

THE STRUCTURE OF CONVEXITY

INTERNAL THEORY

DEFINITION

(X, \mathcal{C}) — *convex space*:

- (1) $\emptyset, X \in \mathcal{C}$
- (2) $A \subset \mathcal{C} \Rightarrow \cap A \in \mathcal{C}$
- (3) $\mathcal{N} \subset \mathcal{C} \Rightarrow \cup \mathcal{N} \in \mathcal{C}$

IDEA

POLYTOPE

DIMENSION

FREEDOM

HYPERPLANE

(Maximal net of polytopes of same dim.)

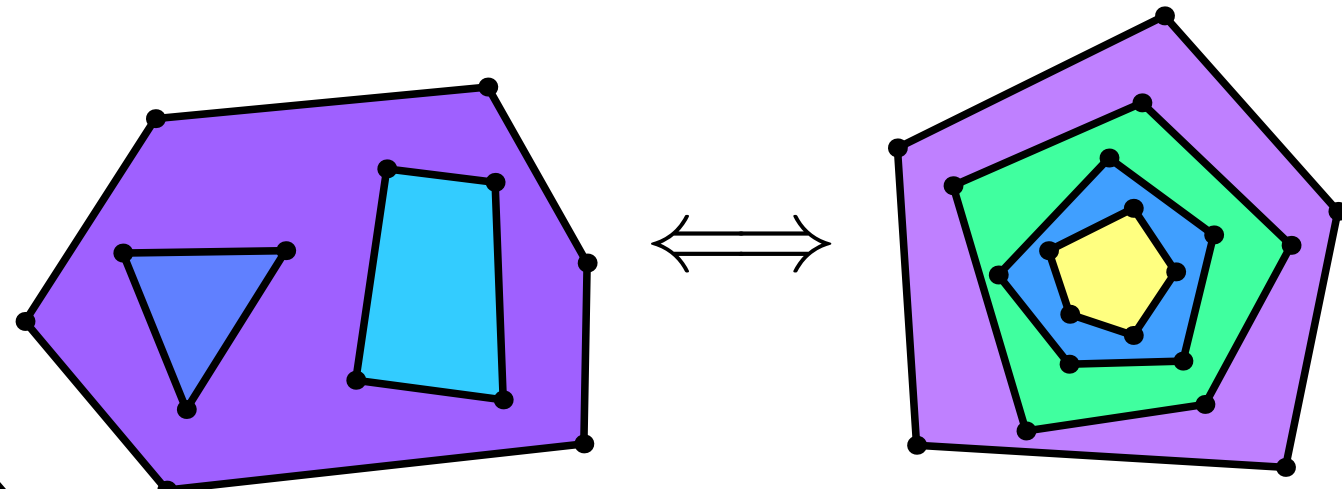
SUBSETS

$$\eta_x = \eta_y = \dim A$$

TPUL

THEOREM

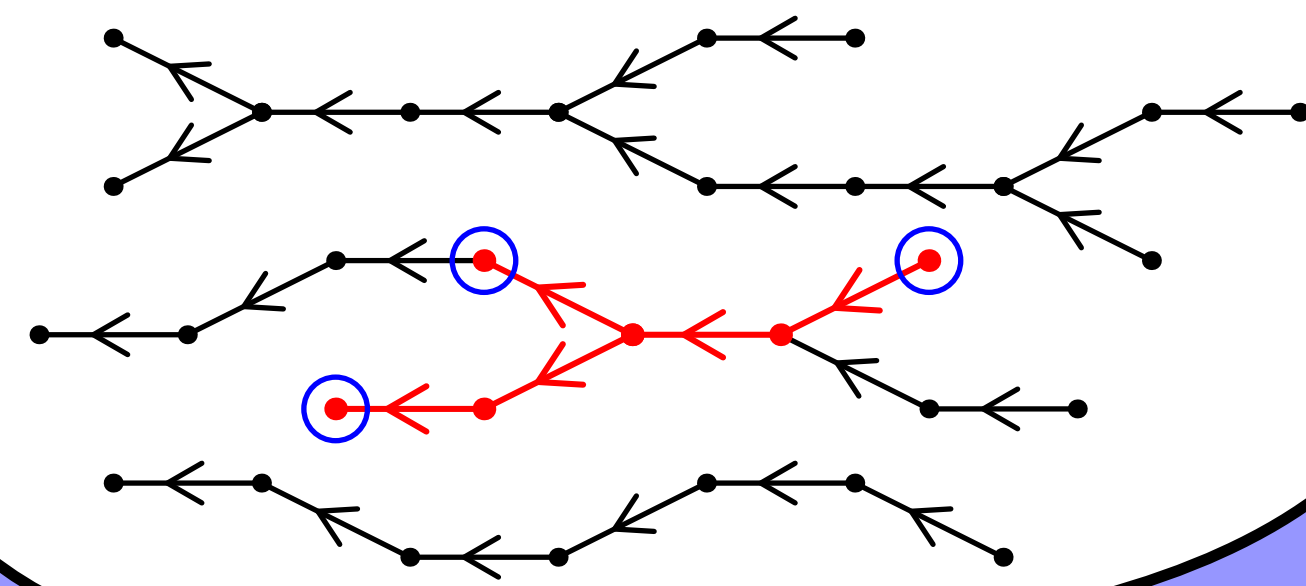
TPUL is equivalent to:



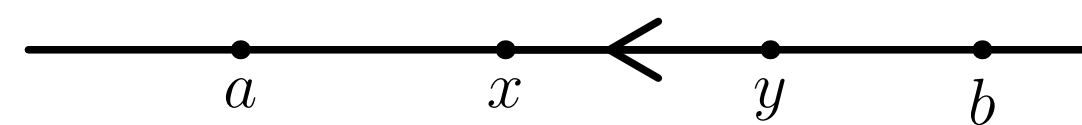
INDUCING STRUCTURE

ORDER

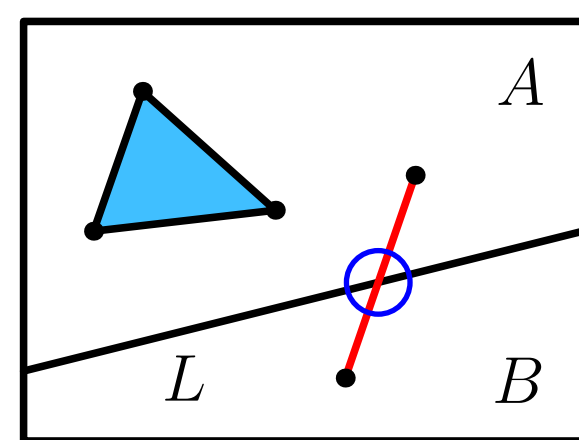
Theorem: all order convexities are free.



