



Chapter 2 - Section 13

Representation Learning in Vision Tasks

Dr. Liu Yu

Thursday, May 20, 2021

Acknowledge : Song Guanglu , Liu Boxiao , Zhang Manyuan



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13.1 Metric Learning

Dr. Liu Yu

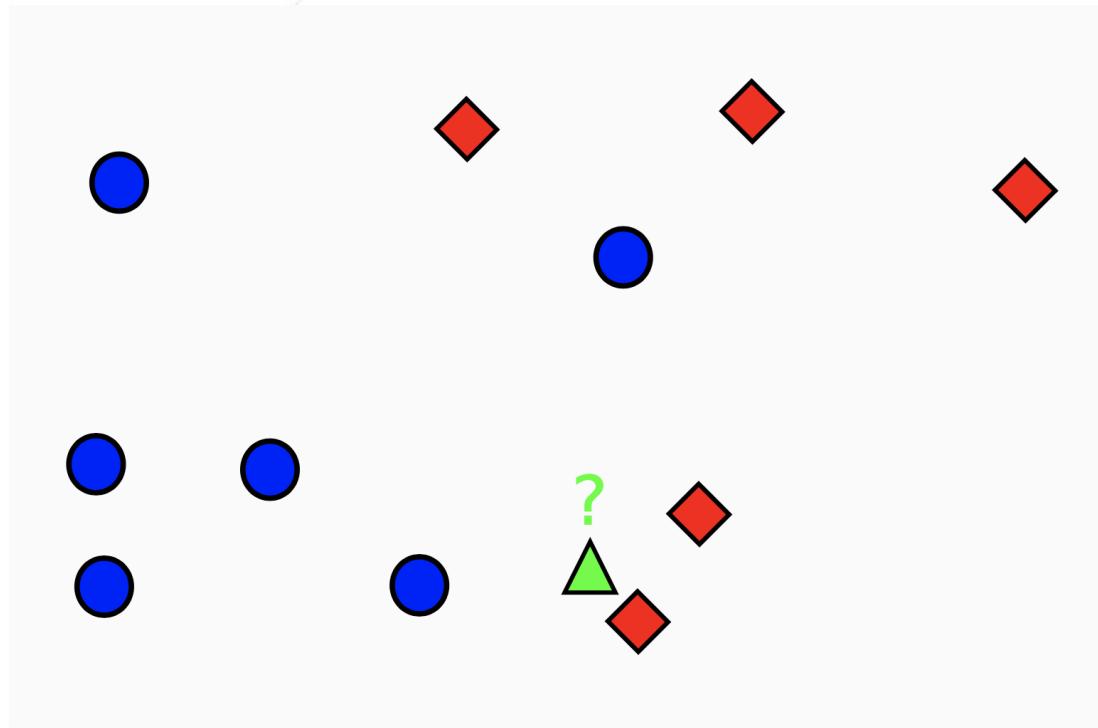
Thursday, May 20, 2021

Outline

-
- Part 1 Introduction**
 - Part 2 Metric learning for face recognition**
 - Part 3 Hamming Deep Metric Learning**
-

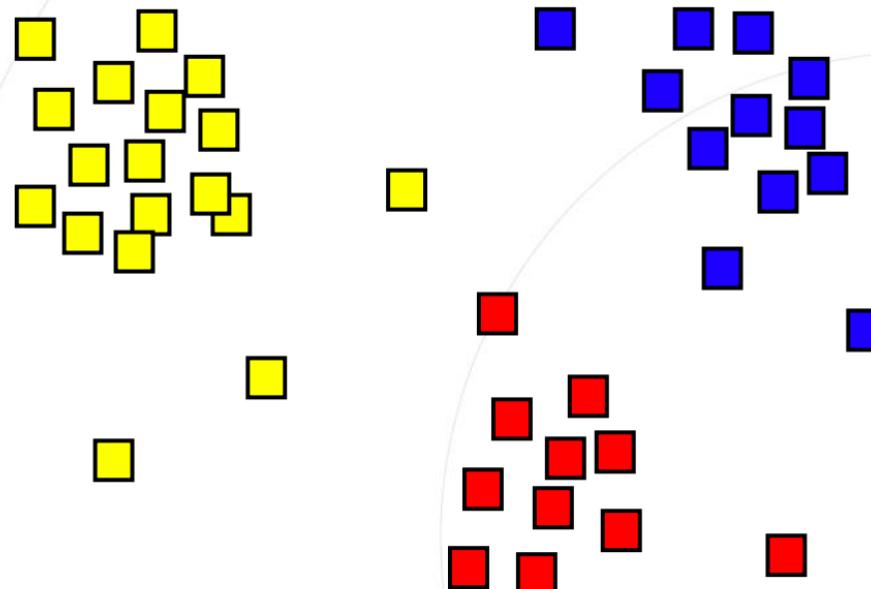
- **Similarity / distance judgements** are essential components of many human cognitive processes.
 - Compare perceptual or conceptual representations.
 - Perform recognition, categorization.
- Underlie most machine learning and data mining techniques.

- Nearest neighbor classification



If you want to find the nearest neighbor, you should calculate the distance between samples.

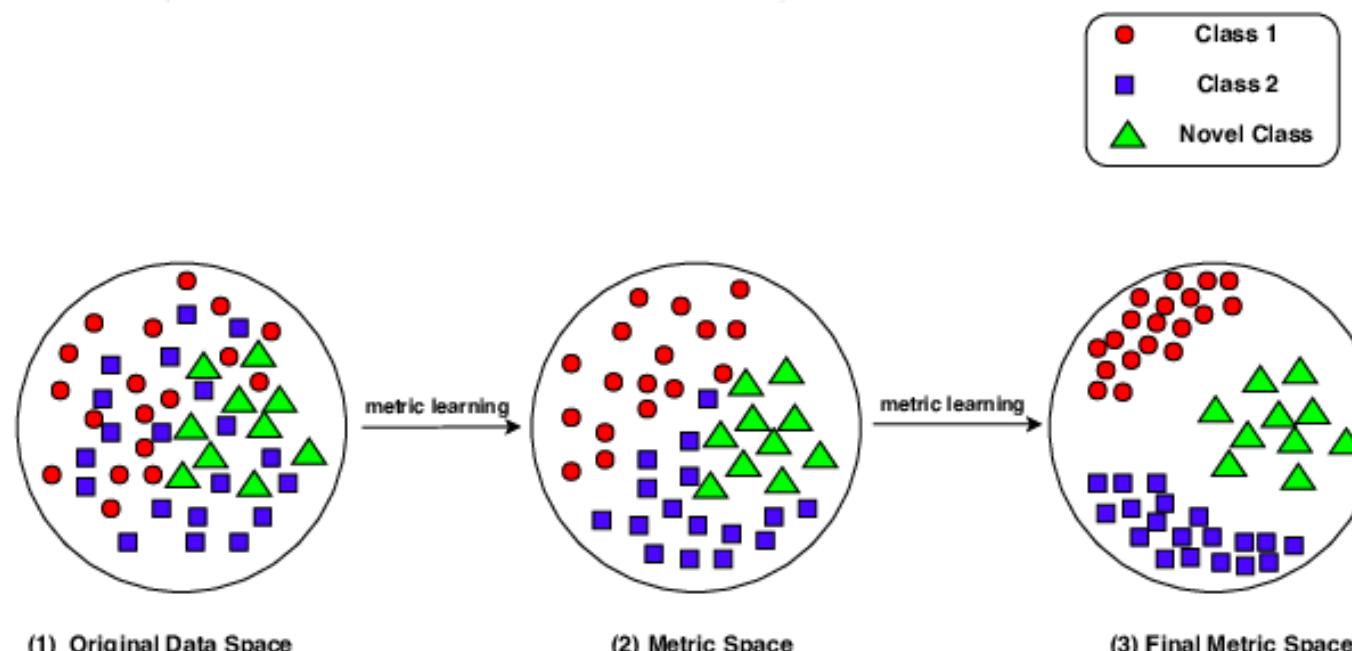
- Clustering



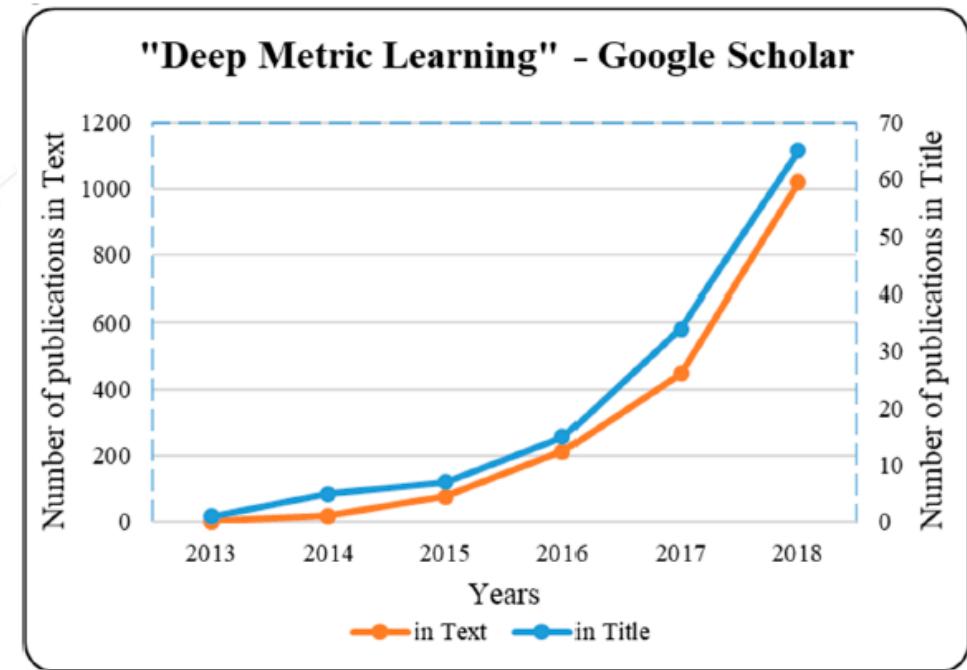
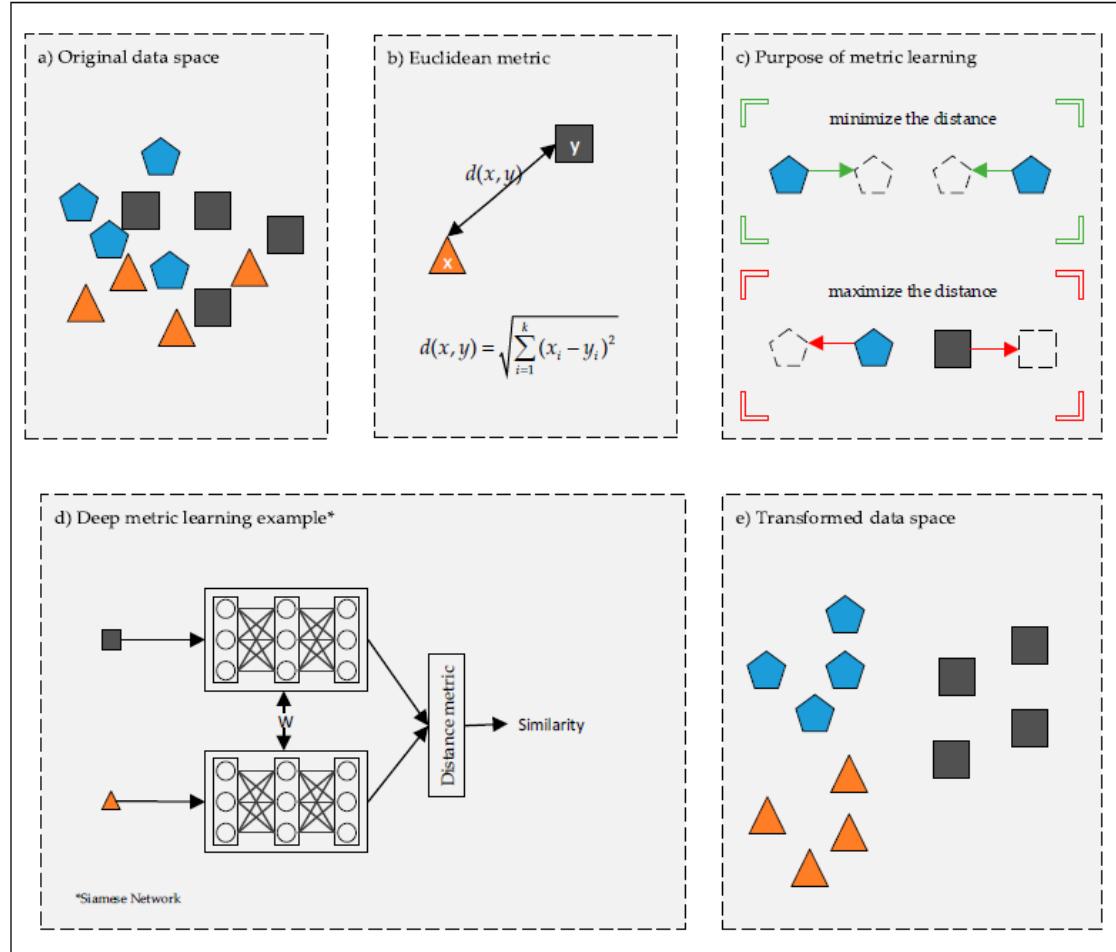
If you want to do clustering, you should calculate the distance between samples.

- Choice of similarity is crucial to the performance.
- Humans weight features differently depending on context.
- Fundamental question: **how to appropriately measure similarity or distance for a given task?**
- Metric learning + infer this automatically from data.
- Note: we will refer to distance or similarity indistinctly as metric.

- Measuring Similarity Between Data
 - Similarity: computing distances between data points.
 - Performance: depending on the definitions of similarity.



- Deep Metric Learning





- Examples for deep metric learning
 - Face recognition
 - Person Re-identification

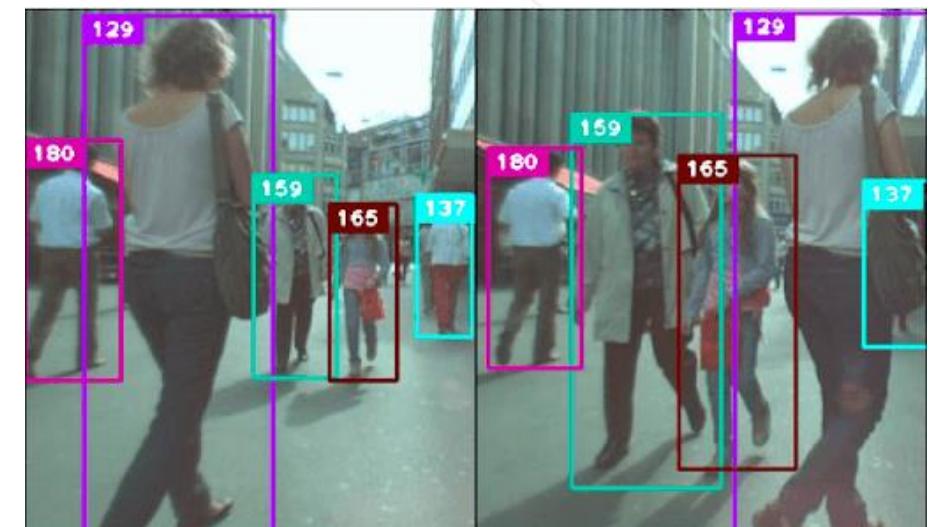


- Examples for deep metric learning

- Multimedia Searching



- Tracking

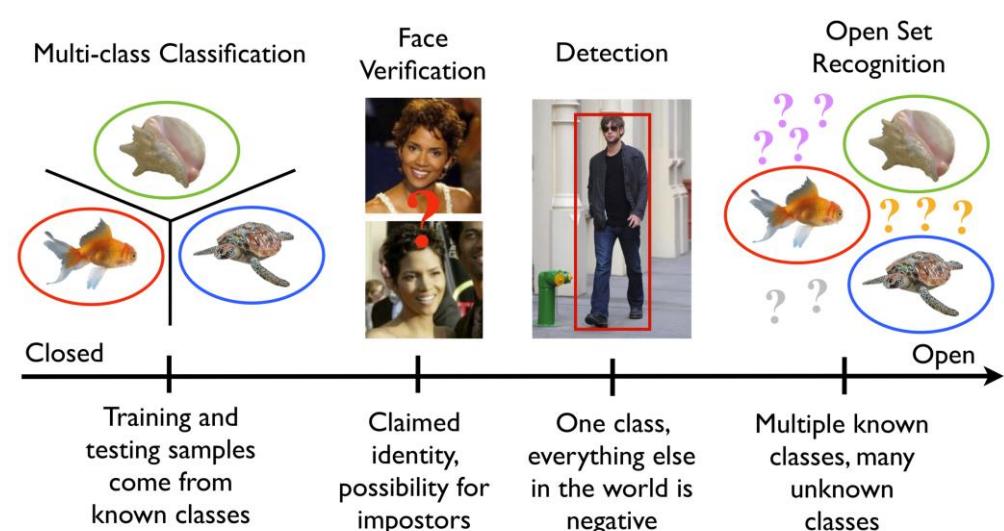


- Examples for deep metric learning

- Activity Recognition



- Open-set recognition



- Measure Similarity: Metric

A **metric** is a function that defines a distance between each pair of elements of a set.

