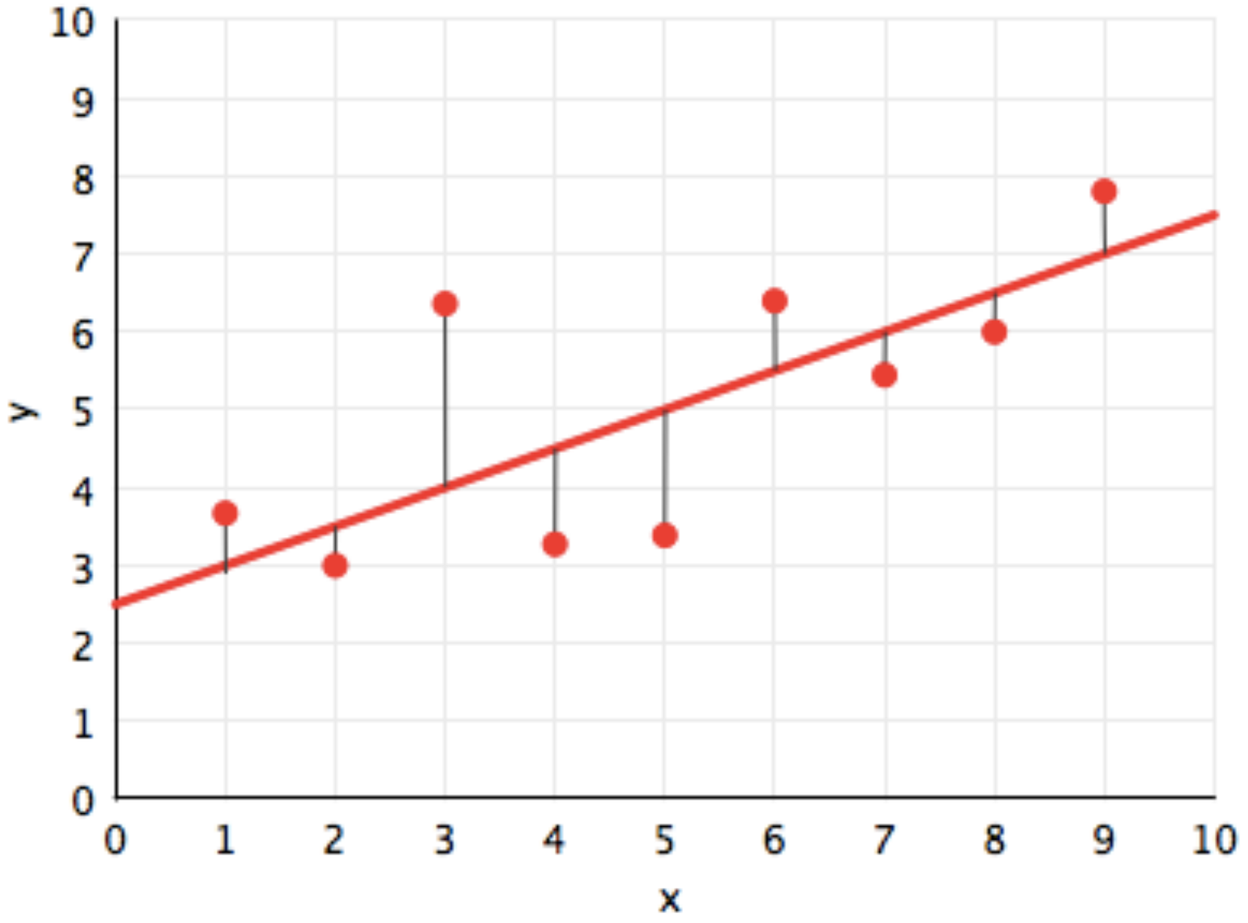
Day 1 Session 2

Learning a Model

Complexity, Validation, and Regularization



RISK: What does it mean to FIT?

Minimize distance from the line?

$$R_{\mathcal{D}}(h_1(x)) = \frac{1}{N}\sum_{y_i \in \mathcal{D}}(y_i - h_1(x_i))^2$$

Minimize squared distance from the line.
Empirical Risk Minimization.

$$g_1(x) = \arg\min_{h_1(x)\in\mathcal{H}} R_{\mathcal{D}}(h_1(x)).$$

Get intercept w_0 and slope w_1.

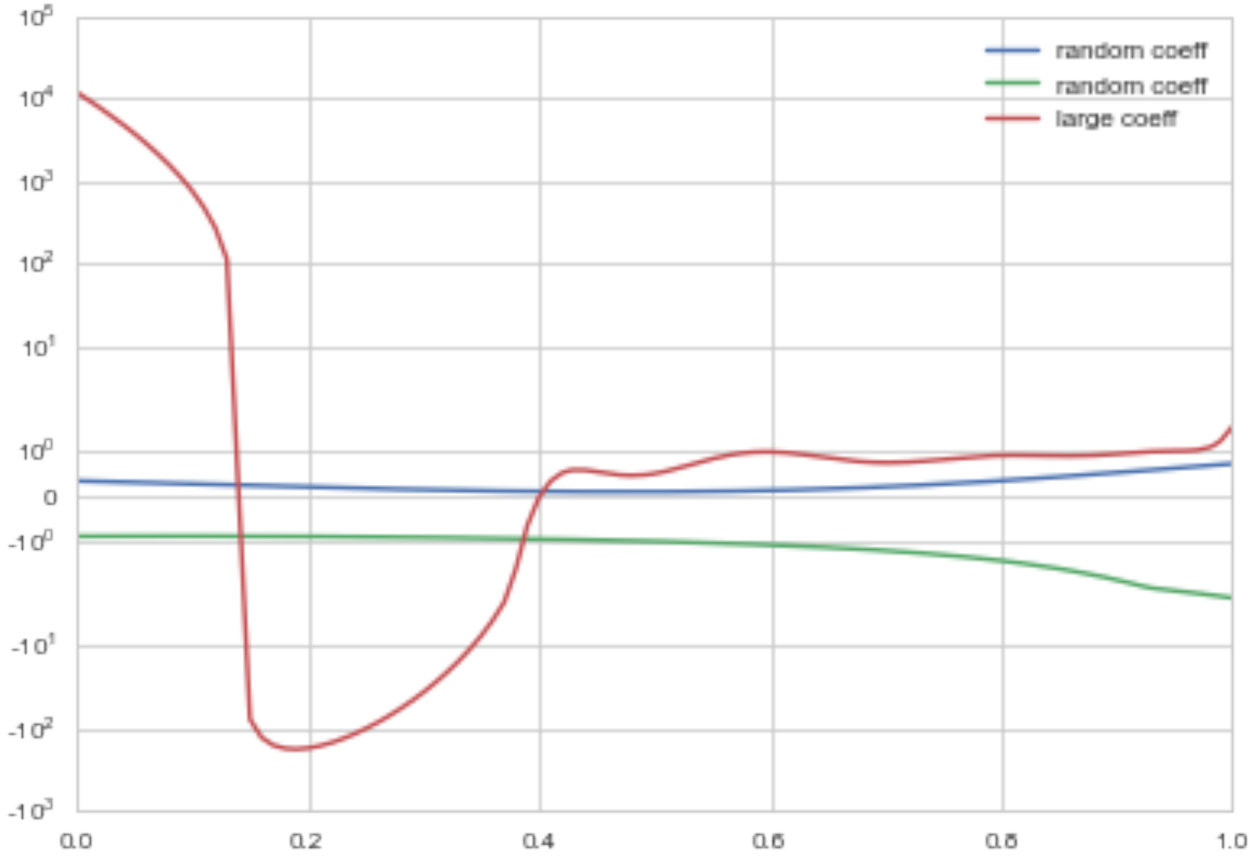
HYPOTHESIS SPACES

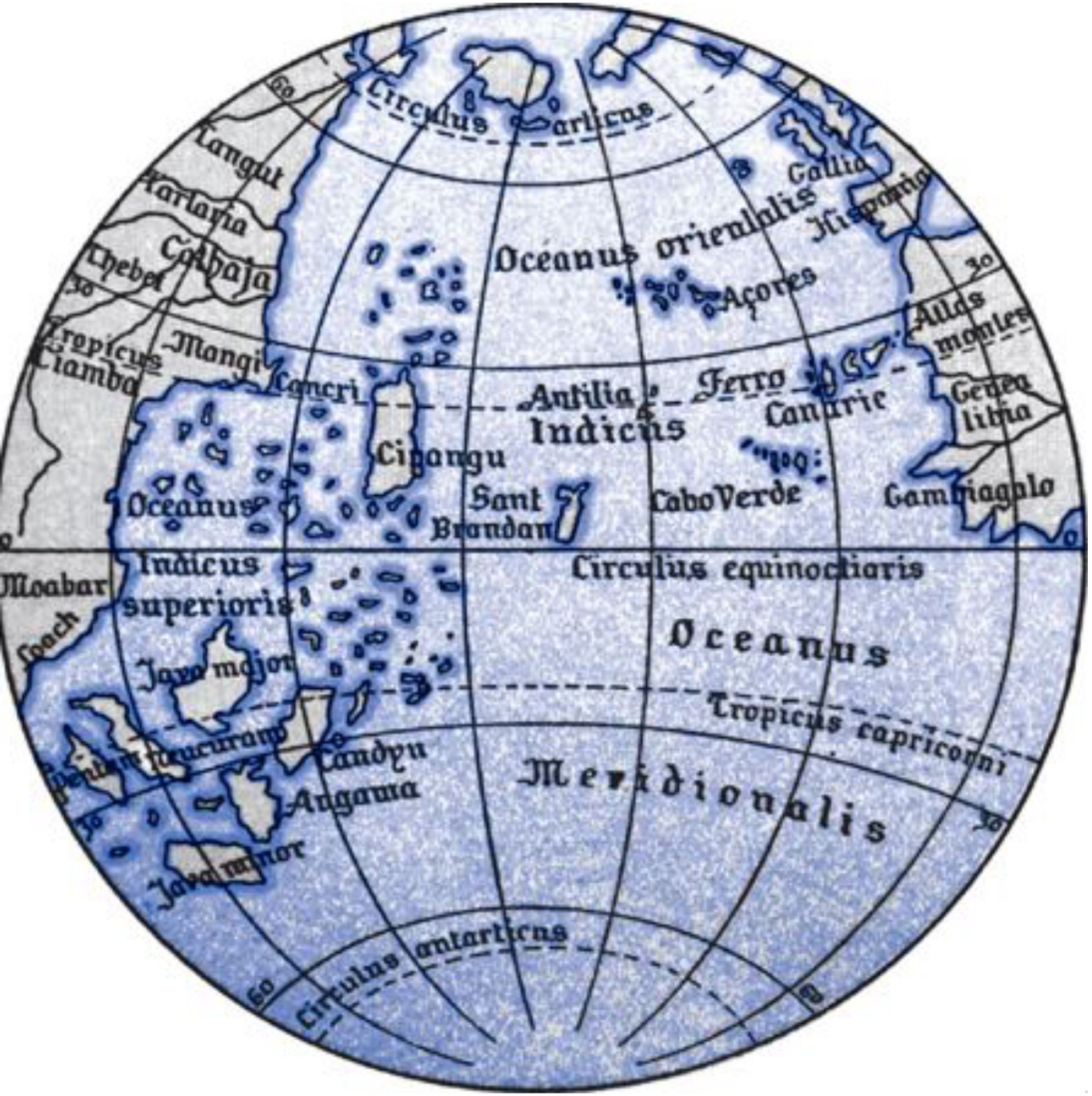
A polynomial looks so:

$$h(x) = \theta_0 + \theta_1 x^1 + \theta_2 x^2 + \ldots + \theta_n x^n = \sum_{i=0}^{n} \theta_i x^i$$

All polynomials of a degree or complexity d constitute a hypothesis space.

$$\mathcal{H}_1 : h_1(x) = \theta_0 + \theta_1 x$$
$$\mathcal{H}_{20} : h_{20}(x) = \sum_{i=0}^{20} \theta_i x^i$$



