

Functional networks expand across anatomical boundaries as correlation time-scale increases

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Abstract

Decades of research has established that correlations play a crucial role in representing sensory information. One drawback associated with the recent improvement in recording technology and consequent large datasets is the difficulty in analysing higher order correlations in large neuronal ensembles. One benefit of these datasets that has not yet been explored is the opportunity to compare correlations within anatomical regions to correlations across anatomical regions. In this work, we measured correlations between neurons residing in nine different brain regions in three awake and behaving mice. Using these correlation measurements, we created weighted undirected graph networks and applied network science methods to detect functional communities in our neural ensembles. We compared these functional communities to their anatomical distribution. We repeated the analysis, using different timescales for our correlation measurements, and found that functional communities were more likely to be dominated by neurons from a single brain region at shorter timescales ($< 100\text{ms}$).

1 Introduction

Decades of research has established that correlations play a crucial role in representing sensory information. For example, the onset of visual attention has been shown

to have a greater affect on the correlations in the macaque V4 region than on the firing rates in that region [1]. Recent findings show that spontaneous behaviours explain correlations in parts of the brain not associated with motor control [4]. In order to understand the brain, we must understand the interactions between neurons.

Because of limitations in recording technology almost all research has explored correlations between neurons within a given brain region. Relatively little is known about correlations between neurons in different brain regions. However, the recent development of ‘Neuropixels’ probes [6] has allowed extracellular voltage measurements to be collected from multiple brain regions simultaneously routinely, and in much larger numbers than traditional methods. In this project we used a publicly-available Neuropixels dataset to analyse correlations between different brain regions [4].

A drawback associated with the improvement in recording technology is an increase in the difficulty of analysing these data. For example, analysing the i th order interactions of N neurons generally requires estimation of N^i parameters. A number that becomes astronomical for large N . New methods are required for analysing these new large datasets. We attempted to address this requirement in this piece of research by applying a cutting-edge network science community detection method to neural data.

Another unexplored area of research is the changes in cell interactions at different timescales. Most studies focus on quantifying interactions at a given timescale. But neurons may interact differently, or may interact with different neurons, at different timescales. Here we explore correlated communities of neurons at different timescales.

In this work, we measured spike count correlations between neurons from nine different regions of the mouse brain. Using these correlation measurements, we created weighted undirected graphs or networks with each node representing a neuron. We used newly invented network methods to detect communities in these networks. We compared these detected communities to the anatomical division of the cells. We also measured the conditional correlation and signal correlation of between cell spike counts, conditioning on the subjects’ behaviour. We repeated the network analysis using these measurements. We also repeated these analyses using different timescales for measuring the correlations.

2 Results

2.1 Average correlation size increases with increasing time bin width

First we inspected the affect of time bin width on spike count correlations. We know that using short time bins results in artificially small correlation measurements[?], so we expected to see an increase in correlation amplitude with increasing time bin width. That is exactly what we observed. Taking 50 cells at random, we calculated the spike count correlation between every possible pair of these cells, using different time bin widths ranging from 0.005s to 3s. We found that the longer the time bin width, the greater the correlations (see figure 1a).

We also separated the positively correlated pairs from the negatively correlated pairs using the mean correlation of each pair across all bin widths (see section 5.2.3). We found that the positively correlated pairs become more positively correlated with increasing time bin width, and the negatively correlated pairs become more negatively correlated with increasing time bin width (see figures 1b and 1c).

When taking the mean across all pairs, the positively correlated pairs dominate in terms of both number of pairs, and amplitude of correlations. Therefore the mean across all pairs is positive.

These results were observed in each of the three mouse subjects from which we had data.

2.2 Goodness-of-fit for Poisson and Gaussian distributions across increasing time bin widths

We wanted to investigate if the width of the time bin used to bin spike times into spike counts had an effect on the distributon of spike counts. We used the χ^2 statistic as a goodness-of-fit measure for Poisson and Gaussian (normal) distributons to the spike count of 100 randomly chosen neurons for a number of bin widths ranging from 0.01s to 4s. For the χ^2 statistic, the higher the value, the worse the fit. As you might expect, we found that that a Poisson distributon is the best fit for shorter time bins less than 0.7s in length. Then a Gaussian distribution is a better fit for time bins greater than 0.7s in length (see figure 1d).

87 A Poisson distributon was very likely to be a better fit for shorter time bin widths
 88 because spike counts must be non-negative, therefore any distributon of spike counts
 89 with mass distributed at or close to 0 will be skewed.

