# MOMENTUM, IMPULSE, AND COLLISIONS II

Intended Learning Outcomes – after this lecture you will learn:

- 1. characteristics of elastic collisions.
- 2. center of mass and its relation to center of gravity.
- 3. the dynamics of the center of mass of a system or a body.

Textbook Reference: Ch 8.4, 8.5

#### **Elastic collision**

This is a good place to introduce the idea of *invariants* which relate a system at different instances. In this case the invariants are energy and momentum.

Conservation of energy:

$$\frac{1}{2}m_A v_{A1x}^2 + \frac{1}{2}m_B v_{B1x}^2 = \frac{1}{2}m_A v_{A2x}^2 + \frac{1}{2}m_B v_{B2x}^2$$

Conservation of momentum:

$$m_A v_{A1x} + m_B v_{B1x} = m_A v_{A2x} + m_B v_{B2x}$$

Want to solve for  $v_{A2x}$  and  $v_{B2x}$ . Trick:

$$m_A(v_{A1x}^2 - v_{A2x}^2) = m_B(v_{B2x}^2 - v_{B1x}^2)$$

$$m_A(v_{A1x} + v_{A2x})(v_{A1x} - v_{A2x}) = m_B(v_{B2x} + v_{B1x})(v_{B2x} - v_{B1x})$$

From momentum conservation we have

$$m_A(v_{A1x} - v_{A2x}) = m_B(v_{B2x} - v_{B1x})$$

$$\Rightarrow v_{A1x} + v_{A2x} = v_{B1x} + v_{B2x}$$

$$v_{B2x} - v_{A2x} = -(v_{B1x} - v_{A1x})$$

Physical meaning:

relative velocity *after* collision = – (relative velocity *before* collision)

▲ In an elastic collision we can write down three equations:

- 1. conservation of energy
- 2. conservation of momentum.
- 3. relative velocity *after* collision = (relative velocity *before* collision)

But only two of them are independent. Usually 2 and 3 are preferred because they are first order.

$$\begin{cases} m_A v_{A1x} + m_B v_{B1x} = m_A v_{A2x} + m_B v_{B2x} \\ v_{B2x} - v_{A2x} = -(v_{B1x} - v_{A1x}) \end{cases}$$

$$\Rightarrow v_{A2x} = \frac{m_A - m_B}{m_A + m_B} v_{A1x} + \frac{2m_B}{m_A + m_B} v_{B1x}, \quad v_{B2x} = \frac{m_B - m_A}{m_A + m_B} v_{B1x} + \frac{2m_A}{m_A + m_B} v_{A1x}$$

 $\triangle$  Symmetric in A and B.

### Special case: Elastic collision with one body initially at rest

B initially at rest

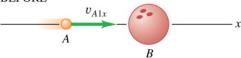
$$\Rightarrow v_{A2x} = \frac{m_A - m_B}{m_A + m_B} v_{A1x}, \quad v_{B2x} = \frac{2m_A}{m_A + m_B} v_{A1x}$$

⚠ Symmetry in A and B is broken

 $\triangle$   $v_{B2x}$  same direction (same sign) as  $v_{A1x}$ , but direction of  $v_{A2x}$  depends on  $m_A - m_B$ 

(a) Ping-Pong ball strikes bowling ball.

**BEFORE** 



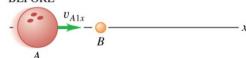
**AFTER** 

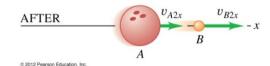


 $m_B > m_A$ , A reflected back

(b) Bowling ball strikes Ping-Pong ball.

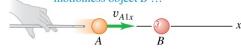
**BEFORE** 





 $m_B < m_A$ , A continue forward and  $v_{A2x} < v_{B2x}$ 

When a moving object A has a 1-D elastic collision with an equal-mass, motionless object B ...



... all of A's momentum and kinetic energy are transferred to B.

$$v_{A2x} = 0 \qquad v_{B2x} = v_{A1x}$$

$$- Q \qquad - X$$

 $m_A = m_B$ ,  $v_{A2x} = 0$ ,  $v_{B2x} = v_{A1x}$ 

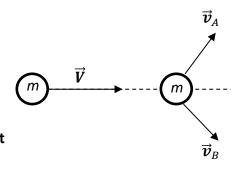
What if the collision is not 1D?

