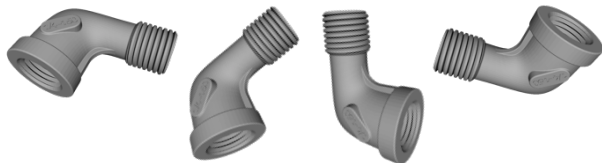


Training

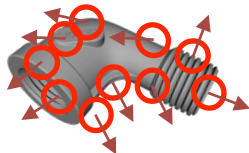


Unregistered training instances

The training instances have unknown poses. No parts are predefined in the training dataset.

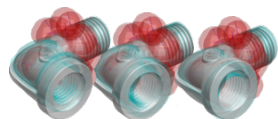
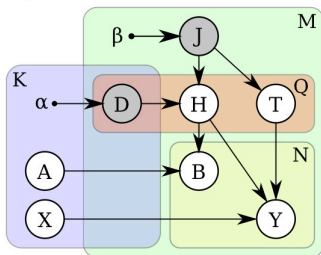
Shape feature extraction

Feature descriptors are extracted from 3D shape-based interest points



Particle-based EM algorithm

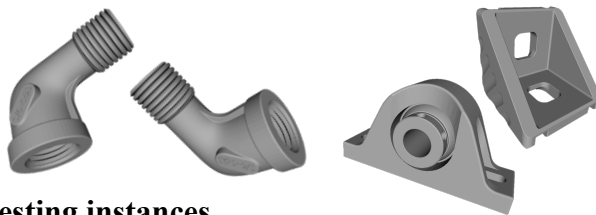
The structure and appearances of object parts, **A** and **X**, are learned. Object poses **T** are inferred simultaneously.



Training instances registered to a common reference frame.

The output SAP model describes structures (**X**) and appearances (**A**) of an object class in a reference frame.

Testing

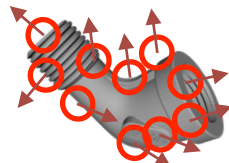


Testing instances

The testing instances have unknown poses and class label.

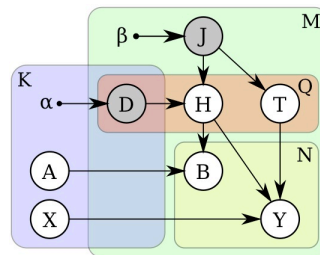
Shape feature extraction

Feature descriptors are extracted from 3D shape-based interest points

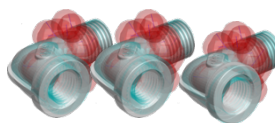


Particle-based EM algorithm

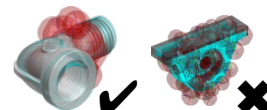
Given **X** and **A**, poses of testing instances **T** are inferred.



Registration



Classification



Registration and classification are performed simultaneously using the SAP model.