vegas subroutine is usually the lowest, even if they all have about the same order of magnitude.
The vegas method also has to "warmup," so I'm guessing that if we want speed we should use the Miser subroutine and if we want more accuracy we should use the Vegas subroutine.

C++ Class for a Random Walk

The random walk code random_walk.cpp is basically written as a C code with C++ input and output. Here we reimplement the code as a C++ class.

1. In the RandomWalk directory, compile and link RandomWalk_test (using make_RandomWalk_class_test). Run it to generate "RandomWalk_test.dat", which you should plot with gnuplot to verify that the output looks the same as from random_walk.cpp.



This looks like the same random walks we are used to seeing

2. Compare the old and new code (you have printouts of each). Discuss with your partner the advantages (and any disadvantages) of the definition of RandomWalk as a class. List some.

I don't have a partner with me right now, but restructuring this as a class has made the actual code we run much more compact and readable.
One disadvantage is that the code is spread across multiple files so there are more pieces to keep track of and it is more difficult to set up. However, if you are handed a working product (as we were), this is a much more convenient format for it to be in.

3. An advantage of programming with classes is the ease of extending or generalizing a code. List two ways to extend the class definition.

4. As time permits, modify the code to do the following:
   - Extend the code to make available (with "get" functions) the x- and y-components of the last step (what are called delta_x and delta_y internally).

I didn't know how to do this inside the class, since the class object doesn't know how long the walk is going to be, but I added an output in the code using the get functions to print the final step to the screen.

   - Allow for the upper and lower limits of the step size to be initialized by the user. (And you still want to be able to use the current version that doesn't require these.) [Hint: Can you have more than one constructor?]

I am not skilled enough with C++ classes to make another constructor, so I just modified the current constructor to take in more arguments and updated the code.

   - *How would you allow for the random number generator to be changed? Implement it!*

I didn't get to this, but it would be cool if the user could choose between uniform and gaussian.