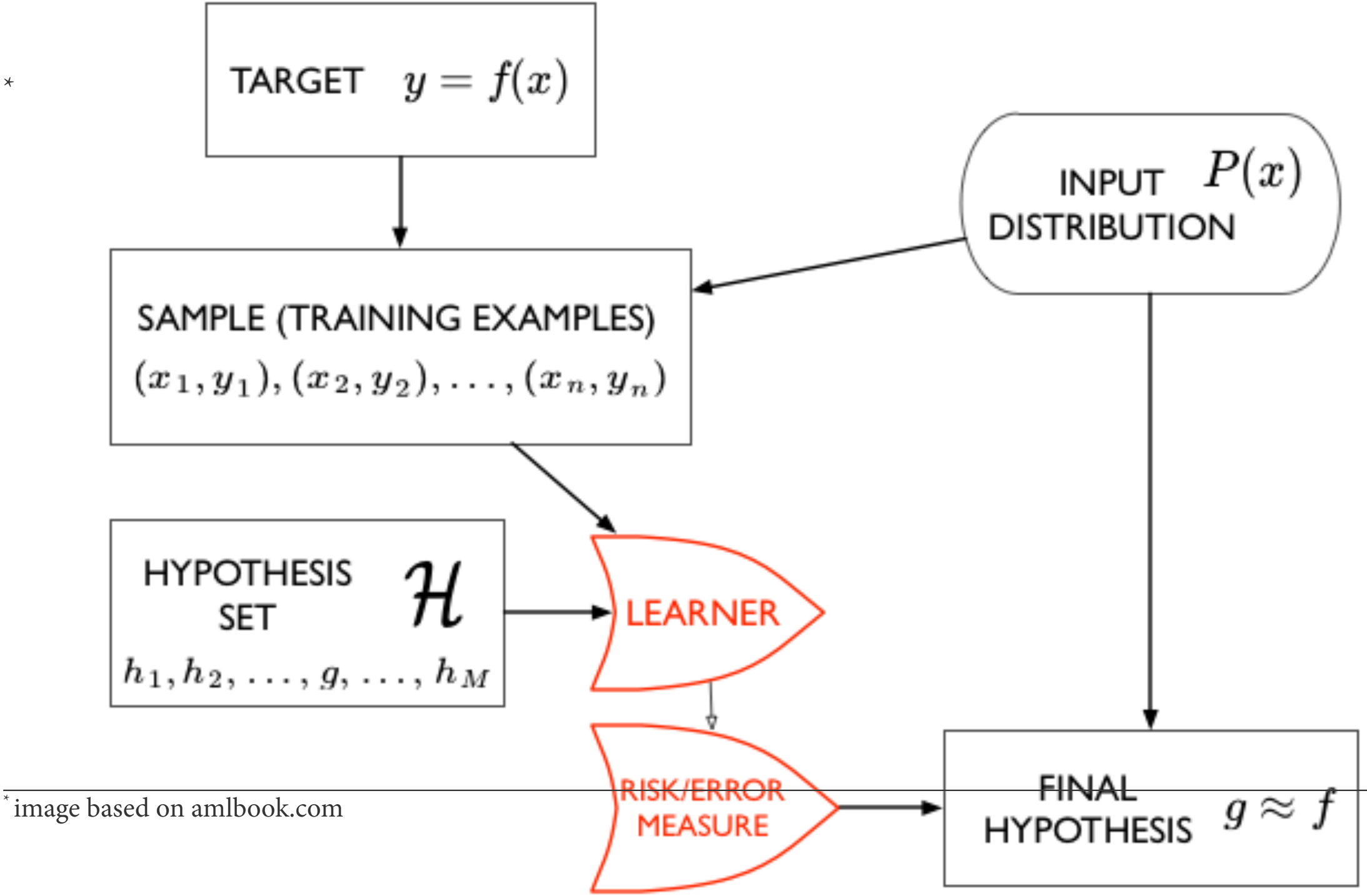


SMALL World vs BIG World

- *Small World* answers the question: given a model class (i.e. a Hypothesis space, whats the best model in it). It involves parameters. Its model checking.
- *BIG World* compares model spaces. Its model comparison with or without "hyperparameters".

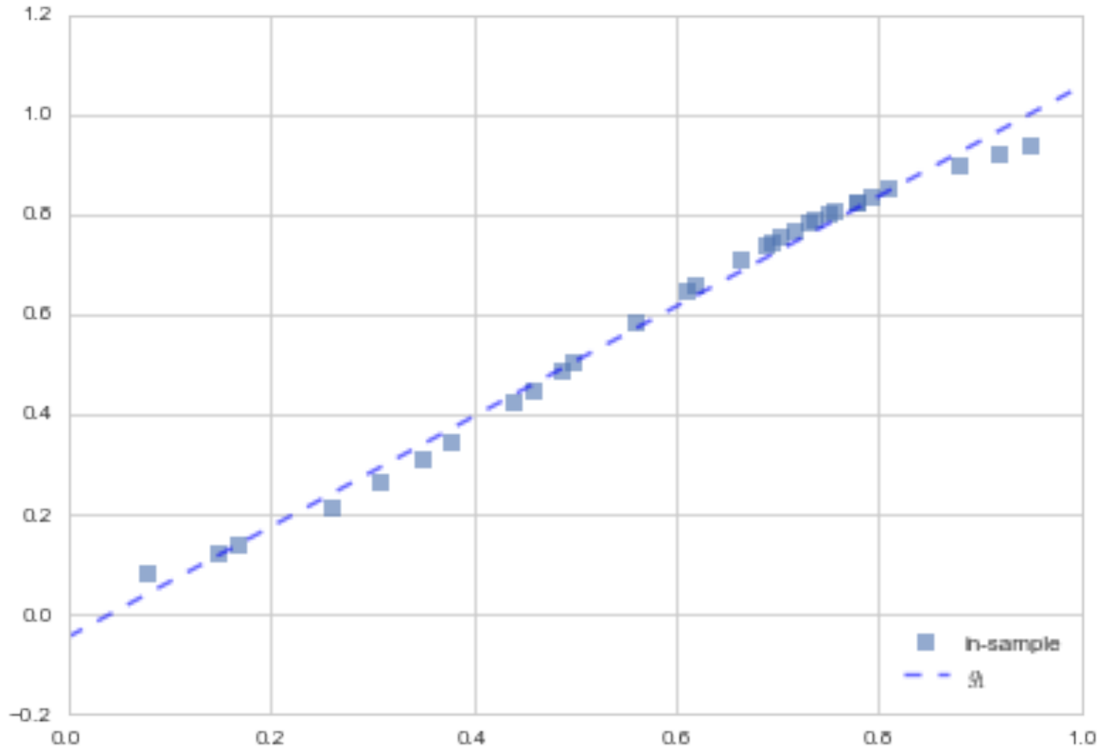
Approximation

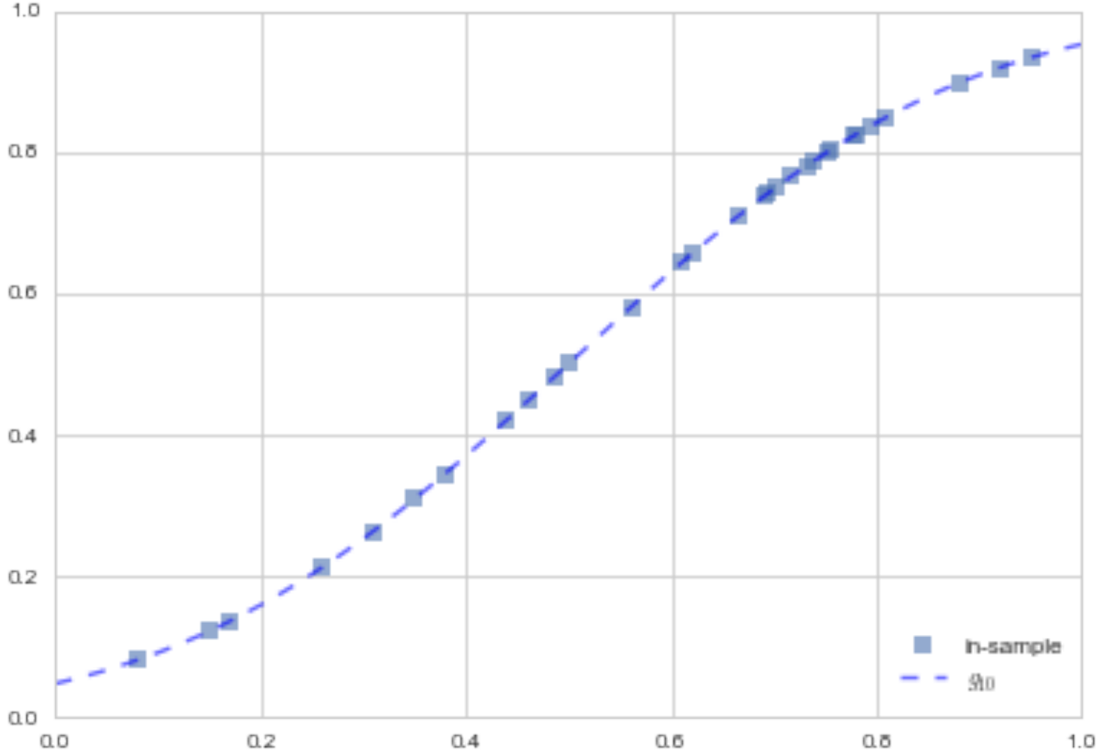
Learning Without Noise...



