# Thomas Weng

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## RESEARCH INTERESTS

I am interested in human-robot interaction, particularly in the domains of socially-guided learning, legible motion, and other forms of computational modeling for social robots.

## **EDUCATION**

#### 2011 - 2015

# B.S. Computer Science & B.A. Economics, Yale University

GPA: 3.77 with distinction in the C.S. major

SENIOR PROJECT: Real-time robot perception of human nonverbal behavior Advisors: Brian Scassellati, Henny Admoni

Created a perception system using the Kinect 2 to detect human gazing and pointing gestures towards objects. Connected the Windows-based Kinect 2 and Linux-based Nao robot via websocket connection to transfer RGBD and skeleton data (no Linux drivers were available for the Kinect 2 at the time). Evaluated the system on object disambiguation tasks.

#### RESEARCH EXPERIENCE

#### 2017 - 2018

#### Research Scientist

Human-Centered Robotics Lab, University of Washington

PI: Maya Cakmak

Developed a situated interface for human-robot communication using a robot-mounted projector. Designing an optimization model that places projected object labels on a surface, maximizing the likelihood of referencing selected objects while minimizing the likelihood of referencing distractor objects. Extended the interface for use as a feedback mechanism in the context of situated tangible programming.

#### 2014 - 2015

#### Research Assistant

Social Robotics Lab, Yale University

PI: Brian Scassellati

Worked on robot generation of social nonverbal behavior (NVB) with Henny Admoni. Implemented gesture generation system based on NVB model using a Kinect 2 and Nao robot. Used system in user studies validating NVB model on human-robot collaborations.

## **PUBLICATIONS**

- 2016 Admoni, H., Weng, T., and Scassellati, B. Modeling communicative behaviors for object references in human-robot interaction. In *IEEE International Conference on Robotics and Automation (ICRA)*, pages 3352-3359. Acceptance rate: 35%
- Admoni, H., **Weng, T.**, Hayes, B. and Scassellati, B. Robot nonverbal behavior improves task performance in difficult collaborations. In *ACM/IEEE International Conference on Human Robot Interaction (HRI)*, pages 51-58. Acceptance rate: 25%

## **AWARDS AND HONORS**

- 2018 Graduate Research Fellowship Honorable Mention, NSF
- 2015 Computer Science Research Prize, Yale University

Awarded to the graduating senior who, in the judgment of the Computer Science faculty, ranks highest in research.

2014 Trumbull College Scholarship for Economics, Yale University

## **OUTREACH**

#### 2017 Robotics Review Newsletter

Writing a weekly newsletter for the public covering robotics-related research and news. Growing audience with over 100 weekly readers.

## 2017 Code Haven at Yale guest speaker, New Haven, CT

Spoke with students at under-served New Haven public schools about STEM careers.

## 2015 Trumbull College Mellon Forum, Yale University

Presented thesis at a selective opportunity for seniors to share their work with peers.

## 2015 Yale Social Robotics Lab open house, Yale University

Demonstrated social perception system at semi-annual open house for the public, drawing approx. 100 adults and children from the greater New Haven community.

# INDUSTRY AND OTHER EXPERIENCE

## APR 2018 -

## **Programming Retreat Participant**

Jun 2018

Recurse Center, New York, New York

Recurse Center hosts self-directed, community-driven retreats for programmers. Worked on projects such as implementing RL algorithms to solve OpenAl Gym environments, building a web app to recommend robotics publications to users using latent semantic analysis, and developing intelligent behaviors such as navigation and ball-following on a mobile robot built from scratch.

#### SEP 2015 -

#### **Software Engineer 2**

JUL 2017

Bing Answers, Microsoft Corporation, Bellevue, WA

Created nine interactive Bing answers relating to the 2016 U.S. elections, generating over 100 million impressions over the course of the campaign. Developed a Q&A card on the Bing search results page to display workplace-related results for an enterprise search product.

## SUMMER

2014

## **Software Engineer Intern**

Bing Answers, Microsoft Corporation, Bellevue, WA

Built WordPress plugins for Bing widgets, enabling third party WordPress sites to add contextual images and other rich content from Bing to their web pages.

#### SUMMER

### **Program Manager Intern**

2013

Bing Ads, Microsoft Corporation, Bellevue, WA

Shipped a service health page for the Bing Ads API service, coordinating the project end-to-end.

# TECHNICAL SKILLS AND TRAINING

Software C/C++, Python, C#.NET, Java, JavaScript, R, Octave/MATLAB, SQL

Relevant frameworks: ROS, OpenCV, Movelt!, OpenRAVE, Tensorflow, React

Hardware PR2, Aldebaran Nao, Rethink Robotics Baxter, 6DOF Kuka KR210,

Kinect, Raspberry Pi, Arduino

Courses Motion Planning Robotics Nanodegree Neural Networks

UW CSE 599 Udacity Coursera
Taken Fall Qrtr '17 Finished Term 1 of 2, Sep '17 Completed Feb '17
Python, OpenRAVE Python, ROS, TF Octave/MATLAB