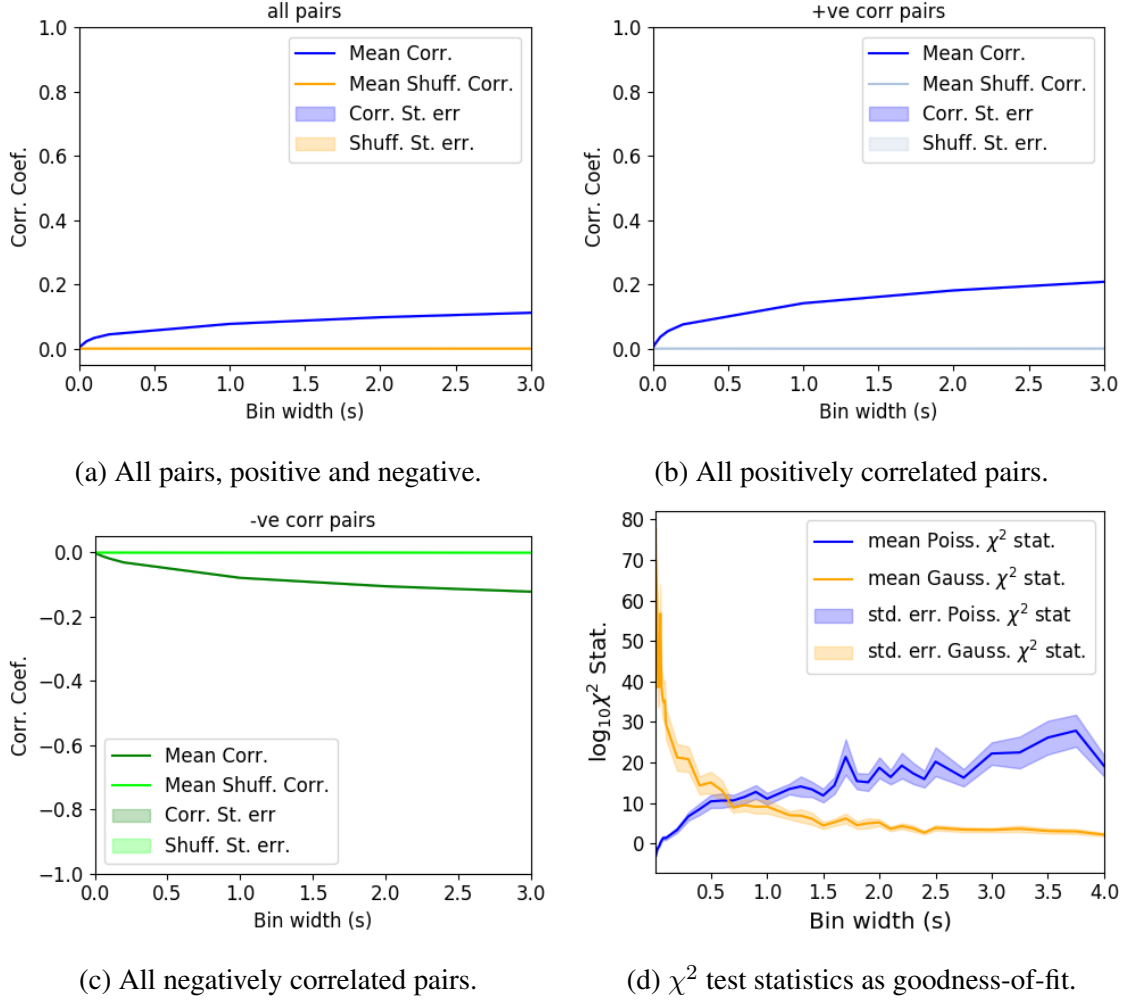
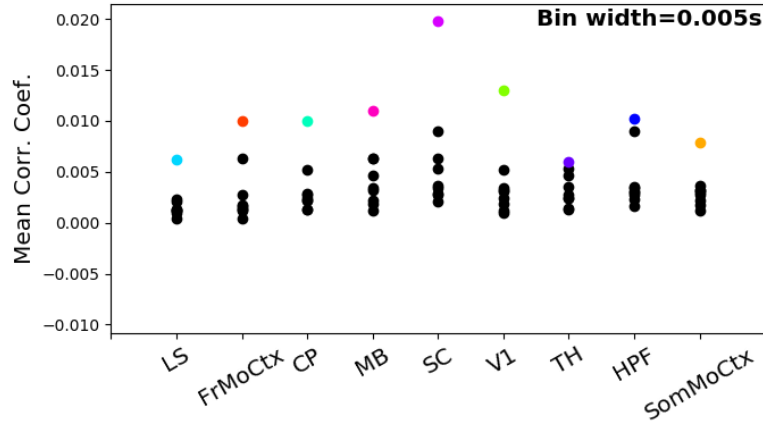


Figure 1: Mean correlation coefficients measured from pairs of 50 randomly chosen neurons. (a) All possible pairs, (b) positively correlated pairs, and (c) negatively correlated pairs. (d) Mean and standard error of χ^2 test statistics for Poisson and Gaussian distributions fitted to neuron spike counts.

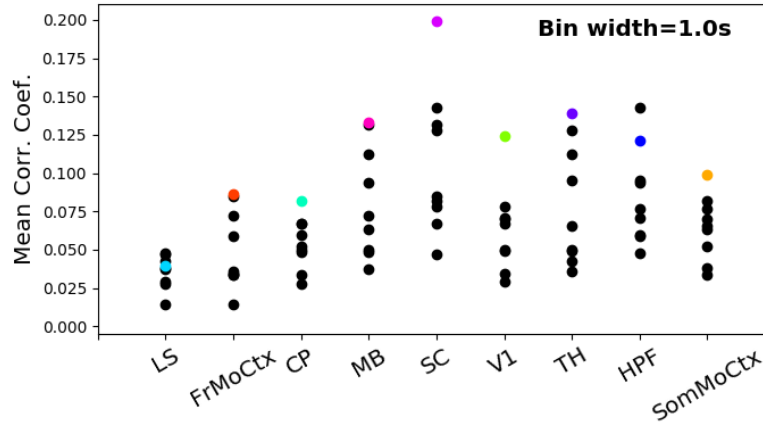
2.3 Differences between and inter- and intra- regional correlations decrease with increasing bin width

We investigated the differences in distribution between inter-regional correlations, i.e. correlations between neurons in different brain regions, and intra-regional correlations, i.e. correlations between neurons in the same brain region. Firstly, we

noted that the mean intra-regional correlations for a given region tended to be higher than the mean inter-regional correlations involving cells from that region. Secondly, we noted that the difference between the mean intra-regional correlations and mean inter-regional correlations reduced as we increased the time bin width (see figures 2a and 2b).



