



Image Segmentation with Different ML Model

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Executive Summary

Introduction

- What is image segmentation?

Methodology

- How we do image segmentation?

Result

- What is pros and cons of image segmentation by using different models

Conclusion

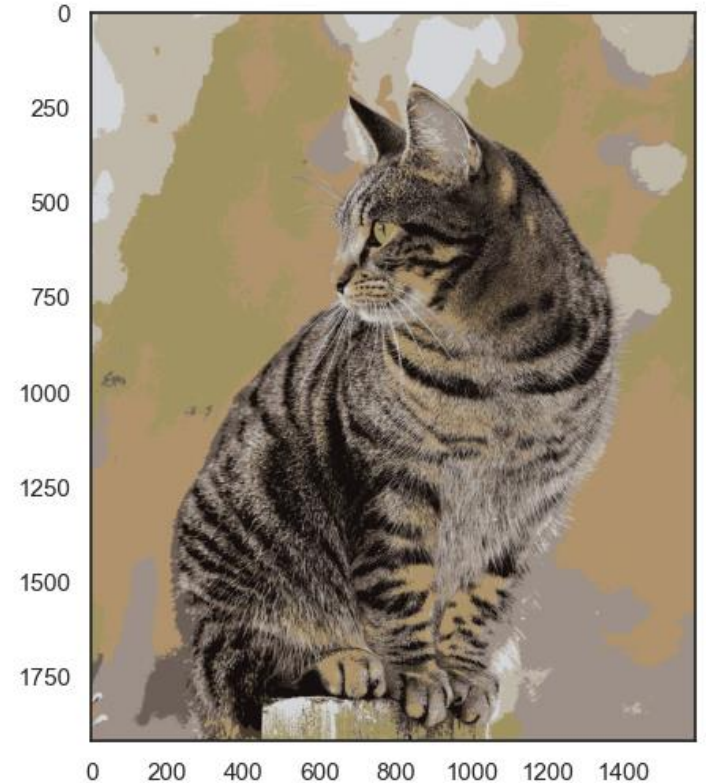
- Summary of the result

Appendix

- Links & other reference

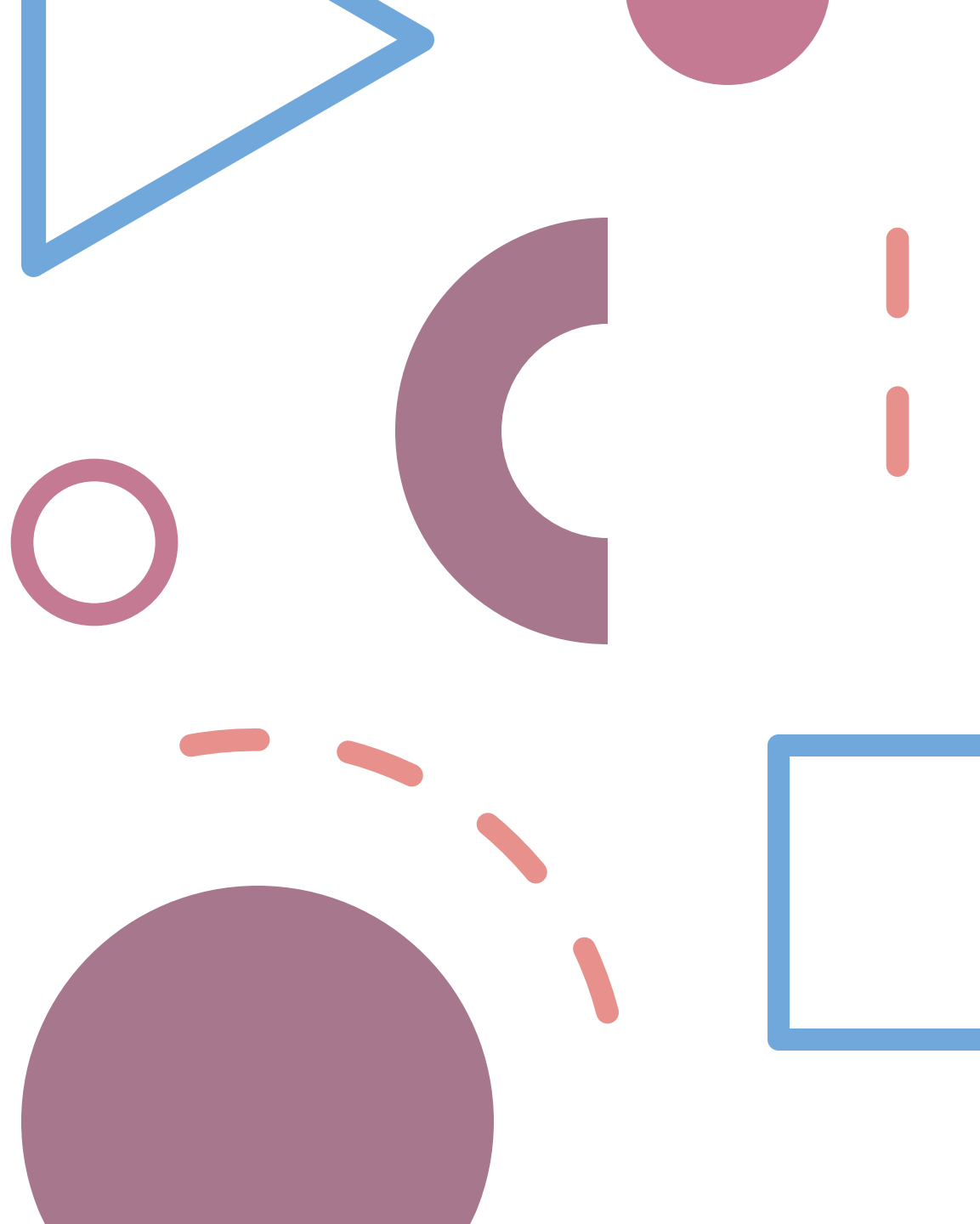
