

Self driving infrastructure

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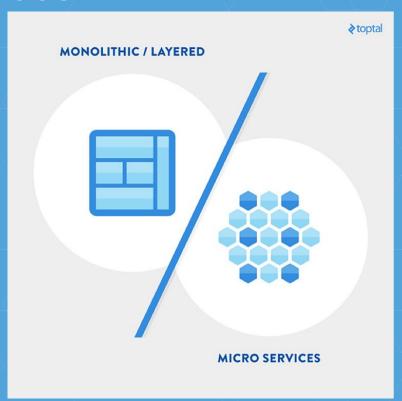
Topics

- Cluster management systems
- Today's problems with operating cluster management systems
- A self-driving approach



Motivation: microservices

- Increased operational cost
 - a lot of components
 - dynamic dependencies
 - fast deployment iteration
- Solution: automation



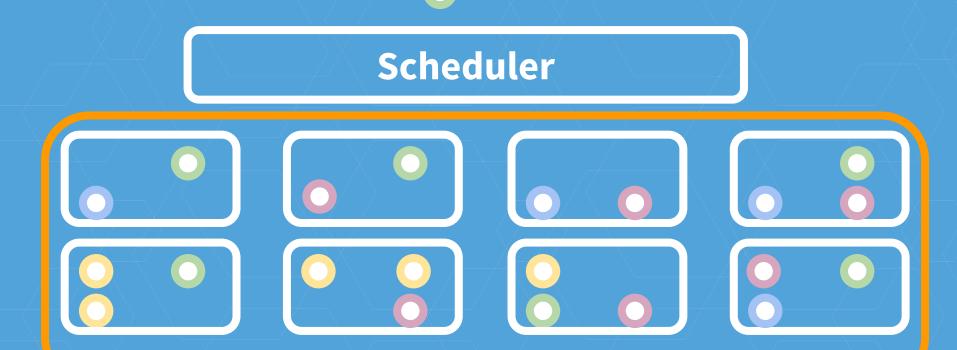


Cluster management system

- Automation
 - Scheduling
 - Deployment
 - Healing
 - Discovery/load balancing
 - Scaling