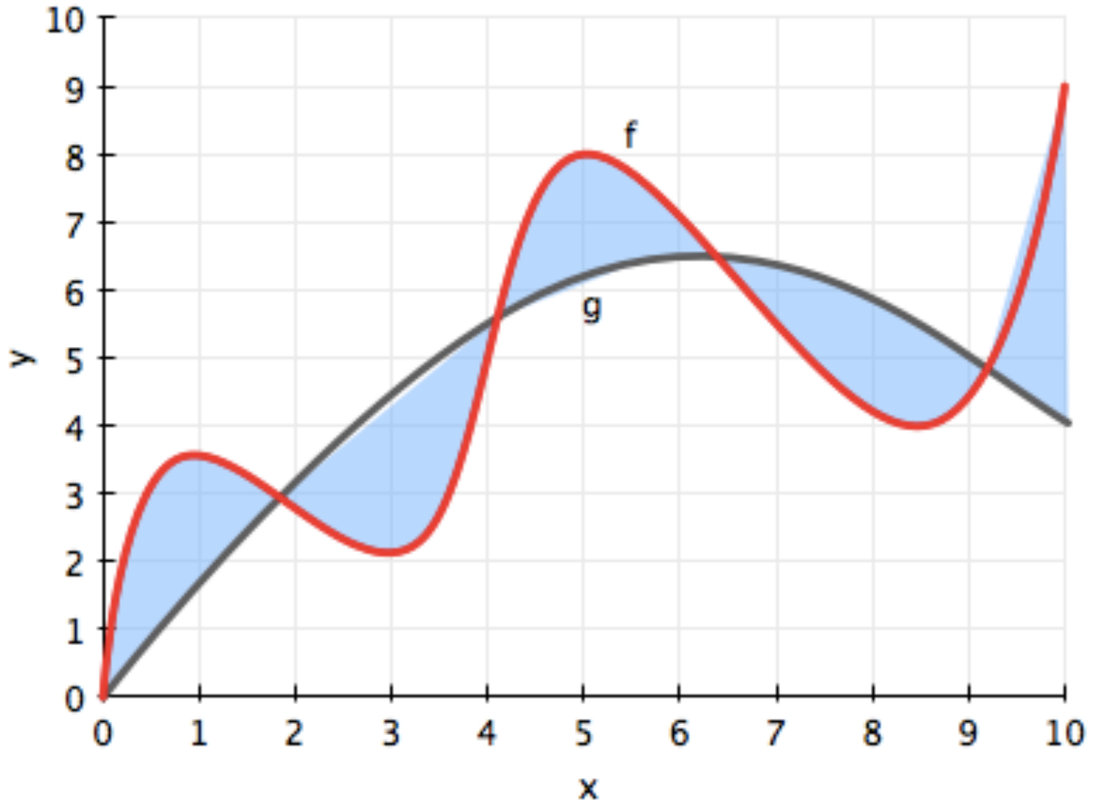
* image based on amlbook.com

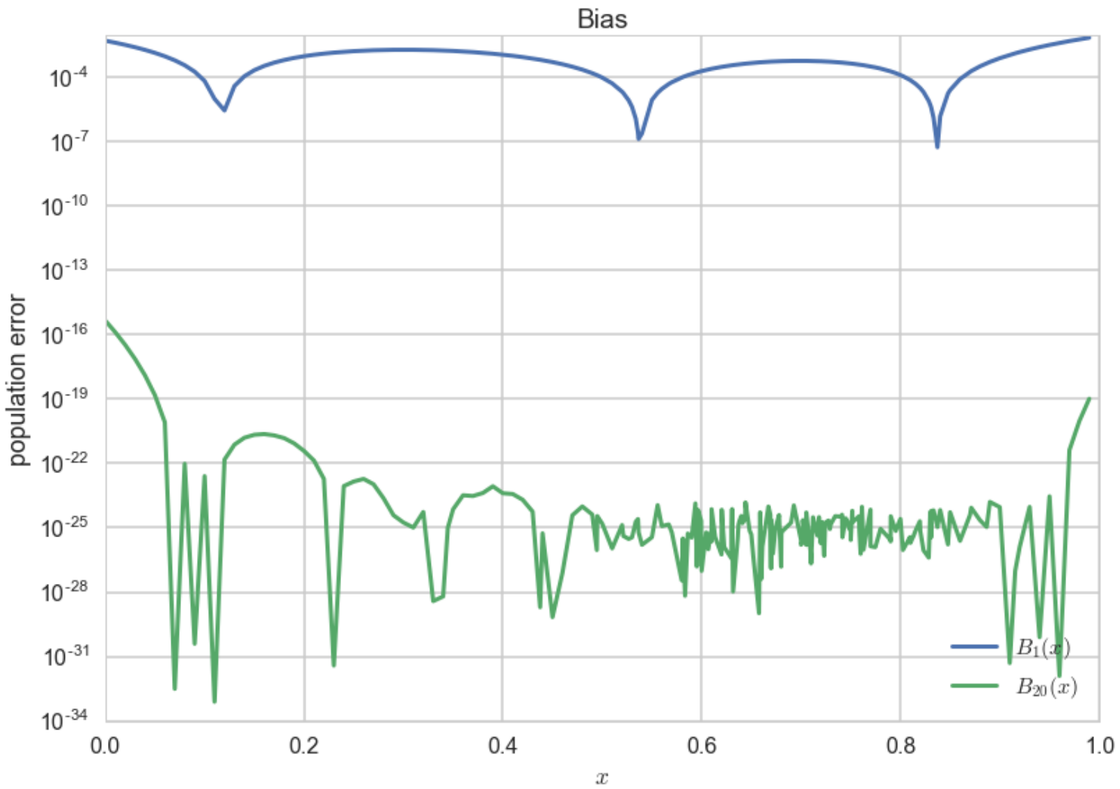
30 points of data. Which fit is better? Line in $\mathcal{H}_1$ or curve in $\mathcal{H}_{20}$?





Bias or Mis-specification Error





Sources of Variability

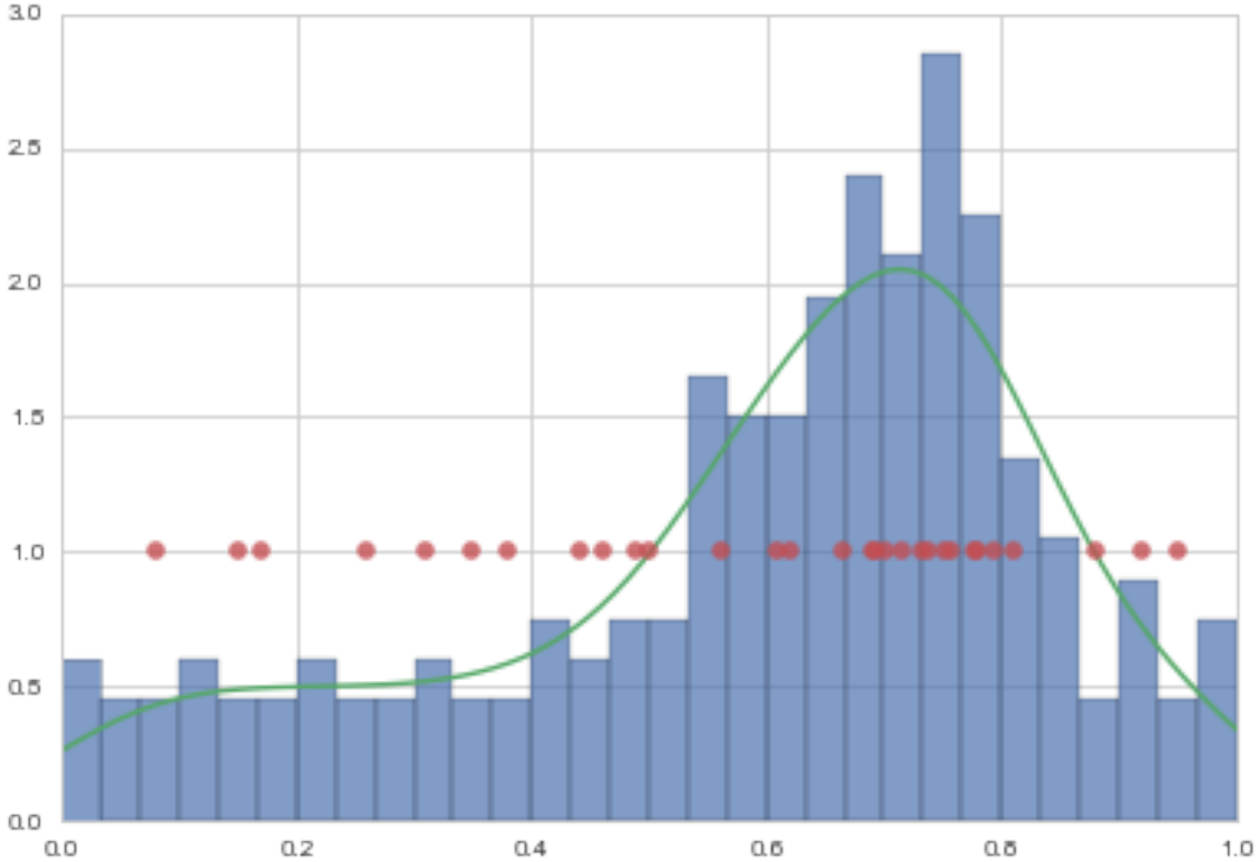
- sampling (induces variation in a mis-specified model)
- noise (the true $p(y|x)$)
- mis-specification

What is noise?

- noise comes from measurement error, missing features, etc
- sometimes it can be systematic as well, but its mostly random on account of being a combination of many small things...

THE REAL WORLD HAS NOISE

(or finite samples, usually both)



Statement of the Learning Problem

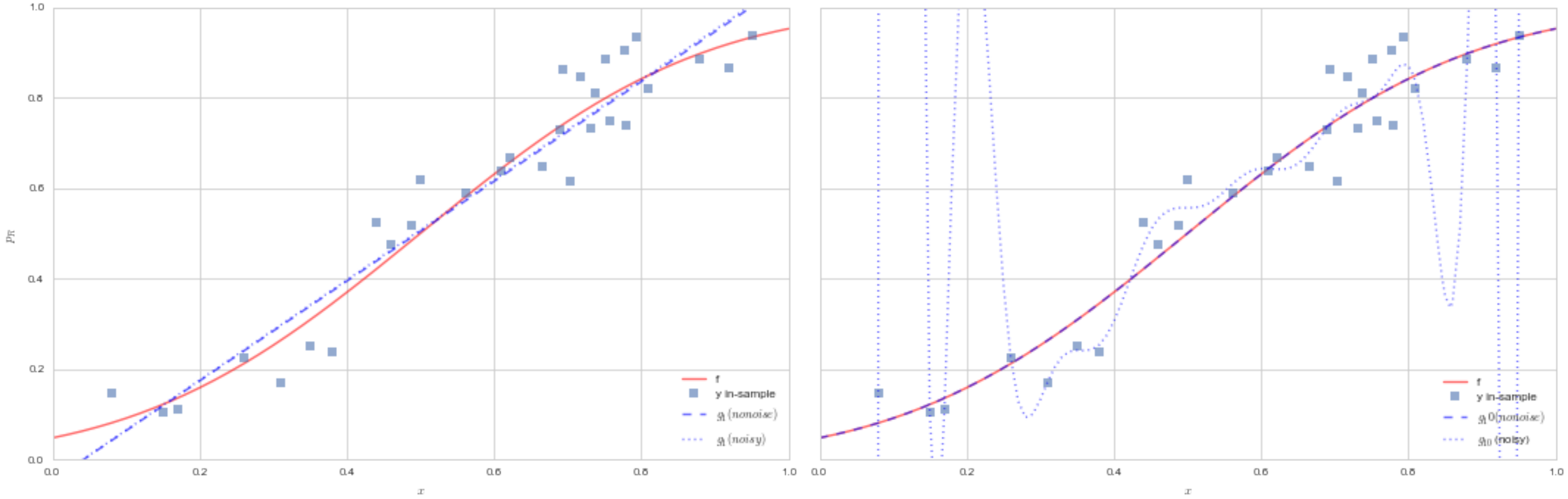
The sample must be representative of the population!

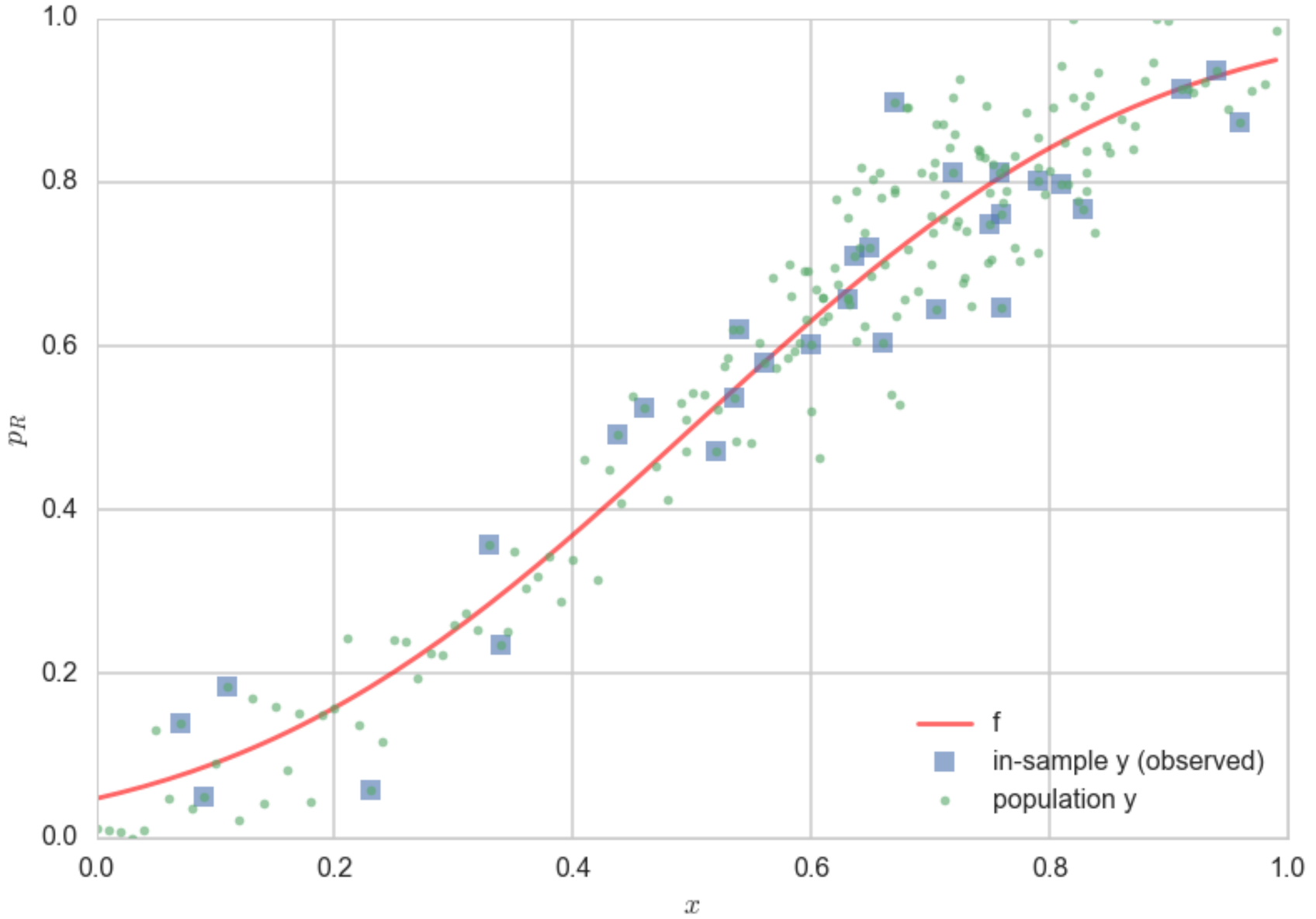
$A : R_{\mathcal{D}}(g) \ \ smallest\, on\, \mathcal{H}$
$B : R_{out}(g) \approx R_{\mathcal{D}}(g)$