Introduction

- Image segmentation is a computer vision technique that partitions a digital image into discrete groups of pixels—image segments—to inform object detection and related tasks.
- By parsing an image's complex visual data into specifically shaped segments, image segmentation enables faster, more advanced image processing.



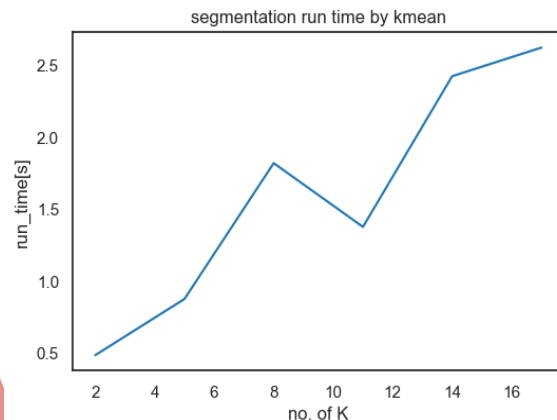
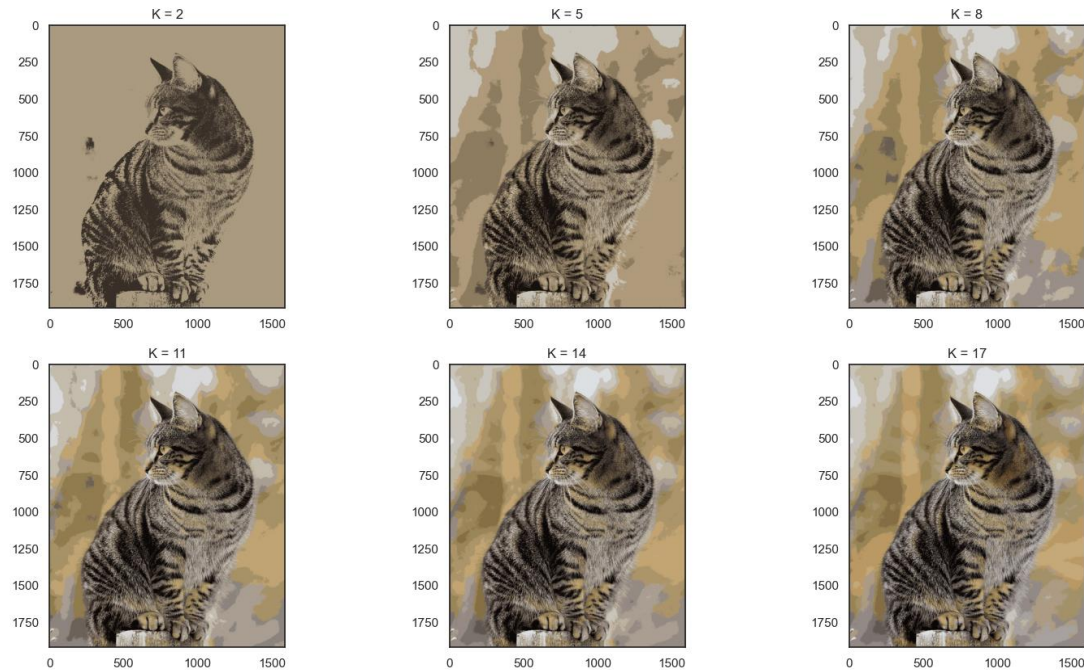
Methodology

