

① 10分

(1)  $\vec{u} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = a \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix} + b \begin{pmatrix} -1 \\ 2 \\ 3 \end{pmatrix} + c \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}$  とおく.

$$\begin{pmatrix} 1 & -1 & 0 & | & x \\ 1 & 2 & 1 & | & y \\ 2 & 3 & 2 & | & z \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -1 & 0 & | & x \\ 0 & 3 & 1 & | & -x+y \\ 0 & 5 & 2 & | & -2x+z \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -1 & 0 & | & x \\ 0 & 3 & 1 & | & -x+y \\ 0 & 15 & 6 & | & -6x+3z \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -1 & 0 & | & x \\ 0 & 3 & 1 & | & -x+y \\ 0 & 0 & 1 & | & -x-5y+3z \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -1 & 0 & | & x \\ 0 & 1 & 0 & | & 2y-z \\ 0 & 0 & 1 & | & -x-5y+3z \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & 0 & 0 & | & x+2y-z \\ 0 & 1 & 0 & | & 2y-z \\ 0 & 0 & 1 & | & -x-5y+3z \end{pmatrix} \quad \text{従って, } \vec{u} = (x+2y-z)\vec{v}_1 + (2y-z)\vec{v}_2 + (-x-5y+3z)\vec{v}_3 //$$

(2) (1)より,  $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \vec{v}_1 - \vec{v}_3$ ,  $\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = 2\vec{v}_1 + 2\vec{v}_2 + 5\vec{v}_3$ ,  $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = -\vec{v}_1 - \vec{v}_2 + 3\vec{v}_3$  である.

$$f\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix}, f\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = 2\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + 2\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + 5\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 4 \\ 5 \end{pmatrix}, f\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = -\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + 3\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ 2 \end{pmatrix} \text{ である.}$$

$f$  の表現行列を  $A$  とおくと,  $\begin{pmatrix} f\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \\ f\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \\ f\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \end{pmatrix} = A$  であるから.

$A$  の各列の一次関係を探る.

$$A = \begin{pmatrix} 0 & 2 & -1 \\ -1 & 4 & -1 \\ 0 & 5 & 2 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 2 & -1 \\ -1 & 4 & -1 \\ 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 2 & -1 \\ 0 & 6 & -2 \\ 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 3 & -1 \\ 0 & 6 & -2 \\ 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 3 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

行基本変形で 各列の一次関係は 変化しないから,  $f\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, f\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$  が線型独立.

従って,  $\dim \text{Im } f = 2$  で  $\left\{ \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 4 \\ 5 \end{pmatrix} \right\}$  を基底ととれる.

(3)  $A \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$  を満たす  $\begin{pmatrix} x \\ y \\ z \end{pmatrix}$  を求める.

$$A \rightarrow \begin{pmatrix} 0 & 2 & -1 \\ -1 & 4 & -1 \\ 0 & 5 & 2 \end{pmatrix} \text{ より } \begin{pmatrix} x \\ y \\ z \end{pmatrix} = a \begin{pmatrix} -55 \\ -1 \\ 9 \end{pmatrix} \quad (a \text{ は任意}).$$

従って,  $\dim \text{Ker } f = 1$  で  $\left\{ \begin{pmatrix} -55 \\ -1 \\ 9 \end{pmatrix} \right\}$  を基底ととれる.

② 24分

$$(1) |A - \lambda E| = \begin{vmatrix} 1-\lambda & 2 & 1 \\ -1 & 4-\lambda & 1 \\ 2 & -4 & -\lambda \end{vmatrix} = \begin{vmatrix} 2-\lambda & 2-\lambda & 2-\lambda \\ -1 & 4-\lambda & 1 \\ 2 & -4 & -\lambda \end{vmatrix} = (2-\lambda) \begin{vmatrix} 1 & 1 & 1 \\ -1 & 4-\lambda & 1 \\ 2 & -4 & -\lambda \end{vmatrix} = (2-\lambda) \begin{vmatrix} 1 & 0 & 0 \\ -1 & 5-\lambda & 2 \\ 2 & -6 & -2-\lambda \end{vmatrix} = (2-\lambda) \{(\lambda-5)(\lambda+2)+12\}$$

$$= (2-\lambda)(\lambda^2-3\lambda+2) = (2-\lambda)(\lambda-2)(\lambda-1) \quad \lambda = 2 \text{ (重解)}, 1$$