From conservation of energy and momentum:

$$\begin{aligned} \left| \vec{V} \right|^2 &= |\vec{v}_A|^2 + |\vec{v}_B|^2 \\ \vec{V} &= \vec{v}_A + \vec{v}_B \end{aligned}$$

Then

$$2\vec{v}_A\cdot\vec{v}_B=|\vec{v}_A+\vec{v}_B|^2-|\vec{v}_A|^2-|\vec{v}_B|^2=0$$
 i.e., the two velocities after collision are at right angle.



#### **Demonstrations:**

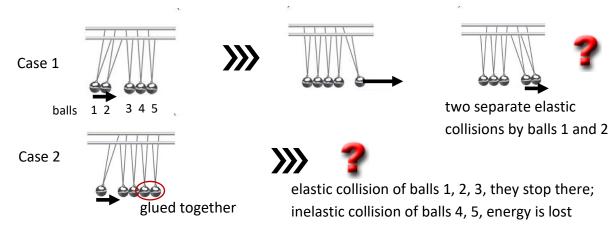
Newton's cradle



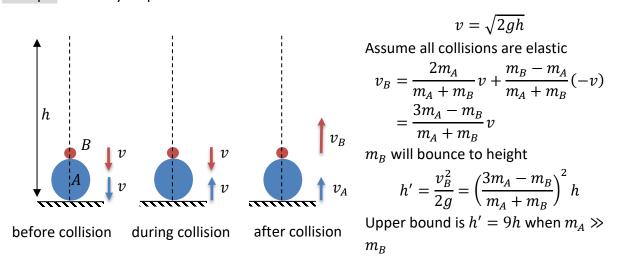
<u>Gaussian gun</u> – where comes the extra energy when there is a magnet?



#### More on Newton's cradle



#### Example - velocity amplification revisit



## Example 8.11 P. 279 Moderating fission neutrons in a nuclear reactor

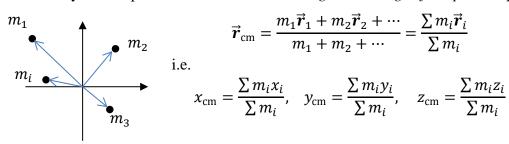
Fission of uranium produces high speed neutrons which must be slowed down before it can initiate another fission process. Suppose graphite (carbon) is used as moderator to slow down neutrons.

Before 
$$v_{\text{n1x}} = 2.6 \times 10^{7} \text{ m/s}$$
 assuming elastic collision relative velocities:  $v_{\text{C2x}} - v_{n2x} = -(0 - v_{n1x})$  conservation of momentum: 
$$m_{\text{n}} v_{\text{n1x}} = m_{\text{C}} v_{\text{C2x}} + m_{\text{n}} v_{\text{n2x}}$$
 get:  $v_{\text{n2x}} = -2.2 \times 10^{7} \text{ m/s}, v_{\text{C2x}} = 0.4 \times 10^{7} \text{ m/s}$ 

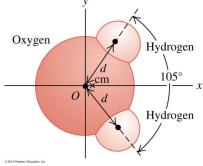
 $\triangle$  Don't worry about the direction (forward or backward) of neutron after collision. Assume all v are +ve, c.f., figure in textbook.

#### Center of Mass (CM)

The CM of a system of particles is defined as the weighted average of the particle positions



Example 8.13 P. 281 CM of a water molecule



Need to worry about mass of nuclei only (why not e<sup>-</sup>?)

