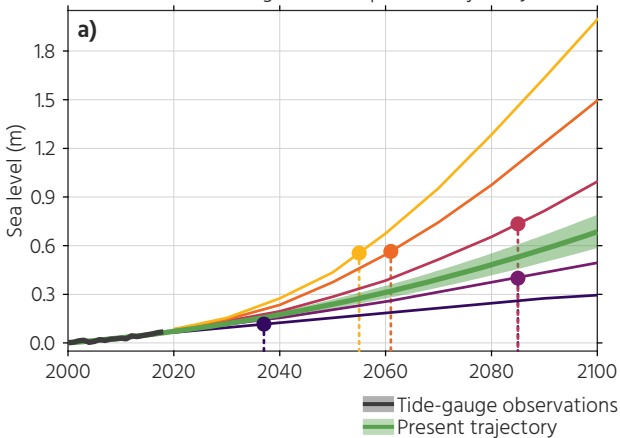


Scenario divergence from present trajectory



Scenario divergence from Intermediate