(2) (i)  $\lambda = 1$  について.

$$A - E = \begin{pmatrix} 0 & 2 & 1 \\ -1 & 3 & 1 \\ 2 & -4 & -1 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 2 & 1 \\ -1 & 3 & 1 \\ 0 & 2 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -3 & -1 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

従って,  $A\vec{x} = \vec{x}$  を満たす  $\vec{x}$  は  $a \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}$  ( $a$  は任意) 従って  $\left\{ \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} \right\}$  を基底にとる.

(ii)  $\lambda = 2$  について

$$A - 2E = \begin{pmatrix} -1 & 2 & 1 \\ -1 & 2 & 1 \\ 2 & -4 & -2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & -2 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

従って  $A\vec{x} = 2\vec{x}$  を満たす  $\vec{x}$  は  $a \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + b \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$  ( $a, b$  は任意) 従って  $\left\{ \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \right\}$  を基底にとる.

$$(3) (f(\vec{p}_1) \ f(\vec{p}_2) \ f(\vec{p}_3)) = (\vec{p}_1 \ \vec{p}_2 \ \vec{p}_3) \cdot M$$

$$AB = BM$$

$\vec{p}_1, \vec{p}_2, \vec{p}_3$  は線型独立だから  $B^{-1}$  が存在する.

$$B^{-1}AB = M.$$

$$B = \begin{pmatrix} 1 & 2 & 1 \\ 1 & 1 & 0 \\ -2 & 0 & 1 \end{pmatrix} \text{ とすると } M = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix}.$$

③ 8分

$$f(x, y) = xy \cdot e^{-x^2 - y^2}$$

$$(1) f_x = y \cdot e^{-x^2 - y^2} - 2xy \cdot e^{-x^2 - y^2}, \quad f_y = x \cdot e^{-x^2 - y^2} - 2xy \cdot e^{-x^2 - y^2}$$

$$(2) f_x = 0 \text{ かつ } y(1 - 2x^2) = 0. \quad \text{従って } y = 0 \text{ または } x = \pm \frac{1}{\sqrt{2}}$$

$$f_y = 0 \text{ かつ } x(1 - 2y^2) = 0. \quad \text{従って } x = 0 \text{ または } y = \pm \frac{1}{\sqrt{2}}$$

$$\text{よって } (a, b) = (0, 0), \left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right), \left(\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}\right), \left(-\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right), \left(-\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}\right)$$

$$(3) f_{xx} = -2xy \cdot e^{-x^2 - y^2} - 4xy \cdot e^{-x^2 - y^2} + 4x^3y \cdot e^{-x^2 - y^2} = (-6xy + 4x^3y) e^{-x^2 - y^2}$$

$$f_{yy} = (-6xy + 4xy^3) e^{-x^2 - y^2}$$

$$f_{xy} = (1 - 2x^2)(e^{-x^2 - y^2} - 2y^2 e^{-x^2 - y^2}) = (1 - 2x^2)(1 - 2y^2) e^{-x^2 - y^2}$$

$$\begin{aligned} \wedge \text{つまり } H(a, b) &= 4x^2y^2(2x^2 - 3)(2y^2 - 3) e^{-2(x^2 + y^2)} - (1 - 2x^2)^2(1 - 2y^2)^2 e^{-2(x^2 + y^2)} \\ &= \left\{ 4x^2y^2(2x^2 - 3)(2y^2 - 3) - (1 - 2x^2)^2(1 - 2y^2)^2 \right\} e^{-2(x^2 + y^2)} \end{aligned}$$

