# Unit 3 Method of Maximum Likelihood Estimation

Let 
$$\underline{\boldsymbol{\theta}} = (\phi_1,...,\phi_p,\theta_1,...,\theta_q,\underline{\sigma}^2)'$$
 denote the vector of population parameters. Suppose we have observed a sample of size  $T$  
$$\mathbf{x} = (x_1,...,x_T)$$

Let the joint probability density function (p.d.f.) of these data be denoted

$$f(x_T, x_{T-1}, ..., x_1; \boldsymbol{\theta})$$

The likelihood function is this joint density treated as a function of the parameters  $\theta$  given the data  $\mathbf{x}$ :

$$L(\boldsymbol{\theta}|\mathbf{x}) = f(x_T, x_{T-1}, ..., x_1; \boldsymbol{\theta})$$

$$\frac{df(x)}{dx} = 0$$

$$\frac{d^2f(x)}{dx^2} < 0$$

The maximum likelihood estimator (MLE) is

$$\hat{\boldsymbol{\theta}}_{MLE} = \arg\max_{\boldsymbol{\theta} \in \boldsymbol{\Theta}} L(\boldsymbol{\theta}|\mathbf{x})$$

where  $\underline{\Theta}$  is the parameter space.

For simplifying calculations, it is customary to work with the natural logarithm of L, given by

$$\log L(\boldsymbol{\theta}|\mathbf{x}) = I(\boldsymbol{\theta}|\mathbf{x}).$$

This function is commonly referred to as the log-likelihood.

Since the logarithm is a monotone transformation the values that maximize  $L(\theta|\mathbf{x})$  are the same as those that maximize  $I(\theta|\mathbf{x})$ , that is

$$\hat{\boldsymbol{\theta}}_{MLE} = \arg\max_{\boldsymbol{\theta} \in \boldsymbol{\Theta}} L(\boldsymbol{\theta}|\mathbf{x}) = \arg\max_{\boldsymbol{\theta} \in \boldsymbol{\Theta}} \underline{\boldsymbol{l}(\boldsymbol{\theta}|\mathbf{x})}$$

but the log-likelihood is computationally more convenient.

Now, we assume that the derivative of  $I(\theta|\mathbf{x})$  (w.r.  $\theta$ ) exists and is continuous for all  $\theta$ .

The necessary condition for maximizing  $I(\theta|\mathbf{x})$  is

$$\frac{\delta I(\boldsymbol{\theta}|\mathbf{x})}{\delta \boldsymbol{\theta}} = \mathbf{0}$$

which is called likelihood equation.

The maximum likelihood estimate,  $\hat{\boldsymbol{\theta}}_{MLE}$ , will be the solution of

$$\frac{\delta I(\boldsymbol{\theta}|\mathbf{x})}{\delta \boldsymbol{\theta}} = \mathbf{0}$$

#### Properties of Maximum Likelihood Estimators

Maximum Likelihood Estimators are most attractive because of their asymptotic properties.

Under regularity conditions, the Maximum Likelihood Estimator,  $\hat{\boldsymbol{\theta}}_{MLE}$ , will have the following asymptotic properties:

- It is consistent
- It is asymptotically normally distributed
- It is asymptotically efficient

These three properties explain the prevalence of the maximum likelihood technique in time series analysis

# The exact Gaussian likelihood of an ARMA process (Normal)

To write down the likelihood function for an ARMA process, one must assume a particular distribution for the white noise process  $u_t$ . Here, we assume that  $u_t$  is a Gaussian white noise:

$$u_t \sim \underline{i.i.d.N(0,\sigma^2)}$$

# The exact Gaussian likelihood of an ARMA process

$$f(x) = \sqrt{\frac{1}{2\pi}} e^{-\frac{1}{2\pi}(x-u)^2}$$

This implies that the exact Gaussian likelihood of  $\mathbf{x} = (x_1, x_2, ..., x_T)'$  is given by

$$L(\boldsymbol{\theta}|\mathbf{x}) = \underline{(2\pi)^{-T/2}} \underline{|\Gamma(\boldsymbol{\theta})|}^{-1/2} \exp\left\{-\frac{1}{2}\mathbf{x}'\Gamma(\boldsymbol{\theta})^{-1}\mathbf{x}\right\}$$

where  $\underline{\Gamma(\theta) = E(\mathbf{x}\mathbf{x}')}$  is the  $T \times T$  covariance matrix of  $\mathbf{x}$  depending on  $\theta$ .