Scheduling





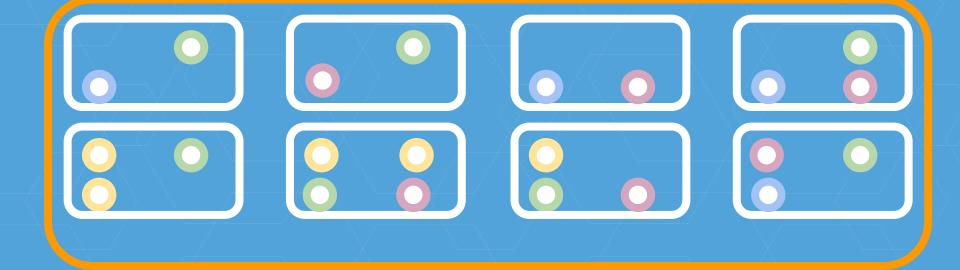
Scheduling

Scheduler



Scheduling

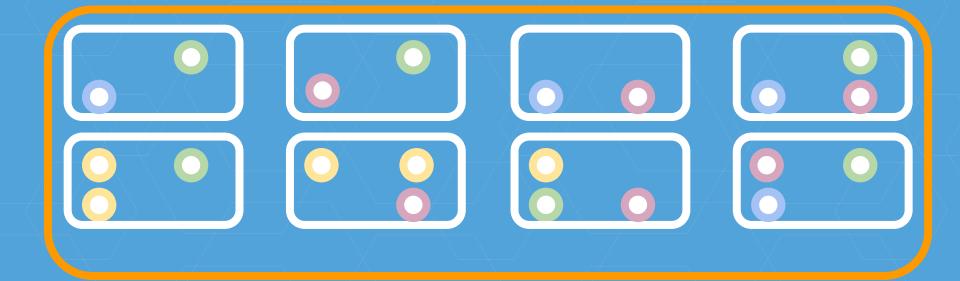
Scheduler





Discovery

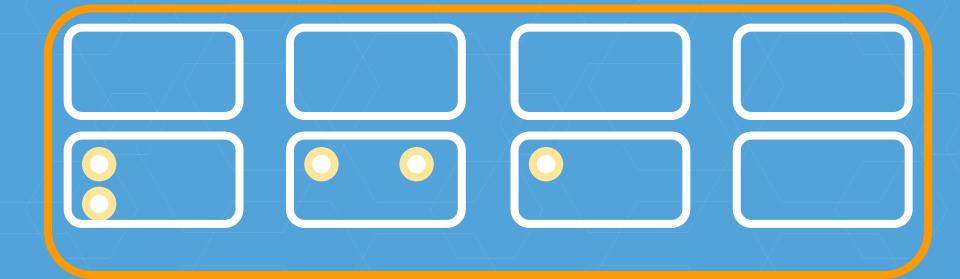
color=yellow





Discovery

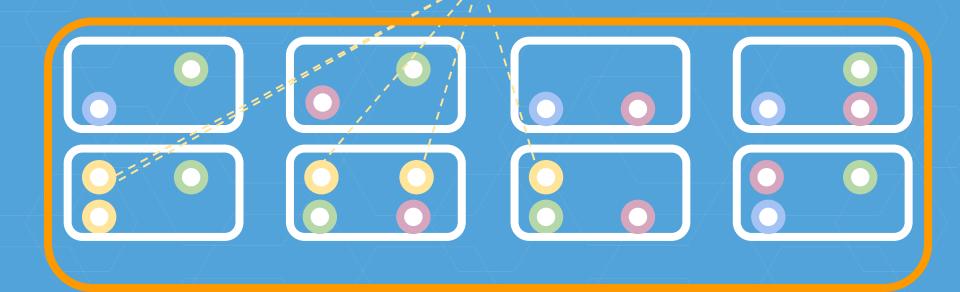
color=yellow Select color = yellow





Load balancing

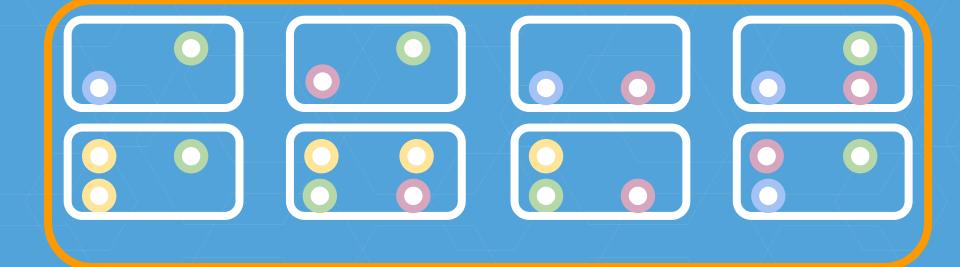
yellow.mycluster
Select color = yellow





Controller manager

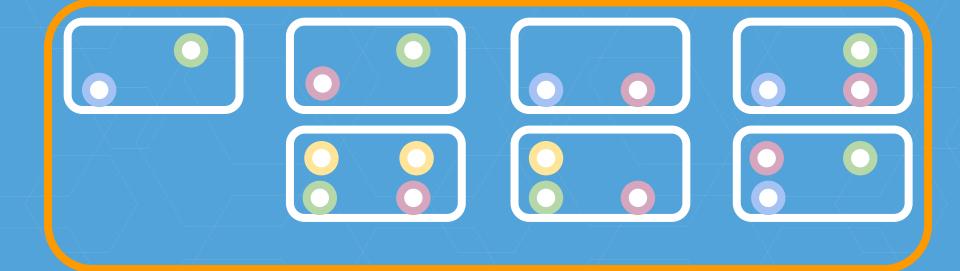
• 5





Controller manager

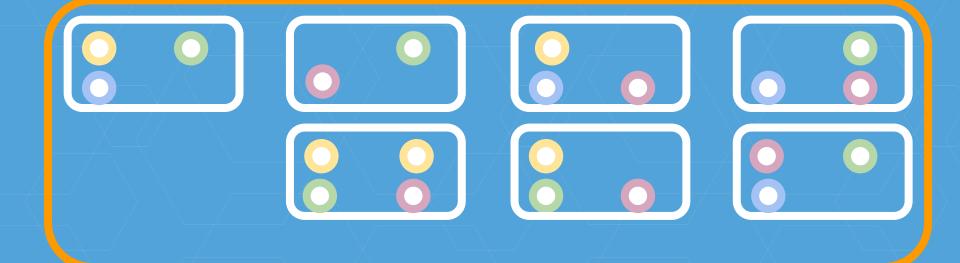
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Controller manager

