

46.1.

Modules over PIDs:

AKA linear algebra in more generality.

Recall that an R -module M is free if it has a finite basis: there exist $a_1, \dots, a_n \in M$ s.t., for all $x \in M$, we have $x = r_1 a_1 + \dots + r_n a_n$ for unique r_1, \dots, r_n .

Have $M \cong R^n$ as R -modules.

Proposition. Let R be an integral domain, and let M be a rank (dimension) n R -module.

Then any set of $n+1$ vectors is linearly ~~independent~~.

Proof 1. Embed R in its quotient field F .

By linear algebra, there is a relation in F .
Clear denominators.

Proof 2. Use determinants.

Def. If R is a domain and M is any R -module,

$$\text{Tor}(M) := \{ x \in M : rx = 0 \text{ for some } 0 \neq r \in R \}.$$

This is the torsion submodule (ex: prove it's a submodule) of M .

If $\text{Tor}(M) = 0$, then M is torsion-free.

46.2

Def. For any submodule $N \subseteq M$, the annihilator of N is
$$\text{Ann}(N) = \{ r \in R : rn = 0 \text{ for all } n \in N \}.$$

Basic properties: (0) $\text{Ann}(R) = \text{Ann}(R)$.

(1) $\text{Ann}(N) \triangleleft R$.

(2) If $N \not\subseteq \text{Tor}(M)$ (if N is "not a torsion submodule") then $\text{Ann}(N) = 0$.

(3) If $N \subseteq L$ then $\text{Ann}(L) \subseteq \text{Ann}(N)$.

(4) If R is a PID, $N \subseteq L$, $\text{Ann}(N) = (a)$,
 $\text{Ann}(L) = (b)$,
then $a \mid b$.

(5) If R is a PID, and $x \in M$, $\text{Ann}(x) \mid \text{Ann}(M)$.

Example. Consider the \mathbb{Z} -module $M = \mathbb{Z} \times \mathbb{Z}/6$.

Then: $\text{Tor}(M) \cong \mathbb{Z}/6$.

$$\text{Ann}(0 \times \mathbb{Z}/6) = 6\mathbb{Z} \subseteq \mathbb{Z}.$$

$$\text{Ann}(0 \times 2\mathbb{Z}/6) = 3\mathbb{Z} \subseteq \mathbb{Z}.$$

$$\text{Ann}(0 \times 3\mathbb{Z}/6) = 2\mathbb{Z} \subseteq \mathbb{Z}.$$

Def. If R is an integral domain, the rank of an R -module M is the maximum # of R -linearly independent elements of M .

By proposition,

$$\text{rk}(\text{any submodule of } M) \leq \text{rk}(M).$$

46.3. (= 47.1)

Coroll! A torsion-free R -module need not be free.

(exercise 12.1.5.)

Example. $R = \mathbb{Z}[x]$, $M = (2, x)$ ideal of R
hence an R -module.

Torsion free because R is.

This has rank 1.

Theorem. Let R be a PID, M a free R -module of rank n , $N \subseteq M$ submodule. Then:

(1) N is free of rank m , with $m \leq n$.

(2) There is a basis y_1, \dots, y_n of M s.t.

$a_1 y_1, \dots, a_m y_m$ is a basis of N for some a_1, \dots, a_m satisfying $a_1 \mid a_2 \mid \dots \mid a_m$.

Example. $R = \mathbb{Z}$, ~~$N \subseteq M$ are $(\mathbb{Z}\mathbb{Z})^3 \subseteq \mathbb{Z}^3$~~ .

let $M = \mathbb{Z}^2$,

$N \subseteq M = \langle (6, 8), (10, 4) \rangle$.

Pop quiz: What is N ? Not obvious by looking.

$N \subseteq (\mathbb{Z}\mathbb{Z})^2$. Is it equal _____?

Anyway, can write bases for M, N simultaneously.

Proof. Assume $N \neq \{0\}$.

Let $\Sigma = \{ (a_\varphi) : \varphi \in \text{Hom}_R(M, R) \}$.

What does that mean? If φ is an R -mod hom $M \rightarrow R$,

$\varphi(N)$ is an R -submodule of R ,

hence an ideal,

hence a principal ideal (a_φ) .

