

Method of Moments for parameter estimation

Method of Moments Estimation

- ▶ One of the easiest methods of parameter estimation is the method of moments (MOM).
- ✓ ▶ The basic idea is to find expressions for the sample moments and for the population moments and equate them:

$$\frac{1}{n} \sum_{i=1}^n X_i^r = \underline{E(X^r)}$$

- ▶ The $E(X^r)$ expression will be a function of one or more unknown parameters.
- ✓ ▶ If there are, say, 2 unknown parameters, we would set up MOM equations for $r = 1, 2$, and solve these 2 equations simultaneously for the two unknown parameters.
- ▶ In the simplest case, if there is only 1 unknown parameter to estimate, then we equate the sample mean to the true mean of the process and solve for the unknown parameter.

MOM with AR models

- ▶ First, we consider autoregressive models.
- ▶ In the simplest case, the AR(1) model, given by $Y_t = \phi Y_{t-1} + \epsilon_t$, the true lag-1 autocorrelation $\rho_1 = \phi$.
- ▶ For this type of model, a method-of-moments estimator would simply equate the true lag-1 autocorrelation to the sample lag-1 autocorrelation r_1 . or $\hat{\rho}_1$
- ▶ So our MOM estimator of the unknown parameter ϕ would be $\hat{\phi} = r_1$. or $\hat{\rho}_1$

MOM with an AR(2) model

- ▶ In the AR(2) model, we have unknown parameters ϕ_1 and ϕ_2 .
- ▶ From the Yule-Walker equations,

$$\rho_1 = \phi_1 + \rho_1\phi_2 \text{ and } \rho_2 = \rho_1\phi_1 + \phi_2$$

- ▶ In the method of moments, we will replace the true lag-1 and lag-2 autocorrelations, ρ_1 and ρ_2 , by the sample autocorrelations r_1 and r_2 , respectively.

$$\text{or } \hat{\rho}_1 \quad \hat{\rho}_2$$

MOM with an AR(2) model

- ▶ That gives the equations

$$\underline{r_1 = \phi_1 + r_1\phi_2} \text{ and } \underline{r_2 = r_1\phi_1 + \phi_2}$$

which are then solved for ϕ_1 and ϕ_2 to obtain

$$\underline{\hat{\phi}_1 = \frac{r_1(1 - r_2)}{1 - r_1^2}} \text{ and } \underline{\hat{\phi}_2 = \frac{r_2 - r_1^2}{1 - r_1^2}}$$

- ▶ The general AR(p) model is estimated in a similar way, with the Yule-Walker equations being used to obtain the Yule-Walker estimates $\hat{\phi}_1, \hat{\phi}_2, \dots, \hat{\phi}_p$.

MOM with MA Models

- ▶ We run into problems when trying to using the method of moments to estimate the parameters of moving average models.

- ▶ Consider the simple MA(1) model, $Y_t = e_t - \theta e_{t-1}$.

$$y_t = \varepsilon_t - \theta \varepsilon_{t-1}$$

or

- ▶ The true lag-1 autocorrelation in this model is

$$\rho_1 = -\theta / (1 + \theta^2).$$

- ▶ If we equate ρ_1 to r_1 , we get a quadratic equation in θ .

- ▶ If $|r_1| < 0.5$, then only one of the two real solutions satisfies the invertibility condition $|\theta| < 1$.

- ▶ That solution is $\hat{\theta} = \left(-1 + \sqrt{1 - 4r_1^2} \right) / (2r_1)$.

- ▶ But if $|r_1| = 0.5$, no invertible solution exists, and if $|r_1| > 0.5$, then no real solution at all exists, and the method of moments fails to give any estimator of θ .

$$\rho_1 = \frac{-\theta}{1 + \theta^2}$$

$$r_1 + r_1 \theta^2 + \theta = 0$$

$$r_1 \theta^2 + \theta + r_1 = 0$$

$$\theta = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

More MOM Problems with MA Models

- ▶ With higher-order $MA(q)$ models, the set of equations for estimating $\theta_1, \dots, \theta_q$ is highly nonlinear and could only be solved numerically.
- ▶ There would be many solutions, only one of which is invertible.
- ▶ In any case, for $MA(q)$ models, the method of moments usually produces poor estimates, so it is not recommended to use MOM to estimate MA models.

MOM Estimation of Mixed ARMA Models

- ▶ Consider only the simplest mixed model, the ARMA(1, 1) model.
- ▶ Since $\rho_2/\rho_1 = \phi$, a MOM estimator of ϕ is $\hat{\phi} = r_2/r_1$.
- ▶ Then the equation

$$r_1 = \frac{(1 - \theta\hat{\phi})(\hat{\phi} - \theta)}{1 - 2\theta\hat{\phi} + \theta^2}$$

can be used to solve for an estimate of θ .

- ▶ This is a quadratic equation is θ , and so we again keep only the invertible solution (if any exist) as our $\hat{\theta}$.

MOM Estimation of the Noise Variance

- ▶ We still must estimate the variance σ_e^2 of our error component.
- ▶ For any model, we first estimate the variance of the time series process itself, $\gamma_0 = \text{var}(Y_t)$, by the sample variance

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n (Y_t - \bar{Y})^2$$

- ▶ Then we can take advantage of known relationships among the parameters in our specified model to obtain a formula for $\hat{\sigma}_e^2$.

Formulas for MOM Noise Variance Estimators in Common Models

- ▶ For AR(p) models, $\hat{\sigma}_e^2 = (1 - \hat{\phi}_1 r_1 - \hat{\phi}_2 r_2 - \dots - \hat{\phi}_p r_p) s^2$.
- ▶ For the AR(1) model, this reduces to $\hat{\sigma}_e^2 = (1 - r_1^2) s^2$.
- ▶ For MA(q) models,

$$\hat{\sigma}_e^2 = \frac{s^2}{1 + \hat{\theta}_1^2 + \hat{\theta}_2^2 + \dots + \hat{\theta}_q^2}.$$

- ▶ For ARMA(1, 1) models,

$$\hat{\sigma}_e^2 = \frac{1 - \hat{\phi}^2}{1 - 2\hat{\phi}\hat{\theta} + \hat{\theta}^2} s^2.$$