

# Unit -3

## *ESTIMATION OF ARMA MODELS*

Estimation of ARMA models: Yule- Walker estimation of AR Processes, Maximum likelihood and least squares estimation for ARMA Processes, Residual analysis and diagnostic checking.

# ARMA (p,q) process

In general, an ARMA(p, q) model is given as

$$y_t = \delta + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \dots + \phi_p y_{t-p} + \varepsilon_t - \theta_1 \varepsilon_{t-1} - \theta_2 \varepsilon_{t-2} - \dots - \theta_q \varepsilon_{t-q}$$

$$= \delta + \sum_{i=1}^p \phi_i y_{t-i} + \varepsilon_t - \sum_{i=1}^q \theta_i \varepsilon_{t-i}$$

...equation 1


or

$$\Phi(B) y_t = \delta + \Theta(B) \varepsilon_t$$

...equation 2

where  $\varepsilon_t$  is a white noise process.

# Estimation of ARMA models


$$\begin{aligned} y_t &= \delta + \phi_1 y_{t-1} + \phi_2 y_{t-2} + \cdots + \phi_p y_{t-p} + \varepsilon_t - \theta_1 \varepsilon_{t-1} \\ &\quad - \theta_2 \varepsilon_{t-2} - \cdots - \theta_q \varepsilon_{t-q} \\ &= \delta + \sum_{i=1}^p \phi_i y_{t-i} + \varepsilon_t - \sum_{i=1}^q \theta_i \varepsilon_{t-i} \end{aligned}$$

is characterized by  $p + q + 1$  unknown parameters

- $\phi = (\phi_1, \dots, \phi_p)'$  ✓  $\Rightarrow \phi = \begin{bmatrix} \phi_1 \\ \vdots \\ \phi_p \end{bmatrix}$
- $\theta = (\theta_1, \dots, \theta_q)'$
- $\sigma^2$  ✓

that need to be estimated.

# Estimation of ARMA models

We consider three techniques for estimation of the parameters  $\phi$ ,  $\theta$  and  $\sigma^2$  They are:

- ✓ 1. Yule-Walker Estimation
- ✓ 2. Maximum Likelihood Estimation
- ✓ 3. least squares estimation

# The Yule-Walker Estimation

Consider an autoregressive stochastic process  $y_t$  of order  $p$ . It is well known that there is a link among the autoregressive coefficients and the autocovariances. In particular, we have

$$\Gamma\phi = \gamma$$

and

$$\sigma^2 = \gamma(0) - \phi'\gamma$$

where

$$\Gamma = \begin{bmatrix} \gamma_0 & \gamma_1 & \cdots & \gamma_{p-1} \\ \gamma_1 & \gamma_0 & \cdots & \gamma_{p-2} \\ \vdots & \vdots & \ddots & \vdots \\ \gamma_{p-1} & \gamma_{p-2} & \cdots & \gamma_0 \end{bmatrix}$$

is the covariance matrix and

$$\gamma = (\gamma_1, \dots, \gamma_p)'$$

# The Sample Yule-Walker Estimation

If we replace the theoretical autocovariances by the corresponding sample autocovariances, we obtain

$$\hat{\Gamma} \phi = \hat{\gamma}$$

where

$$\hat{\Gamma} = \begin{bmatrix} \hat{\gamma}_0 & \hat{\gamma}_1 & \cdots & \hat{\gamma}_{p-1} \\ \hat{\gamma}_1 & \hat{\gamma}_0 & \cdots & \hat{\gamma}_{p-2} \\ \vdots & \vdots & \ddots & \vdots \\ \hat{\gamma}_{p-1} & \hat{\gamma}_{p-2} & \cdots & \hat{\gamma}_0 \end{bmatrix}$$

is the sample autocovariance matrix and

$$\hat{\gamma} = (\hat{\gamma}_1, \dots, \hat{\gamma}_p)'$$

# The Yule-Walker Estimation

Var. ✓

We assume  $\hat{\gamma}(0) > 0$ . To obtain the Yule-Walker estimators as a function of the autocorrelation function, we divide the two sides of equation

$$\hat{\Gamma}\phi = \hat{\gamma}$$

by  $\hat{\gamma}(0) > 0$ .  
We have

✓  $\underline{\underline{\hat{R}}}\phi = \underline{\underline{\hat{\rho}}}$  sample AC