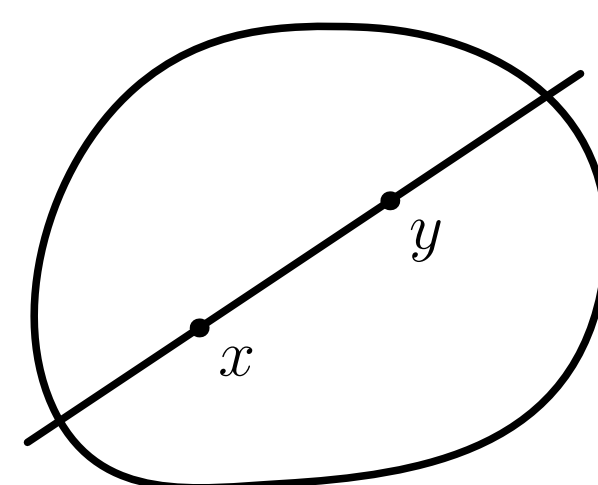
LINEARITY



n-AFFINITY



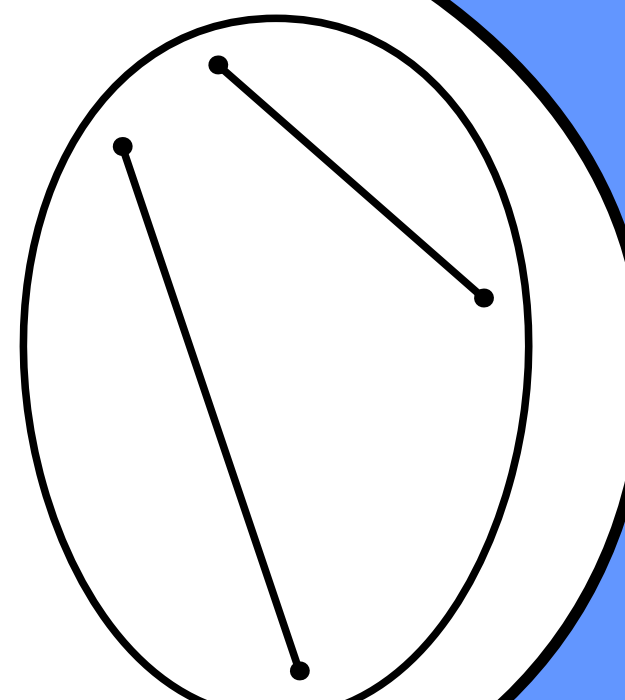
1-AFFINITY



METRIC

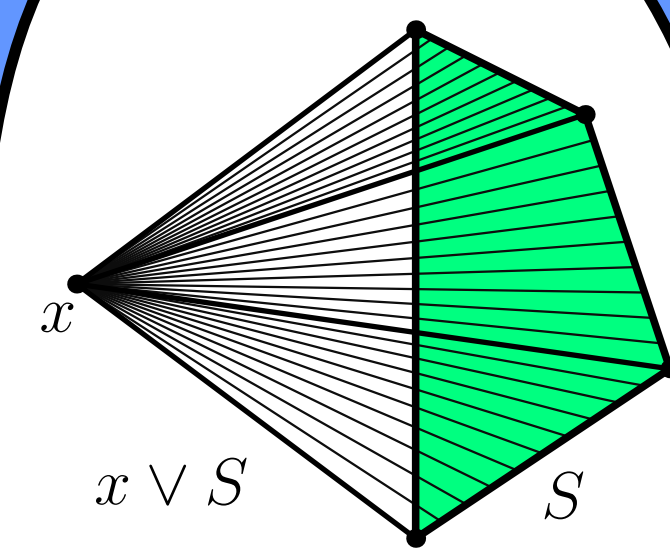
$$d(a, b) = d(a, x) + d(x, b)$$

SEGMENTIAL



FINITE

JOIN



$$x \vee \langle F \rangle = \langle x \cup F \rangle$$

THEOREM

Finite-segmental
2-Affine
TPUL

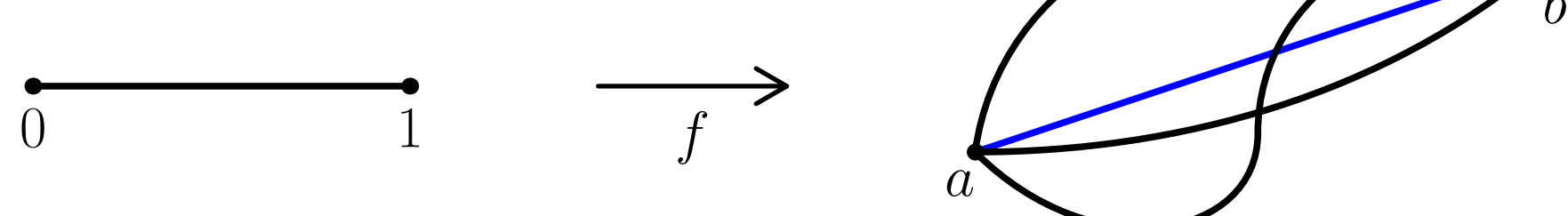
↓
Free

INDUCED STRUCTURE

REFERENCES

UNIQUELY GEODESIC SPACES

DEFINITION



LEMMA

$$d(a, b) = d(a, f(t)) + d(f(t), b)$$

LEMMA

In a UGS all metric segments are free polytopes.