- In this project we used the following library and ML model for image segmentation experience
 - Clustering Models
 - Kmeans (sklearn)
 - GaussianMixture(sklearn)
 - MeanShift
 - Decomposition
 - Principal component analysis(PCA)



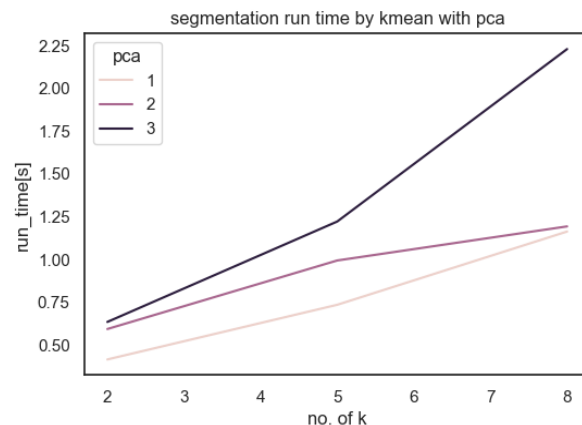
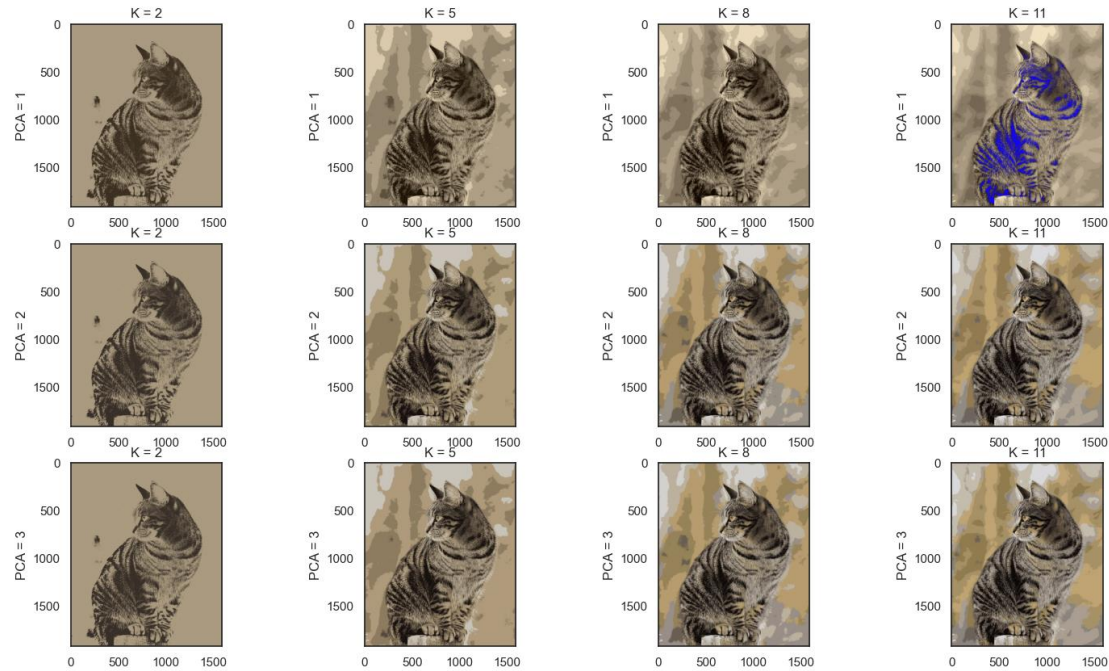
Result

- Kmeans without PCA
 - K=2 mean there is only two groups and our imaged was segmented to two colors only.
 - By increasing K (no. Of colors) we can see our segmented image looks remarkably similar to the original.
 - Increasing K take more time to run than less K