- **Euclidean or L2:**

$$d_{\text{Euclidean}}(\bar{x}_1, \bar{x}_2) = \|\bar{x}_1 - \bar{x}_2\|_2 = \sqrt{\sum_i (x_1^i - x_2^i)^2}$$

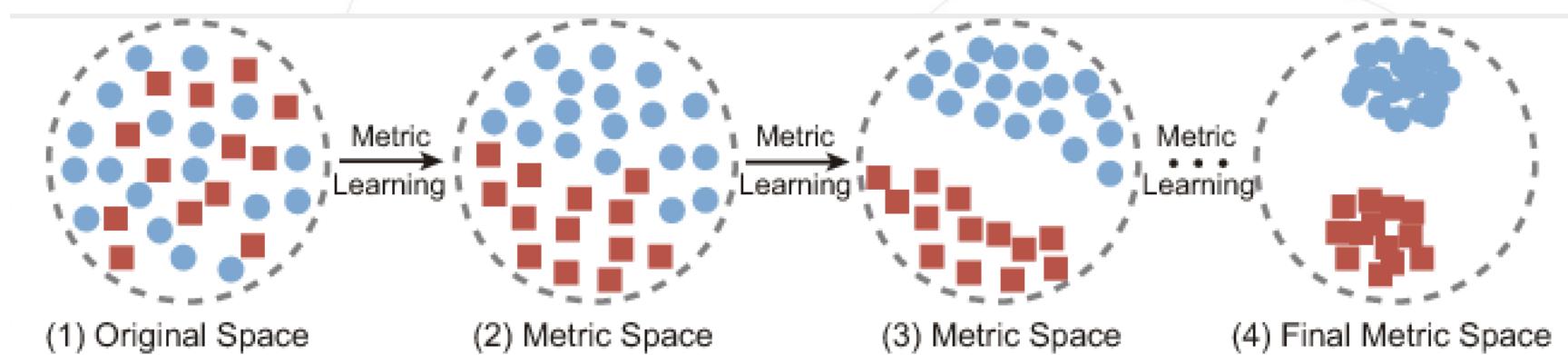
- **Manhattan or L1:**

$$d_{\text{Manhattan}}(\bar{x}_1, \bar{x}_2) = \|\bar{x}_1 - \bar{x}_2\|_1 = \sum_i |x_1^\ell - x_2^\ell|$$

- **Cosine distance:**

$$d_{\text{Cosine}}(\bar{x}_1, \bar{x}_2) = 1 - \frac{\bar{x}_1 \cdot \bar{x}_2}{\|\bar{x}_1\|_2 \|\bar{x}_2\|_2}$$

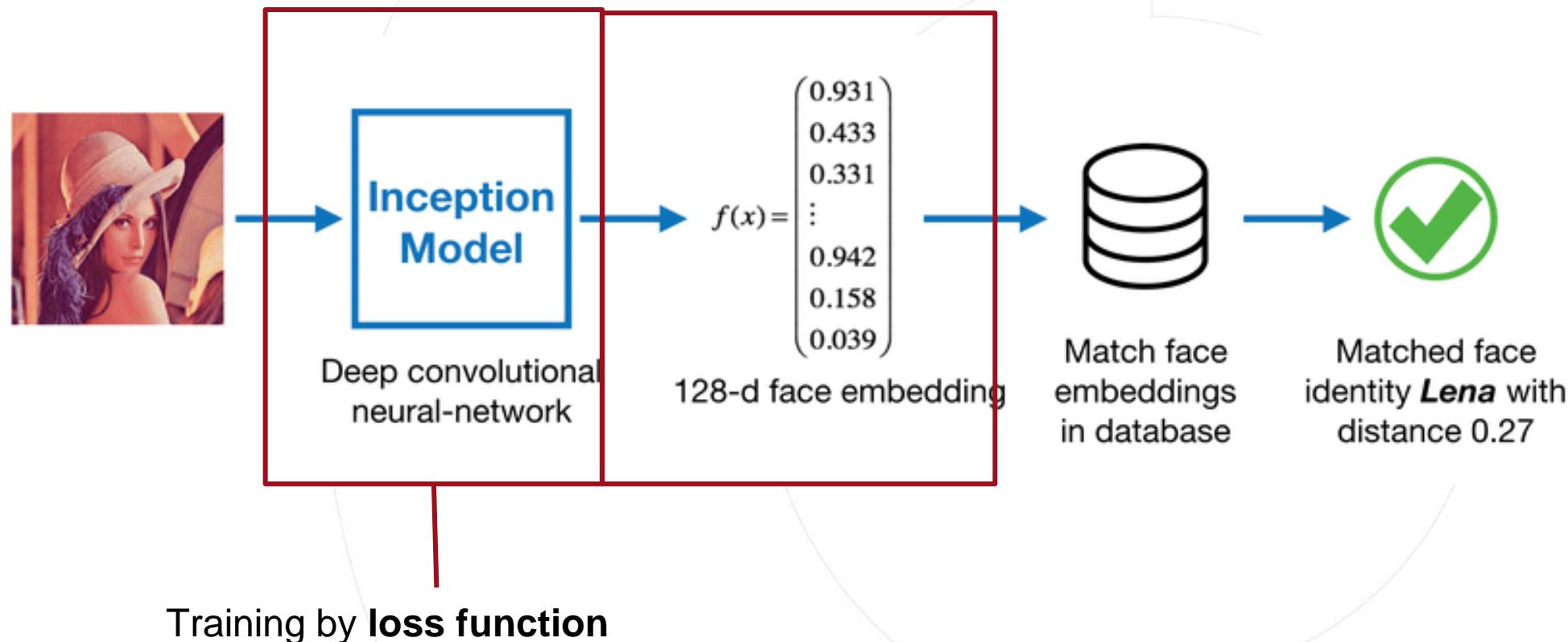
- To form compact representations



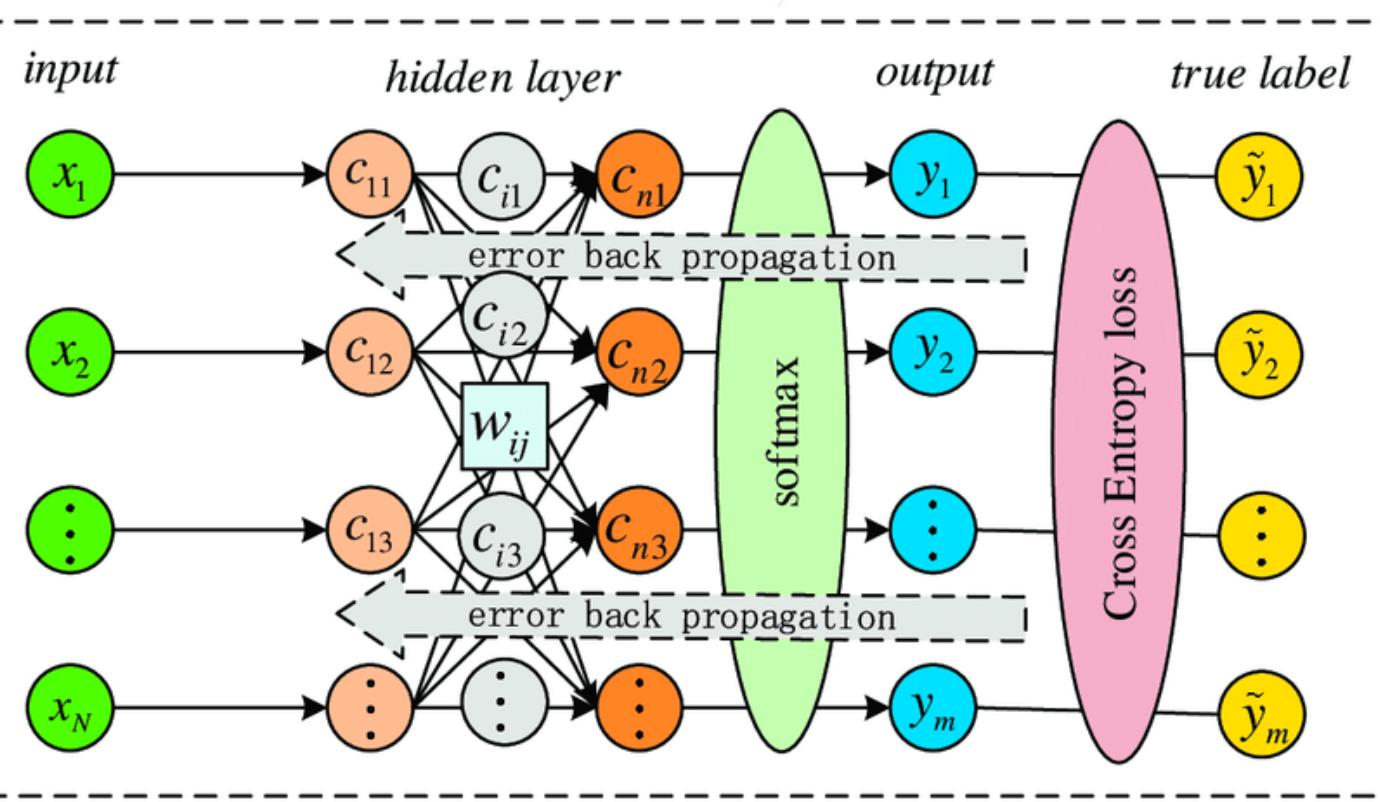
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- Face recognition pipeline

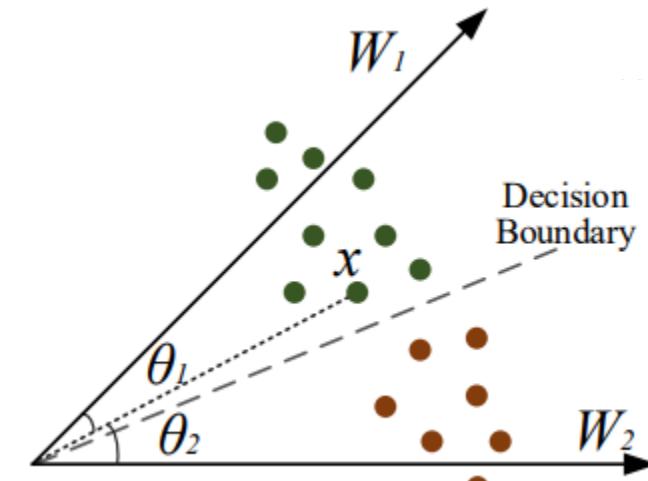


- Softmax cross-entropy Loss

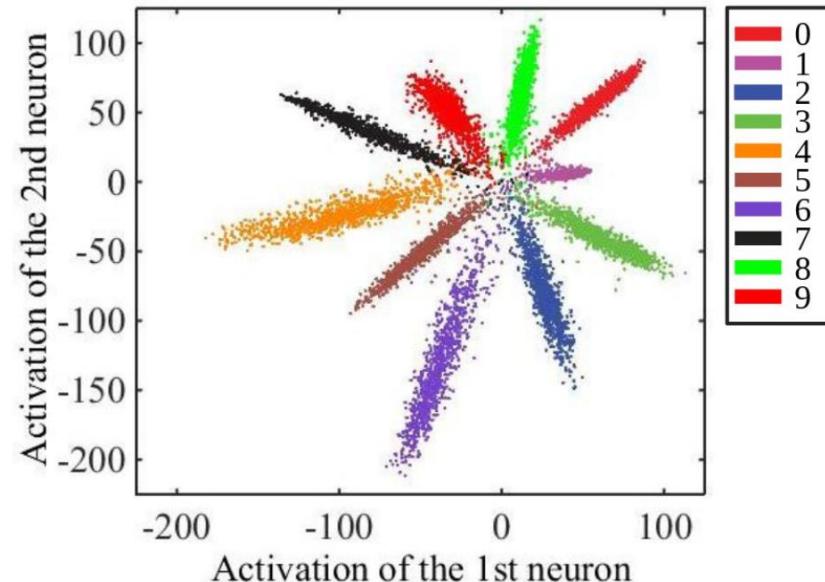
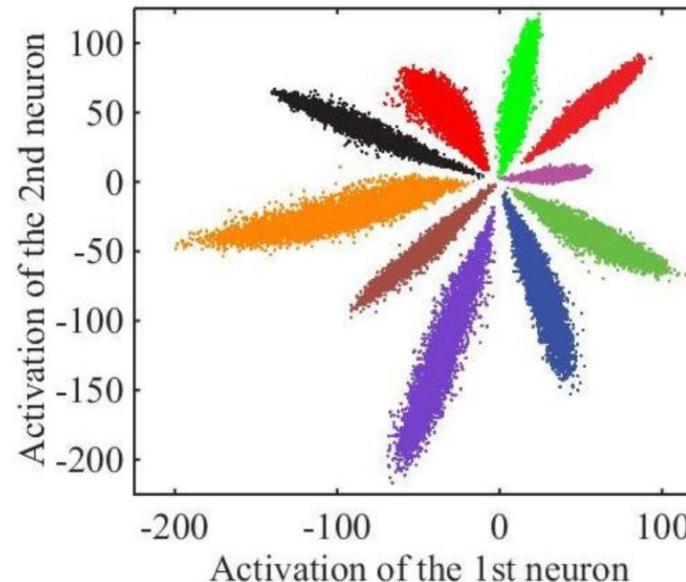


$$L = \frac{1}{N} \sum_i L_i = \frac{1}{N} \sum_i -\log \left(\frac{e^{f_{y_i}}}{\sum_j e^{f_j}} \right)$$

$$\begin{aligned} W_1^T x &\geq W_2^T x \\ \Leftrightarrow \|W_1\|_2 \|x\|_2 \cos(\theta_1) &\geq \|W_2\|_2 \|x\|_2 \cos(\theta_2) \end{aligned}$$



