



- User needs to be able to see error outside of Control Center because error could cause loss of connection to control center

- User does not access data from robot, should do that via the control center

- Get obstacles, get visited & get pictures needs to be able to be executed separately. As when the user asks the control center for any of those specific data sets the control center should be able to obtain the latest version. Instead of using the version obtained last time "get all data" was used.