## Problem Set 4

### 1 Numerical Questions

# 1.1 Competitive Equilibrium in One-Sector Growth Model Under Certainty

Consider a decentralized economy with a large number of firms and a large number of households of total size normalized to one.

The state of the economy is the aggregate capital stock. We distinguish between "big K" and "little k". Households and firms see big K as the aggregate state that is beyond their control. Little k is chosen by firms and households. When making their optimization decisions, they do not see the connection between K and k. In equilibrium K = k.

We specify the price functions  $\tilde{r}(K)$  and w(K) that represent, respectively, the rental price on capital and the wage rate when the aggregate state is K. The law of motion for the aggregate capital is denoted as

$$K' = G(K)$$
.

A firm maximizes its profits given the factor prices  $(\tilde{r}_t, w_t) = (\tilde{r}(K_t), w(K_t))$ :

$$\max_{k_t, n_t} A k_t^{\alpha} n_t^{1-\alpha} - \tilde{r}_t(K_t) k_t - w(K_t) n_t,$$

where  $Ak_t^{\alpha}n_t^{1-\alpha}$  is a production function,  $k_t$  is the capital input and  $n_t$  is the labour input. Note that the firms' first-order conditions and market clearing implies that the equilibrium pricing functions are

$$\tilde{r}(K) = \alpha A K^{\alpha - 1}$$

$$w(K) = A K^{\alpha} - \tilde{r}(K) K. \tag{1}$$

Each household possesses homogeneous physical capital, denoted k, and supplies one unit of labour. Since the number of households is normalized to one, total supply of

labour in the economy is one (i.e. n = 1). The problem faced by the households is

$$\max_{c_t, x_t} \sum_{t=0}^{\infty} \beta^t \log c_t$$
subject to 
$$c_t + x_t = \tilde{r}(K_t)k_t + w(K_t)$$

$$k_{t+1} = (1 - \delta)k_t + x_t$$

$$k_0 \text{ given}$$

where  $c_t$  is consumption,  $x_t$  is gross investment,  $\tilde{r}(K_t)$  is the rental rate on capital,  $w(K_t)$  is a competitive wage, and  $\delta \in (0,1)$  is the depreciation rate on capital. Given the initial aggregate capital  $K_0 = k_0$ , the law of motion of aggregate capital,  $K_{t+1} = G(K_t)$ , determines a sequence of future aggregate capital stock  $\{K_t\}_{t=0}^{\infty}$  and hence, through equation (1), a sequence of future prices  $\{(w_t, \tilde{r}_t)\}_{t=0}^{\infty}$ .

Each household solves the above maximization problem taking as given the price sequence  $\{(w_t, \tilde{r}_t)\}_{t=0}^{\infty}$ . The policy function for the household is

$$k_{t+1} = g(k_t, K_t).$$

In equilibrium, k = K, so this household maximization, in turn, determines the law of motion K = g(K, K), which then determines another sequence of prices  $\{(w_t, \tilde{r}_t)\}_{t=0}^{\infty}$ .

Rewrite the household problem in terms of Bellman's equation as follows:

$$V(k,K) = \max_{c,k'} \log(c) + \beta V(k', G(K))$$
  
subject to:  $c + k' \le (1 + \tilde{r}(K) - \delta)k + w(K)$ . (2)

Let the associated policy function be g(k, K).

Define a recursive competitive equilibrium for this economy as a collection of functions: V(k, K), c(k, K), g(k, K),  $\tilde{r}(K)$ , w(K), G(K), and C(K) such that

- 1. Given the pricing functions,  $\tilde{r}(K)$  and w(K), and aggregate law of motion G(K), the functions V(k, K), c(k, K), and q(k, K), satisfy the household Bellman equation.
- 2. Given the pricing functions,  $\tilde{r}(K)$  and w(K), firms maximize profits.
- 3. the markets for consumption good, labour, and capital clear so that c(k, K) = C(K), n = 1, and g(k, K) = G(K).

We may define a steady state of this economy with the steady state aggregate capital level  $K^*$  that satisfies  $K^* = g(K^*, K^*) = G(K^*)$ .

In the following you are asked to numerically solve the recursive competitive equilibrium.

1. Use the parameter values  $\alpha = 0.25$ ,  $\beta = 0.96$   $A = (\alpha\beta)^{-1}$ , and  $\delta = 1$ . Our discretization for k and K will be  $k_i = 0.8 + (i-1)\kappa$  and  $K_i = 0.8 + (i-1)\kappa$ , for i = 1, 2, ..., n. We choose  $\kappa = 0.01$  with n = 41 so  $k_1 = K_1 = 0.8$  and  $k_n = K_n = 1.2$ . Also, set the value of the "relaxation parameter" as  $\xi = 0.99$ . You should use a tolerance  $\varepsilon_0 = 0.00001$  to test the convergence of the value function and a tolerance of  $\varepsilon_1 = 0.01$  for the convergence of the household policy function and the aggregate transition function.