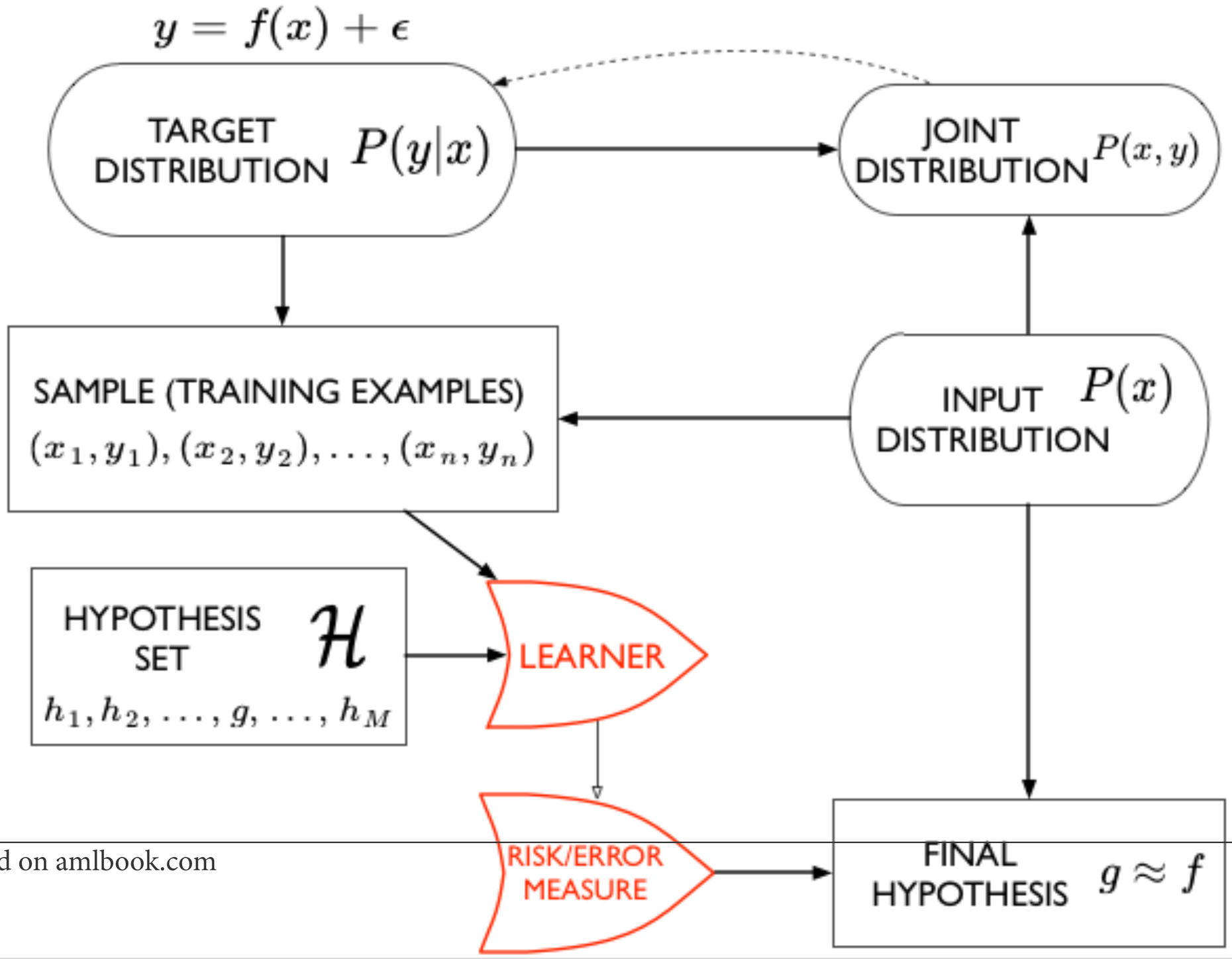
A: Empirical risk estimates in-sample risk.
B: Thus the out of sample risk is also small.

Which fit is better now?

The line or the curve?




1.0
0.8
0.6
0.4
0.2
0.0
p_R
0.0
0.2
0.4
0.6
0.8
1.0
x
f
in-sample y (observed)
population y

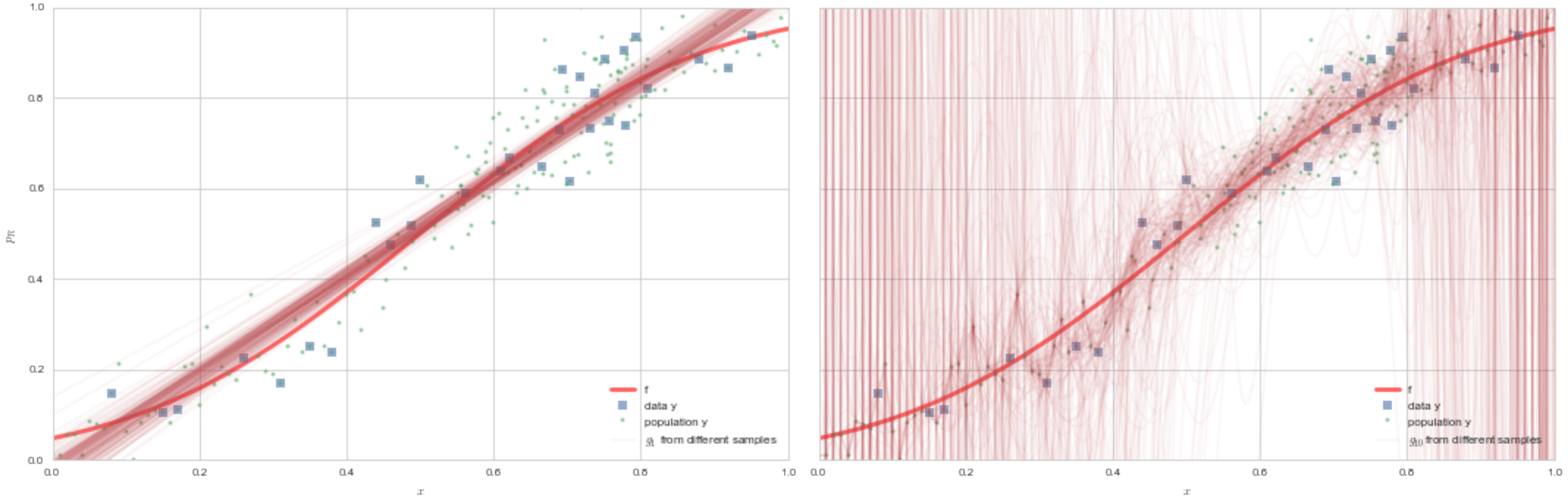


* image based on amlbook.com

Training sets

- look at fits on different "training sets $\mathcal{D}$"
- in other words, different samples
- in real life we are not so lucky, usually we get only one sample
- but lets pretend, shall we?

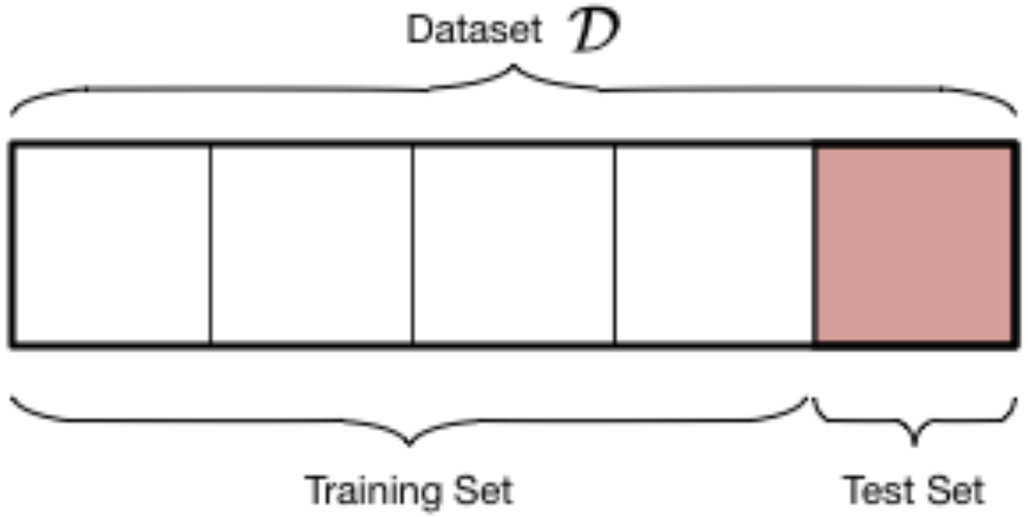
UNDERFITTING (Bias) vs OVERFITTING (Variance)