(a) Mean inter-regional and intra-regional correlations using a time bin width of 5ms.



(b) Mean inter-regional and intra-regional correlations using a time bin width of 1s.

Figure 2: The mean intra-regional correlations (coloured dots) and mean inter-regional correlations (black dots) for a given region, indicated on the x-axis, for different time bin widths. Each black dot represents the mean inter-regional correlations between the region indicated on the x-axis and one other region. (a) shows these measurements when we used a time bin width of 5ms. (b) shows these measurements when we used a time bin width of 1s. Note that the difference between the mean inter-regional correlations and mean intra-regional correlations is smaller for 1s bins.

2.4 Detecting communities in correlation based networks

2.5 Functional communities resemble anatomical division at short timescales

2.6 Conditional correlations & signal correlations

3 Discussion

To be added.

4 Data

The data that we used in this project were collected by Nick Steinmetz and his lab members[4].

4.1 Brain regions

Neuropixels probes were used to collect extracellular recordings [6] from three different mice. The mice were awake, headfixed, and engaging in spontaneous behaviour. The mice were of different sexes and different ages. One mouse was ‘wild-type’, the others were mutants. Details as follows:

1. male, wild type, P73.
2. female, TetO-GCaMP6s, Camk2a-tTa, P113
3. male, Ai32, Pvalb-Cre, P99

Eight probes were used to collect readings from 2296, 2668, and 1462 cells respectively. Data were collected from nine brain regions in each mouse:

- Caudate Putamen (CP)
- Frontal Motor Cortex (Frmctx)
- Hippocampal formation (Hpf)
- Lateral Septum (Ls)
- Midbrain (Mb)

- 124 • Superior Colliculus (Sc)
- 125 • Somatomotor cortex (Sommctx)
- 126 • Thalamus (Th)
- 127 • Primary visual cortex (V1)

128 Readings were continuous and lasted for about 1 hour [4]. Locations of each of the
 129 probes can be seen in figure 3.

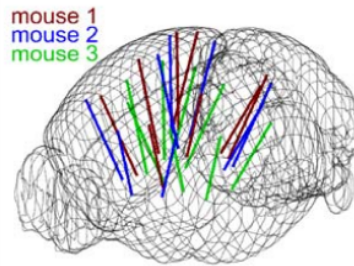


Figure 3: **Probe Locations:** The locations of the probes in each of the three mouse brains[4].

130 4.2 Video recordings

131 Video recordings of the mouse’s face were taken during the spontaneous behaviour.
 132 We had access to the top 500 principle components and top 500 eigenvectors of the
 133 processed videos. The frequency of recording was slightly less than 40Hz. Each
 134 frame contained 327×561 pixels. These principal components were used as be-
 135 havioural data. We controlled for these components when taking measurements con-
 136 ditioned on behaviour.

137 5 Methods

138 5.1 Binning data

139 We transoformed the spike timing data into binned spike count data by dividing the
 140 experimental period into time bins and counting the spikes fired by each cell within
 141 the time period covered by each of those bins. The data were divided into time bins
 142 of various widths ranging from 0.01s to 4s.

143 If the total length of the recording period was not an integer multiple of the time
 144 bin width, we cut off the remaining time at the end of the recording period. This
 145 period was at most 3.99s. This is far less than the total recording time of around 1
 146 hour. So, this detail would not affect our results.

147 5.2 Correlation coefficients

We calculated Pearson’s correlation coefficient for pairs of spike counts from pairs of neurons. For jointly distributed random variables X and Y , Pearson’s correlation coefficient is defined as:

$$\rho_{XY} = \frac{\text{cov}(X, Y)}{\sigma_X \sigma_Y} \quad (1)$$

$$= \frac{E[(X - \mu_X)(Y - \mu_Y)]}{\sigma_X \sigma_Y} \quad (2)$$

148 where E denotes the expected value, μ denotes the mean, and σ denotes the stan-
 149 dard deviation. The correlation coefficient is a normalised measure of the covari-
 150 ance. It can take values between 1 (completely correlated) and -1 (completely anti-
 151 correlated). Two independent variables will have a correlation coefficient of 0. But,
 152 having 0 correlation does not imply independence.

If we do not know the means and standard deviations required for equation 1, but we have samples from X and Y , Pearson’s sample correlation coefficient is defined as:

$$r_{XY} = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2} \sqrt{\sum_{i=1}^n (y_i - \bar{y})^2}} \quad (3)$$

153 where $\{(x_i, y_i)\}$ for $i \in \{1, \dots, n\}$ are the paired samples from X and Y , and
 154 $\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i$, and $\bar{y} = \frac{1}{n} \sum_{i=1}^n y_i$ are the sample means.

155 In practice we used the python function `scipy.stats.pearsonr` to calcu-
 156 late the correlation coefficients.

157 5.2.1 Spike Count Correlation, r_{SC}

158 The spike count correlation (r_{SC}) of two cells is the correlation between the spike
 159 counts of those cells in response to a given stimulus condition. In this study, there

was only one stimulus condition, that of no stimulus. The subjects engaged in spontaneous behaviour during recording.

