

DEPARTMENT OF COMPUTER SCIENCE AND DESIGN

CD19P02 – FUNDAMENTALS OF IMAGE PROCESSING LABORATORY RECORD

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CD19P02 – FUNDAMENTALS OF IMAGE PROCESSING

	List of Experiments					
1.	Practice of important image processing commands – imread(), imwrite(), imshow(), plot() etc.					
2.	Program to perform Arithmetic and logical operations					
3.	Program to implement sets operations, local averaging using neighborhood processing.					
4.	Program to implement Convolution operation.					
5.	Program to implement Histogram Equalization.					
6.	Program to implement Mean Filter.					
7.	Program to implement Order Statistic Filters					
8.	Program to remove various types of noise in an image					
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INTRODUCTION TO MATLAB

MATLAB stands for MATrix LABoratory and the software is built up around vectors and matrices. It is a technical computing environment for high performance numeric computation and visualization. It integrates numerical analysis, matrix computation, signal processing and graphics in an easy-to-use environment, where problems and solutions are expressed just as they are written mathematically, without traditional programming. MATLAB is an interactive system whose basic data element is a matrix that does not require dimensioning. It enables us to solve many numerical problems in a fraction of the time that it would take to write a program and execute in a language such as FORTRAN, BASIC, or C. It also features a family of application specific solutions, called toolboxes. Areas in which toolboxes are available include signal processing, image processing, control systems design, dynamic systems simulation, systems identification, neural networks, wavelength communication and others. It can handle linear, nonlinear, continuous-time, discretetime, multivariable and multirate systems.

How to start MATLAB

Choose the submenu "Programs" from the "Start" menu. From the "Programs" menu, open the "MATLAB" submenu. From the "MATLAB" submenu, choose "MATLAB".

Procedure

- 1. Open Matlab.
- 2. File New Script.
- 3. Type the program in untitled window
- 4. File Save type filename.m in Matlab workspace path.
- 5. Debug Run.
- 6. Output will be displayed at Figure dialog box.

Library Functions

clc:

Clear command window

Clears the command window and homes the cursor.

clear all:

Removes all variables from the workspace.

close all:

Closes all the open figure windows.

exp:

 $Y = \exp(X)$ returns the exponential e x for each element in array X.

linespace:

y = linspace(x1,x2) returns a row vector of 100 evenly spaced points between x1 and x2.

rand:

X = rand returns a single uniformly distributed random number in the interval (0,1).

ones:

X = ones(n) returns an n-by-n matrix of ones.

zeros:

X = zeros(n) returns an n-by-n matrix of zeros.

plot:

plot(X,Y) creates a 2-D line plot of the data in Y versus the corresponding values in X.

subplot:

subplot(m,n,p) divides the current figure into an m-by-n grid and creates an axes for a subplot in the position specified by p.

stem:

stem(Y) plots the data sequence, Y, as stems that extend from a baseline along the x-axis. The data values are indicated by circles terminating each stem.

title:

title(str) adds the title consisting of a string, str, at the top and in the center of the current axes.

xlabel:

xlabel(str) labels the x-axis of the current axes with the text specified by str.

ylabel:

ylabel(str) labels the y-axis of the current axes with the string, str. A Summary of Matlab Commands Used