$$H(0, 0) = (0 - 1) \cdot 1 = -1 < 0$$

$$H\left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right) = ((-2)(-2) - 0) e^{-2} = 4e^{-2} > 0, \quad f_{xx}\left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right) = (-3 + 1) e^{-1} = -2e^{-1} < 0$$

$$H\left(\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}\right) = 4e^{-2} > 0, \quad f_{xx}\left(\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}\right) = (3 - 1) e^{-1} = 2e^{-1} > 0.$$

$$H\left(-\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right) = 4e^{-2} > 0, \quad f_{xx}\left(-\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right) = (3 - 1) e^{-1} = 2e^{-1} > 0.$$

$$H\left(-\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}\right) = 4e^{-2} > 0, \quad f_{xx}\left(-\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}\right) = (-3 + 1) e^{-1} = -2e^{-1} < 0. \quad \text{よって}$$

$$\left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right), \left(-\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}\right) \text{ で 極大値 } \frac{1}{2e}$$

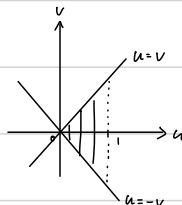
$$\left(\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}\right), \left(-\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right) \text{ で 極小値 } -\frac{1}{2e} \text{ と } 3.$$

4) 53%

$$(1) \iint_D \frac{x+y}{1+(x-y)} dx dy \quad D: x \geq 0, y \geq 0, x+y \leq 1$$

$$x+y = u, x-y = v \text{ とおく.}$$

$$x = \frac{u+v}{2}, y = \frac{u-v}{2} \quad \begin{matrix} v \geq -u & v \leq u \\ u+v \geq 0 & u-v \geq 0, & u \leq 1. \end{matrix}$$



$$\text{従って, } D \text{ は } E = \{(u, v) \mid 0 \leq u \leq 1, -u \leq v \leq u\} \text{ である.}$$

$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{vmatrix} = -\frac{1}{2} \text{ 故に, } \left| \frac{\partial(x, y)}{\partial(u, v)} \right| = \frac{1}{2} \text{ である.}$$

$$\begin{aligned} \iint_D \frac{x+y}{1+(x-y)} dx dy &= \frac{1}{2} \int_0^1 \left( \int_{-u}^u \frac{u}{1+v} \cdot dv \right) du = \frac{1}{2} \int_0^1 u \left[ \log |1+v| \right]_{v=-u}^{v=u} du \\ &= \frac{1}{2} \int_0^1 u \cdot \log \frac{1+u}{1-u} \cdot du \end{aligned}$$

$$\begin{aligned} \int u \cdot \log \frac{1+u}{1-u} du &= \frac{1}{2} u^2 \log \frac{1+u}{1-u} - \frac{1}{2} \int u^2 \cdot \frac{1-u+1+u}{1+u} \cdot \frac{1-u+1+u}{(1-u)^2} du = \frac{1}{2} u^2 \log \frac{1+u}{1-u} - \frac{1}{2} \int u^2 \cdot \frac{2}{1-u^2} du \\ &= \frac{1}{2} u^2 \log \frac{1+u}{1-u} + \int \left( 1 + \frac{1}{u^2-1} \right) du = \frac{1}{2} u^2 \log \frac{1+u}{1-u} + u + \frac{1}{2} \left( \frac{1}{u-1} - \frac{1}{u+1} \right) \cdot du \\ &= \frac{1}{2} u^2 \log \frac{1+u}{1-u} + u + \frac{1}{2} \log \frac{1-u}{1+u} \\ &= u + \frac{1}{2} (u^2-1) \log \left( \frac{1+u}{1-u} \right). \end{aligned}$$

$$\text{従って, } \frac{1}{2} \int_0^1 u \cdot \log \frac{1+u}{1-u} \cdot du = \frac{1}{2} \left[ u + \frac{1}{2} (u^2-1) \log \frac{1+u}{1-u} \right]_0^1$$