To numerically solve the recursive equilibrium, consider the following algorithm:

- (a) Start from the initial guess of the law of motion of aggregate capital  $G^0(K)$ . Choose a constant function  $G^0(K) = 1$  for every K as an initial guess. Note that this initial guess implies that households expect aggregate capital to be K = 1 next period, regardless of what aggregate capital is today. This is a reasonable guess as K = 1 is the steady state capital level.
- (b) After h iterations, we have the law of motion of capital  $G^h(K)$ . Then, using the pricing functions (1), we solve a discretized version of the household Bellman equation by backward induction:

$$V(k,K) = \max_{k'} \log([1 + \tilde{r}(K) - \delta]k + w(K) - k') + \beta V(k', G^h(K)).$$
 (3)

Let the policy function be  $g^h(k, K)$ . Se below for how to solve (3) .

- (c) If  $||g^h(K,K) G^h(K)|| < \varepsilon_1$ , then  $G^h(K)$  is the fixed point and so stop. If  $||g^h(K,K) - G^h(K)|| \ge \varepsilon_1$ , then compute a new estimate of  $G^{h+1}(K) = \xi G^h(K) + (1-\xi)g^h(K,K)$  for a fixed "relaxation parameter"  $\xi \in (0,1)$  and go back to step (b).
- 2. Plot on a graph both the law of motion for the recursive equilibrium G(K), the house household policy function, and the policy function of corresponding planner's Bellman equation.<sup>1</sup> Check if they are the same. Hand in your program and the output.

### 1.1.1 How to numerically solve (3)

Notice that the state space is now (k, K) rather than k. Thus, the number of possible states in the household problem is  $n^2$ .

First, define the utility function  $U(k, K, k') \equiv \log([1 + \tilde{r}(K) - \delta]k + w(K) - k')$ . This utility function can be represented by an "n<sup>2</sup> by n" utility matrix, say U, where an

<sup>&</sup>lt;sup>1</sup>We computed this in homework 1.

[(i+(j-1)n), i'] element is equal to  $\log (\max \{[1+\tilde{r}(K_j)-\delta]k_i+w(K_j)-k_{i'}, \mathtt{eps}\}).^2$ Second, the law of motion  $G^h(K)$  can be represented by an "n by n" Markov matrix, denoted by  $Q_K$ , such that the (j,j')th element is 1 if  $K_{j'}=G^h(K_j)$  and 0 otherwise. Let  $q_{j,j'}$  be the (j,j')th element of the Markov matrix  $Q_K$ . The law of motion is then represented by the matrix operation

$$K' = G^h(K) = Q_K \times K.$$

Now, the discretized Bellman equation is given by

$$V(i,j) = \max_{i'=1,2,\dots,n} U(k_i, K_j, k_{i'}) + \beta \sum_{j=1}^{n} q_{j,j'} V(i', j').$$
(4)

We solve the fixed point of the Bellman equation as follows:

- 1. Set the initial guess  $V^0 = \mathbf{0}_{n,n}$ , where  $\mathbf{0}_{n,n}$  is an "n by n" matrix with each element a scalar 0.
- 2. After l value function iterations, we have an "n by n" matrix representing a value function,  $V^l$ . Given  $V^l$ , compute

$$V^{l+1}(i,j) = \max_{i'=1,2,\dots,n} U(k_i, K_j, k_{i'}) + \beta \sum_{j=1}^{n} q_{j,j'} V^l(i',j'),$$

for every  $(i, j) \in \{1, 2, ..., n\} \times \{1, 2, ..., n\}$ .

- One way to do this is to use a "do-loop" twice. For (i,j)=(1,1), compute  $U(k_1,K_1,k_{i'})+\beta\sum_{j'=1}^{\infty}q_{1,j'}V^l(i',j')$  for i'=1,2,...,n and store their values in an "n by 1" vector. Then, find the max among those values. If the  $i^*(1,1)$ th element is the max, then  $V^{l+1}(1,1)=U\left(k_1,K_1,k_{i^*(1,1)}\right)+\beta\sum_{j'=1}^{\infty}q_{1,j'}V^l(i^*(1,1),j')$ . This is the inner loop. Repeat this for every pair of  $(i,j)\in\{1,2,...,n\}$  ("outer loop") to get  $\{V^{l+1}(i,j)\}$  and store them in an "n by n" matrix; this is the function  $V^{l+1}$ .
- In practice, avoid loops as much as possible in Matlab since they slow down your program. Instead, use vector or matrix operations. In the current context, we may "vectorize" the state space. First, given the value function  $V^l$ , an "n by n" matrix with element  $V^l(i,j) = V^l(k_i, K_j)$ , create an "n by n" matrix,  $EV^l = V^lQ^T$  (where T is the transpose) which will represent the next period's value

<sup>&</sup>lt;sup>2</sup>The max operation inside the log is to ensure we do not take the log of a non-positive number. eps represents "machine zero" in Matlab. This is the smallest positive number that the computer can distinguish from zero.

function under the law of motion of aggregate capital Q. The (i', j)th element of  $EV^l$  represents the next period's value function when  $k = k_{i'}$  aggregate capital is  $K_j$ .