where

$$\underline{\underline{\hat{R}}} = \begin{bmatrix} \hat{\rho}_0 & \hat{\rho}_1 & \cdots & \hat{\rho}_{p-1} \\ \hat{\rho}_1 & \hat{\rho}_0 & \cdots & \hat{\rho}_{p-2} \\ \vdots & \vdots & \ddots & \vdots \\ \hat{\rho}_{p-1} & \hat{\rho}_{p-2} & \cdots & \hat{\rho}_0 \end{bmatrix}$$

is the sample autocorrelation matrix and

$$\underline{\underline{\hat{\rho}}} = (\hat{\rho}_1, \dots, \hat{\rho}_p)'$$

$$P_k = \frac{\gamma(k)}{\gamma(0)}$$

$$\phi = \begin{bmatrix} \phi_1 \\ \vdots \\ \phi_p \end{bmatrix}_{1 \times p}$$

$$\phi' = [\phi_1 \cdots \phi_p]'$$

# The Yule-Walker Estimation

It is possible to show that

$$\underline{\underline{\hat{\gamma}(0) > 0}} \Rightarrow \underline{\underline{\det \hat{R} \neq 0}}$$



# The Yule-Walker Estimation

AR(p)

Thus we can solve the system

$$\underline{\hat{R}\phi = \hat{\rho}}$$

obtaining the so-called Yule-Walker estimators, namely

$$\checkmark \quad \underline{\hat{\phi}} = \underline{\hat{R}^{-1} \hat{\rho}}$$

and

$$\underline{\hat{\sigma}^2} = \underline{\hat{\gamma}(0)} \left[ 1 - \underline{\hat{\rho}' \hat{R}^{-1} \hat{\rho}} \right]$$

# The Yule-Walker Estimation

✓ **Theorem.** If  $\{y_t\}$  is a zero-mean stationary autoregressive process of order  $p$  with  $\varepsilon_t \sim iid(0, \sigma^2)$ , and  $\hat{\phi}$  is the Yule-Walker estimator of  $\phi$ , then

$$T^{1/2}(\hat{\phi} - \phi) = \sqrt{n}(\hat{\phi} - \phi) \sim N(0, \sigma^2 \Gamma^{-1})$$

has a limiting normal distribution with mean  $\mathbf{0}$  and covariance matrix  $\sigma^2 \Gamma^{-1}$ . Moreover

$$\hat{\sigma}^2 \xrightarrow{P} \sigma^2$$

Thus, under the assumption that the order  $p$  of the fitted model is the correct value, we can use the asymptotic distribution of  $\hat{\phi}$  to derive approximate large-sample confidence regions for  $\phi$  and for each of its components.

$$y_t = \overset{\phi_1}{0.75} y_{t-1} - \overset{\phi_2}{0.5} y_{t-2} + \varepsilon_t$$

$$\hat{P} = \begin{bmatrix} \hat{p}_0 \\ \hat{p}_1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0.5 \end{bmatrix}$$

$$\hat{R} = \begin{bmatrix} \hat{p}_0 & \hat{p}_1 \\ \hat{p}_1 & \hat{p}_0 \end{bmatrix} = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix}$$

$$\rho_1 = \frac{\phi_1}{1 - \phi_2} = \frac{0.75}{1 + 0.5} = 0.5$$

$$\hat{\Phi} = \hat{R}^{-1} \hat{P}$$

$$\begin{bmatrix} \hat{\phi}_1 \\ \hat{\phi}_2 \end{bmatrix} = \begin{bmatrix} 1 & 0.5 \\ 0.5 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 0.5 \end{bmatrix} \quad \text{--- ①}$$

$$\begin{bmatrix} \hat{\phi}_1 \\ \hat{\phi}_2 \end{bmatrix} = \frac{1}{0.75} \begin{bmatrix} 1 & 0.5 \\ -0.5 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0.5 \end{bmatrix} = \frac{1}{0.75} \begin{bmatrix} 0.75 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

estimator

$$\hat{\phi}_1 = 1$$

$$\hat{\phi}_2 = 0$$

$$A^{-1} = \frac{\text{Adj } A}{|A|}$$

$|A| \neq 0$  (inverse exist)

$$|\hat{R}| = \begin{vmatrix} 1 & 0.5 \\ 0.5 & 1 \end{vmatrix} = 1 - 0.25 = 0.75$$

$$\hat{R}^{-1} = \frac{\text{Adj } \hat{R}}{|\hat{R}|} = \frac{1}{0.75} \begin{bmatrix} 1 & -0.5 \\ -0.5 & 1 \end{bmatrix} =$$