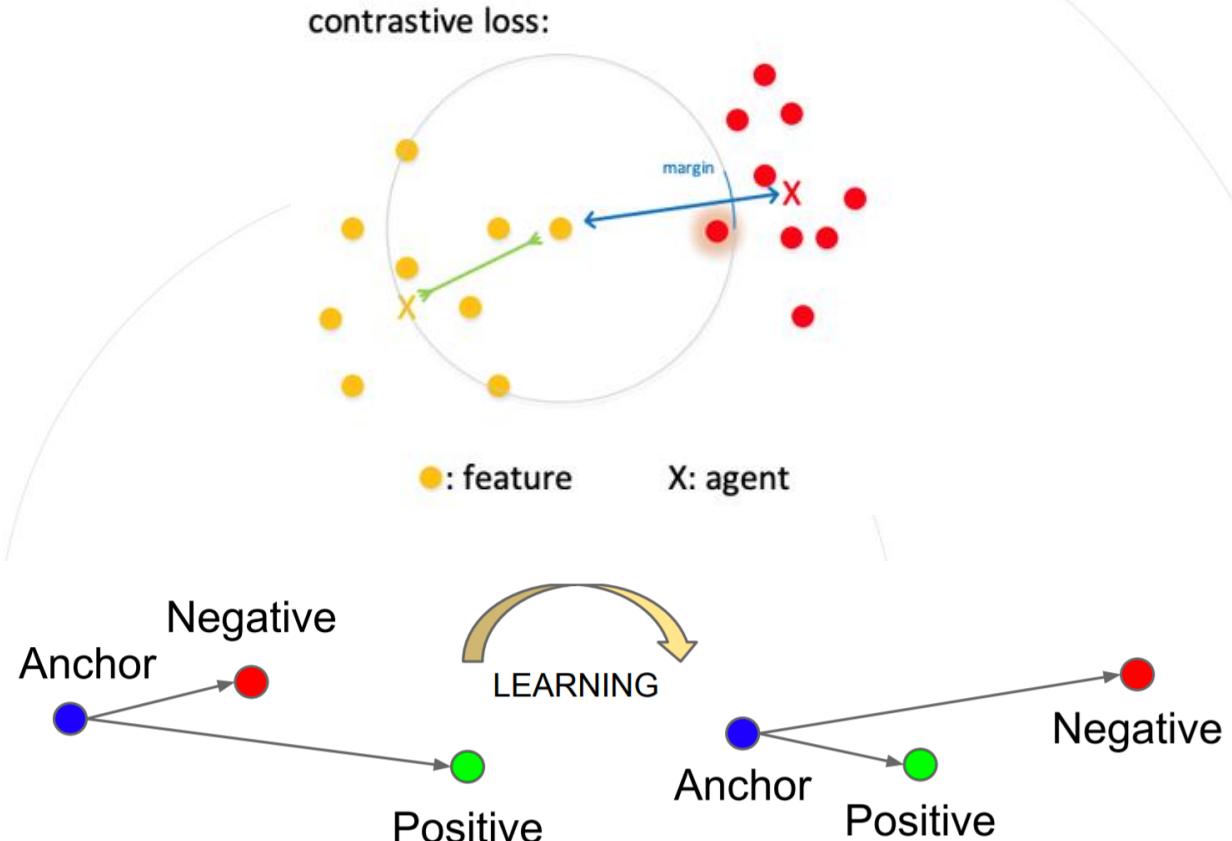
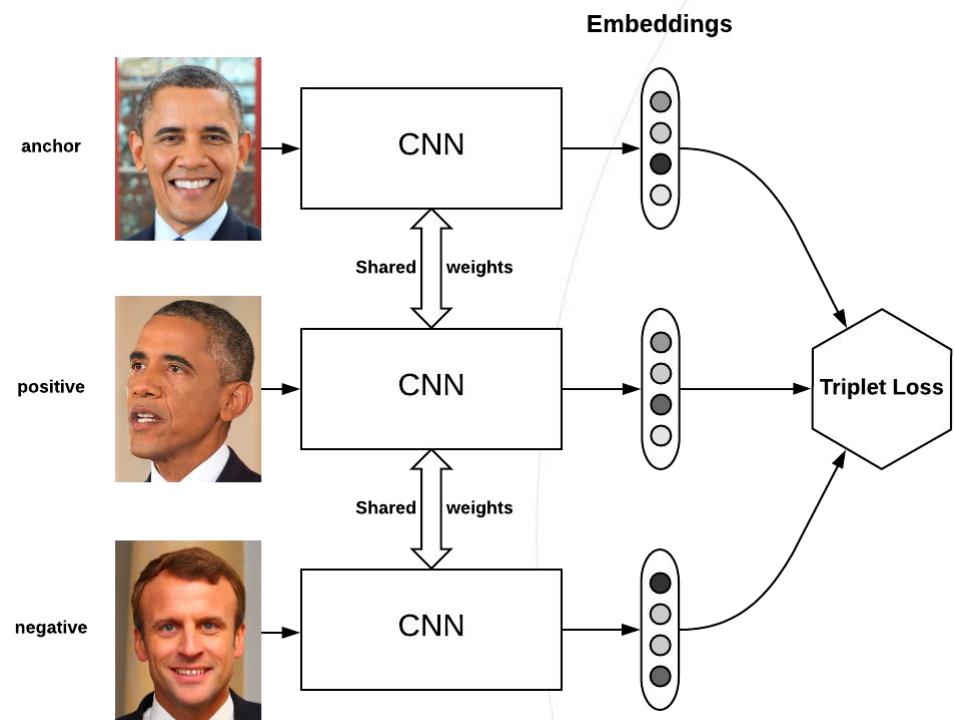
- Is SoftmaxWithLoss good for clustering?



Separable.

The deep features are not discriminative enough due to intra-class variation

- Triplet loss function



Schroff F, Kalenichenko D, Philbin J. Facenet: A unified embedding for face recognition and clustering [C]// CVPR, 2015.

- Triplet loss function

The goal of the triplet loss is to make sure that:

- Two examples with the **same label** have their embeddings **close** together in the embedding space
- Two examples with **different labels** have their embeddings **far away**.

$$\mathcal{L} = \max(d(a, p) - d(a, n) + \text{margin}, 0)$$

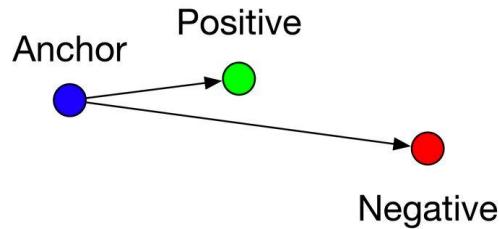
To formalise this requirement, the loss will be defined over triplets of embeddings:

- an anchor
- a positive of the same class as the anchor
- a negative of a different class

- Hard triplet mining

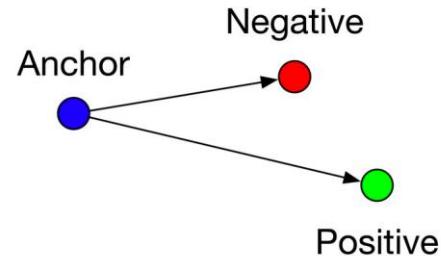
- easy triplets

$$d(a, p) + \text{margin} < d(a, n)$$



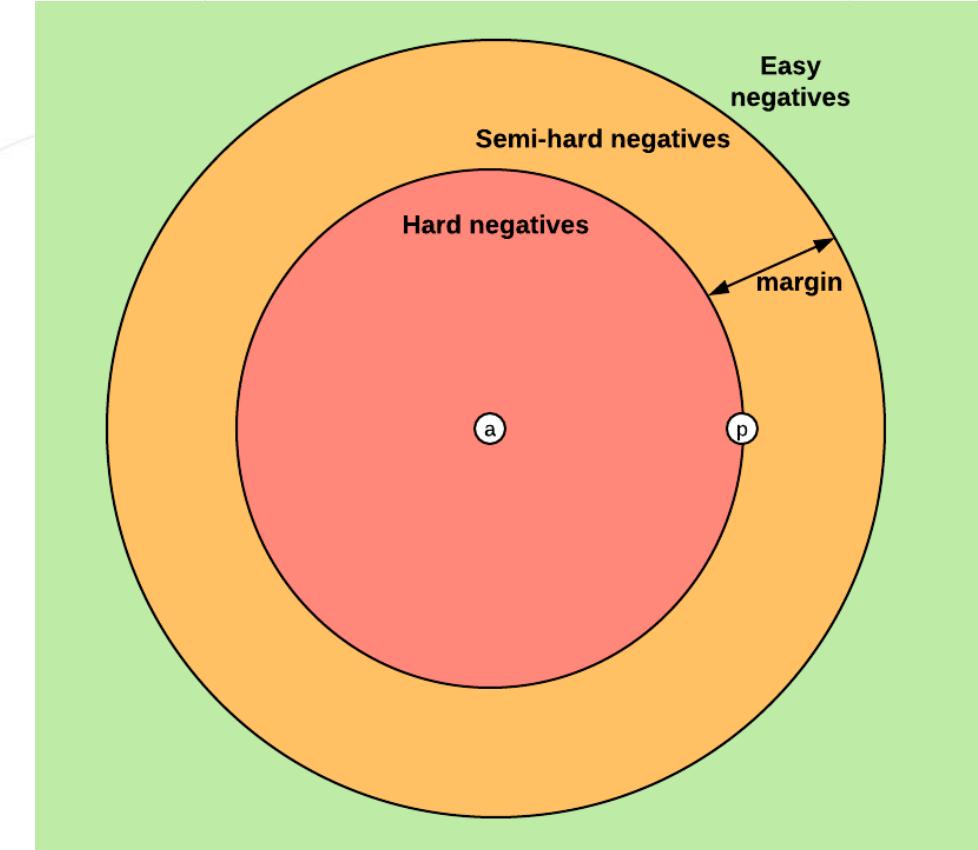
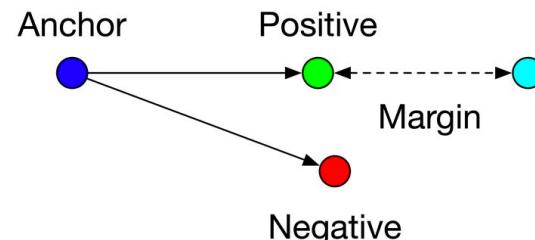
- hard triplets

$$d(a, n) < d(a, p)$$

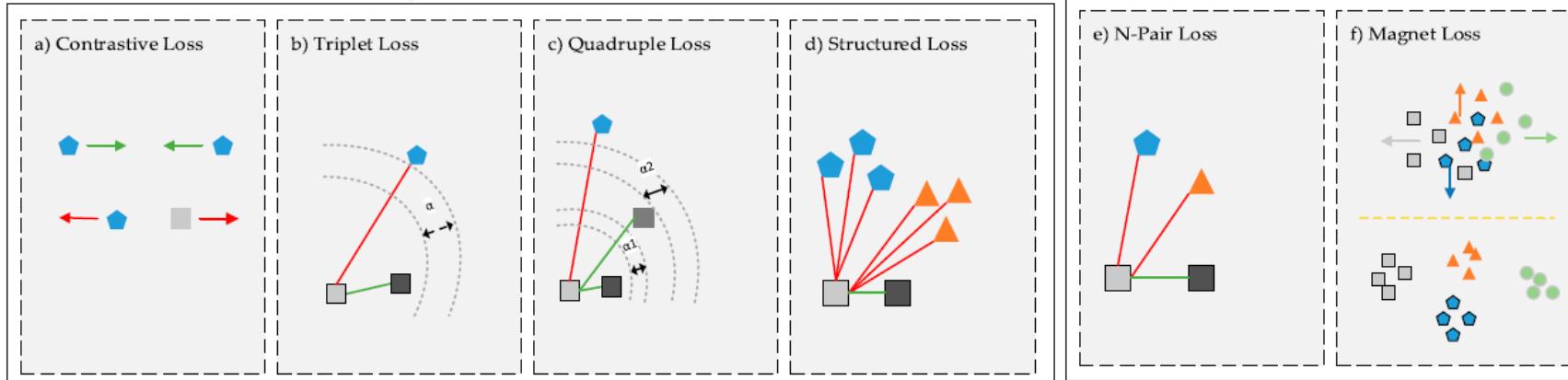


- semi-hard triplets

$$d(a, p) < d(a, n) < d(a, p) + \text{margin}$$



- Metric loss functions



$$D_W(X_1, X_2) = \|G_W(X_1) - G_W(X_2)\|_2$$

$$(a) L_{Contrastive} = (1 - Y) \frac{1}{2} (D_W)^2 + (Y) \frac{1}{2} \{\max(0, m - D_W)\}^2$$

$$(b) L_{Triplet} = \max(0, \|G_W(X) - G_W(X^p)\|_2 - \|G_W(X) - G_W(X^n)\|_2 + \alpha)$$

$$(c) L_{Quadruple} = \max(0, \|G_W(X) - G_W(X^p)\|_2 - \|G_W(X) - G_W(X^s)\|_2 + \alpha_1) + \max(0, \|G_W(X) - G_W(X^s)\|_2 - \|G_W(X) - G_W(X^n)\|_2 + \alpha_2)$$

$$(d) J = \frac{1}{2|\widehat{\mathcal{P}}|} \sum_{(i,j) \in \widehat{\mathcal{P}}} \max(0, J_{i,j})^2,$$

$$J_{i,j} = \max \left(\max_{(i,k) \in \widehat{\mathcal{N}}} \alpha - D_{i,k}, \max_{(j,l) \in \widehat{\mathcal{N}}} \alpha - D_{j,l} \right) + D_{i,j}$$

$$(e) \mathcal{L}_{N\text{-pair-ovo}}(\{(x_i, x_i^+)\}_{i=1}^N; f) = \frac{1}{N} \sum_{i=1}^N \sum_{j \neq i} \log \left(1 + \exp(f_i^\top f_j^+ - f_i^\top f_i^+) \right).$$

$$(f) \mathcal{L}(\Theta) = \frac{1}{N} \sum_{n=1}^N \left\{ -\log \frac{e^{-\frac{1}{2\sigma^2} \|\mathbf{r}_n - \boldsymbol{\mu}(\mathbf{r}_n)\|_2^2 - \alpha}}{\sum_{c \neq C(\mathbf{r}_n)} \sum_{k=1}^K e^{-\frac{1}{2\sigma^2} \|\mathbf{r}_n - \boldsymbol{\mu}_k^c\|_2^2}} \right\}_+$$

- Center loss function

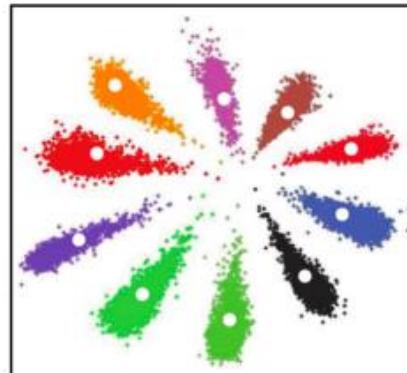
$$\mathcal{L}_C = \frac{1}{2} \sum_{i=1}^m \| \mathbf{x}_i - \mathbf{c}_{y_i} \|_2^2$$

$$\frac{\partial \mathcal{L}_C}{\partial \mathbf{x}_i} = \mathbf{x}_i - \mathbf{c}_{y_i}$$

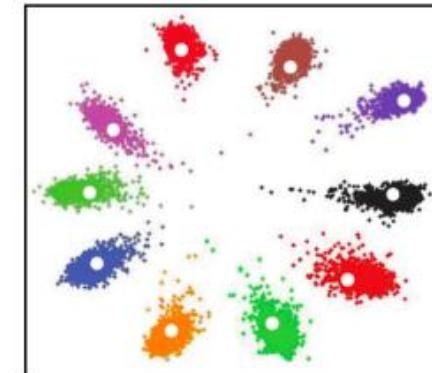
$$\Delta \mathbf{c}_j = \frac{\sum_{i=1}^m \delta(y_i=j) \cdot (\mathbf{c}_j - \mathbf{x}_i)}{1 + \sum_{i=1}^m \delta(y_i=j)}$$

$$\mathcal{L} = \mathcal{L}_S + \lambda \mathcal{L}_C$$

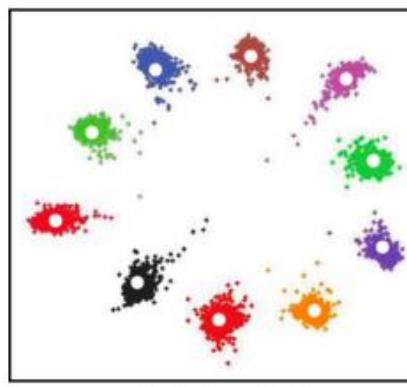
$$= - \sum_{i=1}^m \log \frac{e^{W_{y_i}^T \mathbf{x}_i + b_{y_i}}}{\sum_{j=1}^n e^{W_j^T \mathbf{x}_i + b_j}} + \frac{\lambda}{2} \sum_{i=1}^m \| \mathbf{x}_i - \mathbf{c}_{y_i} \|_2^2$$



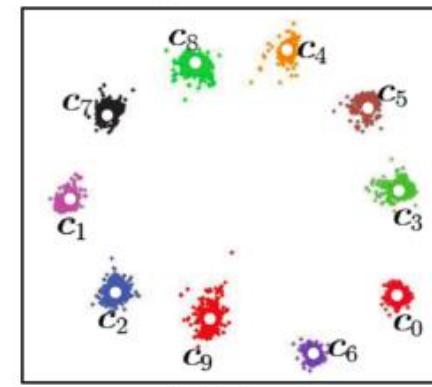
(a) $\lambda = 0.001$



(b) $\lambda = 0.01$



(c) $\lambda = 0.1$

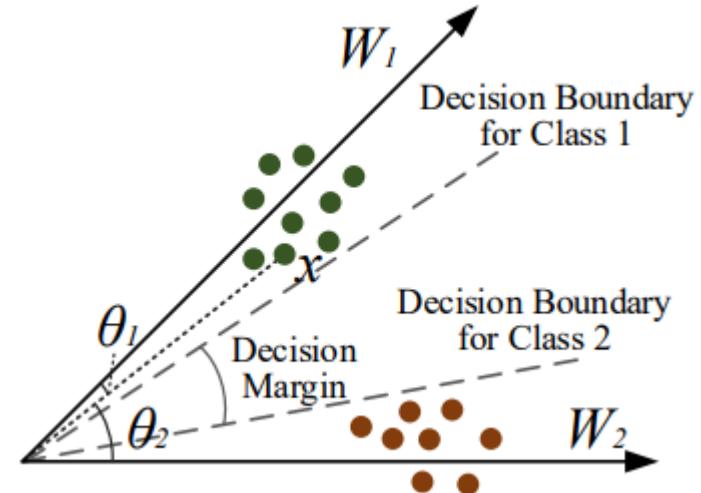
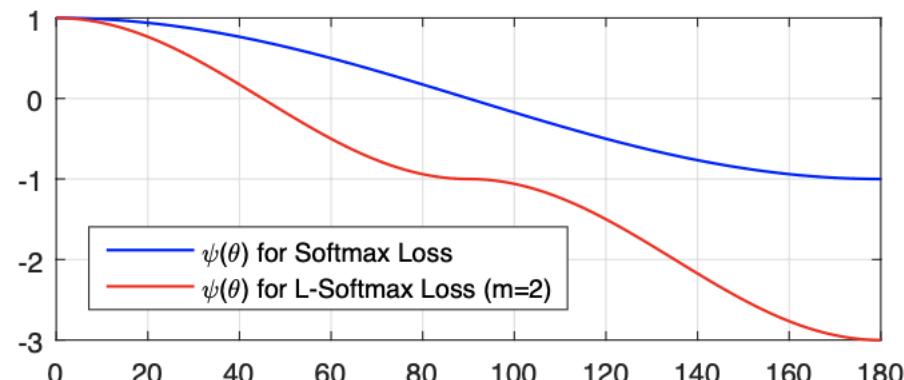


