

Atharv Sonwane

🐙 [threewisemonkeys-as.github.io](https://github.com/threewisemonkeys-as) | 🐙 [threewisemonkeys-as](https://github.com/threewisemonkeys-as)

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RESEARCH INTERESTS

★ Reinforcement Learning ★ Robotics ★ Neurosymbolic AI ★ Meta Learning ★ Autonomous Navigation
★ Cognitive Science ★ Program Synthesis ★ Automata Theory ★ Hierarchical Learning ★ Distributed Systems

EDUCATION

★ **Birla Institute of Technology and Science, Pilani** Aug. 2018 - Present
Bachelor in Engineering (Hons.), Computer Science. CGPA = 8.68 / 10 *Goa, India*

TECHNICAL SKILLS

Programming C/C++, Python, Java, Rust, MATLAB, SQL, OCaml, Bash
Deep Learning PyTorch, Tensorflow, Keras, NumPy, JAX, scikit-learn, pandas, Matplotlib
Robotics Robot Operating System (ROS), rViz, Gazebo, MAVROS, PX4, Raspberry Pi
Tools Git, L^AT_EX, Unix, TravisCI, AutoCAD, Qiskit

EXPERIENCE

- ★ **APP Centre for Artificial Intelligence Research & TCS Research** | [WEB](#) *Jan 2021 - Current*
Undergraduate Researcher | Advisors: [Prof Ashwin Srinivasan](#) and [Dr. Gautam Shroff](#)
▷ Adapting Bayesian Neural Program Synthesis for visual reasoning tasks
▷ Contributing to project on automaton augmented reinforcement learning
- ★ **Centre of Robotics and Machine Intelligence IIIT Allahabad** | [WEB](#) *Summer 2020*
Research Intern | Advisor: [Prof G.C. Nandi](#)
▷ Explored how Deep Reinforcement Learning algorithms can be used for robotics in a simulated setting
▷ Implemented and tested performance of various Deep RL algorithms from scratch in PyTorch
- ★ **Council of Scientific and Industrial Research - CERRI** | [WEB](#) | [CODE](#) *Summer 2020*
Research Intern | Advisors: [Samarth Singh](#) and [Dr. Rakesh Warier](#)
▷ Applied Deep Q learning to navigation of autonomous quadcopters. A live depth-map feed was taken as input to generate movement commands for the drone
▷ Built a controller on top of the MAVROS framework and simulated the learning process using PX4 and PX4 SITL.
- ★ **Digital Communications Lab, BITS Goa** *Jan 2020 – April 2020*
Undergraduate Researcher | Advisors: Abhijit Dey and [Dr. Nitin Sharma](#)
▷ Analysis and forecasting of GNSS (Global Navigation Satellite System) signals to learn more about disturbances due to ionospheric activity using Deep Learning
▷ Implemented LSTM based models in TensorFlow for both forecasting and classification tasks based on ionospheric time series data

PROJECTS

- ★ **GenRL | PyTorch Reinforcement Learning Library** | [CODE](#) *June 2020 – Present*
Society for Artificial Intelligence and Deep Learning (SAiDL)
▷ Collection of SOTA algorithms in Deep and Classical RL along with various utilities
▷ Contributed implementations of various Deep Contextual Bandits
▷ Core Maintainer and currently working on implementation of distributed RL using RPC

- ★ **Trotbot | Autonomous Delivery Robot | [CODE](#)** *Sep 2018 – Present*
Electronics and Robotics Club, BITS Goa ([ERC](#))
 - ▷ Built obstacle detection and path planning stack using Robot Operating System (ROS) in Python
 - ▷ Implemented Rapidly Exploring Random Trees (RRT) for path planning in complex indoor environments
- ★ **Structure and Inductive Biases in Reinforcement Learning | [CODE](#)** *July 2020 – Dec 2020*
 - ▷ Investigating how inductive biases are incorporated in various ML algorithms
 - ▷ Implemented methods which used graph representations in RL to explore structural inductive bias
- ★ **GenNav | Python library for Robotics Navigation | [CODE](#)** *March 2020 – Present*
Electronics and Robotics Club, BITS Goa ([ERC](#))
 - ▷ Co-author and Lead Maintainer working with a team of 10+ student contributors
 - ▷ Modular collection of navigation algorithms and broad range utilities commonly used in Robotics with unified API
 - ▷ Developing a ROS wrapper to enable easy integration into real world robotics systems
- ★ **Causality in Reinforcement Learning | [CODE](#)** *July 2020 – September 2020*
 - ▷ Experimentation with integrating causal factors in RL algorithms for better performance in medical settings.
- ★ **Oneshot Classification using Transfer Learning | [CODE](#)** *Aug 2019*
 - ▷ Used transfer learning techniques to improve performance of a Siamese network for one shot learning on the Omniglot dataset.
- ★ **Deep Q Learning for Atari Environments | [CODE](#)** *Aug 2019*
 - ▷ Experimented with using Double DQN algorithm to play Pong and Pacman gym environments.
- ★ **Spoken Digit Classification | [CODE](#)** *Dec 2019*
 - ▷ Trained a CNN to classify audio clips of spoken digits encoded with a Short Time Fourier transform.

TEACHING AND LEADERSHIP ROLES

- ★ **Teaching Assistant - Machine Learning (BITS F464)** *Jan 2021 – Present*
 - ▷ Conducting weekly labs on implementation of machine learning algorithms, working under Prof Tirtharaj Dash and Prof Ashwin Srinivasan
 - ▷ Responsible for organising the course project component
- ★ **Teaching Assistant - Discrete Structures for Computer Science (CS F222)** *Aug 2020 – Dec 2020*
 - ▷ Mentored undergraduate students in weekly problem solving sessions for course taught by Prof AB Matthews
- ★ **Student Coordinator - Electronics and Robotics Club | [WEB](#)** *Aug 2020 – Present*
 - ▷ Leading a large (100+) group of undergraduates interested in Robotics. Organising research projects, funding, work exhibitions and holding regular discussion sessions
- ★ **Member - Society for Artificial Intelligence and Deep Learning | [WEB](#)** *Aug 2020 – Present*
 - ▷ Involved in research projects, teaching introductory courses, and discussion sessions on AI and deep learning
- ★ **Instructor for Student Run Courses on Robotics and Deep Learning** *April 2020 – Dec 2020*
- ★ **Committee Member - SandBox Innovation Laboratory | [WEB](#)** *Aug 2020 – Present*

RELEVANT COURSES

Meta Learning^{#*}, Machine Learning, Artificial Intelligence^{*}, Linguistics, Probability and Statistics, Graphs and Networks, Theory of Computation, Data Structures and Algorithms, Linear Algebra, Calculus, Operating Systems, Object Oriented Programming, Computational Physics, Quantum Informatics and Computing, **Convolutional Neural Networks for Visual Recognition[†]** (Stanford CS231n), **Deep Reinforcement Learning[†]** (UC Berkeley CS285)

= graduate level, * = ongoing, † = online