5.2.2 Shuffled spike count correlations

We measured the shuffled spike count correlations between two neurons by randomly permuting one of the neuron's spike counts and measuring the spike count correlations. These shuffled correlations were useful when measuring the effect of time bin width on correlations, and when deciding which correlations should be preserved when creating correlation networks (see section 5.5.3).

5.2.3 Separating Correlations & Anti-correlations

In order to compare the effect of bin width on measures of negative r_{SC} (anti-correlation) and positive r_{SC} separately, we had to separate correlated and anti-correlated pairs. To do this, we simply measured the mean r_{SC} , taking the mean across all the bin widths. If this quantity was positive or zero we regarded the pair as positively correlated. If this quantity was negative we regarded the pair as anti-correlated.

5.3 Conditioning on behavioural data

Our behavioural data consisted of the top 500 principal components (PCs) of a processed video recording of the mouse's face (see section 4.2). Denoting the spike count of a given cell by X , and the PCs by Z_1, \dots, Z_{500} , we wanted to model X as a function of Z_1, \dots, Z_{500} in order to estimate

$$E[X|Z_1, \dots, Z_{500}] = \int_{x \in X} x P(X = x|Z_1, \dots, Z_{500}) dx \quad (4)$$

$$= \int_{x \in X} x \frac{P(X = x, Z_1, \dots, Z_{500})}{P(Z_1, \dots, Z_{500})} dx \quad (5)$$

Given the 500 components, a naïve estimation of $P(Z_1, \dots, Z_{500})$ or $P(X, Z_1, \dots, Z_{500})$ by histogramming was impossible. Therefore we modelled X as a linear combination of the PCs.

5.3.1 Linear regression

We modelled the spike count of a given cell, X , as a linear combination of the PCs of the video of the mouse’s face, $\mathbf{Z} = Z_1, \dots, Z_{500}$. We tried three different types of regularization

- $L1$ or ‘Lasso’
- $L2$ or ‘Ridge regression’
- ‘Elastic net’ regularisation (a linear combination of both $L1$ and $L2$ regularisation penalties)

The elastic net regularisation performed the best, so we stuck with that.

5.3.2 Elastic net regularisation

Suppose we wish to model n observations of a random variable X , $\mathbf{x} = (x_1, \dots, x_n)$ using n instances of m predictors $\mathbf{Z} = (Z_1, \dots, Z_m)$. The naïve elastic net criterion is

$$L(\lambda_1, \lambda_2, \boldsymbol{\beta}) = |\mathbf{x} - \mathbf{Z}\boldsymbol{\beta}|^2 + \lambda_2|\boldsymbol{\beta}|_2 + \lambda_1|\boldsymbol{\beta}|_1 \quad (6)$$

where

$$|\boldsymbol{\beta}|_2 = \sum_{j=1}^m \beta_j^2 \quad (7)$$

$$|\boldsymbol{\beta}|_1 = \sum_{j=1}^m |\beta_j| \quad (8)$$

The naïve elastic net estimator $\hat{\boldsymbol{\beta}}$ is the minimiser of the system of equations 6 [12]

$$\hat{\boldsymbol{\beta}} = \arg \min_{\boldsymbol{\beta}} L(\lambda_1, \lambda_2, \boldsymbol{\beta}) \quad (9)$$

We implemented the model using the `ElasticNetCV` method of Python’s `sklearn.linear_models` package.

As well as using the PCs, we also tried fitting the models using the raw video data reconstructed from the PCs and eigenvectors. These models performed worse than those using the PCs. We expected this because each representation contains the same amount of information, but the raw video representation spreads this information

195 across many more components. This requires more parameter fitting, but given the
 196 same information.

197 **5.3.3 Conditional covariance**

We calculated the expected value of the conditional covariance using the law of total covariance.

$$\text{cov}(X, Y) = E[\text{cov}(X, Y|Z)] + \text{cov}(E[X|Z], E[Y|Z]) \quad (10)$$

198 where these expected values are calculated with respect to the distribution of Z as a
 199 random variable.

Using our linear model, we calculated $E[X|Z_1, \dots, Z_{500}]$ for each cell X . Then we proceeded to calculate

$$E[\text{cov}(X, Y|Z_1, \dots, Z_{500})] = \text{cov}(X, Y) - \quad (11)$$

$$\text{cov}(E[X|Z_1, \dots, Z_{500}], E[Y|Z_1, \dots, Z_{500}]) \quad (12)$$

200 **5.3.4 Measures of conditional correlation**

As a measure of expected correlation, we measured the ‘event conditional correlation’ [13]

$$\rho_{XY|Z} = \frac{E[\text{cov}(X, Y|Z)]}{\sqrt{E[\text{var}(X|Z)]E[\text{var}(Y|Z)]}} \quad (13)$$

201 Although this is not an actual correlation, it is an intuitive analogue to the correlation
 202 as a normalised version of the covariance.

For comparison, we also measured the ‘signal correlation’

$$\rho_{\text{signal}} = \frac{\text{cov}(E[X|Z], E[Y|Z])}{\sqrt{\text{var}(E[X|Z])\text{var}(E[Y|Z])}} \quad (14)$$

203 this is an actual correlation.

