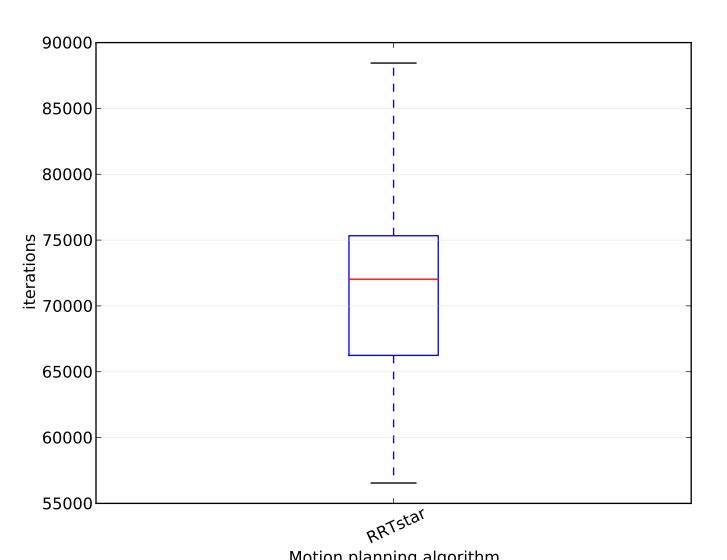
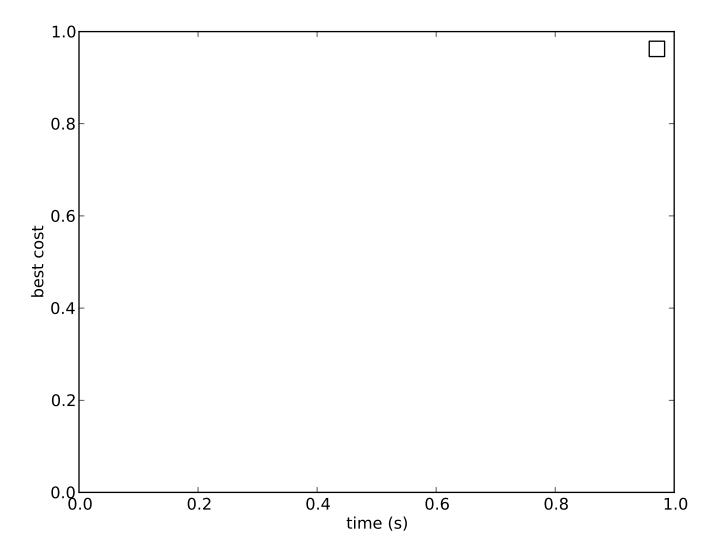
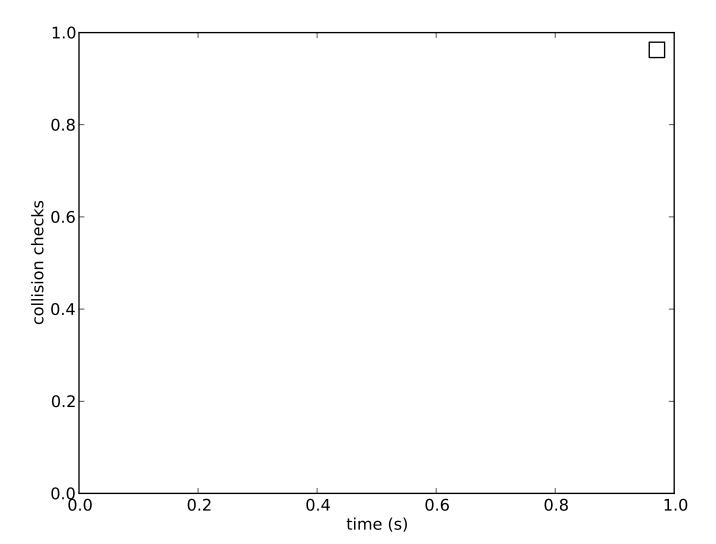
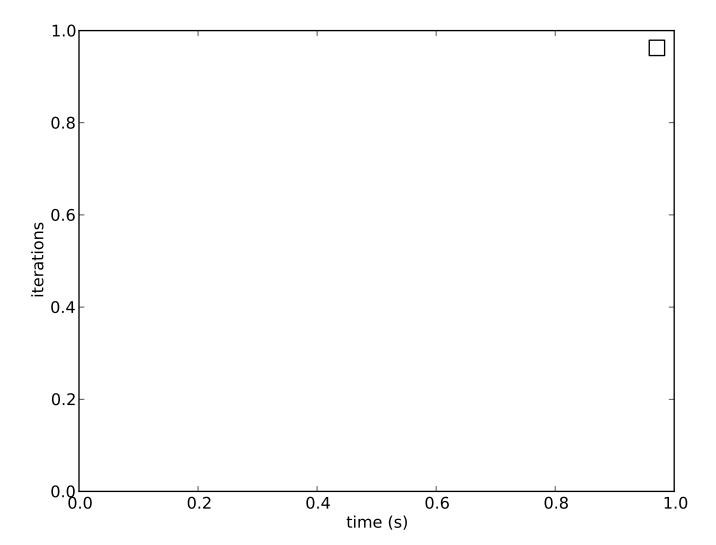


Motion planning algorithm









Experiment "Forest"

Number of averaged runs: 20

Time limit per run: 5 seconds

Memory limit per run: 1024 MB