(d) $\lambda = 1$

- Large Margin Softmax

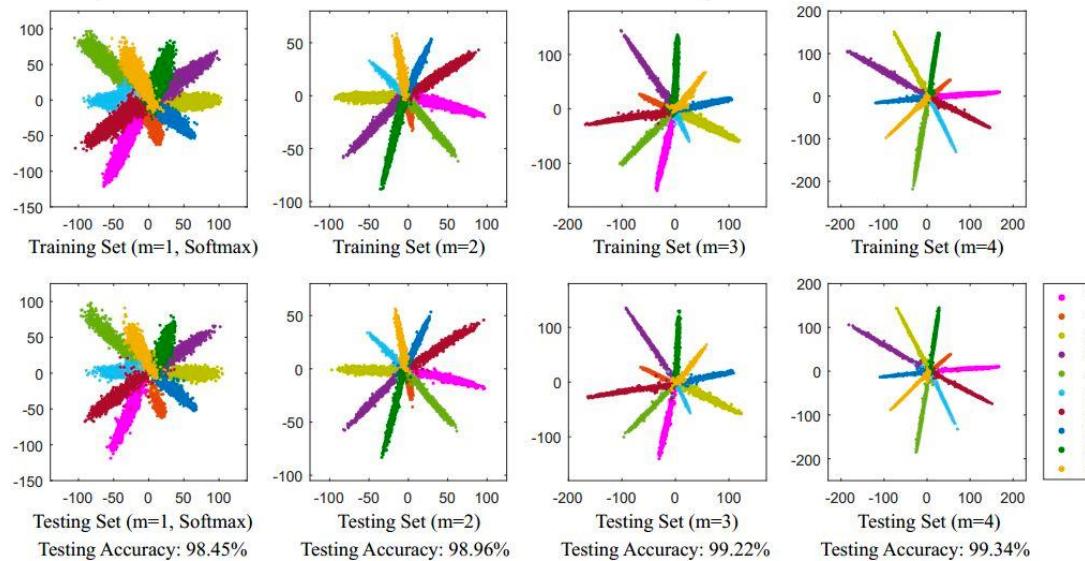
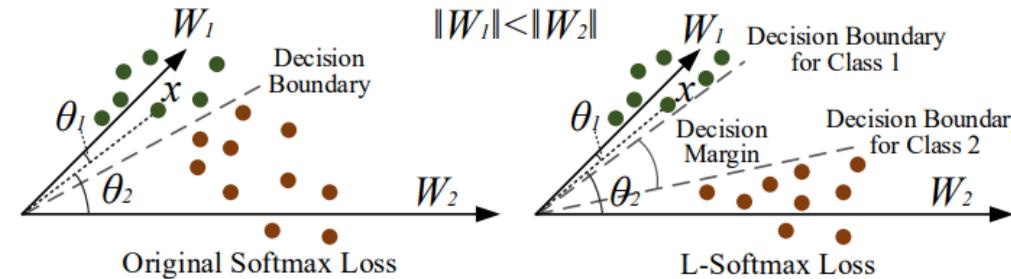
$$L_i = -\log \left(\frac{e^{\|\mathbf{W}_{y_i}\| \|\mathbf{x}_i\| \psi(\theta_{y_i})}}{e^{\|\mathbf{W}_{y_i}\| \|\mathbf{x}_i\| \psi(\theta_{y_i})} + \sum_{j \neq y_i} e^{\|\mathbf{W}_j\| \|\mathbf{x}_i\| \cos(\theta_j)}} \right)$$

$$\psi(\theta) = (-1)^k \cos(m\theta) - 2k, \quad \theta \in \left[\frac{k\pi}{m}, \frac{(k+1)\pi}{m} \right] \quad k \in [0, m-1] \text{ and } k \text{ is an integer}$$



Liu W, Wen Y, Yu Z, et al. Large-Margin Softmax Loss for Convolutional Neural Networks [C]// ICML, 2016.

- Large Margin Softmax



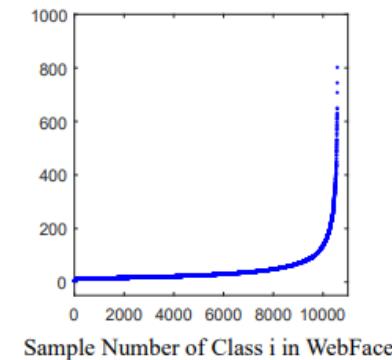
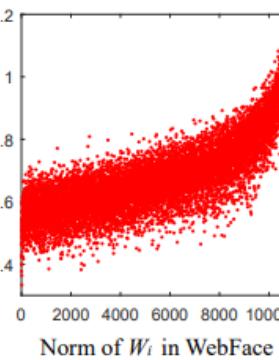
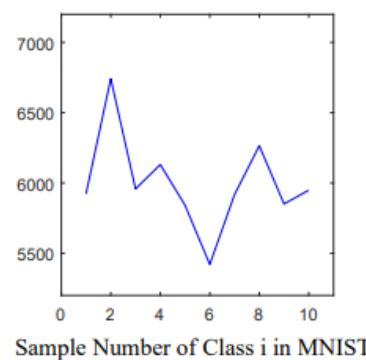
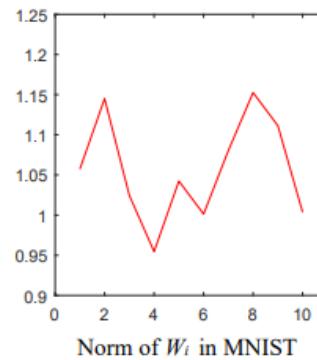
Liu W, Wen Y, Yu Z, et al. Large-Margin Softmax Loss for Convolutional Neural Networks [C]// ICML, 2016.

- SphereFace

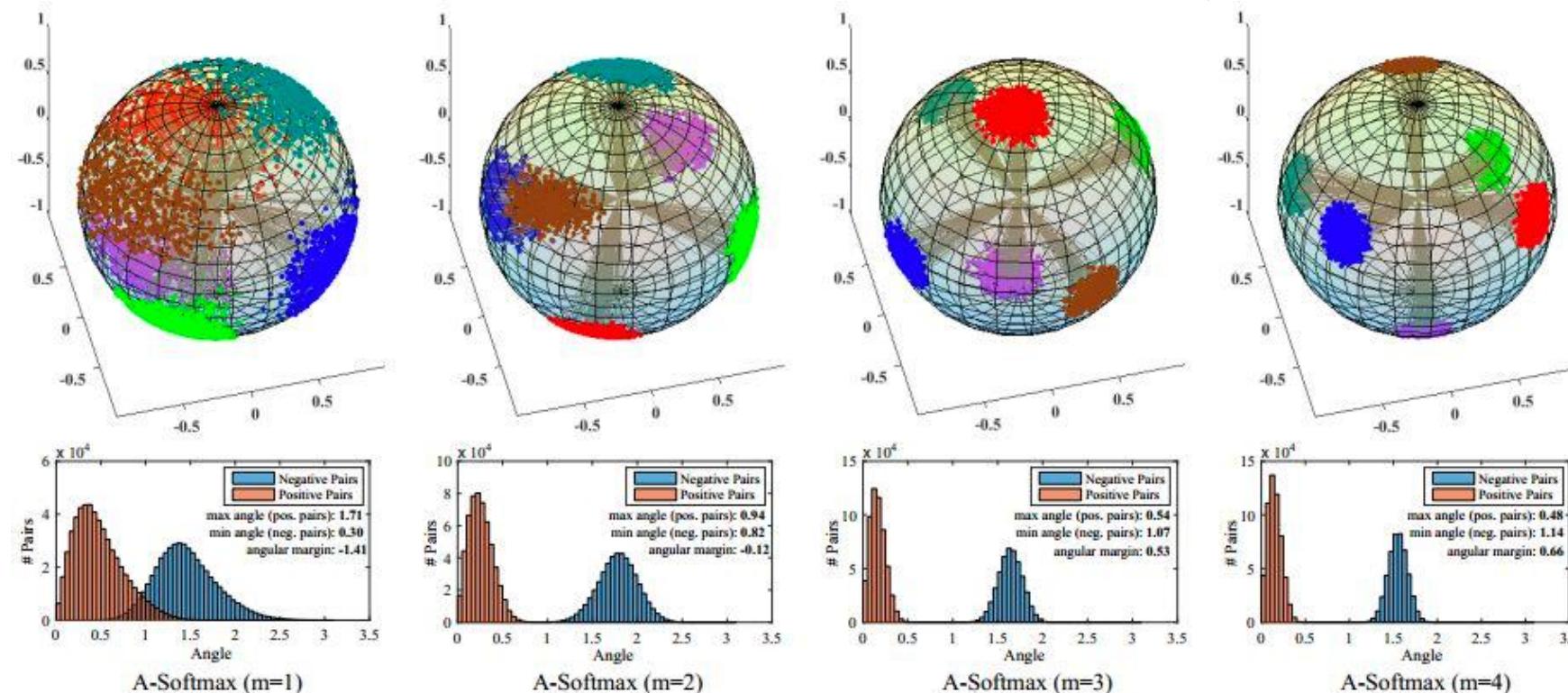
$$L_{\text{ang}} = \frac{1}{N} \sum_i -\log \left(\frac{e^{\|\mathbf{x}_i\| \psi(\theta_{y_i, i})}}{e^{\|\mathbf{x}_i\| \psi(\theta_{y_i, i})} + \sum_{j \neq y_i} e^{\|\mathbf{x}_i\| \cos(\theta_{j, i})}} \right)$$

$$\psi(\theta) = (-1)^k \cos(m\theta) - 2k, \quad \theta \in \left[\frac{k\pi}{m}, \frac{(k+1)\pi}{m} \right]$$

- Normalizing the weights could reduce the prior caused by the training data imbalance



- SphereFace



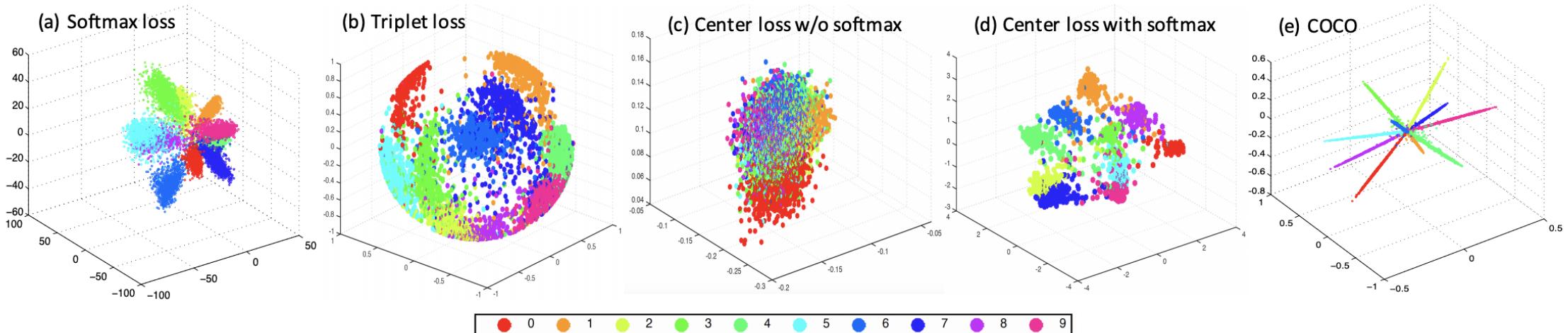
Visualization of features learned with different m .

Liu W, Wen Y, Yu Z, et al. SphereFace: Deep Hypersphere Embedding for Face Recognition [C]// CVPR. 2017.

- COCO (Feature Normalization)

$$\mathcal{L}^{COCO} \left(\mathbf{f}^{(i)}, \mathbf{c}_k \right) = - \sum_{i \in \mathcal{B}, k} t_k^{(i)} \log p_k^{(i)} = - \sum_{i \in \mathcal{B}} \log p_{l_i}^{(i)}$$

$\hat{\mathbf{c}}_k = \frac{\mathbf{c}_k}{\|\mathbf{c}_k\|}, \hat{\mathbf{f}}^{(i)} = \frac{\alpha \mathbf{f}^{(i)}}{\|\mathbf{f}^{(i)}\|}, p_k^{(i)} = \frac{\exp(\hat{\mathbf{c}}_k^T \cdot \hat{\mathbf{f}}^{(i)})}{\sum_m \exp(\hat{\mathbf{c}}_m^T \cdot \hat{\mathbf{f}}^{(i)})}$

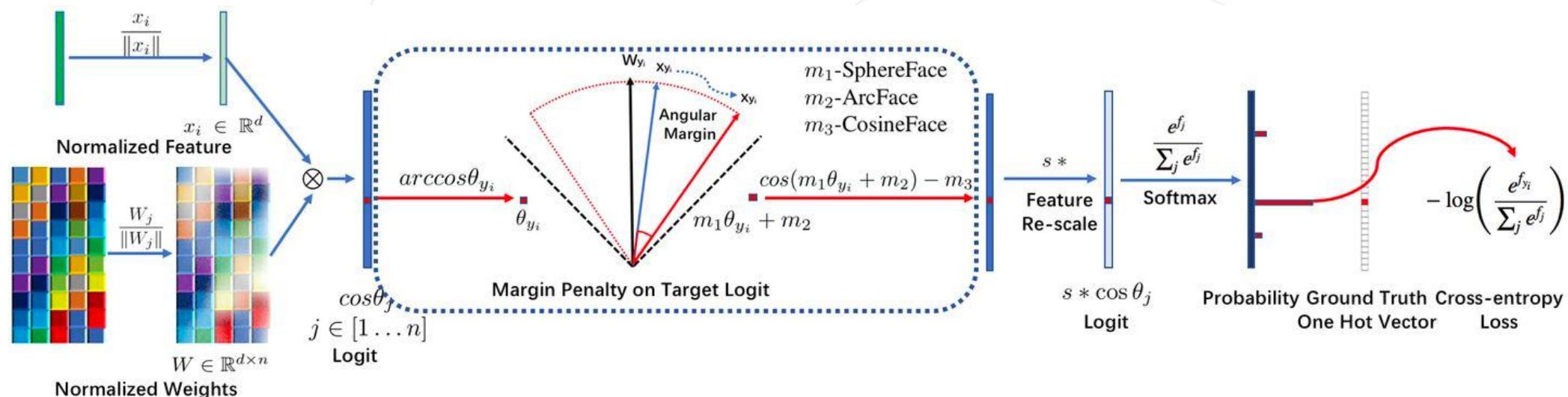


Feature visualization under different loss strategies, trained on MNIST.

Liu W, Wen Y, Yu Z, et al. SphereFace: Deep Hypersphere Embedding for Face Recognition [C]// CVPR. 2017.

- Additive Margin Loss

$$L = -\frac{1}{N} \sum_{i=1}^N \log \frac{e^{s(\cos(\theta_{y_i} + m))}}{e^{s(\cos(\theta_{y_i} + m))} + \sum_{j=1, j \neq y_i}^n e^{s \cos \theta_j}}$$



The overall pipeline for Additive Margin (ArcFace) loss.