46.4.

Then Σ is nonempty, containing (0) .

It contains a maximal elt. because R is Noetherian

~~Consider~~ consider

$v: M \rightarrow R$ where $v(N) = (a_v)$ maximal

Write $a_1 = a_v$ and let $y \in N \rightarrow a_1$.

Claim. $a_1 \neq 0$. Use freeness, maximality.

Here is an elt. of $\text{Hom}_R(M, R)$ whose image is not just zero. Have projection homomorphisms

$$\pi_i: \underbrace{r_1 m_1 + r_2 m_2 + \dots + r_n m_n}_{\text{Here } m_1, \dots, m_n \text{ is any basis}} \rightarrow r_i$$

Since $N \neq 0$, some element has to have some nonzero coordinate.

Claim. $a_1 \mid \varphi(y)$ for all $\varphi \in \text{Hom}_R(M, R)$.

Let $(d) = (a_1, \varphi(y))$ so that $d = r_1 a_1 + r_2 \varphi(y)$
for $r_1, r_2 \in R$.

Get a homomorphism $M \rightarrow R$

$$\psi := r_1 v + r_2 \varphi.$$

$$\begin{aligned} \text{Then } \psi(y) &= (r_1 v + r_2 \varphi)(y) = r_1 v(y) + r_2 \varphi(y) \\ &= r_1 a_1 + r_2 \varphi(y) = d. \end{aligned}$$

So $d \in \psi(N)$ and $(d) \subseteq \psi(N)$.

But $(a_1) \subseteq (d)$, and (a_1) was maximal

so $(a_1) = (d) = \psi(N)$ and since $d \mid \varphi(y)$,
 $a_1 \mid \varphi(y)$.

46.5 .

In particular, $a_i \mid \pi_i(y)$ for all i .

Writing $\pi_i(y) = a_i b_i$ for some $b_i \in R$ for each i ,

$$y_1 := \sum_{i=1}^n b_i m_i$$

Basis for M

with

$$\begin{aligned} a_1 y_1 &= \sum a_i b_i m_i = \sum \pi_i(y) m_i \\ &= y_1 \end{aligned}$$

$$a_1 = v(y) = v(a_1 y_1) = a_1 v(y_1) \quad \text{and } a_1 \neq 0 \text{ in a domain,}$$
$$\underline{v(y_1) = 1}.$$

Now:

Claim. We can choose y_1 as an element in a basis for M and $a_1 y_1$ as a basis element for N . Namely:

$$(a) \quad M = R y_1 \oplus \text{Ker } v$$

$$(b) \quad N = R a_1 y_1 \oplus (N \cap \text{Ker } v).$$

$$(a): \text{ If } M \ni x = \underbrace{v(x) y_1}_{\in R y_1} + \underbrace{(x - v(x) y_1)}_{\substack{v(x - v(x) y_1) \\ = v(x) - v(x) v(y_1) = 0 \\ \text{So } \in \text{Ker}(v)}}),$$

Why is the sum direct?

$$\text{If } r y_1 \in \text{Ker}(v), \quad 0 = v(r y_1) = r v(y_1) = r.$$

4b.6.

(b): Since a_1 generates $v(N)$, $a_1 \mid v(x')$ for all $x' \in N$.

Writing $v(x') = ba_1$,

$$x' = v(x') y_1 + (x' - v(x') y_1)$$

$$= \underbrace{ba_1 y_1}_{\in Ra_1 y_1} + \underbrace{(x' - ba_1 y_1)}_{\text{in } N: x' \text{ is by choice}}$$

$$a_1 y_1 = y \in N.$$

in $\text{Ker}(v)$ because

$$v(x') - v(ba_1 y_1)$$

$$= ba_1 - ba_1 \underbrace{v(y_1)}_{=1}.$$

Direct as a special case of (a).

Part (1) of theorem. (N is free of rank $\leq \text{rank}(M)$)
Induct on $m := \text{rank}(N)$.

If $m=0$, N is a torsion module, hence 0 if also free.

If $m>0$, $N \cap \text{Ker}(v)$ has rank $m-1$ by direct sum decomp.

By induction, it's free and we just added one basis elt.