5.4 Information Theory

5.4.1 Entropy $H(X)$

The entropy of a random variable X , with outcomes x_1, \dots, x_N , and corresponding probabilities p_1, \dots, p_N is defined as

$$H(X) = - \sum_{n=1}^N p_n \log_2 p_n \quad (15)$$

This quantity is also known as the information entropy or the ‘surprise’. It measures the amount of uncertainty in a random variable. For example, a variable with a probability of 1 for one outcome, and 0 for all other outcomes will have 0 bits entropy, because it contains no uncertainty. But a variable with a uniform distribution will have maximal entropy as it is the least predictable. This quantity is analogous to the entropy of a physical system [5]. Note that any base may be used for the logarithm in equation 15, but using base 2 means that the quantity will be measured in ‘bits’.

The joint entropy of two jointly distributed random variables X and Y , where Y has outcomes y_1, \dots, y_M , is defined as

$$H(X, Y) = - \sum_{n=1}^N \sum_{m=1}^M P(X = x_n, Y = y_m) \log_2 P(X = x_n, Y = y_m) \quad (16)$$

If X and Y are independent then $H(X, Y) = H(X) + H(Y)$. Otherwise $H(X, Y) < H(X) + H(Y)$. When X and Y are completely dependent $H(X, Y) = H(X) = H(Y)$.

The conditional entropy of Y conditioned on X is defined as

$$H(Y|X) = - \sum_{n=1}^N \sum_{m=1}^M P(X = x_n, Y = y_m) \log_2 \frac{P(X = x_n, Y = y_m)}{P(X = x_n)} \quad (17)$$

When X and Y are independent $H(Y|X) = H(Y)$. Intuitively, we learn nothing of Y by knowing X , so Y is equally uncertain whether we know X or not. If Y is totally dependent on X , then the fraction in the logarithm is 1, which gives $H(Y|X) = 0$.

These entropy measures are the basis of the mutual information measure.

5.4.2 Maximum entropy limit

When spiking data is binned into spike counts there is an upper limit on the entropy of these data. The maximum entropy discrete distribution is the discrete uniform distribution. A random variable with this distribution will take values from some finite set with equal probabilities. Binned spike count data will take values between 0 and some maximum observed spike count n_{\max} . A neuron with responses that maximises entropy will take these values with equal probability, i.e. if $i \in \{0, \dots, n_{\max}\}$ then $P(X = i) = \frac{1}{n_{\max}+1}$. The entropy of this neuron will be

$$\begin{aligned} H(X) &= - \sum_{i=0}^{n_{\max}} P(X = i) \log_2 P(X = i) \\ &= - \sum_{i=0}^{n_{\max}} \frac{1}{n_{\max} + 1} \log_2 \left(\frac{1}{n_{\max} + 1} \right) \\ &= - \log_2 \left(\frac{1}{n_{\max} + 1} \right) \\ &= \log_2 (n_{\max} + 1) \end{aligned}$$

Therefore, the maximum entropy of the binned spike counts of a neuron is $\log_2 (n_{\max} + 1)$. Of course, it would be very unusual for a neuron to fire in accordance with the discrete uniform distribution. Most measurements of entropy taken on binned spiking data will be much lower than the maximum. See figure 4 to see the maximum entropy as a function of the maximum observed spike count.

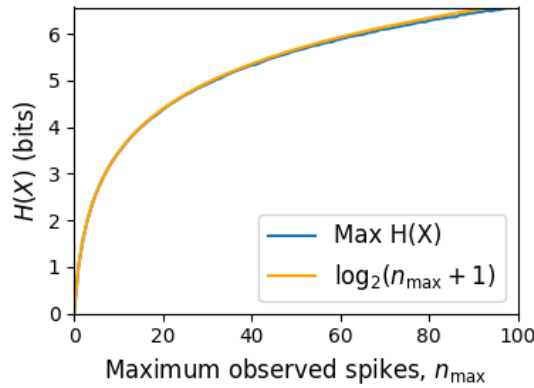


Figure 4: **Entropy Limit:** The upper limit on entropy of binned spike count data as a function of the maximum observed spike count. The orange line is the analytical maximum. The blue line is the entropy of samples with $N = 1000$ data points taken from the discrete uniform distribution.

5.4.3 Mutual Information $I(X; Y)$

The mutual information can be defined mathematically in a number of ways, all of which are equivalent. These definitions illustrate the different ways of interpreting the mutual information.

For two jointly distributed random variables X and Y , the mutual information $I(X; Y)$ is defined as

$$I(X; Y) = H(Y) - H(Y|X) \quad (18)$$

$$= H(X) - H(X|Y) \quad (19)$$

Equation 18 fits with the following intuition: The mutual information between X and Y is the reduction in uncertainty about X gained by knowing Y , or vice versa. We could also say the mutual information is the amount of information gained about X by knowing Y , or vice versa.

Another useful entropy based definition for the mutual information is

$$I(X; Y) = H(X) + H(Y) - H(X, Y) \quad (20)$$

This definition is useful because it does not require the calculation of conditional probabilities.

The mutual information can also be defined in terms of marginal, joint, and conditional distributions. For example,

$$I(X; Y) = - \sum_{n=1}^N \sum_{m=1}^M P(X = x_n, Y = y_m) \log_2 \frac{P(X = x_n, Y = y_m)}{P(X = x_n)P(Y = y_m)} \quad (21)$$

Notice that this can be rewritten as a Kullback–Leibler divergence.

$$I(X; Y) = D_{KL}(P(X, Y) || P(X)P(Y)) \quad (22)$$

So, we can also think of the mutual information as a measure of the difference between the joint distribution of X and Y , and the product of their marginal distributions. Since the product of the marginal distributions is the joint distribution for independent variables, we can think of the mutual information as a measure of the variables' dependence on one another.