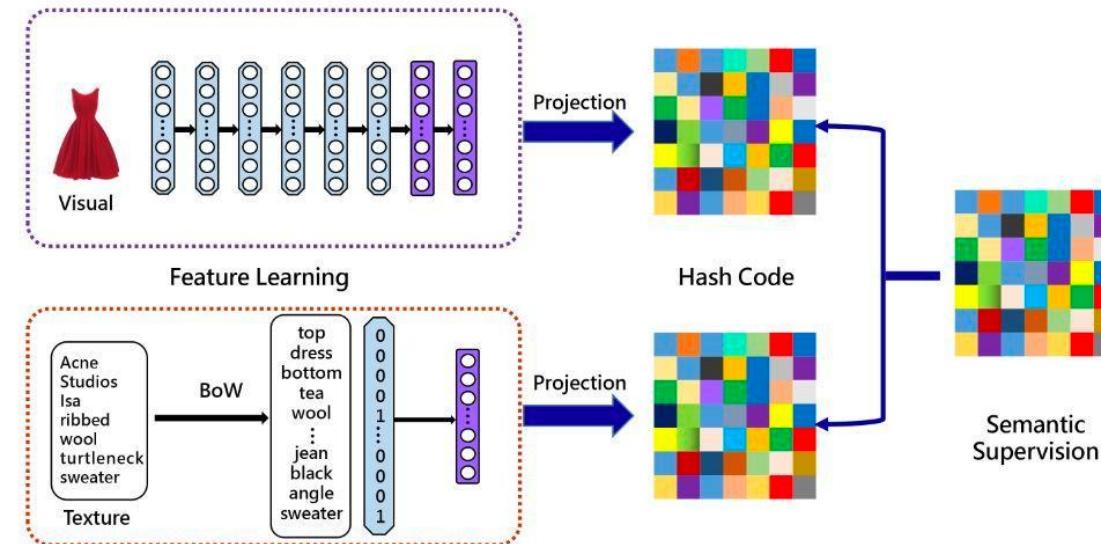
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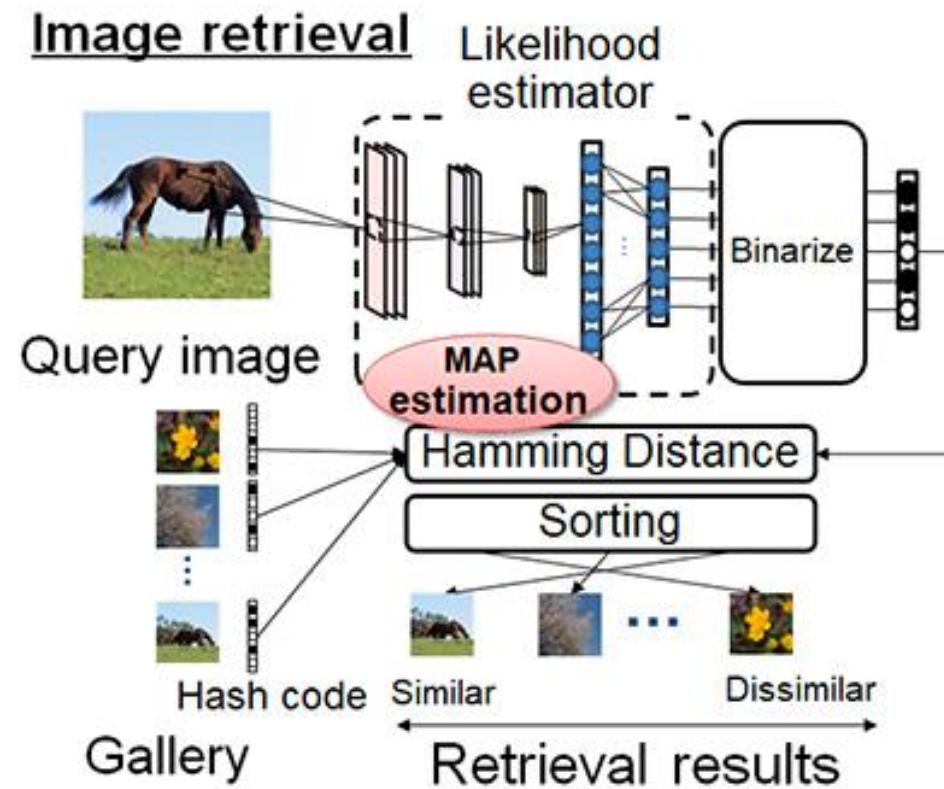
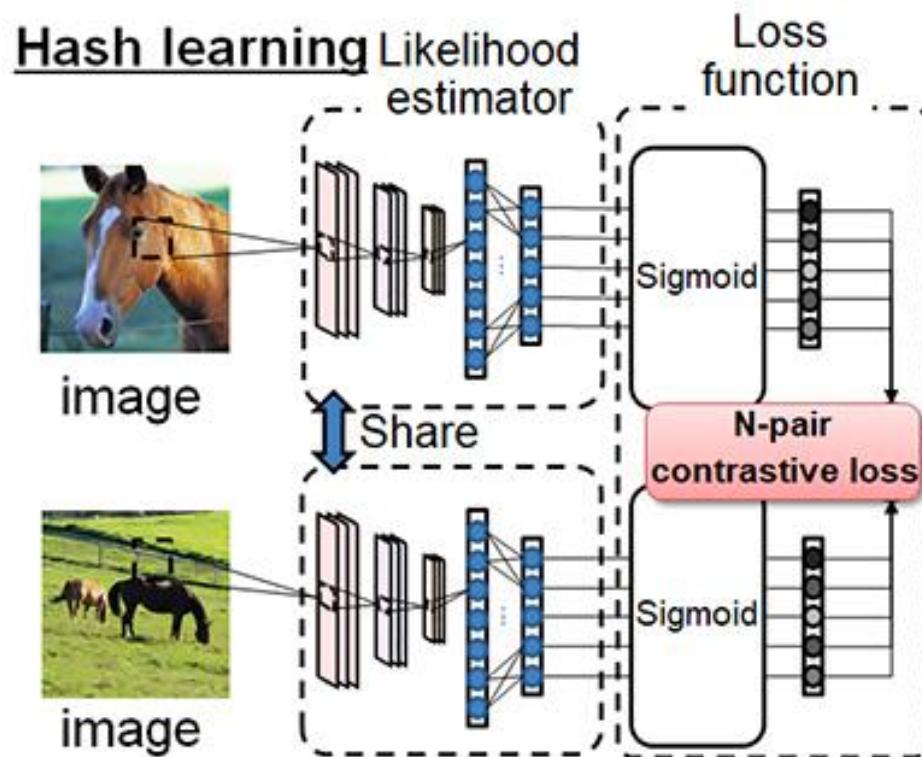
- What is Hamming DML?

- Hamming deep metric learning

Input -> Deep neural network -> **Binary** embedding



- What is Hamming DML?



- Why Binary?
 - > Considering an online image searching system:
 - Offline: training model, gallery features, extraction, **storage**
 - Online: probe feature extraction, **matching**
 - Hamming DML presents high **storage efficiency** and **matching speed**
 - > Lightweight models:
 - efficient for training and feature extraction
 - > Heavyweight models:
 - strong discriminative power



13.2 Self-supervised Learning

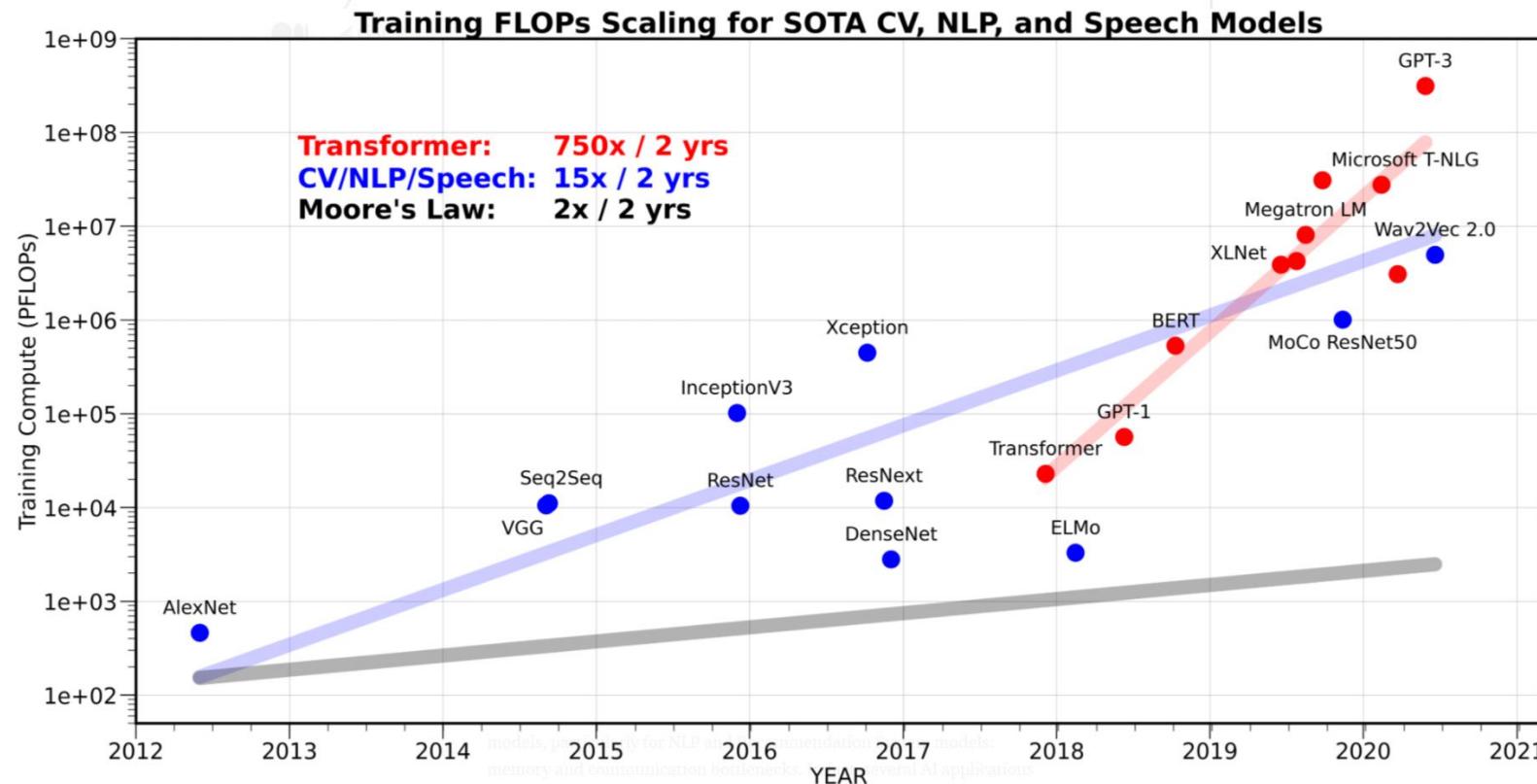
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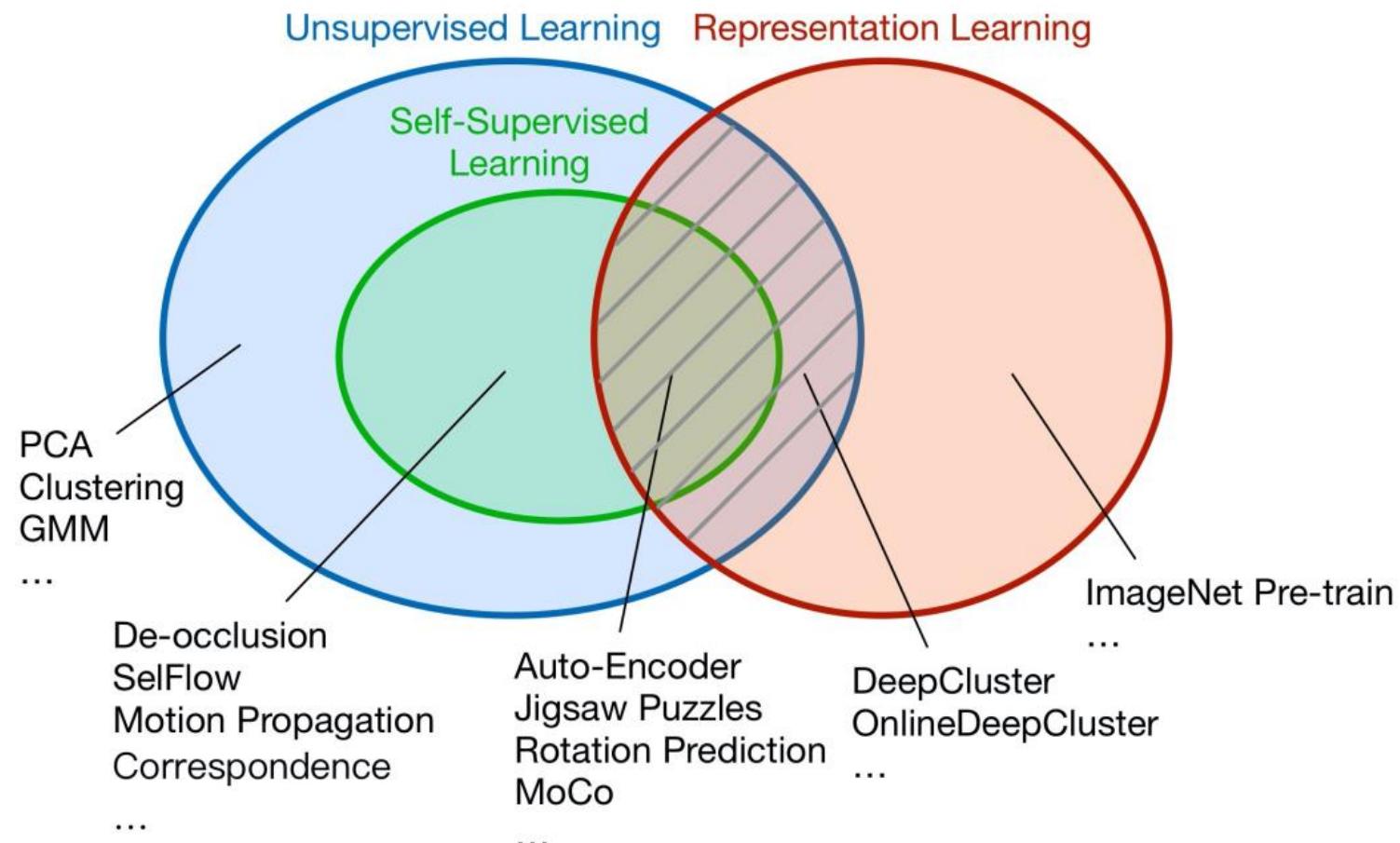
Thursday, May 20, 2021

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 - Part 2 Representative Methods**
 - Part 3 Understanding SSL**
 - Part 4 Challenges**
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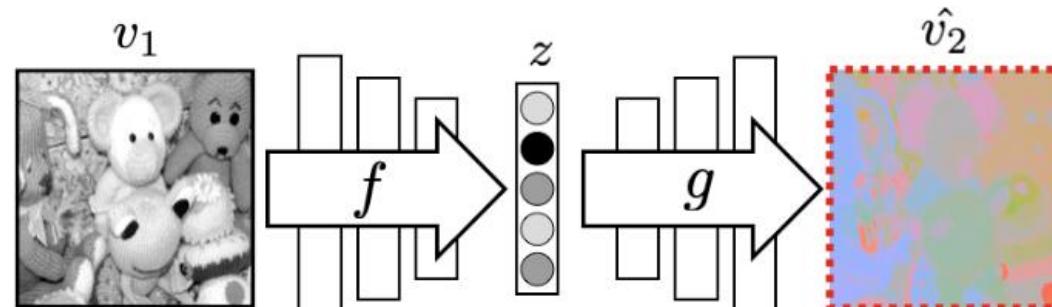
- Learn visual representation from images without annotations.
 - Motivated by the success of large-scale pretraining in NLP.