Second, compute an " $n^2$  by n" matrix  $W^{l+1} = \mathbf{U} + \beta \mathbf{1}_n \otimes \left( EV^l \right)^\top$ , where  $\mathbf{1}_n$  is an "n by 1" vector of ones,  $\top$  is a transpose, and  $\otimes$  is the Kronecker product.<sup>3</sup> Third, for each row, take the max across columns to compute an " $n^2$  by 1" vector  $V^{l+1}$ . You can do this using just one command.<sup>4</sup> Finally, to get back to an "n by n" matrix, use the command reshape(V1,n,n).

- 3. Repeat the recursive computations of step 2 until  $\max_{(i,j)\in\{1,2,\dots,n\}\times\{1,2,\dots,n\}}|V^l(i,j)-V^{l+1}(i,j)|<0.0001$ . Let  $V^*$  be the computed fixed point; the V that solves the Bellman equation.
- 4. Compute the policy function represented by an "n by n" Markov matrix, denoted by  $P_k$ , such that the (i, i')th element is 1 if  $k_{i'} = g(K_i, K_i)$ . Note that we want the policy function implies when markets clear, that is, when  $k_i = K_i$ . The policy function is then represented by the matrix operation

$$k' = g^h(K, K) = P_k \times k.$$

<sup>&</sup>lt;sup>3</sup>In Matlab, you can use the command W=U+beta\*kron(ones(n,1),EV'). Alternatively, you can use the command W=U+beta\*repmat(EV',n,). Look at the help files for kron and repmat to see exactly what each does.

<sup>&</sup>lt;sup>4</sup>In Matlab, you can use the command [V1 I]=max(W,[],2). This will result in two vectors. V1 will contain the value of the maximum of W, and I will contain the position of the maximum.

#### 1.1.2 Example with n = 5

Below I reproduce a sample of the matrices for an example with n = 5. The following are the numerical values for the "n by 1" vectors k, K, r(K), and w(K).

Below I reproduce the " $n \times n$  by n" Utility matrix U, and the values of "n by n" matrices  $Q_K$ ,  $V^0$ , and  $EV^0$ . The latter three are the values for the initial guess of  $G(K_j) = 1$  for all  $k_j$ , and for the first iteration of the value function. Below these we have the " $n \times n$  by n" matrix W, the "n by 1" vectorized versions of the value function  $V^1$ , and the indicator of the column containing the maximum value of W for each row: I.

