# ReadMe- Quad Copter Motor Control

## Release V1.0

* Bug Fix: I2C.c write was updated so that it implements a data put after we send the START instead of sending the slave address set command.
* Bug Fix : Set Normal mode for CTRL1 in Gyro so that our ODR (Read on x,y,z) values updated
* [Reference for I2C](https://eewiki.net/display/microcontroller/I2C+Communication+with+the+TI+Tiva+TM4C123GXL#I2CCommunicationwiththeTITivaTM4C123GXL-ExampleofGenericI2CCommunications)
* Adding Gyroscope Class
* Added ADXL345 preliminary class. This is functioning but not complete
* Added I2C Module. Not fully integrated with multiple I2C modules