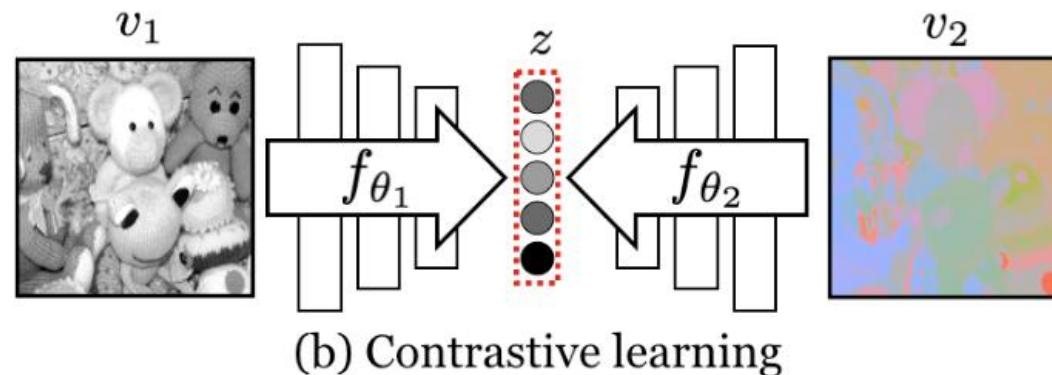


- Design learning tasks without annotations:

- Predictive methods
 - VAE, GAN, ...
- Contrastive methods
 - SimCLR, MOCO, ...
- Others
 - predicting rotation
 - solving jigsaw puzzles

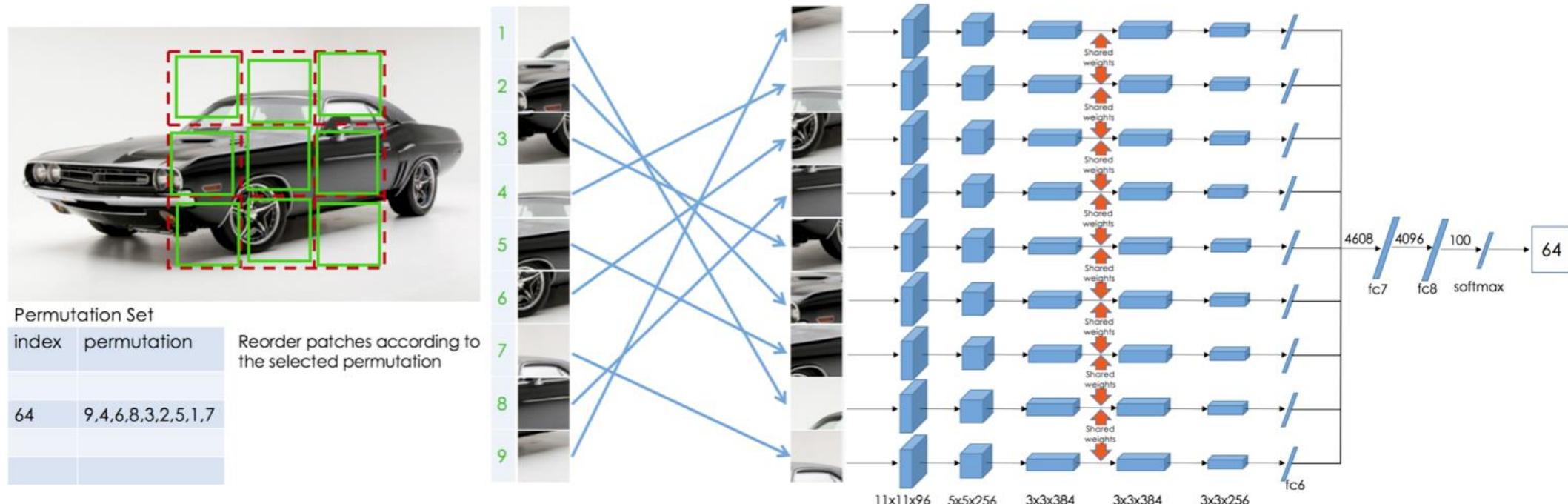


(a) Predictive learning



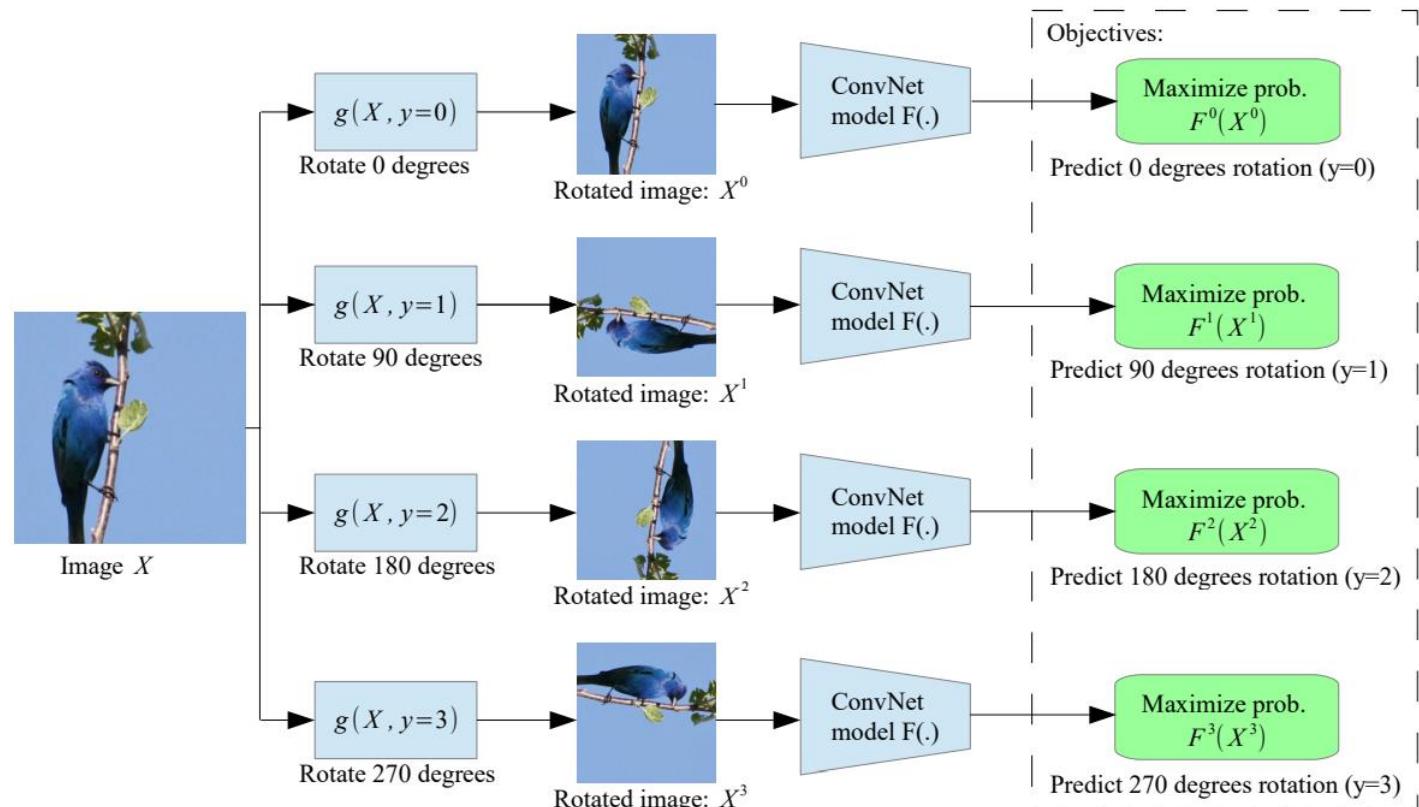
(b) Contrastive learning

- Solving jigsaw puzzles.



Noroози M, Favaro P. Unsupervised learning of visual representations by solving jigsaw puzzles[C]//European conference on computer vision. Springer, Cham, 2016: 69-84.

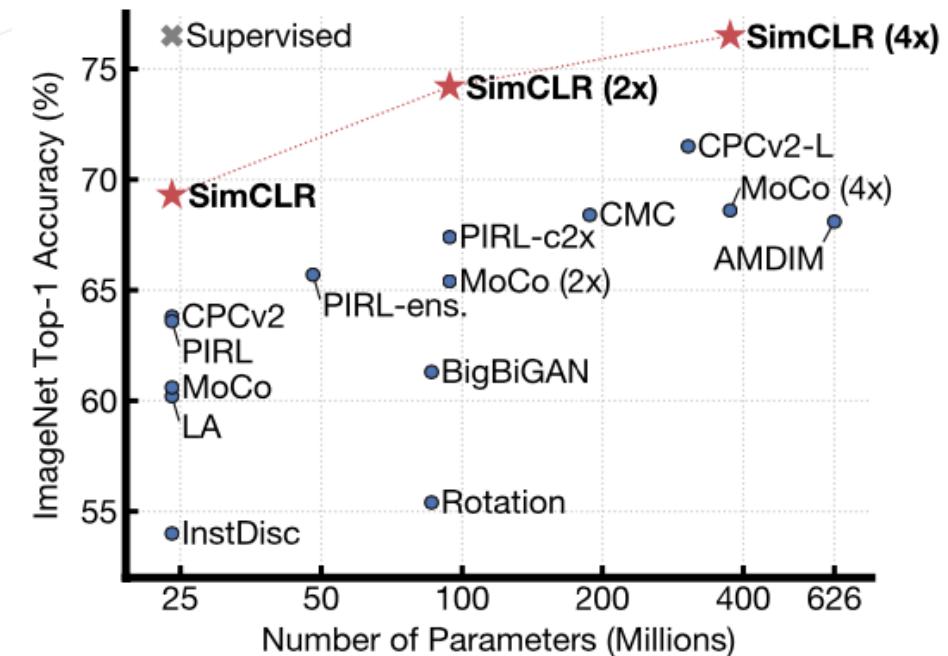
- Predicting rotation.



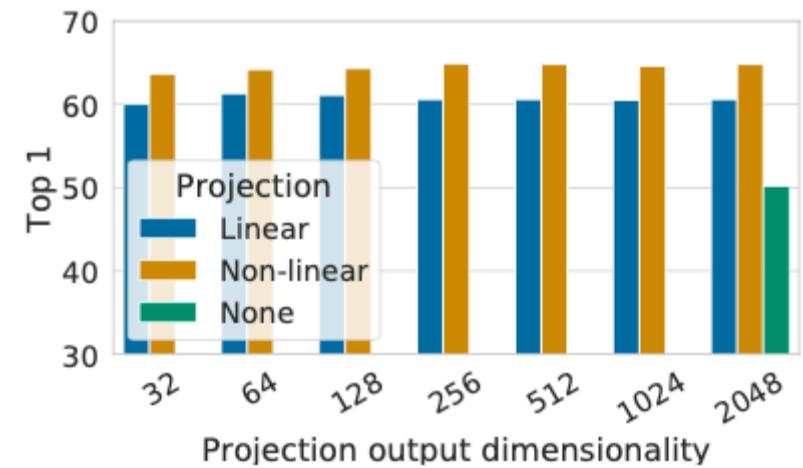
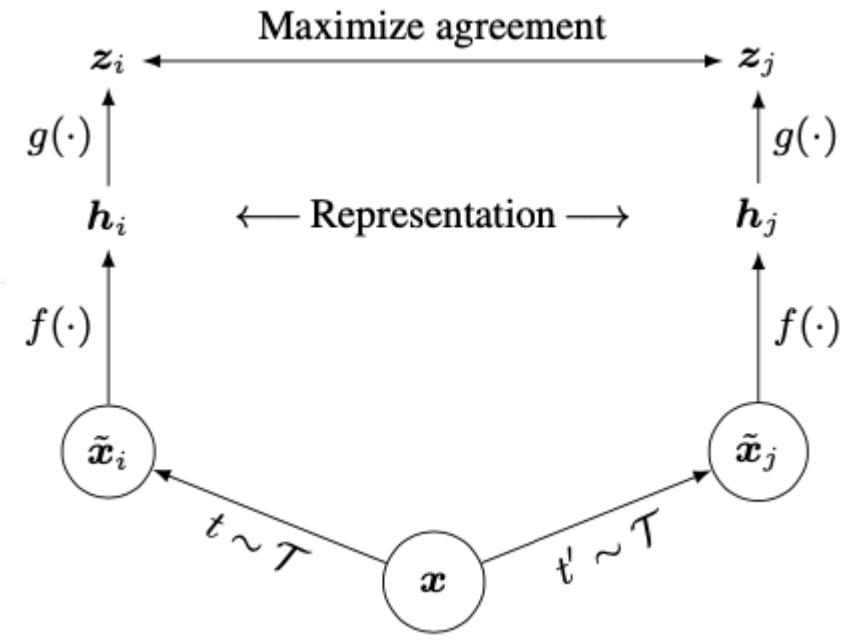
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- SimCLR
- A cornerstone for SSL
- Principle
 - The representations from the same image should be near
 - The representations from different images should be far away from each other



- Key insights:
 - Composition of multiple data augmentation operations
 - Introducing a learnable nonlinear transformation between the representation and the contrastive loss
 - Normalized embeddings and an appropriately adjusted temperature parameter
 - Larger batch sizes and longer training



- SimCLR

Then the loss function for a positive pair of examples (i, j) is defined as:

$$\ell_{i,j} = -\log \frac{\exp(\text{sim}(z_i, z_j)/\tau)}{\sum_{k=1}^{2N} \mathbb{1}_{[k \neq i]} \exp(\text{sim}(z_i, z_k)/\tau)},$$



(a) Original



(b) Crop and resize



(c) Crop, resize (and flip)



(d) Color distort. (drop)



(e) Color distort. (jitter)



(f) Rotate {90°, 180°, 270°}



(g) Cutout



(h) Gaussian noise

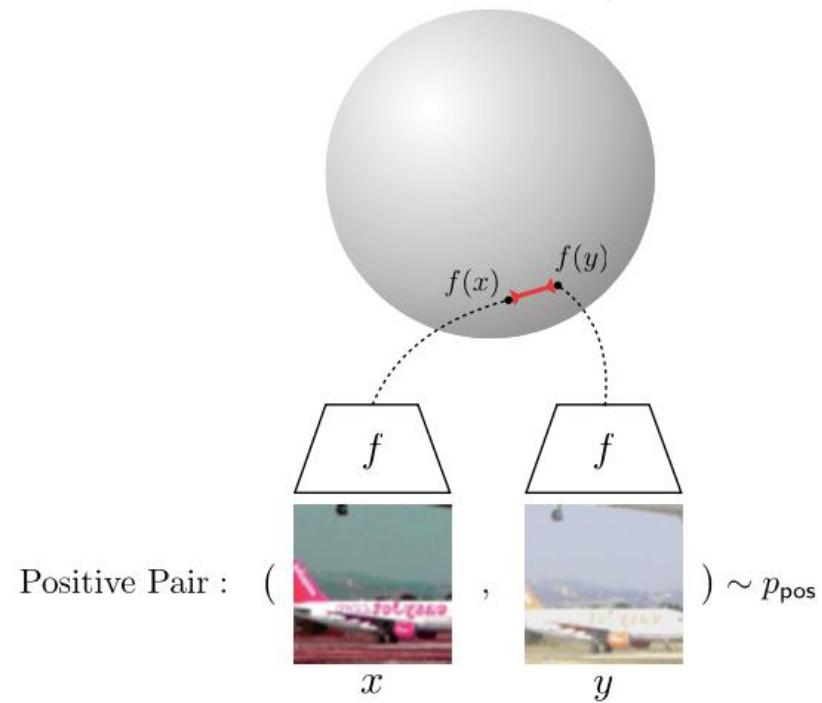


(i) Gaussian blur

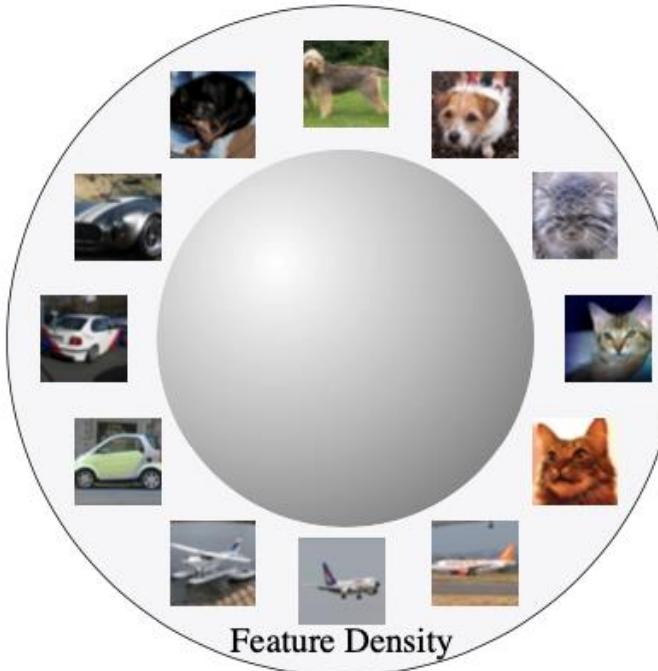


(j) Sobel filtering

- What the representations look like?