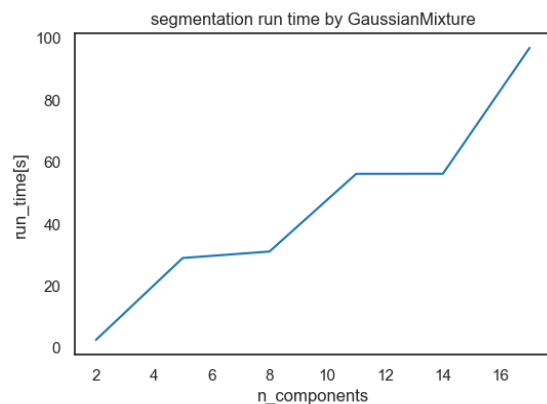
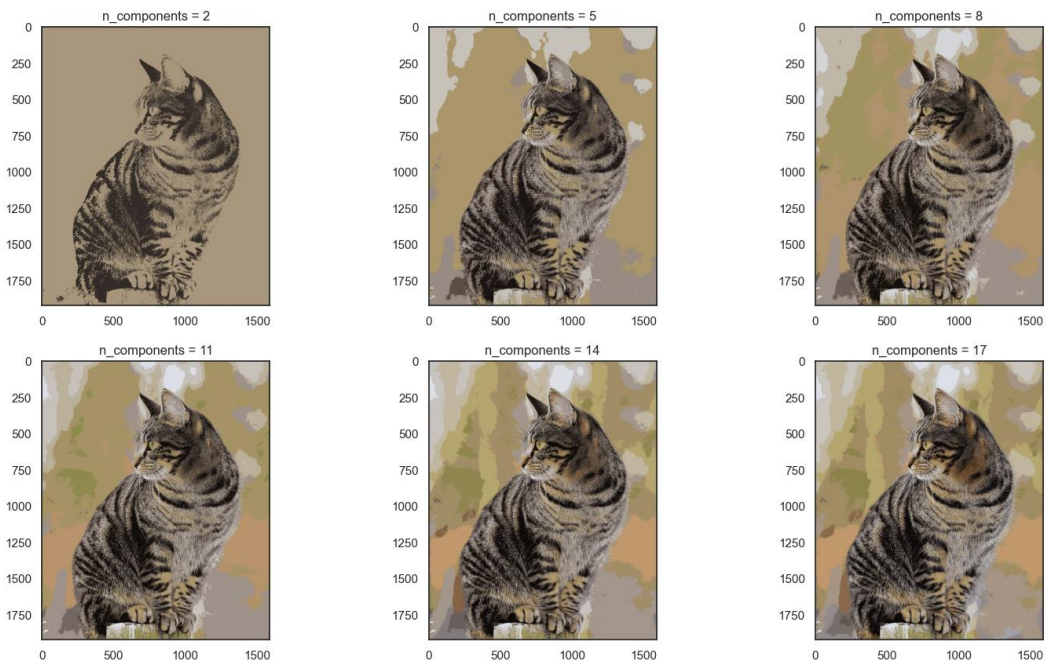


Result

- Kmeans with PCA
 - PCA with less components reduce variance and so we can see it reduced color saturation
 - PCA with less components take less time to run than without pca
 - There was unexpected color when $pca = 1$ and $k = 11$.



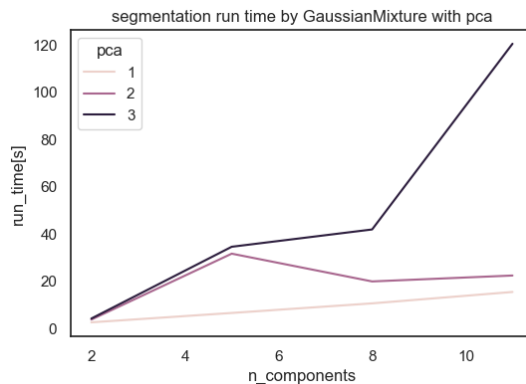
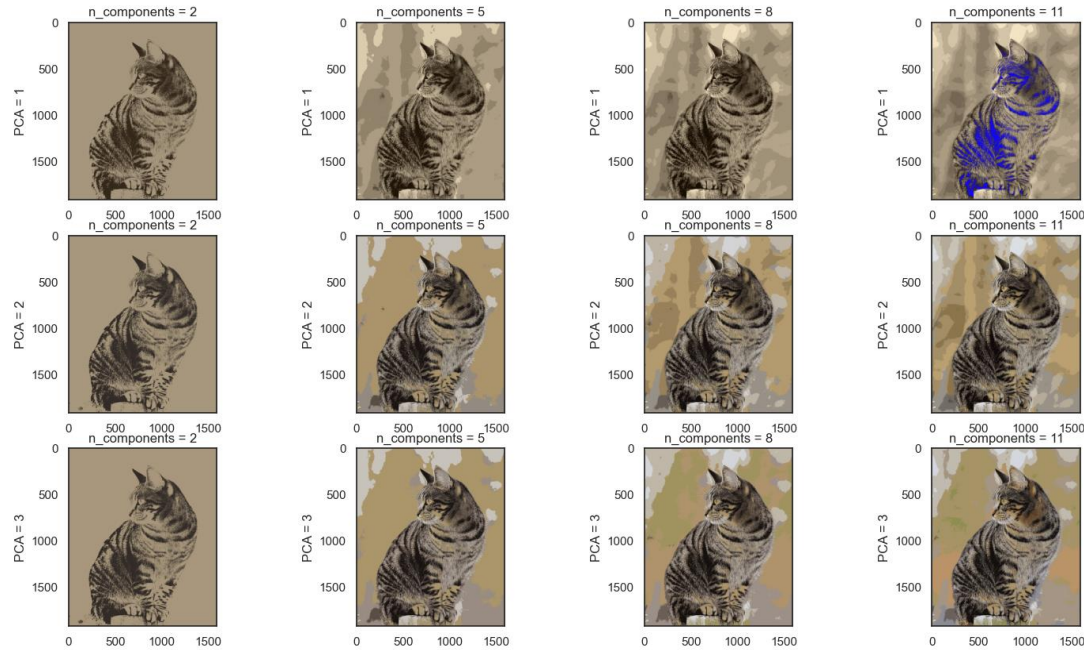
Result



