

4. Are these building blocks
good enough?

Diagrams, formally

Three definitions

- A **diagram** in a category \mathcal{C} is a functor $D: \mathcal{J} \rightarrow \mathcal{C}$ where the **shape** \mathcal{J} is a small category
 - for our purposes, \mathcal{C} is usually some category of “geometric sheaves” on a space, e.g. wedge products of the (co)tangent bundle of a manifold (so sections are differential forms and vector fields)
- Given a category \mathcal{C} and an object $S \in \mathcal{C}$, the category $\text{El}_S(\mathcal{C})$ of **generalised elements of shape** S is the coslice category $\text{El}_S(\mathcal{C}) = S/\mathcal{C}$
- A **lift** of a diagram $D: \mathcal{J} \rightarrow \mathcal{C}$ through a functor $\pi: \mathcal{E} \rightarrow \mathcal{C}$ is a functor $\bar{D}: \mathcal{J} \rightarrow \mathcal{E}$ such that $\pi \circ \bar{D} = D$
 - we generally take π to be a discrete opfibration

