Athary Sonwane

• threewisemonkeys-as.github.io | • threewisemonkeys-as

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RESEARCH INTERESTS

- \star Reinforcement Learning \star Robotics \star Neurosymbolic AI \star Meta Learning \star Autonomous Navigation
- * Cognitive Science * Program Synthesis * Automata Theory * Hierarchical Learning * Distributed Systems

EDUCATION

\star Birla Institute of Technology and Science, Pilani

Bachelor in Engineering (Hons.), Computer Science. CGPA = 8.86 / 10

Aug. 2018 - Present

Goa, India

TECHNICAL SKILLS

Programming C/C++, Python, SQL, Java Rust, OCaml, MATLAB, Bash

Deep Learning PyTorch, Tensorflow, Keras, NumPy, JAX, scikit-learn, pandas, Matplotlib

Robotics Robot Operating System (ROS), rViz, Gazebo, MAVROS, PX4, Raspberry Pi

Tools Git, LATEX, Unix, TravisCI, AutoCAD, Qiskit

EXPERIENCE

* APP Centre for Artificial Intelligence Research & TCS Research | WEB

Jan 2021 - Current

Undergraduate Researcher | Advisors: Prof Ashwin Srinivasan and Dr. Gautam Shroff

- ▷ Currently working on Bayesian Neural Program Synthesis and its applications to visual reasoning tasks
- > Contributing to project on automata augmented Deep Reinforcement Learning
- * Centre of Robotics and Machine Intelligence IIIT Allahabad | WEB

Summer 2020

Research Intern | Advisor: Prof G.C. Nandi

- > Explored how Deep Reinforcement Learning algorithms can be used for robotics in a simulated setting
- > Implemented and tested performance of various algorithms from scratch in PyTorch
- \star Council of Scientific and Industrial Research CERRI | WEB | CODE

 $Summer\ 2020$

Research Intern | Advisors: Samarth Singh and Dr. Rakesh Warier

- ▶ Applied Deep Q learning to navigation of autonomous quadcopters. A live depth-map feed was taken as input to generate movement commands for the drone
- ▶ Built a controller on top of the MAVROS framework and simulated the learning process using PX4 and PX4 SITL.
- * Digital Communications Lab, BITS Goa

Jan 2020 - April 2020

Undergraduate Researcher | Advisors: Abhijit Dey and Dr. Nitin Sharma

- > Analysis and forecasting of GNSS (Global Navigation Satellite System) signals to learn more about disturbances due to ionospheric activity using Deep Learning
- > Implemented LSTM based models in tensorflow for both prediction and classification of ionospheric time series data

PROJECTS

* GenRL | PyTorch Reinforcement Learning Library | CODE

June 2020 - Present

Society for Artificial Intelligence and Deep Learning (SAiDL)

- ▷ Collection of SOTA algorithms in Deep and Classical RL along with various utilities
- ▷ Contributed implementations of various Deep Contextual Bandits
- > Core Maintainer and currently working on implementation of distributed RL using RPC

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 $\star \text{ Trotbot} \mid Autonomous \ Delivery \ Robot \mid \text{CODE}$

Electronics and Robotics Club, BITS Goa (ERC)

- ▷ Built obstacle detection and path planning stack using Robot Operating System (ROS) in Python
- ▶ Implemented Rapidly Exploring Random Trees (RRT) for path planning in complex indoor environments
- * Structure and Inductive Biases in Reinforcement Learning | CODE

July 2020 - Dec 2020

Sep 2018 - Present

- $\, \rhd \,$ Investigating how inductive biases are incorporated in various ML algorithms
- > Implemented methods which used graph representations in RL to explore structural inductive bias
- \star GenNav | Python library for Robotics Navigation | CODE

March 2020 - Present

Electronics and Robotics Club, BITS Goa (ERC)

- ▷ Co-author and Lead Maintainer working with a team of 10+ student contributors
- ▶ Modular collection of navigation algorithms and broad range utilities commonly used in Robotics with unified API
- > Developing a ROS wrapper to enable easy integration into real world robotics systems
- * Causality in Reinforcement Learning | CODE

 $July\ 2020-September\ 2020$

- ▷ Experimentation with integrating causal factors in RL algorithms for better performance in medical settings.
- * Oneshot Classification using Transfer Learning | CODE

Aug 2019

- ▶ Used transfer learning techniques to improve performance of a Siamese network for one shot learning on the Omniglot dataset.
- * Deep Q Learning for Atari Environments | CODE

Aug 2019

- $\,\vartriangleright\,$ Experimented with using Double DQN algorithm to play Pong and Pacman gym environments.
- * Spoken Digit Classification | CODE

Dec 2019

- > Trained a CNN to classify audio clips of spoken digits encoded with a Short Time Fourier transform.
- * Robotic Sketcher | WEB

Jan 2020

▷ Created an automated sketching machine to produce visually appealing sketches from images as a display.

MENTORING AND LEADERSHIP ROLES

* Teaching Assistant - Machine Learning (BITS F464)

Jan 2021 – Present

- ▷ Conducting weekly labs on implementation of machine learning algorithms, working under Prof Tirtharaj Dash and Prof Ashwin Srinivasan
- ▶ Responsible for organising the course project component
- * Teaching Assistant Discrete Structures for Computer Science (CS F222)

 Aug 2020 Dec 2020
 - ▷ Mentored undergraduate students in weekly problem solving sessions for course taught by Prof AB Matthews
- * Student Coordinator Electronics and Robotics Club | WEB

Aug 2020 - Present

- ▶ Leading a large (100+) group of undergraduates interested in Robotics. Organising research projects, funding, work exhibitions and holding regular discussion sessions
- * Member Society for Artificial Intelligence and Deep Learning | WEB

Aug 2020 - Present

- ▷ Involved in research projects, teaching introductory courses, and discussion sessions on AI and deep learning
- * Instructor for Student Run Courses

April 2020 - Dec 2020

- ▶ Mentoblue and created reference material for introductory courses in Robotics and Deep Learning
- * Committee Member SandBox Innovation Laboratory | WEB

Aug 2020 - Present

Relevant Courses

Meta Learning^{#*}, Machine Learning, Artificial Intelligence^{*}, Probability and Statistics, Graphs and Networks, Theory of Computation, Data Structures and Algorithms, Linear Algebra, Calculus, Operating Systems, Object Oriented Programming, Computational Physics, Quantum Informatics and Computing, Convolutional Neural Networks for Visual Recognition † (Stanford CS231n), Deep Reinforcement Learning † (UC Berkeley CS285)

 $\# = \text{graduate level}, * = \text{ongoing}, \dagger = \text{online}$

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