- GaussianMixture without PCA
 - $N_components (K) = 2$ mean there is only two groups and our imaged was segmented to two colors only.
 - By increasing components we can see our segmented image looks remarkably similar to the original.
 - Increasing components take more time to run than less components

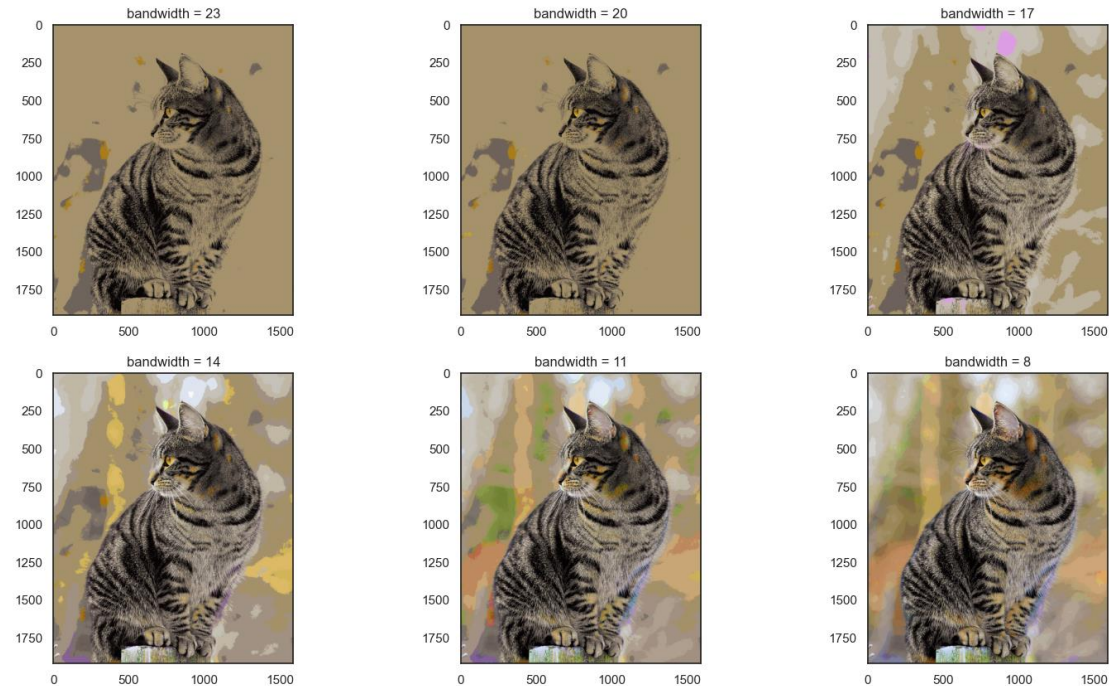
Result

- GaussianMixture PCA
 - PCA with less components reduce variance and so we can see it reduced color saturation
 - PCA with less components take less time to run than without pca
 - There was unexpected color when $pca = 1$ and $k = 11$.