# The exact Gaussian likelihood of an ARMA process

The exact Gaussian log-likelihood is then given by

$$I(\boldsymbol{\theta}|\mathbf{x}) = -\frac{1}{2} \left[ T \log(2\pi) + \log|\Gamma(\boldsymbol{\theta})| + \mathbf{x}'\Gamma(\boldsymbol{\theta})^{-1}\mathbf{x} \right]$$

# The exact Gaussian likelihood of an AR(1) process

A Gaussian AR(1) process takes the form

$$x_t = \phi_1 x_{t-1} + u_t \text{ or } \xi_t$$

with

$$u_t \sim i.i.d.N(0, \sigma^2)$$

For this case, the vector of population parameters to be estimated consists of  $\boldsymbol{\theta} = (\phi_1, \sigma^2)'$ .

# The exact Gaussian likelihood of an AR(1) process

The exact Gaussian likelihood of  $\mathbf{x} = (x_1, x_2, ..., x_T)'$  is given by

$$\underline{L(\boldsymbol{\theta}|\mathbf{x})} = \underline{(2\pi)^{-T/2}} |\Gamma(\boldsymbol{\theta})|^{-1/2} \exp\left\{-\frac{1}{2}\mathbf{x}'\Gamma(\boldsymbol{\theta})^{-1}\mathbf{x}\right\}$$

where

$$\underline{\Gamma(\boldsymbol{\theta})} = \frac{\sigma^2}{1 - \phi_1^2} \begin{bmatrix} 1 & \phi_1 & \phi_1^2 & \cdots & \phi_1^{T-1} \\ \phi_1 & 1 & \phi_1 & \cdots & \phi_1^{T-2} \\ \vdots & \vdots & \vdots & \cdots & \vdots \\ \phi_1^{T-1} & \phi_1^{T-2} & \phi_1^{T-3} & \cdots & 1 \end{bmatrix}$$

In fact we recall that the j-th autovariance for an AR(1) process is given by

$$E(x_t x_{t-j}) = \frac{\sigma^2 \phi_1^j}{1 - \phi_1^2}$$

# The exact Gaussian likelihood of an MA(1) process

The exact Gaussian likelihood of  $\mathbf{x} = (x_1, x_2, ..., x_T)'$  is given by

$$L(\boldsymbol{\theta}|\mathbf{x}) = (2\pi)^{-T/2} |\Gamma(\boldsymbol{\theta})|^{-1/2} \exp\left\{-\frac{1}{2}\mathbf{x}'\Gamma(\boldsymbol{\theta})^{-1}\mathbf{x}\right\}$$

where

$$\Gamma(\boldsymbol{\theta}) = \sigma^2 \begin{bmatrix} (1+\theta_1) & \underline{\theta_1} & 0 & \cdots & 0 \\ \underline{\theta_1} & (1+\theta_1) & \underline{\theta_1} & \cdots & 0 \\ \vdots & \vdots & \vdots & \cdots & \vdots \\ 0 & 0 & 0 & \cdots & (1+\theta_1) \end{bmatrix}$$

#### Non-zero mean µ

Consider an ARMA process  $\{x_t; t \in \mathbb{Z}\}$  with mean  $\mu \neq 0$ , defined by the equation

$$x_{t} - \phi_{1}x_{t-1} - \dots - \phi_{p}x_{t-p} = c + \underbrace{u_{t} + \theta u_{t-1} + \dots + \theta u_{t-p}}_{\mathcal{L}_{t} \text{ by } u_{t}} \sim WN(0, \sigma^{2})$$

where  $\phi^{-1}(1)c = \mu$ . The unknown parameters in this model

are

- $\phi = (\phi_1, ..., \phi_p)'$   $\theta = (\theta_1, ..., \theta_q)'$
- $\circ \sigma^2$

#### Non-zero mean µ

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$$x_t - \phi_1 x_{t-1} - \dots - \phi_p x_{t-p} = c + u_t + \theta u_{t-1} + \dots + \theta u_{t-p}$$

can be rewritten as

$$(x_t - \mu) - \phi_1(x_{t-1} - \mu) - \dots - \phi_p(x_{t-p} - \mu) = u_t + \theta u_{t-1} + \dots + \theta u_{t-p}$$

#### Non-zero mean µ

We estimate 
$$\mu$$
 by  $\bar{x}_T = \sum_{t=1}^T x_t$ 

and proceed to analyze the demeaned series

$$\{(x_t - \bar{x}_T); t = 1, ..., T\}$$