imreadRead image from graphics fileimwriteWrite image to graphics fileimfinfoInformation about graphics fileimshowDisplay ImageImplayPlay movies, videos or image sequent	
imfinfoInformation about graphics fileimshowDisplay ImageImplayPlay movies, videos or image sequent	
imshowDisplay ImageImplayPlay movies, videos or image sequent	
Implay Play movies, videos or image sequen	
	CAS
gray2ind Convert grayscale to indexed image	
ind2gray Convert indexed image to grayscale	
mat2gray Convert matrix to grayscale image Convert matrix to grayscale image	mage
rgb2gray Convert RGB image or colormap to	
grayscale	
imbinarize Binarize image by thresholding	
adapthresh Adaptive image threshold using loca	1
first-order statistics	1
otsuthresh Global histogram threshold using Ot	eu'e
method	su s
im2uint16 Convert image to 16-bit unsigned int	egers
im2uint8 Convert image to 8-bit unsigned inte	
imcrop Crop image	5015
imresize Resize image	
imrotate Rotate image	
imadjust Adjust image intensity values or cold	rman
imcontrast Adjust Contrast tool	лицр
imsharpen Sharpen image using unsharp maskir	1σ
histeq Enhance contrast using histogram	15
equalization	
adapthisteq Contrast-limited adaptive histogram	
equalization (CLAHE)	
imhistmatch Adjust histogram of image to match	N-bin
histogram of reference image	
imnoise Add noise to image	
imfilter N-D filtering of multidimensional im	nages
fspecial Create predefined 2-D filter	
weiner2 2-D adaptive noise-removal filtering	
medfilt2 2-D median filtering	
ordfilt2 2-D order-statistic filtering	
imfill Fill image regions and holes	
imclose Morphologically close image	
imdilate Dilate image	
imerode Erode image	
imopen Morphologically open image	
imreconstruct Morphological reconstruction	
watershed Watershed transform	
dct2 2-D discrete cosine transform	

hough	Hough transform
graydist	Gray-weighted distance transform of
	grayscale image
fft2	2-D fast Fourier transform
ifftshift	Inverse FFT shift
imcomplement	Complement image
immultiply	Multiply two images or multiply image by
	constant
imsubtract	Subtract one image from another or
	subtract constant from image
imdivide	Divide one image into another or divide
	image by constant
imadd	Add two images or add constant to image

Ex.No: 1 IMPLEMENTATION OF IMAGE PROCESSING COMMANDS

Date:

Aim:

To Perform important image processing commands using Matlab.

Software Used:

MATLAB

Program: (1A)

```
clear
close all
clc
I = imread('mountain1.jpg');
imshow(I);
```

Output:



Program:(1B)

```
subplot(2,2,1), imshow('kitchen showcase.jpg'),title('kitchen showcase.jpg');
subplot(2,2,2), imshow('hanging shelf.jpg'),title('hanging shelf.jpg');
subplot(2,2,3), imshow('food.jpg'),title('food.jpg');
subplot(2,2,4), imshow("chandellier.jpg"),title("chandellier.jpg");
impixelinfo;
imageinfo('kitchen showcase.jpg');
imageinfo('hanging shelf.jpg');
imageinfo('food.jpg');
imageinfo("chandellier.jpg");
```

Output:











Pixel info: (X, Y) Pixel Value

Program: (1C)

```
clc;
clear all;
close all;
A = rand(150);
imwrite(A,'mountain.jpg');
imshow('mountain.jpg')
```

Output:



Program: (1D)

```
clc;
clear all;
close all;
load clown.mat
newmap = copper(81);
imwrite(X, newmap, 'copperclown.png');
imshow('copperclown.png');
```

Output:



Result:

The important image commands have been displayed and studied

Ex.No: 2A IMPLEMEN

IMPLEMENTATION OF ARITHMETIC OPERATIONS

Date:

Aim:

To implement arithmetic operations of an image using Matlab.

Software Used:

MATLAB

Program: (A)

```
clc;
close all;
clear all;
I = imread('Squirrel.jpg');
c = imread('autumn-leaves.jpg');
K = imadd(c, I);
figure;
subplot(2,2,1);imshow(I);title('input image 1');
subplot(2,2,2);imshow(c);title('input image 2');
subplot(2,2,3);imshow(K);title('Output image');
```



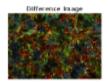




Program: (B)

```
close all;
clear;
I = imread("autumn-leaves.jpg");
background = imopen(I,strel('disk',15));
Ip = imsubtract(I,background);
Iq = imsubtract(I,50);
figure
subplot(2,2,1), imshow(Ip,[]), title('Difference Image');
subplot(2,2,2), imshow(I), title('Original Image');
subplot(2,2,3), imshow(Iq), title('Subtracted Image');
```

Output:







