

Taylor Howell

CONTACT INFORMATION	Durand 032 Stanford University CA, 94305 USA	thowell@stanford.edu thowell.github.io +1 801 300 9431
EDUCATION	Ph.D., Mechanical Engineering , Stanford University, CA, USA Advisor: Zachary Manchester Sept. 2017 - present	
	M.S., Mechanical Engineering , Stanford University, CA, USA Automatic Controls, Robotics June 2019	
	B.S., Mechanical Engineering , University of Utah, UT, USA Summa Cum Laude Dec. 2016	
RESEARCH	Research Assistant , Robotic Exploration Lab, Stanford University My research is focused on devising optimization tools and algorithms for motion planning of robotic systems. Currently, I'm developing fast solvers for contact-implicit trajectory optimization. Previously, I was co-leading development of <code>TrajectoryOptimization.jl</code> , an open-source Julia package for solving constrained trajectory optimization problems. Research Assistant , Telerobotics Laboratory, University of Utah I devised and implemented a control policy to sort swarms of microrobots using rotating uniform magnetic fields for minimally invasive medical applications. This work included: applied physics, simulation, nonlinear optimization, fabrication of a scaled microrobot swarm, and writing C++ code to control a tri-axial Helmholtz-coil system. Research Assistant , Utah Center of Excellence for Biomedical Microfluidics, University of Utah Sept. 2014 - Oct. 2015 I designed and built a forty-eight-syringe pump for a medical microfluidic system, developed standard operating procedures for a high-throughput drug screening and cytotoxicity evaluation system, and performed statistical analysis for ovarian-cancer cell experiments.	May 2018–Present Oct. 2015 - Dec. 2016
EXPERIENCE	Instructor , GREAT Summer Camp, University of Utah Taught practical robotics and programming skills to elementary school students using the LEGO Mindstorm platform and developed projects and challenges for FLL skills, telerobotics, and kinetic-art themed weeks. Co-founder , Cornaby-Howell LLC I prototyped systems including: a touch display module with GUI, Arduino C code, a lead-screw system, and syringe attachment modules for precision high-throughput syringe pumps. Twisty Puzzle Designer I designed and built twisty puzzles with selling prices ranging from \$25 - \$850. I exhibited my work at the community's premier international event, Dutch Cube Day, in 2008.	Jun. 2017 – Jul. 2017 Apr. 2015 – Oct. 2015 Aug. 2007 – Jan. 2011

PUBLICATIONS	<ol style="list-style-type: none"> 1. B. Jackson*, T. Howell*, K. Shah, M. Schwager, Z. Manchester. Scalable Cooperative Transport of Cable-Suspended Loads with UAVs using Distributed Trajectory Optimization. <i>Submitted</i>. 2. T. Howell*, B. Jackson*, Z. Manchester. ALTRO: A Faster Solver for Constrained Trajectory Optimization. 2019. International Conference on Intelligent Robots and Systems. Macao, China. 3. T. Howell, B. Osting, J. Abbott. Sorting Rotating Micromachines By Variations in Their Magnetic Properties. 2018. Physical Review Applied. 4. J. Arellano, T. Howell, J. Gammon, S. Cho, M. Janat Amsbury, B. Gale. Use of a highly parallel Microfluidic Flow Cell Array to determine therapeutic drug dose response curves. 2017. Biomedical Microdevices. 5. J. Arellano, J. Gammon, T. Howell, M. Janat-Amsbury, B. Gale. A Continuous Flow Microspotter for the Implementation of a High-Throughput Drug Screening and Cytotoxicity Evaluation System. 2015. BMES Annual Meeting. 												
SKILLS	<p>Julia, Python, C++, Matlab \LaTeX, Git, Solidworks, ROS, Adobe Premiere Pro, Adobe Illustrator Mill, Lathe, Vacuum Forming, Laser Cutting, Mold Making and Casting, Metal Sheet Fabrication</p>												
COURSEWORK AT STANFORD	<p>Convex Optimization EE364a, Optimal Control AA203, Nonlinear Control AA209, State Estimation AA273, Principles of Robotic Autonomy AA274, Mechatronics ME210, Linear Dynamical Systems EE 263, Introduction to Robotics ME320, Machine Learning CS229, Decision Making Under Uncertainty AA228, Control Design Techniques E205, Advanced Robotic Manipulation CS326, Advanced Feedback Control AA212, Optimization MS&E 211X, Experimental Robotics CS225a</p>												
FELLOWSHIPS AND SCHOLARSHIPS	<table> <tr> <td>Stanford Graduate Fellowship</td><td>2017 – 2018</td></tr> <tr> <td>University of Utah Undergraduate Research Opportunities Program Fellowship</td><td>2016</td></tr> <tr> <td>The Boeing Company Scholarship</td><td>2016</td></tr> <tr> <td>Shirley L. & Kathelyne O. Evans Endowed Scholarship</td><td>2016</td></tr> <tr> <td>Big Ten+ Grad Expo travel scholarship</td><td>2016</td></tr> <tr> <td>University of Utah Presidential Scholarship</td><td>2013 – 2016</td></tr> </table>	Stanford Graduate Fellowship	2017 – 2018	University of Utah Undergraduate Research Opportunities Program Fellowship	2016	The Boeing Company Scholarship	2016	Shirley L. & Kathelyne O. Evans Endowed Scholarship	2016	Big Ten+ Grad Expo travel scholarship	2016	University of Utah Presidential Scholarship	2013 – 2016
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