Project Proposal

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DATASET

METHODS

RESULTS

NEXT STEPS

REFERENCES

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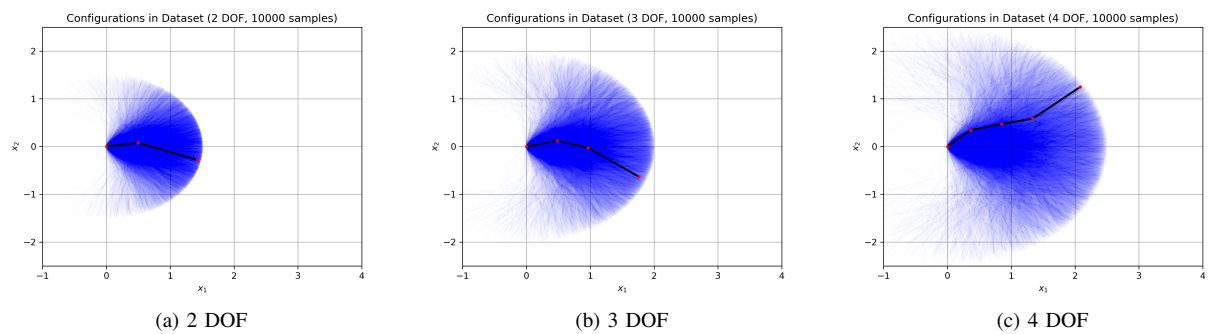
| (a) 2 DOF | (b) 3 DOF | (c) 4 DOF |

Fig. 1. Illustration of datasets used during training of models. Only a subset of the samples contained in the datasets is shown here. One configuration in the dataset is highlighted to illustrate the configuration of the robot arm.