

SymBeam

[SymBeam](#) is a pedagogical Python package for bending diagrams computation, aimed at Mechanical, Civil and Industrial Engineering students.

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In [1]: #!/pip install symbeam # uncomment the line if you need to install symbeam to Colab
%matplotlib inline
from symbeam import beam
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In [2]: # Define the Length of the beam
new=beam(length = 'L')

# Set the Young modulus and second moment of area of beam segments
new.set_young(x_start = 0, x_end = 'L', value = 210e6)
new.set_inertia(x_start = 0, x_end = 'L', value = 5e-6)

# Add supports. Options are (pin, roller, hinge and fixed)
new.add_support(x_coord = 0, support_type = 'fixed')
new.add_support(x_coord = 'L/2', support_type = 'hinge')
new.add_support(x_coord = '3*L/4', support_type = 'roller')

# Add external loads. Loads can be (point_force, point_moment, or distributed_load)
new.add_point_load(x_coord = 'L', value = '-P')
new.add_point_moment(x_coord = 'L/4', value = 'P*L')
new.add_distributed_load(x_start = 0, x_end = 'L/2', expression = '-P * x / L')
```

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In [3]: new.solve()
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Beam points			
Coordinate	Type	Load	Moment
0	Fixed	0	0
L/4	Continuity point	0	L*P
L/2	Hinge	0	0
3*L/4	Roller	0	0
L	Continuity point	-P	0

Beam segments			
Span	Young modulus	Inertia	Distributed load
[0 - L/4]	210000000.000000	5.00000000000000e-6	-P*x/L
[L/4 - L/2]	210000000.000000	5.00000000000000e-6	-P*x/L
[L/2 - 3*L/4]	210000000.000000	5.00000000000000e-6	0
[3*L/4 - L]	210000000.000000	5.00000000000000e-6	0

Exterior Reactions		
Point	Type	Value
0	Force	L*P/8 - P
0	Moment	L**2*P/24 - 3*L*P/2
3*L/4	Force	2*P

Internal Loads		
Span	Diagram	Expression
[0 - L/4]	V(x)	P*(8 - L)/8 + P*x**2/(2*L)
[0 - L/4]	M(x)	L*P*(36 - L)/24 + x*(L*P/8 - P) - P*x**3/(6*L)
[L/4 - L/2]	V(x)	P*(8 - L)/8 + P*x**2/(2*L)
[L/4 - L/2]	M(x)	L*P*(12 - L)/24 + x*(L*P/8 - P) - P*x**3/(6*L)
[L/2 - 3*L/4]	V(x)	P
[L/2 - 3*L/4]	M(x)	L*P/2 - P*x
[3*L/4 - L]	V(x)	-P
[3*L/4 - L]	M(x)	-L*P + P*x

Rotation and deflection		
Span	Variable	Expression
[0 - L/4]	v(x)	x**3*(1.98412698412698e-5*L*P - 0.000158730158730159*P) + x**2*(-1.98412698412698e-5*L**2*P + 0.000714285714285714*L*P) - 7.93650793650794e-6*P*x**5/L
[0 - L/4]	dv/dx(x)	x**2*(5.95238095238095e-5*L*P - 0.000476190476190476*P) + x*(-3.96825396825397e-5*L**2*P + 0.00142857142857143*L*P) - 3.96825396825397e-5*P*x**4/L
[L/4 - L/2]	v(x)	-2.97619047619048e-5*L**3*P + 0.000238095238095238*L**2*P*x + x**3*(1.98412698412698e-5*L*P - 0.000158730158730159*P) + x**2*(-1.98412698412698e-5*L**2*P + 0.000238095238095238*L*P) - 7.93650793650794e-6*P*x**5/L
[L/4 - L/2]	dv/dx(x)	0.000238095238095238*L**2*P + x**2*(5.95238095238095e-5*L*P - 0.000476190476190476*P) + x*(-3.96825396825397e-5*L**2*P + 0.000476190476190476*L*P) - 3.96825396825397e-5*P*x**4/L
[L/2 - 3*L/4]	v(x)	-8.18452380952381e-6*L**4*P + 0.000401785714285714*L**3*P + 0.000238095238095238*L*P*x**2 - 0.000158730158730159*P*x**3 + 1.0*x*(1.09126984126984e-5*L**3*P - 0.000625*L**2*P)
[L/2 - 3*L/4]	dv/dx(x)	1.09126984126984e-5*L**3*P - 0.000625*L**2*P + 0.000476190476190476*L*P*x - 0.000476190476190476*P*x**2
[3*L/4 - L]	v(x)	-8.18452380952381e-6*L**4*P + 0.000267857142857143*L**3*P - 0.000476190476190476*L*P*x**2 + 0.000158730158730159*P*x**3 + 1.0*x*(1.09126984126984e-5*L**3*P - 8.92857142857143e-5*L**2*P)
[3*L/4 - L]	dv/dx(x)	1.09126984126984e-5*L**3*P - 8.92857142857143e-5*L**2*P - 0.000952380952380952*L*P*x + 0.000476190476190476*P*x**2

In [4]: new.plot()

Out[4]: (<Figure size 504x576 with 4 Axes>,
<Axes: >,
<Axes: ylabel='Shear force, \$V(x)\$'>,
<Axes: ylabel='Bending moment, \$M(x)\$'>,
<Axes: xlabel='Coordinate, \$x\$', ylabel='Deflection, \$v(x)\$'>])