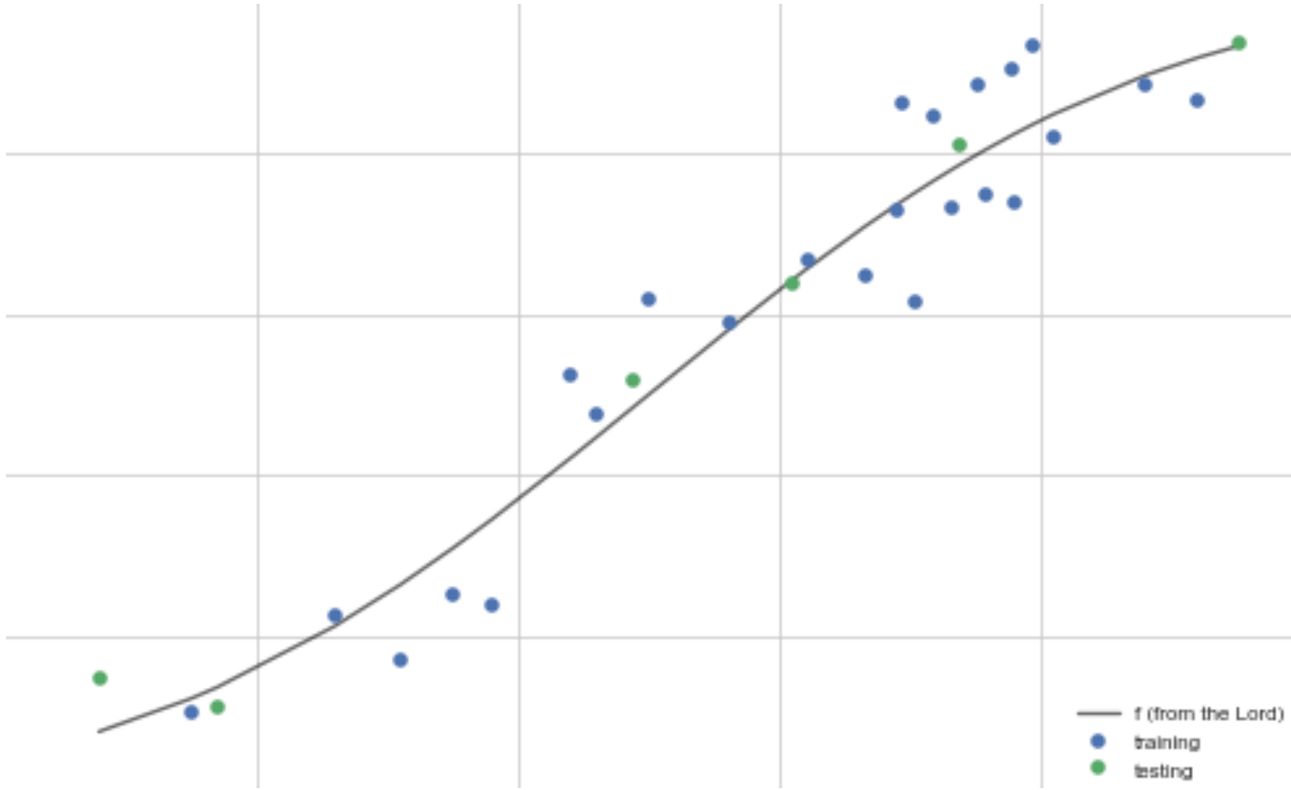


How do we estimate

out-of-sample or population error R_{out}

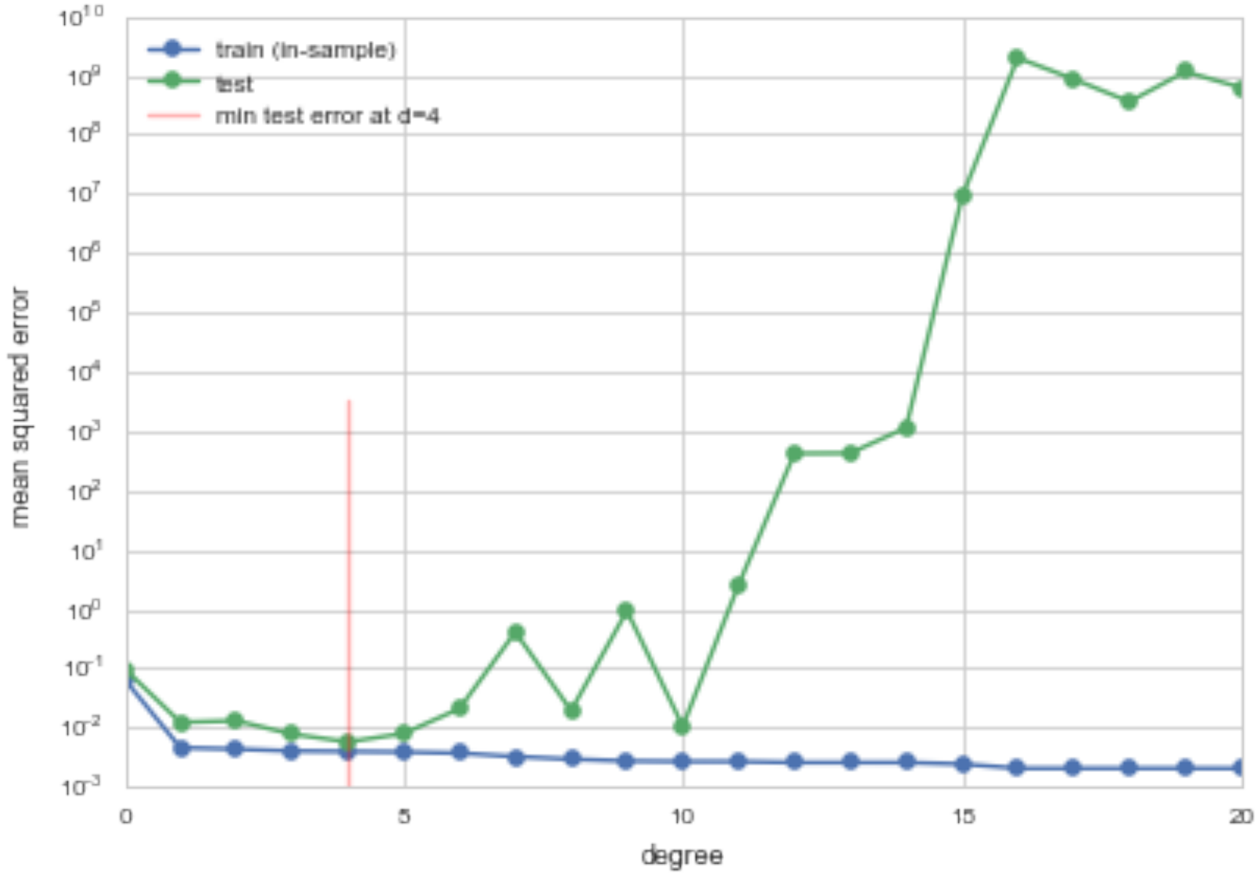
TRAIN AND TEST



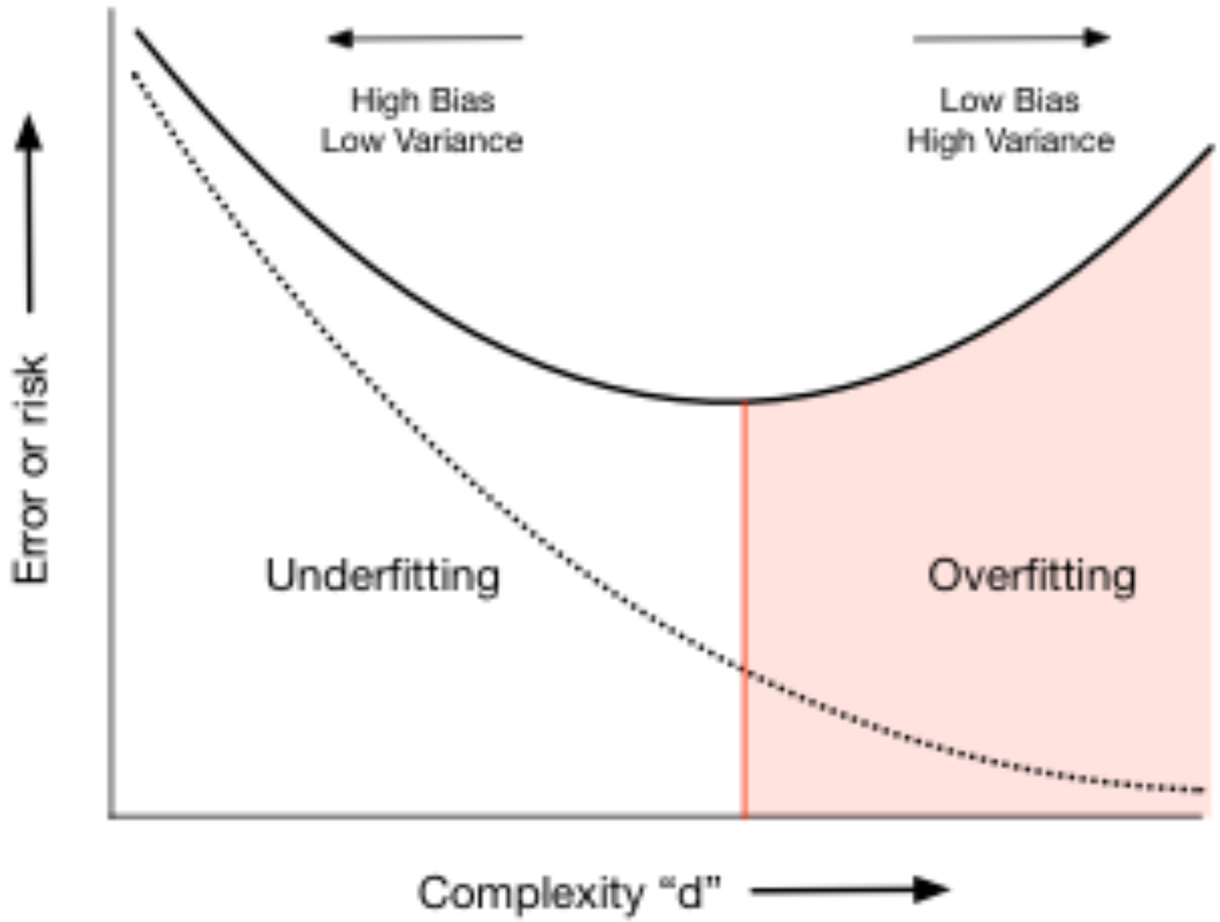


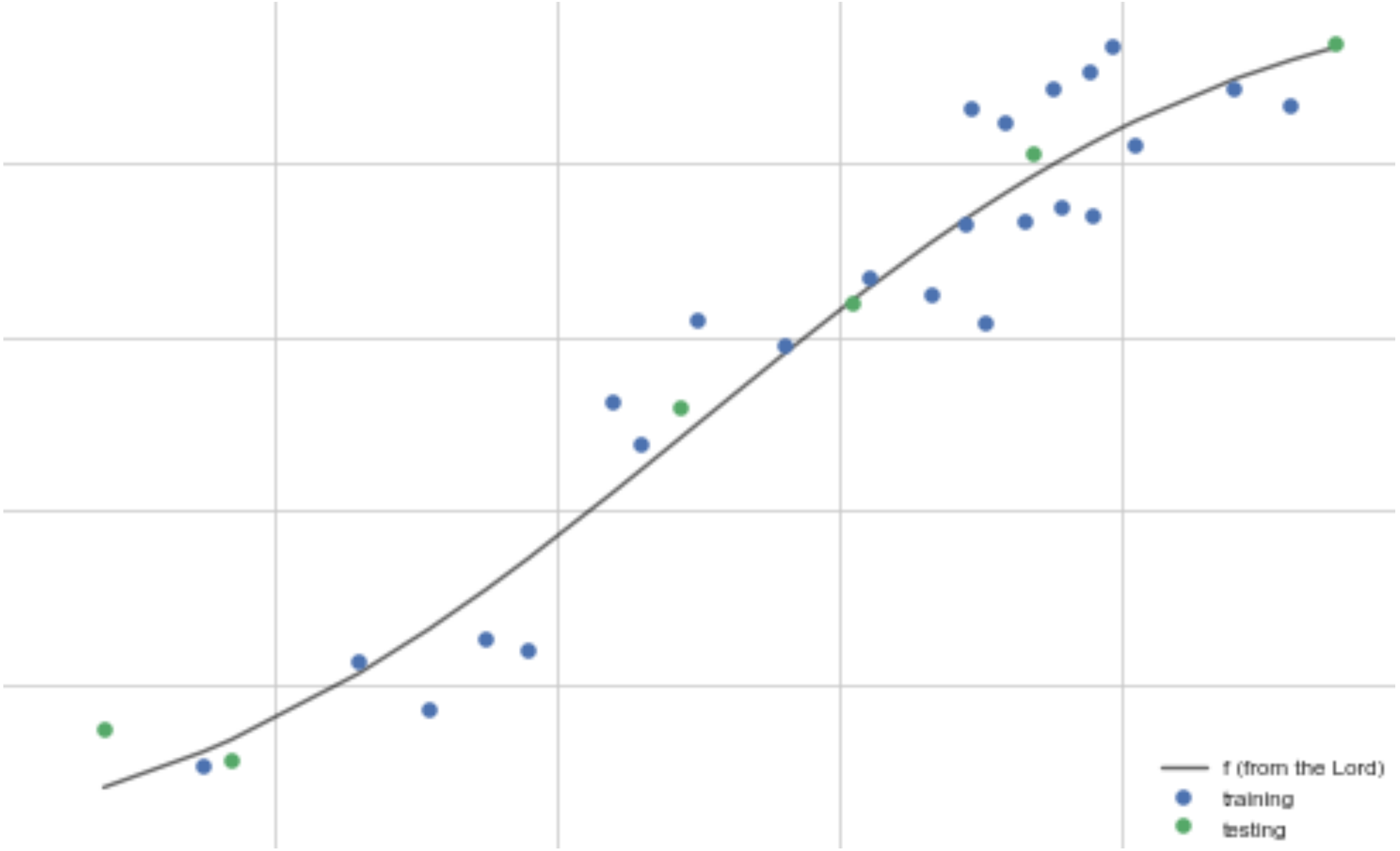
MODEL COMPARISON: A Large World approach

