Problem 1

Consider example elliptic3D.m

- 1. What is the domain of the PDE (the region where the PDE holds)? 7x8x9 cells
- 2. What is the equation this example is solving? Poisson equation

$$\Delta u = 0 \tag{1}$$

3. What the force function or right hand side?

$$\Delta u = RHS$$

$$\nabla^2 u = 0$$
(2)

- 4. What type of boundary conditions? Dirichlet, b = 0
- 5. Change the boundary condition to be 100 on the front and back face of the cube. RHS(:,:,1)=100 RHS(:,:,9)=100
- 6. Run the example with all the changes you have made. On the next pages are the plots for the changes, page 1 to 9.

Homework 3

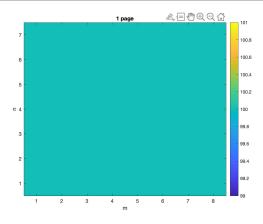


Figure 1: Page 1

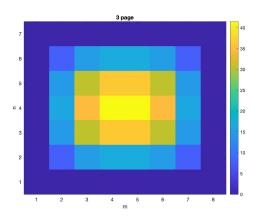


Figure 3: Page 3

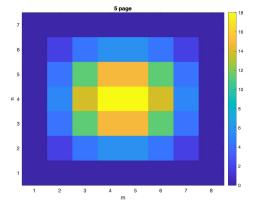


Figure 5: Page 5

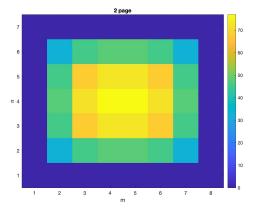


Figure 2: Page 2

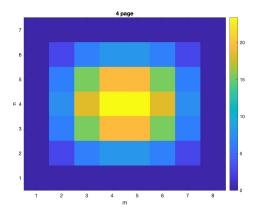


Figure 4: Page 4

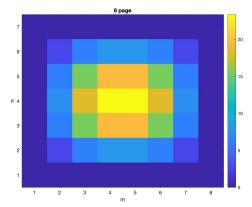


Figure 6: Page 6

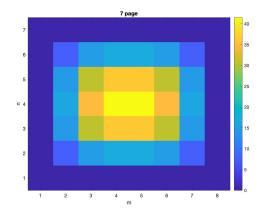


Figure 7: Page 7

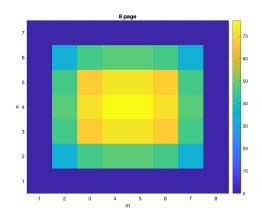


Figure 8: Page 8

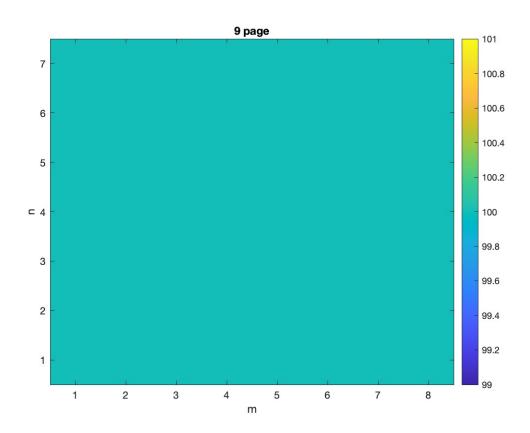


Figure 9: Page 9

7. Please, include all m files you have modified and a document (named elliptic3DWork.docx) describing explicitly the PDE to a Canvas message with subject COMP670 hw3 elliptic3D.