241 The minimum value that $I(X; Y)$ can take is 0. This occurs when the ran-
 242 dom variables X and Y are independent. Then we have $H(X|Y) = H(X)$, and
 243 $H(Y|X) = H(Y)$, which according to equation 18, gives $I(X; Y) = 0$. We
 244 also have that $H(X, Y) = H(X) + H(Y)$ in this case, which according equa-
 245 tion 20, gives $I(X; Y) = 0$. Finally, we also have $P(X, Y) = P(X)P(Y)$, which
 246 leaves us with 1 in the argument for the logarithm in equation 21, which again gives
 247 $I(X; Y) = 0$.

248 The mutual information reaches its maximum value when one of the variables
 249 X and Y is completely determined by knowing the value of the other. In that case
 250 $I(X; Y) = \min\{H(X), H(Y)\}$.

251 **5.4.4 Variation of Information $VI(X, Y)$**

The variation of information is another information theoretical quantity based on the mutual information. It is defined as

$$VI(X; Y) = H(X) + H(Y) - 2I(X; Y) \quad (23)$$

We can rewrite this as the summation of two positive quantities

$$VI(X; Y) = [H(X) - I(X; Y)] + [H(Y) - I(X; Y)] \quad (24)$$

252 In English, the variation of information is the summation of the uncertainty in the
 253 random variables X and Y excluding the uncertainty shared by those variables.

254 This measure will become more relevant when we go on to talk about clusterings
 255 because $VI(X; Y)$ forms a metric on the space of clusterings.

256 **5.4.5 Measuring entropies & mutual information**

257 In practice, we measured the mutual information between spike counts using Python
 258 and the python package `pyitlib`. We used the PT-bias correction technique to esti-
 259 mate the bias of our measurements when measuring the mutual information between
 260 the spike counts of two cells [7].

261 When measuring the mutual information between clusterings we used Python,
 262 but we used the `mutual_info_score`, `adjusted_mutual_info_score`, and

263 `normalized_mutual_info_score` functions from the `sklearn.metrics`
264 part of the `sklearn` package.

265 **5.5 Network analysis**

266 **5.5.1 Correlation networks**

267 In order to analyse functional networks created by the neurons in our ensemble, we
268 measured the spike count correlation between each pair of neurons. These mea-
269 surements induced an undirected weighted graph/network between the neurons. The
270 weight of each connection was equal to the spike count correlation between each pair
271 of neurons.

272 We followed the same procedure for spike count correlations 5.2.1, conditional
273 correlations, and signal correlations 5.3.4.

274 **5.5.2 Rectified correlations**

275 At the time of writing, the community detection method outlined in [3] could only
276 be applied to networks with positively weighted connections. But many neuron pairs
277 were negatively correlated. To apply the community detection method, we *rectified*
278 the network, by setting all the negative weights to zero.

279 We also looked for structure in the network created by negative correlations by
280 reversing the signs of the correlations, and rectifying these correlations before apply-
281 ing our network analysis.

282 Finally, we used the absolute value of the correlations as the weights for the
283 graph/network. By doing this, we hoped to identify both correlated and anti-correlated
284 functional communities of neurons.

285 **5.5.3 Sparsifying data networks**

286 When creating our correlation networks, we wanted to exclude any correlations that
287 could be judged to exist ‘by chance’. To do this, we measured the 5th and 95th
288 percentile of the shuffled correlations (see section 5.2.2) for the given mouse and
289 time bin width. We then set all the data correlations between these two values to
290 0. This excluded any ‘chance’ correlations from our network, and created a sparser

network. This allowed us to make use of the ‘sparse weighted configuration model’ as described in section 5.5.6.

5.5.4 Communities

Given some network represented by an adjacency matrix \mathbf{A} , a community within that network is defined as a collection of nodes where the number of connections within these nodes is higher than the expected number of connections between these nodes. In order to quantify the ‘expected’ number of connections, we need a model of expected networks. This is analogous to a ‘null model’ in traditional hypothesis testing. We test the hypothesis that our data network departs from the null network model to a statistically significant degree. For undirected unweighted networks, the canonical model of a null network is the configuration model [8]. Since we are working with weighted sparse networks, we used more suitable null models, described below.

5.5.5 Weighted configuration model

The *weighted configuration model* is a canonical null network model for weighted networks. Given some data network, the weighted configuration model null network will preserve the degree sequence and weight sequence of each node in the data network. But the edges will be distributed randomly [8]. Any structure in the data network beyond its degree sequence and weight sequence will not be captured in the weighted configuration model. So, this model can be used in testing the hypothesis that this extra structure exists.

5.5.6 Sparse weighted configuration model

The *sparse weighted configuration model* is another null network model. Similar in nature to the weighted configuration model (see section 5.5.5), but the sparsity of the data network is preserved in the null network. This is achieved by sampling from a probability distribution for the creation or non-creation of each possible connection, then distributing the weight of the data network randomly in this sparse network [3]. This is the null network that we used when searching for additional structure in our data networks.

5.5.7 Spectral rejection

We made use of the spectral rejection algorithm as outlined in [3]. The spectral rejection algorithm is a method for finding structure in a network not captured by a supposed null model, if such structure exists.