Part (2): Induct on $n := \text{rank}(M)$.

Question: why the hell do DF write $n = \text{rank}(M)$, $m = \text{rank}(N)$?

By (1), $\text{Ker}(v)$ is free; of rank $n-1$ because sum is direct.

By induction, $\text{Ker}(v)$ has a basis $y_2 \dots y_n$

s.t. $a_2 y_2, \dots, a_m y_m$ is a basis for $N \cap \text{Ker}(v)$

~~with~~ with $a_2 \dots a_m \in R$ satisfying $a_2 \mid a_3 \mid \dots \mid a_m$.

46.7. $(= 47.5) = 48.1.$

By direct sum magic, φ_1 and $a_1 \varphi_1$ complete these to bases. Need $a_1 | a_2$.

Define $\varphi : M \rightarrow R$

$$\varphi_1 \rightarrow 1$$

$$\varphi_2 \rightarrow 1$$

other $\varphi_i \rightarrow 0$.

Then $a_1 = \varphi(a_1 \varphi_1) \in \varphi(N)$, so $(a_1) \subseteq \varphi(N)$.

But a_1 was chosen maximal, so $(a_1) = \varphi(N)$.

Since $a_2 = \varphi(a_2) \in \varphi(N)$, $a_2 \in (a_1)$ and $a_1 | a_2$. QED.

48. Restate theorem and start here.

Def. An R -module M is cyclic if $M \cong R/I$ for some $I \subseteq R$.

Cyclic submodules of R itself: principal ideals)

Then consider $\pi : R \rightarrow M$

$$r \rightarrow rm$$

Surjective, so $M \cong R/\text{Ker}(\pi)$ by first iso thm.

If R is a PID, $M \cong R/(a)$ with $(a) = \text{Ann}(M)$.

Thm. (Fund. Theorem for modules / PID's. Existence)

Let M be a f.g. R -module with R a PID. Then:

(1) M is isomorphic to the direct sum of finitely many cyclic modules:

$$M \cong R^r \oplus R/(a_1) \oplus \dots \oplus R/(a_m)$$

for some integer $r \geq 0$

nonzero $a_1, \dots, a_m \in R$ not units, $a_1 | a_2 | \dots | a_m$.

47.6. = 48.2

(2) M is torsion free iff free.

(3) In the decomp. above,

$$\text{Tor}(M) \cong R/(a_1) \oplus \dots \oplus R/(a_n).$$

Proof. Start w/ a surjection

$$\pi: R^n \longrightarrow M$$

$$b_i \longrightarrow x_i$$

where: $\{x_1, \dots, x_n\}$ is a minimal set of generators of M
 $\{b_1, \dots, b_n\}$ is a basis for R^n

Surjective, with $R^n / \ker \pi \cong M$.

Use previous result. Have a basis y_1, \dots, y_n of R^n

with: $a_1 y_1, \dots, a_m y_m$ a basis for $\ker \pi$, $a_1 \mid a_2 \mid \dots \mid a_n$.

So,

$$\begin{aligned} M \cong R^n / \ker \pi &= (Ry_1 \oplus \dots \oplus Ry_n) / (Ra_1 y_1 \oplus \dots \oplus Ra_m y_m) \\ &\cong R/(a_1) \oplus R/(a_2) \oplus \dots \oplus R/(a_n) \oplus R^{n-m}. \end{aligned}$$

To see this, map

$$\begin{aligned} Ry_1 \oplus \dots \oplus Ry_n &\longrightarrow \text{RHS} \\ (a_1 y_1, \dots, a_n y_n) &\longrightarrow (a_1 \pmod{a_1}, \dots, \\ &\quad a_m \pmod{a_m}, \\ &\quad a_{m+1}, \dots, a_n). \end{aligned}$$

Gives (1).

(2) is true because all the $R/(a)$ are torsion.

$$47.7 \neq 48.3.$$

Notes:

(1) This is already interesting for $R = \mathbb{Z}$.

(2) We will also prove uniqueness: r is uniquely determined, as are the ideals (a_i) .

(3) r is called the free rank or Betti number of M ;

$a_1, \dots, a_m \in R$ are the invariant factors.

