Bayesian Inference with GFlowNets

When do GFlowNets learn the right distribution?

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December 5, 2024

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The sampling problem

Let

- 1. \mathcal{X} be a set and
- 2. $R: \mathcal{X} \to \mathbb{R}_+$ be a positive function on \mathcal{X} .

The sampling problem

How to generate samples from

$$\pi(x) \propto R(x)$$
?

For Bayesian inference: $R(x) = f(\mathcal{D}|x)p(x)$ (unnormalized posterior)

Usual solutions: MCMC, diffusion models, normalizing flows, etc.

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Generative Flow Networks (GFlowNets)

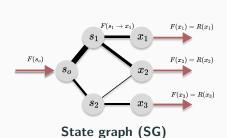
GFlowNets solve the sampling problem for a compositional space.

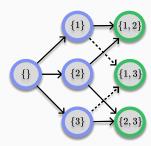


Compositional space

A space \mathcal{X} is **compositional** if its elements can be sequentially constructed from a single **initial state**.

Generative Flow Networks (GFlowNets)



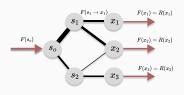


SG for generating 2-sized subsets of $\{1,2,3\}$

Central idea

Reframe the state graph as a **flow network** and the sampling problem as a **flow assignment problem**.

GFlowNets: Learning a flow



State graph (SG)

1. Incoming flow = outgoing flow.

$$\sum_{s' \in \mathsf{Ch}(s)} F(s o s') = \sum_{s' \in \mathsf{Pa}(s)} F(s' o s).$$

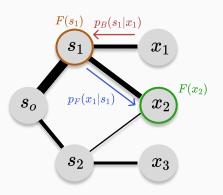
2. Terminal flow = R(x).

$$\sum_{s'\in\mathsf{Pa}(x)} F(s'\to x) = R(x).$$

An ideal setup for Machine Learning

We have a clear goal (finding F) with a simple set of constraints.

GFlowNets: Learning a flow



1. We reparameterize

$$F(s \to s') = F(s) \underbrace{p_F(s'|s)}_{\text{Markovian kernel}}$$

$$F(s' o s) = F(s') \underbrace{p_B(s|s')}_{\text{Markovian kernel}}$$

2. The constraints become

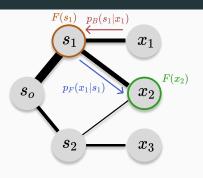
$$F(s)p_F(s'|s) = F(s')p_B(s|s')$$
and
$$F(x) = R(x).$$

Transform the hard constraints into loss functions

$$\mathcal{L}_{DB}(s, s') = \left(\log \frac{F(s)p_F(s'|s)}{F(s')p_B(s|s')}\right)^2$$

This is the **detailed balance** loss. We hardcode F := R for $x \in \mathcal{X}$.

GFlowNets: Learning a flow with neural networks



1. We define

$$F(s) = \underbrace{\mathrm{NN_F}}_{\text{Neural network}} (s)$$

2. Also,

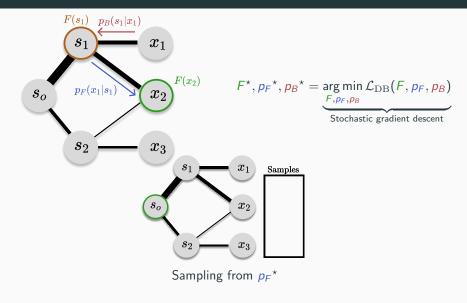
$$p_F(s'|s) = \text{Softmax}(NN_{PF}(s))[s'],$$

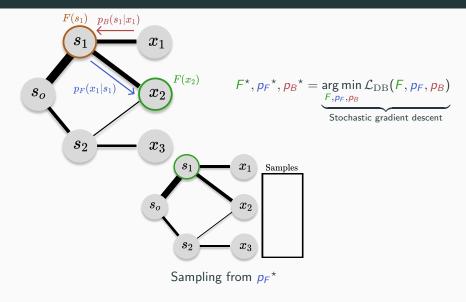
$$p_B(s|s') = \text{Softmax}(NN_{PB}(s'))[s].$$