Program: (C)

```
clc;
close all;
clear all;
I = imread('Squirrel.jpg');
I16 = uint16(I);
J = immultiply(I16,I16);
subplot(1,2,1), imshow(I), title('input image');
subplot(1,2,2), imshow(J), title('multiplied Image');
```





Program: (D)

```
clc;
clear all;
close all;
I = imread('hanging shelf.jpg');
J = imdivide(I,2);
subplot(1,2,1), imshow(I), title('Input Image');
subplot(1,2,2), imshow(J), title('Output Image');
```

Output:





Result:

Thus the arithmetic operations of an image have been implemented using MATLAB.

Ex.No: 2B IMPLEMENTATION OF LOGICAL OPERATIONS

Date:

Aim:

To implement logical operations of an image using Matlab.

Software Used:

MATLAB

Program: (AND Operation)

```
imageSize = [200, 200];
i = zeros(imageSize);
rowStart = 100;
rowEnd = 150;
colStart = 50;
colEnd = 80;
i(rowStart:rowEnd, colStart:colEnd) = 1;
imageSize = [200, 200];
j = ones(imageSize);
resultImage = i & j;
subplot(1, 3, 1), imshow(i), title('Image 1');
subplot(1, 3, 2), imshow(j), title('Image 2');
subplot(1, 3, 3), imshow(resultImage), title('Output Image');
```



Program: (OR operation)

```
imageSize = [200, 200];
i = zeros(imageSize);
rowStart = 80;
rowEnd = 120;
colStart = 50;
colEnd = 120;
i(rowStart:rowEnd, colStart:colEnd) = 1;
imageSize = [200, 200];
j = ones(imageSize);
resultImage = i | j;
subplot(1, 3, 1), imshow(i), title('Image 1');
subplot(1, 3, 2), imshow(j), title('Image 2');
subplot(1, 3, 3), imshow(resultImage), title('Output Image');
```

Output:



Program: (NOT Operation)

```
imageSize = [200, 200];
i = zeros(imageSize);
rowStart = 90;
rowEnd = 110;
colStart = 50;
colEnd = 140;
i(rowStart:rowEnd, colStart:colEnd) = 1;
resultImage = ~i;
subplot(2, 2, 1), imshow(i), title('Input Image ');
subplot(2, 2, 2), imshow(resultImage), title('Output Image');
```



Program: (XOR Operation)

```
imageSize = [200, 200];
i = zeros(imageSize);
rowStart = 20;
rowEnd = 100;
colStart = 40;
colEnd = 120;
i(rowStart:rowEnd, colStart:colEnd) = 1;
imageSize = [200, 200];
j = ones(imageSize);
resultImage = xor(i,j);
subplot(1, 3, 1), imshow(i), title('Image 1');
subplot(1, 3, 2), imshow(j), title('Image 2');
subplot(1, 3, 3), imshow(resultImage), title('Output Image');
```

Output:



Result:

Thus the logical operations of an image have been implemented using MATLAB.

Ex.No: 3A IMPLEMENTATION OF SET OPERATIONS

Date:

Aim:

To implement Set operations of an image using Matlab.

Software Used:

MATLAB

Program:

```
A = imread("blueberry.jpg");
B = imread("strawberry.jpg");
imageA = imresize(A, [200,200]);
imageB = imresize(B, [200,200]);
if ~isequal(size(imageA), size(imageB))
error("Input images must have the same dimensions");
unionImage = max(imageA, imageB);
intersectionImage = min(imageA, imageB);
complementImageA = 255 - imageA;
differenceImage = abs(imageA - imageB);
subplot(2, 3, 1);imshow(imageA);title('Image A');
subplot(2, 3, 2);imshow(imageB);title('Image B');
subplot(2, 3, 3);imshow(unionImage);title('Union (Max)');
subplot(2, 3, 4);imshow(intersectionImage);title('Intersection (Min)');
subplot(2, 3, 5);imshow(complementImageA);title('Complement of A');
subplot(2, 3, 6);imshow(differenceImage);title('Difference');
imwrite(unionImage, 'union image.jpg');
imwrite(intersectionImage, 'intersection image.jpg');
imwrite(complementImageA,'complement imageA.jpg');
imwrite(differenceImage, 'difference image.jpg');
disp('Set operation images saved.');
```

Output:



Result:

Thus, the set operations of an image have been implemented using MATLAB.