$$\lim_{u \rightarrow 1} \frac{\log \frac{1+u}{1-u}}{\frac{1}{u^2-1}} = \lim_{u \rightarrow 1} \frac{\frac{1-u}{1+u} \cdot \frac{-1-u-1+u}{(1-u)^2}}{-\frac{2u}{(u^2-1)^2}} = \lim_{u \rightarrow 1} \frac{-\frac{2}{1-u^2}}{-\frac{2u}{(u^2-1)^2}} = \lim_{u \rightarrow 1} \frac{-2 \cdot (1-u^2)}{-2u} = 0. \text{ である.}$$

$$\frac{1}{2} \left[ u + \frac{1}{2} (u^2-1) \log \frac{1+u}{1-u} \right]_0^1 = \frac{1}{2} (1 + 0 - 0 - 0) = \frac{1}{2}$$

$$(2) \iiint_E xyz \, dx dy dz \quad E: y \geq x \geq 0, z \geq 0, x^2 + y^2 + z^2 \leq 1$$

$$x = r \sin \varphi \cdot \cos \theta, \quad y = r \sin \varphi \cdot \sin \theta, \quad z = r \cos \varphi \quad \text{よくよく}$$

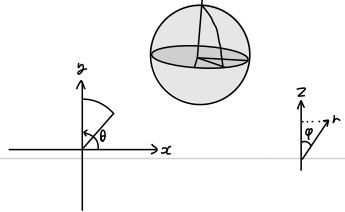
$$E \text{ は } F = \left\{ (r, \theta, \varphi) \mid 0 \leq r \leq 1, \frac{\pi}{4} \leq \theta \leq \frac{\pi}{2}, 0 \leq \varphi \leq \frac{\pi}{2} \right\} \text{ 1: 4.2}$$

$$\frac{\partial(x, y, z)}{\partial(r, \theta, \varphi)} = \begin{vmatrix} \sin \varphi \cos \theta & \sin \varphi \sin \theta & \cos \varphi \\ -r \sin \varphi \sin \theta & r \sin \varphi \cos \theta & 0 \\ r \cos \varphi \cos \theta & r \cos \varphi \sin \theta & -r \sin \varphi \end{vmatrix} = r^2 \sin \varphi \begin{vmatrix} \sin \varphi \cos \theta & \sin \varphi \sin \theta & \cos \varphi \\ -\sin \theta & \cos \theta & 0 \\ \cos \varphi \cos \theta & \cos \varphi \sin \theta & -\sin \varphi \end{vmatrix}$$

$$= r^2 \sin \varphi (-\sin^2 \varphi \cos^2 \theta - \sin^2 \varphi \sin^2 \theta - \cos^2 \varphi \sin^2 \theta - \cos^2 \varphi \cos^2 \theta)$$

$$= r^2 \sin \varphi (-1) = -r^2 \sin \varphi. \quad \therefore \left| \frac{\partial(x, y, z)}{\partial(r, \theta, \varphi)} \right| = r^2 \sin \varphi$$

$$\begin{aligned} \text{14.2.} \quad \iiint_E xyz \, dx dy dz &= \int_0^{\frac{\pi}{2}} \int_{\frac{\pi}{4}}^{\frac{\pi}{2}} \int_0^1 r^3 \sin^2 \varphi \cos \varphi \cdot \cos \theta \cdot \sin \theta \times r^2 \sin \varphi \, dr d\theta d\varphi \\ &= \int_0^{\frac{\pi}{2}} \int_{\frac{\pi}{4}}^{\frac{\pi}{2}} \int_0^1 r^5 \sin^3 \varphi \cos \varphi \cdot \cos \theta \sin \theta \, dr d\theta d\varphi \\ &= \int_0^{\frac{\pi}{2}} \sin^3 \varphi \cos \varphi \cdot d\varphi \times \int_{\frac{\pi}{4}}^{\frac{\pi}{2}} \sin \theta \cos \theta \, d\theta \times \int_0^1 r^5 \, dr \\ &= \left[ \frac{1}{4} \sin^4 \varphi \right]_0^{\frac{\pi}{2}} \times \left[ \frac{1}{2} \sin^2 \theta \right]_{\frac{\pi}{4}}^{\frac{\pi}{2}} \times \frac{1}{6} \\ &= \frac{1}{4} \times \frac{1}{2} \left( 1 - \frac{1}{2} \right) \times \frac{1}{6} \\ &= \frac{1}{96} \end{aligned}$$