(4) You can use CRT to decompose the $R/(a)$ further, into

$$R/(p_1^{a_1}) \oplus \dots \oplus R/(p_k^{a_k}) \text{ for prime elts. } p_i \in R \text{ pos integers } a_i.$$

These are the elementary divisors of M .

Both of these decompositions are interesting!

A similar argument gives:

Theorem. (Primary Decomposition) Let —

R PID, M nonzero torsion R -module

Write $a = \text{Ann}(M)$. ($\text{Ann}(M)$ is an ideal, hence principal.)

If $a = up_1^{\alpha_1} \dots p_n^{\alpha_n}$ unique factorization,

$$N_i = \{x \in M : p_i^{\alpha_i} x = 0\}$$

Then N_i is a submodule of M w/ annihilator $p_i^{\alpha_i}$
the submodule of M of all elts. annihilated
by a power of p_i , and

$$M = N_1 \oplus \dots \oplus N_n.$$

Note. Above theorems tell us $a \neq 0$.
Otherwise we don't get started!

4S.4. A bit more structure theory.

Lemma: if R is a PID, $p \in R$ prime, $F = R/(p)$ a field.

Then:

(1) If $M = R^r$, $M/pM \cong F^r$.

(2) If $M = R/(a)$ with $a \neq 0 \in R$,

$$M/pM \cong \begin{cases} F & \text{if } p|a \\ 0 & \text{if } p \nmid a. \end{cases}$$

(3) If $M = R/(a_1) \oplus R/(a_2) \oplus \dots \oplus R/(a_r)$
each a_i divisible by p .

Then $M/pM \cong F^k$.

Proof. (2) \rightarrow (3) essentially immediate.

(1) $R^r \rightarrow (R/(p))^r$ natural surjection.
Compute the kernel.

(2) What is $pM = p(R/(a))$?

This is $\frac{(p) + (a)}{(a)}$ in $R/(a)$.

$$(p) + (a) = \begin{cases} (p) & \text{if } p|a \\ R & \text{otherwise. (PID, hence UFD.)} \end{cases}$$

Example. (basic algebraic number theory)

Let $R = \mathbb{Z}[i] = \{a + bi : a, b \in \mathbb{Z} \text{ } (i^2 = -1)\}$.

Then R and any quotient is a FG \mathbb{Z} -module.

If $p \in \mathbb{Z}$ is prime, what is $\mathbb{Z}[i]/p\mathbb{Z}[i]$?

It's a torsion module.

Use the elem. divisor/primary decomp thm.

As a \mathbb{Z} -module, isomorphic to either

$$\mathbb{Z}/p \times \mathbb{Z}/p \quad \text{or} \quad \mathbb{Z}/p^2.$$

Never mind, this is not interesting.

Only the ring structure makes it interesting.

48.5. Theorem (Uniqueness)

Two f.g. R -modules are isomorphic if they have:

- (1) the same free rank and list of invariant factors, or
- (2) " " " list of elementary divisors.

Proof. Boring, see DF.

Matrix Canonical Forms.

The setup.

$F = \text{a field}$ (so $F[x]$ is a PID)

$V = \text{fd vector space} / F.$

$T \in \text{End}(V).$

Then V is an $F[x]$ -module where x acts by T .

V is f.g. as an F -module, hence as an $F[x]$ -module.

Will decompose V as an $F[x]$ -module

invariant factor decomp. \Rightarrow get rational canonical form

elementary divisor decomposition \Rightarrow Jordan canonical form.

Point: Choose a basis for V wr.t. matrix rep'n of T is nice.

48.6. Recall the basic setup.

$\lambda \in F$ is an eigenvalue of T if $Tv = \lambda v$ for some $v \in V$ (an eigenvector)

The associated eigenspace is $\{v \in V : Tv = \lambda v\}$
a subspace of V .

Recall, TFAE:

- (1) λ is an eigenvalue of T
- (2) $\lambda I - T$ is a singular (not invertible) elt. of $\text{End}(V)$
- (3) The characteristic polynomial $\text{char}_T(x) = \det(xI - T)$ satisfies $\text{char}_T(\lambda) = 0$.

Definition. The unique monic polynomial generating $\text{Ann}(V)$ in $F[x]$ is called the minimal polynomial of T , $\text{min}_T(x)$.