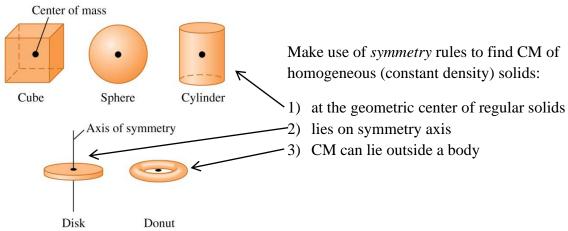
 $\triangle$  choose symmetry axis of the molecule as the x, y, and z directions

meaning under rotation about that axis, the molecule looks the same

$$x_{\rm cm} = \frac{(1.0 \text{ u})(d\cos 52.5^{\circ}) + (1.0 \text{ u})(d\cos 52.5^{\circ}) + (16.0 \text{ u})(0)}{1.0 \text{ u} + 1.0 \text{ u} + 16.0 \text{ u}} = 0.068d$$
$$= 6.5 \times 10^{-12} \text{ m}$$

$$y_{\rm cm} = \frac{(1.0 \text{ u})(d\sin 52.5^\circ) + (1.0 \text{ u})(-d\sin 52.5^\circ) + (16.0 \text{ u})(0)}{1.0 \text{ u} + 1.0 \text{ u} + 16.0 \text{ u}} = 0$$

For solids, need integration



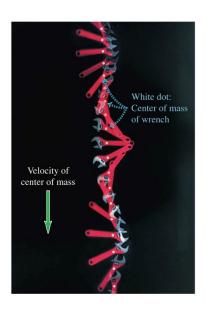
c.f. center of gravity (CG) which you have learned in high school.

 $\triangle$  If g is the same at all points on a body, its CG is identical to its CM.

▲ You know how to determine the CG of a rigid body experimentally.

From definition of  $\vec{r}_{cm}$ , (by differentiation)

$$\vec{v}_{\rm cm} = \frac{m_1 \vec{v}_1 + \cdots}{m_1 + \cdots}$$
  $\implies$   $M\vec{v}_{\rm cm} = m_1 \vec{v}_1 + \cdots = \vec{P}$  total linear momentum 
$$M\vec{a}_{\rm cm} = m_1 \vec{a}_1 + \cdots = \sum_{i} \vec{F}_{\rm ext} + \sum_{i} \vec{F}_{\rm int} = \sum_{i} \vec{F}_{\rm ext}$$
 external forces in equal and opposite pairs, add up to zero ( $\triangle$  didn't we say action and reaction and reaction do not cancel?)



## Conclusion: $M\vec{a}_{cm} = \sum \vec{F}_{ext} = d\vec{P}/dt$

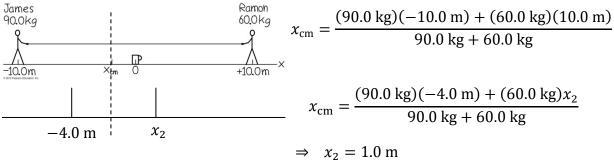
When a body or a collection of particles is acted on by external forces, the CM moves just as though all the mass were concentrated at that point and it were acted on by a net force equal to the sum of the external forces on the system.

e.g. a falling rotating wrench

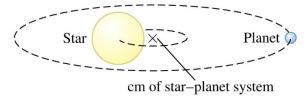
See also the MIT demo at https://www.youtube.com/watch?v=DY3LYQv22qY



Example 8.14 P. 282 An example with no external force – tug of war on ice

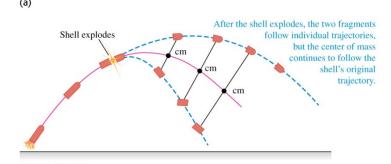


An example of a wobbling star



A wobbling star shows the presence of an accompanying planet which is too dim to be seen

An example with external force – A shell explodes into two fragments in flight.





Question: Will the CM in the above problem continue on the same parabolic trajectory even after one of the fragments hits the ground?

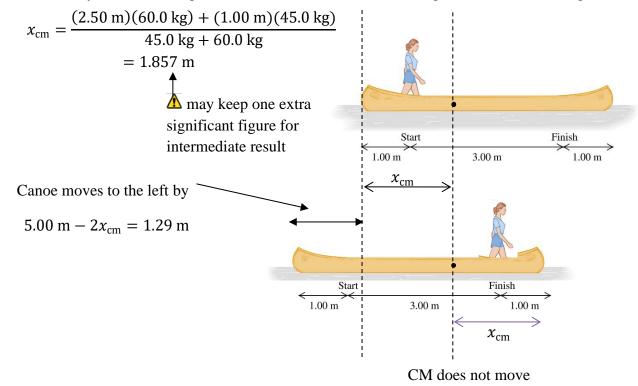
Answer: see the inverted text on P. 284 of textbook