• 5



























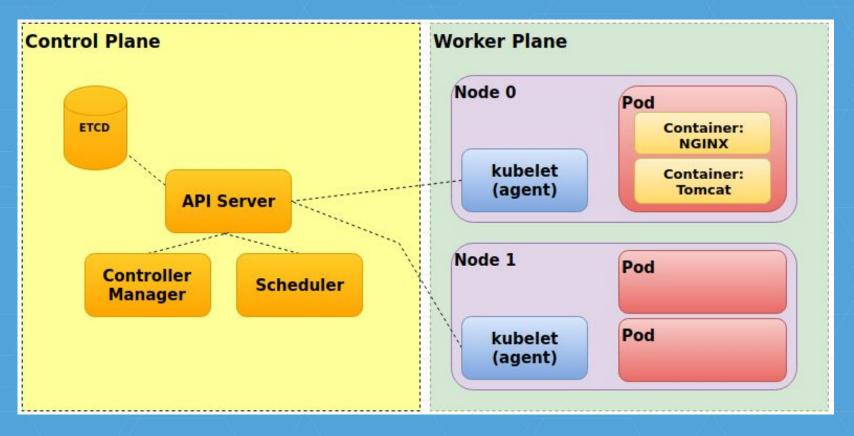
I hate Kubernetes!



I hate to OPERATE Kubernetes!



Kubernetes Architecture





Operating Kubernetes

- Installation
- Upgrade
- Healing
- Scaling
- Security
- Monitoring
- ...



Installation

- SSH
- Install kubelet
 - \$pkgmanager install kubelet
- Install container runtime
 - \$pkgmanager install [docker|rkt]
- Start kubelet
 - Systemctl start kubelet



Installation - master

- SSH
- Install scheduler
- Install controller manager
- Install API server
- Config them correctly
- Start them

