Week 3

0.1 Joint Entropy in multiple RV's

$$H(X_1, \dots, X_n) = \sum_{(x_1, \dots, x_n) \in supp(P_{X_1, \dots, X_n})} P(x_1, \dots, x_n) \log_2 \frac{1}{P(x_1, \dots, x_n)}$$

Where $P_{X,Y} := \mathcal{X} \times \mathcal{Y} \to \text{Cartesian Product.}$ $\mathcal{X} \times \mathcal{Y} := \{(x,y) : x \in \mathcal{X}, y \in \mathcal{Y}\}$

0.2 Conditional Joint Entropy

$$H(X,Y/U,V) := \sum_{(u,v) \in supp(P_{U,V})} P_{U,V}(u,v) H(X,Y/U = u, V = v)$$

where,

$$H(X,Y/U=u,V=v) = \sum_{(x,y) \in supp(P_{X,Y/U=u,V=v})} P(x,y/u,v) \log_2 \frac{1}{P(x,y/u,v)}$$

This can be extended to any number of variables before and after the conditioning.

eg:
$$P(x_1, x_2, x_3/y_1, y_2) = P(x_1, x_2/x_3, y_1, y_2) + P(x_3/x_1, x_2, y_1, y_2)$$
.

1 Chain Rule for Joint Entropy

Lemma:

$$H(X_1, \dots, X_n) = H(X_1) + H(X_2/X_1) + H(X_3/X_1, X_2) + \dots + H(X_n/X_1, \dots, X_n) = \sum_{i=1}^{n} H(X_i/X_{i-1}, \dots, X_1)$$
 (1)

Proof:

$$P(x_1, \dots, x_n) = P(x_1)P(x_2, \dots, x_n/x_1)$$

$$= P(x_1)P(x_2/x_1)P(x_3, \dots, x_n/x_1, x_2)$$

$$= P(x_1)P(x_2/x_1)P(x_3/x_1, x_2)P(x_4, \dots, x_n/x_1, x_2, x_3)$$

$$= P(x_1)P(x_2/x_1)P(x_3/x_1, x_2) \cdots P(x_n/x_1, \dots, x_{n-1})$$

$$= \prod_{i=1}^{n} P(x_i/x_{i-1}, \dots, x_1)$$

We can substitute this value in the definition for joint entropy and expand, giving us the final result.

$$H(X_{1}, \dots, X_{n}) = -\sum_{x_{1}, \dots, x_{n}} P(x_{1}, \dots, x_{n}) \log \prod_{i=1}^{n} P(x_{i}/x_{i-1}, \dots, x_{1})$$

$$= -\sum_{x_{1}, \dots, x_{n}} \sum_{i=1}^{n} P(x_{1}, \dots, x_{n}) \log P(x_{i}/x_{i-1}, \dots, x_{1})$$

$$= -\sum_{i=1}^{n} \sum_{x_{1}, \dots, x_{n}} P(x_{1}, \dots, x_{n}) \log P(x_{i}/x_{i-1}, \dots, x_{1})$$

$$= \sum_{i=1}^{n} H(X_{i}/X_{i-1}, \dots, X_{1})$$

2 Mutual Information

We know that the average uncertainty in X is known as entropy of X, and it is given as H(X). If an observer (RX) sees X, the uncertainty in X would become 0 i.e H(X/X).

Hence the reduction in average uncertainty of X achieved by observing X is H(X) - H(X/X) = H(X).

Suppose X, Y are related to each other and the observer knows it's joint probability distribution $P(x,y) = P(X=x,Y=y) \ \forall \ x,y$.

The "reduction in uncertainity of X after observing Y", "information gained about X after observing Y" or "mutual information between X & Y" is:

$$I(X;Y) := H(X) - H(X/Y)$$

By symmetry it follows that:

$$I(X;Y) = H(Y) - H(Y/X) = H(X) + H(Y) - H(X,Y)$$

1. $I(X;Y) \leq \min(H(X), H(Y))$

Information gained depends on the quantized observation.

2. $I(X;Y) \ge 0$

Proof:

$$\begin{split} I(X;Y) &= H(X) - H(X/Y) \\ &= -\sum_{x \in supp(P_X)} P(x) \log(P(x) - \left(-\sum_{x,y \in suppP_{X,Y}} P(x,y) \log(x/y) \right) \\ &= -\sum_{x,y} P(x,y) \log P(x) + \sum_{x,y} P(x,y) \log P(x/y) \\ &= \sum_{x,y} P(x,y) \log \frac{P(x/y)}{P(x)} \\ &= \sum_{x} \sum_{y} P(x,y) \log \frac{P(x,y)}{P(x)P(y)} \\ &= D(P(x,y) || P(x) P(y)) \end{split}$$

As we know that the relative entropy of 2 probability distributions is positive, the proof is complete.

3 Information Theory

- Efficient source representation.(using some random variable or sequence of R.V's)(data compression and source coding)
- High rate and high fidelity.(low probability of error)(channel coding)

3.1 Source Coding

Suppose we have $X \in \{a, b\}$, a binary source with probability distribution P_X . And an observer observes one instance of X, then wants to store(or communicate) it through a noise-free medium, which can carry or store only $\{0, 1\}$ (bits).

But the reciever already knows P_X and it so happens that:

$$P_X(b) = 1 \quad P_X(a) = 0$$

Then RX doesn't need to read/recieve the encoded value to know X. It can simply declare the value of X to be b and it will be correct/error-free with probability 1.

We need a 0-length code as code is not required at all.

Suppose we allow a small probability of error $\Rightarrow P(\text{error}) \leq \epsilon, \quad \epsilon \in [0, 1).$

Then we could have length = $0 \& P(\text{error}) \le \epsilon$, if we let

$$P_X(b) = 1 - \epsilon, P_X(a) = \epsilon.$$