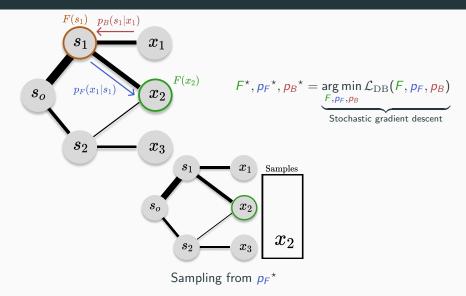
A stochastic objective for learning the neural networks

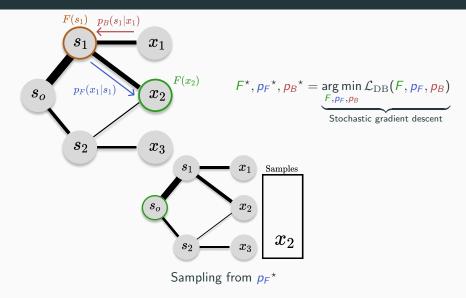
$$\mathcal{L}(F, p_F, p_B) = \mathbb{E}_{ au \sim p_E} \left[\frac{1}{\# au} \sum_{(s, s') \in au} \mathcal{L}_{DB}(s, s')
ight]$$

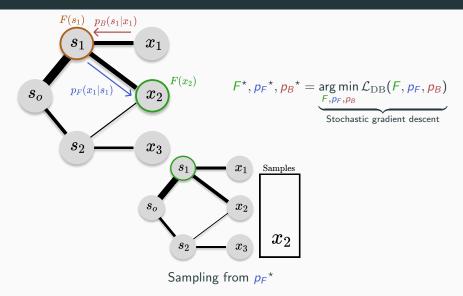
 p_E is a policy. τ is a trajectory starting at s_o and finishing on \mathcal{X} (e.g., x_2), and $\#\tau$ represents the number of transitions in τ .

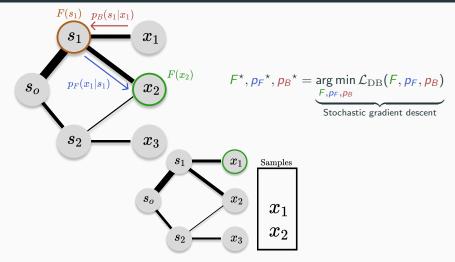






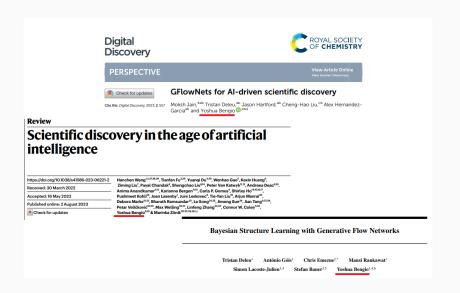






Independent samples with **non-asymptotic** guarantees (\neq MCMC)!

What do GFlowNets promise?



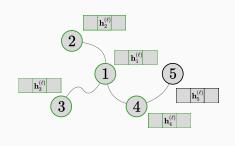
When do GFlowNets learn the right distribution?

What are the limits of GFlowNets?

How to assess a trained GFlowNet?

What are the limits of GFlowNets? A review of GNNs

GFlowNets use Graph Neural Networks (GNNs) to parameterize the flow functions for graph-structured objects. We review what a GNN is below.



 Aggregate the the features of each node's neighbors.

$$\mathbf{h}_n^{(\ell), \mathsf{agg}} = \sum_{m \in \underbrace{\mathcal{N}(n)}_{\mathsf{Neighborhood of } n}} \mathsf{h}_m^{(\ell)}$$

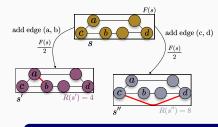
2. Update the node's feature.

$$\mathbf{h}_n^{(\ell+1)} = \mathrm{NN}_{\mathrm{G}}(\mathbf{h}_n^{(\ell),\mathsf{agg}}).$$

Repeat this a few times.

Result:
$$\mathbf{H} = \left[\mathbf{h}_n^{(L)}\right]_n \in \mathbb{R}^{\# \text{nodes} \times d}$$
 used as input for downstream tasks.