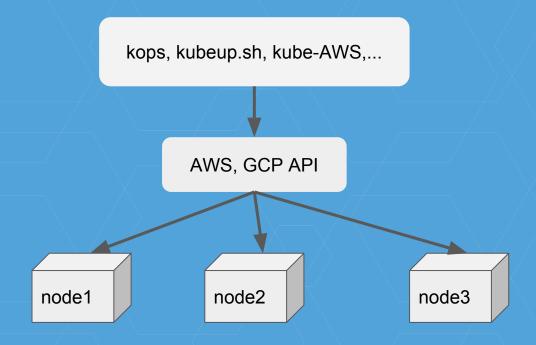


Installation - etcd

- SSH
- Install etcd
- Config them correctly
- Start them



Installation





Upgrade

- SSH
- Upgrade container runtime
- Upgrade Kubelet



Upgrade - master

- SSH
- Upgrade master components

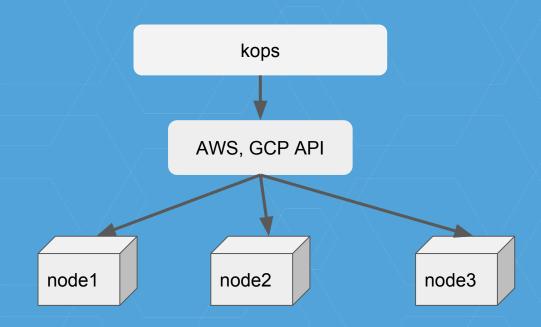


Upgrade - etcd

- SSH
- Upgrade etcd

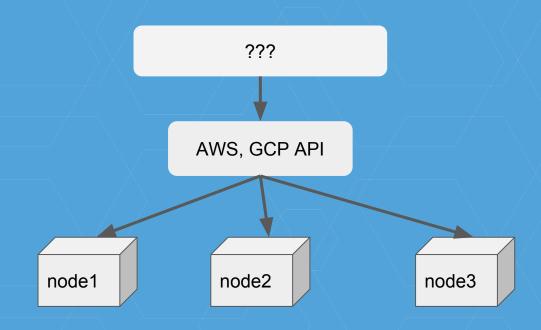


Upgrade

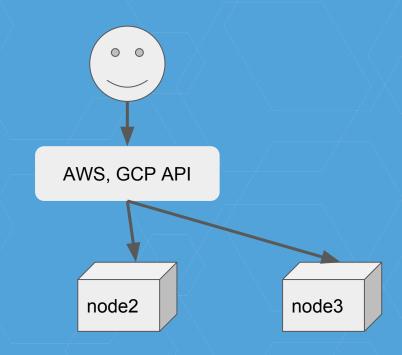




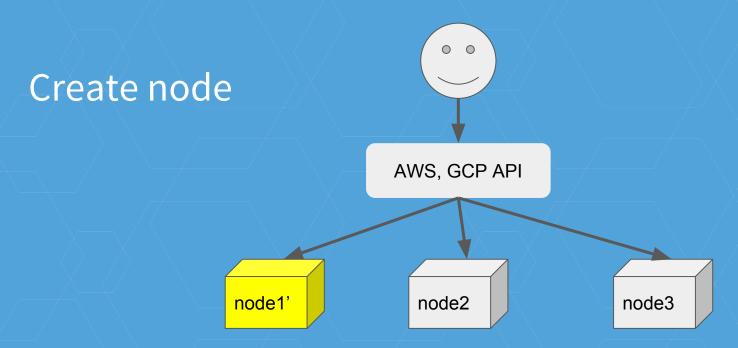
Rollback







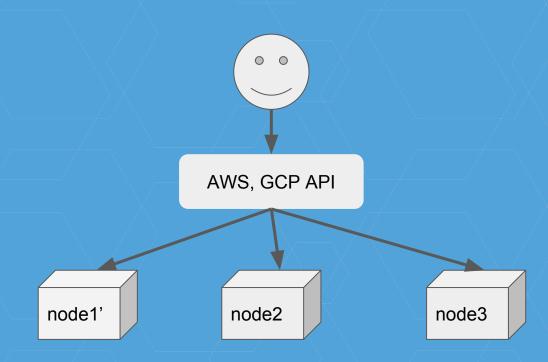






Install

Config





Problems

A lot of manual/semi-manual work
No standard way to approach all the problems

do it wrong, lose the cluster!



```
// gcc source code
#include <stdio.h>
int main()
   compile_c(argv[1]);
       gcc
```

gcc



```
// golang source code
package main
import "os"

func main() {
  compile_go(os.Args[1:])
}
```



go

go









\$ uname -s
minix
\$ gcc linux.c





\$ uname -s
minix
\$ gcc linux.c











\$ uname -s
linux
\$ gcc linux.c





\$ uname -s

linux
\$ gcc linux.c





Self-hosted Kubernetes?

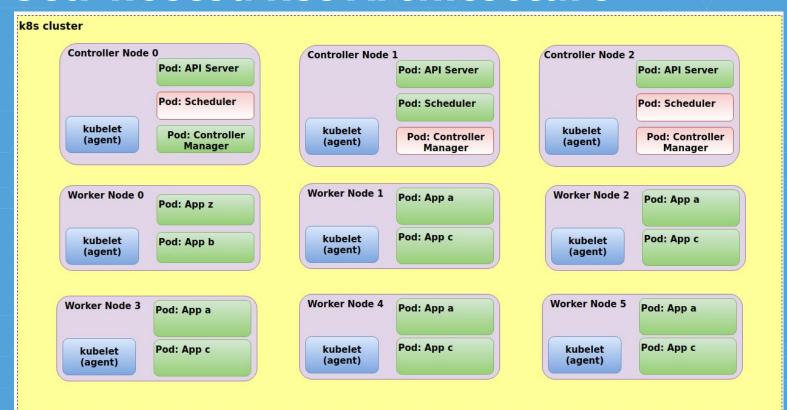


What is self-hosted Kubernetes?

- Kubernetes manages own core components
- Core components deployed as native API objects



Self-hosted k8s Architecture





Why Self-host Kubernetes?

- Operational expertise around app management in k8s extends to k8s itself
 - E.g. scaling
- Bootstrapping simplified
- Simply cluster life cycle management
 - E.g. updates
- Upstream improvements in Kubernetes directly translate to improvements in managing Kubernetes



Simplify Node Bootstrap

On-host requirements become:

- Kubelet
- Container Runtime (docker, rkt, ...)