- want to choose which Hypothesis set is best
- it should be the one that minimizes risk
- but minimizing the training risk tells us nothing: interpolation
- we need to minimize the training risk but not at the cost of generalization
- thus only minimize till test set risk starts going up

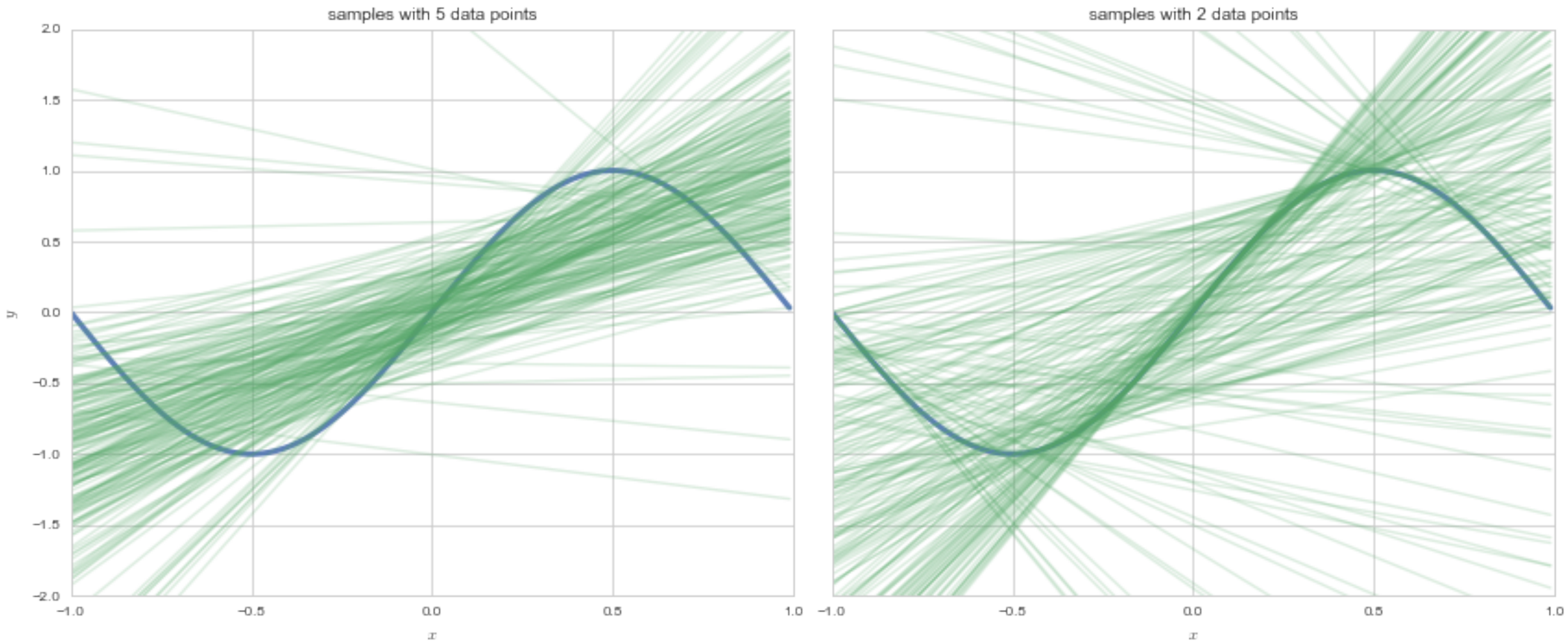


Complexity Plot




f (from the Lord)
training
testing

DATA SIZE MATTERS: straight line fits to a sine curve



Corollary: Must fit simpler models to less data! This will motivate the analysis of learning curves later.

Do we still have a test set?

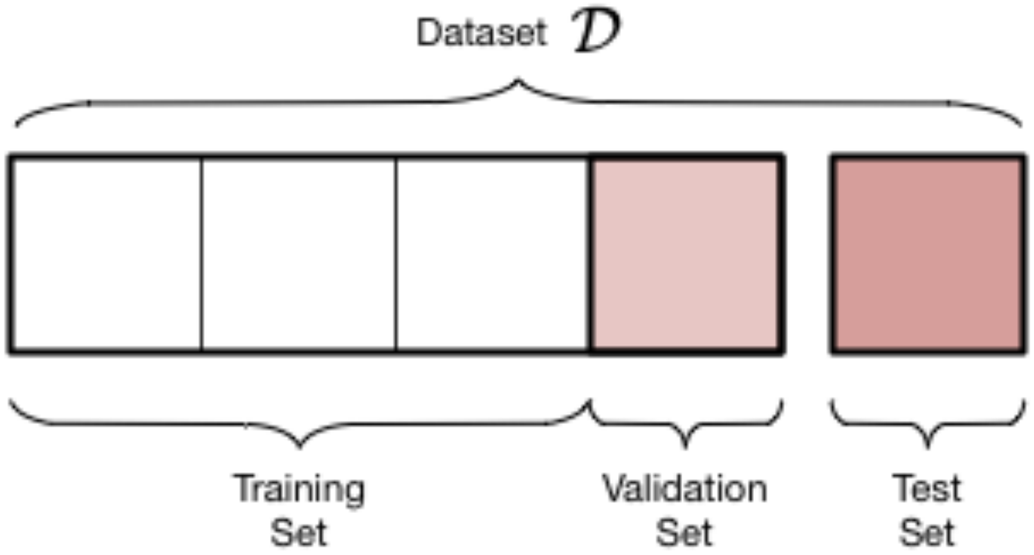
Trouble:

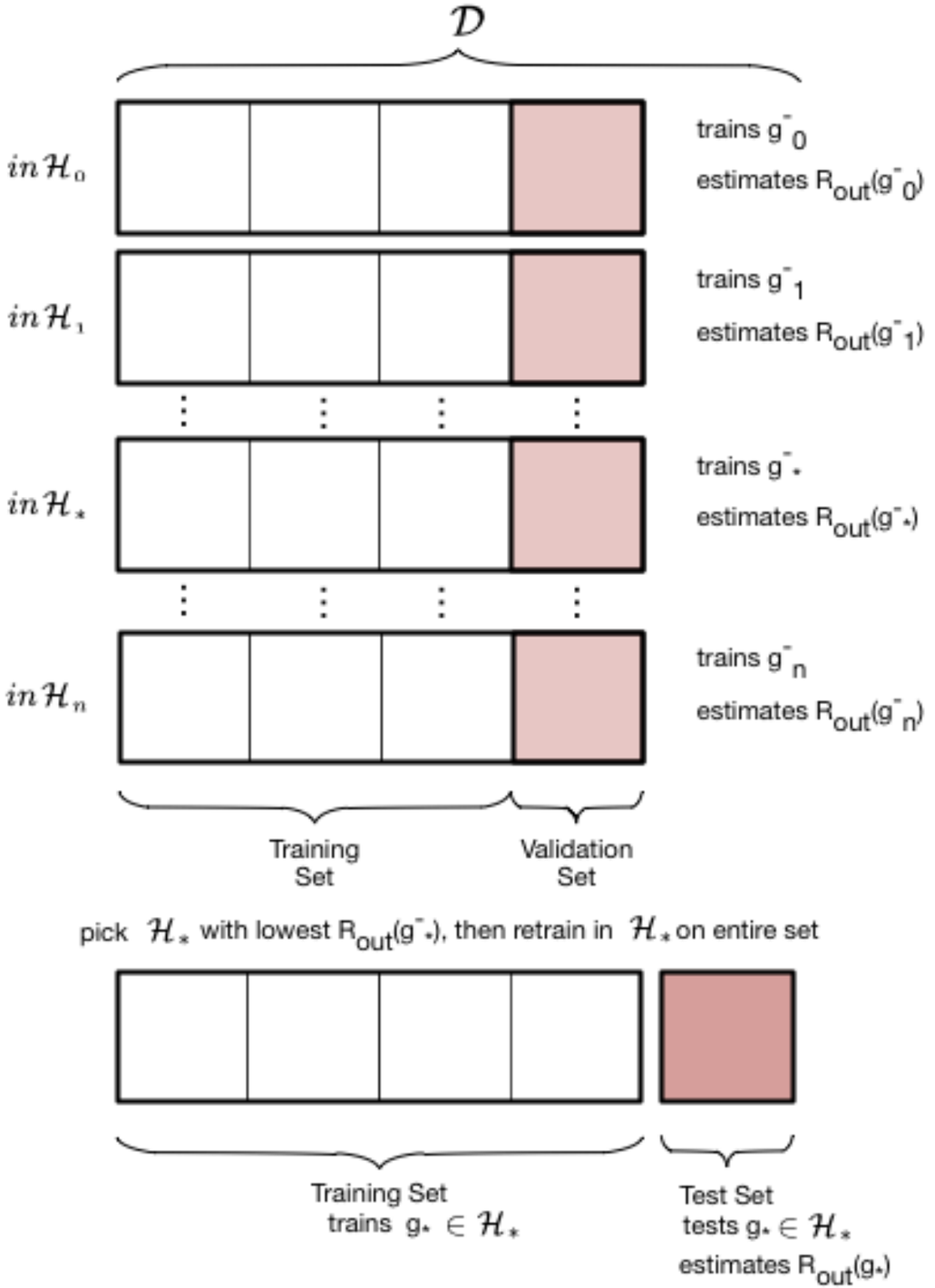
- no discussion on the error bars on our error estimates
- "visually fitting" a value of $d \implies$ contaminated test set.

The moment we **use it in the learning process, it is not a test set**.

VALIDATION

- train-test not enough as we *fit* for d on test set and contaminate it
- thus do train-validate-test