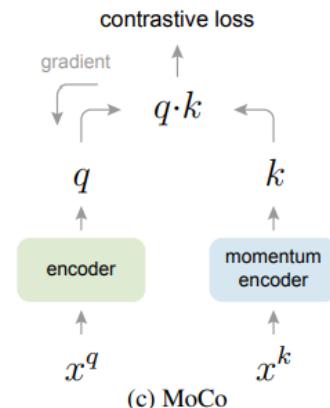
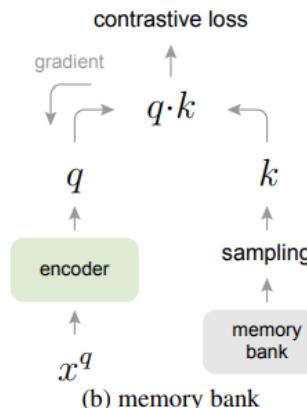
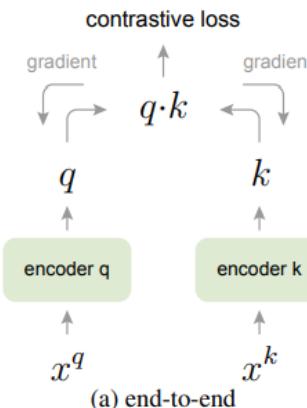
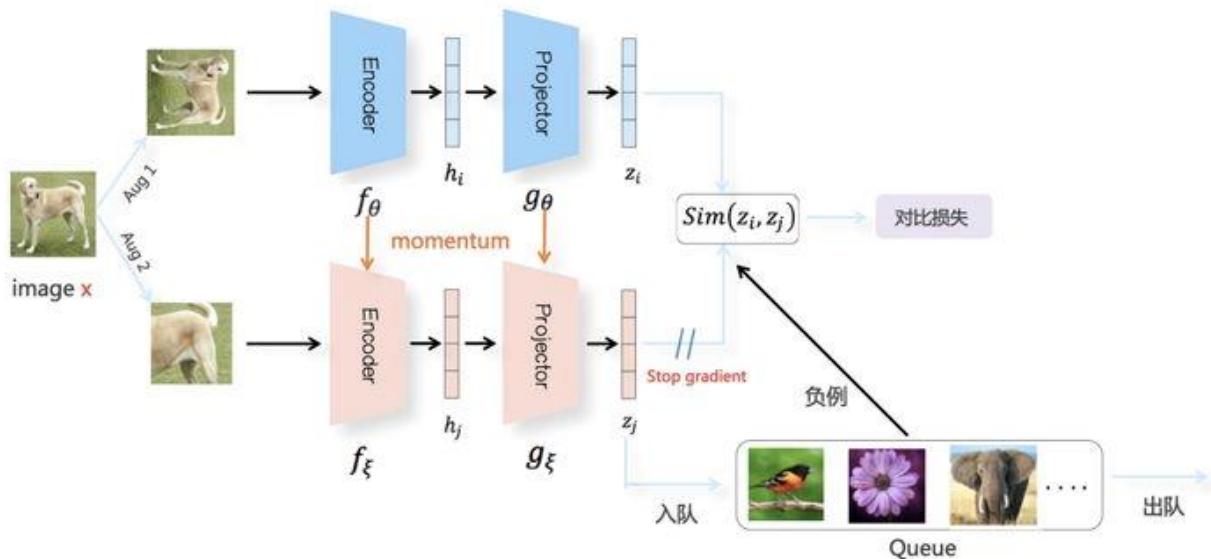


Alignment: Similar samples have similar features.



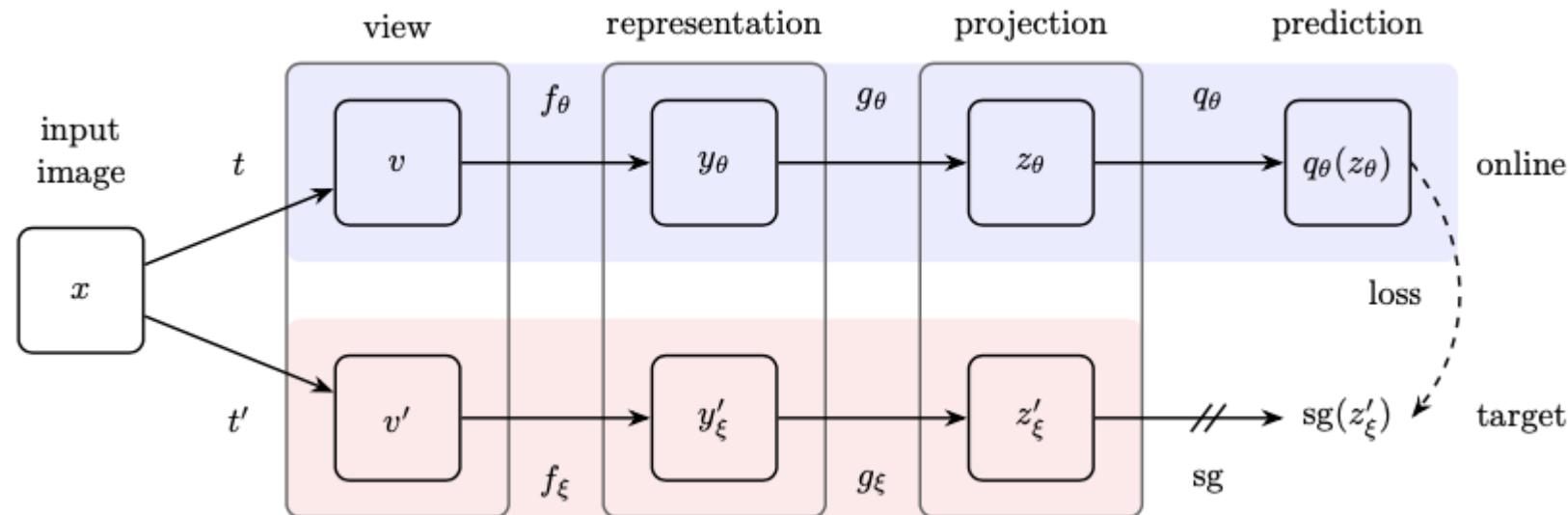
Uniformity: Preserve maximal information.

- MoCo
- Use buffer of representations to harvest more negative pairs



$$\theta_k \leftarrow m\theta_k + (1 - m)\theta_q.$$

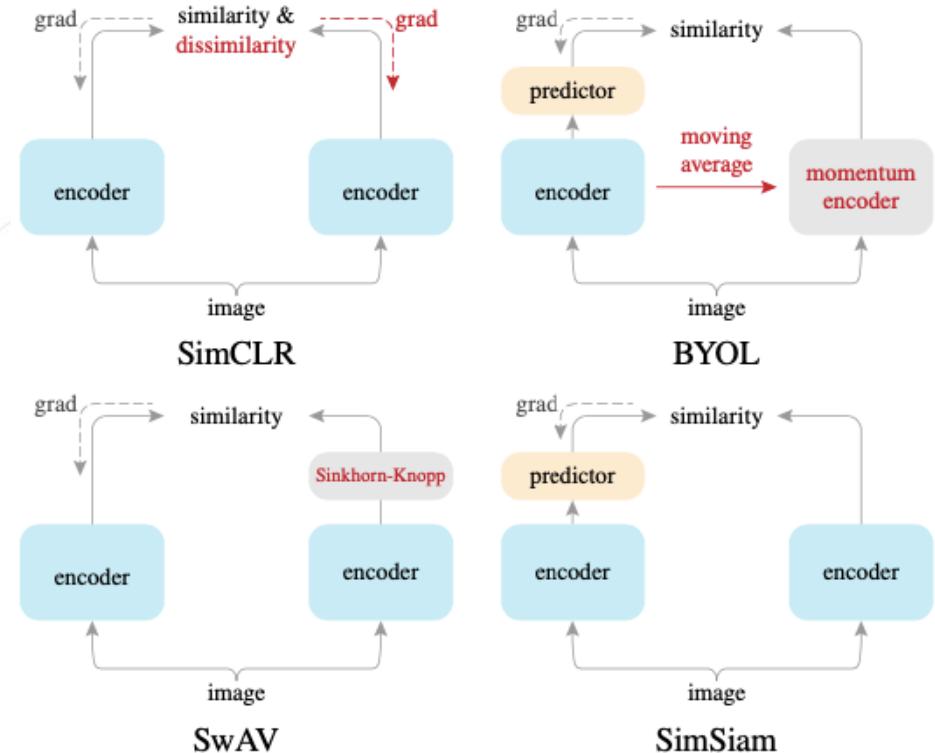
- BYOL
- Negative samples may be semantically similar
 - How to avoid model collapse after discarding negative pairs?



Grill J B, Strub F, Altché F, et al. Bootstrap your own latent: A new approach to self-supervised learning[J]. arXiv preprint arXiv:2006.07733, 2020.

- SimSiam
- The key component to avoid model collapse is stop-gradient

method	batch size	negative pairs	momentum encoder	100 ep	200 ep	400 ep	800 ep
SimCLR (repro.+)	4096	✓		66.5	68.3	69.8	70.4
MoCo v2 (repro.+)	256	✓	✓	67.4	69.9	71.0	72.2
BYOL (repro.)	4096		✓	66.5	70.6	73.2	74.3
SwAV (repro.+)	4096			66.5	69.1	70.7	71.8
SimSiam	256			68.1	70.0	70.8	71.3

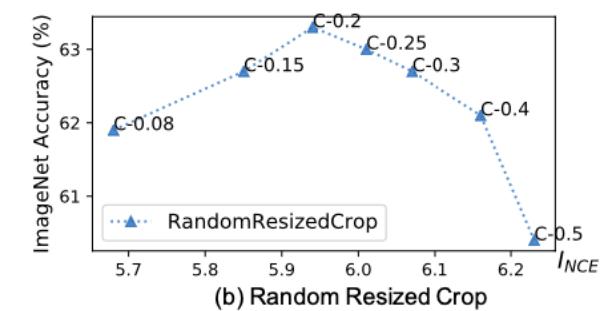
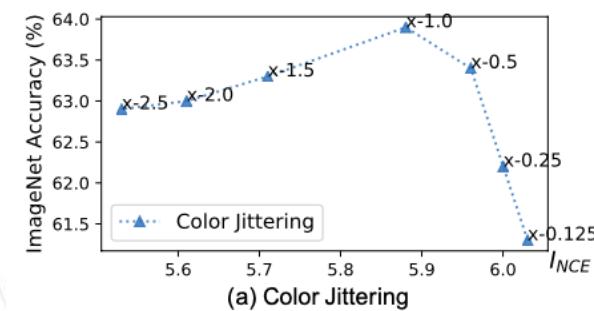
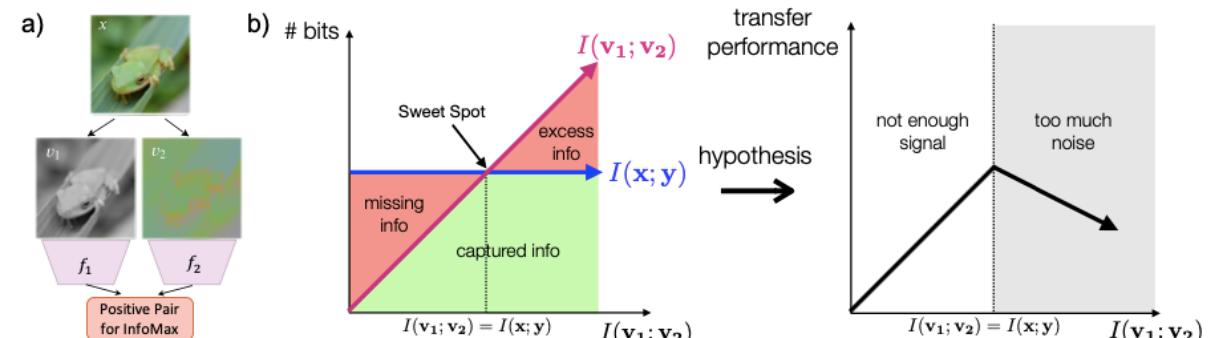


Outline

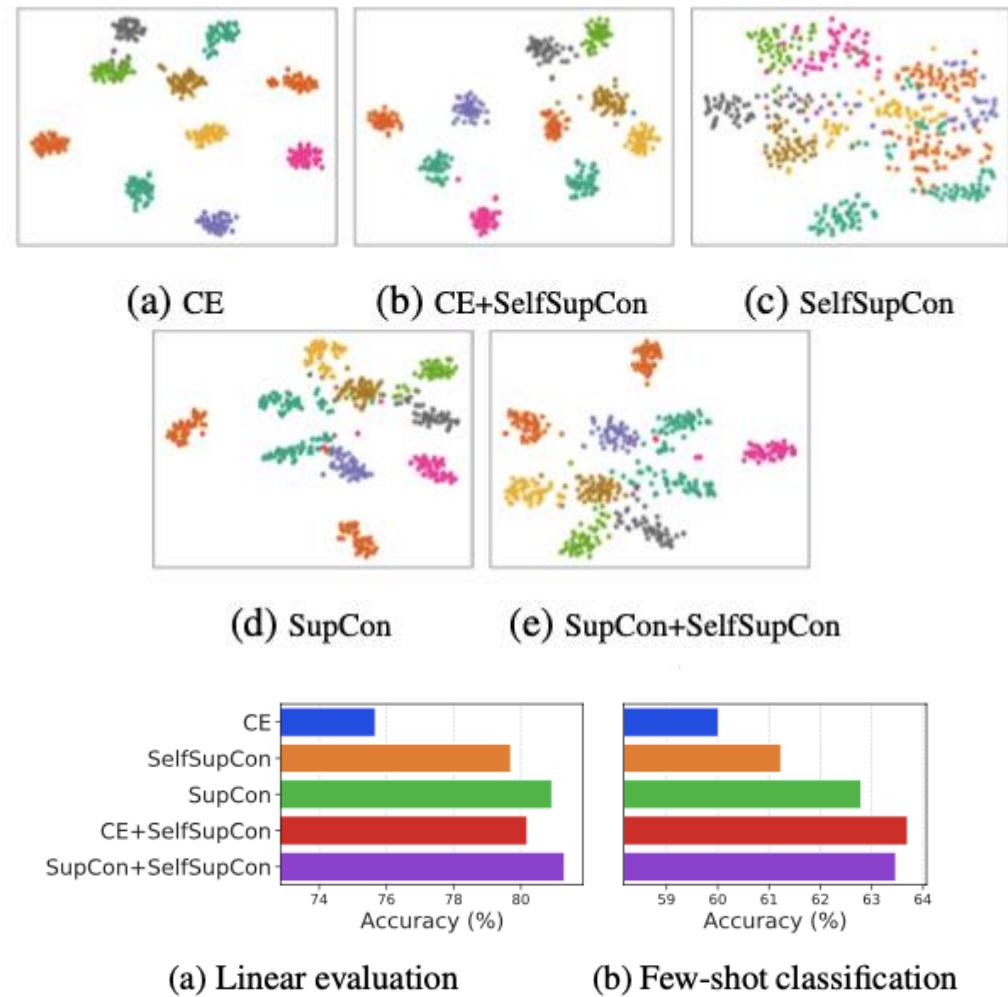
-
- Part 1 Introduction**
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-

- What augmentation should we use in SSL?

- A tradeoff between missing info and excess info
- Learnable augmentation in an adversarial way



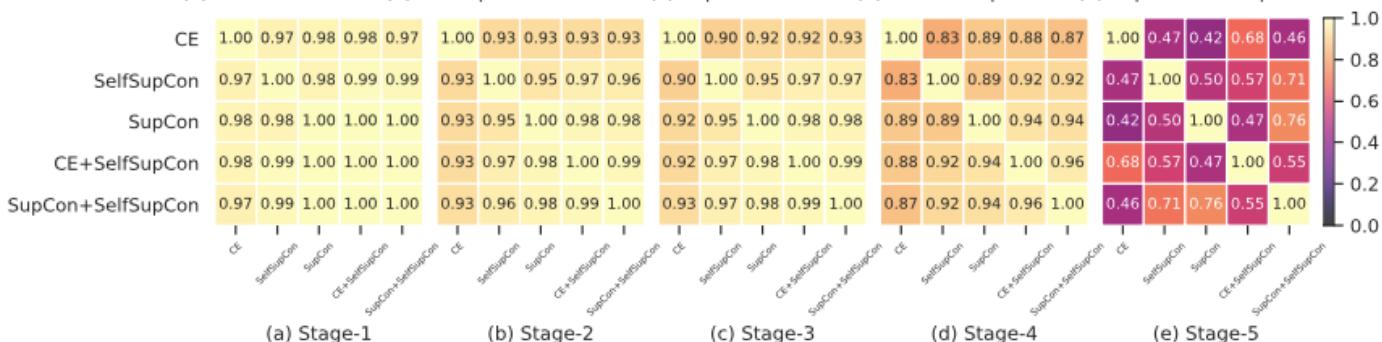
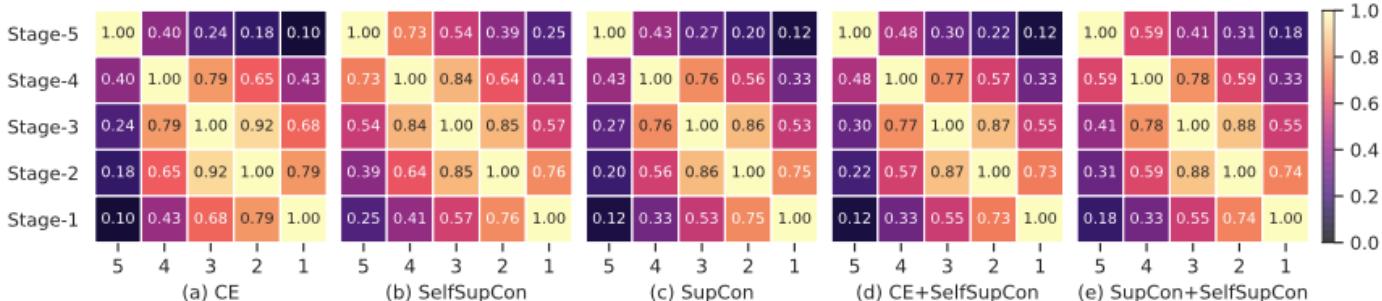
- How is the transferability of SSL?
 - Compared with supervised learning, the representations show more intra-variance.
 - Combining SL with SSL improves final performance.