To describe the method, we denote our data network matrix \mathbf{W} , we denote the expected network of our null network model as $\langle \mathbf{P} \rangle$. Then the departure of our data network from the null network can be described by the matrix

$$\mathbf{B} = \mathbf{W} - \langle \mathbf{P} \rangle \quad (25)$$

a common choice for $\langle \mathbf{P} \rangle$ in community detection is the ‘configuration model’ [8, 9]. The matrix \mathbf{B} is often called the configuration matrix, in this context we will use the term ‘deviation matrix’ as it captures the deviation of \mathbf{W} from the null model.

To test for structure in the network represented by \mathbf{W} , we examine the eigenspectrum of \mathbf{B} and compare it to the eigenspectrum of our null model. Firstly, note that since our data model doesn’t allow self loops, and is not directed, the matrix representing the network will be symmetric and positive semi-definite, and will therefore be invertible with real eigenvalues. We selected a null model with the same characteristics.

To find the eigenspectrum of the null model, we generated N samples from our null model P_1, \dots, P_N , and we measured their deviation matrices B_1, \dots, B_N . We then calculated the eigenspectrum of each of those samples. We calculated the upper bound of the null model eigenspectrum by taking the mean of the largest eigenvalues of B_1, \dots, B_N . We calculated a lower bound on the null model eigenspectrum by taking the mean of the smallest eigenvalues of B_1, \dots, B_N .

We then calculated the eigenspectrum of \mathbf{B} , our data network deviation matrix. If any of those eigenvalues lay outside of the upper or lower bounds of the null model eigenspectrum, this is evidence of additional structure not captured by the null model. If we chose the sparse weighted configuration model (see section 5.5.6) as our null network model, then eigenvalues lying below the lower bound indicate n -partite structure in the network. For example, if one eigenvalue lay below the lower bound, this would indicate some bipartite structure in the data network. If any eigenvalues lay above the upper bound of the null model eigenspectrum, this is

evidence of community structure in the data network. For example, one eigenvalue of \mathbf{B} lying above the upper bound of the null model eigenspectrum indicates the presence of two communities in the network [9].

5.5.8 Node rejection

If there are d data eigenvalues lying outside of the null network eigenspectrum, the d eigenvectors corresponding to these eigenvalues will form a vector space. If we project the nodes of our network into this vector space, by projecting either rows or columns of the data matrix, we can see how strongly each node contributes to the vector space. Nodes that contribute strongly to the additional structure will project far away from the origin, nodes that do not contribute to the additional structure will project close to the origin. We want to use this information to discard those nodes that do not contribute.

We can test whether a node projects *far* away from the origin or *close* to the origin using the eigenvalues and eigenvectors of B_1, \dots, B_N . The j th eigenvector and eigenvalue of B_i gives a value for a null network's projection into the j th dimension of the additional structure vector space. The matrices B_1, \dots, B_N give N projections into that dimension. These projections are a distribution of the null networks' projections. If the data node's projection exceeds that of the null network projections this node is judged to project *far* from the origin, and therefore contribute to the additional structure. Otherwise, the node is judged to project *close* to the origin, and is therefore rejected [3].

5.5.9 Community detection

Another application for this d dimensional space is community detection. We first project all of the nodes into this d -dimensional space, then perform the clustering in this space. The clustering and community detection procedure is described in [9].

In practice, the procedure is carried out n times (we chose $n = 100$ times), this returns n clusterings. We resolve these n clusterings to one final clustering using *consensus clustering*. We used the consensus clustering method that uses an explicit null model for the consensus matrix, as outlined in [3].

375

5.6 Clustering Comparison

A clustering \mathcal{C} is a partition of a set D into sets C_1, C_2, \dots, C_K , called clusters, that satisfy the following for all $k, l \in \{1, \dots, K\}$:

$$C_k \cap C_l = \emptyset \quad (26)$$

$$\bigcup_{k=1}^K C_k = D \quad (27)$$

376

If we consider two clusterings, \mathcal{C} with clusters C_1, C_2, \dots, C_K and \mathcal{C}' with clusters

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C'_1, C'_2, \dots, C'_K . There are a number of measurements we can use to compare \mathcal{C} and

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\mathcal{C}' . In the following, the number of elements in D is denoted by n , and the number

379

of elements in cluster C_k is n_k .

380

5.6.1 Adjusted Rand Index

381

The *adjusted Rand Index* is a normalised similarity measure for clusterings based on

382

pair counting.

383

If we consider the clusterings \mathcal{C} and \mathcal{C}' , and denote

384

- the number of pairs in the same cluster in \mathcal{C} and \mathcal{C}' by N_{11}

385

- the number of pairs in different clusters in \mathcal{C} and \mathcal{C}' by N_{00}

386

- the number of pairs in the same cluster in \mathcal{C} and different clusters in \mathcal{C}' by N_{10}

387

- the number of pairs in different clusters in \mathcal{C} and the same cluster in \mathcal{C}' by N_{01}

then the *Rand Index* is defined as

$$RI = \frac{N_{11} + N_{00}}{N_{11} + N_{00} + N_{10} + N_{01}} = \frac{N_{11} + N_{00}}{\binom{n}{2}} \quad (28)$$

388

The Rand Index is 1 when the clusterings are identical, and 0 when the clusterings

389

are completely different.