Ex.No: 3B IMPLEMENTATION OF LOCAL AVERAGING USING NEIGHBORHOOD PROCESSING

Date:

Aim:

To implement local averaging using neighborhood processing in an image using Matlab.

Software Used:

MATLAB

Program:

```
inputImage = imread('rose.jpg');
path
neighborhoodSize = 3;
filter = fspecial('average', neighborhoodSize);
averagedImage = imfilter(inputImage, filter);
subplot(1, 2, 1);
imshow(inputImage);
title('Original Image');
subplot(1, 2, 2);
imshow(averagedImage);
title('Averaged Image');
imwrite(averagedImage, 'averaged_image.jpg');
disp('Averaged image saved as "averaged image.jpg&quot');
```

Output:





Averaged Image



Result:

Thus, the local averaging using neighborhoods processing of an image have been implemented using MATLAB.

Ex.No: 4 IMPLEMENTATION OF CONVOLUTION OPERATION

Date:

Aim:

To implement Convolution operation of an image using Matlab.

Software Used:

MATLAB

Program:

```
clc;
clear all;
close all;
a=imread('Squirrel.jpg');
subplot(3,3,1);imshow(a);title('Original image');
b=rgb2gray(a);
subplot(3,3,2);imshow(b);title('Gray scale image');
c=imnoise(b,'salt & pepper',0.1);
subplot(3,3,5);imshow(c);title('Salt & pepper noise');
h1=1/9*ones(3,3);
c1=conv2(c,h1,'same');
subplot(3,3,3);imshow(uint8(c1));title('3x3 Smoothing');
h2=1/25*ones(5,5);
c2=conv2(c,h2,'same');
subplot(3,3,6);imshow(uint8(c2));title('5x5 Smoothing');
```

Output:











Result:

Thus, the convolution operations of an image have been implemented using MATLAB.

Ex.No: 5 IMPLEMENTATION OF HISTOGRAM EQUALIZATION

Date:

Aim:

To implement Histogram equalization of an image using Matlab.

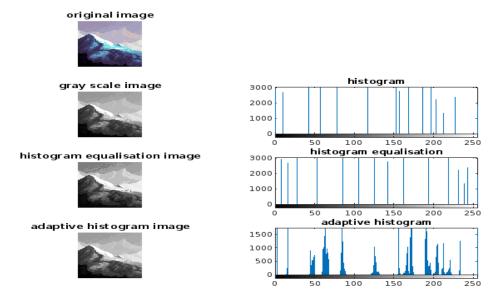
Software Used:

MATLAB

Program:

```
a= imread("blue-mountain.png");
subplot(4,2,1);imshow(a);title("original image");
b=rgb2gray(a);
subplot(4,2,3);imshow(b);title("gray scale image");
subplot(4,2,4);imhist(b);title("histogram");
subplot(4,2,5);c=histeq(b);
imshow(c);title("histogram equalisation image");
subplot(4,2,6);imhist(c);title("histogram equalisation");
subplot(4,2,7);f=adapthisteq(b);
imshow(f);title("adaptive histogram image");
subplot(4,2,8);imhist(f);title("adaptive histogram");
```

Output:



Result:

Thus, the Histogram equalization of an image has been implemented using MATLAB.

Ex.No: 5A IMPLEMENTATION OF CORRELATION BETWEEN THE VISUAL QUANTITY OF AN IMAGE

Date:

Aim:

To study the correlation between the visual quality of an image with its histogram.

