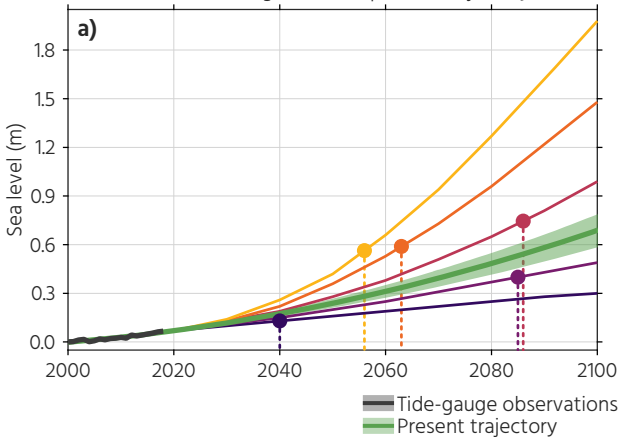


Scenario divergence from present trajectory



Projection divergence from Intermediate