Any Distro Node Bootstrap

- Install kubelet
 - \$pkgmanager install kubelet
- Install container runtime
 - \$pkgmanager install [docker|rkt]
- Write kubeconfig
 - scp kubeconfig user@host:/etc/kubernetes/kubeconfig
- Start kubelet
 - Systemctl start kubelet



Simplify k8s lifecycle management

Manage your cluster with only kubectl

Upgrading a self-hosted Kubernetes cluster:

```
$ kubectl apply -f kube-apiserver.yaml
$ kubectl apply -f kube-scheduler.yaml
$ kubectl apply -f kube-controller-manager.yaml
$ kubectl apply -f kube-proxy.yaml
```



Launching a self-hosted cluster

Need an initial control plane to bootstrap a self-hosted cluster

Bootkube:

- Acts as a temporary control plane long enough to be replaced by a self-hosted control plane.
- Run only on very first node, then not needed again.

github.com/kubernetes-incubator/bootkube



How Bootkube Works



etcd

Kubelet



Bootkube

API Server

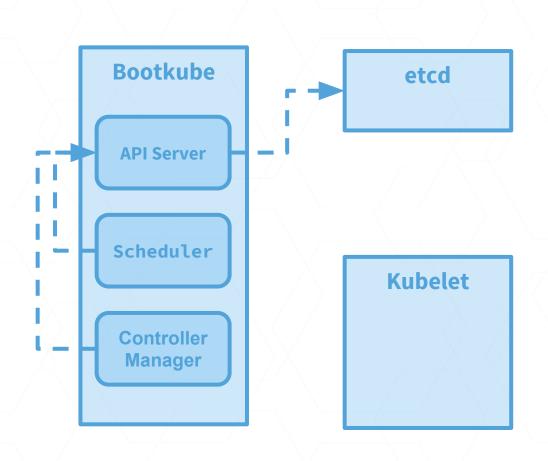
Scheduler

Controller Manager

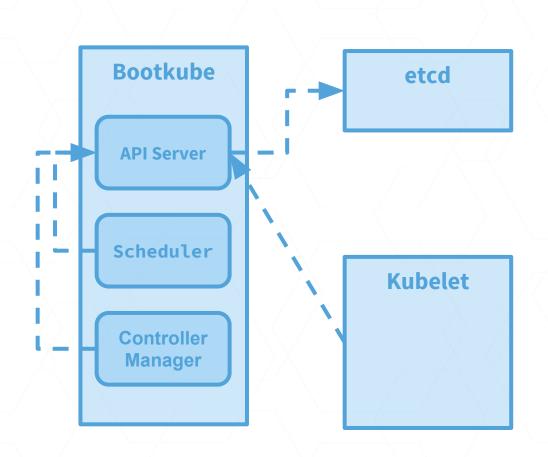
etcd

Kubelet

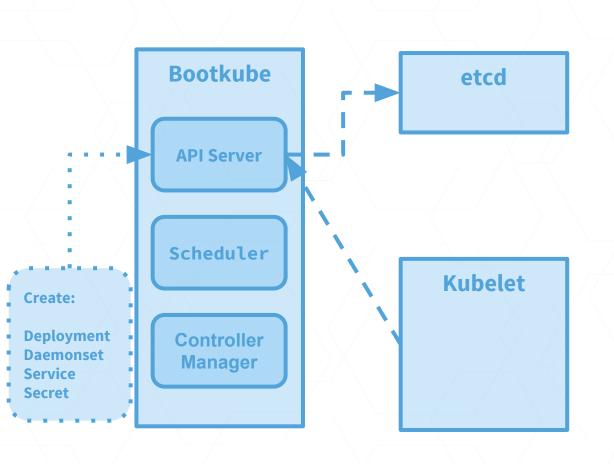




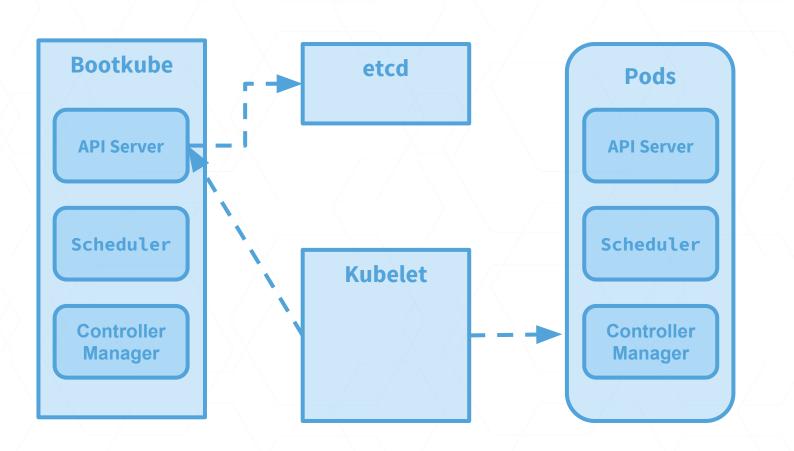




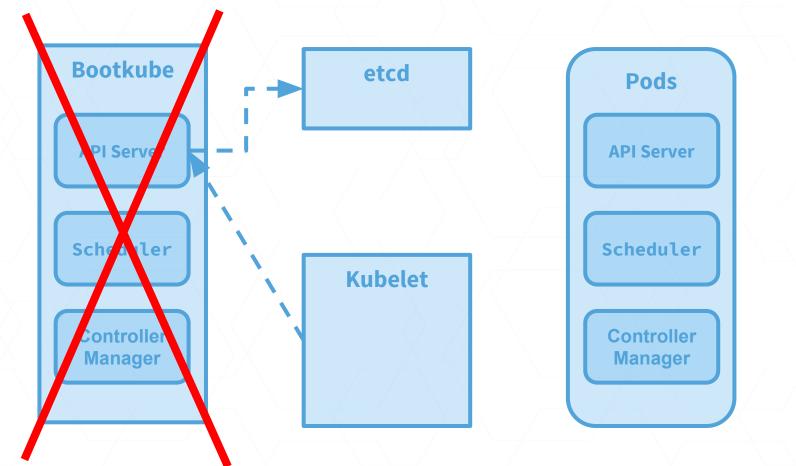




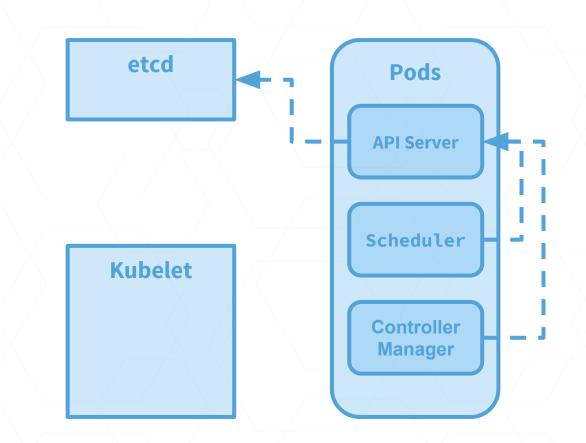




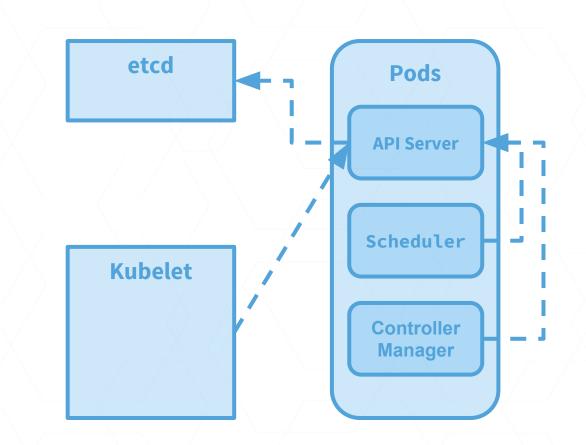














But wait! There's more!

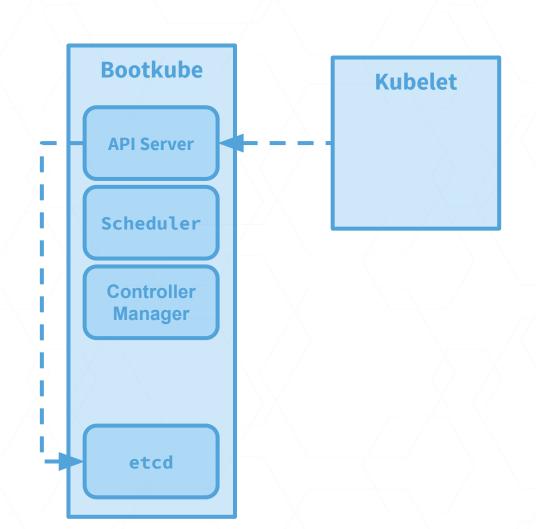
You can even self-host etcd!