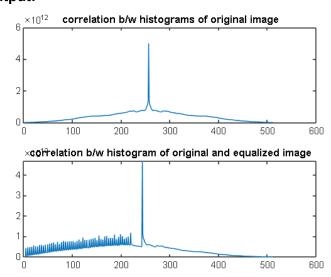
Software Used:

MATLAB

Program:

```
img= imread ('color.jpg');
img=rgb2gray(img);
[ count , cells ]= imhist (img) ;
Iheq = histeq(img);
[count1,cells1 ]= imhist (Iheq);
corrbsameimg = corr2(img,Iheq)
disp(corrbsameimg);
x = xcorr ( count , count ) ;
x1 = xcorr ( count , count ) ;
subplot(2,1,1);
plot(x);
title('correlation b/w histograms of original image');
subplot(2,1,2);
plot(x1)
title('correlation b/w histogram of original and equalized image')
```

Output:



Result:

Thus, the correlation between visual quantity of an image have been implemented using MATLAB.

Ex.No: 6 IMPLEMENTATION OF MEAN FILTER

Date:

Aim:

To implement mean filter in an image reduce noise in digital images using Matlab.

Software Used:

MATLAB

Program:

```
A = imread("chandellier.jpg");
B = rgb2gray(A)
filterSize = 25;
paddedImage = padarray(B, [filterSize, filterSize], "replicate");
outputImage = zeros(size(B));
for i = 1:size(B, 1)
for j = 1:size(B, 2)
  neighborhood = paddedImage(i:i+filterSize-1, j:j+filterSize-1);
  meanValue = mean(neighborhood(:));
   outputImage(i, j) = meanValue;
 end
end
subplot(1, 2, 1);
imshow(B);
title("Original Image");
subplot(1, 2, 2);
imshow(uint8(outputImage));
title("Mean Filtered Image");
```

Output:





Mean Filtered Image



Result:

The noise in an image is reduced using a mean filter, and it has been implemented using MATLAB.

Ex.No: 7 **IMPLEMENTATION OF ORDER STATISTICS FILTERS**

Date:

Aim:

To implement Order Statistics filters in an image using Matlab.

Software Used:

MATLAB

Program:

```
clc;
clear all;
close all;
b = imread("mont.jpeg");
subplot(3,3,1);imshow(b);title('Original Image');
a=rgb2gray(b);
a = im2double(a);
a = imnoise(a, 'salt & pepper', 0.02);
subplot(3,3,2);imshow(a);title('Noise Image');
I = medfilt2(a);
subplot(3,3,3);imshow(I);title('Median filtered Image');
x=rand(size(a));a(x(:)<0.05)=0;
\max Img = ordfilt2(a, 9, ones(3, 3));
subplot(3,3,5);imshow(max Img);title('Maximum filtered Image');
a(x(:) < 0.95) = 255; min Img = ordfilt2(a,1,ones(3,3));
subplot(3,3,6);imshow(min Img);title('Minimum filtered Image');
```

Output:

Original Image



Noise Image



Median filtered Image



Maximum filtered Image Minimum filtered Image





Result:

The different Order Statistics filters in an image have been implemented using MATLAB.

Ex.No: 8 REMOVE VARIOUS TYPES OF NOISE IN AN IMAGE

Date:

Aim:

To Remove Various types of Noise in an Image an image using Matlab.

Software Used:

MATLAB

Program: (Salt and Pepper Noise)

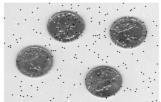
```
I = imread("eight.tif");
J = imnoise(I, "salt & pepper", 0.02);
subplot(2,3,1), imshow(I), title("Original Image");
subplot(2,3,2), imshow(J), title("Noisy Image");
Kmedian = medfilt2(J);
subplot(2,3,3), imshow(Kmedian), title("Noise removed Image");
```

Output:

Original Image



Noisy Image



Noise removed Image



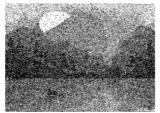
Program:(Gaussian Noise)

```
RGB = imread("red mountain.png");
I = im2gray(RGB);
J = imnoise(I, 'gaussian', 0, 0.025);
K = wiener2(J, [5 5]);
subplot(2,3,1);
imshow(I)
title('Original Image');
subplot(2,3,2);
imshow(J)
title('Added Gaussian Noise');
subplot(2,3,3);
imshow(K);
title('Wiener Filtered Image');
```