Example Problem 8.92, P. 297 Walking on a canoe in still water

⚠ Here the invariant is not energy nor momentum, but the location of the CM

Canoe is 5.00 m long. CM of canoe is at its center

CM of the system (canoe + girl) doesn't move. Girl's mass 45.0 kg, canoe's mass 60.0 kg



#### Alternate method:

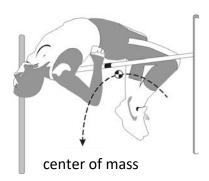
In shore frame: v and V are velocities of girl and canoe, mv + MV = 0

In canoe's frame: v' velocity of girl, v' = v - V

Invariant: time taken for the process is the same measured in shore and canoe's frame

$$t = \left| \frac{l}{v'} \right| = \left| \frac{x}{V} \right| \Rightarrow x = \left| \frac{l}{v/V - 1} \right| = \frac{l}{M/m + 1} = \frac{3.00 \text{ m}}{(60.0 \text{ kg})/(45.0 \text{ kg}) + 1} = 1.29 \text{ m}$$

#### Example The Fosbury Flop in high jump



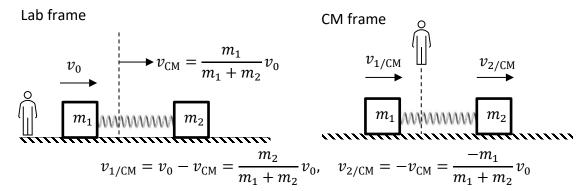
Introduced by Dick Fosbury at the 1968 Summer Olympics, CM always below the bar in order to minimize the gain in potential energy

#### Example motion in CM frame

Two masses  $m_1$  and  $m_2$  are attached to the ends of a light spring of force constant k. The masses are at rest on a frictionless floor and the spring is at its natural length  $l_0$ .  $m_1$  is given a speed  $v_0$  to the right. What is the minimum length  $l_{\min}$  of the spring in subsequent motion?

Note: no external force, CM moves with constant velocity,  $\therefore$  CM frame is an inertial frame Physical picture: In the CM frame, the masses are oscillating (compress, expand, ...). Obviously at minimum length  $l_{\min}$  the masses are instantaneously at rest (this corresponds to both masses moving with the same velocity in the lab frame). Total energy of the system at that instant is  $\frac{1}{2}k(\Delta l)^2$ .

To find the initial energy in the CM frame, transform the velocities from lab to CM frame:



Conservation of energy in CM frame:

$$\frac{1}{2} k(\Delta l)^{2} = \frac{1}{2} m_{1} v_{1/\text{CM}}^{2} + \frac{1}{2} m_{2} v_{2/\text{CM}}^{2} \quad \Rightarrow \quad \Delta l = v_{0} \sqrt{\frac{m_{1} m_{2}}{k(m_{1} + m_{2})}}$$

max compression, no KE initial total energy, no PE

Ans:  $l_{\min} = l_0 - \Delta l$ 

lambda this  $l_{
m min}$  is measured in CM frame. Is it the same as measured in the lab frame?

#### **Clicker Questions:**

Q8.11

A yellow block and a red rod are joined together. Each object is of uniform density. The center of mass of the *combined* object is at the position shown by the black "X." Which has the *greater mass*, the yellow block or the red rod?



- A. The yellow block has the greater mass.
- B. The red rod has the greater mass.
- C. They both have the same mass.
- D. Either A or B is possible.
- E. A, B, or C is possible.

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O8.13

Block *A* on the left has mass 1.00 kg. Block *B* on the right has mass 3.00 kg.



Block A is initially moving to the right at 6.00 m/s, while block B is initially at rest. The surface they move on is level and frictionless. What is the velocity of the center of mass of the two blocks *after* the blocks collide?

- A. 6.00 m/s, to the right
- B. 3.00 m/s, to the right
- C. 1.50 m/s, to the right
- D. zero
- E. Not enough information is given to decide.

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Ans: Q8.11) A, Q8.13) C