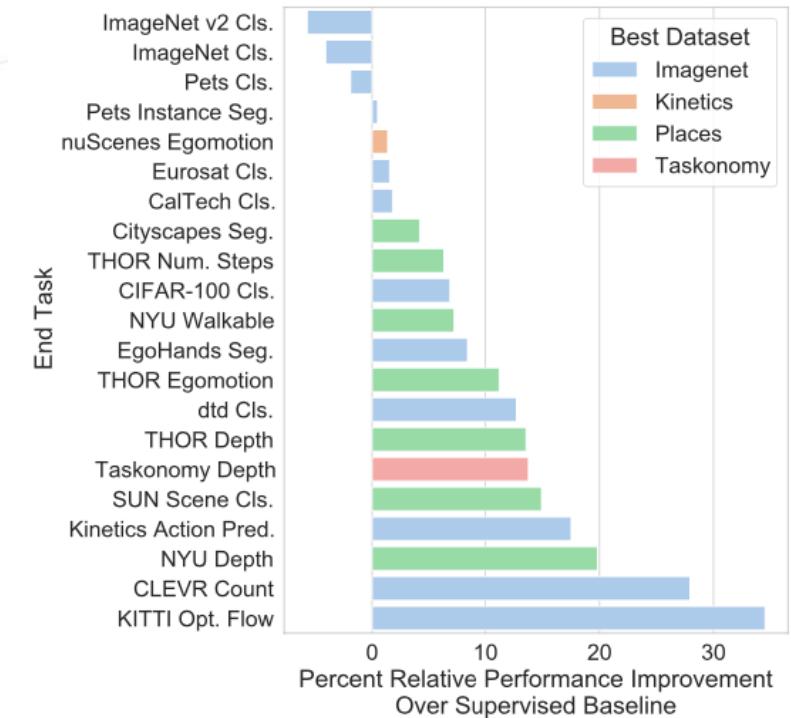
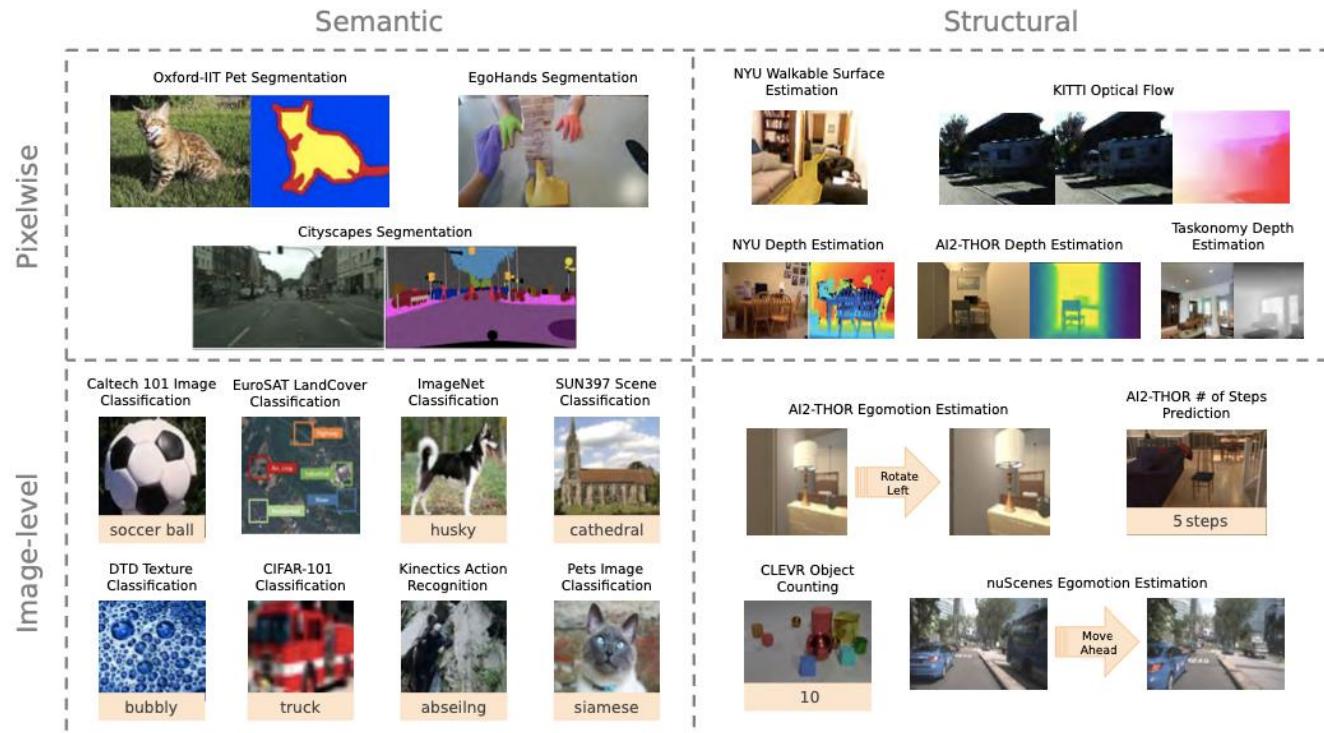
- SSL approaches learn more

low/mid-level feature

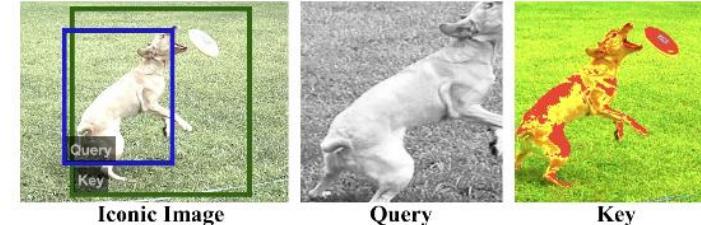
- The similarity of different layers' weight learned in SSL is higher
- The similarity between weights of SL and SSL is low only in stage-5



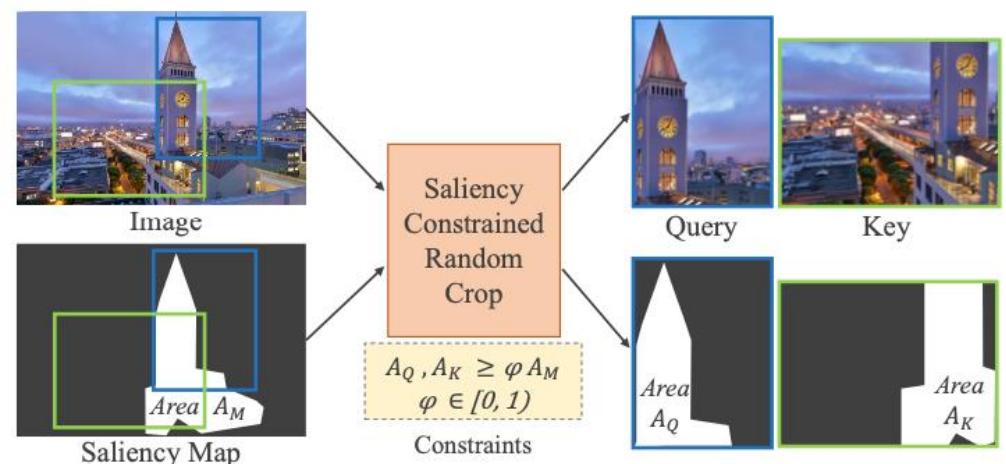
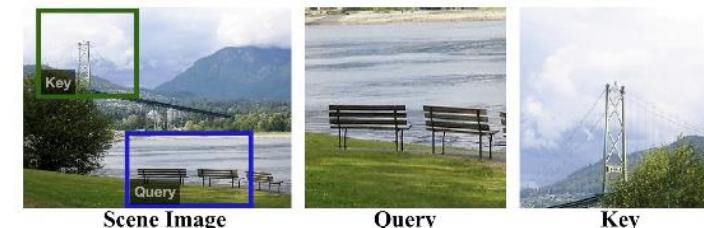
- SSL show higher transferability in most down-stream tasks.



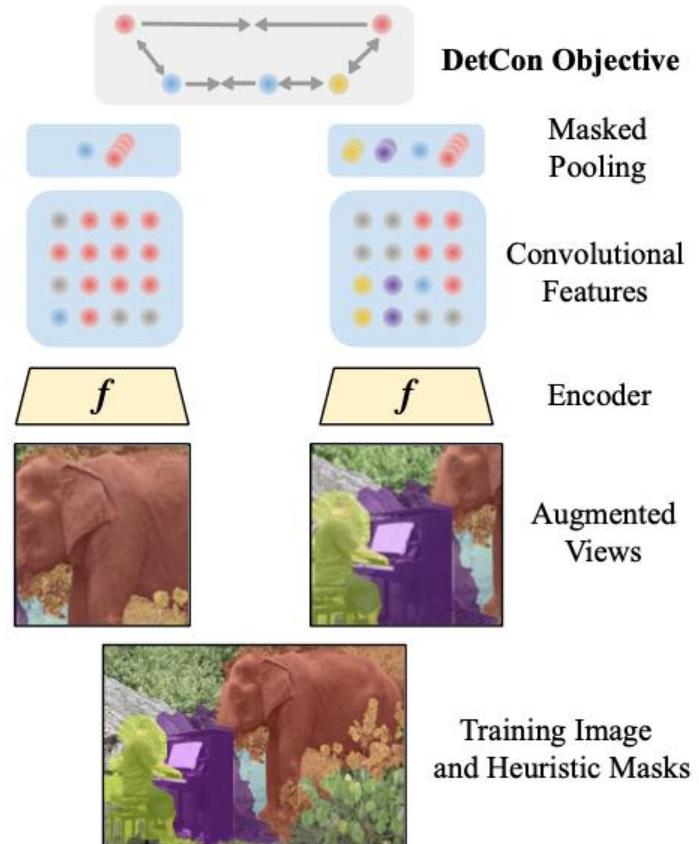
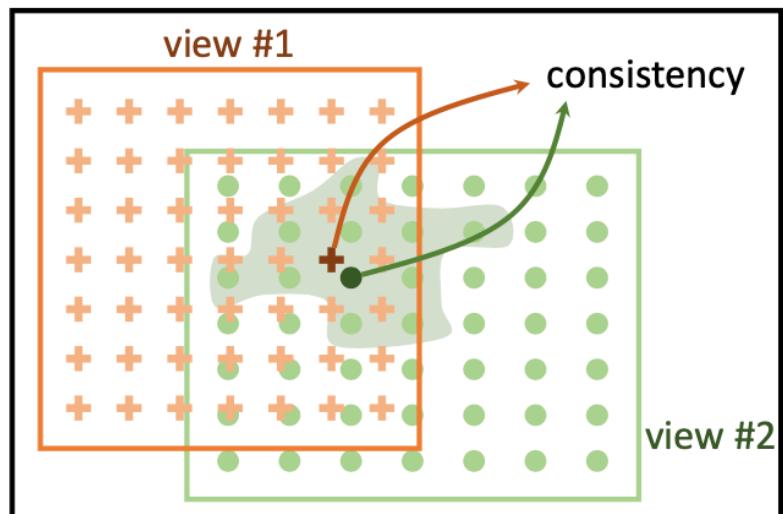
- Dataset bias in SSL
 - Augmented crops from the same image may be semantically different
 - Images in ImageNet are iconic and object-centric
 - Unsupervised saliency map can be used to guide the crops



(a) Poor visual grounding ability



- Dense contrastive learning for dense prediction
 - Contrast representations in patch or pixel level



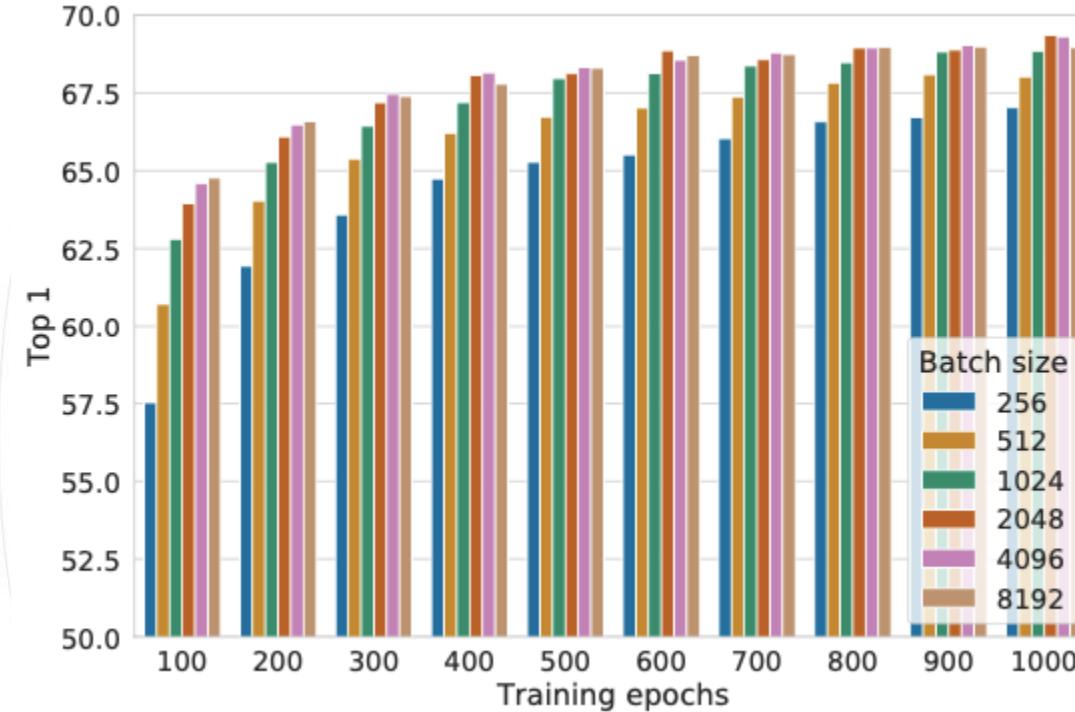
Hénaff O J, Koppula S, Alayrac J B, et al. Efficient Visual Pretraining with Contrastive Detection[J]. arXiv preprint arXiv:2103.10957, 2021.

Xie Z, Lin Y, Zhang Z, et al. Propagate Yourself: Exploring Pixel-Level Consistency for Unsupervised Visual Representation Learning[J]. arXiv preprint arXiv:2011.10043, 2020.

Outline

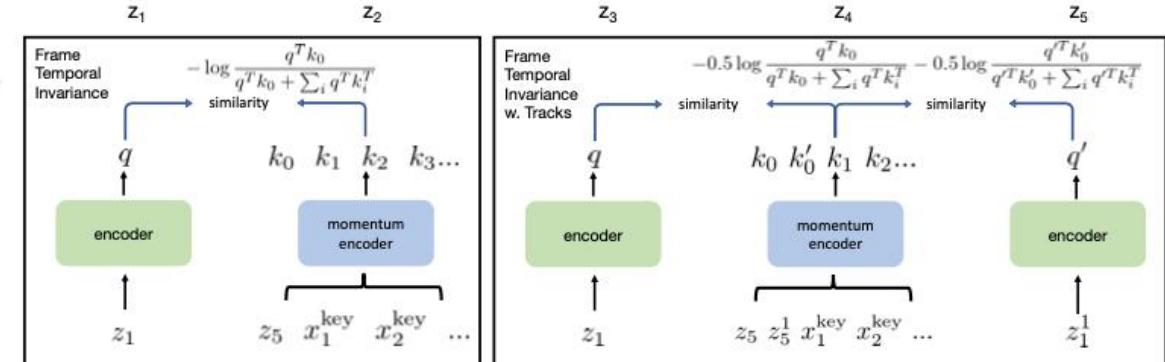
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- Performance highly depends on large epochs and batch-size
 - Typically 800 epochs and 4096 batch-size for ImageNet
 - SimCLR:



- Only utilize augmentation-invariance in SSL.

- SSL is better only at occlusion invariance
- Utilize video with unsupervised tracking to harvest images under different views.



Dataset	Method	Occlusion		Viewpoint		Illumination Dir.		Illumination Color		Instance		Instance+Viewpoint	
		Top-10	Top-25	Top-10	Top-25	Top-10	Top-25	Top-10	Top-25	Top-10	Top-25	Top-10	Top-25
Imagenet	Sup. R50	80.89	74.21	89.54	82.62	94.63	89.08	99.88	99.38	66.11	59.44	70.17	63.47
Imagenet	MOCOV2	84.19	77.88	85.15	75.08	90.28	80.76	99.66	97.11	62.49	55.01	67.4	60.52
Imagenet	PIRL	84.46	78.38	85.8	76.08	87.7	78.45	99.68	97.19	52.97	46.79	57.01	51.03

Zbontar J, Jing L, Misra I, et al. Barlow twins: Self-supervised learning via redundancy reduction[J]. arXiv preprint arXiv:2103.03230, 2021.