

Calc 3 Review

$$\tau = 2\pi$$

Part 1

Lines and Surfaces

$$\text{Line: } \vec{r}(t) = \vec{r}_0 + t * \vec{v}$$

$$\text{Line: } \frac{x - x_0}{a} = \frac{y - y_0}{b} = \frac{z - z_0}{c}$$

$$\text{Line Segment: } \vec{r}(t) = (1 - t)\vec{r}_0 + t * \vec{r}_1 \text{ for } 0 \leq t \leq 1$$

$$\text{Plane: } \vec{n} \cdot (\vec{r} - \vec{r}_0) = 0$$

$$\text{Elliptic Paraboloid: } \frac{z}{c} = \frac{x^2}{a} + \frac{y^2}{b}$$

$$\text{Hyperbolic Paraboloid: } \frac{z}{c} = \frac{x^2}{a} - \frac{y^2}{b}$$

$$\text{Ellipsoid: } \frac{x^2}{a} + \frac{y^2}{b} + \frac{z^2}{c} = 1$$

$$\text{Cone: } \frac{x^2}{a} + \frac{y^2}{b} - \frac{z^2}{c} = 0$$

$$\text{Hyperboloid of 1 sheet: } \frac{x^2}{a} + \frac{y^2}{b} - \frac{z^2}{c} = 1$$

$$\text{Hyperboloid of 2 sheets: } \frac{x^2}{a} + \frac{y^2}{b} - \frac{z^2}{c} = -1$$

Vectors

$$|\vec{r}| = \sqrt{a_x^2 + a_y^2 + a_z^2}$$

$$\vec{a} \cdot \vec{b} = a_1 * b_1 + b_2 * b_3$$

$$\vec{a} \cdot \vec{b} = |\vec{a}||\vec{b}| * \cos \theta, 0 \leq \theta \leq \tau$$

$$\text{comp}_a \vec{b} = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}|}$$

$$\text{proj}_a \vec{b} = \text{comp}_a \vec{b} * \frac{\vec{a}}{|\vec{a}|}$$

$$\vec{a} \times \vec{b} = \begin{vmatrix} i & j & k \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

$$\text{Distance from point to a line} = \text{comp}_{\vec{n}} \vec{b}$$

$$|\vec{a} \times \vec{b}| = |\vec{a}||\vec{b}| * \sin \theta$$

Vector Functions

$$\text{Arc Length} = \int_a^b |\vec{r}'(t)| dt, \vec{a} = \vec{r}', v = |\vec{v}|$$

$$\vec{T} = \vec{v}/|\vec{v}|$$

$$\vec{B} = \vec{v} \times \vec{a}$$

$$\vec{B} = \vec{T} \times \vec{N}$$

$$\vec{N} = \vec{N} \times \vec{B}$$

$$a_T = \text{comp}_T \vec{a} = \vec{a} \cdot \vec{T}$$

$$\vec{w} = \vec{a} a_T * \vec{T}$$

$$\vec{w} = a_N \vec{N}$$

$$a_N = |\vec{w}|$$

$$\vec{N} = \frac{\vec{w}}{a_N}$$

$$\kappa = \frac{|\vec{a} \times \vec{v}|}{|\vec{v}|^3}$$

Part 2 Multivariable Differentiation

$$f_x(x, y) = f_x = \frac{\partial f}{\partial x}$$

$$f_{xy} = f_{yx}$$

$$dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy$$

$$\text{Linear Approx: } f(x, y) \approx f(a, b) + dz$$

$$\text{Chain Rule: } \frac{\partial z}{\partial s} = \frac{\partial z}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s}$$

$$\text{Implicit Diff: } \frac{\partial z}{\partial x} = -\frac{F_x}{F_z}$$

$$\text{Gradient: } \nabla f = \langle f_x, f_y, f_z \rangle$$

$$\text{Normal of Tangent Plane: } \vec{n} = \nabla f$$

$$\text{Directional Derivative: } D_{\vec{u}} f = \nabla f \cdot \vec{u}$$

$$\text{2nd Derivative Test: } D = f_{xx} * f_{yy} - f_{xy}^2$$

$$(a) D > 0 \text{ and } f_{xx} > 0 \rightarrow f(a, b) \text{ is a local min}$$

$$(b) D > 0 \text{ and } f_{xx} < 0 \rightarrow f(a, b) \text{ is a local max}$$

$$(c) D < 0 \rightarrow f(a, b) \text{ is a saddle point}$$

$$\text{Lagrange Multipliers: } \nabla f = \lambda \nabla g + \mu \nabla h$$

$$g = k$$

$$h = c$$

Part 3 Multiple Integrals:

$$\text{Double Integral: } \iint_R f(x, y)$$

$$\text{Triple Integral: } \iiint_R f(x, y, z)$$

$$\iint_D dA = \text{Area}(D)$$

$$\iiint_B dV = \text{Volume}(B)$$

$$\text{Iterated Integral: } \iint_R f(x, y) dA = \int_a^b \int_c^d f(x, y) dy dx = \int_c^d \int_a^b f(x, y) dx dy$$

$$\text{Double Integral (Constant Bounds): } \iint_R g(x)h(y) dA = \int_a^b g(x) dx \int_c^d h(y) dy$$

$$\text{Iterated Integral: } \iiint_B f(x, y, z) dV = \int_r^s \int_c^d \int_a^b f(x, y, z) dx dy dz$$

$$\text{Triple Integral (Constant Bounds): } \iiint_B f(x)g(y)h(z) dV = \int_a^b f(x) dx \int_c^d g(y) dy \int_r^s h(z) dz$$