https://coreos.com/blog/introducing-the-etcd-operator.html https://github.com/coreos/etcd-operator

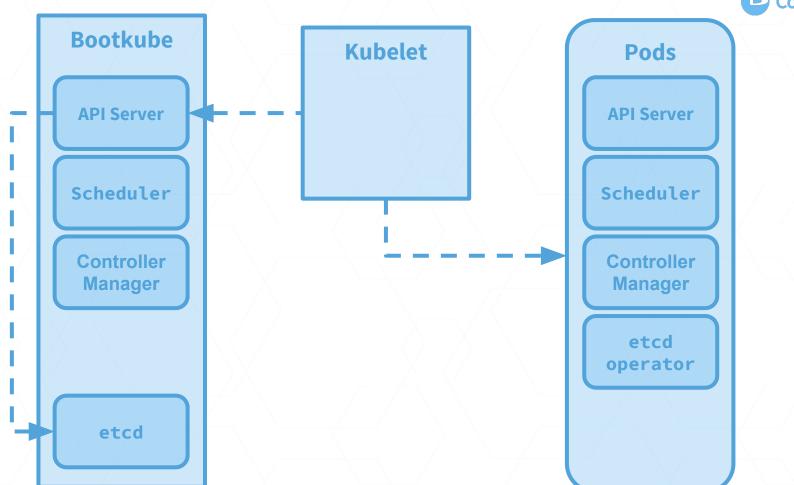


How to bootstrap self-hosted etcd

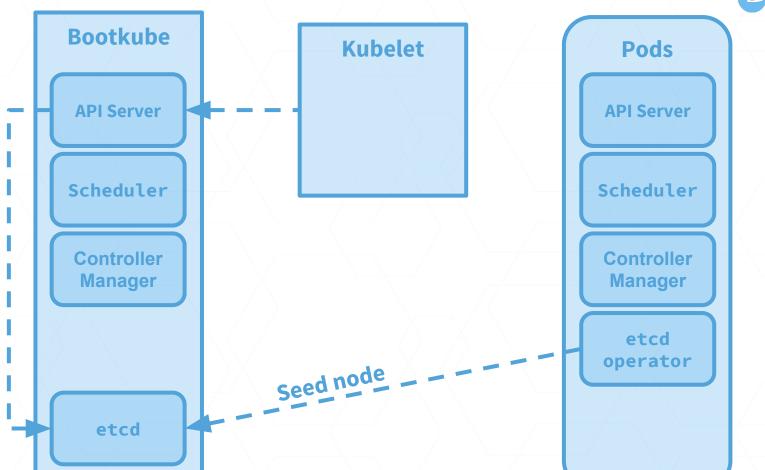


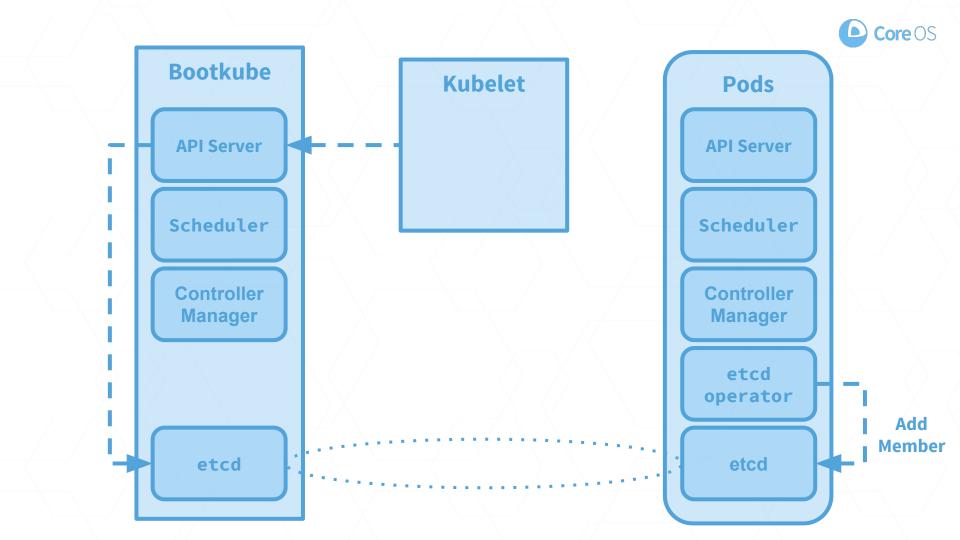




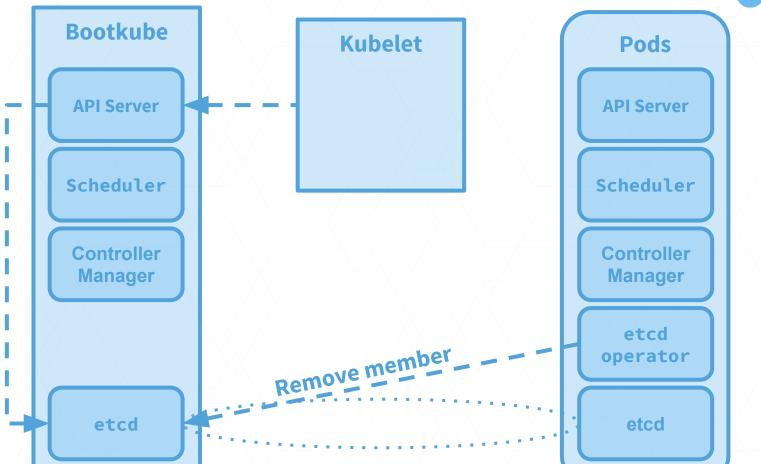


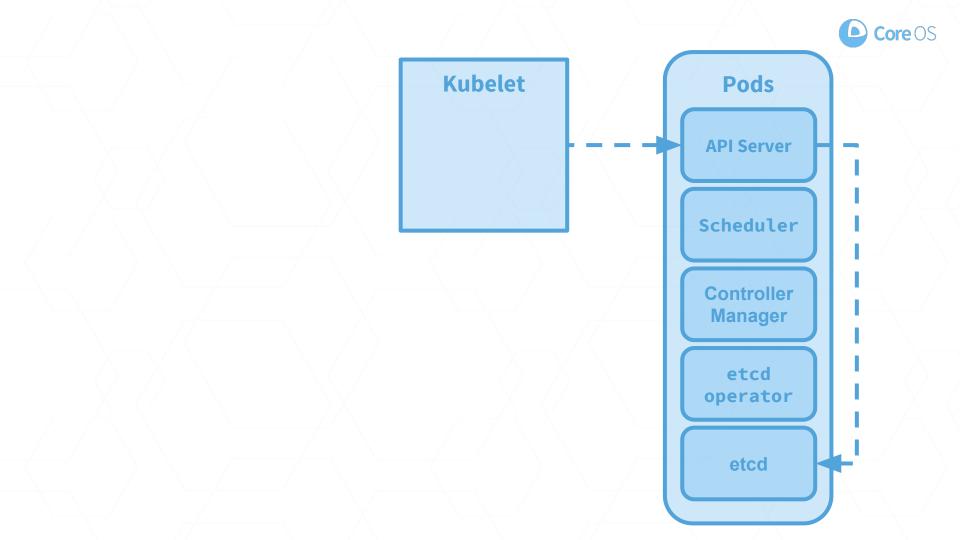














Disaster Recovery

Node failure in HA deployments (Kubernetes)

Partial loss of control plane components (Kubernetes)

Power cycling the entire control plane (Kubernetes)

Permanent loss of control plane (External tool)



Disaster Recovery

Permanent loss of control plane

- Similar situation to initial node bootstrap, but utilizing existing etcd state or etcd backup.
- Need to start a temporary replacement api-server
 - Could be binary, static pod, new tool, bootkube, etc.
- Recovery once etcd+api is available can be done via kubectl (as seen previously)



Self-Driving Kubernetes



Self driving

- A self-hosted cluster launched via Bootkube
- Upgraded via Kubernetes APIs and an Operator
- Automated by single-button or fully automatic



Kubernetes Version Operator





Cluster is running v1.4.3 and configured to run v1.4.5

- API Server is v1.4.3
- Scheduler is v1.4.3

Differences from desired config

- API Server should be v1.4.5
- Scheduler should be v1.4.5

How to get there

- Upgrade all API servers Daemons to v1.4.5 safely one-by-one
- Upgrade all Scheduler Deployments to v1.4.5
- Update status to v1.4.5



The infrastructure

Workload driven

Automation driven

Easy to manage: self driving approach (Today's topic)

Security focused



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Thank you!