Recall: $\text{Ann}(V) = \{f \in F[x] : f(T) = 0\}$
is a principal ideal, has a unique generator up to units, demand monic to make it unique.

~~Do not use immediate results:~~

Recall the Cayley - Hamilton theorem:

$$\text{min}_T(x) \mid \text{char}_T(x).$$

Equivalently, $\text{char}_T(T) = 0$.

48.7.

By our structure theorem, as $F[x]$ -modules

$$V \cong F[x]/(a_1(x)) \oplus F[x]/(a_2(x)) \oplus \dots \oplus F[x]/(a_m(x))$$

where the invariant factors $a_i(x)$ satisfy

$$a_1(x) \mid a_2(x) \mid \dots \mid a_m(x).$$

If we insist they be monic, they are unique.

Now, $\text{Ann}(V) = (a_m(x))$, this is the minimal polynomial.

We always have a nice basis for $F[x]/(a(x))$ as an F -vector space: if $k = \deg(a(x))$, then $1, x, x^2, \dots, x^{k-1}$.
The linear transformation * multiply by x * has ~~basic~~ matrix

$$\begin{bmatrix} 0 & 0 & \dots & 0 & -b_0 \\ 1 & & & & -b_1 \\ & 0 & & & \vdots \\ 0 & & & 1 & -b_{k-1} \end{bmatrix}$$

$$\text{where } a(x) = x^k + b_{k-1}x^{k-1} + b_{k-2}x^{k-2} + \dots + b_0.$$

(Store it for awhile.)

This is called the companion matrix of $a(x)$.

48.8 = 49.1

with $V \cong F[x]/(a_1(x)) \oplus \dots \oplus F[x]/(a_m(x))$

choose such bases for each of the factors, get a block diagonal matrix

$$\begin{pmatrix} C_{a_1}(x) & & \\ & C_{a_2}(x) & \\ & & \ddots \\ & & & C_{a_m}(x) \end{pmatrix}$$

where each $C_{a_i}(x)$ is a companion matrix of the form above. This is the rational canonical form of T . It is unique because the a_i are.

So, for example:

Theorem. If $S, T \in \text{End}(V)$ then TFAE:

- (1) S and T are conjugate
- (2) S and T have the same rat'l canonical form
- (3) The $F[x]$ -modules obtained from V via S and T are isomorphic.

Moreover, in matrix language, any $n \times n$ matrix is conjugate to a unique matrix in rational canonical form.

(Over any field.)

Also, doesn't change when you pass to extension fields.

49.2.

Lemma. The determinant of a block diagonal matrix

$$\begin{pmatrix} D_1 & & \\ & \ddots & \\ & & D_n \end{pmatrix} \text{ is } \det(D_1) \cdots \det(D_n).$$

(Prove by "pure thought.")

So the characteristic polynomial of the PCF is the product of the companion matrices.

Proposition. Let $a(x) = x^k + b_{k-1}x^{k-1} + \cdots + b_0$

w/ companion matrix

$$\begin{bmatrix} 0 & & -b_0 \\ 1 & & -b_1 \\ & \ddots & \\ & & 0 \\ & & 1 & -b_{k-1} \end{bmatrix}$$

$$\det \begin{bmatrix} x & & -b_0 \\ -1 & & -b_1 \\ & \ddots & \\ & & x \\ & & -1 & x+b_{k-1} \end{bmatrix}$$

Then its charpoly is just $a(x)$.

Proof 1. If you assume Cayley-Hamilton ($\min_T(x) \mid \text{char}_T(x)$),

* $\min_T(x) = a(x)$ by construction

* $\text{char}_T(x)$ is of the same degree. Done.

Proof 2. If you want to prove CH this way, do an

elementary computation.

For example: Add x times last row to next-to-last
 x times next-to-last to previous.
 etc.

$$\text{Get } \det \begin{bmatrix} 0 & & f \\ -1 & & x \\ & \ddots & \\ & & 0 \\ & & -1 & x \end{bmatrix}$$

with

$$f = b_0 + x(b_1 + x(b_2 + \cdots$$

$$+ x(x + b_{k-1}) \cdots)$$

$$= a(x).$$

49.3.

