MotionControl
+ init() + moveToPosition() + moveServo() + moveServo() + moveServoTimed() + moveServoTimed() + moveMultipleServosTimed() + stopMovementCommand() + stopServo() + stopServo() + stopAllServos() + isMovementFinished() + getServoCurrentPulseWidth() + getBaudRate() + setBaudRate() + addServoStartupPosition() + downloadStartupString() + clearStartupString() + getServoChannelFromName() + getServoFromChannel() + ~MotionControl() + getInterfaceState() + setInterfaceState() + getInstance()