The Matlab code includes the following changes:

• line 21: RHS(:, :, 9) = 100;

```
% 3D Staggering example using a 3D Mimetic laplacian
1
2
3
       close all
      addpath ('../mole_MATLAB')
5
      k = 2; % Order of accuracy
      m = 5; \% -> 7
                       Number of cells along x-axis
      n = 6; \% -> 8
g
      o = 7; \% -> 9
10
      L = lap3D(k, m, 1, n, 1, o, 1); \% 3D Mimetic laplacian operator
12
      L = L + robinBC3D(k, m, 1, n, 1, o, 1, 1, 0); % Dirichlet BC
13
14
      RHS = zeros(m+2, n+2, o+2);
15
      % RHS
16
17
      RHS(:, :, 1) = 100; % Known value at the cube's front face
18
19
      RHS
      RHS(:, :, 9) = 100; % Known value at the cube's back face
20
      RHS
21
22
      RHS = reshape(RHS, (m+2)*(n+2)*(o+2), 1); % Create vector with 6*7*8 rows
23
      % RHS
24
25
      SOL = L\backslash RHS;
26
27
      SOL = reshape(SOL, m+2, n+2, o+2); % reshape back to matrix
28
29
      p = (8); % Page to be displayed
30
      page = SOL(:, :, p);
31
32
      imagesc (page)
33
       title ([num2str(p) 'page'])
34
       xlabel ('m')
35
       ylabel('n')
36
       set(gca, 'YDir', 'Normal')
37
       colorbar
38
39
```

Listing 1: changed Matblab code for file elliptic3D.m

Problem 2

Consider example parabolic 1D.m (in this example you will not modify the MATLAB source code)

- 1. What is the domain of the PDE (the region where the PDE holds)? Domain: 0-1
- 2. What is the equation this example is solving? Heat equation

$$\frac{\partial u}{\partial t} = \alpha \Delta u \tag{3}$$

- 3. What is the initial condition? $U + zeros(m+2,1); \rightarrow U = (0; 0; 0; 0; 0; ...)$
- 4. What are the boundary conditions? U(1)=100; U(end)=100; Dirichlet
- 5. What the force function or right hand side? RHS=0
- 6. Explore and explain what is the Neumann stability criterion. Explore:

$$dt = \frac{dx^2}{3 \cdot \alpha} \tag{4}$$

Explain:

The system is conditionally stable for the backward euler method. The equation 4 is the criteria which has to be fulfilled for a stable system. Otherwise we get inappropriate behavior due to scheme.

7. How the partial derivative with respect to time is discretized in the explicit scheme of this code?

Forward Euler

8. How the partial derivative with respect to time is discretized in the implicit scheme of this code?

Backward Euler

9. Run the example with the explicit scheme and store its numerical solution.

U =

- 1.0e+02*
- 1.0000000000000000
- 0.999990291533084
- 0.999973708183323
- 0.999967356462446
- 0.999973708183323
- 0.999990291533084
- 1.00000000000000000
- 10. Run the example with the implicit scheme and store its numerical solution.

U =

- 1.0e+02*
- 1.0000000000000000
- 0.999964740685190
- 0.999904513096742
- 0.999881444848386
- 0.999904513096743
- 0.999964740685190
- 1.0000000000000000
- 11. Make a plot of both solutions, explicit in blue and implicit in red. You can leverage on the plotting code that the example has.

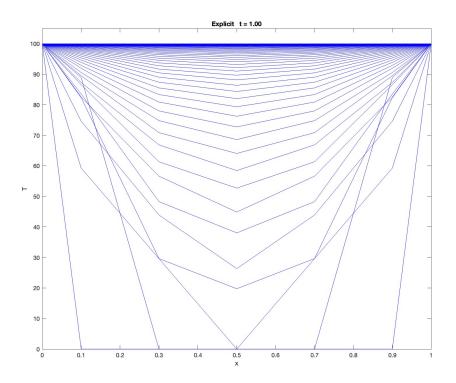


Figure 10: Explicit

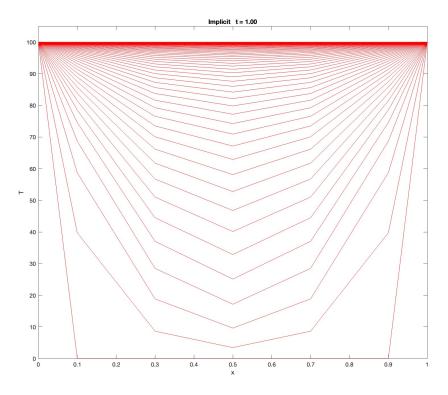


Figure 11: Implicit

12. Please, include the plot and a document (named parabolic1DWork.pdf) describing explicitly the PDE to a Canvas message with subject COMP670 hw3 parabolic1D.