Result

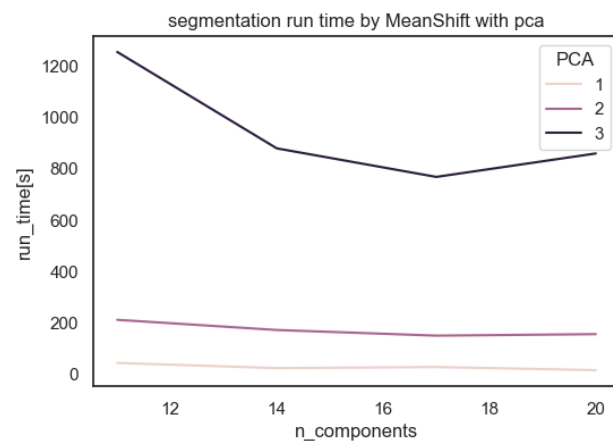
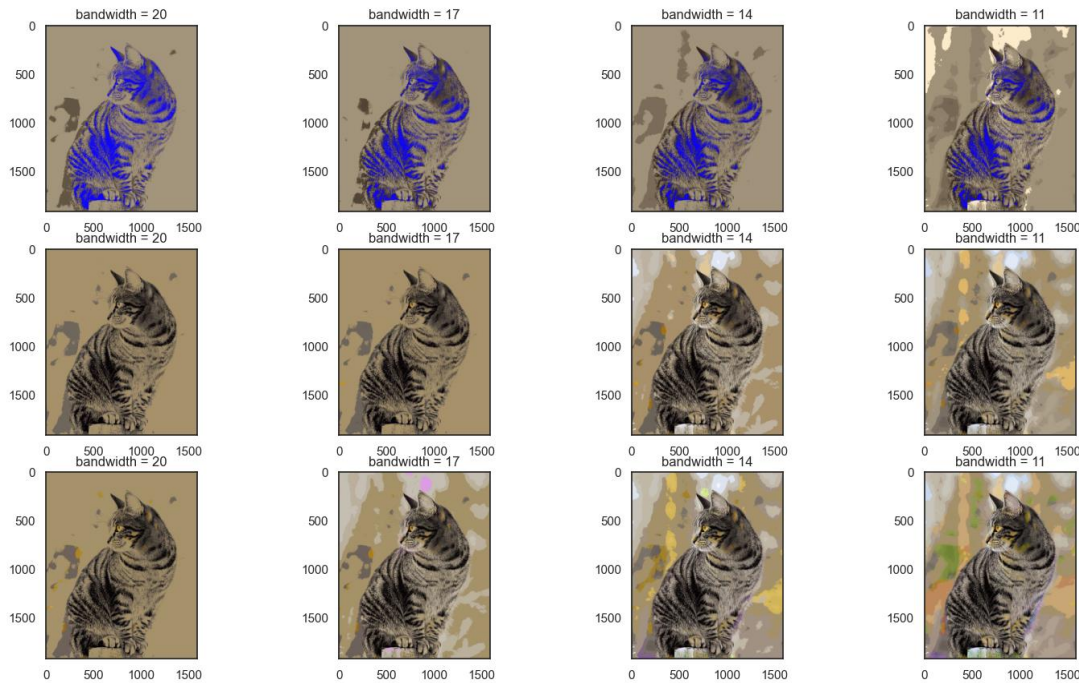
- MeanShift without PCA
 - Bigger bandwidth make less cluster and so less color
 - By decreasing bandwidth we can see our segmented image increased more cluster (colors) and so more likely to original.
 - MeanShift take a lot of time to segment and so take a lot of computational power
 - Less bandwidth groups make more clusters and so take more computational power.