The *adjusted Rand Index* intends on correcting the Rand Index for chance matching pairs. This is defined as

$$ARI = \frac{2(N_{00}N_{11} - N_{01}N_{10})}{(N_{00} + N_{01})(N_{01} + N_{11}) + (N_{00} + N_{10})(N_{10} + N_{11})} \quad (29)$$

390 The adjusted Rand Index is 1 when the clusterings are identical, and 0 when the Rand
391 Index is equal to its expected value.

392 5.6.2 Clusterings as random variables

If we take any random element of D , the probability that this element is in cluster C_k of clustering \mathcal{C} is

$$P(K = k) = \frac{n_k}{n} \quad (30)$$

393 this defines a probability distribution, which makes the clustering a random variable.
394 Any clustering can be considered as a random variable this way.

This means that we can measure any of the information theoretic quantities defined in section 5.4 with respect to clusterings. For example, the entropy of a clustering is

$$H(\mathcal{C}) = - \sum_{k=1}^K \frac{n_k}{n} \log \frac{n_k}{n} \quad (31)$$

If we have two clusterings, the joint probability distribution of these clusterings is defined as

$$P(K = k, K' = k') = \frac{|C_k \cap C'_{k'}|}{n} \quad (32)$$

395 The joint distribution allows us to define the mutual information between two clus-
396 terings, $I(\mathcal{C}; \mathcal{C}')$ [10].

397 5.6.3 Information based similarity measures

The mutual information between two clusterings is a similarity measure, with $I(\mathcal{C}; \mathcal{C}') = 0$ if \mathcal{C} and \mathcal{C}' are completely different, and $I(\mathcal{C}; \mathcal{C}') = H(\mathcal{C}) = H(\mathcal{C}')$ if \mathcal{C} and \mathcal{C}' are identical. This can be normalised in a number of different ways to make more

similarity measures [11]

$$NMI_{joint} = \frac{I(\mathcal{C}; \mathcal{C}')}{H(\mathcal{C}, \mathcal{C}')} \quad (33)$$

$$NMI_{max} = \frac{I(\mathcal{C}; \mathcal{C}')}{\max\{H(\mathcal{C}), H(\mathcal{C}')\}} \quad (34)$$

$$NMI_{sum} = \frac{2I(\mathcal{C}; \mathcal{C}')}{H(\mathcal{C}) + H(\mathcal{C}')} \quad (35)$$

$$NMI_{sqr} = \frac{I(\mathcal{C}; \mathcal{C}')}{\sqrt{H(\mathcal{C})H(\mathcal{C}')}} \quad (36)$$

$$NMI_{min} = \frac{I(\mathcal{C}; \mathcal{C}')}{\min\{H(\mathcal{C}), H(\mathcal{C}')\}} \quad (37)$$

We can control for chance similarities between the two clusterings by measuring the *adjusted mutual information* between the clusterings. This is defined as

$$AMI_{sum} = \frac{I(\mathcal{C}; \mathcal{C}') - E\{I(\mathcal{C}; \mathcal{C}')\}}{\frac{1}{2}[H(\mathcal{C}) + H(\mathcal{C}')] - E\{I(\mathcal{C}; \mathcal{C}')\}} \quad (38)$$

398 The first term in the demoniator, taking the average of the marginal entropies, can be
399 replaced by taking the maximum, minimum, or the geometric mean [11].

400 5.6.4 Information based metrics

The variation of information between two clusterings $VI(\mathcal{C}; \mathcal{C}')$ (see section 5.4.4) is a metric on the space of clusterings [10]. That is,

$$VI(\mathcal{C}; \mathcal{C}') \geq 0 \quad (39)$$

$$VI(\mathcal{C}; \mathcal{C}') = 0 \iff \mathcal{C} = \mathcal{C}' \quad (40)$$

$$VI(\mathcal{C}; \mathcal{C}') = VI(\mathcal{C}'; \mathcal{C}) \quad (41)$$

$$VI(\mathcal{C}; \mathcal{C}'') \leq VI(\mathcal{C}; \mathcal{C}') + VI(\mathcal{C}'; \mathcal{C}'') \quad (42)$$

Another metric is the *information distance* [11]

$$D_{max} = \max\{H(\mathcal{C}), H(\mathcal{C}')\} - I(\mathcal{C}; \mathcal{C}') \quad (43)$$

Both of these can be normalised

$$NVI(\mathcal{C}; \mathcal{C}') = 1 - \frac{I(\mathcal{C}; \mathcal{C}')}{H(\mathcal{C}, \mathcal{C}')} \quad (44)$$

$$d_{max} = 1 - \frac{I(\mathcal{C}; \mathcal{C}')}{\max\{H(\mathcal{C}), H(\mathcal{C}')\}} \quad (45)$$

5.6.5 Comparing detected communities and anatomical divisions

In order to quantify the difference or similarity between the communities detected in our correlation network and the anatomical classification of the cells in that network, we considered the communities and the anatomical regions as clusters in two different clusterings, \mathcal{C}_{comm} and \mathcal{C}_{anat} , respectively. We then measured the similarity between the clusterings using the mutual information, the adjusted mutual information, and the normalised mutual information. We measured the difference between, or the distance between, the clusterings using the variation of information, the normalised variation of information, and the normalised information distance. We also measured the difference between the clusterings using the adjusted Rand Index, just to use a non-information based measure.

We took all of these measures for communities detected using different time bin widths. This gave us an idea of the effect of time bin width on correlation networks in neural ensembles relative to anatomical regions within those ensembles.

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