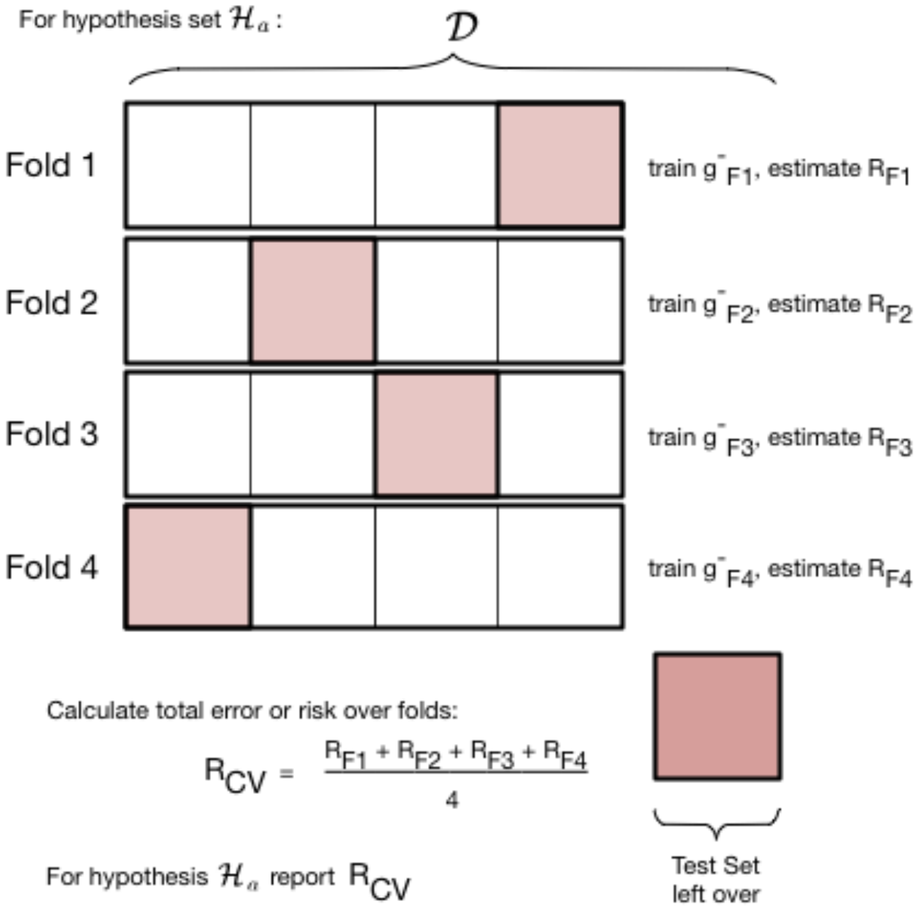
usually we want to fit a hyperparameter

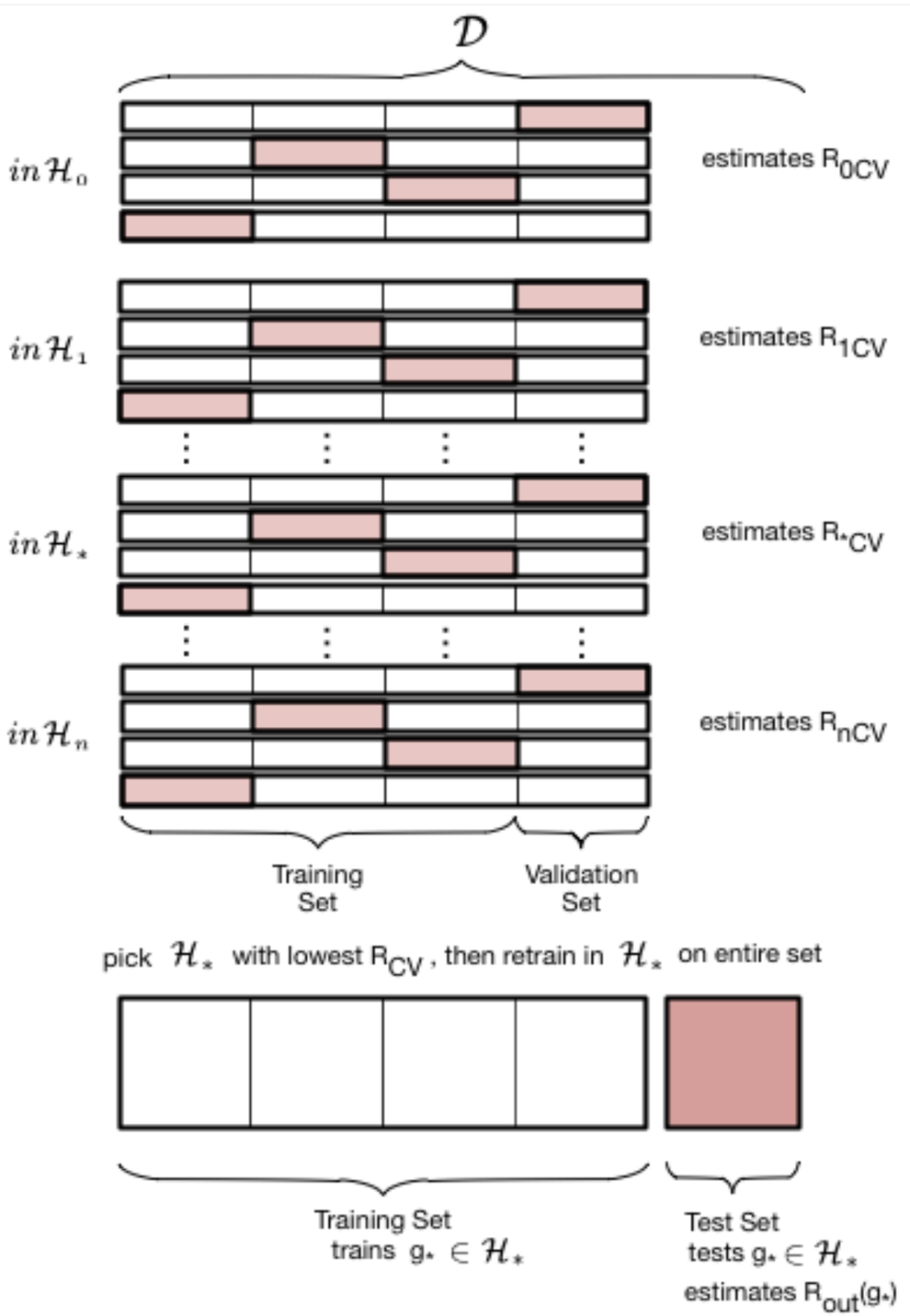
- we **wrongly** already attempted to fit d on our previous test set.
- choose the d, g^{-*} combination with the lowest validation set risk.
- $R_{val}\left(g^{-*}, d^{*}\right)$ has an optimistic bias since d effectively fit on validation set

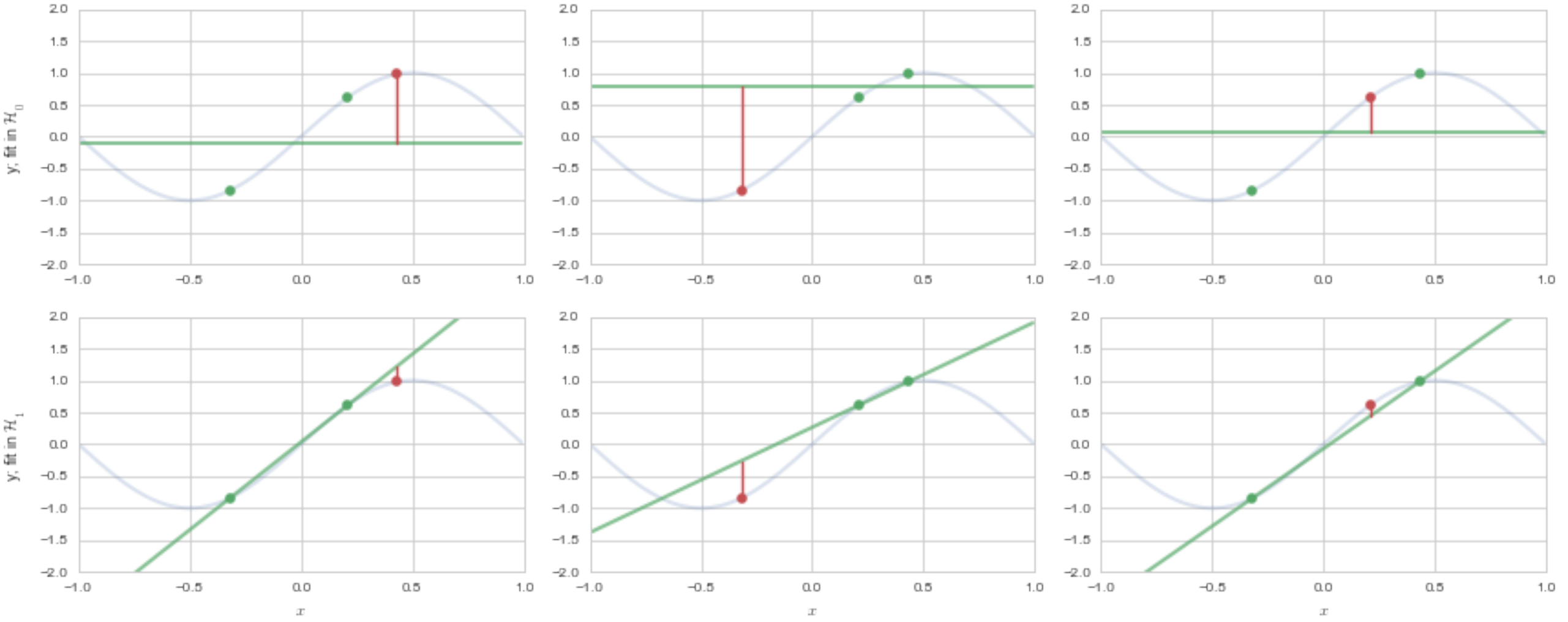
Then Retrain on entire set!

- finally retrain on the entire train+validation set using the appropriate d^{*}
- works as training for a given hypothesis space with more data typically reduces the risk even further.

CROSS-VALIDATION





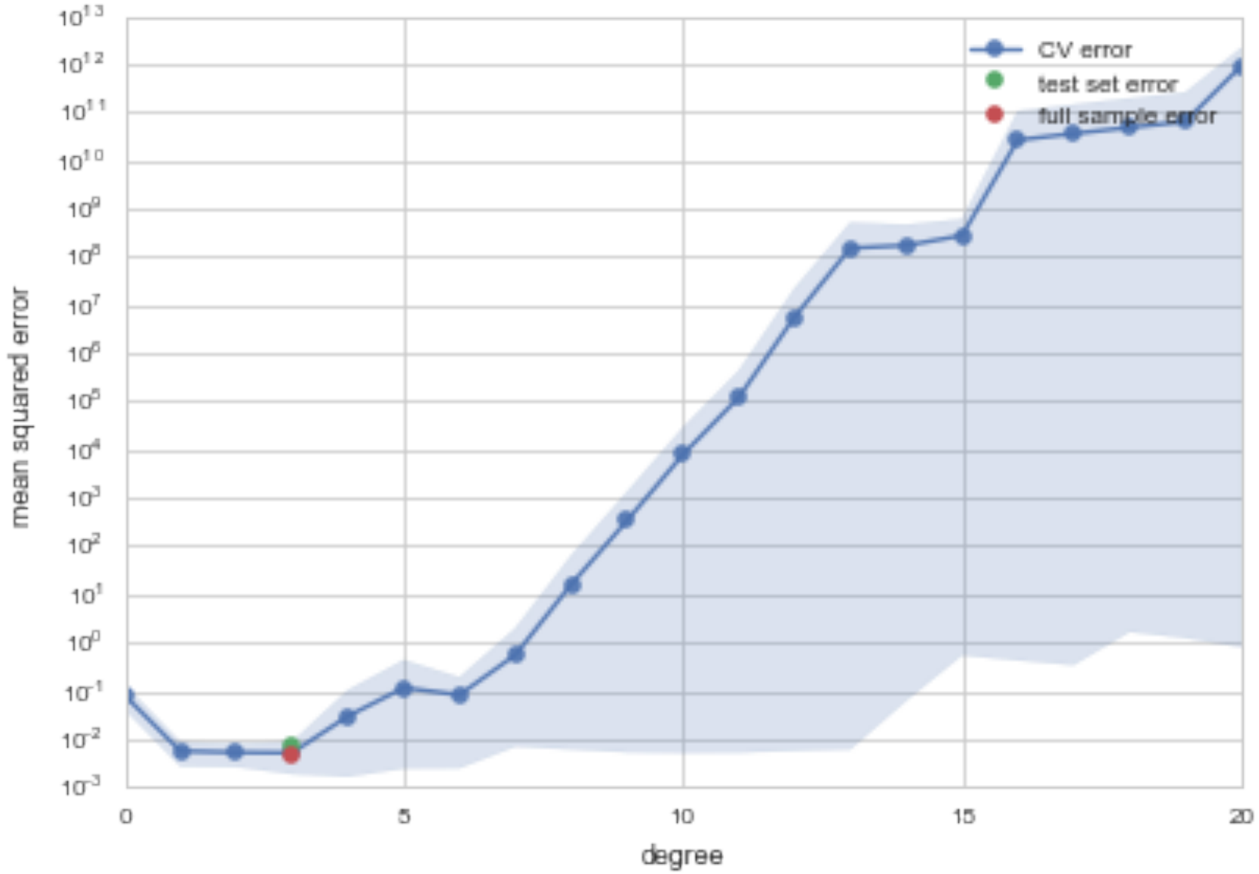

y; fit in $\mathcal{H}_0$
y; fit in $\mathcal{H}_1$
2.0
1.5
1.0
0.5
0.0
−0.5
−1.0
−1.5
−2.0
−1.0
−0.5
0.0
0.5
1.0
x

CROSS-VALIDATION

is

- a resampling method
- robust to outlier validation set
- allows for larger training sets
- allows for error estimates

Here we find $d = 3$.