Result

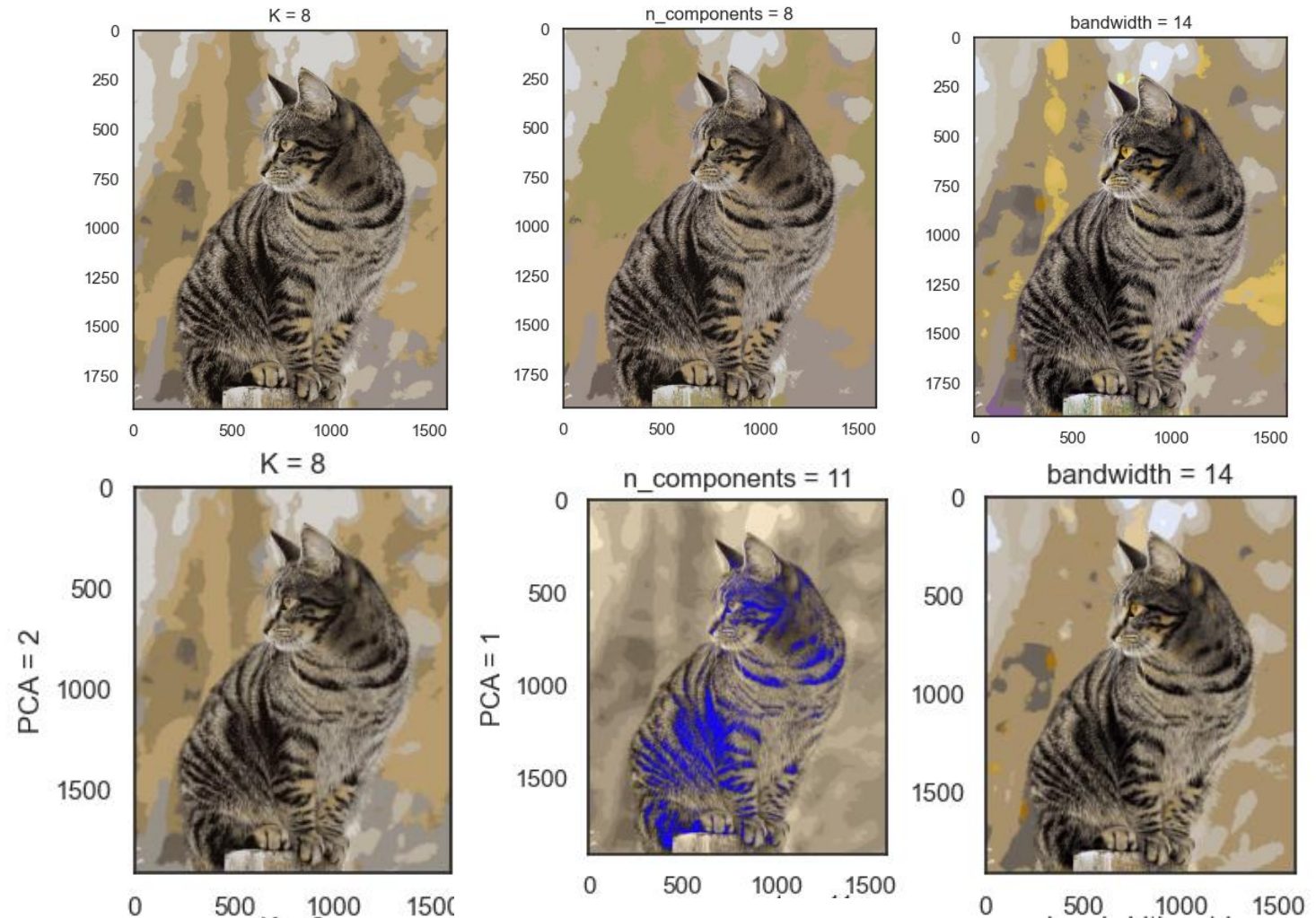
- MeanShift with PCA

- PCA with only 1 components seen loss some data and strange blue color appear after segmentation
- PCA with components < original features improve much on run time
- PCA with components = 2 improved run time also does not impacted much on quality