Corollary (of Proof 2)

For a companion matrix, $\min_T(x) = \text{char}_T(x)$.

Now, in rat'l canonical form,

* $\min_T(x)$ = the last (largest) invariant factor
 $\text{char}_T(x)$ = product of the invariant factors
 $a_1(x) \cdots a_m(x)$.

Cor. (Cayley - Hamilton Theorem).

1. $\min_T(x) \mid \text{char}_T(x)$.

2. $\text{char}_T(T) = 0$.

Computations. (ugh, see DF).

Example. Determine, up to conjugacy, all $A \in GL_3(\mathbb{Q})$ with $A^6 = I$.

Solution. We will have

$$\min_A(x) \mid x^6 - 1 = (x-1)(x+1)(x^2-x+1)(x^2+x+1).$$

$$\text{So } \min_A(x) = \begin{cases} x-1 \\ x+1 \\ x^2-x+1 \\ x^2+x+1 \\ (x-1)(x+1) \\ (x-1)(x^2-x+1) \\ (x+1)(x^2-x+1) \\ (x-1)(x^2+x+1) \\ (x+1)(x^2+x+1) \end{cases}$$

The irreducible quadratics cannot occur!

Need, e.g. $(x^2-x+1) \cdot \{\text{some divisor of } x^2-x+1\}$
= cubic. NOPE

$$49.4 = 50.1$$

$$\min_A (x) = x - 1 : \quad A - I = 0. \quad \text{So } A = I.$$

$$\min_A (x) = x + 1 : \quad A + I = 0, \quad A = -I.$$

$\min_A (x) = \text{cubic}$. This is easy.

e.g. if $\min_A (x) = x^3 - 1$, then A has RCF

$$\begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}.$$

$$\min_A (x) = x^2 - 1.$$

Then the smaller inv. factor can be $x-1$ or $x+1$:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, \quad \begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}.$$

Exercise.

(1) Repeat for $GL_3(\mathbb{C})$ (where everything factors)

(2) Determine, up to conjugacy, all the homomorphisms ("representations")

$$\text{Sym}(3) \longrightarrow GL_3(\mathbb{Q})$$

$$\text{Sym}(3) \longrightarrow GL_3(\mathbb{C}).$$

o/ Jordan canonical form.

We factored the $F[x]$ -module V as

$$V \cong F[x]/(a_1(x)) \oplus \dots \oplus F[x]/(a_m(x))$$

with invariant factors $a_1 \mid \dots \mid a_m$.

$$49.5 = 50.2$$

Consider the other factorization

$$V \cong F[x] / (p_1(x)^{a_1}) \oplus \cdots \oplus F[x] / (p_m(x)^{a_m})$$

into irreducibles, and let's assume F is algebraically closed so the p_i are all linear.

(In fact, enough if F contains the eigenvalues of T)

Choose a basis for each subspace $F[x] / p(x)^a$,
write down the matrix WRT that basis.

Lump these together to get a basis for V and a block diagonal matrix for T in that basis.

We have $p(x) = x - \lambda$ for some $\lambda \in \mathbb{C}$

and indeed λ will range over the eigenvalues of T .

Why? The minimum polynomial on the i th piece V_i is $p_i(x)$ to some power. (Think about rat'l CF)

All the invariant factors divide it.

~~the~~ Char poly is product of such factors.

For $F[x] / (x - \lambda)^a$, could choose $1, x, x^2, \dots, x^{a-1}$
as a basis.

But better: Choose $1, x - \lambda, (x - \lambda)^2, \dots, (x - \lambda)^{a-1}$.

$$\underline{49.6 = 50.3}$$

How does multiplication by x act?

$$1 \longrightarrow x = (x - \lambda) + \lambda \cdot 1$$

$$x - \lambda \longrightarrow x^2 - \lambda x = (x - \lambda)^2 + \lambda \cdot (x - \lambda)$$

$$\vdots$$

$$(x - \lambda)^{q-1} \longrightarrow \underbrace{(x - \lambda)^q}_{\text{This is 0.}} + \lambda (x - \lambda)^{q-1}$$

This is 0.

