

## PDE II PROJECT 1

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### 1. QUESTION 1

**1.1. Approach to Problem.** We want to find the solution  $u(x, t)$  that solves the initial boundary-value problem:

$$\begin{aligned} u_t &= u_{xx} + 25x(1 - x^2), \quad 0 \leq x \leq 1, \quad 0 \leq t \leq 0.3 \\ u(0, t) &= 0, \quad u(1, t) = 0.9 \quad \forall t, \quad u(x, 0) = 0.9 \sin\left(\frac{\pi x}{2}\right) \end{aligned}$$

To approximate this solution, we will split the solution into two parts, one which satisfies the boundary conditions and one which satisfies zero boundary conditions. Let  $v(x, t)$  be a solution with zero boundary conditions and  $g(x, t)$  be the solution satisfying the boundary condition. That is:

$$u(x, t) = v(x, t) + g(x, t)$$

Where  $v(x, t)$  satisfies the inhomogenous initial boundary-value problem with zero boundary conditions, this will be solved by the Crank-Nicolson method as later described. Now,  $v(x, t)$  is a solution to the following problem:

$$\begin{aligned} v_t &= v_{xx} + \tilde{f}(x, t), \quad 0 \leq x \leq 1, \quad 0 \leq t \leq 0.3 \\ v(0, t) &= 0, \quad v(1, t) = 0 \quad \forall t, \quad v(x, 0) = v_0(x) \end{aligned}$$

Using the lecture notes, we can define  $g(x, t)$  as:

$$g(x, t) = \mu_1(t) + \frac{(\mu_2(t) - \mu_1)}{L} x$$

where  $u(0, t) = \mu_1(t) = 0$ ,  $u(1, t) = \mu_2(t) = 0.9$  and  $L = 1$ . We therefore obtain:

$$g(x, t) = g(x) = 0.9x$$

We can also find  $\tilde{f}(x, t)$  and  $v_0(x)$  using the formulae in the lecture notes:

$$\begin{aligned} \tilde{f}(x, t) &= f(x, t) - \frac{\partial g}{\partial t}(x, t) + K \frac{\partial^2 g}{\partial x^2}(x, t) \\ &= 25x(1 - x^2) \end{aligned}$$

and

$$\begin{aligned} v(x, 0) &= u(x, 0) - g(x, 0) \\ (1) \quad &= 0.9 \sin\left(\frac{\pi x}{2}\right) - 0.9x \end{aligned}$$

**1.1.1. Crank-Nicolson.** Using the lecture notes to obtain the Crank-Nicolson method for the inhomogeneous heat equation (with zero boundary conditions), we have the approximation for  $v(x, t)$  is:

$$\frac{w_{i,j+1} - w_{i,j}}{\tau} - K \frac{(w_{k+1,j+1} - 2w_{k,j+1} + w_{k-1,j+1} + w_{k+1,j} - 2w_{k,j} + w_{k-1,j})}{2h^2} = f(x_k, t_j + \tau/2)$$

In our problem,  $K = 1$  and  $f(x, t) = 25x(1 - x^2)$ . We also replace the right-hand side of the equation by:

$$\frac{1}{2} (f(x_k, t_j) + f(x_k, t_{j+1})) = f(x_k)$$

We have been able to simplify this since our  $f$  has no time dependence and therefore  $f(x_k, t_{j+1}) = f(x_k, t_j)$ . We also Taylor expanded the term  $f(x_k, t_j + \tau/2)$  prior to simplifying it. We can now re-write the equation so that we can use the double-sweep method.

1.1.2. *Double-Sweep Method.* We can re-write the general double-sweep formula from the lecture notes to our specific problem.

$$\underbrace{\frac{\gamma}{2}w_{k-1,j+1}}_{A_i} - \underbrace{(1+\gamma)w_{k,j+1}}_{C_i} + \underbrace{\frac{\gamma}{2}w_{k+1,j+1}}_{B_i} = \underbrace{-(1-\gamma)w_{k,j} - \frac{\gamma}{2}w_{k+1,j} - \frac{\gamma}{2}w_{k-1,j} - \tau f(x_k, t_j)}_{F_i}$$

Now we will be able to find the  $\alpha_i$ s and  $\beta_i$ s required.

$$\alpha_{i+1} = \frac{\frac{\gamma}{2}}{1 + \frac{\gamma}{2}(2 - \alpha_i)}$$

$$\beta_{i+1} = \frac{\frac{\gamma}{2}\beta_i - F_i}{1 + \frac{\gamma}{2}(2 - \alpha_i)}$$

1.2. **MATLAB solution.** My solution to this problem is based on the “crank\_nicol\_heat.m” solution to Exercise 2 of the 4th practical session. The following code is typed into the Command Window before my function file is called:

```
>> x = (0:30)/30;
>> T = 0.3;
>> M = 30;
>> u0 = 0.9*sin(pi*x/2);
```

The  $x$  variable represents the 31 grid points from 0 to 1. The  $T$  term denotes the end point of our time grid, as specified in the question, whilst  $M+1$  is how many grid points we want to consider for  $t$ . I chose this value of  $M$  so that we will be able to slice our solution at times  $t = 0, 0.1$ , and  $0.3$  which is required in the next question. The last line of code specifies the initial condition of the problem through  $u_0$ . We then call the function “project\_c\_n.m” which returns the surface plot of our approximation of the solution to  $u(x, t)$  as well as the matrix used to produce this plot; this function is called using the following command in the Command Window:

```
>> u = project_c_n(T, M, x, u0);
```

1.2.1. *The Function File.* In the function file `project_c_n.m`, we split the problem into two sections, first we approximate the solution of  $v(x, t)$  using the Crank-Nicolson and double-sweep method, then we find  $g(x, t)$  by evaluating the function on the grid  $x$ . At the end of the function file, we then add the two solutions together to obtain  $u(x, t)$  and return the surface plot. First, the function calculates the step size in time and space, it then creates a grid for  $t$  based on the  $T$  and  $M$  inputs. It then calculates the initial condition of  $v(x, t)$  from the initial condition  $u_0$ , using the equation (1).

To perform the double sweep method, we first note that  $\alpha_1$  and  $\beta_1$  are 0 since  $v(x, t)$  is 0 at the boundary. We then implement nested loops as seen in the function file to calculate all the  $\alpha_i$  and  $\beta_i$  coefficients before performing the backwards sweep to calculate the entries of the matrix  $w$ .

Finally, we calculate  $g(x, t)$  at every spacial step. Since  $g(x, t)$  does not depend on  $t$ , we obtain a matrix which consists of a vector, repeated at every time step. This is then added to  $w$ , our approximation for  $v(x, t)$ , to obtain  $u(x, t)$ . The `surf` function is then called after transposing  $u$ , to obtain the required surface plot. Note that in our function  $u$  is returned so that we can answer the next question.

## 2. QUESTION 2

To plot  $u(x, t)$  against  $x$  at different time intervals, we use the matrix  $u$  that was returned when we called the function file in the previous section. By slicing the matrix at points where  $t = 0, 0.1$ , and  $0.3$  separately, we obtain the values of  $u$  over the range  $x \in [0, 1]$  as required. We then call a separate file named `plot_u_on_single_figure.m` which takes the inputs  $x$  and  $u$  (the output of the `project_c_n.m` function) and returns the plot required. In the command window, this is called by:

```
>> plot_u_on_single_figure(x, u);
```

where  $x$  is the grid we defined at the start. The file `plot_u_on_single_figure.m` uses the `plot` and `hold on` commands to produce multiple plots in a single figure.