

Ten known Integrals

By collecting the equations into certain combinations, we can integrate some of the new equations and solve relative 2-body motion.

Linear Momentum

|| If \vec{p} is conserved, what happens?

If $n = 2$, what is $\ddot{\vec{p}}$ in terms of $\ddot{\vec{r}}_1 + \ddot{\vec{r}}_2$?

$$\dot{\vec{p}} =$$

Thus

$$\dot{\vec{p}} =$$

$$\vec{p} =$$

$$\sum_{i=1}^n m_i \vec{r}_i =$$

Center of mass (cm)

$$\bar{\mathbf{r}}_{\text{cm}} =$$

Differentiate (note m_i is constant)

$$M \bar{\mathbf{v}}_{\text{cm}} =$$

thus the CM of the system moves

Is the CM inertially fixed?

We need an inertially fixed coordinate system to find $\bar{\mathbf{r}}_{12}$ in the 2-body system.

Define a new frame

$$\vec{r}_{\text{CM}} =$$

Angular Momentum

$$\vec{H} = \sum_{i=1}^n (\vec{r}_i \times m_i \dot{\vec{r}}_i)$$

If \bar{H} is conserved,

First, we will prove it.

For $n = 2$,

$$\frac{d}{dt}(\bar{H}) = \frac{d}{dt}(m_1 \bar{\mathbf{r}}_1 \times \dot{\bar{\mathbf{r}}}_1) + \frac{d}{dt}(m_2 \bar{\mathbf{r}}_2 \times \dot{\bar{\mathbf{r}}}_2)$$

Thus

$$\bar{H} = \quad ,$$

For 2-body motion, find \bar{H}
in terms of CM

$$\begin{aligned} H &= m_1 \bar{\mathbf{r}}_1 \times \dot{\bar{\mathbf{r}}}_1 + m_2 \bar{\mathbf{r}}_2 \times \dot{\bar{\mathbf{r}}}_2 \\ &= m_1 \left(-\frac{m_2}{m_1+m_2} \bar{\mathbf{r}} \times -\frac{m_2}{m_1+m_2} \dot{\bar{\mathbf{r}}} \right) \\ &\quad + m_2 \left(\frac{m_1}{m_1+m_2} \bar{\mathbf{r}} \times \frac{m_1}{m_1+m_2} \dot{\bar{\mathbf{r}}} \right) \end{aligned}$$

Let

Since $\bar{h} \perp \bar{r}$ and $\bar{h} \perp \dot{\bar{r}}$ we
have an

Total Energy

$$T - U =$$

or

$$\frac{dT}{dt} - \frac{dU}{dt} =$$

Write $T = \frac{1}{2} \sum_{i=1}^n m_i \dot{\vec{r}}_i \cdot \dot{\vec{r}}_i$ in terms of \vec{r} .

$$T = \frac{1}{2} m_1 \dot{\vec{r}}_1 \cdot \dot{\vec{r}}_1 + \frac{1}{2} m_2 \dot{\vec{r}}_2 \cdot \dot{\vec{r}}_2$$

$$U = \frac{1}{2} G \left(\frac{m_1 m_2}{r} + \frac{m_2 m_1}{r} \right) = G \frac{m_1 m_2}{r}$$

$$\vec{T} - U =$$

Multiply by $\frac{m_1 + m_2}{m_1 m_2}$

Then

Now we can solve for r from $\ddot{\vec{r}} = -\frac{\mu}{r^3} \vec{r}$
 change dt to $d\theta$ (by h), we
 can solve for $r(\theta)$ via variable
 change to $1/r$.

After some mathematical manipulations
 we get the conic equation.

$$r = \frac{p}{1 + e \cos(\theta - \omega)}$$

where

If we derive the conic equation using just vectors, we get the eccentricity vector

$$\bar{e} = \frac{\dot{\bar{r}} \times \bar{h}}{\mu} - \frac{\bar{r}}{r}$$