Original Image



Added Gaussian Noise



Wiener Filtered Image

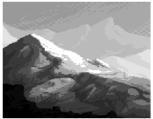


Program: (Rayleigh Noise)

```
RGB = imread('blue-mountain.png' );
I = im2gray(RGB);
rayleighNoise = raylrnd(0.05, size(I));
J = im2double(I) + rayleighNoise;
K = wiener2(J, [5 5]);
subplot(2,3,1);
imshow(I)
title('Original Image');
subplot(2,3,2);
imshow(J)
title('Added Rayleigh Noise');
subplot(2,3,3);
imshow(K);
title('Wiener Filtered Image');
```

Output:





Added Rayleigh Noise



Wiener Filtered Image



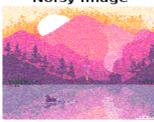
Program:(Erlang Noise)

```
I = imread('red mountain.png');
scale = 10; shape= 5;
sizeSignal = size(I);
erlangNoise = scale*gamrnd(shape, 1, sizeSignal);
noisy = double(I) + erlangNoise;
noisy = min(max(noisy, 0), 255);
noisy = uint8(noisy);
denoised=medfilt3(noisy);
figure;
subplot(2, 3, 1);imshow(I);title('Input Image');
subplot(2, 3, 2);imshow(noisy);title('Noisy Image');
subplot(2, 3, 3);imshow(denoised);title('Denoised Image');
```

Input Image



Noisy Image



Denoised Image



Program:(Exponential Noise)

```
I = imread('blue-mountain.png');
lambda = 0.1;
sizeSignal = size(I);
exponentialNoise = -log(1 - rand(sizeSignal)) / lambda;
noisy = double(I) + exponentialNoise;
noisy = min(max(noisy, 0), 255);
noisy = uint8(noisy);
denoised=medfilt3(noisy);
figure;
subplot(2, 3, 1);imshow(noisy);title('Noisy Image');
subplot(2, 3, 2);imshow(denoised);title('Denoised Image');
```

Output:

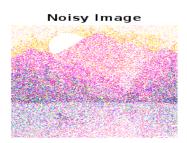




Program:(Uniform Noise)

```
I = imread('red mountain.png');
minValue = 0;
maxValue = 255;
sizeImage = size(I);
uniformNoise = (maxValue - minValue) * rand(sizeImage) + minValue;
noisy = double(I) + uniformNoise;
noisy = min(max(noisy, 0), 255);
noisy = uint8(noisy);
denoised=medfilt3(noisy);
figure;
subplot(2, 2, 1);imshow(noisy);title('Noisy Image');
subplot(2, 2, 2);imshow(denoised);title('Denoised Image');
```

Output:





Result:

Thus, the various types of noise in an image have been removed and implemented using MATLAB.

Ex No: 9 IMPLEMENTATION OF SOBEL OPERATOR

Date:

Aim:

To implement SOBEL operator in digital images for edge detection using Matlab.

Software Used:

MATLAB

Program:

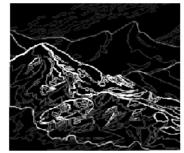
```
a = imread('blue-mountain.png');
b = rgb2gray(a);
gray_img = double(b);
h_kernel = [-1, 0, 1; -2, 0, 2; -1, 0, 1];
v_kernel = [-1, -2, -1; 0, 0, 0; 1, 2, 1];
c = imfilter(gray_img, h_kernel);
d = imfilter(gray_img, v_kernel);
gradient_magnitude = sqrt(c.^2 + d.^2);
figure;
subplot(2, 2, 1);imshow(a);title('Original Image');
subplot(2, 2, 2);imshow(uint8(gradient_magnitude));
title('Sobel Edge Detected Image');
```

Output:

Original Image



Sobel Edge Detected Image



Result:

The SOBEL operator in digital images for edge detection has been implemented using MATLAB.