Change of Variable:

$$\text{2D Jacobian: } J = |\nabla x(u, v) \times \nabla y(u, v)| = \left\| \begin{pmatrix} \nabla x(u, v) \\ \nabla y(u, v) \end{pmatrix} \right\|$$

$$\text{3D Jacobian: } J = \left\| \begin{pmatrix} \nabla x(u, v, w) \\ \nabla y(u, v, w) \\ \nabla z(u, v, w) \end{pmatrix} \right\|$$

$$dA = dy dx dz = J du dv dw$$

$$\text{Polar: } r^2 = x^2 + y^2$$

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$z = z$$

$$J = r$$

$$\text{Spherical: } \rho^2 = x^2 + y^2 + z^2$$

$$x = \rho \sin \phi \cos \theta$$

$$y = \rho \sin \phi \sin \theta$$

$$z = \rho \cos \phi$$

$$J = \rho^2 \sin(\phi)$$

Applications of Multiple Integrals

$$\text{Mass: } m = \int \int \int_E \rho(x, y, z) dV$$

$$\text{Moment: } M_{vw} = \int \int \int_E u \rho(u, v, w) dV$$

$$\text{Center of Mass Cord: } \bar{u} = \frac{M_{vw}}{m}$$

$$\text{Center of Mass: } c_m = (\bar{x}, \bar{y}, \bar{z})$$

Part 4 Vector Fields

Line integral:

$$\int_C \vec{F} \cdot d\vec{r} = \int_C F \cdot \vec{T} ds$$

$$\int_C f(x, y) ds = \int_a^b f(x(t), y(t)) \sqrt{\frac{dx^2}{dt} + \frac{dy^2}{dt}} dt$$

$$\int_C \vec{F} \cdot d\vec{r} = \int_C P dx + Q dy + R dz \text{ where } \vec{F} = P\vec{i} + Q\vec{j} + R\vec{k}$$

Vector Operations 2:

$$\text{Curl: } \text{curl} \vec{F} = \nabla \times \vec{F}$$

$$\text{curl}(\nabla f) = \nabla \times \nabla f = 0$$

$$\text{Divergence: } \text{div} \vec{F} = \nabla \cdot \vec{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

$$\text{div}(\text{curl}(\vec{F})) = \nabla \cdot \nabla \times \vec{F} = 0$$

$$\text{Parametric surface: } \vec{r}(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$$

Surface Area:

$$\vec{N} = \vec{r}_u \times \vec{r}_v$$

$$A(S) = \int \int_D |\vec{N}| dA$$

$$A(S) = \int \int_D \sqrt{1 + z_x^2 + z_y^2} dA$$

Surface Integrals:

$$\int \int f(x, y, z) dS = \int \int f(\vec{r}(u, v)) |\vec{N}| dA$$

$$\int \int f(x, y, z) dS = \int \int_D f(x, y, g(x, y)) \sqrt{1 + z_x^2 + z_y^2} dA$$

$$\vec{n} = \frac{\vec{N}}{|\vec{N}|}$$

$$\int \int_S \vec{F} \cdot d\vec{S} = \int \int_S \vec{F} \cdot \vec{n} dS$$

$$\int \int_S \vec{F} \cdot d\vec{S} = \int \int_D \vec{F} \cdot \vec{N} dA$$

$$\int \int_S \vec{F} \cdot d\vec{S} = \int \int_D (-Pg_x - Qg_y + R) dA$$

Conservative Vector Fields

$$\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x} \text{ and } D \text{ is an open simply-connected region}$$

$$\vec{F}(x, y, z) = \nabla f$$

$$\oint \vec{F} \cdot d\vec{r} = 0$$

$$\int_C \nabla f \cdot d\vec{r} = f(\vec{r}(b)) - f(\vec{r}(a))$$

Green's Theorem:

$$\int_C P dx + Q dy = \int \int_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$

$$\oint_C \vec{F} \cdot d\vec{r} = \int \int_D (\nabla \times \vec{F}) \cdot \vec{k} dA$$

$$\oint_C \vec{F} \cdot \vec{n} ds = \int \int_D \nabla \cdot \vec{F}(x, y) dA$$

Stoke's Theorem

$$\int_C \vec{F} \cdot d\vec{r} = \int \int_S \nabla \times \vec{F} \cdot d\vec{S}$$

Divergence Theorem

$$\int \int_S \vec{F} \cdot d\vec{S} = \int \int \int_E \nabla \cdot \vec{F} dV$$