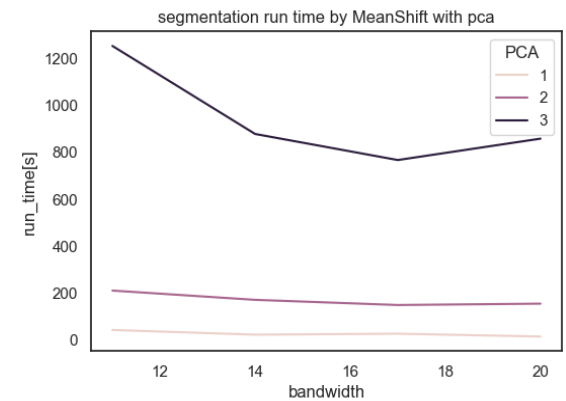
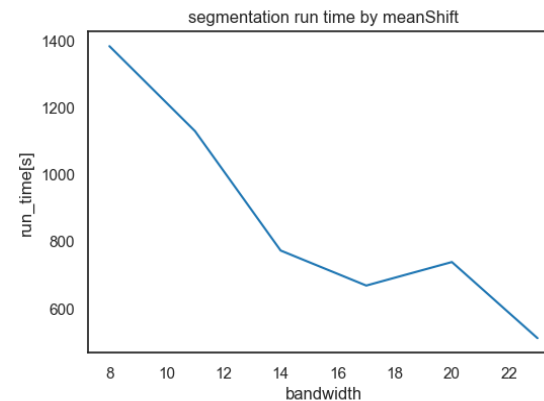
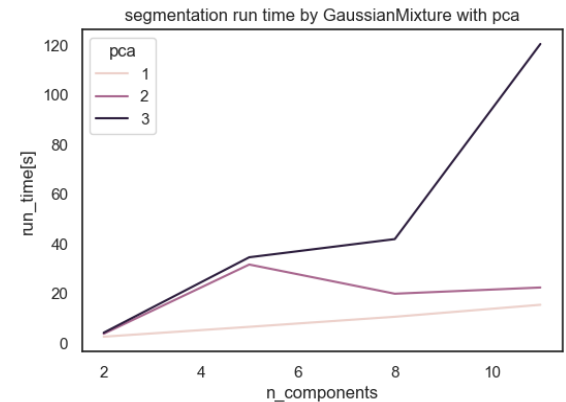
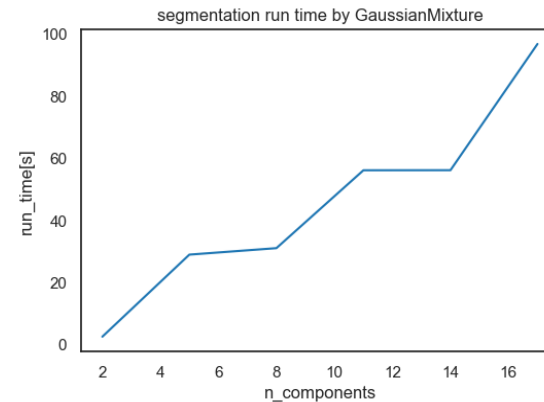
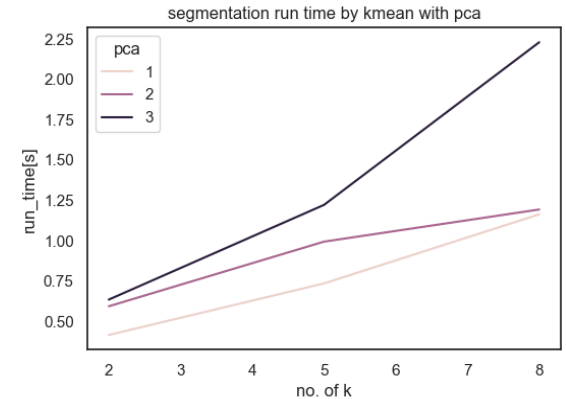
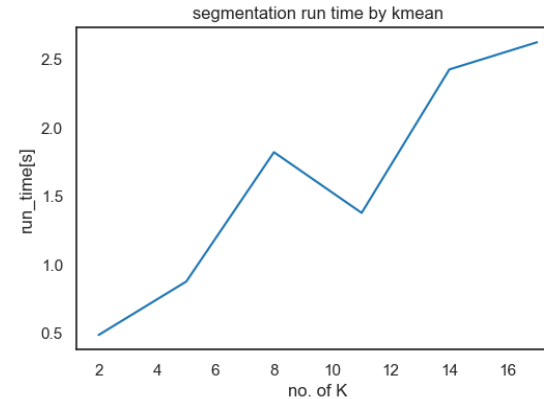
Conclusion

- Segmentation Result
 - Meanshift are sensitive to noise and make more cluster according
 - GaussianMixture seen generalized more than kmeans
 - Decomposition with $pca=2$ seen does not impact much on quality as we compare on kmean but it more generalized on meanshift result
 - Decomposition with $pca = 1$ seen does not have much variance because it introduce strange blue color when cluster is 11 and more



Conclusion

- Segmentation Result
 - Kmean is the fastest and even better with pca
 - GaussianMixture a little bit slower than kmeans but it still acceptable and better performance by pca
 - Meanshift are very slow but got some improvement with pca



Appendix

- Image in this project was downloaded from the following link
 - <https://cf-courses-data.s3.us.cloud-object-storage.appdomain.cloud/IBM-ML0187EN-SkillsNetwork/labs/module%201/images/gauss-cat.jpeg>
- Other cluster models such as Agglomerative and DBSCAN seen required more computation power and don't have chance to try it
- Decomposition like kernel PCA and SVD also not tested due to computational limitation



Thank You