MINI - PROJECT

IMPLEMENTATION OF CAR PARKING INDICATOR USING MATLAB

Aim:

This project primarily aims to create a smart parking system with the help of MATLAB programming

Software Used:

MATLAB

Theory:

The goal of this experiment is to detect and count the number of cars in a parking lot image using image processing techniques. This involves converting the image to grayscale, enhancing features through edge detection, applying morphological operations to improve car separation, and finally, detecting and counting the individual cars based on their areas.

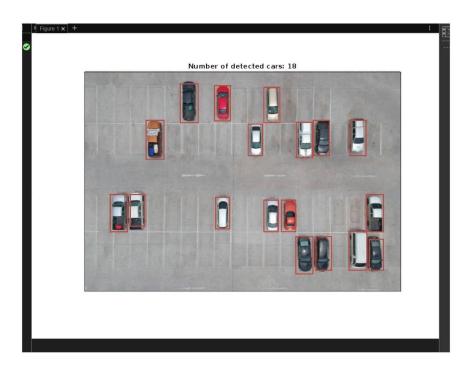
Steps Involved:

- 1. **Grayscale Conversion**: If the input image is in color (RGB), it is first converted to grayscale to simplify processing. Grayscale images contain intensity values, making it easier to perform subsequent analysis like edge detection.
- 2. **Noise Reduction**: A Gaussian filter is applied to the grayscale image to smooth the image and reduce noise. This is important to eliminate small, irrelevant details that could interfere with the car detection.
- 3. **Edge Detection**: The Canny edge detector is used to identify edges in the image. This step highlights the boundaries of objects (cars), making it easier to distinguish the cars from the background.
- 4. **Morphological Operations**: Dilation and erosion are used to enhance the detected edges. Dilation connects nearby edges, helping to identify adjacent cars, while erosion removes small noise that might falsely appear as a car.
- 5. **Component Labeling**: The bwlabel function is used to label connected components in the processed binary image. Each connected component corresponds to a potential car.
- 6. Bounding Box and Area Filtering: For each labeled component, the area is calculated. Components with areas within a specified range (e.g., 90 to 1500 pixels) are considered valid cars. A bounding box is drawn around each valid component to highlight the detected cars.
- 7. **Car Counting**: The number of cars is determined by counting the number of valid components. The number of available parking spaces is calculated by subtracting the detected car count from the total available spaces.

Program:

```
img = imread('car parking.jpg');
if size(img, 3) == 3
   grayImg = rgb2gray(img);
else
   grayImg = img;
end
filteredImg = imgaussfilt(grayImg, 2);
edges = edge(filteredImg, 'Canny', [0.15, 0.3]);
se = strel('disk', 5);
dilatedImg = imdilate(edges, se);
cleanedImg = imerode(dilatedImg, se);
[labeledImg, numLabels] = bwlabel(closedImg);
minAreaThreshold = 90;
maxAreaThreshold = 1500;
carCount = 0;
if size(img, 3) == 1
   resultImg = cat(3, img, img, img);
else
   resultImg = img;
end
for label = 1:numLabels
   component = (labeledImg == label);
  area = sum(component(:));
   if area >= minAreaThreshold && area <= maxAreaThreshold</pre>
       carCount = carCount + 1;
       stats = regionprops(component, 'BoundingBox');
       bbox = stats.BoundingBox;
       resultImg = insertShape(resultImg, 'Rectangle', bbox, 'Color', 'red',
'LineWidth', 2);
   end
end
figure;
imshow(resultImg);
title(['Number of detected cars: ', num2str(carCount)]);
totalSpaces = 76;
availableSpaces = totalSpaces - carCount;
disp(['Available parking spaces: ', num2str(availableSpaces)]);
```

Output:



Result:

The 'Available parking spaces: 58', is displayed in the Command Window. The car detection program was tested on a variety of parking lot images to verify its accuracy and effectiveness. The results from the program were compared to manual counts of the cars and visual inspection of the bounding boxes.