So, w.r.t. this basis, the matrix of T is

$$\begin{bmatrix} \lambda & & & & \\ 1 & \lambda & & & \\ & 1 & \ddots & & \\ & & 0 & \ddots & \\ & & & 1 & \lambda \end{bmatrix}$$

It is customary to write the basis backwards to get

$$\begin{bmatrix} \lambda & & & & \\ & 1 & & & \\ & \lambda & 1 & & \\ & & \ddots & \ddots & \\ & & & 1 & \lambda \end{bmatrix}$$

We see again, $\text{char}_{T(x)} = (x - \lambda)^q$ so the one eigenvalue is λ .

49.7 \approx 50.4

This matrix is a Jordan block of size k with eigenvalue λ .

Theorem. (1) Let $T \in \text{End}(V)$, over a field containing the eigenvalues of T . Then, there is a ~~unique~~ basis wrt which T ~~can be~~ has a matrix in Jordan canonical form

$$\begin{bmatrix} J_1 & & \\ & \ddots & \\ & & J_m \end{bmatrix}$$

J_i : Jordan blocks of the shape we saw.

(2) The Jordan form is unique up to rearrangement of the J_i .

(Follows from uniqueness of elem divisor decomposition).

The subspace corresponding to each J_i is a generalized eigenspace :

Eigenspace for λ is $\{v \in V : (T - \lambda)v = 0\}$.

Generalized eigenspace is $\{v \in V : (T - \lambda)^k v = 0 \text{ for some } k\}$.

Note however that the J_i 's or their eigenvalues are not necessarily distinct.

So. 5.

Cor. If a matrix A is diagonalizable (conjugate to a diagonal matrix D), then D is the Jordan form.

(2) Two diagonal matrices are similar if and only if their diagonal entries are the same up to a permutation.

In other words: A matrix is diagonalizable iff it has a basis of eigenvectors; up to conjugacy, such matrices are determined by their eigenvalues (\sim multiplicity).

Cor. Given a LT T over a field containing all the eigenvalues. Then T is diagonalizable iff the minimal polynomial has no repeated roots.

Pf. If diagonalizable, then $\min_T(x) = \prod_{\lambda \text{ distinct}} (x - \lambda)$.

[Think about this directly.] So \rightarrow is true.

\leftarrow : Jordan form it.

$\min_T(x)$ is the LCM of min polys of Jordan blocks.

~~The~~ $\min_T(x)$ if T has matrix $\begin{bmatrix} \lambda & & \\ & \ddots & \\ & & \lambda \end{bmatrix}$.

Visibly, $\min_T(x) = (x - \lambda)^k$ (k = size of matrix).

No repeated roots means all the Jordan blocks are 1×1 .
So no room for 1's over the diagonal.

So. 6.

Example. Describe all $A \in GL_3(\mathbb{C})$ with $A^6 = I$.

Could use RCF. This time, $x^6 - 1 = \prod_{i=0}^5 (x - \zeta_6^i)$

and there are lots of possibilities.

Use Jordan form instead.

Get : $\begin{bmatrix} * & 0 & 0 \\ 0 & * & 0 \\ 0 & 0 & * \end{bmatrix}$ where the $*$ are any 6th roots of unity
(note: reorderings are conjugate)

$\begin{bmatrix} \mu & 1 & 0 \\ 0 & \mu & 0 \\ 0 & 0 & \lambda \end{bmatrix}$ where μ, λ are 6th roots of unity (not nec. distinct)

$\begin{bmatrix} \mu & 1 & 0 \\ 0 & \mu & 1 \\ 0 & 0 & \mu \end{bmatrix}$

See DF for a variety of examples.

So. 7.

Smith normal form. (for exercises).

Let $0 \neq A \in M_{m \times n}(R)$ for a PID R . Then, there are invertible $m \times m$ and $n \times n$ matrices S, T (w/ coeffs in R) s.t.

$$S A T = \begin{bmatrix} \alpha_1 & & & & \\ & \alpha_2 & & & \\ & & \ddots & & \\ & & & \alpha_r & \\ & 0 & & & 0 \\ & & & & & \ddots & \\ & & & & 0 & & 0 \end{bmatrix}$$

with $\alpha_i \mid \alpha_{i+1}$ for all i .