Cross Validation considerations

- validation process as one that estimates R_{out} directly, on the validation set. It's critical use is in the model selection process.
- once you do that you can estimate R_{out} using the test set as usual, but now you have also got the benefit of a robust average and error bars.
- key subtlety: in the risk averaging process, you are actually averaging over different g^{-} models, with different parameters.

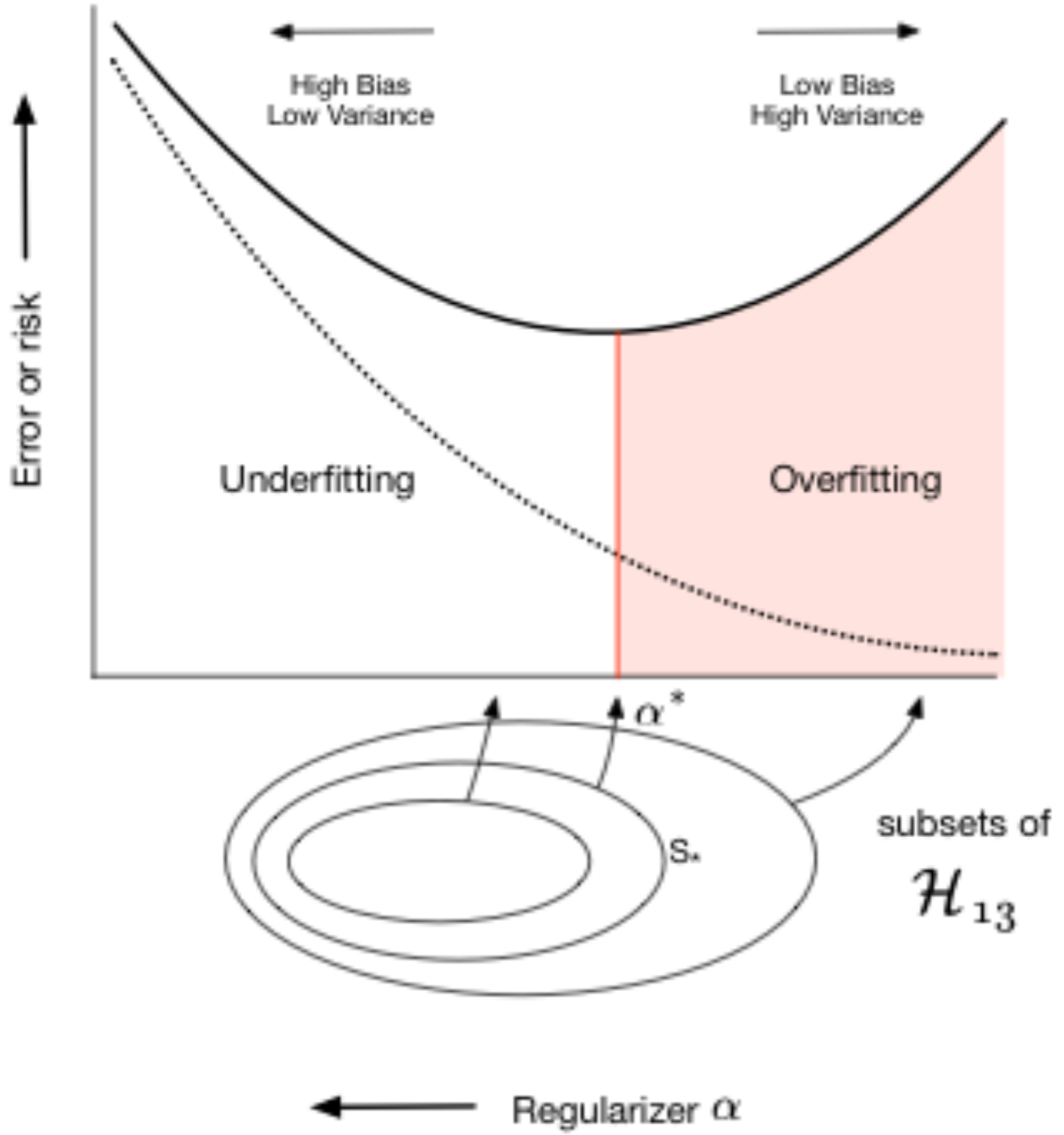
REGULARIZATION: A SMALL WORLD APPROACH

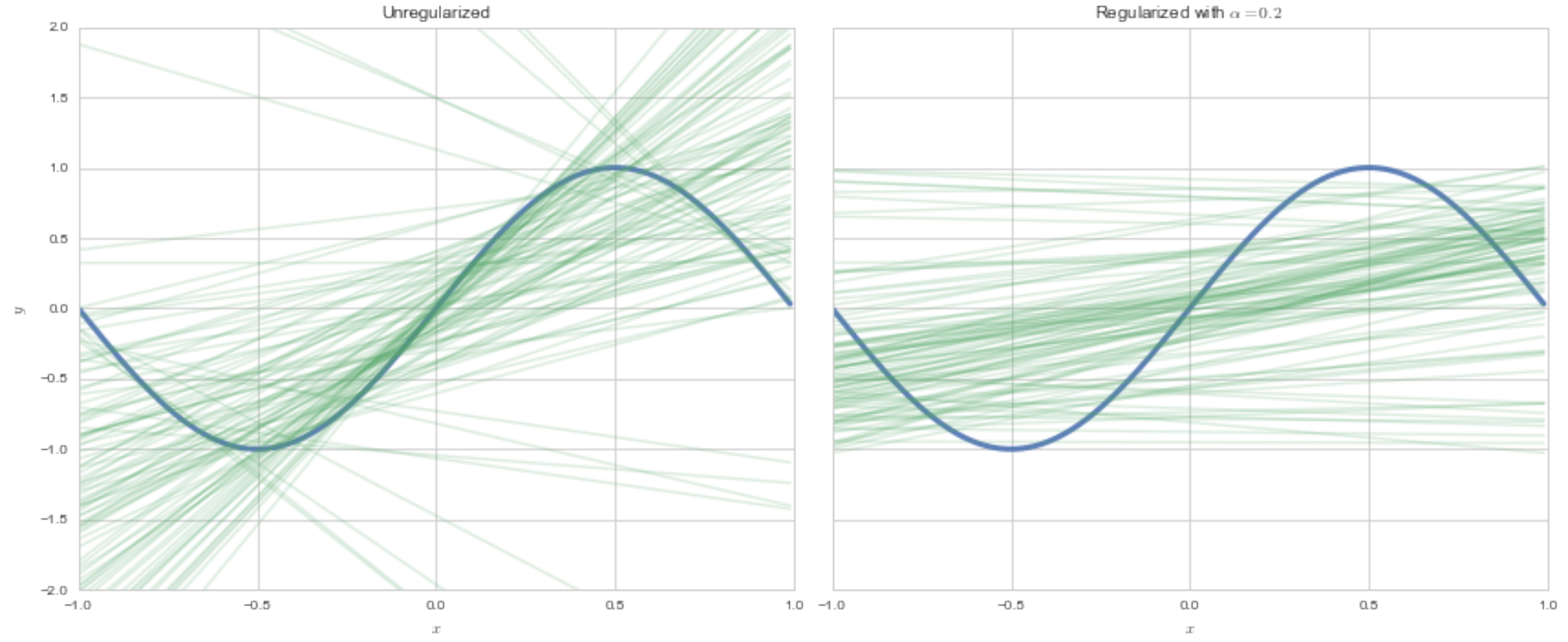
Keep higher a-priori complexity and impose a

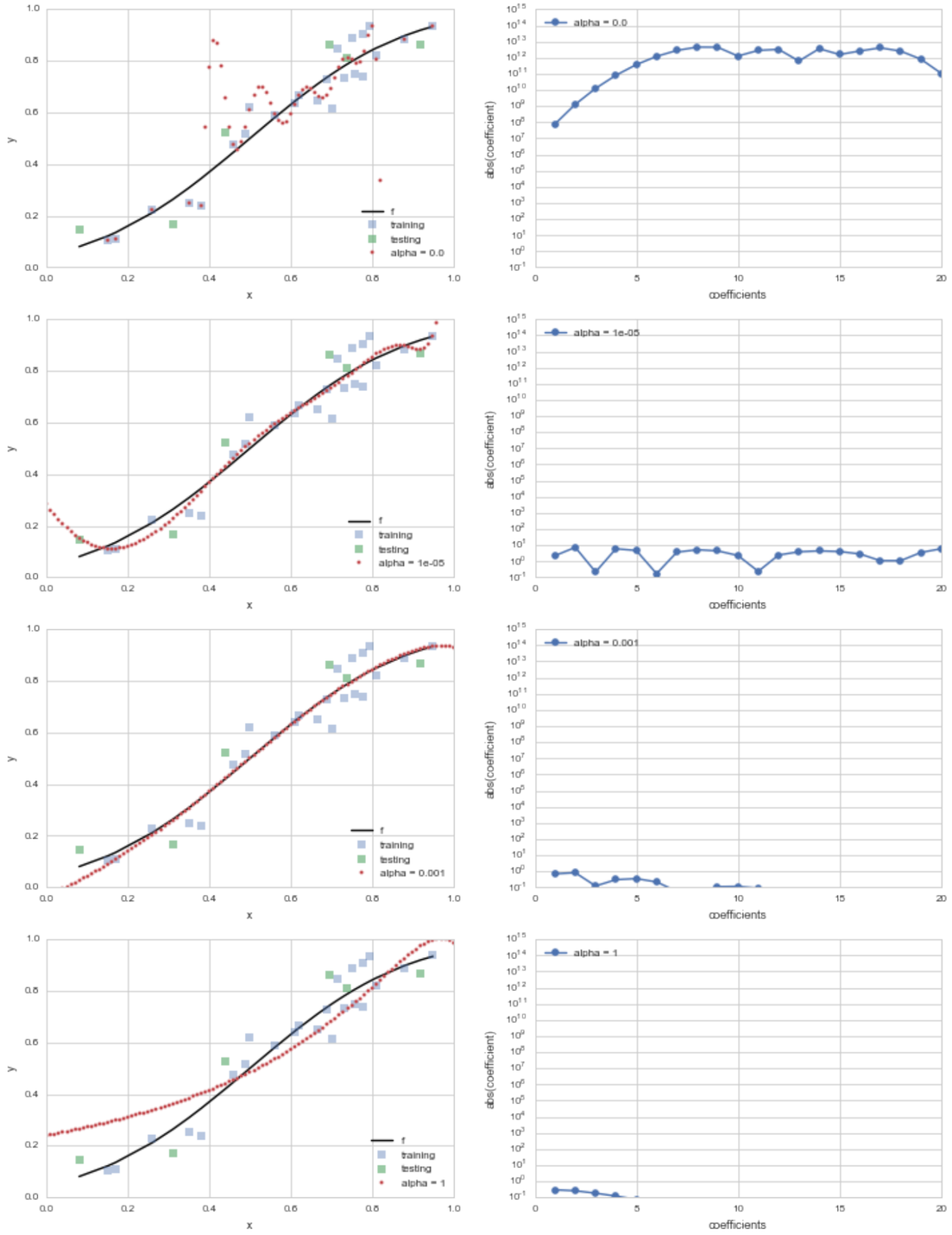
complexity penalty

on risk instead, to choose a SUBSET of $\mathcal{H}_{big}$.
We'll make the coefficients small:

$$\sum_{i=0}^{j} \theta_i^2 < C.$$




Unregularized
Regularized with $\alpha = 0.2$
2.0
1.5
1.0
0.5
0.0
−0.5
−1.0
−1.5
−2.0
y
−1.0
−0.5
0.0
0.5
1.0
x



REGULARIZATION

$$\mathcal{R}(h_j) = \sum_{y_i \in \mathcal{D}} (y_i - h_j(x_i))^2 + \alpha \sum_{i=0}^{j} \theta_i^2.$$

As we increase α, coefficients go towards 0.

Lasso uses $\alpha \sum_{i=0}^{j} |\theta_i|$, sets coefficients to exactly 0.

Regularization with Cross-Validation