Problem 3

Write an extension of the parabolic1D.m example (name parabolic2D.m) to apply MOLE with explicit time discretization scheme to the following 2D heat equation Use what you have learned from elliptic3D.m and parabolic1D.m examples.

- 1. Be sure the code runs successfully.
- 2. Please, include parabolic2D.m to a Canvas message with subject COMP670 hw3 parabolic2D.

The following Matlab code shows the code for parabolic2D.m file.

```
% Solves the 2D Heat equation, changed example wave2D/parabolic1D
      % Thomas Keller, COMP670 HW3
2
3
       clc: close all;
      addpath ('../mole_MATLAB')
5
6
      % Spatial discretization
               % Order of accuracy
      k = 2;
      m = 3*k+1; % Number of cells along the x-axis
9
                % Number of cells along the y-axis
      n = m;
      a = 0;
                % West
11
                % East
      b = 1;
12
                % South
       c = 0;
13
                % North
      d = 1:
14
      dx = (b-a)/m; % Step length along the x-axis
15
      dy = (d-c)/n; % Step length along the y-axis
17
      % 2D Staggered grid
18
      xgrid = [a a+dx/2 : dx : b-dx/2 b];
19
      ygrid = [c c+dy/2 : dy : d-dy/2 d];
20
21
      % Create 2D meshgrid
22
       [X, Y] = \frac{\text{meshgrid}}{\text{meshgrid}}(xgrid, ygrid);
23
24
      % Mimetic operator Laplacian 2D
25
      L = lap 2D(k, m, dx, n, dy);
26
27
      % alpha
28
      alpha = 1;
29
30
      % Check neumann stability
      % Neumann stability criterion
32
      dt = dx^2/(5*alpha);
33
34
      % BC
35
      U = zeros(m+2, n+2);
36
      U(1,:)=100;
37
      U(:,1) = 100;
```

```
U(end,:) = 100;
39
       U(:, end) = 100;
40
       U
41
       U = reshape(U, (m+2)*(n+2), 1);
42
43
44
       % Simulation time
45
       TIME = 0.3;
46
       explicit = 1; % Explicit, for 0 -> implicit
48
49
       if explicit
50
           % Explicit
           L = alpha*dt*L + speye(size(L)); \% S = speye returns a sparse scalar 1
       to L
           % Time integration loop
            for t = 1: TIME/dt+1
55
                % Plot result explicit
56
                \operatorname{mesh}(X, Y, \operatorname{reshape}(U, m+2, n+2))
                title (['Parabolic, Explicit Solution, Time = 'num2str(dt*t, '%1.2
58
      f ')])
                xlabel('x')
59
                ylabel('y')
60
                zlabel('z')
61
                colorbar
62
                caxis ([0, 100]) % change colors of plot
63
                axis ([0 1 0 1 0 101])
                drawnow
65
                U = L*U; % Apply the operator
66
            end
67
       else
           % Implicit
69
           L = -alpha*dt*L + speye(size(L));
70
71
           % Time integration loop
72
            for t = 1: TIME/dt+1
                % Plot result implicit
74
                \operatorname{mesh}(X, Y, \operatorname{reshape}(U, m+2, n+2))
75
                title (['Parabolic, Implicit Solution, Time = 'num2str(dt*t, '%1.2
      f ')])
                xlabel('x')
77
                ylabel('y')
                zlabel('z')
                colorbar
80
                caxis ([0, 100]) % change colors of plot
81
                axis ([0 1 0 1 0 101])
                drawnow
83
                U = L \setminus U; % Solve a linear system of equations (unconditionally
      stable)
85
            end
       end
86
87
```

Listing 2: changed Matblab code for file parabolic2D.m