U =	:					Q =				
	1.1444	1.1121	1.0786	1.0440	1.0082	0	0	1	0	0
	1.1829	1.1518	1.1196	1.0864	1.0521	0	0	1	0	0
	1.2199	1.1899	1.1590	1.1272	1.0942	0	0	1	0	0
	1.2556	1.2267	1.1970	1.1663	1.1346	0	0	1	0	0
	1.2901	1.2622	1.2335	1.2039	1.1735	0	0	1	0	0
	1.1460	1.1137	1.0803	1.0458	1.0100					
	1.1812	1.1500	1.1179	1.0846	1.0502					
	1.2152	1.1851	1.1541	1.1220	1.0889	VO =				
	1.2481	1.2190	1.1890	1.1581	1.1262	••				
	1.2800	1.2518	1.2228	1.1929	1.1621	0	0	0	0	0
	1.1500	1.1179	1.0846	1.0502	1.0146	0	0	0	0	0
	1.1825	1.1514	1.1192	1.0860	1.0517	0	0	0	0	0
	1.2139	1.1838	1.1527	1.1206	1.0874	0	0	0	0	0
	1.2444	1.2152	1.1850	1.1540	1.1219	0	0	0	0	0
	1.2740	1.2456	1.2164	1.1863	1.1553	U	U	U	U	U
	1.1557	1.1237	1.0906	1.0565	1.0211					
	1.1858	1.1237	1.1227	1.0896	1.0554	EV =				
						EV =				
	1.2150	1.1848	1.1538	1.1217	1.0886	^	_	•	^	_
	1.2433	1.2141	1.1839	1.1528	1.1207	0	0	0	0	0
	1.2709	1.2425	1.2132	1.1830	1.1519	0	0	0	0	0
	1.1624	1.1306	1.0978	1.0639	1.0287	0	0	0	0	0
	1.1904	1.1595	1.1277	1.0947	1.0607	0	0	0	0	0
	1.2177	1.1876	1.1567	1.1247	1.0917	0	0	0	0	0
	1.2442	1.2150	1.1848	1.1538	1.1217					
	1.2700	1.2416	1.2122	1.1820	1.1509					
W =						V1 =	I =			
	1.1444	1.1121	1.0786	1.0440	1.0082	1.1444		1		
	1.1829	1.1518	1.1196	1.0864	1.0521	1.1829		1		
	1.2199	1.1899	1.1590	1.1272	1.0942	1.2199		1		
	1.2556	1.2267	1.1970	1.1663	1.1346	1.2556		1		
	1.2901	1.2622	1.2335	1.2039	1.1735	1.2901		1		
	1.1460	1.1137	1.0803	1.0458	1.0100	1.1460		1		
	1.1812	1.1500	1.1179	1.0846	1.0502	1.1812		1		
	1.2152	1.1851	1.1541	1.1220	1.0889	1.2152		1		
	1.2481	1.2190	1.1890	1.1581	1.1262	1.2481		1		
	1.2800	1.2518	1.2228	1.1929	1.1621	1.2800		1		
	1.1500	1.1179	1.0846	1.0502	1.0146	1.1500 1				
	1.1825	1.1514	1.1192	1.0860	1.0517	1.1825 1				
	1.2139	1.1838	1.1527	1.1206	1.0874	1.2139 1				
	1.2444	1.2152	1.1850	1.1540	1.1219	1.2444 1				
	1.2740	1.2456	1.2164	1.1863	1.1553	1.2740 1				
	1.1557	1.1237	1.0906	1.0565	1.0211	1.1557 1				
	1.1858	1.1547	1.1227	1.0896	1.0554	1.185	8	1		
	1.2150	1.1848	1.1538	1.1217	1.0886	1.215	50	1		

```
1.2433
         1.2141
                   1.1839
                             1.1528
                                                      1.2709
1.2709
         1.2425
                   1.2132
                             1.1830
                                       1.1519
1.1624
         1.1306
                   1.0978
                             1.0639
                                       1.0287
                                                      1.1624
         1.1595
                   1.1277
                             1.0947
                                       1.0607
                                                      1.1904
1.1904
1.2177
         1.1876
                   1.1567
                             1.1247
                                       1.0917
                                                      1.2177
1.2442
         1.2150
                   1.1848
                             1.1538
                                       1.1217
                                                      1.2442
1.2700
         1.2416
                   1.2122
                             1.1820
                                       1.1509
                                                      1.2700
```

The following matrices are (again for the initial guess for  $G(K_j) = 1$  for all  $k_j$ ) The vectorized version of the converged value function  $V^1$ , The vector version of the indicator I, the matrix version of  $V^1$ , the policy function  $P_k^0$ , and the new guess for the aggregate transition function  $Q_K^1 = \xi Q_K^0 + (1 - \xi) P_k^0$ .

```
V1 =
           I =
                   V1 =
  28.7452
                     28.7452 28.7468
                                        28.7509
                                                  28.7565
                                                           28.7632
  28.7842
                     28.7842
                              28.7825
                                        28.7838
                                                  28.7872
                                                           28.7920
  28.8231
                              28.8181
                                        28.8168
                                                  28.8179
                     28.8231
                              28.8537
                                        28.8496
  28.9006
                     28.9006
                              28.8892
                                        28.8825
                                                  28.8790
  28.7468
  28.7825
  28.8181
  28.8537
  28.8892
  28.7509
                                              0
  28.7838
                                              0
  28.8168
  28.8496
  28.8825
  28.7565
  28.7872
               3 Q =
  28.8179
  28.8485
  28.8790
                      0.0100
                                    0
                                         0.9900
                      0
  28.7632
                               0.0100
                                         0.9900
                                                     0
  28.7920
                          0
                                    0
                                         1.0000
  28 8207
               3
                          Ω
                                    0
                                         0.9900
                                                   0.0100
  28.8494
                                                             0.0100
  28.8780
```

Using the new  $Q_K^1 = \xi Q_K^0 + (1 - \xi) P_k^0$ , we repeat the value function iteration again. Note that the household policy function is  $k' = g(K, K) = P_k^0 k$  and the new aggregate transition function for capital is  $K' = G(K) = Q_K^1 K$ . Below I plot the first five iterations on  $Q_K$ . That is, I plot the guess of  $K' = Q_K^1 K$  and the implied household policy function  $k' = P_k^0 k$ . Policy functions,  $k' = P_k^l k$ , and Aggregate capital transitions,  $K' = Q_K^l K$ , for an example with grid size n = 5.