5 15分.

$$(1) z^4 + 1 = 0$$

$$z = re^{i\theta} \text{ とおく.}$$

$$r = 1, 4\theta = \pi + 2n\pi, \quad \theta = \frac{\pi}{4}, \frac{3}{4}\pi, \frac{5}{4}\pi, \frac{7}{4}\pi$$

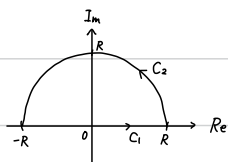
$$\therefore z = \frac{1}{\sqrt{2}} + i\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}} + i\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}} - i\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}} - i\frac{1}{\sqrt{2}}.$$

$$(2) \operatorname{Res}\left(\frac{1}{\frac{1}{2} + i\frac{1}{2}}\right) = \frac{1}{\sqrt{2} \cdot 2\left(\frac{1}{2} + i\frac{1}{2}\right) \cdot \sqrt{2}i} = \frac{1}{4\left(\frac{1}{2} + i\frac{1}{2}\right)}$$

同様に、他の極に対して留数をとる.

$$\operatorname{Res}(z) = \frac{1}{4z} \left( = \frac{\alpha}{4} \right) z \text{ である.}$$

$$(3) I = \int_{-\infty}^{\infty} f(x) dx = \frac{1}{2} \int_{-\infty}^{\infty} \frac{1}{x^2 + 1} dx.$$



図のよう経路  $C_1 + C_2$  で  $R \rightarrow \infty$  とした.

$$\oint_{C_1 + C_2} f(z) dz \text{ を考える.}$$

$$C_1 + C_2 \text{ 内に含まれる } f(z) \text{ の極は } z = \frac{1}{\sqrt{2}} + i\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}} + i\frac{1}{\sqrt{2}} \text{ である.}$$

$$\operatorname{Res}\left(\frac{1}{\frac{1}{2} + i\frac{1}{2}}\right) = \frac{1}{4\left(\frac{1}{2} + i\frac{1}{2}\right)} = \frac{\frac{1}{2} - i\frac{1}{2}}{4}, \quad \operatorname{Res}\left(-\frac{1}{2} + i\frac{1}{2}\right) = \frac{-\frac{1}{2} - i\frac{1}{2}}{4}$$

$$\text{従って } \oint_{C_1 + C_2} f(z) dz = 2\pi i \cdot \left( -\frac{i\sqrt{2}}{4} \right) = \frac{\pi}{2}.$$

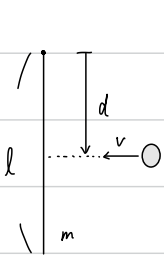
$$\int_{C_2} f(z) dz \text{ は } R \rightarrow \infty \text{ としたとき } \left| z \times \frac{1}{z^2 + 1} \right| \rightarrow 0 \text{ となる. } \int_{C_2} f(z) dz = 0.$$

$$\oint_{C_1 + C_2} f(z) dz = \int_{C_1} f(z) dz = \frac{\pi}{2} \text{ である. } \int_{C_1} f(z) dz = \int_{-\infty}^{\infty} f(x) dx \text{ である.}$$

$$\text{求める値は } \underline{\underline{\frac{\pi}{2\sqrt{2}}}}.$$

# 物理

11



$$(1) I = \int_0^l \frac{m}{l} \cdot x^2 \cdot dx = \frac{m}{l} \left[ \frac{1}{3} x^3 \right]_0^l = \frac{1}{3} m l^2$$

