

view_frames Result
Recorded at time: 1759990545.6172092

prius_hybrid/odom

Broadcaster: default authority
Average rate: 41.324
Buffer length: 4.38
Most recent transform: 53753.82
Oldest transform: 53749.44

map

prius_hybrid/base_footprint

Broadcaster: default authority
Average rate: 42.381
Buffer length: 4.2
Most recent transform: 53753.81
Oldest transform: 53749.61

Broadcaster: default authority
Average rate: 42.143
Buffer length: 4.2
Most recent transform: 53753.82
Oldest transform: 53749.62

Broadcaster: default authority
Average rate: 42.857
Buffer length: 4.2
Most recent transform: 53753.82
Oldest transform: 53749.62

robot3/odom

robot1/odom

robot2/odom

robot3/base_footprint

robot1/base_footprint

robot2/base_footprint

robot3/base_link

robot1/base_link

robot2/base_link

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 162.685
Buffer length: 4.395
Most recent transform: 53753.83
Oldest transform: 53749.435

Broadcaster: default authority
Average rate: 162.685
Buffer length: 4.395
Most recent transform: 53753.83
Oldest transform: 53749.435

Broadcaster: default authority
Average rate: 162.685
Buffer length: 4.395
Most recent transform: 53753.83
Oldest transform: 53749.435

Broadcaster: default authority
Average rate: 162.685
Buffer length: 4.395
Most recent transform: 53753.83
Oldest transform: 53749.435

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 161.312
Buffer length: 4.42
Most recent transform: 53753.83
Oldest transform: 53749.41

Broadcaster: default authority
Average rate: 161.312
Buffer length: 4.42
Most recent transform: 53753.83
Oldest transform: 53749.41

Broadcaster: default authority
Average rate: 161.312
Buffer length: 4.42
Most recent transform: 53753.83
Oldest transform: 53749.41

Broadcaster: default authority
Average rate: 161.312
Buffer length: 4.42
Most recent transform: 53753.83
Oldest transform: 53749.41

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 200.296
Buffer length: 3.38
Most recent transform: 53753.83
Oldest transform: 53750.45

Broadcaster: default authority
Average rate: 200.296
Buffer length: 3.38
Most recent transform: 53753.83
Oldest transform: 53750.45

Broadcaster: default authority
Average rate: 200.296
Buffer length: 3.38
Most recent transform: 53753.83
Oldest transform: 53750.45

Broadcaster: default authority
Average rate: 200.296
Buffer length: 3.38
Most recent transform: 53753.83
Oldest transform: 53750.45

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot3/left_caster_plate_link

robot3/left_wheel_link

robot3/right_caster_plate_link

robot3/right_wheel_link

robot3/airy_back_link

robot3/airy_front_link

robot3/jt16_center_link

robot1/left_caster_plate_link

robot1/left_wheel_link

robot1/right_caster_plate_link

robot1/right_wheel_link

robot1/airy_back_link

robot1/airy_front_link

robot1/jt16_center_link

robot2/left_caster_plate_link

robot2/left_wheel_link

robot2/right_caster_plate_link

robot2/right_wheel_link

robot2/airy_back_link

robot2/airy_front_link

robot2/jt16_center_link

Broadcaster: default authority
Average rate: 162.685
Buffer length: 4.395
Most recent transform: 53753.83
Oldest transform: 53749.435

Broadcaster: default authority
Average rate: 162.685
Buffer length: 4.395
Most recent transform: 53753.83
Oldest transform: 53749.435

Broadcaster: default authority
Average rate: 161.312
Buffer length: 4.42
Most recent transform: 53753.83
Oldest transform: 53749.41

Broadcaster: default authority
Average rate: 161.312
Buffer length: 4.42
Most recent transform: 53753.83
Oldest transform: 53749.41

Broadcaster: default authority
Average rate: 200.296
Buffer length: 3.38
Most recent transform: 53753.83
Oldest transform: 53750.45

Broadcaster: default authority
Average rate: 200.296
Buffer length: 3.38
Most recent transform: 53753.83
Oldest transform: 53750.45

robot3/left_caster_wheel_link

robot3/right_caster_wheel_link

robot1/left_caster_wheel_link

robot1/right_caster_wheel_link

robot2/left_caster_wheel_link

robot2/right_caster_wheel_link