What are the limits of GNN-based GFlowNets?

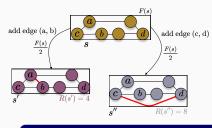


- 1. GNNs cannot distinguish edges (a, b) and (c, d) in s.
- A GFlowNet always assigns the same flow to s's children regardless of R.

GNN-based GFlowNets are fundamentally limited

The limited capacity of a GNN constrains the expressivity of the GNN-parameterized GFlowNet.

What are the limits of GNN-based GFlowNets?



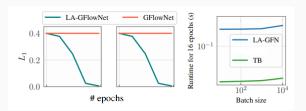
Solution: Look-Ahead (LA) GFlowNets.

$$p_F(s'|s) \propto \exp\left(\mathbf{w}^T \left[\phi_{(a,b)}^{(s')}||\phi_{(a,b)}^{(s)}]\right),$$

$$\phi^{(s)} = \mathsf{GNN}(s), \, \phi^{(s')} = \mathsf{GNN}(s').$$

LA-GFlowNets boost the expressiveness GNN-based GFlowNets

LA-GFlowNets incorporate **future embeddings** into the **current policy** to compute the transition probabilities.

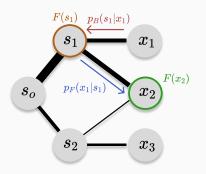


When do GFlowNets learn the right distribution?

What are the limits of GFlowNets?

How to assess a trained GFlowNet?

How to assess a trained GFlowNet?



$$\begin{split} \underbrace{p_{\top}(x)}_{\text{Marginal over }\mathcal{X}} &\coloneqq \sum_{\tau \leadsto x} p_F(\tau) \\ &= \underbrace{\mathbb{E}_{\tau \sim p_B(\tau|x)} \left[\frac{p_F(\tau)}{p_B(\tau|x)} \right]}_{\text{Importance sampling}} \\ &= \frac{1}{T} \sum_{1 \le i \le T} \frac{p_F(\tau_i)}{p_B(p_B|x)}, \\ &\{\tau_1, \dots, \tau_T\} \sim p_B(\cdot|x). \end{split}$$

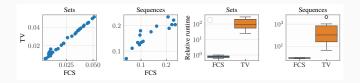
Flow Consistency in Subgraphs (FCS)

FCS consists of the expected total variation in random $\mathcal{X}\text{-subsets}.$

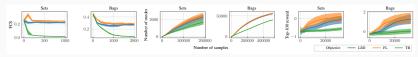
$$\mathbb{E}_{S(\subseteq \mathcal{X}) \sim P} \left[\mathrm{TV}(p_\top^{(S)}, R^{(S)}] = \frac{1}{2} \mathbb{E}_{S(\subseteq \mathcal{X}) \sim P} \left[\sum_{x \in S} \left| p_\top^{(S)}(x) - R^{(S)}(x) \right| \right],$$

with
$$R^{(S)}(x) = R(x)/\sum_{y \in S} R(y)$$
 and $p_{\top}^{(S)}(x) = p_{\top}(x)/\sum_{y \in S} p_{\top}(y)$.

How to assess a trained GFlowNet?



FCS is highly correlated and drastically faster-to-compute than TV.



Mode-coverage is not a reliable indicator of correctness.

FCS is a realiable measurement of GFlowNet's accuracy

FCS provides a relatively **fast-to-compute** and **accurate** surrogate for the distributional correctness of a GFlowNet.



Take-home message

GFlowNets are excellent samplers for compositional spaces.

GFlowNets cast the sampling problem as a flow assignment problem in a flow network. This network describes the sequential construction of complex objects from a single initial state.

GNN-based GFlowNets have fundamentally limited expressiveness.

GNN-based flow functions explicitly constraint the range of distributions realizable by the corresponding GFlowNet. Designing efficient solutions to this problem remains an open issue.

FCS has the potential to standardize the evaluation of GFlowNets.

As such, FCS stands as the best available diagnostic for this family of models. It is a computationally amenable and theoretically sound proxy for the distributional accuracy of GFlowNets.

Questions? Thank you!