(2) 角運動量が保存されるので

$$m v l = m \cdot l \cdot \omega \cdot l + I \omega$$

$$I = \frac{1}{3} m l^2 \text{ より } m v l = m l^2 \omega + \frac{1}{3} m l^2 \omega = \frac{4}{3} m l^2 \omega$$

$$\therefore \omega = \frac{3v}{4l}$$

$$(3) K = \frac{1}{2} m \left( \frac{3v}{4} \right)^2 + \frac{1}{2} I \left( \frac{3v}{4l} \right)^2 = \frac{9}{32} m v^2 + \frac{1}{6} m l^2 \cdot \frac{9v^2}{16l^2} = m v^2 \left( \frac{9}{32} + \frac{3}{32} \right) = \frac{3}{8} m v^2$$

(4) 角運動量が保存されるので

$$m v d = m d \cdot \omega \cdot d + I \omega$$

$$I = \frac{1}{3} m l^2 \text{ より } m v d = m d^2 \omega + \frac{1}{3} m l^2 \omega$$

$$3 v d = (l^2 + 3 d^2) \omega \quad \omega = \frac{3 v d}{l^2 + 3 d^2}$$

$$(5) K = \frac{1}{2} m \left( \frac{3 v d}{l^2 + 3 d^2} \right)^2 + \frac{1}{2} I \left( \frac{3 v d}{l^2 + 3 d^2} \right)^2$$

$$= \frac{1}{2} m \left( \frac{3 v d}{l^2 + 3 d^2} \right)^2 + \frac{1}{6} m l^2 \left( \frac{3 v d}{l^2 + 3 d^2} \right)^2$$

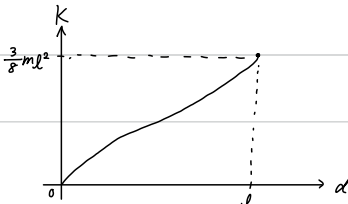
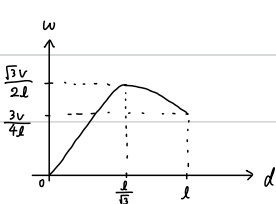
$$= \frac{3}{2} m v^2 \frac{d^2 (3 d^2 + l^2)}{(l^2 + 3 d^2)^2} = \frac{3}{2} m v^2 \cdot \frac{d^2}{l^2 + 3 d^2}$$

(6)  $\eta$  を書くために  $\frac{d\omega}{dd}$ ,  $\frac{dK}{dd}$  を求める

$$d = \frac{l}{\sqrt{3}} \text{ となる } \omega = \frac{\sqrt{3}v}{2l}$$

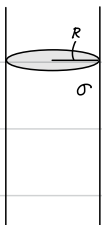
$$\frac{d\omega}{dd} = 3v \cdot \left( \frac{1}{l^2 + 3d^2} + d \cdot \frac{-6d}{(l^2 + 3d^2)^2} \right) = 3v \cdot \frac{l^2 - 3d^2}{(l^2 + 3d^2)^2}$$

$$\frac{dK}{dd} = \frac{3}{2} m v^2 \left( \frac{2d}{l^2 + 3d^2} + d^2 \cdot \frac{-6d}{(l^2 + 3d^2)^2} \right) = \frac{3}{2} m v \cdot \frac{2d(l^2 - 3d^2)}{(l^2 + 3d^2)^2} = 3 m v \cdot \frac{d(l^2 - 3d^2)}{(l^2 + 3d^2)^2}$$



変曲点となる  
時間あれば

2



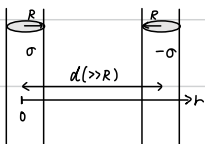
$$(1) Q = 2\pi R \times l \times \sigma = 2\pi R \sigma l$$

(2) 長さ  $l$ , 半径  $r$  で  $A$  と同軸の内筒表面  $S$  について.

$$\text{ガウスの法則を適用して } E_p(r) \cdot 2\pi r \times l = \frac{2\pi R \sigma l}{\epsilon_0}$$

$$E_p(r) = \frac{R\sigma}{\epsilon_0 r}$$

$$(3) \phi_p = - \int_R^r \frac{R\sigma}{\epsilon_0 r} dr = - \frac{R\sigma}{\epsilon_0} \log \frac{r}{R}$$



$$(4) E_s(r) = E_p(r) + E_p(d-r) = \frac{R\sigma}{\epsilon_0} \left( \frac{1}{r} + \frac{1}{d-r} \right)$$

(5) (電位差を求めるのに基準??)  $\rightarrow$  通常  $A$  から見た  $B$  の電位を聞いている.

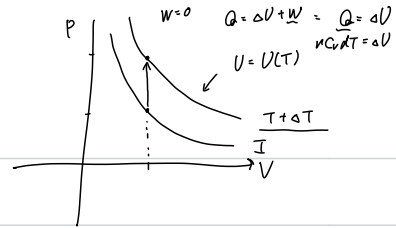
$$\begin{aligned} \Delta\phi_{AB} &= - \int_R^{d-R} \frac{R\sigma}{\epsilon_0} \left( \frac{1}{r} + \frac{1}{d-r} \right) dr = - \frac{R\sigma}{\epsilon_0} \left[ \log \left| \frac{r}{d-r} \right| \right]_R^{d-R} = - \frac{R\sigma}{\epsilon_0} \left( \log \frac{d-R}{R} - \log \frac{R}{d-R} \right) \\ &= - \frac{2R\sigma}{\epsilon_0} \log \frac{d-R}{R} \end{aligned}$$

$$d-R \approx d \text{ と近似すれば } \Delta\phi_{AB} = - \frac{2R\sigma}{\epsilon_0} \cdot \log \frac{d}{R}$$

$$(6) C = \frac{2\pi R \sigma}{|\Delta\phi_{AB}|} = \frac{\pi \epsilon_0}{\log \frac{d}{R}}$$



3



(1) 気体のエントロピー変化  $\Delta U$  は、

$$\Delta U = \int_{T_A}^{T_B} C_V dT = \int_{T_A}^{T_B} (C_V^0 + \alpha T) dT = \left[ C_V^0 T + \frac{1}{2} \alpha T^2 \right]_{T_A}^{T_B} = C_V^0 (T_B - T_A) + \frac{1}{2} \alpha (T_B^2 - T_A^2)$$

気体が外部にすることを  $W$  は、圧力一定より、 $W = p_A \cdot V_0$

熱力学第一法則より、吸収する熱量  $Q$  を用いて、 $Q = \Delta U + W$  が成立つので、

$$Q_{AB} = C_V^0 (T_B - T_A) + \frac{1}{2} \alpha (T_B^2 - T_A^2) + p_A V_0$$

(2) 断熱変化でポアソンの関係式が成立つ、

$$p_A (2V_0)^{\gamma} = p_C \cdot (3V_0)^{\gamma}$$

$$T_B (2V_0)^{\gamma-1} = T_C \cdot (3V_0)^{\gamma-1} \quad \frac{T_B}{T_C} = \left( \frac{3}{2} \right)^{\frac{2}{3}} = 1.3 \quad \text{従って、} T_B = 1.3 T_C$$

状態方程式  $p_A V_0 = R T_A$ ,  $p_A \cdot 2V_0 = R T_B$  より、 $T_B = 2 T_A$ 、従って  $T_A < T_C < T_B$ 。

(3) (1) と同様、

$$\Delta U = \int_{T_C}^{T_D} (C_V^0 + \alpha T) dT = C_V^0 (T_D - T_C) + \frac{1}{2} \alpha (T_D^2 - T_C^2)$$

$$W = \int p \cdot dV = 0.$$

$$\text{よ、} Q_{CD} = -(\Delta U + W) = -C_V^0 (T_D - T_C) - \frac{1}{2} \alpha (T_D^2 - T_C^2).$$

状態 D から状態 A は断熱変化だから、 $Q_{DA} = 0$ 。

$$(4) \eta = \frac{Q_{AB} - Q_{CD}}{Q_{AB}} = 1 + \frac{C_V^0 (T_D - T_C) + \frac{1}{2} \alpha (T_D^2 - T_C^2)}{C_V^0 (T_B - T_A) + \frac{1}{2} \alpha (T_B^2 - T_A^2) + p_A V_0}$$